

# ***Evaluation of the $d_0$ resolution from data***

- ◆ Track impact parameter ( $r\phi$ ) resolution in pp
- ◆ Pulls on the impact parameter
- ◆ First ideas to extract the resolution from real data

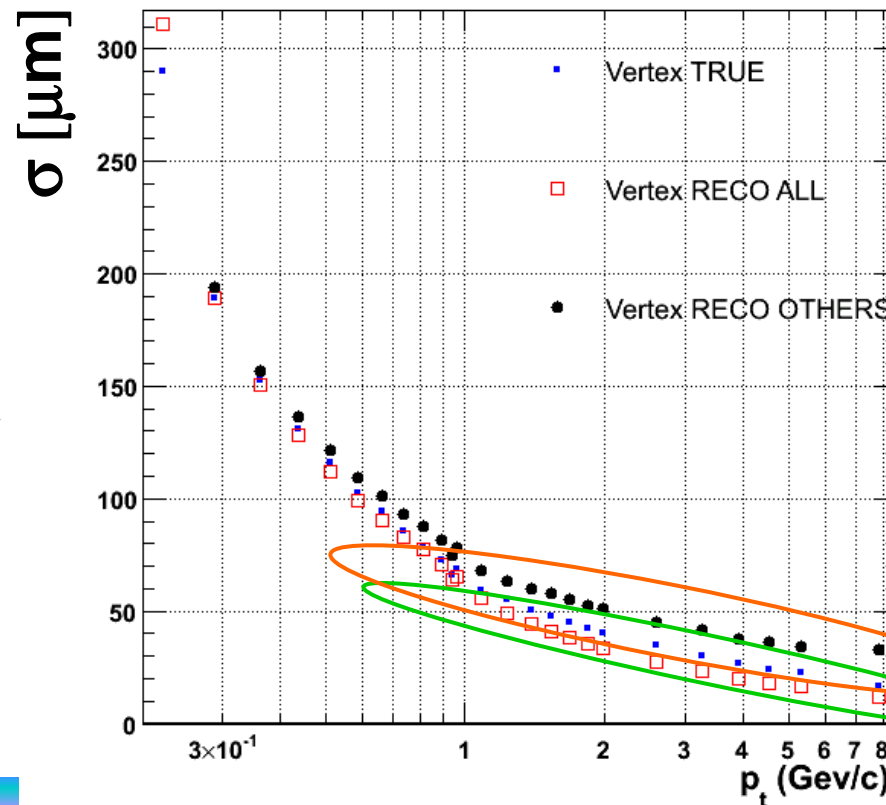
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# Track impact parameter measurement in pp collisions

- ◆ Track impact parameter resolution:  $\sigma_{d_0} = \sigma_{vtx} \oplus \sigma_{track}$
- ◆ Vertex reconstructed from tracks
- ◆ Bias (underestimate of  $d_0$ ) if the considered track is used for vertex fit:

$\sigma$  of  $d_0$  distribution for primaries

true vertex from simul.  
reco vertex using all tracks  
reco vertex excluding current track



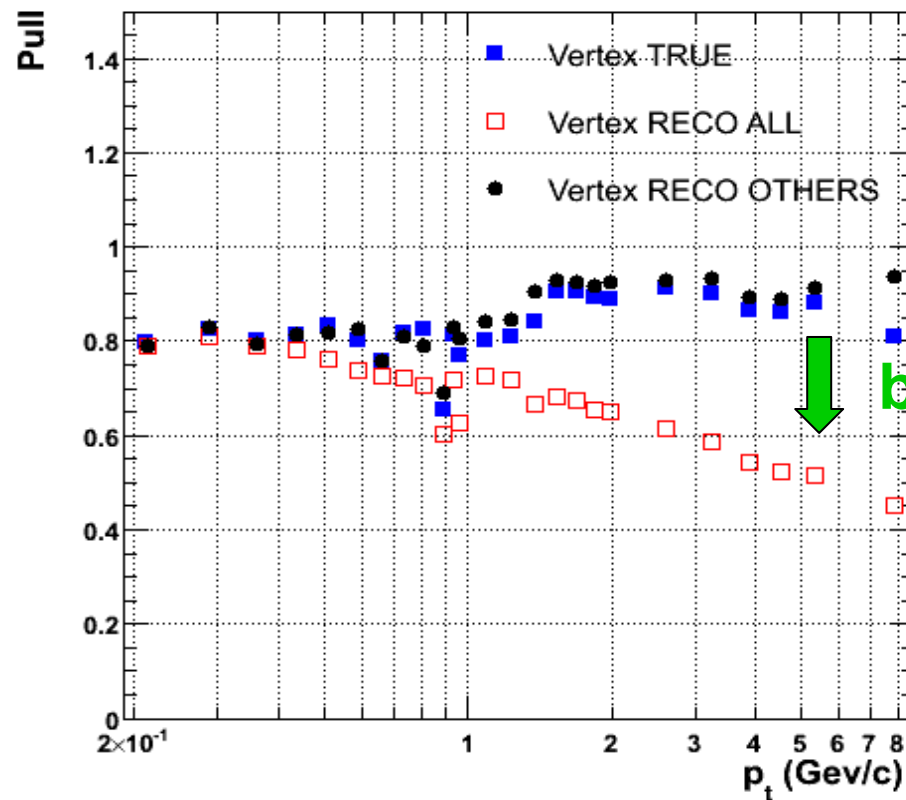
effect of vertex uncertainty bias!

# Pulls on the impact parameter

- Bias is visible also if one looks at the pulls:

true vertex from simul.  
 reco vertex using all tracks  
 reco vertex excluding current track

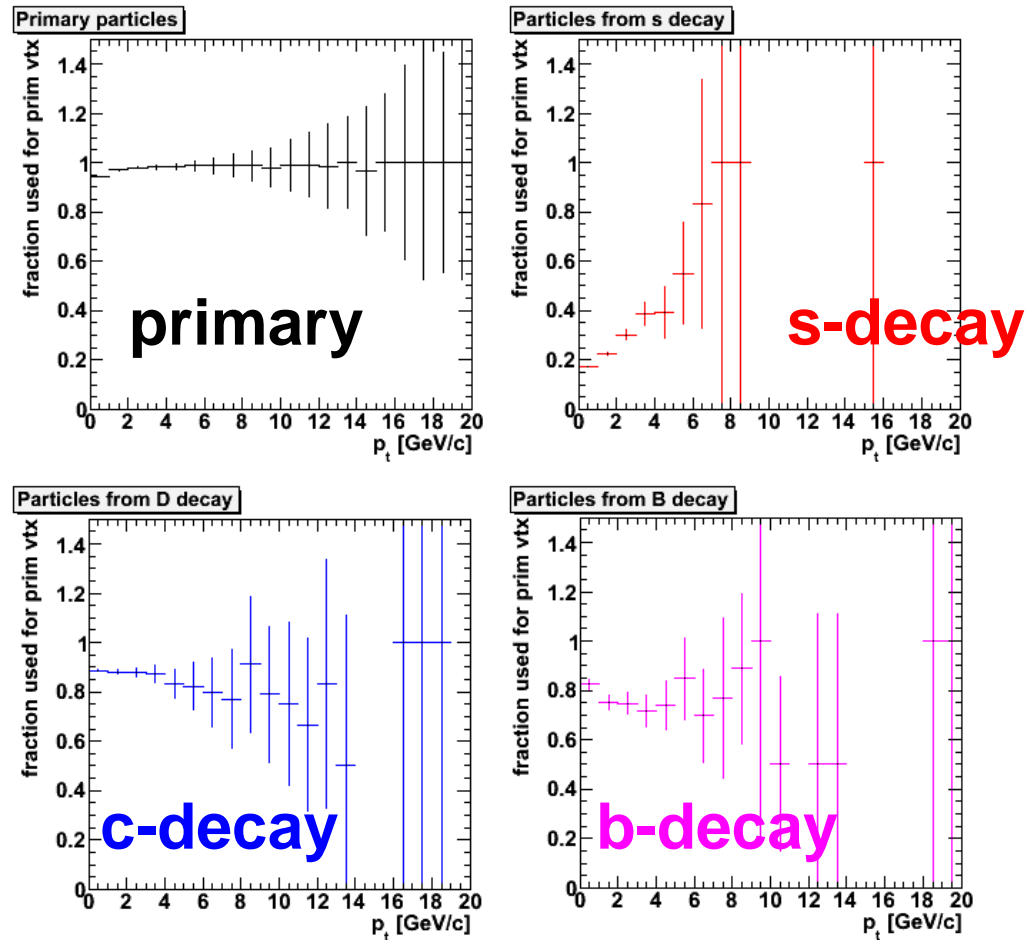
$\sigma$  of  $d_0/\text{error}(d_0)$  distr. for primaries



bias!

# Tracks used for vertex reco

- Fraction of tracks of given origin used in vertex fit:



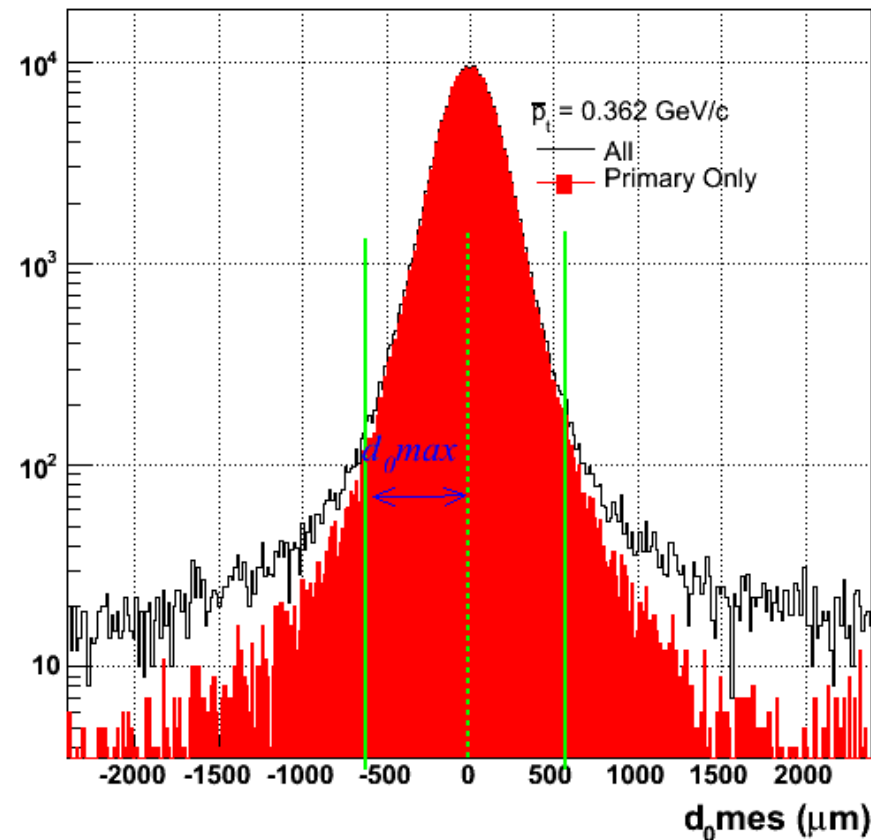
→ this bias could be relevant for charm/beauty studies

**Motivation:** For all analyses using  $d_0$  cuts (charm and beauty in particular), very important to extract  $d_0$  resolution from data in order to check whether it is reproduced by the simulation

## First-day approach:

$d_0$  distribution is dominated by primary particles for  $|d_0| < d_0 \text{MAX}$

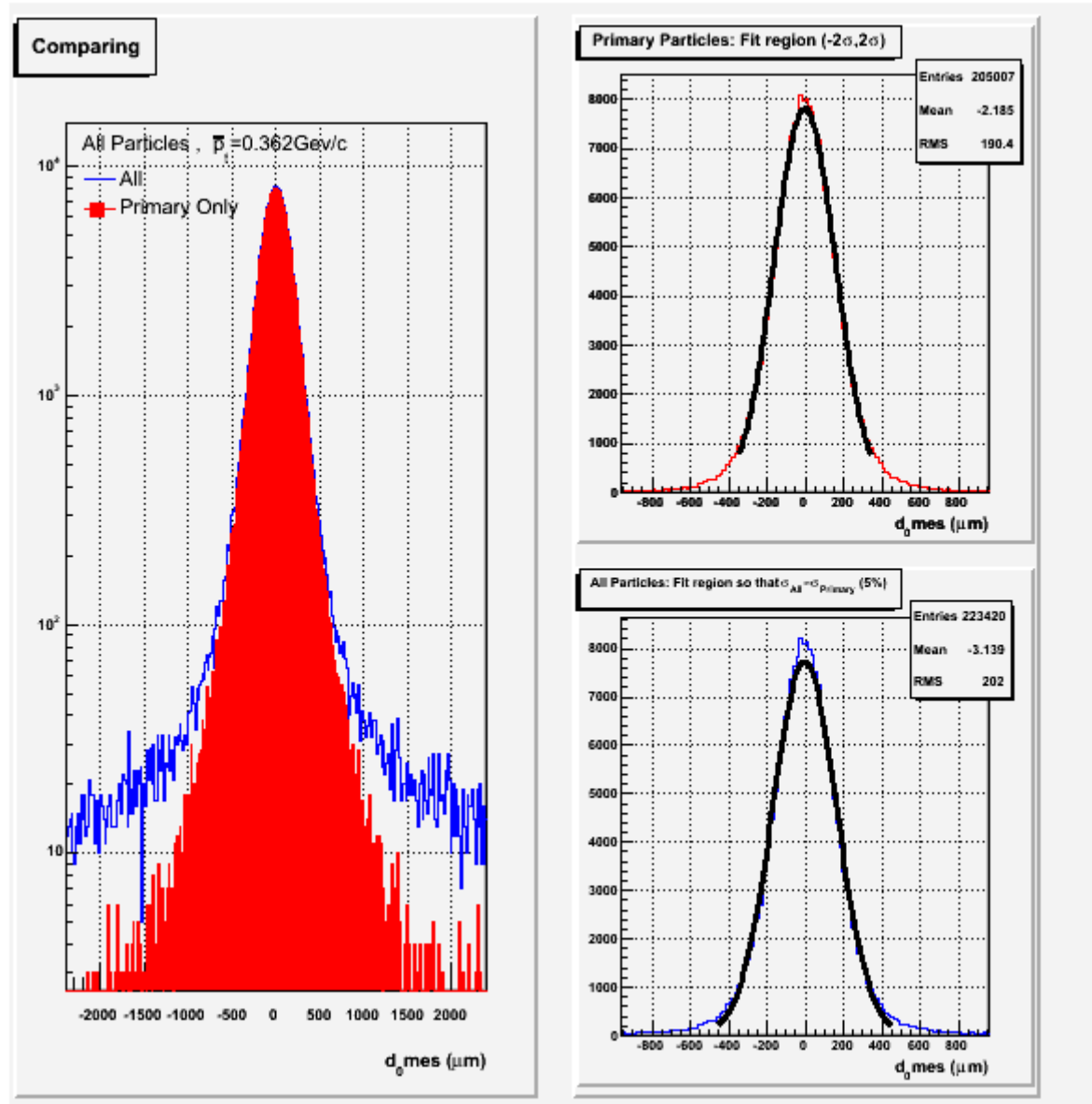
→ Gaussian fit in this range provides the resolution



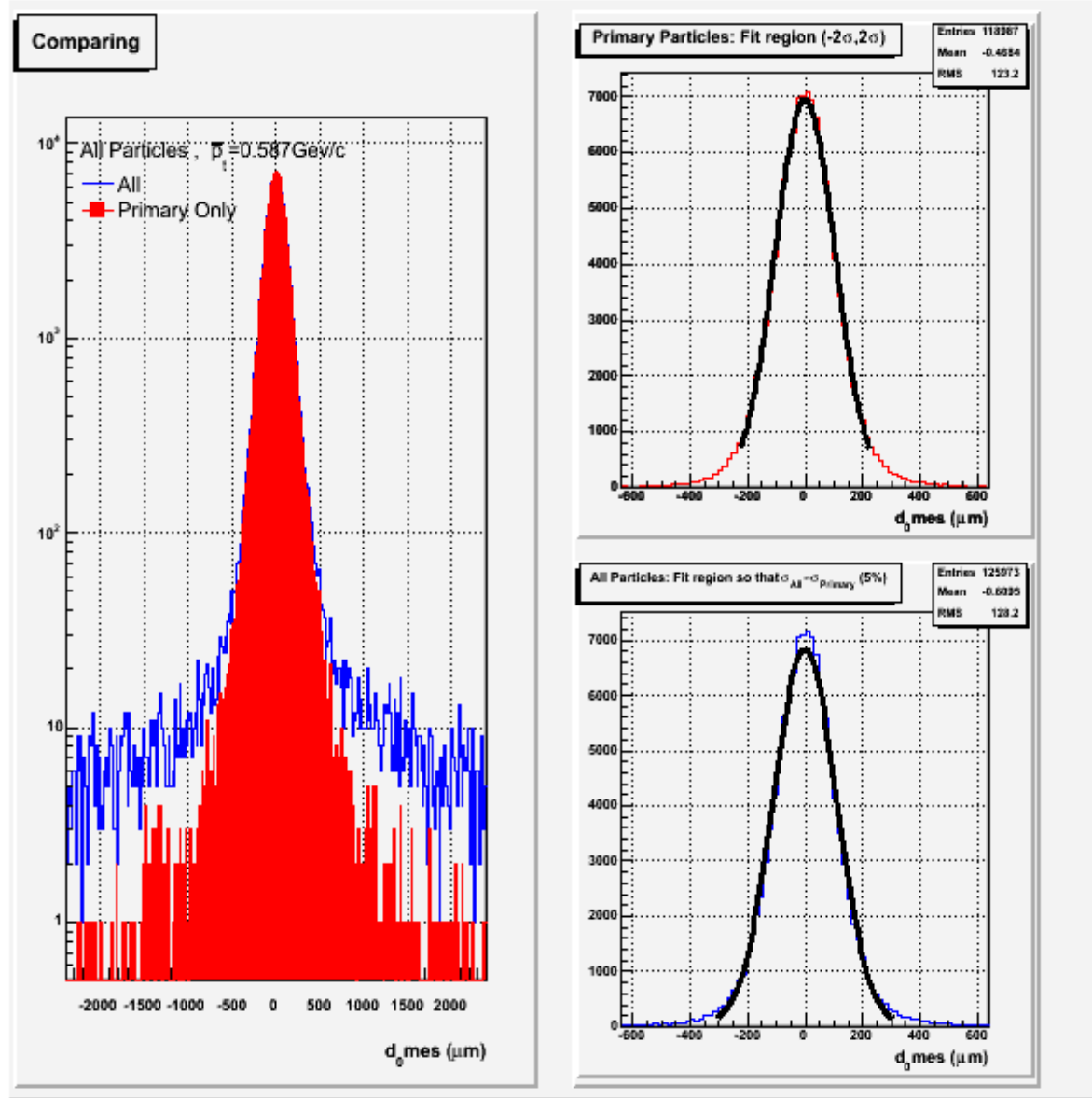
## Exercise:

- ◆ Used PYTHIA pp events (PDC06-like cocktail)
- ◆ Vertex reconstructed using the tracks
- ◆ In bins of  $p_t$ , consider distribution of  $d_0$  w.r.t. reco vertex, for primaries and for all tracks
- ◆ Fit of primaries gives  $d_0$  resolution
- ◆ On distribution of all tracks, used iterative procedure to fit in interval  $|d_0| < d_0\text{MAX}$ , with  $d_0\text{MAX}$  gradually decreasing
- ◆ Stop when extracted  $\sigma$  is equal (within 5%) to  $\sigma$  of primaries
  
- ◆ Get  $d_0\text{MAX}$  values to be used on the data, as function of  $p_t$ 
  - ⊕ WARNING: possible bias due to differences on secondary/primary ratio in simulation and in real events

$p_t \approx 0.4 \text{ GeV}/c$

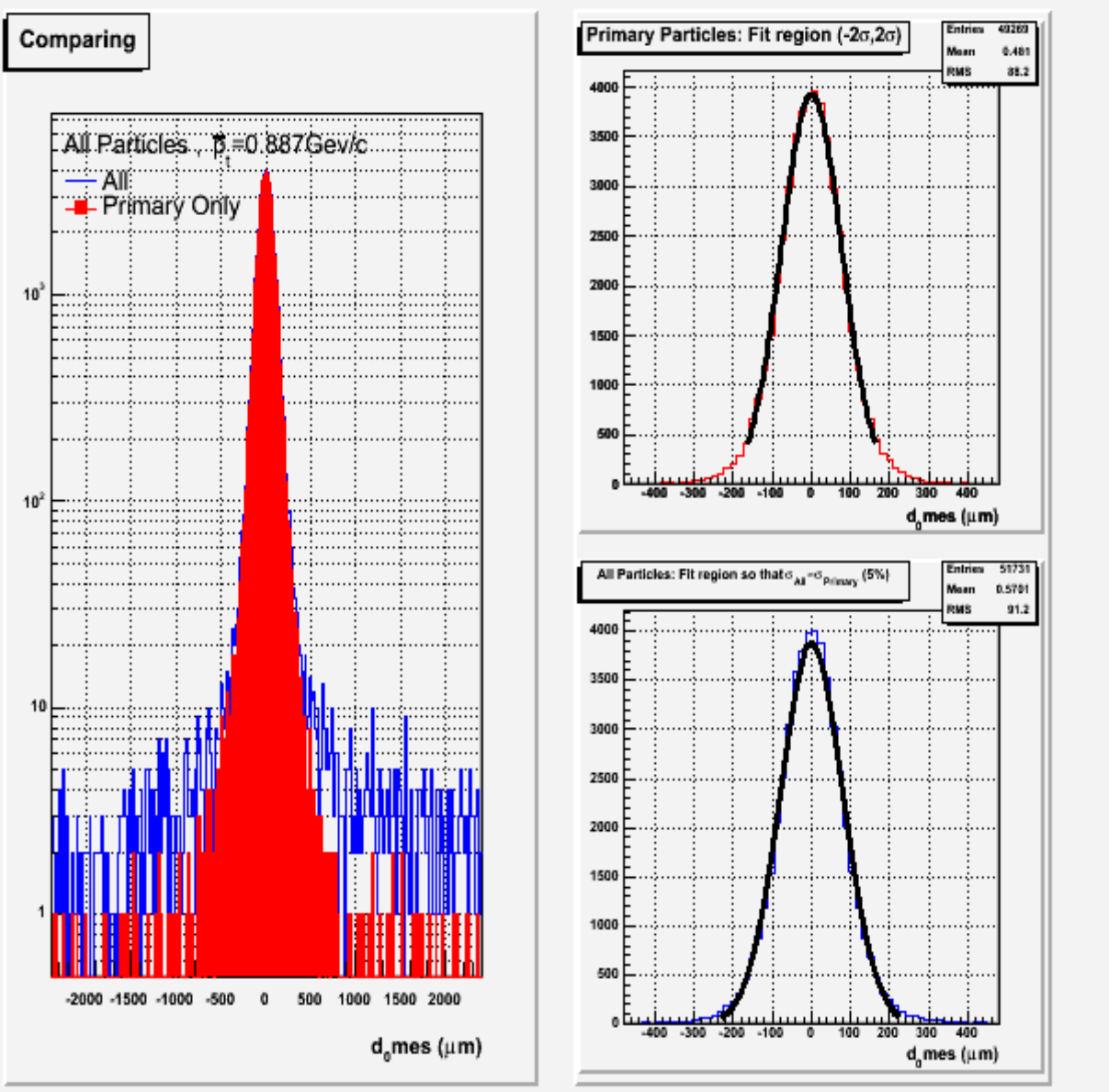


$p_t \approx 0.6 \text{ GeV}/c$

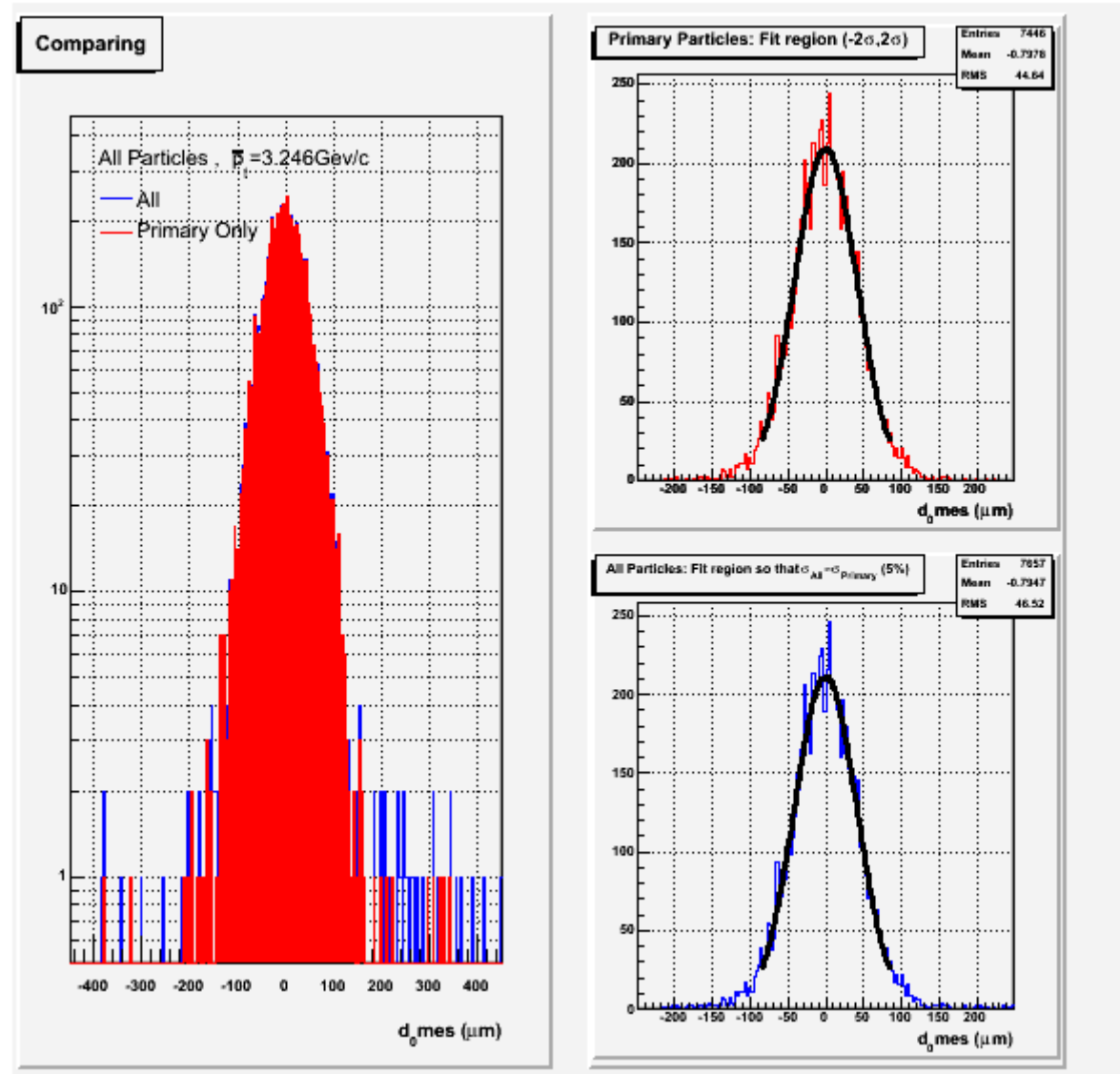




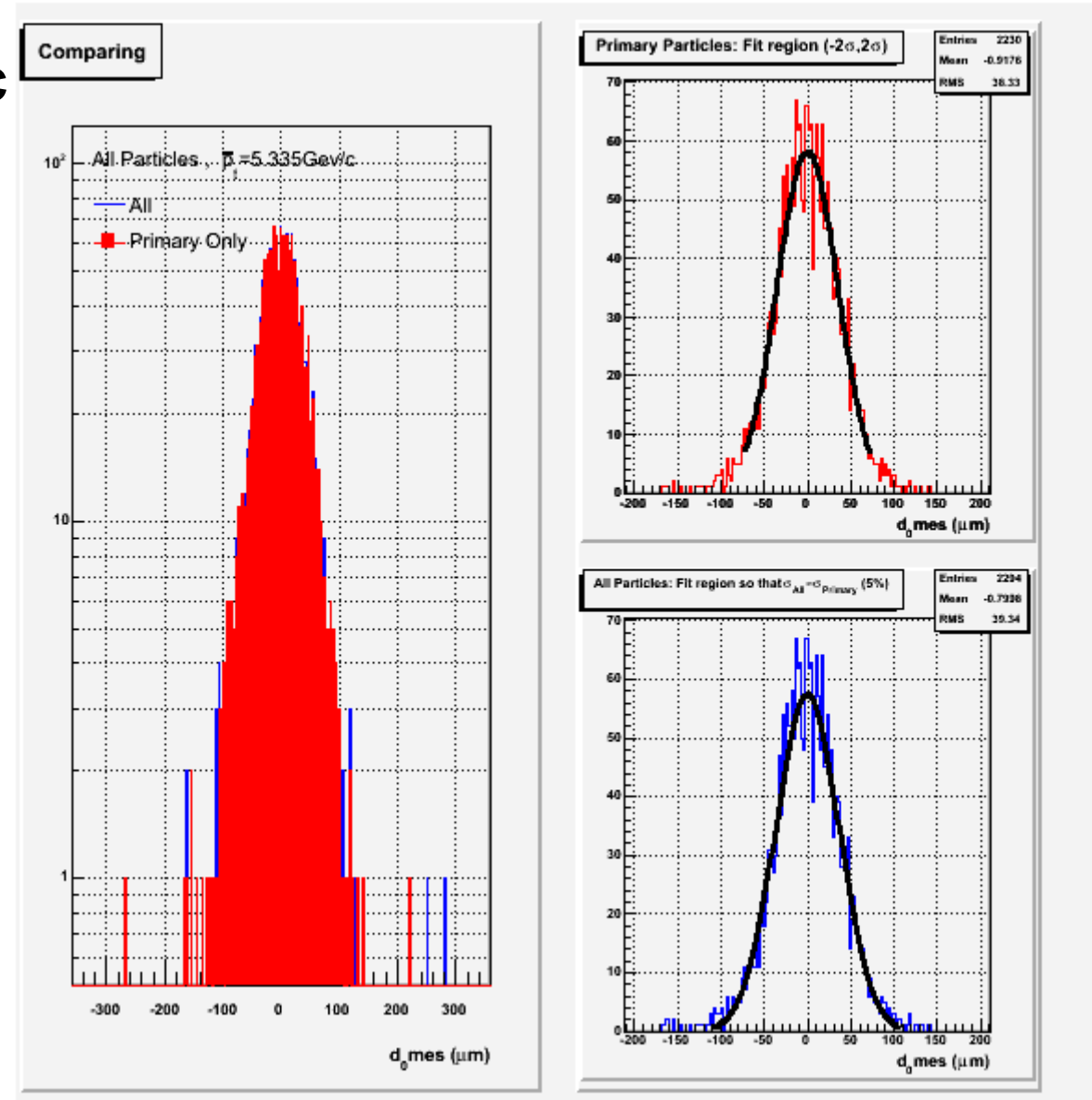
$p_t \approx 0.9 \text{ GeV}/c$



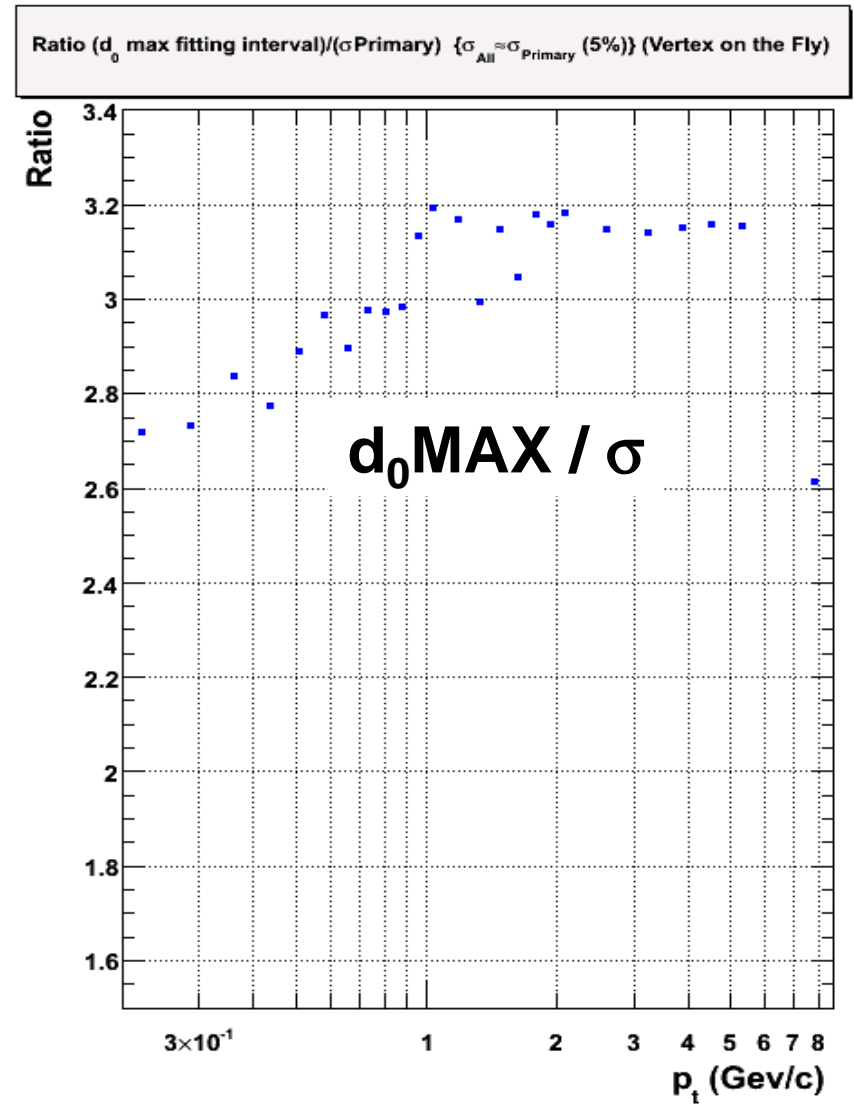
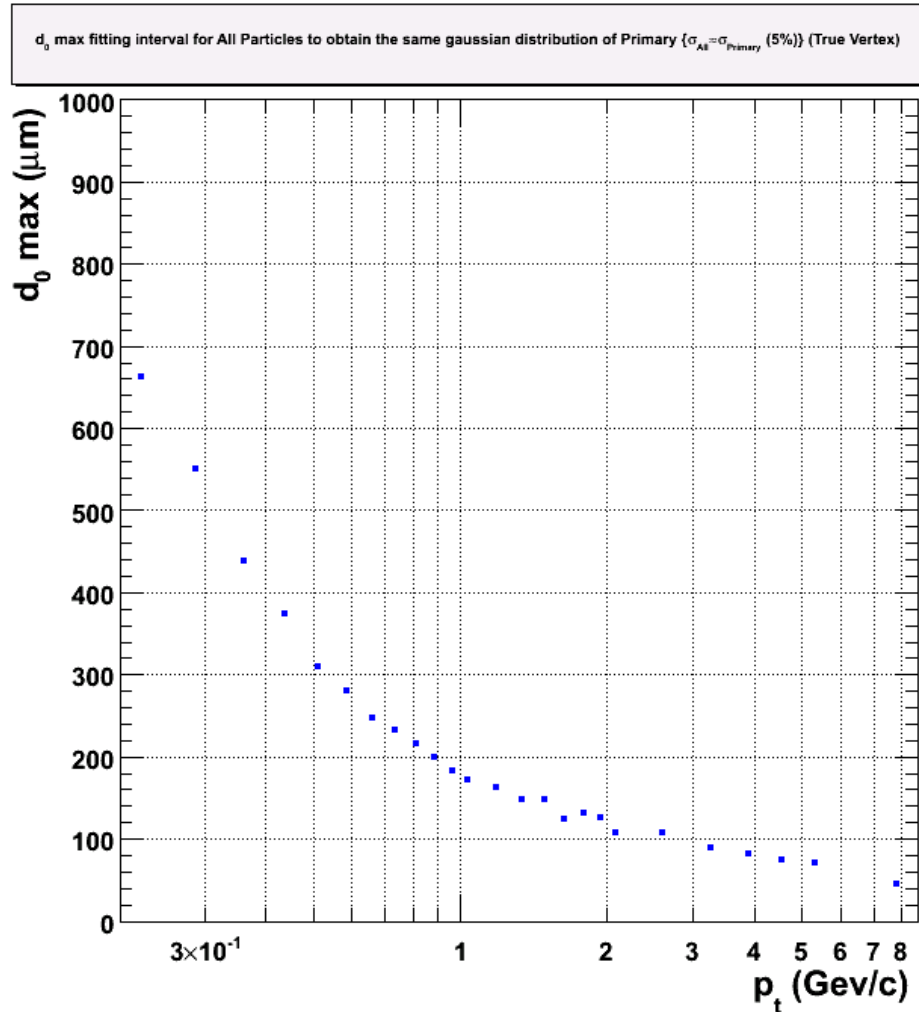
$p_t \approx 3.2 \text{ GeV}/c$



$p_t \approx 5.3 \text{ GeV}/c$



# Fit range for evaluation of resolution



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- ◆ A gaussian fit of all tracks'  $d_0$  distr. in the range  $\sim (-3\sigma, +3\sigma)$  allows to extract the  $d_0$  resolution from the data
- ◆ Extracted resolution is a convolution of track position resolution and primary vertex resolution (the latter is relevant only for high- $p_t$  tracks)
- ◆ Need to devise method to separate track and vertex contributions
  - ⊕ Idea to get track position resolution at high- $p_t$ : use distribution of DCA between pairs of high- $p_t$  tracks (exploiting the fact that most high- $p_t$  tracks are primary)
- ◆ Consider other methods
  - ⊕ Idea (to be checked): use cosmics crossing all detector

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