

# CRAB CAVITIES CRYOMODULE REVIEW

## **VACUUM TANK DESIGN**

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on behalf of the Crab Cavity Collaboration 10/11/2015



The HiLumi LHC Design Study is included in the High Luminosity LHC project and is partly funded by the European Commission within the Framework Programme 7 Capacities Specific Programme, Grant Agreement 284404.



# **Previous design review**

## 1 – Lateral insertion



#### **Advantages :**

Simplicity of conception / manufacturing Large openings

#### **Disadvantages :**

Vacuum valves inside vacuum tank Overall dimensions Insertion of thermal screen and MLI very complex Heavy side doors (~300kg)









# **Previous design review**

## 2 – Longitudinal insertion

#### Advantages :

Externalization of valves Simplification of assembly sequence Overall size reduced

#### **Disadvantages** :

Limited space available for assembly Vacuum tank less rigid compare to other solutions Multiplication of large size sealing Insertion of thermal screen and MLI very complex









# **Chosen design : Vertical assembly**

#### **Design from Triumph**

Advanced Rare IsotopE Laboratory (ARIEL)



#### Advantages :

Externalization of valves Suppression of large openings Vacuum tank more rigid Simplification of assembly sequence Space available for assembly





## Cryomodule overview (DQW)





## Cryomodule overview (RFD)





## Connections

DN100 Relief valve

DN40 HOM extraction lines (x6)

DN100 Sensors and heaters connexions (x2)

DN300 Cryogenics connexions

DN63 FSI ports (Position measurement)

DN40 for vacuum equipments (gaujes...)



# Welds interfaces

## Flange

STATISTICS STATISTICS



## Flat sides



Table 17-4 — Classification of welded joints g) Flanges and pads

| 7.2 | welded flange | a)        |    |    | Full penetration weld:    | F2.1 to F2.3 |
|-----|---------------|-----------|----|----|---------------------------|--------------|
|     |               | R1        | 71 | 63 | - as welded               |              |
|     |               | Section 1 | 80 | 63 | - If weld toe dressed     |              |
|     |               |           | 63 | 63 | Partial penetration welds |              |
|     |               | b)        |    |    |                           |              |
|     |               |           |    |    |                           |              |
|     |               |           |    |    |                           |              |
|     |               |           |    |    |                           |              |
|     |               |           |    |    |                           |              |
|     |               | 4.4.2.5   |    |    |                           |              |

Table A-3 — Pressure bearing welds - Flats ends





# **FE calculations**



# Overview

Atmospheric pressure

Vacuum

Gravity

Objectives of the FE calculations:

- Minimize the vessel deformation.
- > Optimize the mass.
- > Verify the stress level.
- Assess the structure against buckling.



# FE model



FE model of the vessel includes:

- 600 components,  $\succ$
- ➢ 478 bolted joints,
- 24 welded joints,  $\succ$
- frictional contacts.

The detailed model was required to properly capture the vacuum vessel structural response.

| Material             | Poisson's Elastic<br>ratio modulus |       | Density              | R <sub>p0.2</sub> | Max<br>allowable<br>R <sub>p0.2</sub> /1.5 |
|----------------------|------------------------------------|-------|----------------------|-------------------|--|
| -                    |                                    | [GPa] | [kg/m <sup>3</sup> ] | [MPa]             | [MPa]                                      |
| Stainless Steel 316L | 0.27                               | 193   | 7950                 | 225               | 150  |
| AI AW6082 T6         | 0.33                               | 69.5  | 2710                 | 240               | 160  |
|                      |                                    |       |                      |                   |  |

[1] Materials and Ansys Library for Design Office, EDMS 1291793.





High Luminosity LHC

# Bolts



Bolt preload:
> 35 kN (M10),
> 22 kN (M8).
Coefficients of friction μ:
> 0.32<sup>1</sup> (316L − 316L),
> 0.3<sup>1</sup> (Al − 316L).

Total number of bolts: 476.

Bolt properties calculated according to the VDI 2230-2.



Bolt definition in ANSYS. Beam attached by a spider net to the bearing face and screw hole.

<sup>1</sup> J. C. Burton, P. Taborek and J. E. Rutledge, Temperature dependence of friction under cryogenic conditions in vacuum. Tribology Letters, Vol. 23, No. 2, August 2006



# Stiffeners



- > The additional stiffeners encompassing the frame and top stiffeners added.
- > The lateral stiffeners were added to increase the stiffness of the vessel and minimize deformation of the plates.



# Loads and BCs



- > Differential pressure 0.1 MPa assigned to the external faces of the vacuum vessel.
- > The helium vessels replaced by corresponding reaction forces extracted from the related calculation.
- CoG for the magnetic and thermal shields defined and the coresponding mass attached to the top plate.



# Mesh

Mesh convergence test performed to select the most reasonable size in order to obtain trusted results.



| Component | Size [mm] | Name                 | Description   | DoF                                |
|-----------|-----------|----------------------|---|------------------------------------|
| 1         | 25        |                      | SOLID186<br>3-D 20-node<br>hexahedral<br>solid element<br>with quadratic<br>displacement<br>behaviour<br>SOLID187<br>3-D 10-node<br>tetrahedral<br>solid element<br>with quadratic<br>displacement<br>behaviour | UX, UY, UZ                         |
| 2         | 25        |                      |   |                                    |
| 3         |           |                      |   |                                    |
| 4         | 20        |                      |   |                                    |
| 5         |           | SOLID186<br>SOLID187 |   |                                    |
| 6         |           |                      |   |                                    |
| 7         |           |                      |   |                                    |
| 8         |           |                      |   |                                    |
| 9         | 15        |                      |   |                                    |
| bolts     | 1         | BEAM188              | 3-D 2-node<br>linear beam<br>element  | UX, UY, UZ,<br>ROTX, ROTY,<br>ROTZ |



# Deformation of the lateral plates

Total Deformation Type: Total Deformation Unit: mm





| $\rm Zoom\times100$ |
|---------------------|
|---------------------|

The maximum value is 1.25 mm and is located in the middle of the side plate. That deformation may be reduced slightly using thicker plates, however it increases the total mass. Therefore the trade-off between the deformation and total mass was made.



# Vertical deformation

Directional Deformation Type: Directional Deformation(Z Axis) Unit: mm





# Stress intensity



- ➤ The regions with stress higher than acceptable are coloured in red. The mesh refinement resulted in even higher stress and since they are localized and occur close to the weld contacts and screw holes, they were classified as peak stresses.
- > The overall stress level for the vacuum vessel is lower than acceptable value.
- The stress intensification occurs on the lateral stiffener, under the bolt heads and the bottom of the side plates.

Peak stresses.



# Buckling



0.1112

2.212e-5 Min



The pre-stressed structure was extracted from the structural calculations. The lowest buckling factor for the vacuum vessel is 193 and proves the structure stability.



# Conclusions

- The FE calculations have demonstrated the satisfactory structural performance of the vacuum vessel.
- > A detailed model was prepared and verified to obtain the most realistic results.
- The lateral and vertical deformations are acceptable, however there is still space for improvement.
- The stress level is under control. The peak stresses were found as a result of the mesh distortion and contact definition.
- The buckling analysis showed that the vacuum vessel is safe and under the operating load buckling will not occur.







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#### DQW section view





#### RFD section view



