# (LHC) Controls — an OP perspective

K. Fuchsberger on behalf of the LHC-OP team

Many, many thanks to the whole OP team for the input!

# OP Perspective on Controls



## Content

Users view

**Developers View** 

Summary

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Summary

## First of all ...

# We have a very good control system!!!!

- Very stable
- All operational scenarios managable (e.g. Ramp & squeeze)
- Big cleanup and a lot of improvements done of APIs during LS1.

## So, ... Do we have to change at all?

- Avoiding Mistakes → Increase Availability (cf Andreas Presentation)
- Evolve (carefully!) → Be prepared!
  - The world around us changes (e.g. processors, java, ...)
  - E.g. Future accelerators
- Be Compatible with the 21st Century ;-)

What we did not ask for ...

#### Breaking API changes

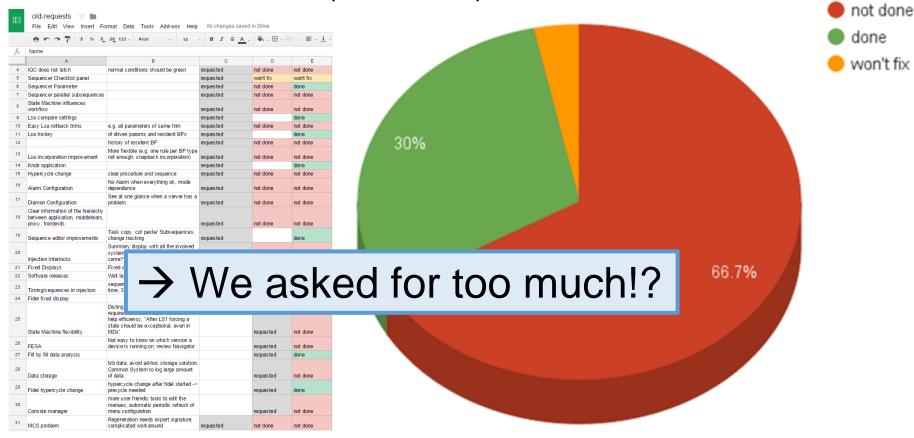
- LSA Refactoring
- Logging Service API (x2)
- Changes in many FESA classes

We understand that such changes might be necessary..

# Transparency & Communication (in advance)

→ See Marines Presentation

# What we asked for (2010/11)...



https://drive.google.com/open?id=1AOXREGR6X7VmoizAldJFS6gPCtACeTP2Mmo6P-o9AUA

### What does OP want?

What do you consider as the ...

- ... most important features/properties/components that an ideal control system should have? (Long term)
- ... most important improvements that should be made to the available tools?
- ... most important issues that should have been fixed as soon as possible?

→ Not easy to find out what we want ⊗

# Finding Priorities PRELIMINARY Votes (High, Medium, Low importance) 16 Count(MEDIUM) Count(LOW) #Votes 15 Votes in total 50% 8 Importance

Top 5 of LHC-OP's most wanted improvements



# 5 – Improve Window Management on Consoles

SINCE 2011

- Rationalize the space
- Many overlapping windows
- 'Perspectives' per activity: e.g. Injection, Ramp, Lossmaps, Powering
- Beam mode / State machine deciding what gets displayed and where?
- Different window manager?
- Autostart of predefined set of applications on consoles (e.g. after a reboot)
- Shortcuts (e.g. new logbook entry, search for an application)

- 4 Easily usable tool to move collimators
- Currently: complicated acrobatics of making some BP resident plus pressing the right combinations of buttons in equip state.
- Certain Scenarios
  - Move all to parking
  - Symmetrize TCTs
- Nice display where to see the collimators (probably w.r.t. the beam)

# 3 – Improved Filling Diagnostics

- A lot of time lost
- See at one glance why the beam did not come (Missing Fixed display)
- E.g. Why did the CBCM reject the request?
- Show in advance what has to be done before to request an injection.
- → Availability (Delphine)

# 2 – QPS/PIC/Equip State

- PIC permit loss-> immediately display root cause
- PM knows it can this be faster?
- Replacement for QPS macros
- Better integration in other controls system
  - Simple overview
  - Dig down in case of problems
  - Easy tool for Circuit (+QPS) resets

→ See also: Mirkos presentation



# 1 – Improved Automation/Sequencer/Scripting

# SINCE 2010

#### **Execution:**

- (Automated) Parallelism
- Better overview (several sequences running)
- Small things (e.g. Quirky Windows behaviour, Better error presentation)

#### Editing:

- Long time/chain from idea to operation (every change in a task needs a sequencer release)
- Tools that make it easier to refactor between different layers (Sequence <-> Task).

Scripting (More flexible (and more dynamic) way to create scripts/macros/sequences). E.g. for

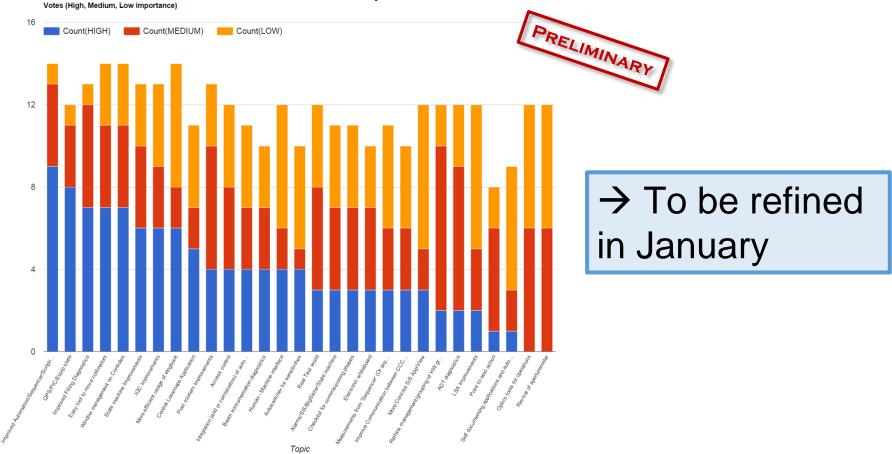
- Easy way to formulate commissioning tests
- MDs

# 1 – Improved Automation II

#### Settings vs. Sequences

- Clear separation between settings and sequence
  - → Avoid hardcoded values in sequence (devices, contexts, values...)
- Templates/Operational Scenarios (certain modes of operation (e.g. Proton Physics, Lossmaps, VdM scans)
  - Avoid e.g. different sequences for different particle types.
     (Now Copies with slight changes)
  - Clearly see the discrepancies when something is wrong.

Just for the sake of completeness ...

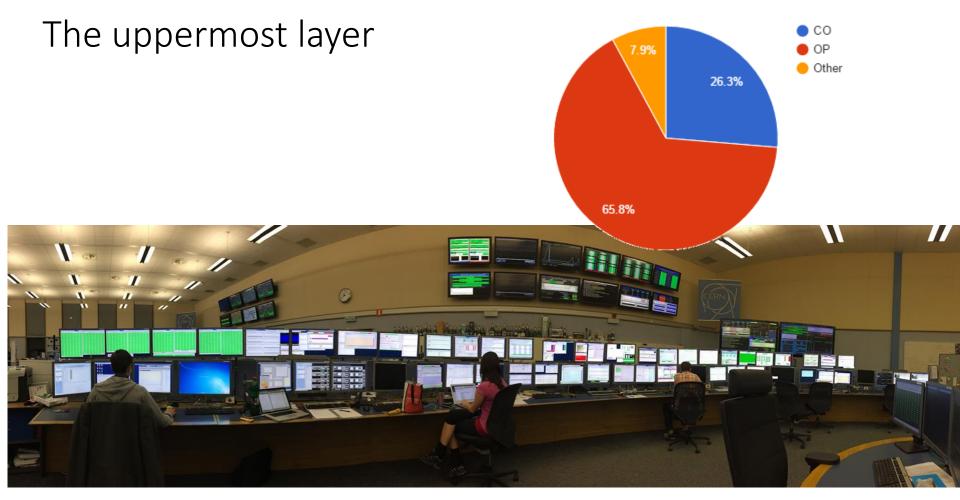


## Content

Users view

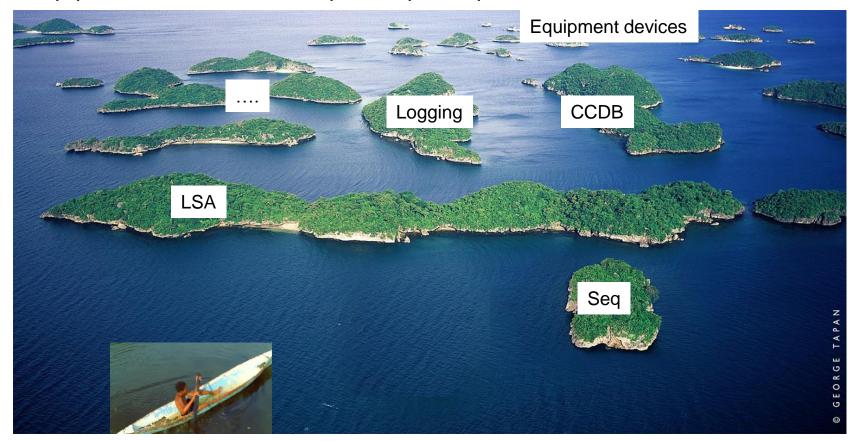
**Developers View** 

Summary

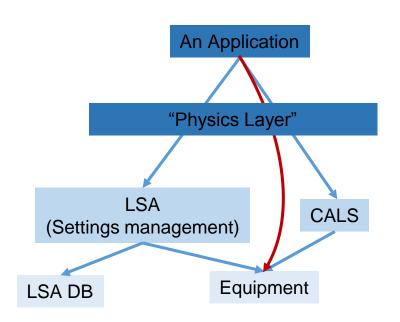


Courtesy: D. Valuch

# Application developers perspective



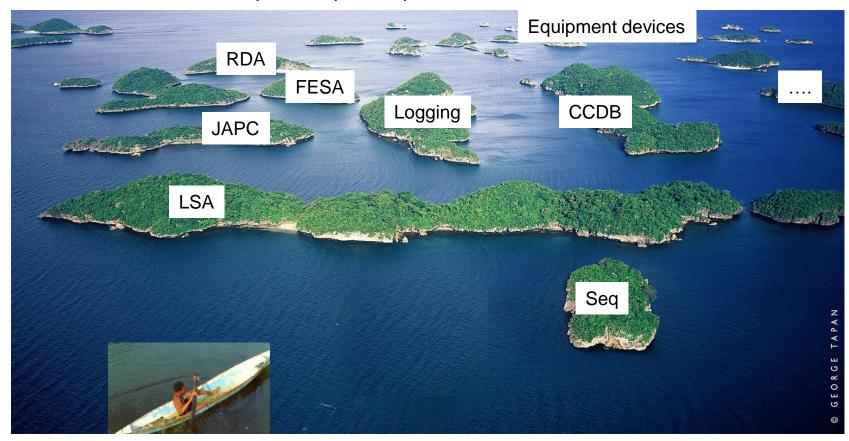
# The layered control system ...

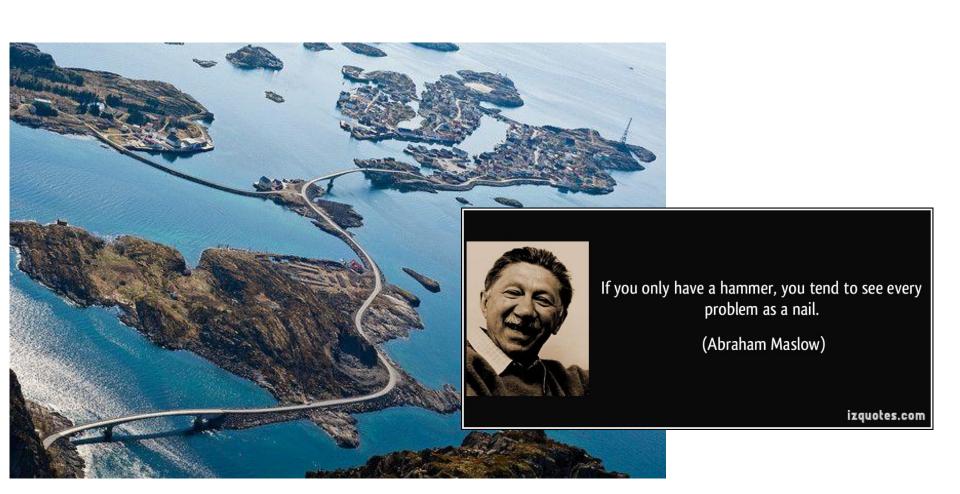


- Domain Driven Design
- Ease testing
- Making writing Applications easy!

```
Tune tune = get(HORIZONTAL, TUNE).of(LHC);
on(HORIZONTAL, TUNE).of(LHC).subscribe((tune) -> System.out.println(tune));
```

# OP SW developers perspective





# Who has the global view?



## Global long term vision

Based on some principles e.g.

- Intuitive
- Consistent
- Simple on top, easy to dig down.
- Built to be tested
- Built to grow
- Right dose of Automation

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# Do not be afraid of validation testing ....?

#### **Procedure for software tests during operational periods:**

Option A - Do not test

Option B - Be brave and do the following:

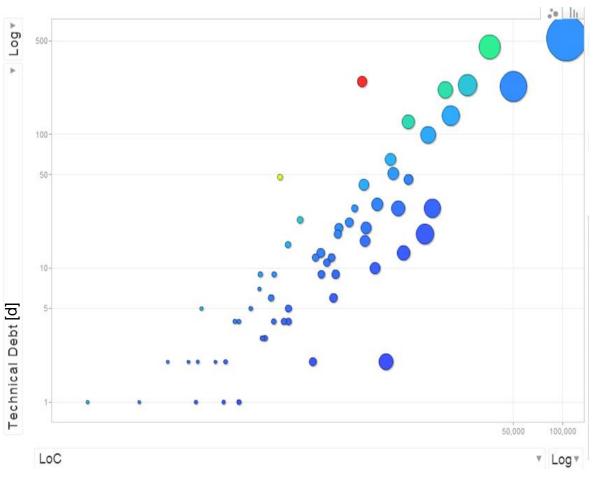
- 1. Check that you are connected to LSA NEXT and your test device
- 2. Open LHC Page 1
- 3. Check that you are really connected to LSA NEXT and the test device (better restart the application once more, just to be sure)
- 4. Close your eyes and and mumble the mantra: "No worries, RBAC will save me if I do something wrong!".
- 5. press the button ...
- 6. Open your eyes and check on page 1 if the beam is still in ...
- 7. (optional) if the beam was dumped, call the CCC and apologize
- → Would appreciate a comforting development and testing environment outside the TN ©



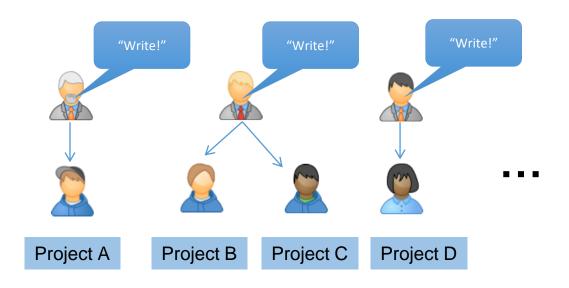
## LHC OP Software - Status

- ~500.000 lines of code (800.000 lines in total)
- 13.6 manyears of technical dept
- 6+2(SPS) people writing software

→ 8.4 minutes of tech dept per line of code!!!!!

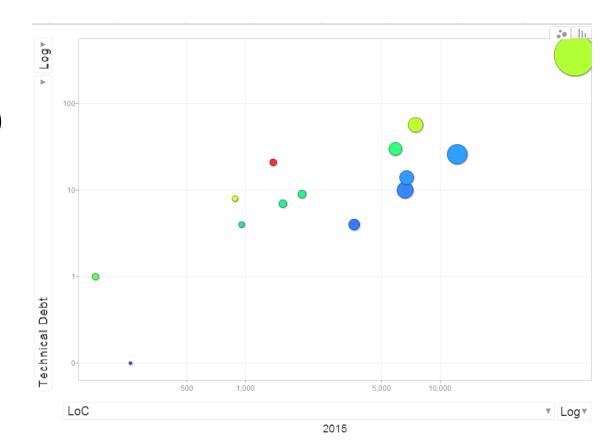


## How come?

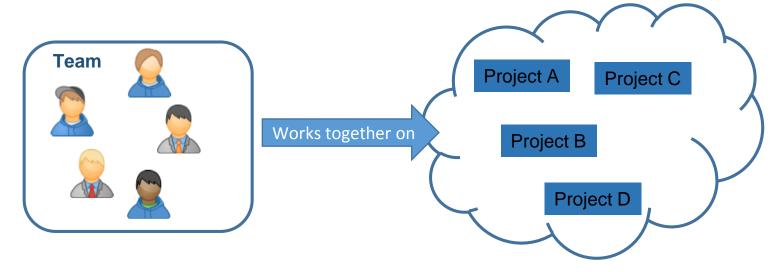


# Potential Incoming

- ~100.000 Lines of code
   (20% of actual codebase)
   (~160.000 lines in total)
- ~2.5 man-years of tech debt
- → ~ 8 min/LoC
- ~2 students projects + 1 external SW stack.
- Lack of continuity



# How we are trying to tackle this problem

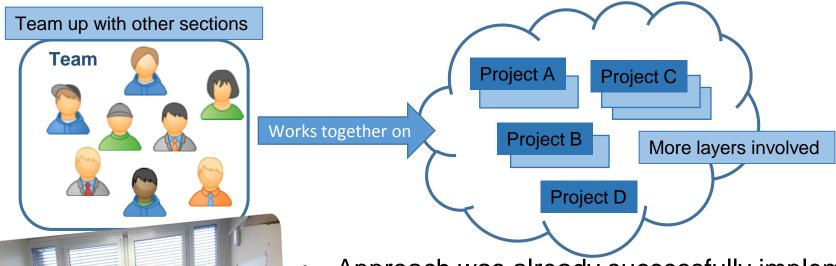


- + Knowledge exchange
- →better SW!
- + Focus (more done)
- + More fun!!

Because of shiftwork, difficult to ensure

- ... continuous progress
- ... continuous supervision
- ... continuous support

## Collaborate more with other sections



- Approach was already successfully implemented for development of FB-testing framework.
- Some iterations "in preparation" together with TE-MPE for Jan/Feb
- CO-APS is willing to give it a try together with us next year ("good old LSA collaboration";-)

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Everything working well! Time to evolve (carefully)!

As Control System Users, we would like

- a Control system that
  - behaves as we expect it to
  - prevents us from making mistakes
- Evolution according to our priorities

... while we know that we have to improve in defining our priorities.

#### As LHC-OP SW developers, we would like to

- develop in teams together with CO developers.
- have intuitive domain specific layers to program against and
- be closely involved in evolving the control system in design and implementation as well as strategic decisions.

... while we know that we have to improve our SW-development skills

