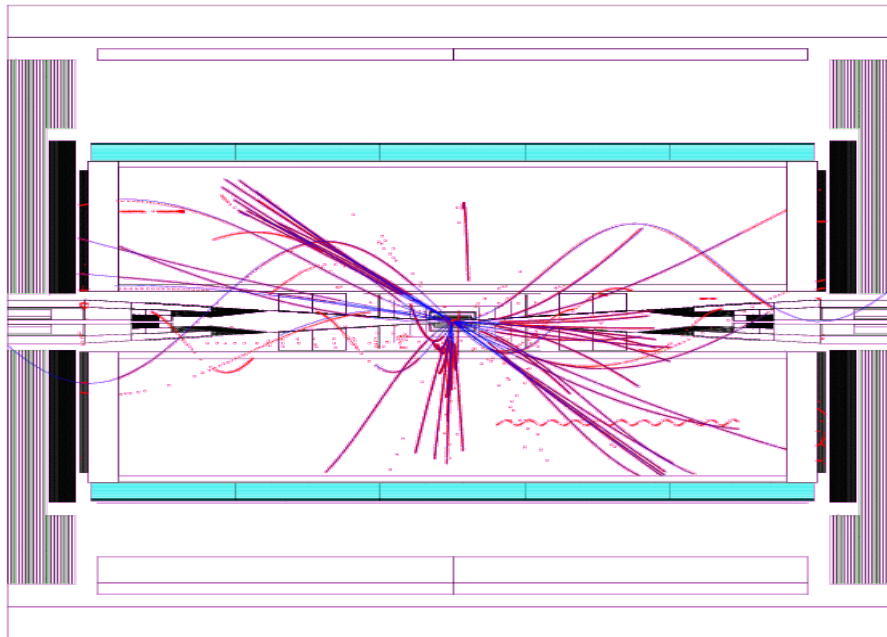


Simulation Framework

- Full simulation systems: status report
- The next steps: where do we go from here
- The data challenge: status report



The LC simulation groups:

Europe: David Ward, Ties Behnke

[:http://www-zeuthen.de/linear_coll](http://www-zeuthen.de/linear_coll)

US: Norman Graf

[:http://blueox.uoregon.edu/~lc/alcpag/](http://blueox.uoregon.edu/~lc/alcpag/)

Asia:

[:http://acfahep.kek.jp](http://acfahep.kek.jp)

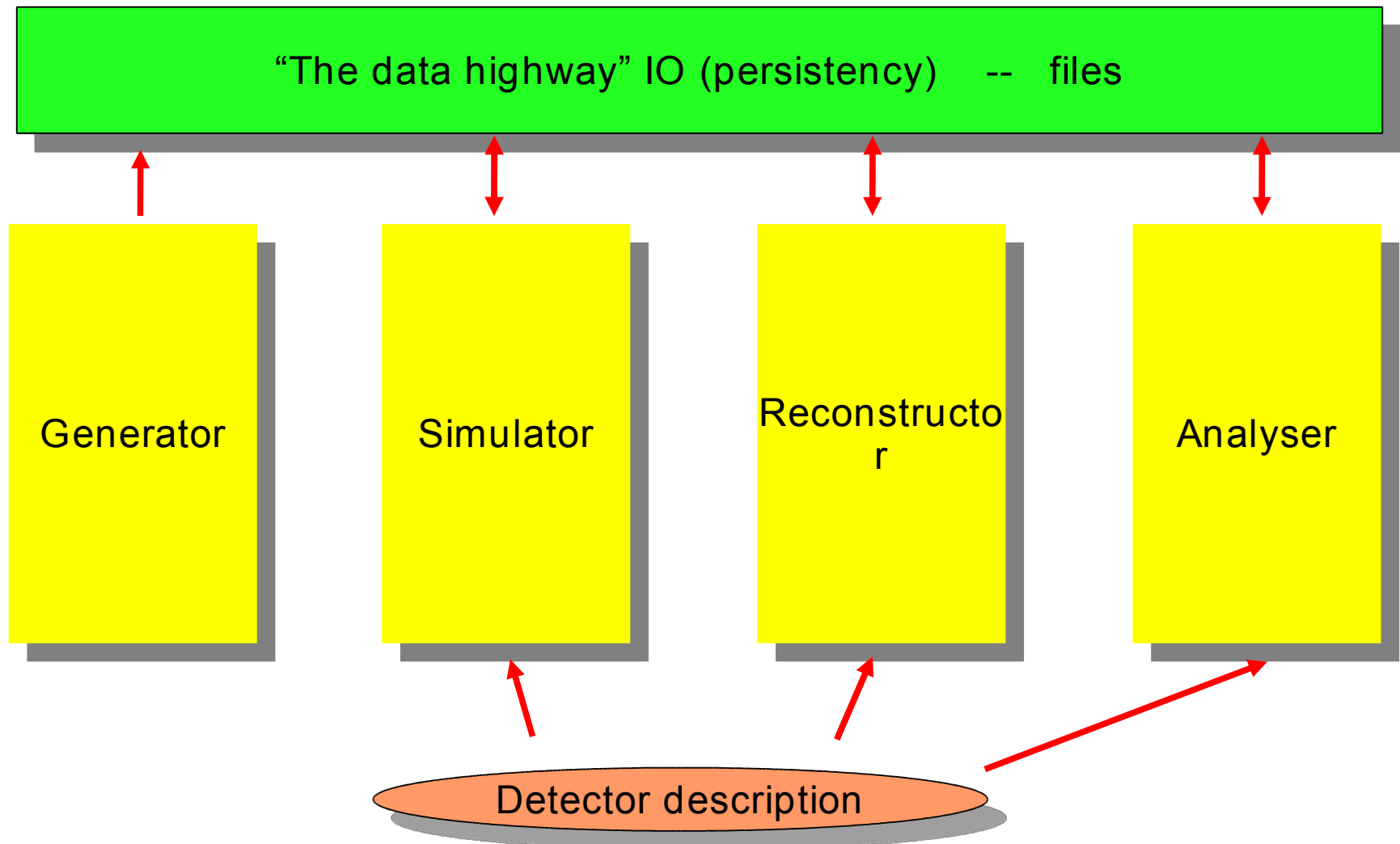
The mission

- Coordinate the creation of appropriate simulation tools
- Coordinate the creation of appropriate reconstruction tools
- Provide a frame for the creation of appropriate analysis tools

The boundary conditions:

- System should be long lived
- Should be lightweight
- We are not a collaboration: commercial software is difficult (funding)
- Share across regions as much as possible
- Little to no person power available

The ingredients



Full simulation

- BRAHMS:
 - GEANT3/ f77 based
 - TESLA TDR detector updated for recent changes
 - Complete simulation (and reconstruction)
 - MOKKA:
 - GEANT4/ C++ based
 - TESLA TDR detector “more or less”
 - No reconstruction framework
- BRAHMS is still the most complete package, but
- MOKKA is quickly getting there, will soon replace BRAHMS SIM



The future of the simulator(s)

MOKKA is our main GEANT4 based full simulation environment

- GEANT4 based
- light weight, C++ code
- geometry via mysql and C++ drivers

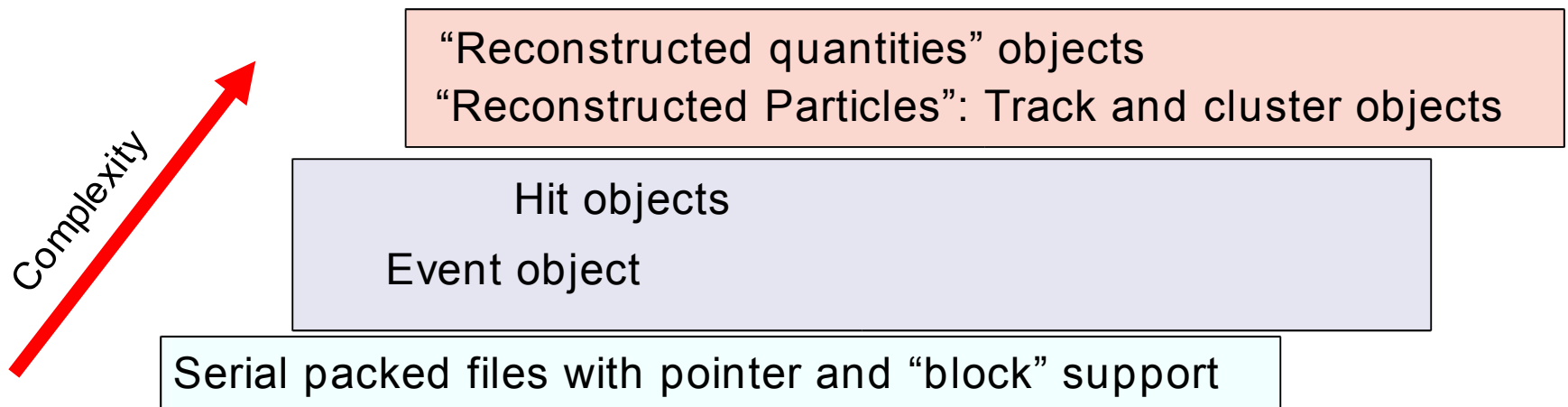
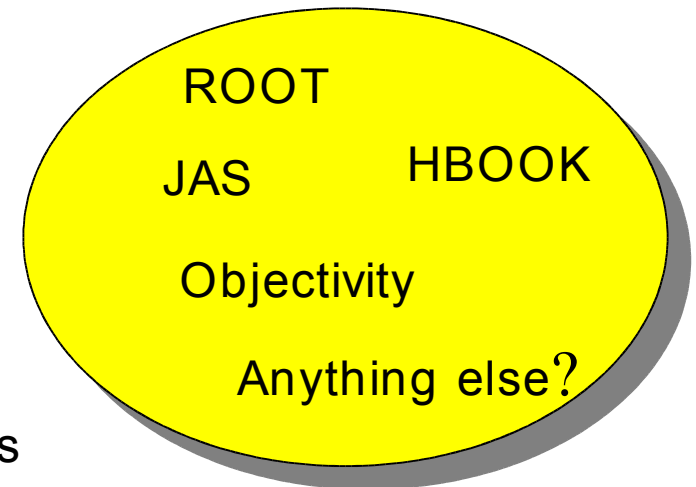
Our US colleagues are evaluating MOKKA to use it as a base for their GEANT4 simulation environment.

MOKKA developments:

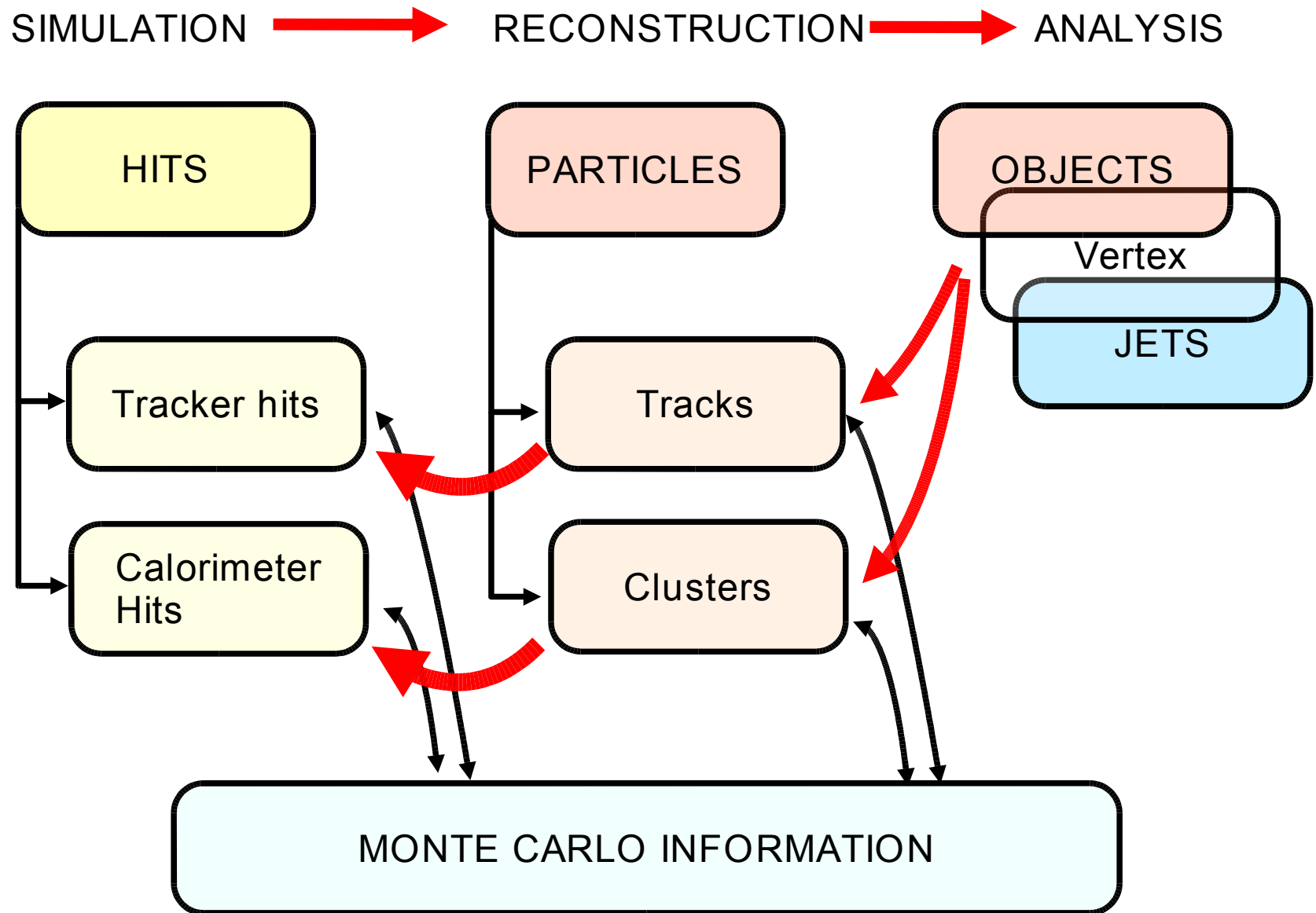
- Improve the detector models
- allow for more flexible system: concept of user plugins
- Watch closely CERN geometry developments (GDML)

The data highway: LCIO

- Need definition of a data model:
 - ➔ What is a hit
 - ➔ What is a track
 - ➔ What is a calorimeter cluster
 - ➔ etc.
- Need a common way to store (“persist”) objects
- **LCIO**: a simple data model with underlying persistency system:



LCIO: LC persistency framework



LCIO: Status

- Developed in collaboration between SLAC / DESY / LLR (France)
- Common data model / persistency framework for LC studies
- Simple API to store and retrieve data
 - Same API in C++, Java (and Fortran)
 - Simple underlying IO format (SIO): can be changed easily at a later time

Status:

- Development started December 2002
- First public pre-release in March
- First public production release for Montpellier: LCIO 1.0
 - Full C++ implementation
 - Full Java implementation
 - Full Fortran implementation
 - Hit based data model “fully” defined, reconstructed objects under discussion

LCIO: Implementation

- LCIO interface exists for

- MOKKA
- BRAHMS

Write *.slcio files

Simple Icio browser in JAS3:

The screenshot shows the LCIO Event browser interface. The left pane displays a tree view of the event structure under 'DataSets' > 'panpyttbar-0-500.slcio'. The right pane shows a table of MCParticle data for 'Run:0 Event: 1'. The table has columns for N, Type, Status, Parent, PX, PY, PZ, and Mass. The status column contains truncated text 'Docum...'. The bottom status bar indicates 'Analyzed 1 records in 430ms' and '4.13/6.67MB'.

N	Type	Status	Parent	PX	PY	PZ	Mass
0	11	Docum...		0	0	250.00	0
1	-11	Docum...		0	0	-250.00	0
2	11	Docum...	0	0	0	250.50	0
3	-11	Docum...	1	0	0	-249.21	0
4	6	Docum...	2,3	-144.68	4.9229	102.32	177.29
5	-6	Docum...	2,3	144.68	-4.9229	-101.03	175.58
6	5	Docum...	4	-142.00	26.531	77.708	4.8000
7	24	Docum...	4	-2.6814	-21.609	24.613	80.216
8	-5	Docum...	5	53.262	-2.7891	-116.88	4.8000
9	-24	Docum...	5	91.424	-2.1338	15.857	76.864
10	-1	Docum...	7	18.556	25.386	7.2394	0.33000
11	2	Docum...	7	-21.238	-46.995	17.374	0.33000
12	15	Docum...	9	8.1708	5.2916	33.669	1.7770
13	16	Docum...	9	82.252	7.4254	17.812	1.0772

Similar functionality exists in C++ (examples in distribution)

Reconstruction

- BRAHMS/ f77 based reconstruction:
 - Complete and sophisticated tracking
 - Particle flow reconstruction package
 - Tools (n-tuple for analysis, interface to main packages like ZVTOP, ...)
- OO world:
 - No coherent reconstruction frame yet
 - LCIO allows using f77 based reconstruction package on MOKKA output (REPLIC, BRAHMS reco to be released this week)

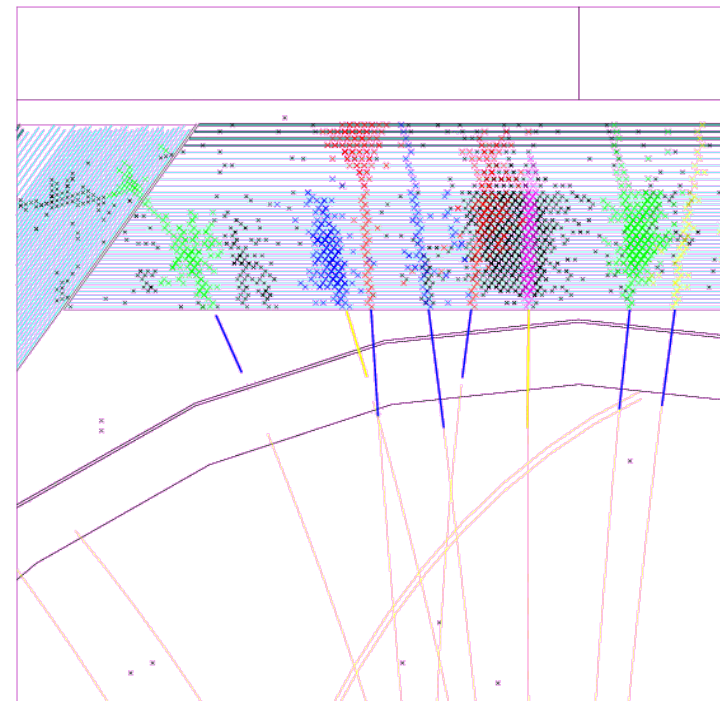
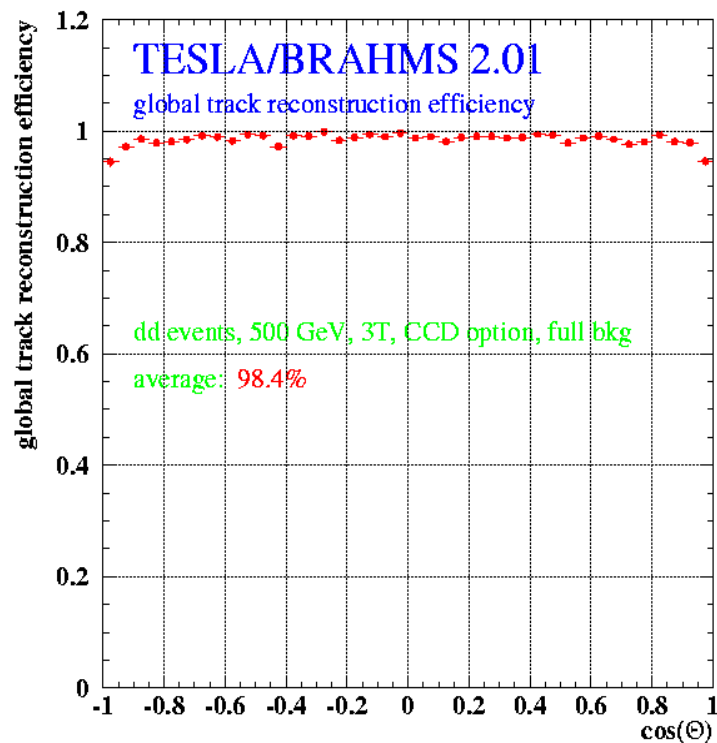
We need to move fast towards a OO based reconstruction framework, to enable reconstruction program developments!

Reconstruction

Status of reconstruction packages:

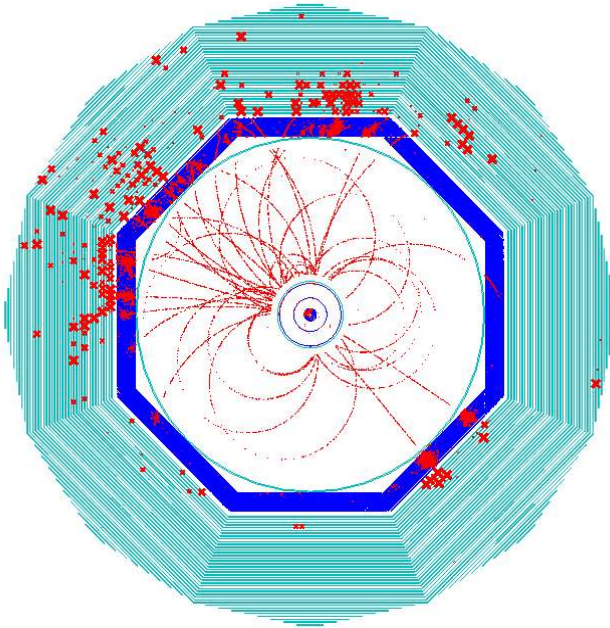
BRAHMS:

- sophisticated and complete reconstruction software available
- OO based: no reconstruction tools available at the moment

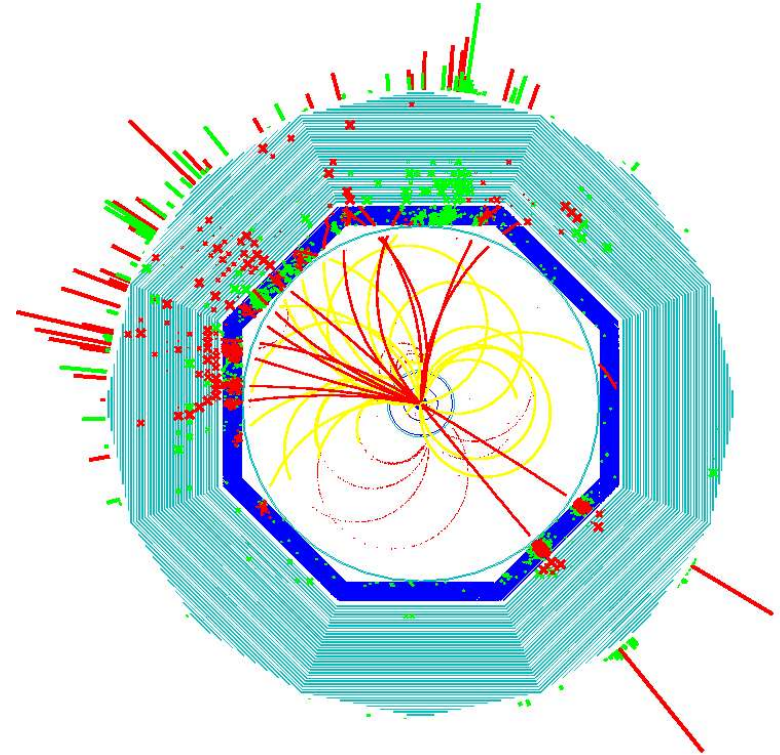


Reconstruction

Hits simulated in detector (BRAHMS)



Tracks and Pflow objects reconstructed (BRAHMS reco)



Plots Karsten Buesser

The Plan

- Develop a plain C++ reconstruction framework
 - ➔ LCIO as data model
 - ➔ Possibly CGA as geometry access model
 - ➔ Very simple interface, no fancy interactive environment for a start
 - ➔ Multi language support is no problem (JAVA ...)

Use LCIO ROOT
LCIO JAS

to provide a simple user interaction with the reconstruction

At this stage:

remain independent of any particular environment (root, JAS, PAW, ...)
be open for future developments
be light-weight (minimise the number of libraries the user needs to

install)

.... but we are still far from this goal...

Fast Simulation

- SIMDET: fast, parametrised Monte Carlo

NEW: interface to used track based ZVTO P in SIMDET
improvements to parametrisations

- SGV: fast, semi-parametrised Monte Carlo (produces hits)

Our US colleagues are developing a similar system

NEW: interface to ZVTOP in SGV

At the moment, fast simulations work, are producing physics results
but
we have no project for a modern fast simulator

Software: Outlook

Simulation:

- Converge towards GEANT4 based MOKKA simulation
- program should become more flexible and user friendly
- Close collaboration with our US colleagues on simulation established

IO:

- LC specific persistency scheme and data model established
- Interface to C++, JAVA and Fortran exists
- Common development with our US colleagues

Reconstruction:

- Next big project
- Digitisation and reconstruction “complete” in BRAHMS
- Much effort needed in OO framework: the next project

Towards a data challenge

Software environment: see previous slides

Access to data:

- Need transparent and flexible access system
- Data volume small compared to LHC, but still significant

The plan:

- User interface/ interaction: use the GRID computing model and software

GLOBUS authentication manager

- Storage manager: dCache (FNAL and DESY, integrated into GRID)

LC Data depository

- Database interface to data stored under dCache at DESY

File Edit View Go Bookmarks Tools Window Help

http://www-flc.desy.de/mc/ Search

Home Bookmarks The Mozilla Organi... Latest Builds

Linear Collider MC Production Navigation Bar

[Search Run](#) [Enter new Run](#) [Administratate](#)

Runs matching your query:

Run Number	Category	MC Generator	Energy	Process	No. Ev.
5005	2-Fermion	Pythia6.136	500	e+e-->Z/gamma->top+top-	160000
5004	2-Fermion	Pythia6.136	500	e+e-->z/gamma-->tau+tau-	800000
5003	2-Fermion	Pythia6.136	500	e+e-->z/gamma-->mu+mu-	800000
5002	2-Fermion	Pythia6.136	500	e+e-->Z/gamma->e+e- (only s-channel)	800000
5001	2-Fermion	Pythia6.136	500	e+e-->z/gamma->qq	6800000

Show detailed information about:

Run Number:

Search

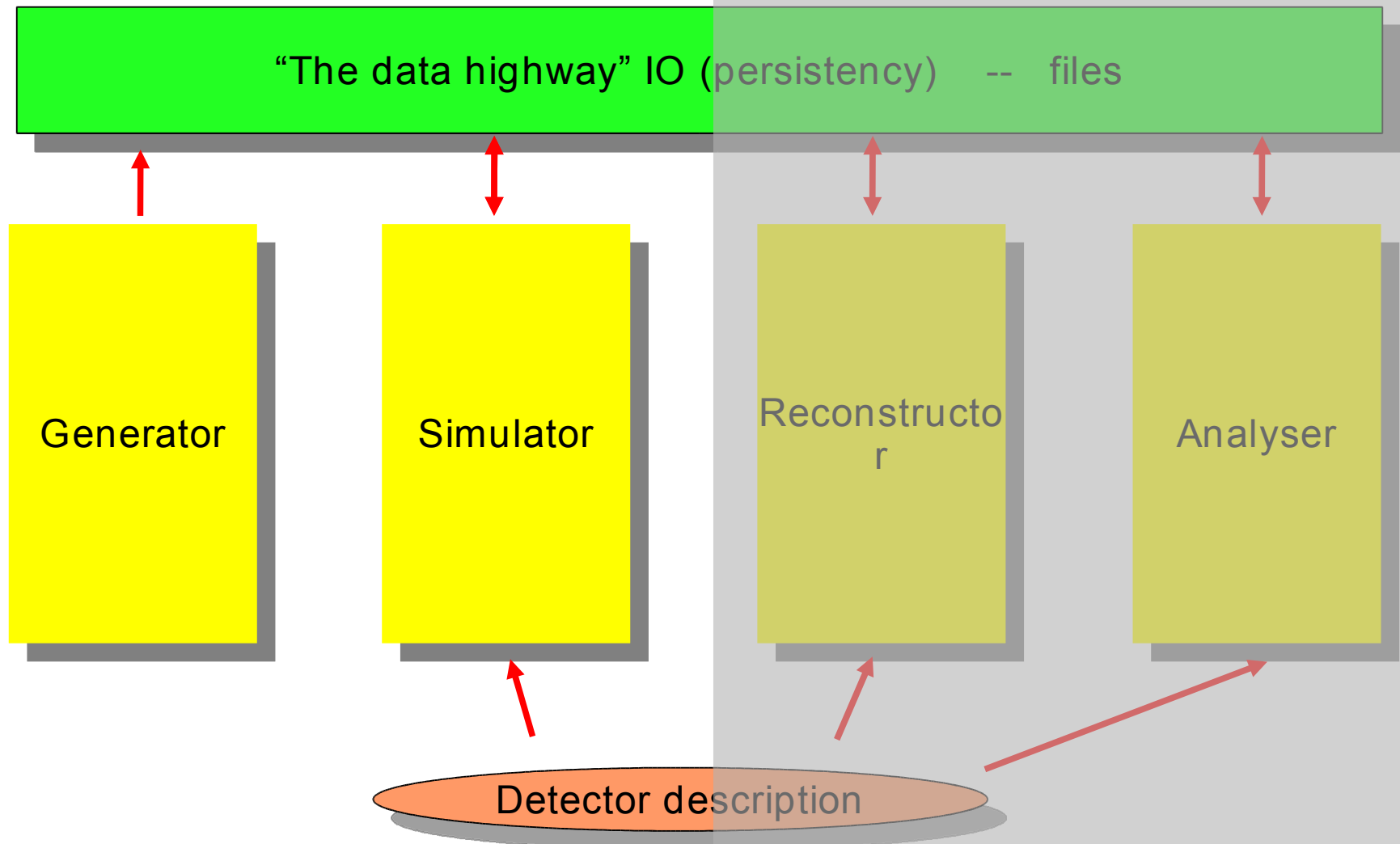
BACK

Philip Bechtie

Done

- Current problems: access from outside DESY

Summary



Summary

- Software tools present a significant challenge
- Progress on the simulation:
 - GEANT3 based simulation more stable and complete
 - GEANT4 based simulation becoming available
 - Common persistency scheme is reality
- Progress on the reconstruction:
 - BRAHMS based reconstruction exists
 - OO reconstruction still in the future
 - LCIO input exists
 - LCIO output being defined
- Goals:
 - GEANT4 based simulator
 - Simple reconstruction environment independent of particular framework
 - LCIO as basic data format and model to facilitate data exchange
 - Management of data sets through GRID like system