

### The CNGS Target Expectation vs. Experience

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### The CNGS Target Expectation vs. experience



### OUTLINE

Requirements & engineering approach
Material choices & target cooling
Engineering limits of the target
Handling overview
Summary

## Physical requirements...



#### The CNGS Target has to ...

... reliably intercept a <u>400 GeV</u> proton beam <u>every 6 s</u> in a double fast extraction with <u>10.5 µs long spills</u> at <u>50 ms</u> distance. The nominal beam intensity is  $4.8 \times 10^{13}$  protons per cycle, but an ultimate intensity of <u>7×10<sup>13</sup></u> protons must be considered in view of a possible beam upgrade. The beam has a <u> $\sigma$  = 0.53 mm.</u>

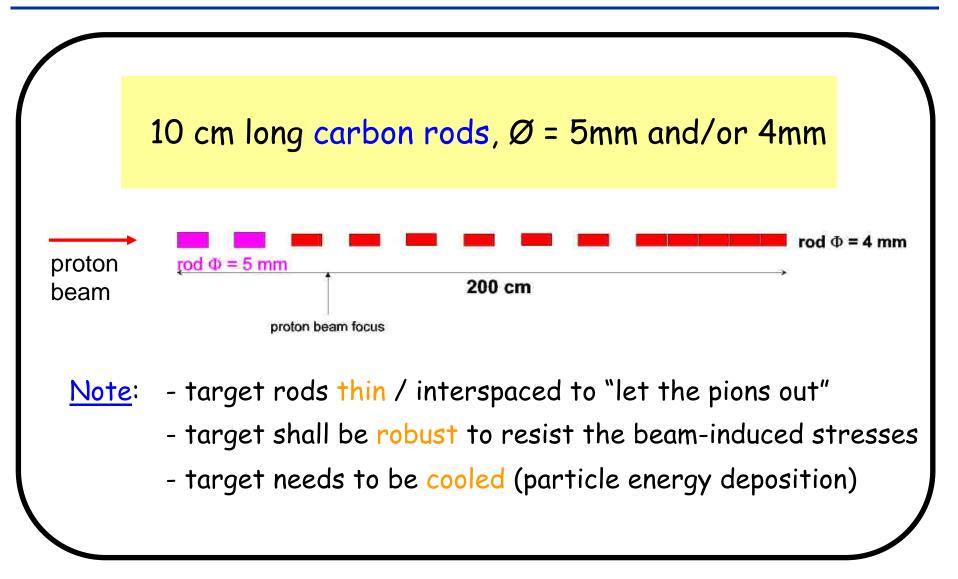


#### The CNGS Target has to ...

... interact with a <u>high intensity</u>, <u>well focused fast</u> <u>extracted</u> beam of <u>750 kW</u> average power. The target must be located along the beam path within <u>±0.1mm</u> in the transversal direction and must withstand the <u>thermo-</u> <u>mechanical shock</u> and evacuate the deposited <u>thermal</u> <u>energy</u>. Spare targets, remote alignment and monitoring are required.

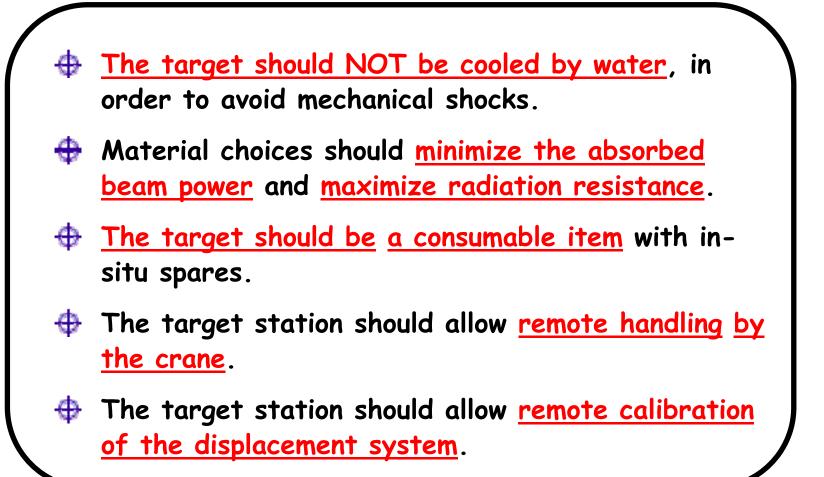
### The target elements





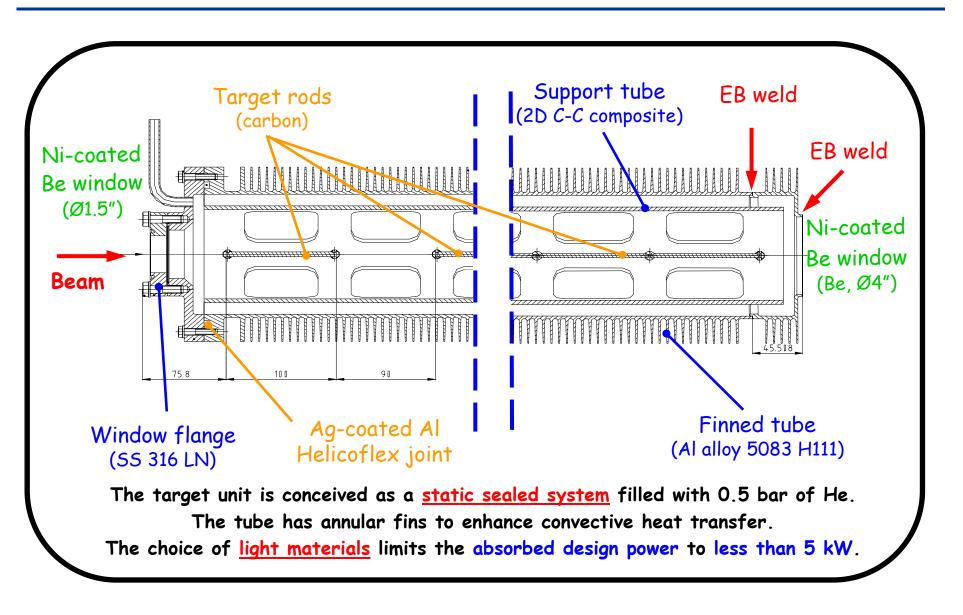






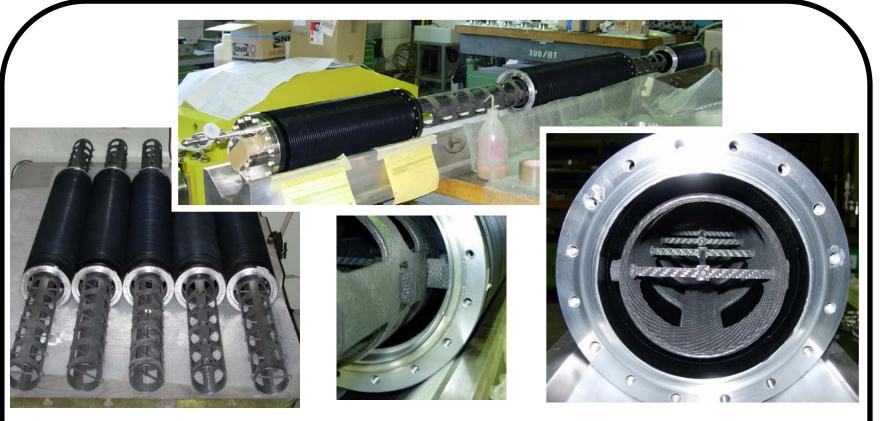






### The target units

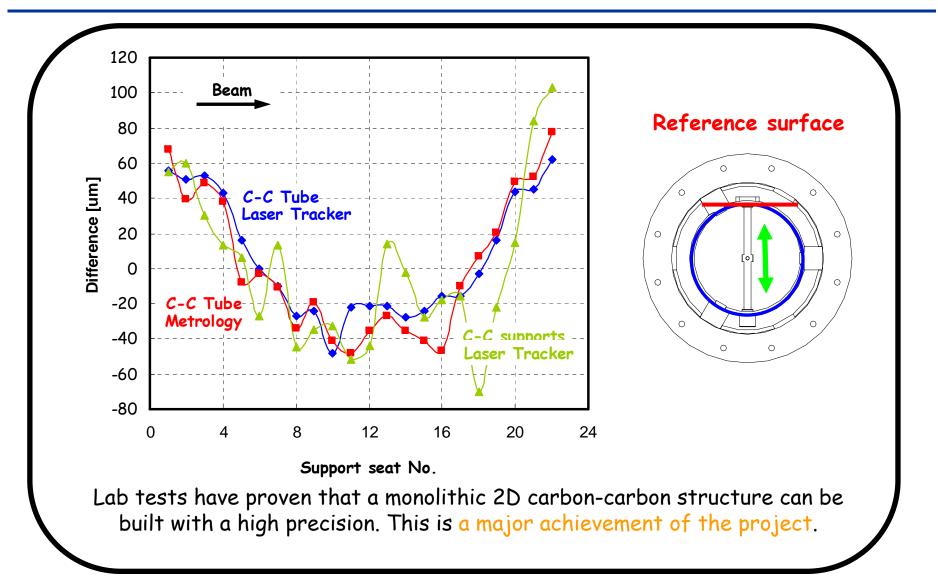




Ten targets (+1 prototype) have been built. They are assembled in two magazines worth 500 kCHF each.

#### **Target rod alignment** Results of the lab measurements

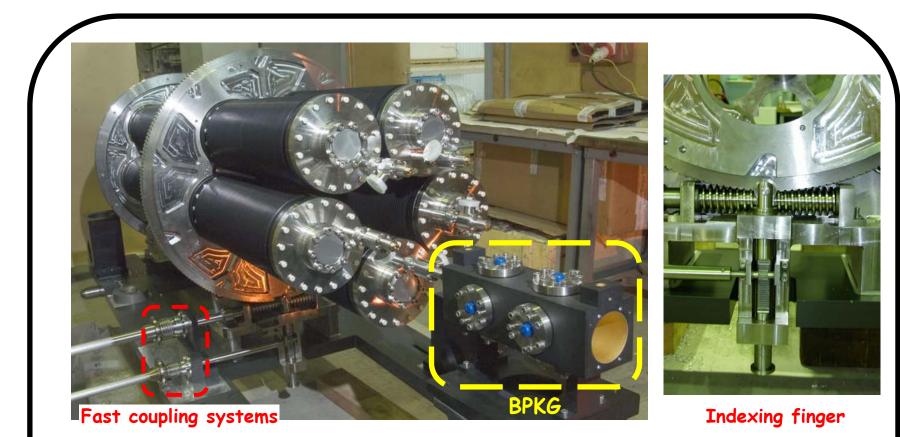




### The CNGS Target Station as-built

### The target magazine





The commissioning experience has proved that the active target unit can be changed with an in-situ spare within 15 min. Still, an erratic time-out when disengaging the indexing finger has been detected which requires a reset of the exchange system. This is being investigated on the target spare.

# The first target magazine...

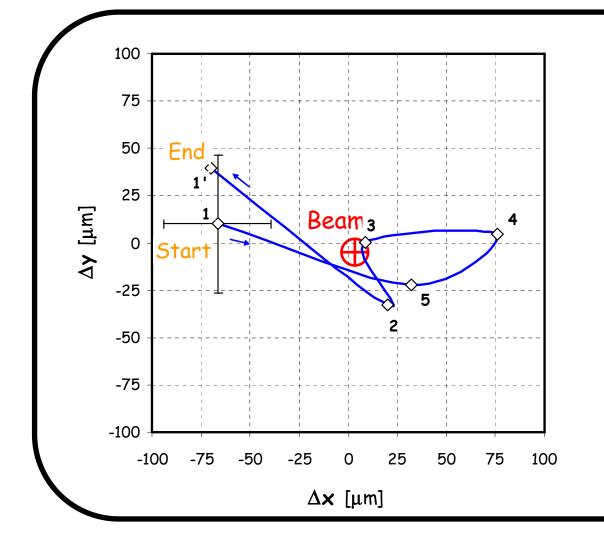


### ...Is equipped as follows:

- 1. Graphite target with baseline geometry under helium (Graphite 2020PT by Carbone Lorraine);
- 2. Carbon target with baseline geometry under helium (Sintered Carbon SC24 by Sintec Keramik);
- 3. C-C composite target with baseline geometry under helium (Aerolor A035 by Carbone Lorraine);
- 4. Carbon target with baseline geometry under vacuum (Sintered Carbon SC24 by Sintec Keramik);
- "Safe" target: Graphite target with all Ø5mm rods under helium (possibility to increase the beam size, 2020PT);.

#### <u>Measured</u> rotation precision of the target magazine





The location of the active target has been measured by a laser-tracker during a complete rotation of the target magazine.

The discrepancies shown in the diagram cumulate the local machining tolerances and the global precision of the target rotation mechanism.

The results are within the required precision of ±100 µm.

#### CNGS target rod alignment Control by the laser tracker





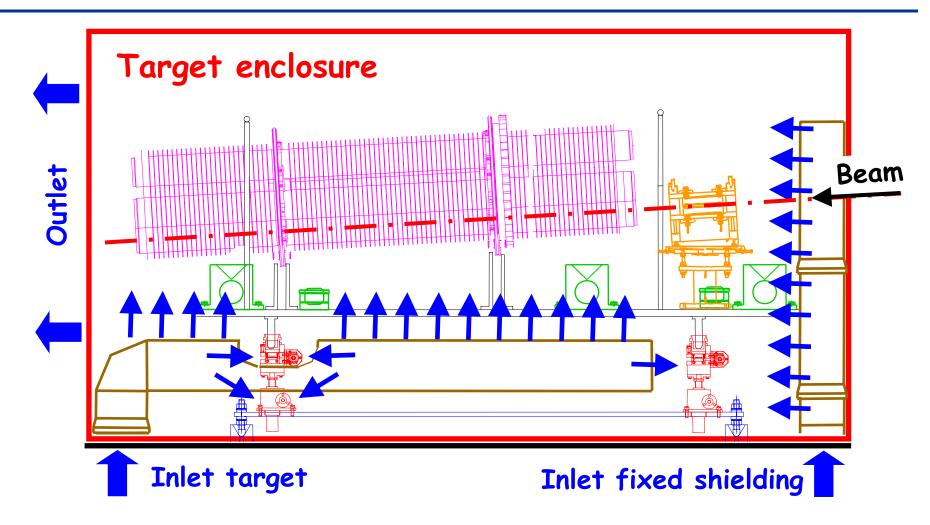
#### **C-C Tube prototype** Control at CERN - August 2004





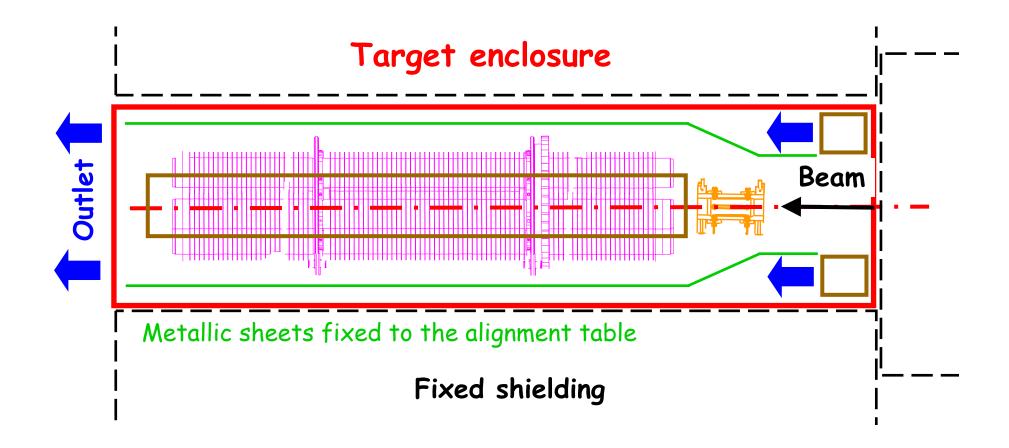
### Air cooling Schematic side view





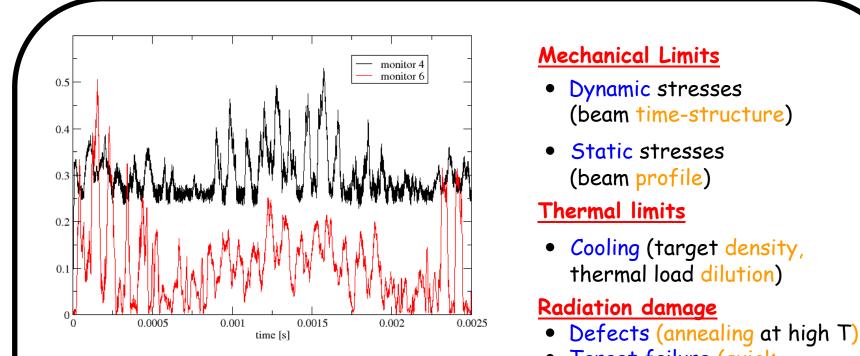
# Air cooling Schematic top view





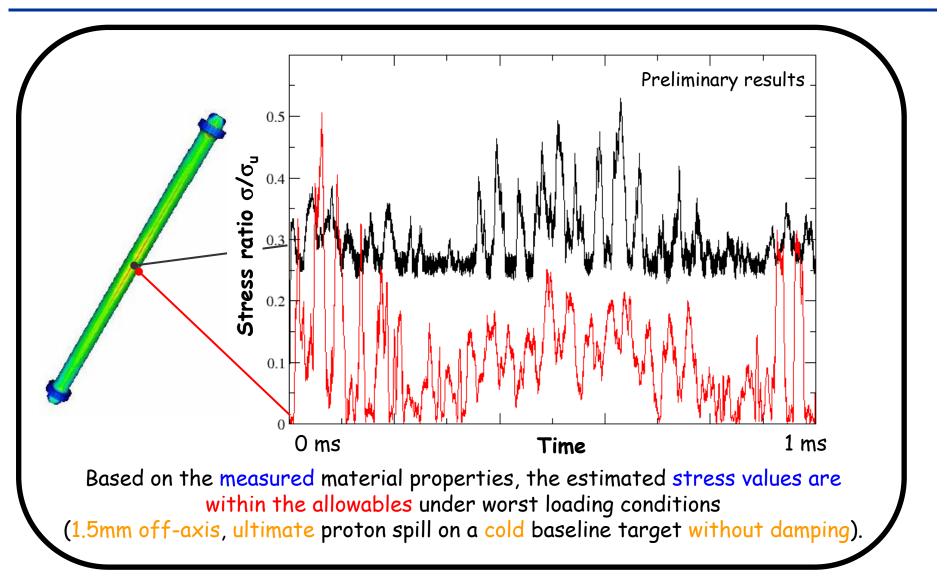
### Engineering limits of the CNGS target





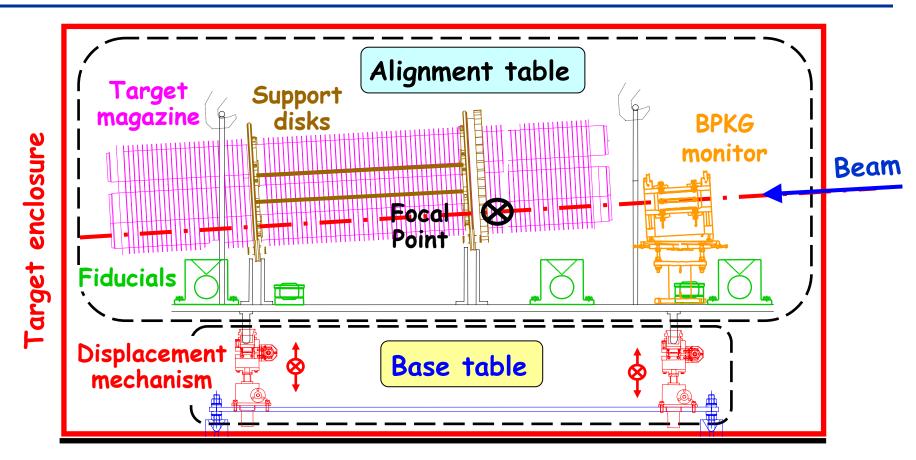
Presently, the limit of the CNGS target is set by the dynamic stresses. Spreading the extracted protons more batches and increasing the spacing of the proton extractions would allow to increase the proton beam intensity beyond 1 MW. • Target failure (quick exchange, in-situ spares) Estimated Target Stress Measured material properties





### Handling principles



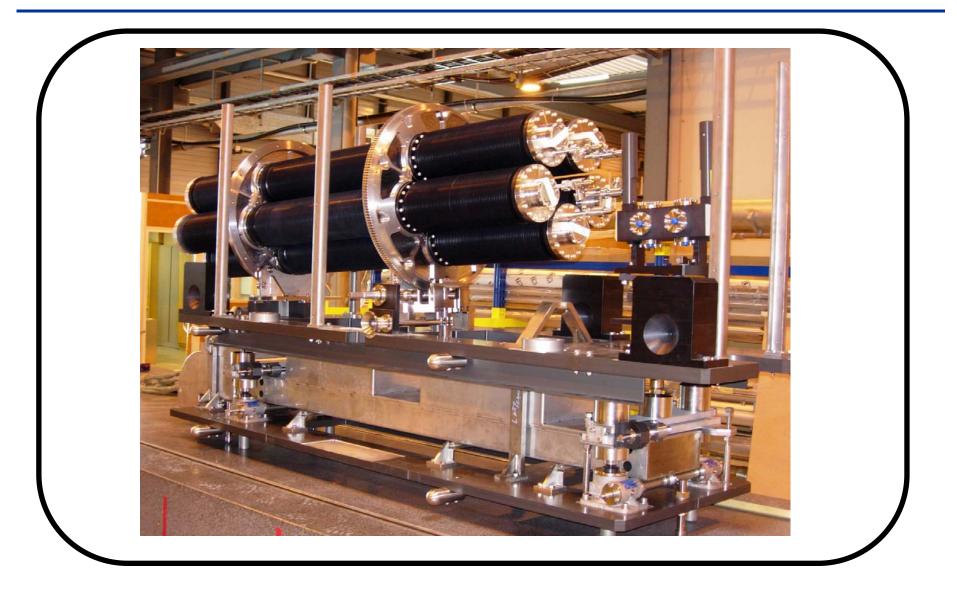


#### Shielding

The target magazine is mechanically coupled to the BPKG monitor. They are aligned in the lab and are remotely handled as a single component (the « alignment table »). They rest on the « base table », bearing the displacement mechanisms. The cooling manifold is not shown.

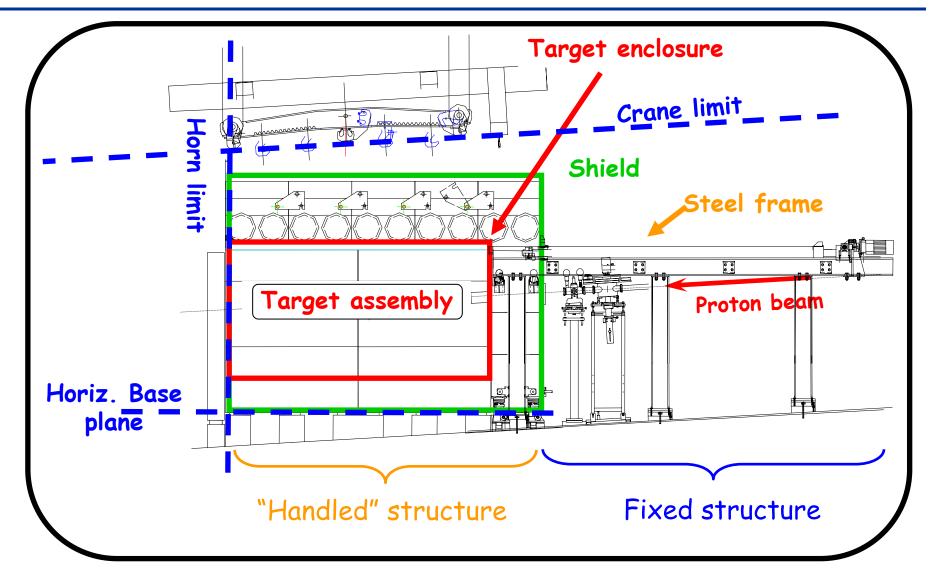
### The CNGS Target as-built The Target Assembly





### T40 - Schematic Vertical view





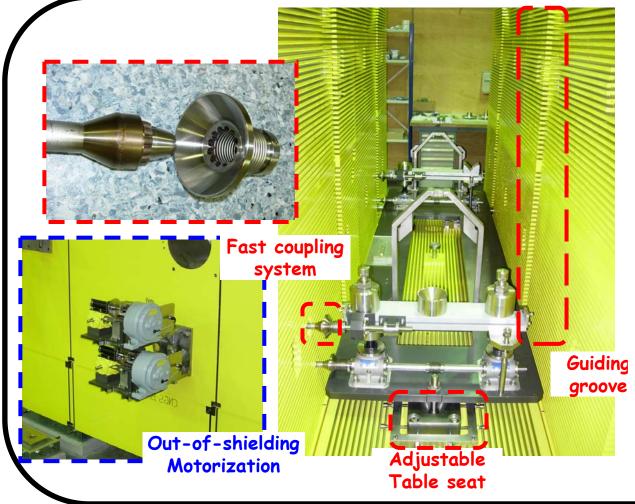
#### The CNGS Target Station as-built The target within its shielding





### The base table





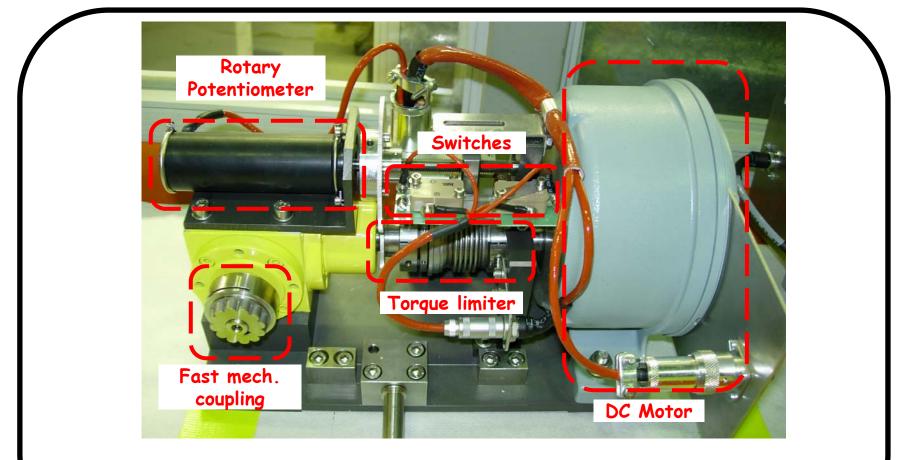
The base table is placed automatically by guiding grooves on three adjustable seats.

The motorization driving the table mechanisms is located out of the shielding.

The connection is realized through the shielding by shafts provided with fast coupling systems.

## Alignment Motorization Main parts

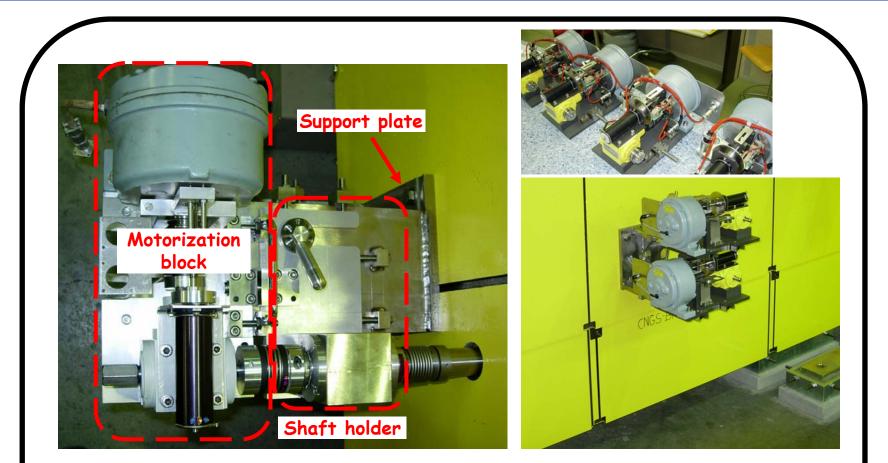




The <u>four</u> alignment motorizations have been assembled, cabled and successfully tested in the lab with the final local electronic control system.

## Alignment Motorization Assembly





Each motorization block is mounted together with a shaft holder on a support plate fixed to the shielding. The motorization and the holder can be easily (de)mounted (< 60 sec) for maintenance.





