

# Multi-strange hadrons and the precision extraction of QGP properties in the RHIC-BES domain

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SQM 2016, Berkeley

June 28, 2016



## Strangeness as a probe of QCD matter

- Multistrange hadrons  $\Omega$  and  $\phi$  are expected to have small hadronic cross sections  
 $\Rightarrow$  Potentially good constraints for chemical freezeout region

Modeling approach:

Model parameters (input):  $\vec{x} = (x_1, \dots, x_n)$

$(\tau_0, R_{\text{trans}}, R_{\text{long}}, \eta/s, \epsilon_C)$

$\Downarrow$

Model output  $\vec{y} = (y_1, \dots, y_m) \Leftrightarrow$  Experimental values  $\vec{y}^{\text{exp}}$

$(N_{\text{ch}}, \langle p_T \rangle, v_2, \dots)$

Goal: Find the “true” values of the input parameters, for which  $\vec{x}^* \Rightarrow \vec{y}^{\text{exp}}$ .

What is the level of **uncertainty** associated with the proposed values?

# Transport + hydrodynamics hybrid model

Karpenko, Huovinen, Petersen, Bleicher, Phys.Rev.C, 91, 064901 (2015)

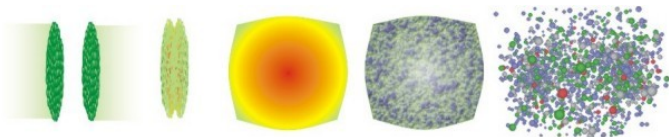


Image source: S. A. Bass

- Initial State from UrQMD<sup>1</sup> hadron+strings cascade
- Start the hydrodynamical evolution when nuclei have passed through each other:  $\tau_0 \geq \frac{2R_{\text{nucleus}}}{\sqrt{\gamma_{CM}^2 - 1}}$
- Particle properties (energy, baryon number) to densities: 3D Gaussians with “smearing” parameters  $R_{\text{trans}}$ ,  $R_{\text{long}}$  ( $\equiv \sqrt{2}\sigma$ )
- 3+1D viscous hydrodynamics<sup>2</sup> with viscosity parameter  $\eta/s$
- Transition from hydro back to transport (“particlization”) when energy density  $\epsilon < \epsilon_C$

<sup>1</sup>S. A. Bass *et al.*, Prog. Part. Nucl. Phys. 41, 255 (1998), M. Bleicher *et al.*, J. Phys. G 25, 1859 (1999).

<sup>2</sup>Iu. Karpenko *et al.*, Comput.Phys.Commun. 185, 3016 (2014).

## Bayes' theorem

Given a set  $X = \{\vec{x}_k\}_{k=1}^N$  of points in parameter space and a corresponding set  $Y = \{\vec{y}_k\}_{k=1}^N$  of points in observable space,

$$P(\vec{x}^* | X, Y, \vec{y}^{\text{exp}}) \propto P(X, Y, \vec{y}^{\text{exp}} | \vec{x}^*) P(\vec{x}^*)$$

- $P(\vec{x}^* | X, Y, \vec{y}^{\text{exp}})$  is the *posterior* probability distribution of  $\vec{x}^*$  for given  $(X, Y, \vec{y}^{\text{exp}})$
- $P(\vec{x}^*)$  is the *prior* probability distribution (simplest case: ranges of parameter values)
- $P(X, Y, \vec{y}^{\text{exp}} | \vec{x}^*)$  is the *likelihood* of  $(X, Y, \vec{y}^{\text{exp}})$  for given  $\vec{x}^*$  (to be determined with statistical analysis)

$$P(X, Y, \vec{y}^{\text{exp}} | \vec{x}^*) = \exp\left(-\frac{1}{2}(\vec{y}^* - \vec{y}^{\text{exp}})^T \Sigma^{-1}(\vec{y}^* - \vec{y}^{\text{exp}})\right),$$

where  $\Sigma$  is the **covariance matrix**. In this study  $\Sigma = \text{diag}(\sigma \vec{y}^{\text{exp}})^2$ , with  $\sigma = 0.05$  as a global estimate of relative uncertainty, and  $\vec{y}^*$  is model output at  $\vec{x}^*$

## Analysis procedure

Model parameters (input):  $\tau_0, R_{\text{trans}}, R_{\text{long}}, \eta/s, \epsilon_C$   
Uniform priors: input parameter space = 5-D hypercube



Hybrid model  $\Rightarrow$

**Gaussian process**; statistical emulator trained with model data, necessary for quick evaluation of the likelihood



Experimental data  $\Rightarrow$

Random walk (**MCMC**) in the input parameter space, guided by the likelihood

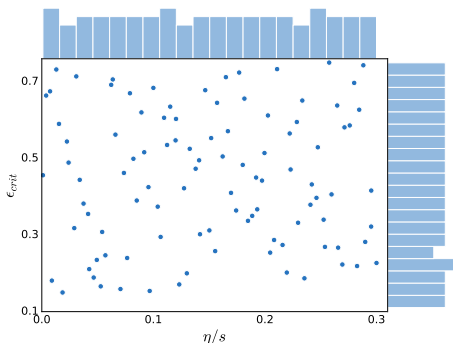


Posterior distribution of input parameters  
(best-fit values + **uncertainty**)

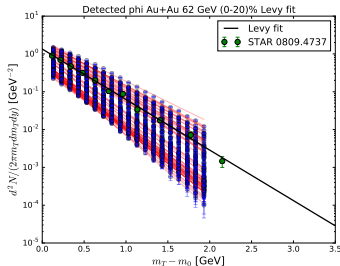
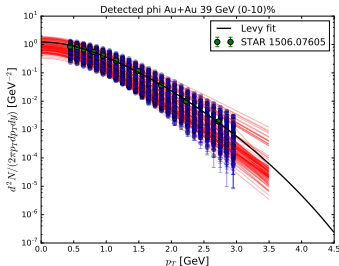
## Investigated parameter ranges

To provide the Gaussian process with a proper representation of the hybrid model, training points are sampled evenly over whole parameter space using Latin hypercube method

- Shear viscosity over entropy density  $\eta/s$ : 0.001 - 0.4
- Transport-to-hydro transition time  $\tau_0$ : 0.4 - 3.1 fm
- Transverse Gaussian smearing of particles  $R_{\text{trans}}$ : 0.2 - 2.2 fm
- Longitudinal Gaussian smearing of particles  $R_{\text{long}}$ : 0.2 - 2.2 fm
- Hydro-to-transport transition energy density  $\epsilon_C$ : 0.15 - 0.75 GeV/fm<sup>3</sup>



# $\phi$ Levy fits to $dN/dp_T$ , $dN/dm_T$ at $\sqrt{s_{NN}} = 39, 62.4$ GeV



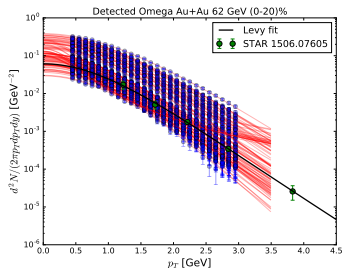
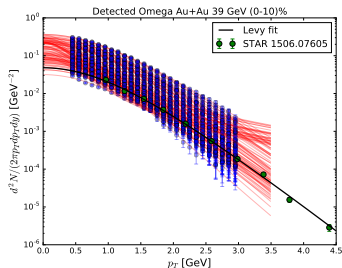
- "Detected  $\phi$ ":  $\phi$  which has both its decay products surviving to the end of UrQMD simulation

- Levy fit:  $Y \frac{(n-1)(n-2)}{2\pi nT(nT+m_0(n-2))} \left( 1 + \frac{\sqrt{p_T^2+m_0^2}-m_0}{nT} \right)^{-n}$  PRC 71, 064902

Fit parameters:  $Y$  = yield,  $T$  = slope,  $n$  = exponent

- $\phi$  yield extracted from Levy fits =  $\phi$  count from simulation output  
 $\Rightarrow$  apples-to-apples comparison with data
- Underestimation of detected  $\phi$  with most parameter combinations

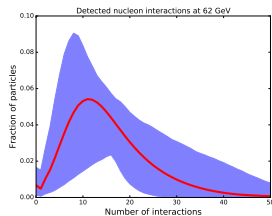
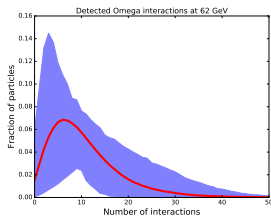
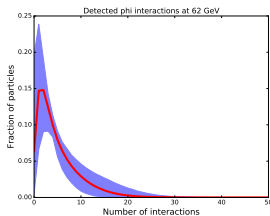
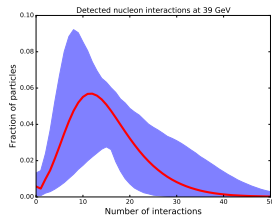
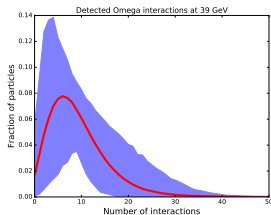
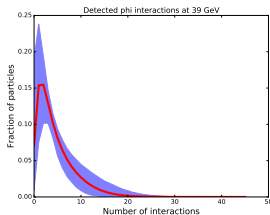
# $\Omega$ Levy fits to $dN/dp_T$ at $\sqrt{s_{NN}} = 39, 62.4$ GeV



- $\Omega$  considered "stable" in UrQMD  $\Rightarrow$  "detected" = "total"
- Fit quality suffers from low statistics at higher  $p_T$
- Yield is typically overestimated; however, more points around the experimental value compared to  $\phi$

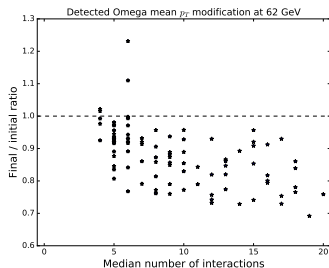
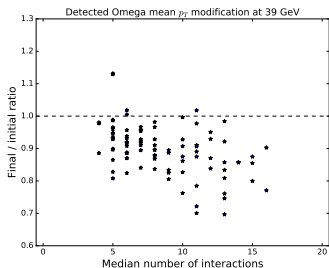


## Number of interactions

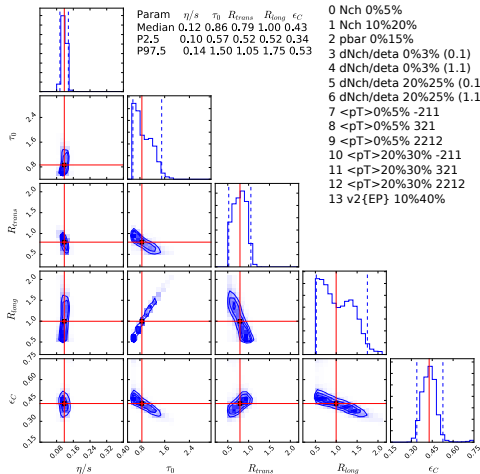
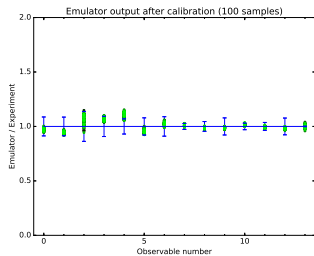
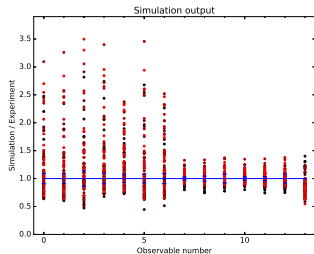


- $\phi$  typically has a few interactions during its lifetime
  - Most  $\Omega$  experience  $\approx 10$  interactions, but notable portion  $> 20!$
- Effect on  $p_T$  spectrum?

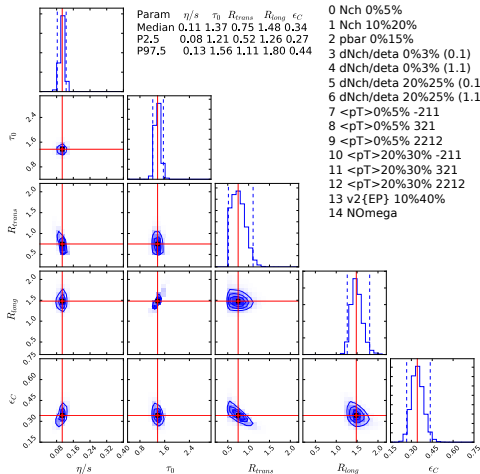
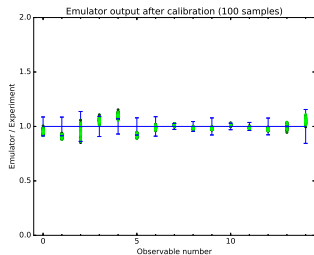
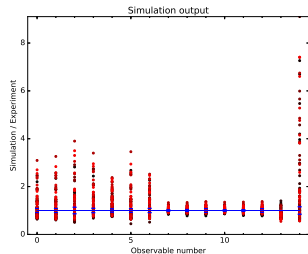
## Effect of interactions on $\Omega$ mean $p_T$



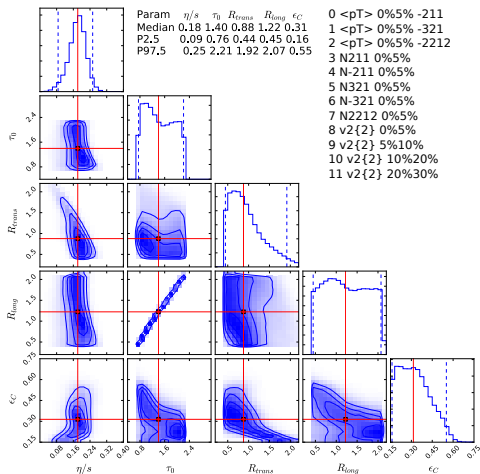
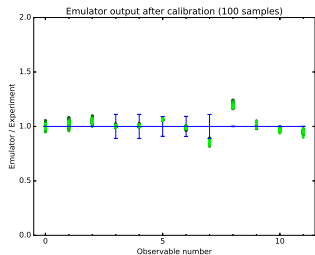
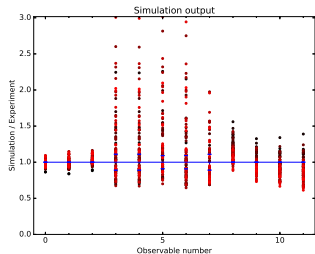
- Suppression up to 30% detected for some training points
- Large variations even with the same median value of interactions
- Check  $p_T$  distribution at hypersurface vs. final distribution once the best-fit parameter values are determined

62.4 GeV analysis without  $\Omega$ 

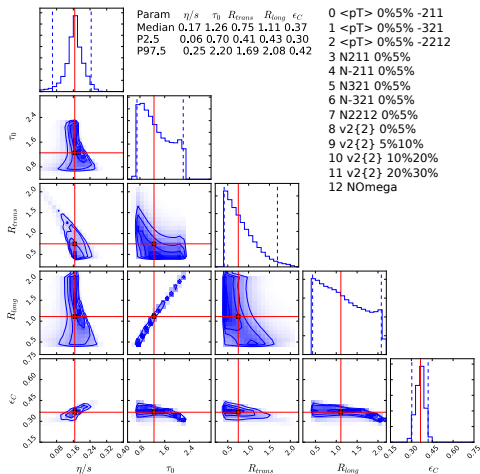
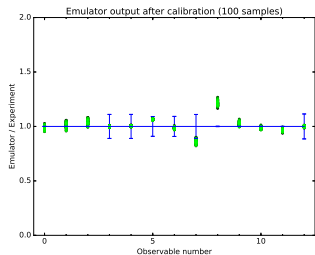
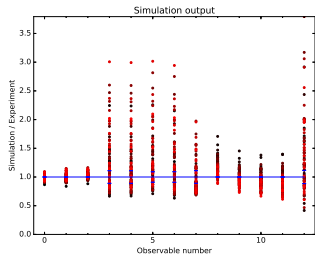
Results preliminary

62.4 GeV analysis with  $\Omega$ 

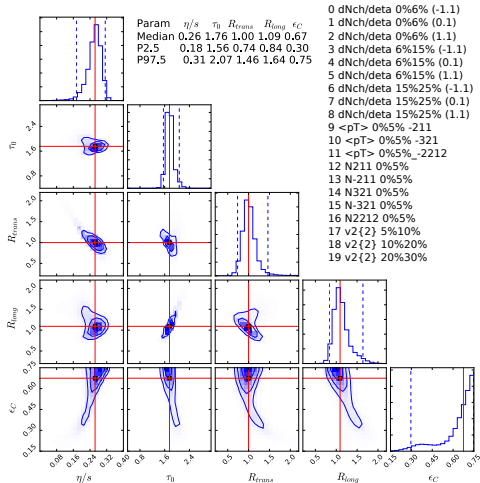
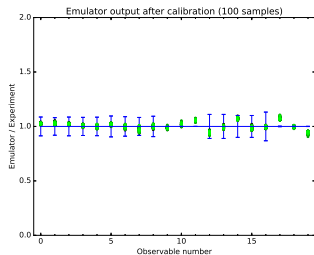
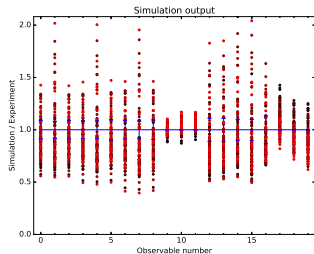
Results preliminary

39 GeV analysis without  $\Omega$ 

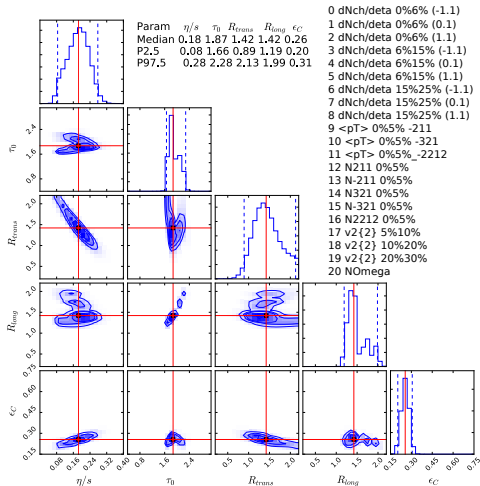
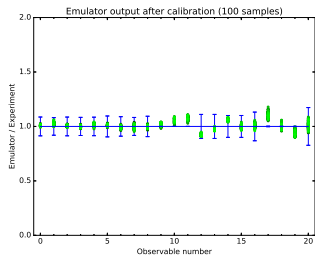
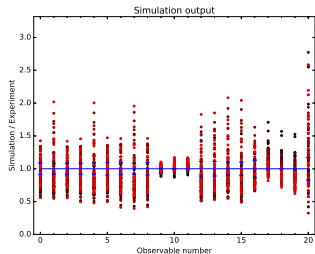
Results preliminary

39 GeV analysis with  $\Omega$ 

Results preliminary

19.6 GeV analysis without  $\Omega$ 

Results preliminary

19.6 GeV analysis with  $\Omega$ 

Results preliminary



## Summary and outlook

- Gaussian processes allow the emulation of complex models, making it possible to investigate multidimensional parameter spaces within reasonable computational effort
- First results from the statistical analysis of a transport+hydro hybrid model suggest that multi-strange hadrons provide very important constraints on model parameters at lower collision energies
- $\Omega$  has less interactions than nucleons, but still enough to potentially distort the signal from hypersurface. Need to run simulation with posterior median values and compare  $p_T$  distributions before and after UrQMD afterburner
- $\phi$  needs to be also included in statistical analysis
  - $\phi$ s detected based on UrQMD analysis seem to underestimate the measured value
  - Quantify the uncertainty by allowing the "true number" of  $\phi$  vary between the "detected" and "total" values of UrQMD

# Extra slides

# Gaussian process

<http://dan.iel.fm/george>

**Assumption:** Set  $Y_a$  of values of observable  $y_a$ , corresponding to set  $X$  of points in parameter space, has a **multivariate normal distribution**:

$$Y_a \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$$

where  $\boldsymbol{\mu} = \mu(X) = \{\mu(x_1), \dots, \mu(x_N)\}$  is the mean (often set to 0 by centering the data) and

$$\boldsymbol{\Sigma} = \sigma(X, X) = \begin{pmatrix} \sigma(\vec{x}_1, \vec{x}_1) & \cdots & \sigma(\vec{x}_1, \vec{x}_N) \\ \vdots & \ddots & \vdots \\ \sigma(\vec{x}_N, \vec{x}_1) & \cdots & \sigma(\vec{x}_N, \vec{x}_N) \end{pmatrix}$$

is the covariance matrix with **covariance function**  $\sigma(\vec{x}, \vec{x}')$  (model-dependent choice; constant, linear, exponential, periodic, ...).

## Drawing samples from a Gaussian process

- Define a vector of  $N$  points,  $\vec{x} = (x_1, \dots, x_N)$ , on which to evaluate the GP
- Compute covariance matrix  $\Sigma_{ij} = \sigma(x_i, x_j)$
- Compute Cholesky decomposition  $\Sigma = SS^T$
- The vector  $\vec{y} = \mu(\vec{x}) + S\vec{u}$ ,  $u_i \sim N(0, 1)$ , defines a GP sample

The joint distribution of observations  $Y_o = (y(x_{o1}), \dots, y(x_{ok}))$  and predictions  $Y_p = (y(x_{p1}), \dots, y(x_{pn}))$  is

$$\begin{pmatrix} Y_p \\ Y_o \end{pmatrix} = \mathcal{N} \left( \begin{pmatrix} \mu_p \\ \mu_o \end{pmatrix}, \begin{pmatrix} \Sigma_{pp} & \Sigma_{po} \\ \Sigma_{op} & \Sigma_{oo} \end{pmatrix} \right)$$

resulting to posterior mean (prediction based on known values)

$$\bar{\mu}(X_p) = \mu_p + \Sigma_{po}\Sigma_{po}^{-1}(Y_o - \mu_o)$$

and posterior variance  $\bar{\Sigma} = \Sigma_{pp} - \Sigma_{po}\Sigma_{oo}^{-1}\Sigma_{op}$ .

## Gaussian process

Choice: Squared-exponential covariance function with a noise term

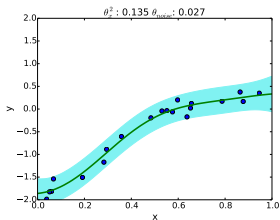
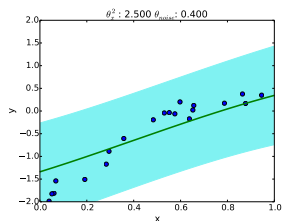
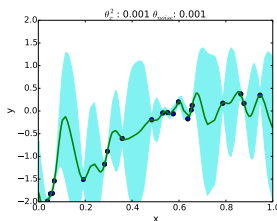
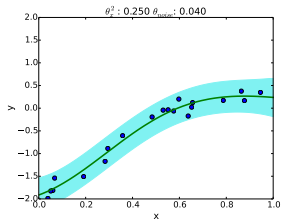
$$\sigma(\vec{x}, \vec{x}') = \theta_0 \exp\left(-\sum_{i=1}^n \frac{(x_i - x'_i)^2}{2\theta_i^2}\right) + \theta_{\text{noise}}\delta_{\vec{x}\vec{x}'}$$

The *hyperparameters*  $\vec{\theta} = (\theta_0, \theta_1, \dots, \theta_n, \theta_{\text{noise}})$  are not known a priori and must be estimated from the given data

⇒ emulator **training**: Maximise the marginal likelihood (aka “evidence”)

$$\log P(Y|X, \vec{\theta}) = \underbrace{-\frac{1}{2}Y^T \Sigma^{-1}(X, \vec{\theta})Y}_{\text{data fit}} \underbrace{-\frac{1}{2} \log |\Sigma(X, \vec{\theta})|}_{\text{complexity penalty}} \underbrace{-\frac{N}{2} \log(2\pi)}_{\text{normalization}}$$

## 1-D example



# Markov Chain Monte Carlo

“emcee”: D. Foreman-Mackey *et al.*, Publ. Astron. Soc. Pacific 125, 306 (2013), arXiv:1202.3665

The posterior distribution is sampled with **Markov Chain Monte Carlo** (MCMC) method

- Random walk in parameter space, where each step is accepted or rejected based on a relative likelihood (calculated in terms of principal components)
- Converges to posterior distribution as number of steps  $N \rightarrow \infty$
- **Acceptance fraction**  $a_f$  of steps measures the quality of random walk
  - $a_f \sim 0 \Rightarrow$  walker “stuck”
  - $a_f \sim 1 \Rightarrow$  purely random walk
  - aim for 0.2-0.5
- **Autocorrelation time** = Number of steps between independent samples  
“Burn-in” takes a few autocorrelations,  
gathering enough samples  $\sim \mathcal{O}(10)$  autocorrelations