

Boosted Object Tagging With Deep Networks

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Background: Boosted $H \rightarrow bb$

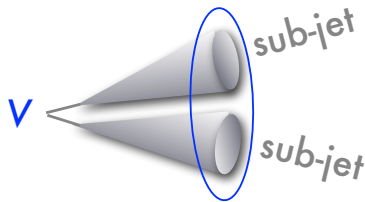
... for the sake of example

Calorimeter

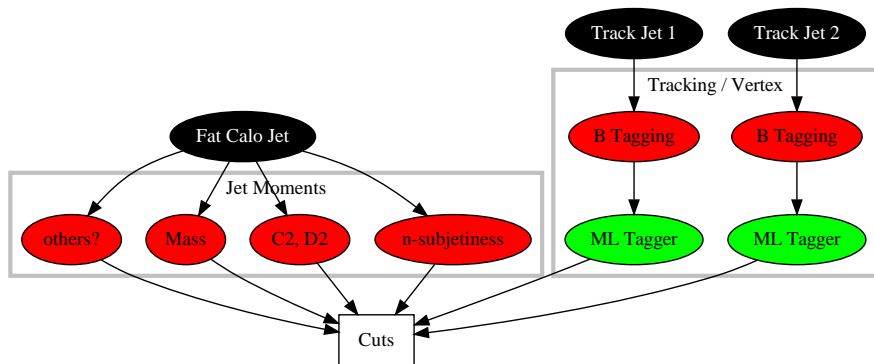
- ▶ EW scale particle V recoils against something
- ▶ Two-pronged energy deposit in the calorimeter \rightarrow “fat jet”
- ▶ Use jet moments as discriminants
 - ▶ τ_{21}, C_2, D_2 etc...

Tracking

- ▶ We expect two b jets
- ▶ Find subjets
- ▶ Run flavor tagging

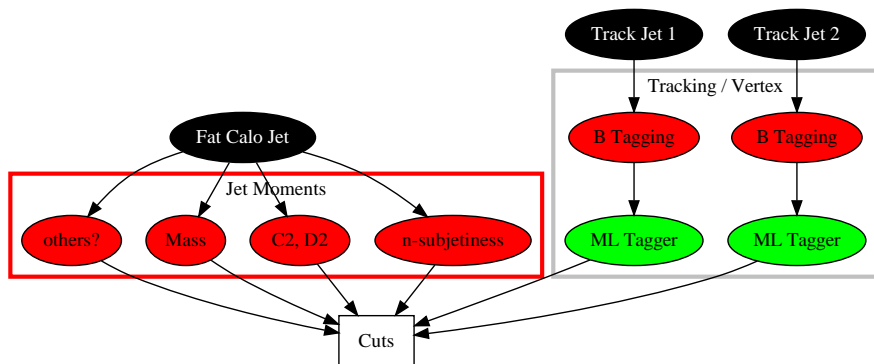


Boosted $H \rightarrow bb$: Algorithmic Overview



- ▶ Many levels of filtering / compression
 - ▶ *Are we missing something?*
- ▶ Lots of BDTs/NNs already
 - ▶ *Can we simplify this?*

Part 1: The Calorimeter

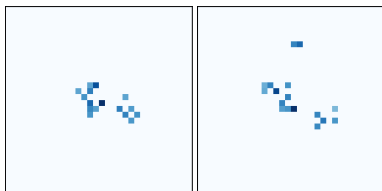


- ▶ The idea: replace jet moments with “jet images”
 - ▶ Original paper: [arXiv:1407.5675](https://arxiv.org/abs/1407.5675)
 - ▶ NN addition: [arXiv:1511.05190](https://arxiv.org/abs/1511.05190)
 - ▶ **This talk:** [arXiv:1603.09349](https://arxiv.org/abs/1603.09349)

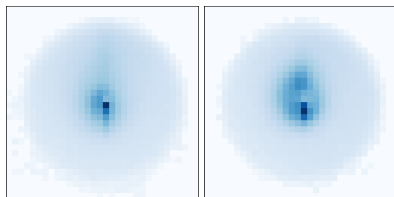
What is this “Image”?

- ▶ The idea: a jet is just an image in the calorimeter
- ▶ Discretized as $32 \times 32 = 1024$ pixel image
- ▶ We assume rotational symmetry (but don't have to)
- ▶ We can use standard image recognition
 - ▶ Deep neural networks have shown the best results
- ▶ See previous talk!

One Jet

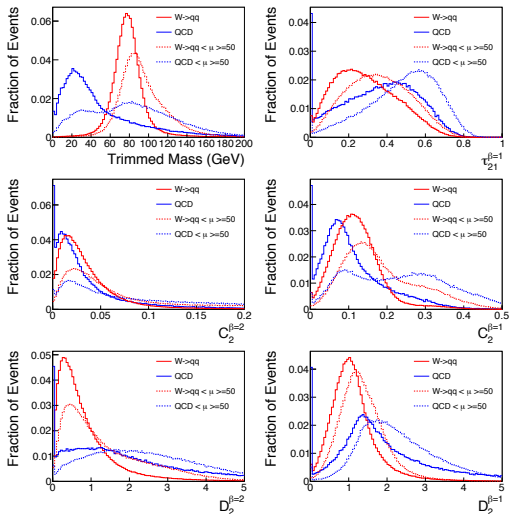


100,000 Jets

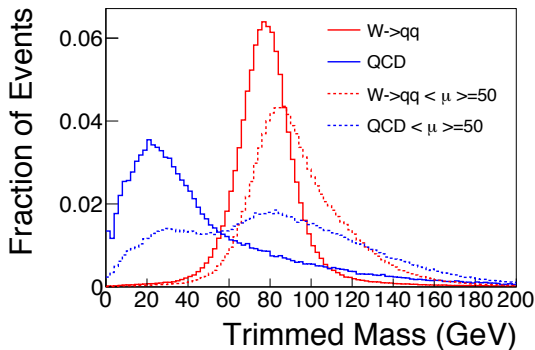


What to compare images to? Jet Moments

- ▶ Which one to use?
- ▶ One, many?
- ▶ Combinations?
- ▶ For the sake of argument feed them *all* to a BDT



Adding Realism



- ▶ We can get (halfway) to reality with Delphes
- ▶ Detector response smears hadron momentum
- ▶ Pileup interactions make a *huge* difference
 - ▶ ... even with pileup suppression applied

Our Setup

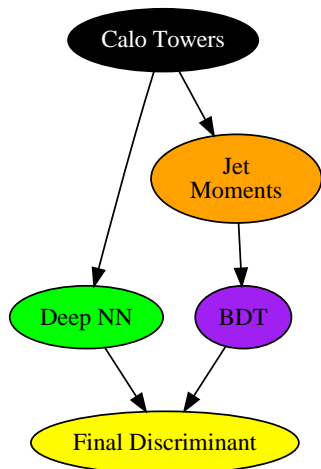
- ▶ Used Delphes, $\sqrt{s} = 14 \text{ TeV}$, $\langle\mu\rangle = 50$
- ▶ Signal: $pp \rightarrow WW \rightarrow qqqq$
- ▶ Background: $pp \rightarrow qq, q, gg$
- ▶ Anti- k_T jets $\Delta R = 1.2$
- ▶ $300 \text{ GeV} < p_T < 400 \text{ GeV}$
- ▶ Apply pileup suppression (trimming)

The Question

If we compare

- ▶ A BDT on engineered variables, to
- ▶ A deep network on the jet image

which one is a better classifier?



Training

- ▶ 10M Jets (500k for validation)
- ▶ Used Spearmint Bayesian optimization ([arXiv:1206.2944](https://arxiv.org/abs/1206.2944))

Deep NN

Hyperparameter	Range		Optimum	
	Min	Max	No pileup	Pileup
Hidden units per layer	100	500	425	500
Fully-connected layers	1	5	4	5
Locally-connected layers	0	5	4	3

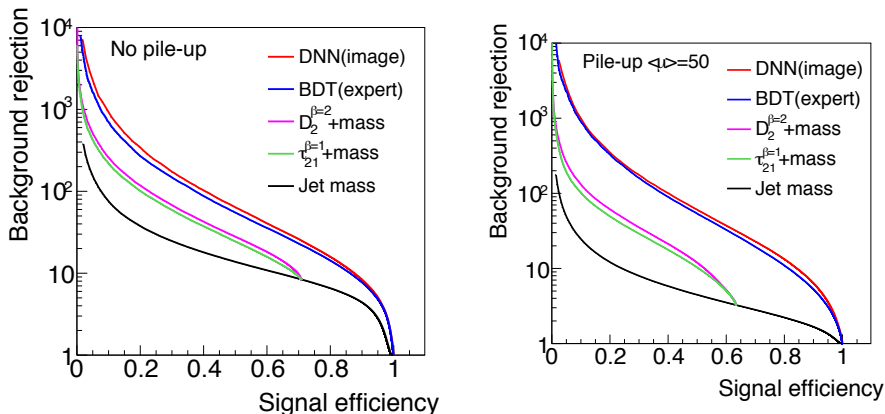
BDT

Hyperparameter	Range		Optimum	
	Min	Max	No pileup	Pileup
Tree depth	15	75	49	49
Learning rate	0.01	1.00	0.07	0.07
Minimum split percent	0.0001	0.1000	0.0021	0.0021

- ▶ 4×4 locally connected
→ fully connected
- ▶ Training: Theano + Keras
- ▶ ADAM optimizer
- ▶ **750k free parameters**

- ▶ Training: Scikit-Learn
- ▶ **750k free parameters**

Results

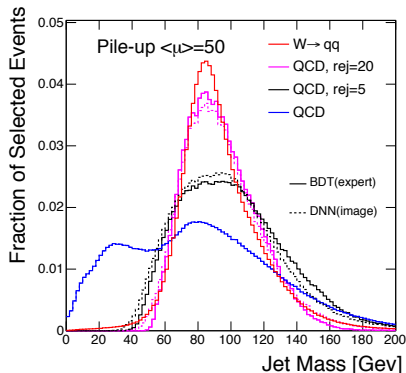


- ▶ Image NN outperforms moment BDT (slightly)
- ▶ Both seem to use more information than single moments
- ▶ Are they using the same information?

Moment Sculpting in Background

- ▶ Initially, **background** doesn't look like **signal**
- ▶ Cut on discriminant **background** \rightarrow **signal**
- ▶ ... unless the NN learns different information

- ▶ Rej = 5: **bgjets** starts to peak
- ▶ **Rej = 20** looks *a lot* like **signal**
- ▶ BDTs similar to NN
- ▶ NNs *learn mass, τ_{21} , etc*

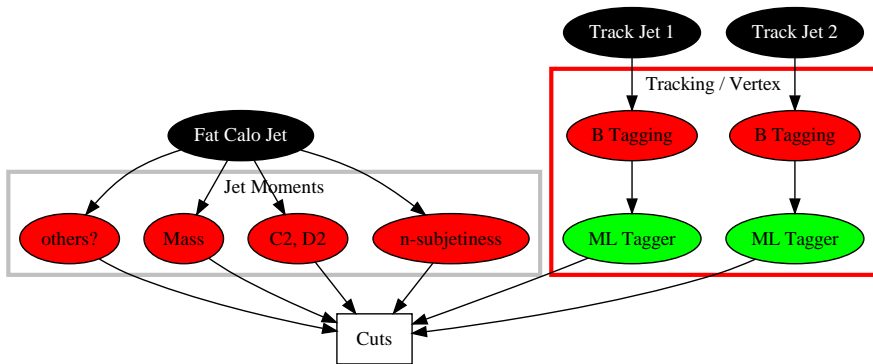


Calorimeter Conclusions

- ▶ Deep Network on image works slightly better than moment BDT
- ▶ But moments do *very well*
- ▶ *Most* of the information seems to be encoded in 6 variables
 - ▶ Good job QCD theorists!

What About Tracking?

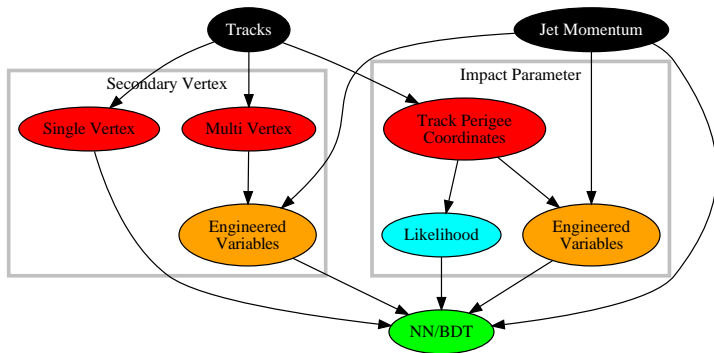
Flavor tagging based discriminants



- ▶ We can replace jet moments with raw inputs
- ▶ Can we do something similar for tracks?
- ▶ ML is more standard in flavor-tagging

Flavor Tagging is *Complicated*

Based on (simplified) ATLAS framework



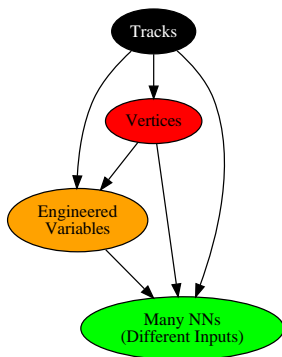
- ▶ Basically two algorithms + dimensionality reduction
- ▶ Each new feature → better discrimination
 - ▶ We still haven't found the right basis
- ▶ Hard to optimize, *can we simplify this?*

Our (even more) Simplified Setup

Details will appear on arXiv very soon

- ▶ $pp \rightarrow (qq, bb) \rightarrow$ Delphes
- ▶ Anti- k_T jets $\Delta R = 0.4$
- ▶ Start with **tracks**
 - ▶ Usually < 15
- ▶ Fit **vertices**
 - ▶ \sim two or three
- ▶ Build **HL Features**
 - ▶ **Always 14**

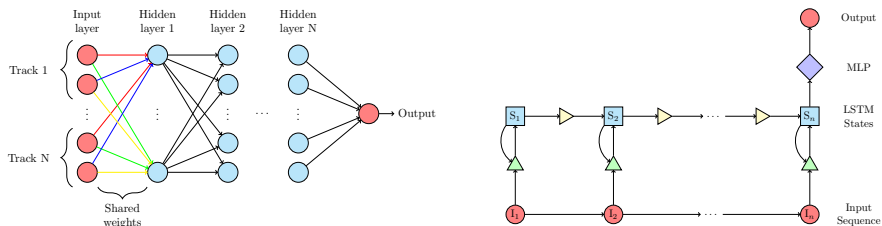
- ▶ HL is strictly derived from Vertex and Tracks
- ▶ Showing: $20 \text{ GeV} < p_T \lesssim 100 \text{ GeV}$
 - ▶ More boosted studies ongoing



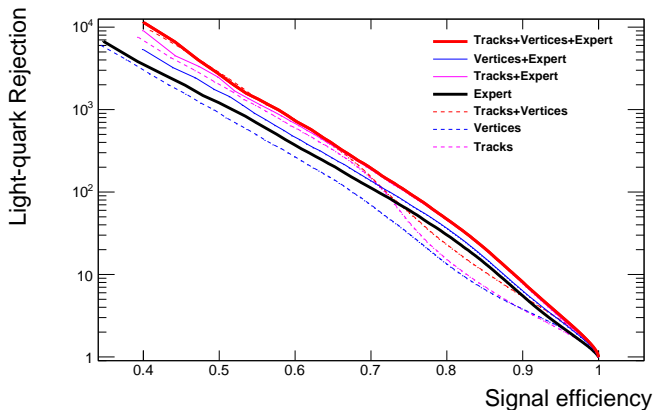
Challenges

Why hasn't someone already done this?

- ▶ No FASTJET for vertices
 - ▶ use Rave (thanks CMS)
- ▶ High (variable) dimensional input space
 - ▶ $15 \text{ tracks} \times 5 \text{ parameters} = 75 \text{ inputs}$ (but usually more)
 - ▶ That's a lot for HEP ML
 - ▶ But not bad for modern image / text processing



Results



- ▶ Low level information helps
- ▶ ... but tracks + vertices + expert features still beats all

Conclusions, Part 2

- ▶ Compared to the calo problem:
 - ▶ The tracking problem is more difficult for neural nets:
 - ▶ NN with track inputs *doesn't* beat expert features ...
 - ▶ ...even though the expert features are derived from tracks
 - ▶ The expert features gain more from the tracks
- ▶ Something like FASTVERTEX would be useful
 - ▶ Rave is a good start (bit hard to compile...)
 - ▶ Recent Delphes branch includes crude vertex algorithms

Conclusions and Ongoing Work

Summary

- ▶ Calo image as good as jet moments
- ▶ Raw tracks help the more traditional flavor tagging approach

Next Steps

- ▶ Many questions applying flavor tagging to $H \rightarrow bb$
 - ▶ How should subjets be selected? (if at all)
 - ▶ How much do we gain by including track + calo in one NN?

BACKUP

Flavor Tagging Inputs

