

The SAMPER project

(Semi-numerical **AMPL**itude **EvaluatoR**)

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- Next-to-Leading Order: LHC requirements
- Issues in Loop calculus: the semi-numerical approach
- First proof of the method: **Higgs + 4 partons** at one loop
- Future directions: multiplicity and complexity

Next-to-Leading Order: LHC requirements

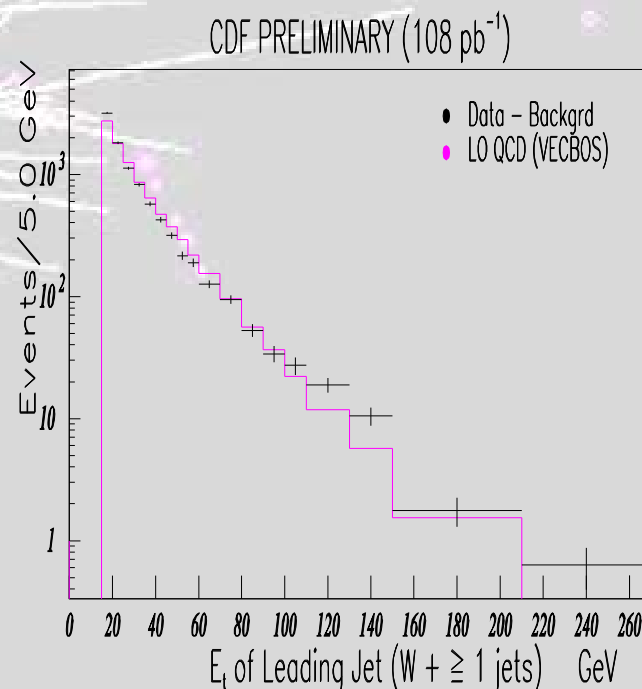
From the TEVATRON experiments we learned:

- Leading order works well for most *shape* predictions, but fail as far as cross section normalization goes.
- However, normalization fails.

At Next-to-Leading order:

- Understanding of the uncertainty on the shape of distribution.
- A first estimate of the cross section normalization. (i.e. a definition of the strong coupling constant)

Given the expected precision and types of searches at the LHC Next-to-Leading Order predictions are highly desirable.



Next-to-Leading Order: LHC requirements

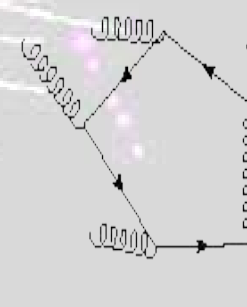
A start of the basic NLO needs for a serious phenomenology program at the LHC (from [Les Houches 2005](#)):

2. $PP \quad V V + \text{jet}$ (new physics and Higgs search background)
3. $PP \quad H + 2 \text{ jets}$ (Higgs production through vector boson fusion background)
4. $PP \quad T T\text{bar} + B B\text{bar}$ (Higgs plus top quark background)
5. $PP \quad V V + B B\text{bar}$ (new physics and Higgs search background)
6. $PP \quad V V + 2 \text{ jets}$ (Higgs search background)
7. $PP \quad V + 3 \text{ jets}$ (Generic background)
8. $PP \quad V V V$ (background to tri-lepton searches)
9. Etcetera

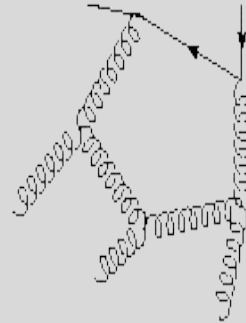
$$V \in \{W, Z, \gamma\}$$

Issues in Loop calculus

- At Leading order we have seen great progress through recursive techniques and algebraic computations.
- One loop calculations are still a “cottage industry”, much like Leading order ~20 years ago.
- To get anywhere near the priority list processes radical new techniques have to be introduced.
- Like at Leading order we want to reformulate the one loop calculation in an algorithm which can be numerically implemented.
- We will have to deal with analytical loop graphs: semi-numerical approach.



QGRAF-diagram 263



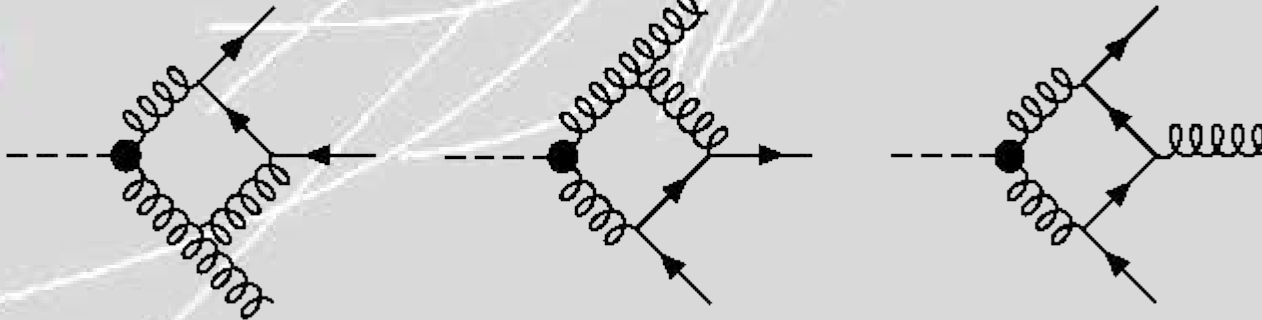
QGRAF-diagram 266

Figure 1. Sample Feynman diagrams contributing to the virtual corrections.

Issues in Loop calculus

- An one loop amplitude consists of a sum over Feynman diagrams (which can be generated using e.g. a fortran program like QGRAF):

$$\mathcal{M} = \sum_{i=1}^{N_D} \mathcal{A}_i$$



$c2(x1,x2)^*$
 $gg(a1,a2)*lp(k1+k2)^*$
 $c2(x3,x4)^*$
 $gg(a3,a4)*lp(-l1)^*$
 $c2(x5,x6)^*$
 $gg(a5,a6)*lp(l1-Q)^*$
 $c2(x7,x8)^*$
 $gg(a7,a8)*lp(-l1+k3)^*$
 $ggg(a-2,-k1,x-2,a-4,-k2,x-4,a1,k1+k2,x1)^*$
 $Hgg(a-1,Q,x-1,a3,-l1,x3,a5,l1-Q,x5)^*$
 $ggg(a-6,-k3,x-6,a4,l1,x4,a7,-l1+k3,x7)^*$
 $ggg(a2,-k1-k2,x2,a6,-l1+Q,x6,a8,l1-k3,x8);$

$G\ m47 = (+1)^*$
 $H(a-1)*g(a-2)*g(a-4)*g(a-6)^*$
 $c2(x1,x2)^*$
 $gg(a1,a2)*lp(k1+k3)^*$
 $c2(x3,x4)^*$
 $gg(a3,a4)*lp(-l1)^*$
 $c2(x5,x6)^*$
 $gg(a5,a6)*lp(l1-Q)^*$
 $c2(x7,x8)^*$
 $gg(a7,a8)*lp(-l1+k2)^*$
 $ggg(a-2,-k1,x-2,a-6,-k3,x-6,a1,k1+k3,x1)^*$
 $Hgg(a-1,Q,x-1,a3,-l1,x3,a5,l1-Q,x5)^*$
 $ggg(a-4,-k2,x-4,a4,l1,x4,a7,-l1+k2,x7)^*$
 $ggg(a2,-k1-k3,x2,a6,-l1+Q,x6,a8,l1-k2,x8);$

$G\ m48 = (+1)^*$
 $H(a-1)*g(a-2)*g(a-4)*g(a-6)^*$
 $c2(x1,x2)^*$
 $gg(a1,a2)*lp(k2+k3)^*$
 $c2(x3,x4)^*$
 $gg(a3,a4)*lp(-l1)^*$
 $c2(x5,x6)^*$
 $gg(a5,a6)*lp(l1-Q)^*$
 $c2(x7,x8)^*$
 $gg(a7,a8)*lp(-l1+k1)^*$
 $ggg(a-4,-k2,x-4,a-6,-k3,x-6,a1,k2+k3,x1)^*$
 $Hgg(a-1,Q,x-1,a3,-l1,x3,a5,l1-Q,x5)^*$
 $ggg(a-2,-k1,x-2,a4,l1,x4,a7,-l1+k1,x7)^*$
 $ggg(a2,-k2-k3,x2,a6,-l1+Q,x6,a8,l1-k1,x8);$

$G\ m49 = (+1)^*$
 $H(a-1)*g(a-2)*g(a-4)*g(a-6)^*$
 $c2(x1,x2)^*$
 $gg(a1,a2)*lp(-l1)^*$
 $c2(x3,x4)^*$
 $gg(a3,a4)*lp(l1-Q)^*$
 $c2(x5,x6)^*$
 $gg(a5,a6)*lp(-l1+k1)^*$
 $c2(x7,x8)^*$
 $gg(a7,a8)*lp(l1-Q+k2)^*$
 $Hgg(a-1,Q,x-1,a1,-l1,x1,a3,l1-Q,x3)^*$
 $ggg(a-2,-k1,x-2,a2,l1,x2,a5,-l1+k1,x5)^*$
 $ggg(a-4,-k2,x-4,a4,-l1+Q,x4,a7,l1-Q+k2,x7)^*$

Issues in Loop calculus

- Next each Feynman diagram is factorized in tensor integrals and kinematic factors using FORM

$$\mathcal{A}(p_1, \dots, p_N; \varepsilon_1, \dots, \varepsilon_N) = \sum_{M=0}^N K_{\mu_1 \dots \mu_M}(p_1, \dots, p_N; \varepsilon_1, \dots, \varepsilon_N) I^{\mu_1 \dots \mu_M}(D; q_1, \dots, q_N)$$

$$I^{\mu_1 \dots \mu_M}(D; q_1, \dots, q_N) \equiv \int \frac{d^D l}{i\pi^{D/2}} \frac{l^{\mu_1} \dots l^{\mu_M}}{d_1 d_2 \dots d_N}, \quad d_i \equiv (l + q_i)^2, \quad q_i \equiv \sum_{j=1}^i p_j$$

```

if (count(L,1)==5);
ld L(a0?)*L(a1?)*L(a2?)*L(a3?)*L(a4?)*I'N'(D?,?q)=
  1/4*((d_(a0,a1)*d_(a2,a3)+d_(a0,a2)*d_(a1,a3)+d_(a0,a3)*d_(a1,a2))*P
(a4,?q)
  +(d_(a0,a1)*d_(a2,a4)+d_(a0,a2)*d_(a1,a4)+d_(a0,a4)*d_(a1,a2))*P
(a3,?q)
  +(d_(a0,a1)*d_(a3,a4)+d_(a0,a3)*d_(a1,a4)+d_(a0,a4)*d_(a1,a3))*P
(a2,?q)
  +(d_(a0,a2)*d_(a3,a4)+d_(a0,a3)*d_(a2,a4)+d_(a0,a4)*d_(a2,a3))*P
(a1,?q)
  +(d_(a1,a2)*d_(a3,a4)+d_(a1,a3)*d_(a2,a4)+d_(a1,a4)*d_(a2,a3))*P
(a0,?q))*I'N'(D+4,?q)
-1/2*(d_(a0,a1)*P(a2,?q)*P(a3,?q)*P(a4,?q)+d_(a0,a2)*P(a1,?q)*P(a3,?q)*P

```

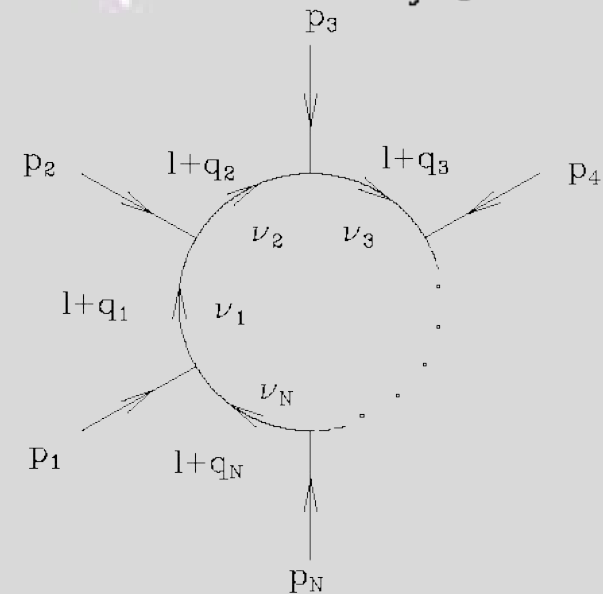


FIG. 1: The generic N-point loop graph.

Issues in Loop calculus

- We can evaluate the kinematic factors numerically
- The tensor integrals have to be further processed using a decomposition

$$\begin{aligned}
 I^{\mu_1 \dots \mu_M}(D; q_1, \dots, q_N) &= \sum_{i_1 i_2 \dots i_M}^N a_{i_1 i_2 \dots i_M} q_{i_1}^{\mu_1} q_{i_2}^{\mu_2} \dots q_{i_M}^{\mu_M} \\
 &+ \sum_{i_3 i_4 \dots i_M}^N a_{00 i_3 i_4 \dots i_M} g^{\mu_1 \mu_2} q_{i_3}^{\mu_3} q_{i_4}^{\mu_4} \dots q_{i_M}^{\mu_M} \\
 &+ \sum_{i_5 i_6 \dots i_M}^N a_{0000 i_5 \dots i_M} g^{\mu_1 \mu_2} g^{\mu_3 \mu_4} q_{i_5}^{\mu_5} q_{i_6}^{\mu_6} \dots q_{i_M}^{\mu_M} \\
 &+ \dots,
 \end{aligned}$$

- The coefficients are proportional to generalized scalar integrals (Davydychev, 1991)

$$I(D; \{q_1, \nu_1\}, \dots, \{q_N, \nu_N\}) \equiv I(D; \nu_1, \nu_2, \dots, \nu_N) \equiv \int \frac{d^D l}{i\pi^{D/2}} \frac{1}{d_1^{\nu_1} d_2^{\nu_2} \dots d_N^{\nu_N}}$$

Issues in Loop calculus

- Example:

$$\begin{aligned}
 I^{\mu_1 \mu_2}(D; q_1, \dots, q_N) &= -\frac{1}{2} I(D+2; \{1\}_{k=1}^N) g^{\mu_1 \mu_2} \\
 &+ \sum_{P\{\mu_1, \mu_2\}}^{2!} \sum_{i_1 \leq i_2}^N I(D+4; \{1 + \delta_{i_1 k} + \delta_{i_2 k}\}_{k=1}^N) q_{i_1}^{\mu_1} q_{i_2}^{\mu_2} \\
 &= -\frac{1}{2} I(D+2; 1, 1, 1, \dots, 1) g^{\mu_1 \mu_2} \\
 &+ 2 I(D+4; 3, 1, 1, \dots, 1) q_1^{\mu_1} q_1^{\mu_2} \\
 &+ I(D+4; 2, 2, 1, \dots, 1) (q_1^{\mu_1} q_2^{\mu_2} + q_1^{\mu_2} q_2^{\mu_1}) \\
 &+ \dots,
 \end{aligned}$$

- This can be implemented numerically *provided* we can evaluate the generalized scalar integrals numerically.

```

template <class T1, class T2, typename Y> Y Contract(Tensor<T1> v1, Tensor<T2> v2) {
    int rank=v1.rank;
    assert(v2.rank==rank);
    Y result=0.0;
    double g[4]={1.0,-1.0,-1.0,-1.0};
    if (rank==0) result=v1.t0*v2.t0;
    else { for (int i1=0; i1<4; i1++) {

```

Issues in Loop calculus

- The generalized scalar integrals can be calculated recursively, e.g. (red line):

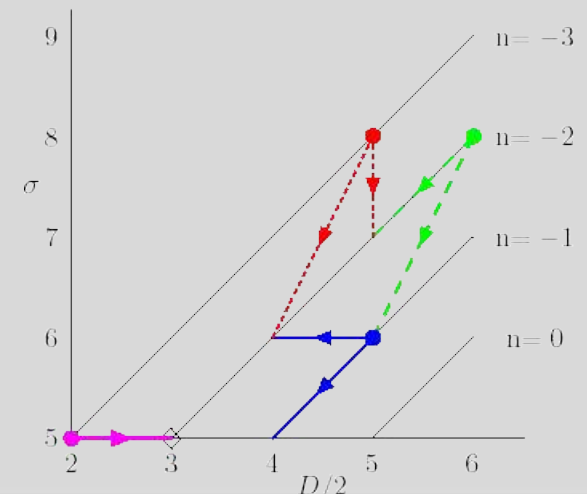
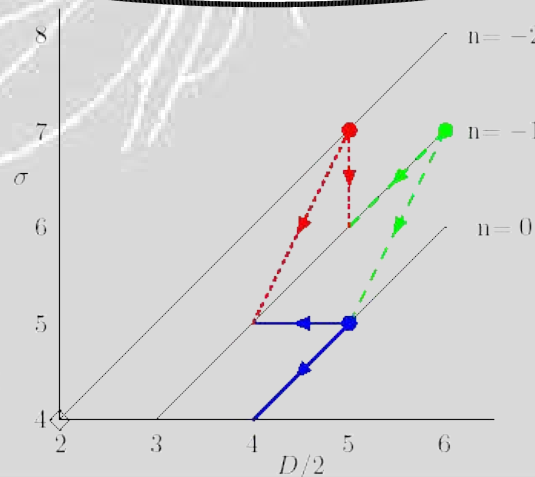
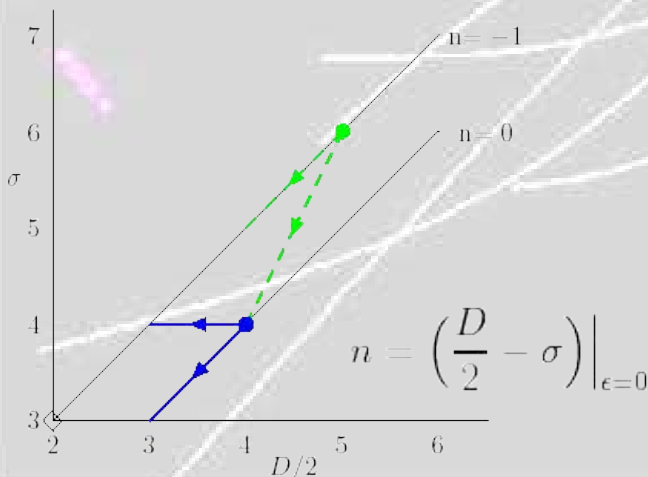
Based on integration by part techniques: Tkachov & Chetyrkin, 1981

$$(\nu_l - 1)I(D; \{\nu_k\}_{k=1}^N)$$

$$= -\frac{b_l}{B}I(D-2; \{\nu_k - \delta_{lk}\}_{k=1}^N) + \sum_{i=1}^N \left(\frac{b_l b_i}{B} - S_{li}^{-1} \right) I(D-2; \{\nu_k - \delta_{ik} - \delta_{lk}\}_{k=1}^N).$$

$$S_{ij} \equiv (q_i - q_j)^2 \quad \sigma \equiv \sum_{i=1}^N \nu_i; \quad b_i \equiv \sum_{j=1}^N S_{ij}^{-1}; \quad B \equiv \sum_{i=1}^N b_i = \sum_{i,j=1}^N S_{ij}^{-1}$$

Numerically calculable



Issues in Loop calculus

- We can setup a recursion algorithm which reduces all generalized scalar integrals to a few standard scalar integrals (which are known analytical)

Glover & Giele, 2004

- Example:

$$I_4(D = 4 - 2\epsilon; 1, 1, 1, 1, \{s_{12}, s_{23}, 0, p_2^2, p_3^2, p_4^2\}) = \frac{c_\Gamma}{(s_{23}s_{12} - p_2^2 p_4^2)} \\ \times \left[\frac{2}{\epsilon^2} \left((-s_{12})^{-\epsilon} + (-s_{23})^{-\epsilon} - (-p_2^2)^{-\epsilon} - (-p_3^2)^{-\epsilon} - (-p_4^2)^{-\epsilon} \right) \right. \\ \left. + \frac{1}{\epsilon^2} \left((-p_2^2)^{-\epsilon} (-p_3^2)^{-\epsilon} \right) / (-s_{23})^{-\epsilon} + \frac{1}{\epsilon^2} \left((-p_3^2)^{-\epsilon} (-p_4^2)^{-\epsilon} \right) / (-s_{12})^{-\epsilon} \right. \\ \left. - 2 \text{Li}_2 \left(1 - \frac{p_2^2}{s_{12}} \right) - 2 \text{Li}_2 \left(1 - \frac{p_4^2}{s_{23}} \right) + 2 \text{Li}_2 \left(1 - \frac{p_2^2 p_4^2}{s_{12} s_{23}} \right) \right] + \mathcal{O}(\epsilon)$$

Numerically calculable

Issues in Loop calculus

- This means we can completely evaluate the tensor loop integral numerical

$$\begin{aligned}
 I^{\mu_1 \dots \mu_M}(D; q_1, \dots, q_N) = & \sum_{i_1 i_2 \dots i_M}^N a_{i_1 i_2 \dots i_M} q_{i_1}^{\mu_1} q_{i_2}^{\mu_2} \dots q_{i_M}^{\mu_M} \\
 & + \sum_{i_3 i_4 \dots i_M}^N a_{00 i_3 i_4 \dots i_M} g^{\mu_1 \mu_2} q_{i_3}^{\mu_3} q_{i_4}^{\mu_4} \dots q_{i_M}^{\mu_M} \\
 & + \sum_{i_5 i_6 \dots i_M}^N a_{0000 i_5 \dots i_M} g^{\mu_1 \mu_2} g^{\mu_3 \mu_4} q_{i_5}^{\mu_5} q_{i_6}^{\mu_6} \dots q_{i_M}^{\mu_M} \\
 & + \dots,
 \end{aligned}$$

- and consequently each Feynman diagram numerical

$$\mathcal{A}(p_1, \dots, p_N; \varepsilon_1, \dots, \varepsilon_N) = \sum_{M=0}^N K_{\mu_1 \dots \mu_M}(p_1, \dots, p_N; \varepsilon_1, \dots, \varepsilon_N) I^{\mu_1 \dots \mu_M}(D; q_1, \dots, q_N)$$

Issues in Loop calculus

- The final issue is instabilities in the recursion relation due to the fact that the kinematic matrix S can be (almost) singular in certain regions of phase space (for example the Higgs momentum is small).
- Solution is to rewrite the recursion relations as expansions in the small determinant of the matrix S

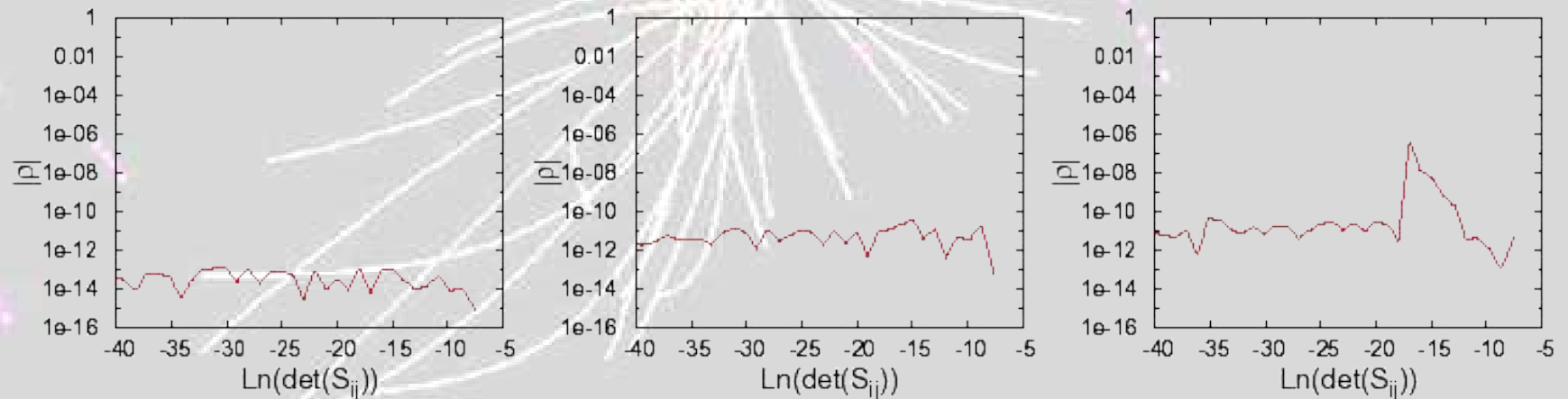


FIG. 6: Relative accuracy $|\rho|$ for the $1/\epsilon^2$ pole (left), the $1/\epsilon$ pole (center) and the constant part (right) of the one-loop amplitude squared for $H \rightarrow q\bar{q}q'\bar{q}'$ as a function of the determinant of the kinematics matrix S_{ij} .

Proof of method

- It is easy to come up with calculational schemes, but its only worth something if one can calculate new processes
- We chose *H + 4 partons* (one of the processes on the Les Houches list)
- We calculated *H + 4 quarks* both analytic and numerical
- We calculated *H + 2 quarks + 2 gluons* and *H + 4 gluons* numerical (with gauge invariance tests etc...)

$$\begin{aligned}
 Y^A(k_1, k_2, k_3, k_4) = & -N_c \frac{c_T \mu^{2\epsilon}}{\epsilon^2} \left[(-s_{14})^{-\epsilon} + (-s_{23})^{-\epsilon} \right] \\
 & + \frac{1}{N_c} \frac{c_T \mu^{2\epsilon}}{\epsilon^2} \left[(-s_{12})^{-\epsilon} + (-s_{34})^{-\epsilon} - 2(-s_{13})^{-\epsilon} + 2(-s_{14})^{-\epsilon} + 2(-s_{23})^{-\epsilon} - 2(-s_{24})^{-\epsilon} \right] \\
 & - \frac{c_T \mu^{2\epsilon}}{\epsilon} \left[3C_f - b_0 \right] \left[(-s_{12})^{-\epsilon} + (-s_{34})^{-\epsilon} \right] - \frac{20}{9} n_f + \frac{152}{9} N_c - 16C_f \\
 & + \frac{1}{N_c} \left[L s_{-1}^{2m\epsilon}(s_{134}, s_{234}, s_{34}, M_H^2) + L s_{-1}^{2m\epsilon}(s_{123}, s_{134}, s_{12}, M_H^2) \right] \\
 & - \frac{2}{N_c} \left[L s_{-1}^{2m\epsilon}(s_{123}, s_{134}, s_{13}, M_H^2) + L s_{-1}^{2m\epsilon}(s_{124}, s_{234}, s_{24}, M_H^2) \right] \\
 & - \left(N_c - \frac{2}{N_c} \right) \left[L s_{-1}^{2m\epsilon}(s_{124}, s_{134}, s_{14}, M_H^2) + L s_{-1}^{2m\epsilon}(s_{123}, s_{234}, s_{23}, M_H^2) \right],
 \end{aligned}
 \tag{29}$$

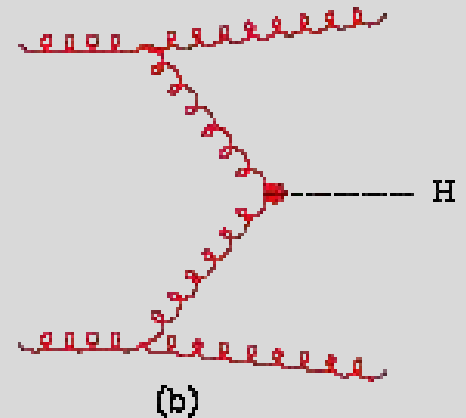
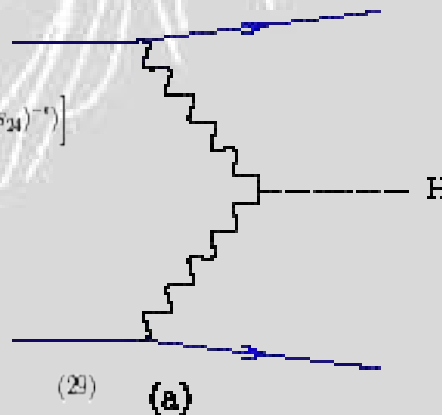


FIG. 1: (a) Lowest order process for vector boson fusion. (b) Example of a diagram contributing to the gluon fusion process in association with two jets.

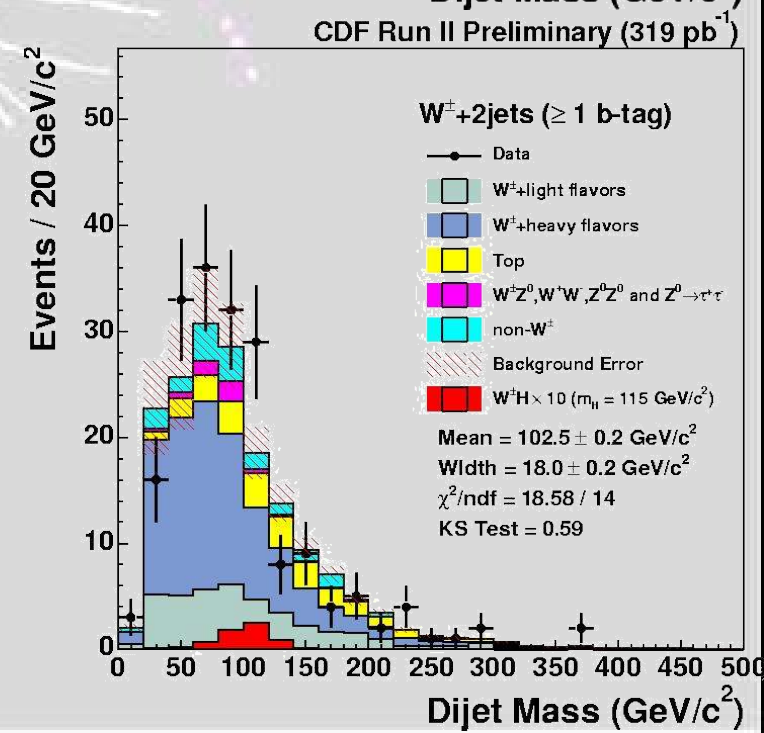
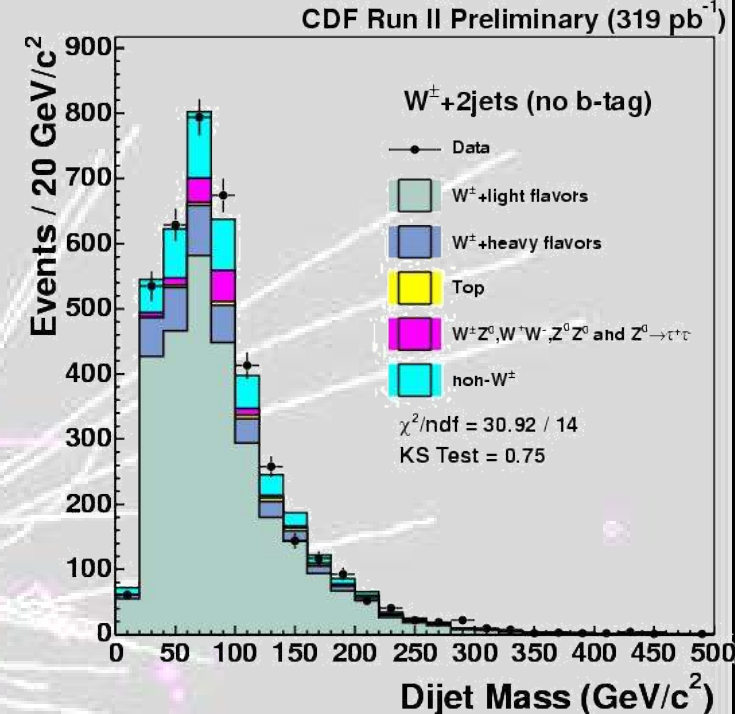
Proof of method

- Results for a phase space point:

	$\frac{1}{\epsilon^2}$	$\frac{1}{\epsilon}$	1		
H+qq+qq	A_B	0	0	12.9162958212387	← Born
	$A_{V,N}$	-68.8869110466063	-114.642248172519	120.018444115458	← Numerical
	$A_{V,A}$	-68.8869110466064	-114.642248172523	120.018444115429	← Analytic
H+qq+q'q'	B_B	0	0	858.856417157052	
	$B_{V,N}$	-4580.56755817094	-436.142317955208	26470.9608978350	
	$B_{V,A}$	-4580.56755817099	-436.142317955660	26470.9608978346	
H+qq+gg	C_B	0	0	968.590160211857	
	$C_{V,N}$	-8394.44805516930	-19808.0396331354	-1287.90574949112	
	$C_{V,A}$	-8394.44805516942	-19808.0396331363	not known	
H+gggg	D_B	0	0	3576991.27960852	
	$D_{V,N}$	$-4.29238953553022 \cdot 10^7$	$-1.04436372655580 \cdot 10^8$	$-6.79830911471604 \cdot 10^7$	
	$D_{V,A}$	$-4.29238953553022 \cdot 10^7$	$-1.04436372655580 \cdot 10^8$	not known	

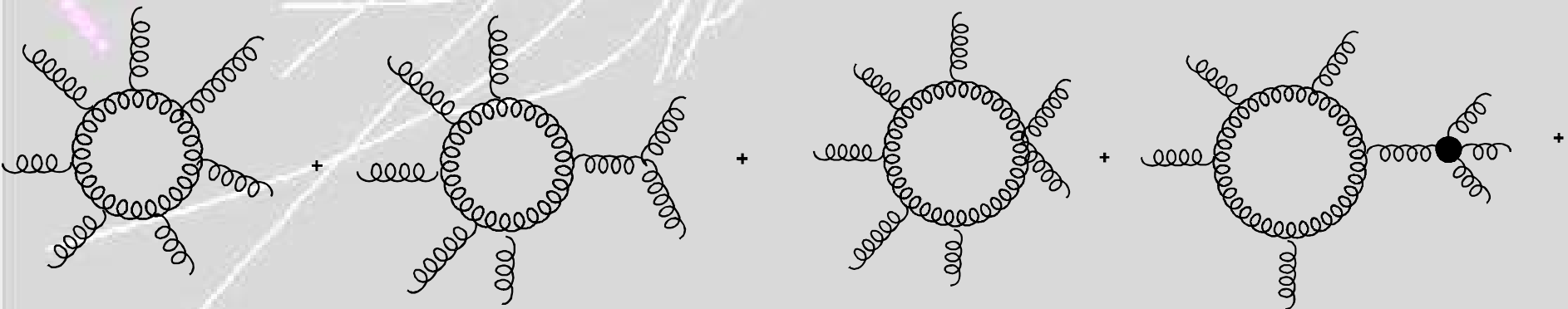
Future Directions

- At this point we are sure we can calculate **2** **3** one loop amplitudes efficiently and maintain numerical stability all over phase space.
- This leaves us with implementing the virtual corrections in a monte carlo and add the unresolved Leading order **2** **4** contributions. Currently this is in progress for the process **PP** **H + 2 jets** through gluon fusion.
- When successful we can start implementing **all 2 3** processes for the LHC at Next-to-Leading order.



Future Directions

- How about going beyond $2 \rightarrow 3$ processes (e.g. $PP \rightarrow TTbar+BBbar$ or even $PP \rightarrow W+4 jets$) ?
- We have started an “exploration project” to develop methods (simply running QGRAF will not do) and gauge required computer resources for running such a monte carlo.
- Following the Leading order developments the perfect process to do all of this is $gluon gluon \rightarrow n gluons$ pushing n as high a possible.



Conclusions

- We have a method which will give us the ability to calculate the relevant 2^3 processes at Next-to-Leading order for the LHC.
- Given enough manpower and computer resources this can be done in a relatively short time span.
- We are exploring the feasibility of going beyond 2^3 processes. The limitations will in the end be computer resources (just as it is for Leading order processes).

