

Optimisation of the Ion Feedback in a GEM Setup for a TPC Readout

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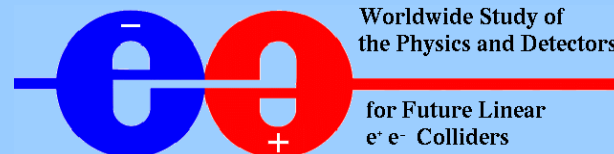
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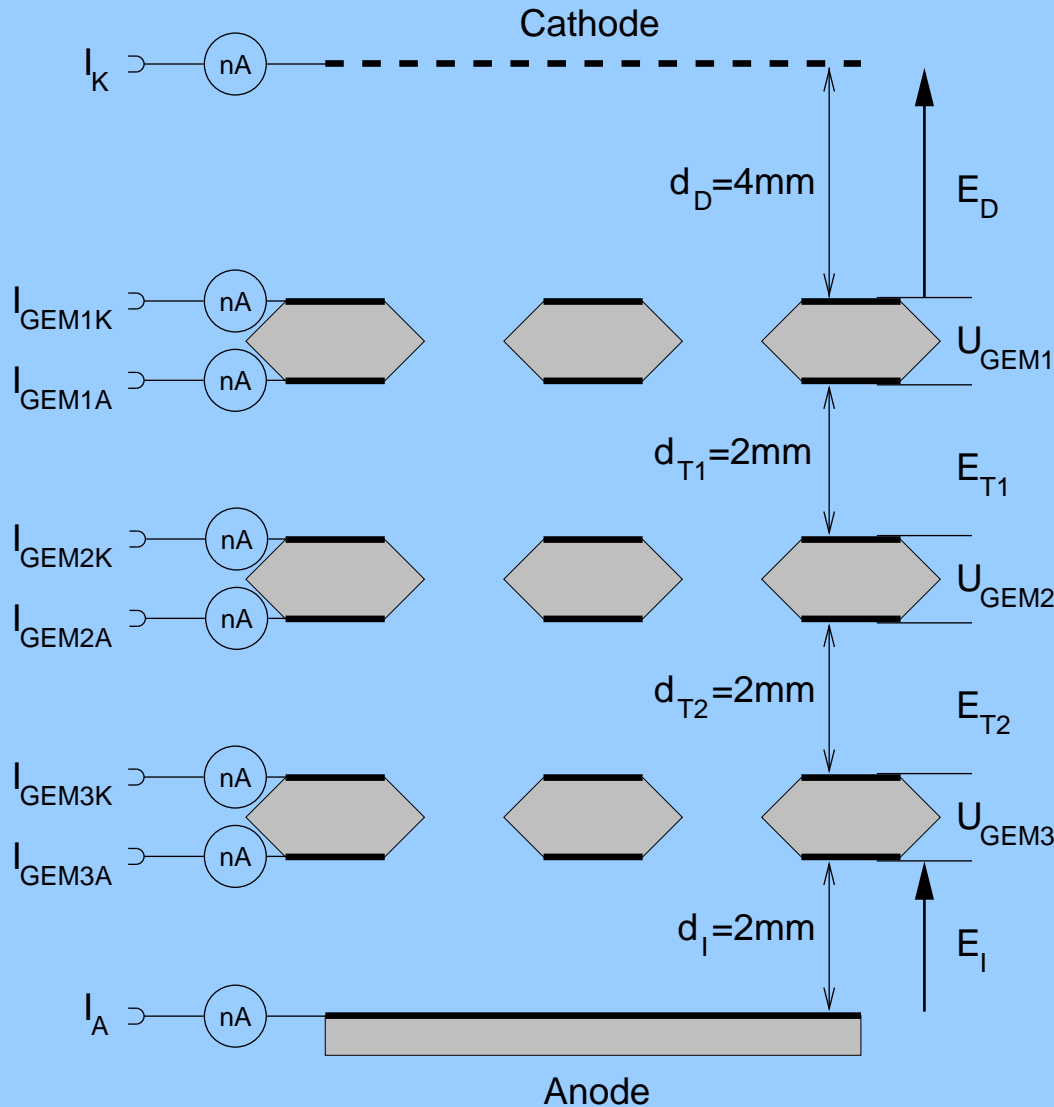


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- Parametrisation of the charge transfer coefficients
- Optimisation of chamber settings
- Current and track measurements with optimized settings
- Micro Hole Strip Plates (MHSPs)
- Conclusion and outlook



- 3 GEM voltages and 4 electric fields (**7 chamber parameters**) determine charge transfer
- By parametrisation of measured transfer coefficients, quantities like ion feedback (IF) and eff. gain (G_{eff}) can be calculated from a set of these 7 parameters

■ Collection Efficiency

$$C^{\pm} = \frac{N_{e^{-},I^{+}} \text{ collected into hole}}{N_{e^{-},I^{+}} \text{ before GEM}}$$

■ Extraction Efficiency

$$X^{\pm} = \frac{N_{e^{-},I^{+}} \text{ extracted from GEM}}{N_{e^{-},I^{+}} \text{ in GEM-hole}}$$

■ Gain (single GEM)

$$G = \frac{N_{e^{-}} \text{ in GEM-hole}}{N_{e^{-}} \text{ collected into hole}}$$

■ Effective Gain (multiple GEMs)

$$G_{eff} = \frac{I_{Anode}}{I_{primary}} = \prod_{i=1}^{N_{GEMs}} C_i G_i X_i$$

■ Relative Ion Feedback

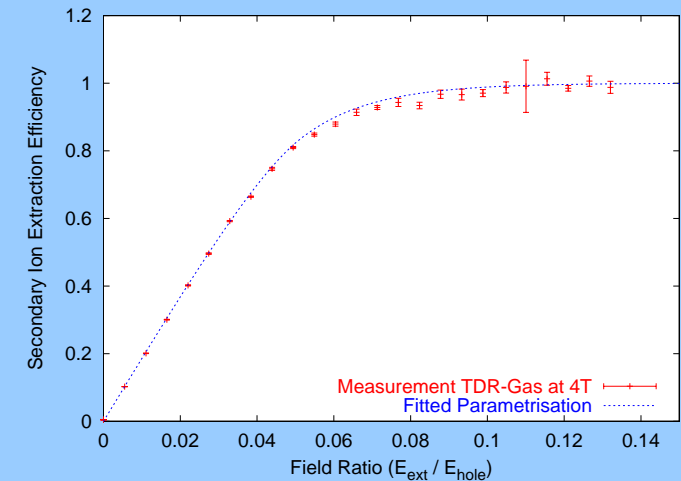
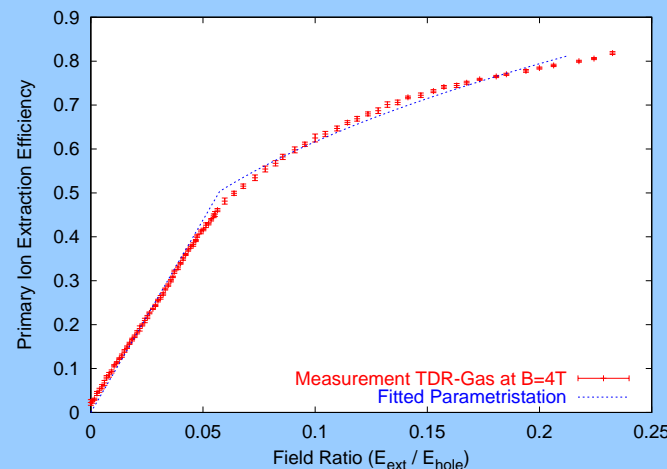
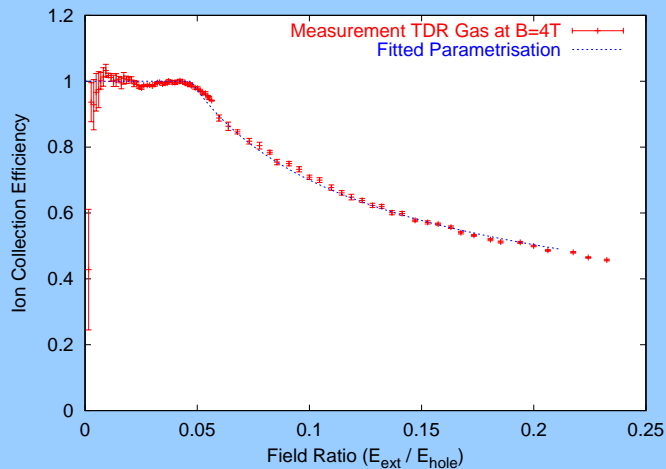
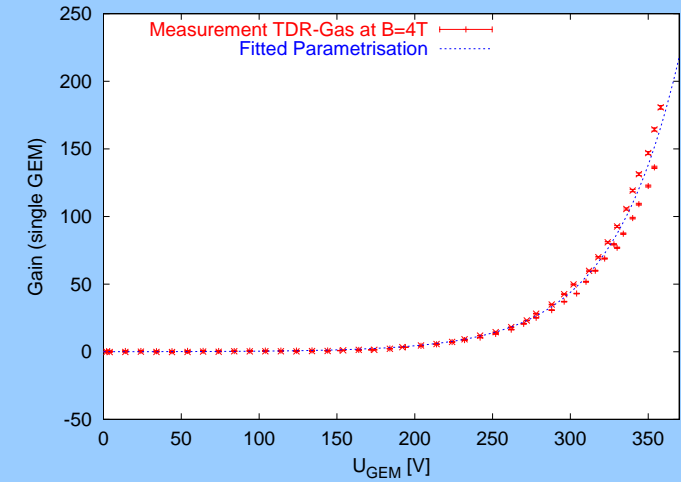
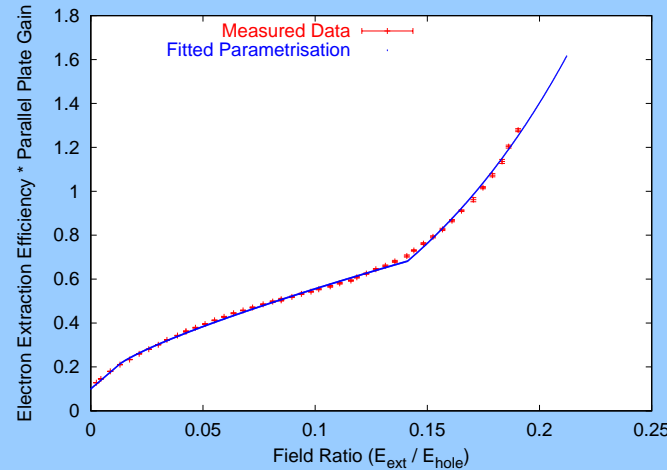
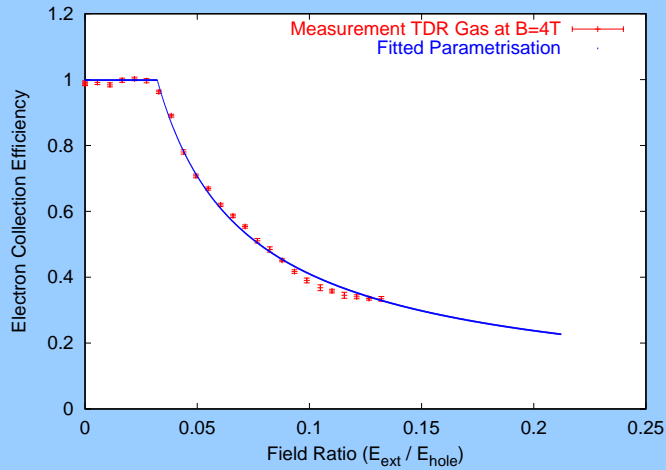
$$IF := \frac{I_{Cathode}}{I_{Anode}}$$

$$\Rightarrow G_{eff} \cdot IF = \frac{I_{Cathode}}{I_{primary}}$$

$$\Rightarrow I_{Cathode} \approx I_{primary} \Leftrightarrow IF = \frac{1}{G_{eff}}$$

For this Analysis: $G_{eff} = 10^4 \Rightarrow$ **Goal:** $IF = 10^{-4}$

Parametrisation of Transfer Coefficients

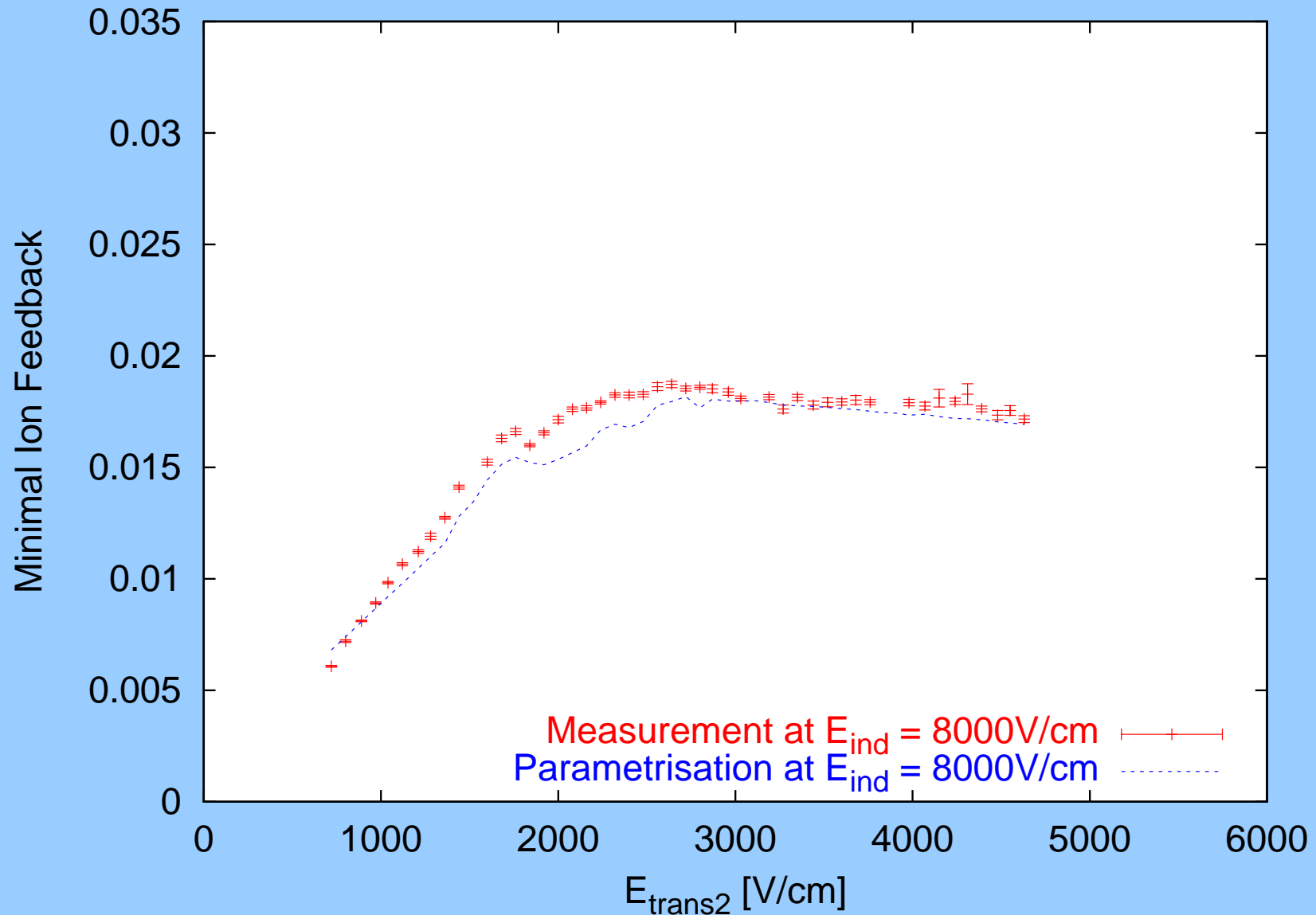


All Parametrisations for TDR Gas at B=4T!

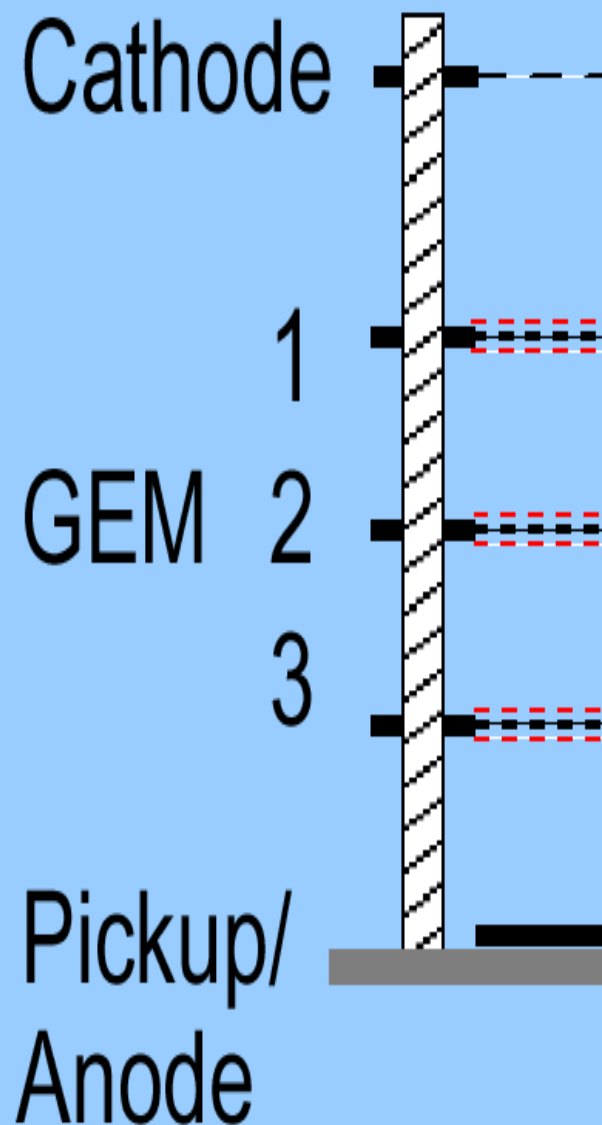
Brute Force:

- Parameter space spanned by five parameters (keeping drift and induction fields fixed) is **scanned** stepwise with a C program
- At every point the **calculated** ion feedback, effective gain and corresponding parameters are written to hard disk (root tree)
- Then the obtained data set can be **searched** for minima (e.g. with root macros)
- Optimized settings can then be written to a **script file** that controls our automated measurement application (**xtc**)

Example for one Parameter:

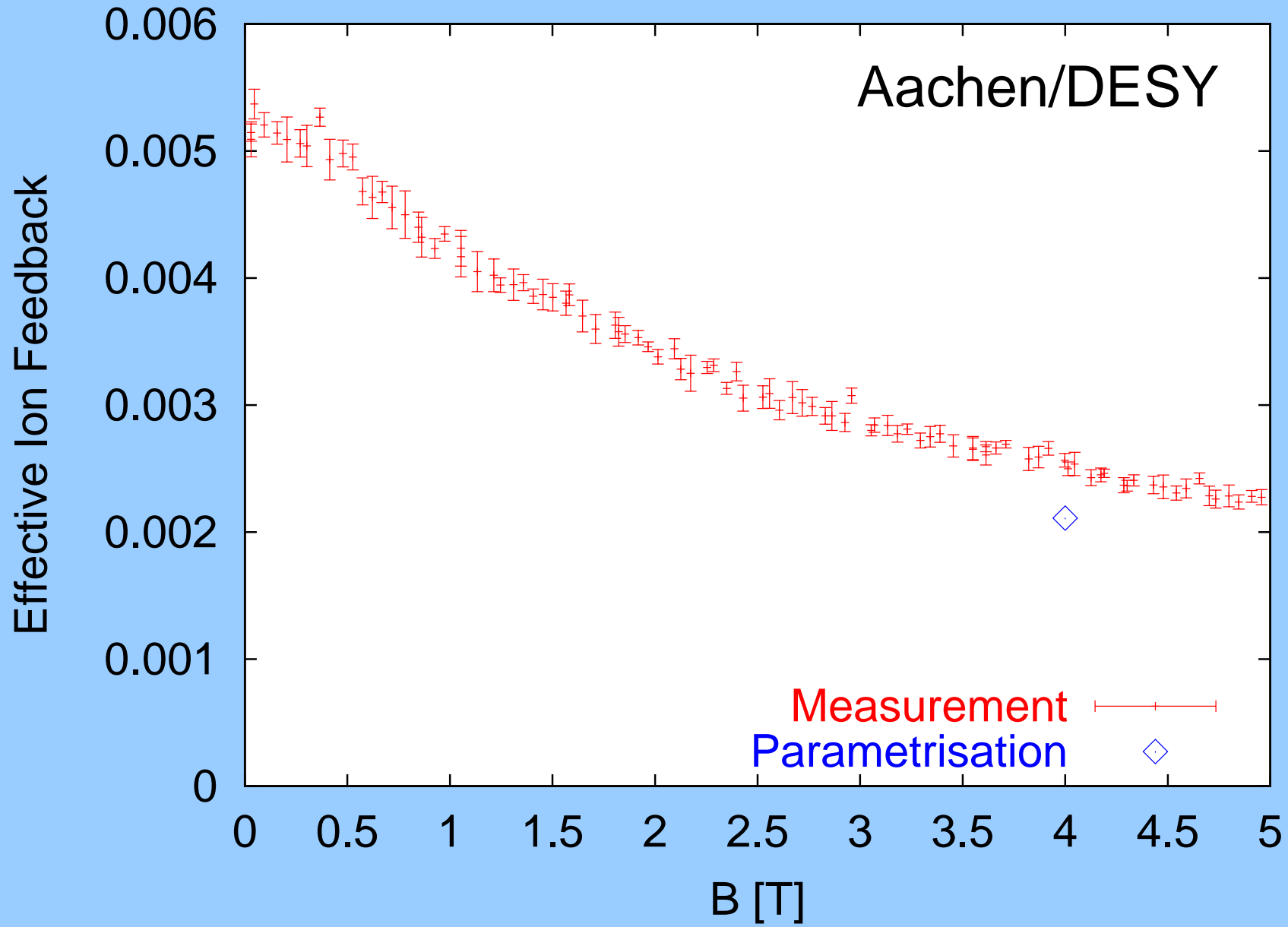


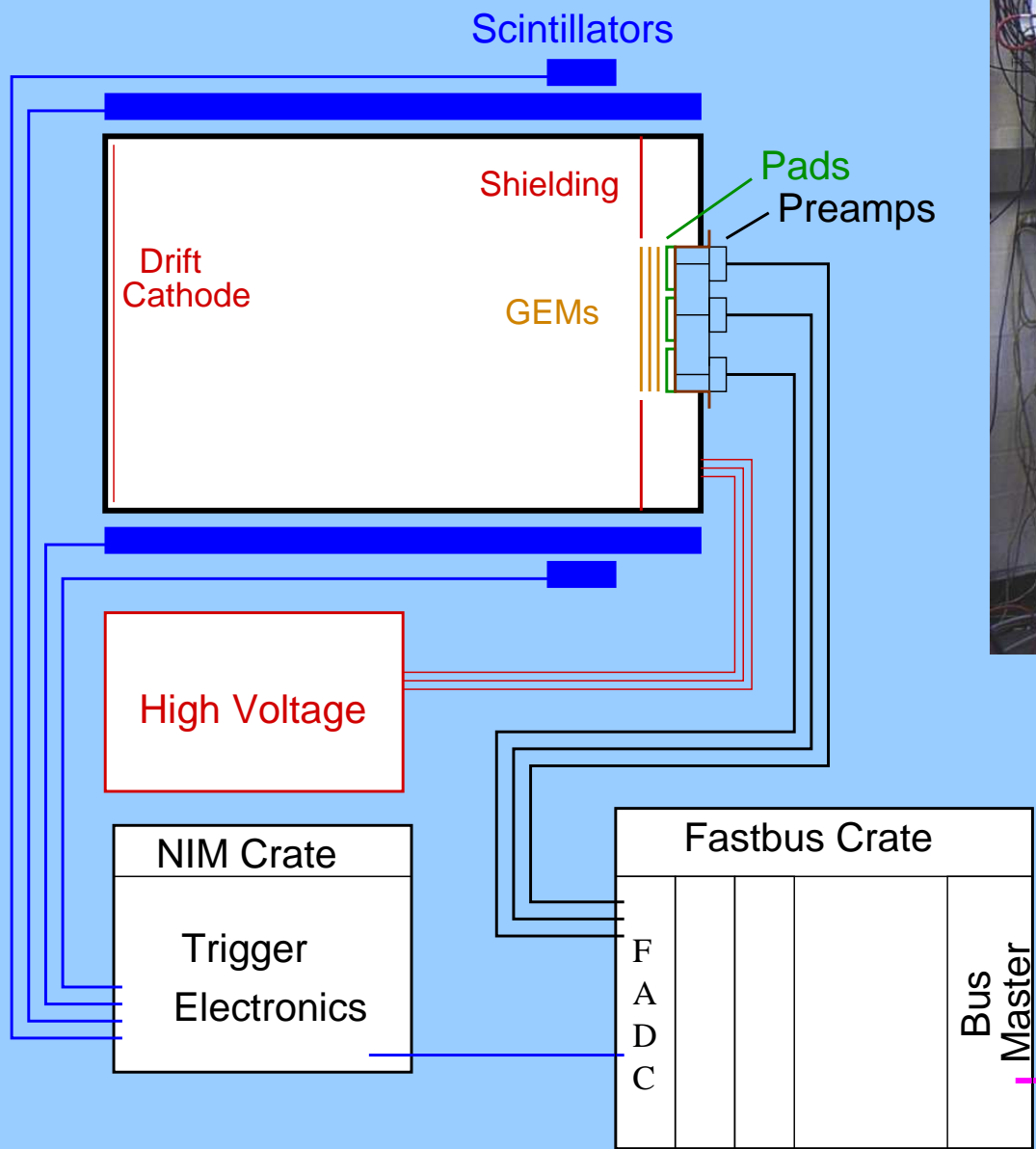
Parameter settings at minimal Ion Feedback



- E_{Drift} : fixed at 200 V/cm
- U_{GEM1} : **small** influence
- E_{Trans1} : **maximal**
- U_{GEM2} : **small** influence
- E_{Trans2} : **minimal**
- U_{GEM3} : **maximal**
- $E_{Induction}$: **maximal**

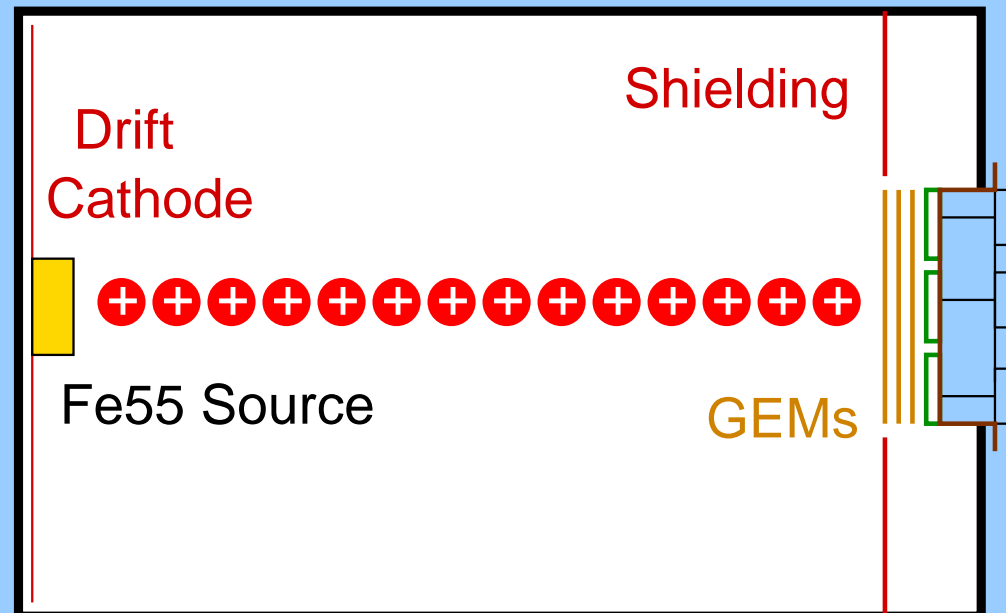
U_{GEM1} and U_{GEM2} allow variation of eff. Gain, without changing the IF.

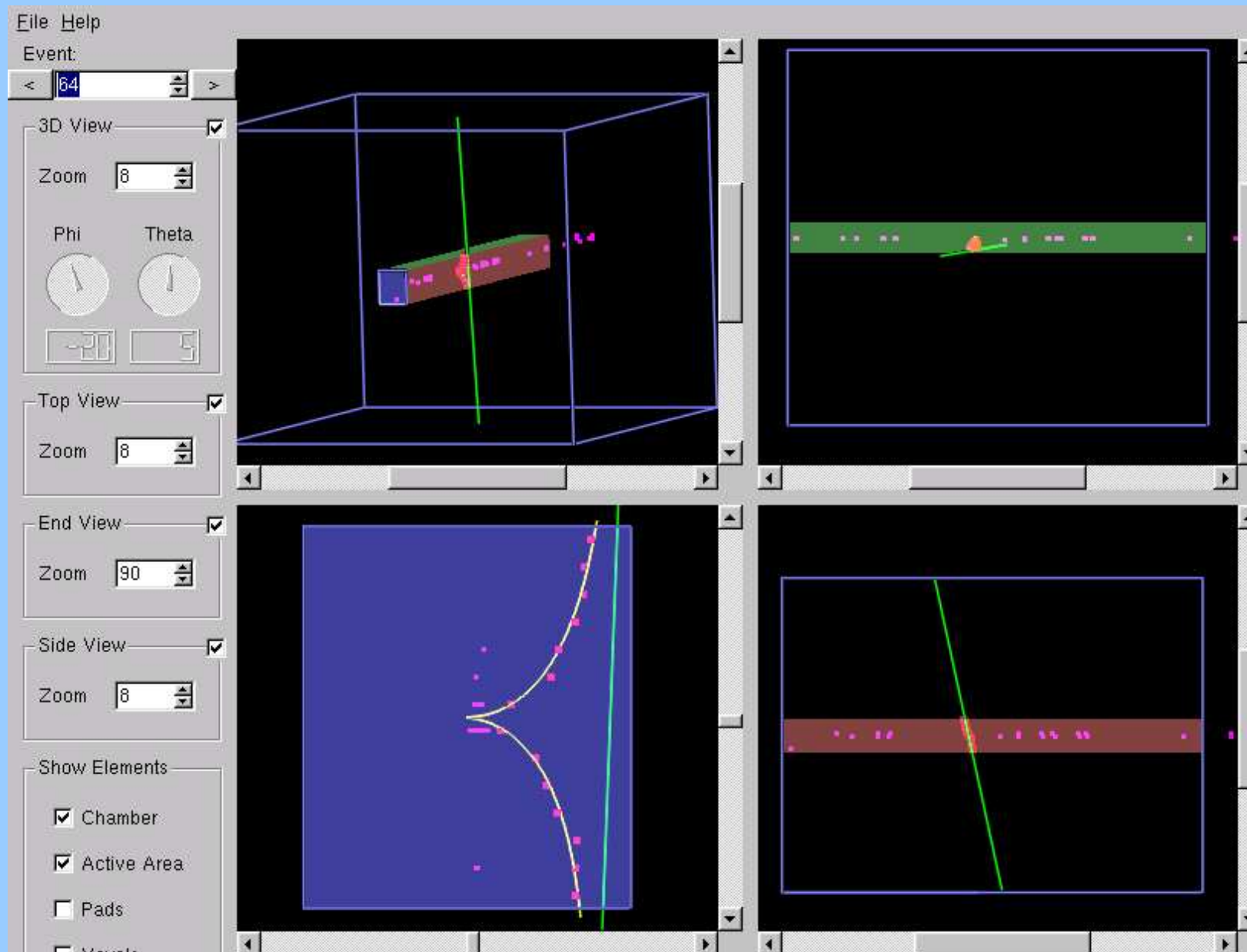


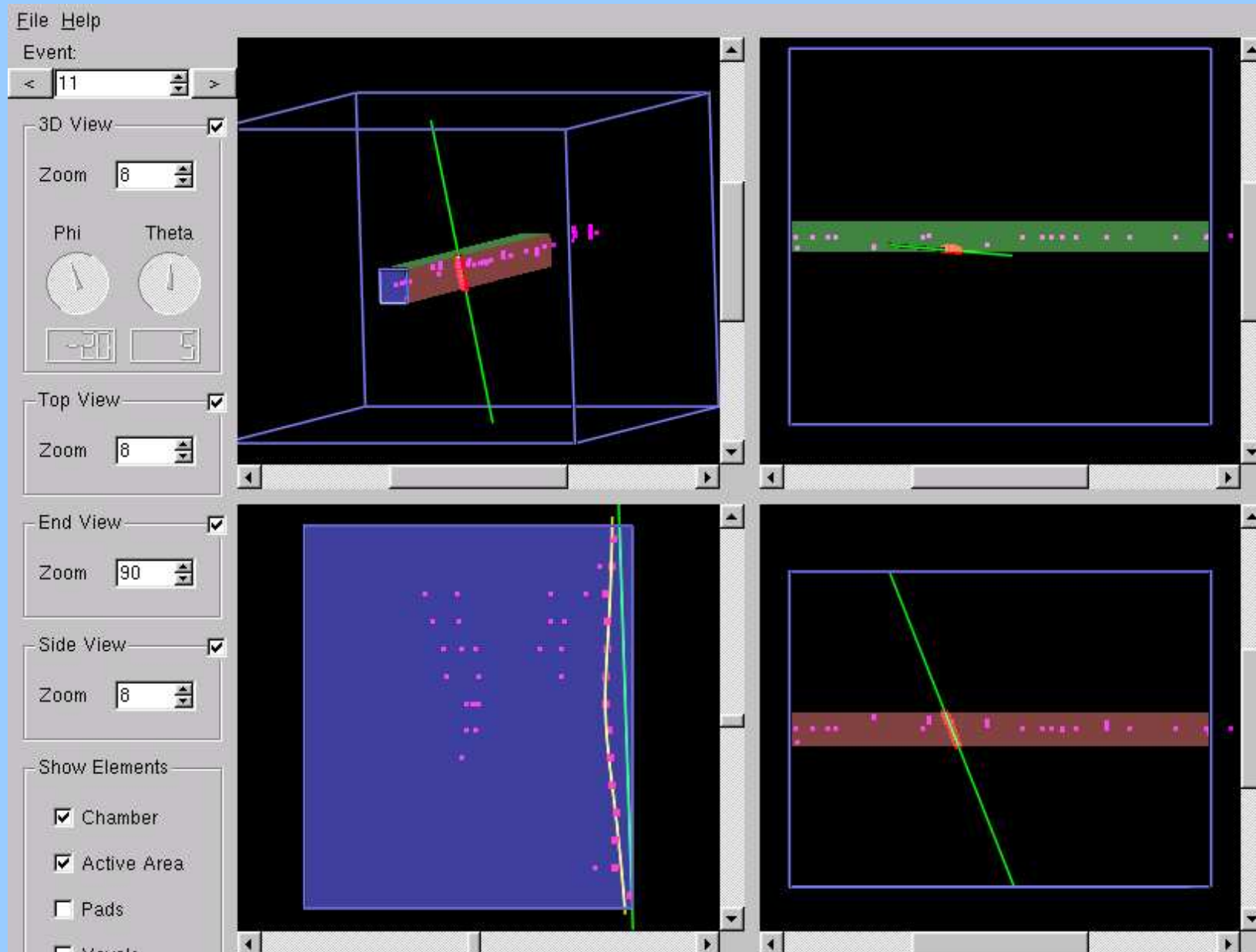


Application of a radioactive ^{55}Fe source at the cathode exactly opposite of the readout

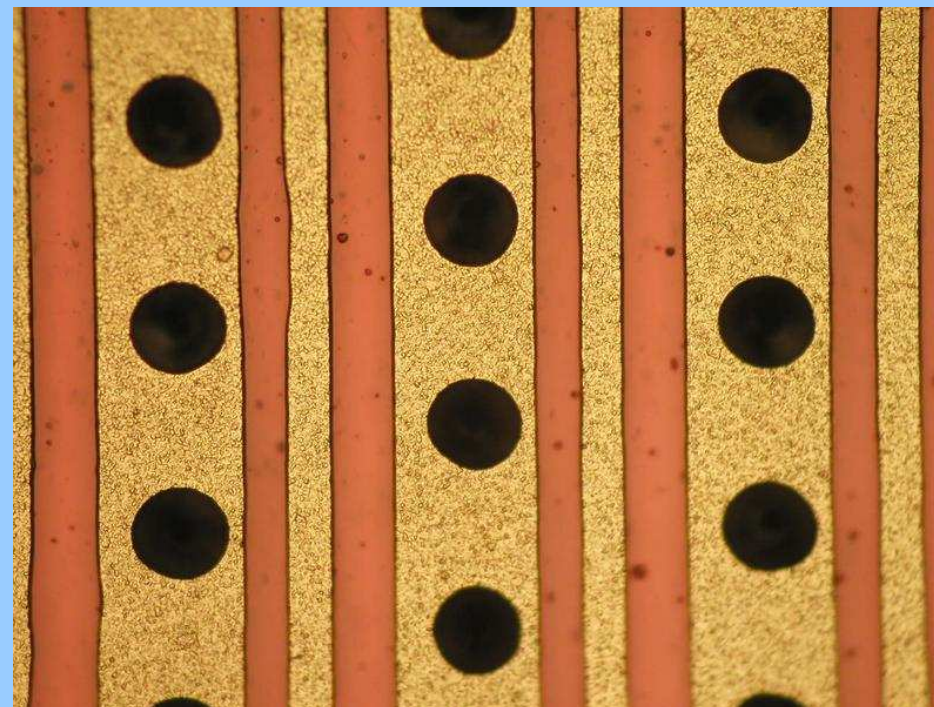
- Continuous creation of a large amount of electrons
- Forming of an ion tube between source and readout



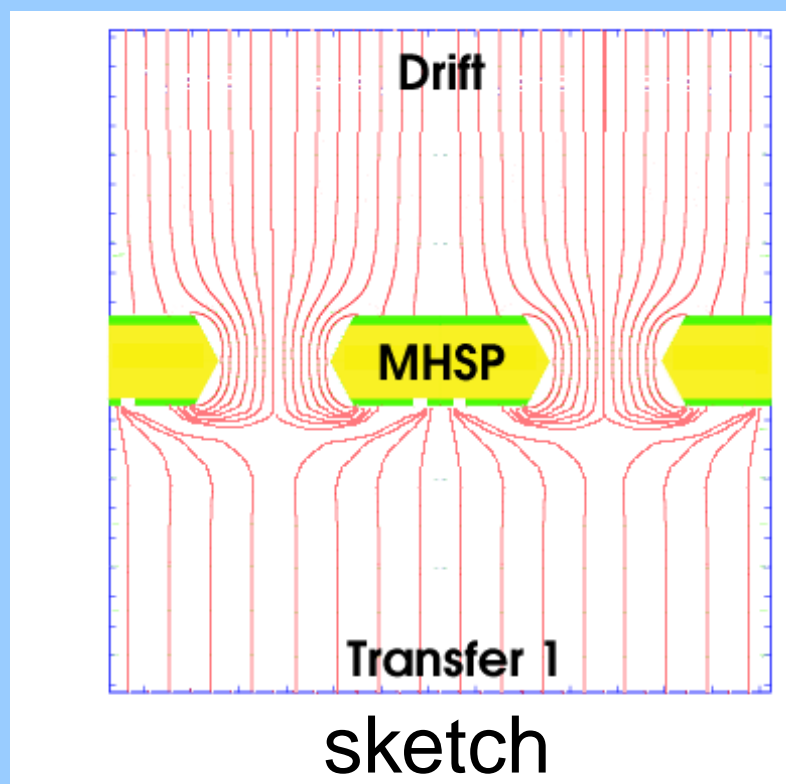


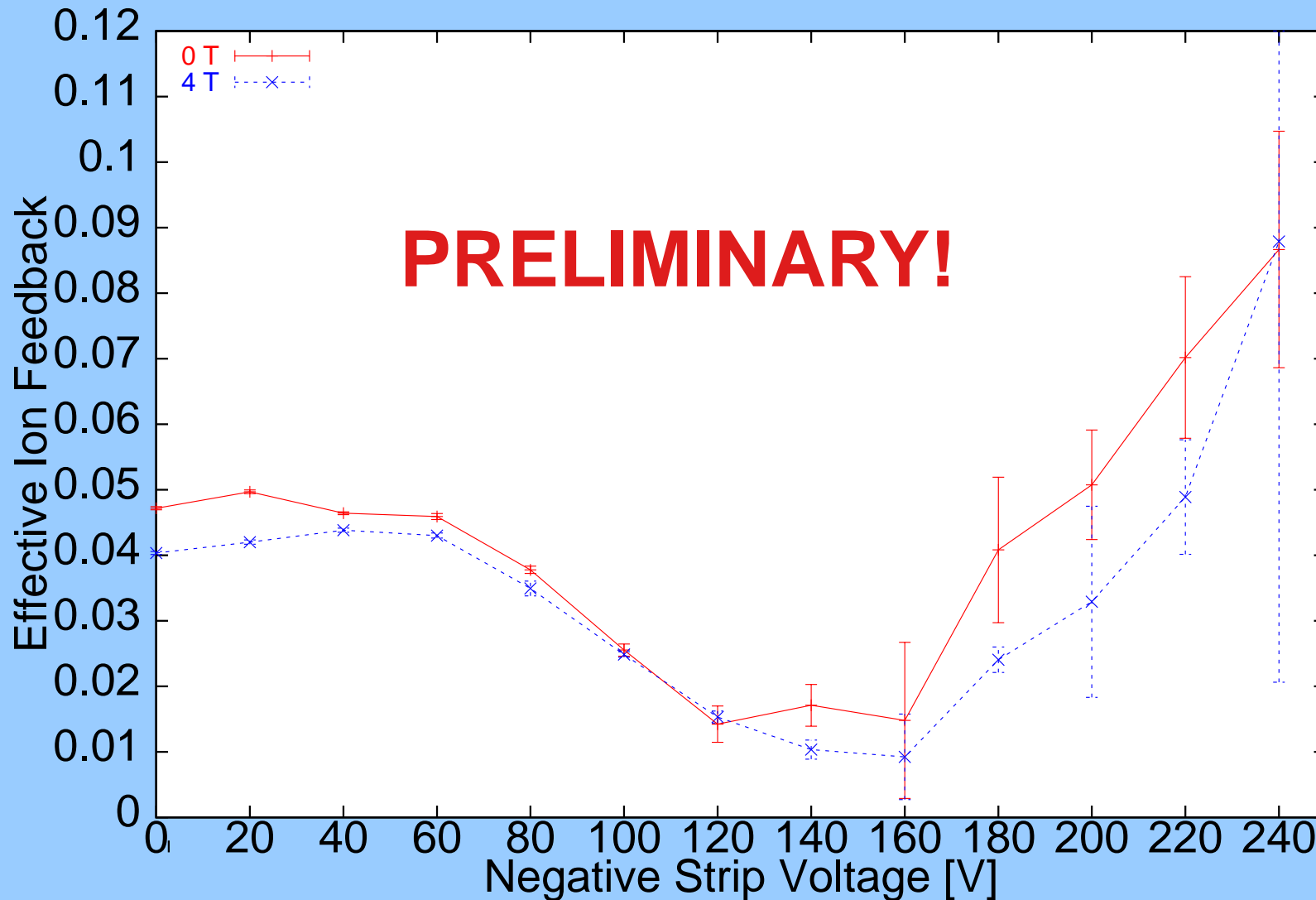


Replace the first GEM with a MHSP:



Idea: Negative strip voltage \Rightarrow Ions are collected on the strips, while electrons, due to diffusion, pass.





Not yet optimised setting!

Standard GEMs:

- The **qualitative influence** of the individual chamber parameters on the ion feedback is understood
- The minimum ion feedback depends strongly on the maximal reachable fields and GEM voltages
- A magnetic field of **4 T decreases ion feedback by a factor of ≈ 2**
- An ion feedback $\leq 2.5 \times 10^{-3}$ was achieved with TDR-gas and is **stable for ≥ 12 h** (stability test without magnetic field)
- Check how settings optimized for IF affect dE/dx etc.

MHSPs:

- MHSPs offer an additional possibility for IF suppression
- First results look promising, but till now no improvement over normal GEMs is achieved
- further studies of this new technology have to be done

The goal of $IF = 10^{-4}$ seems unrealistic!!

⇒ check if higher ion feedback or lower effective gain are acceptable

- line of backdrifting ions of infinitesimal thickness and infinite length $\Rightarrow \vec{E} = \frac{\alpha'}{r} \frac{\vec{r}}{r}$
- $v_{drift} \propto \vec{E}$ for small fields

Equation of motion for point:

$$\frac{d\vec{r}}{dt} = -M\vec{E} \quad M \text{ is electron mobility}$$

In polar coordinates: $\frac{dr}{dt} = -M\frac{\alpha'}{r}$

$$\Rightarrow r(t) = \sqrt{r_0^2 - \alpha t}$$

Start with straight line $x = ay + b$

in polar coordinates: $x = r \cos(\varphi)$ $y = r \sin(\varphi)$

$$r_0 = \frac{b}{\cos(\varphi_0) - a \sin(\varphi_0)}$$

φ does not change with time

$$\Rightarrow r(\varphi, t) = \sqrt{\frac{b^2}{(\cos(\varphi) - a \sin(\varphi))^2} - \alpha t}$$

