

The CMS

Timing *and*
Control
Distribution
System

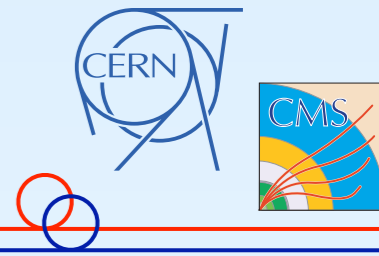


J. Troska

M. Hansen, J. Hegeman, F. Meijers, P. Vichoudis

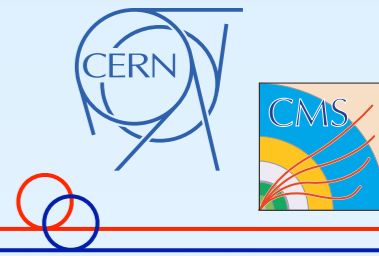
CERN-PH-ESE & CERN-PH-CMD

Overview

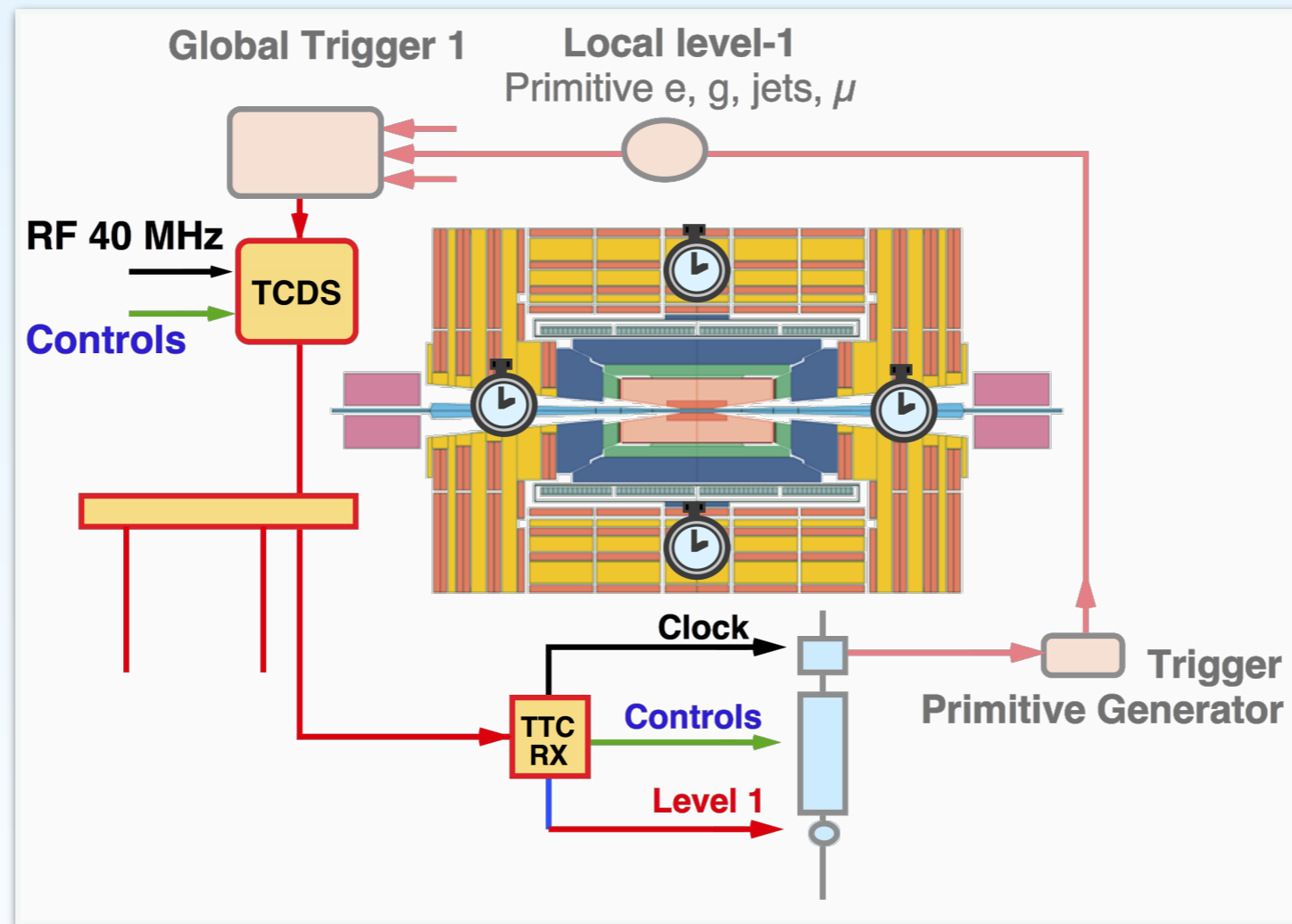


- Introduction to the CMS TCDS system
- Elements of the system
- System performance
- Operational experience
- Summary

Timing distribution introduction

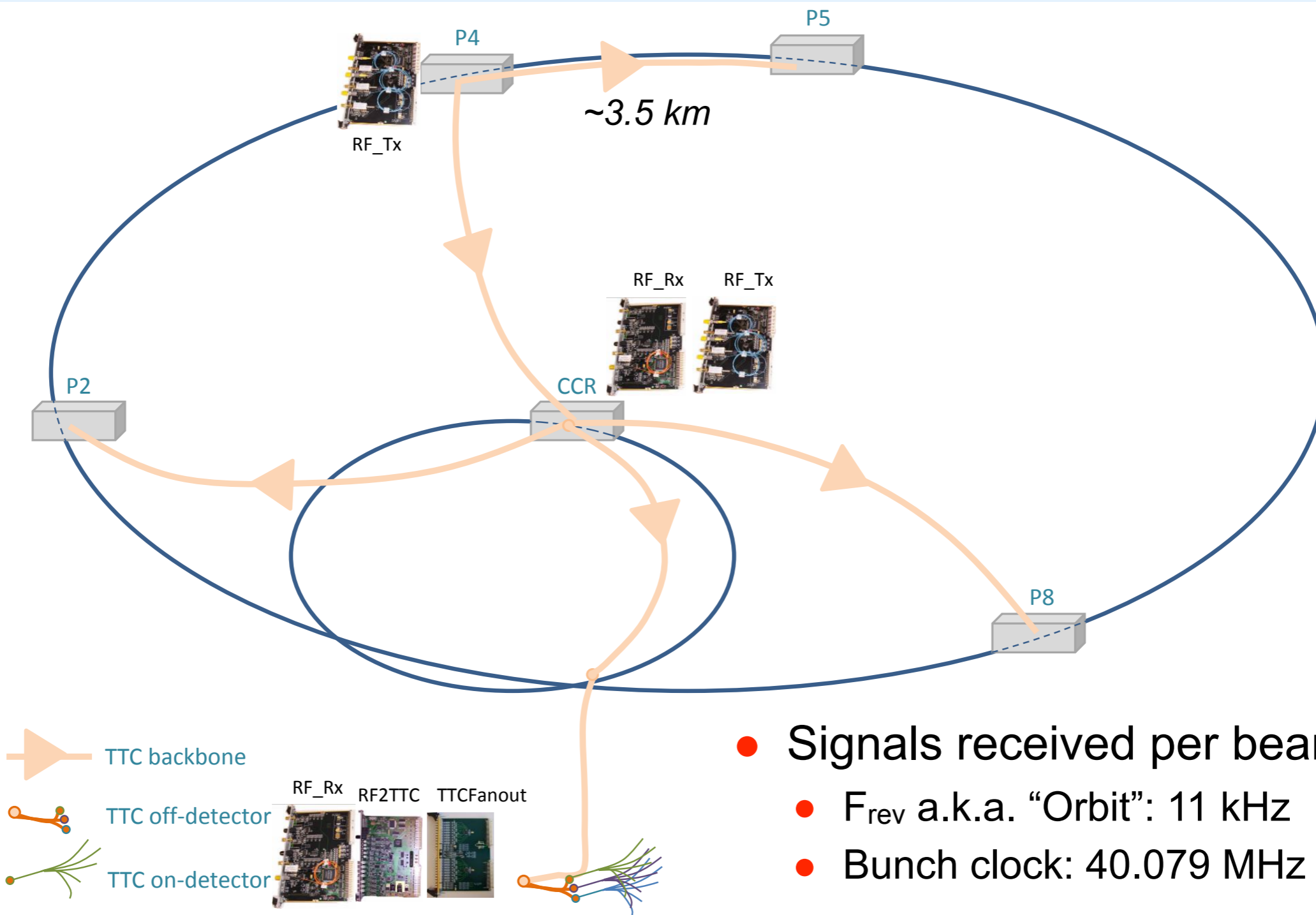


- Historical perspective:



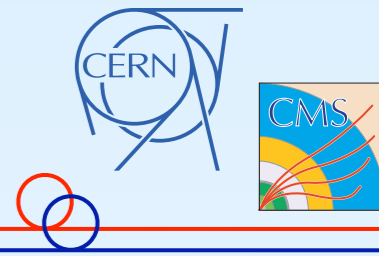
- LHC collision rate: 40 MHz
- CMS Level 1 Trigger rate: 100kHz
- CMS Level 1 Latency: 3.2 μ s

RF reference signals



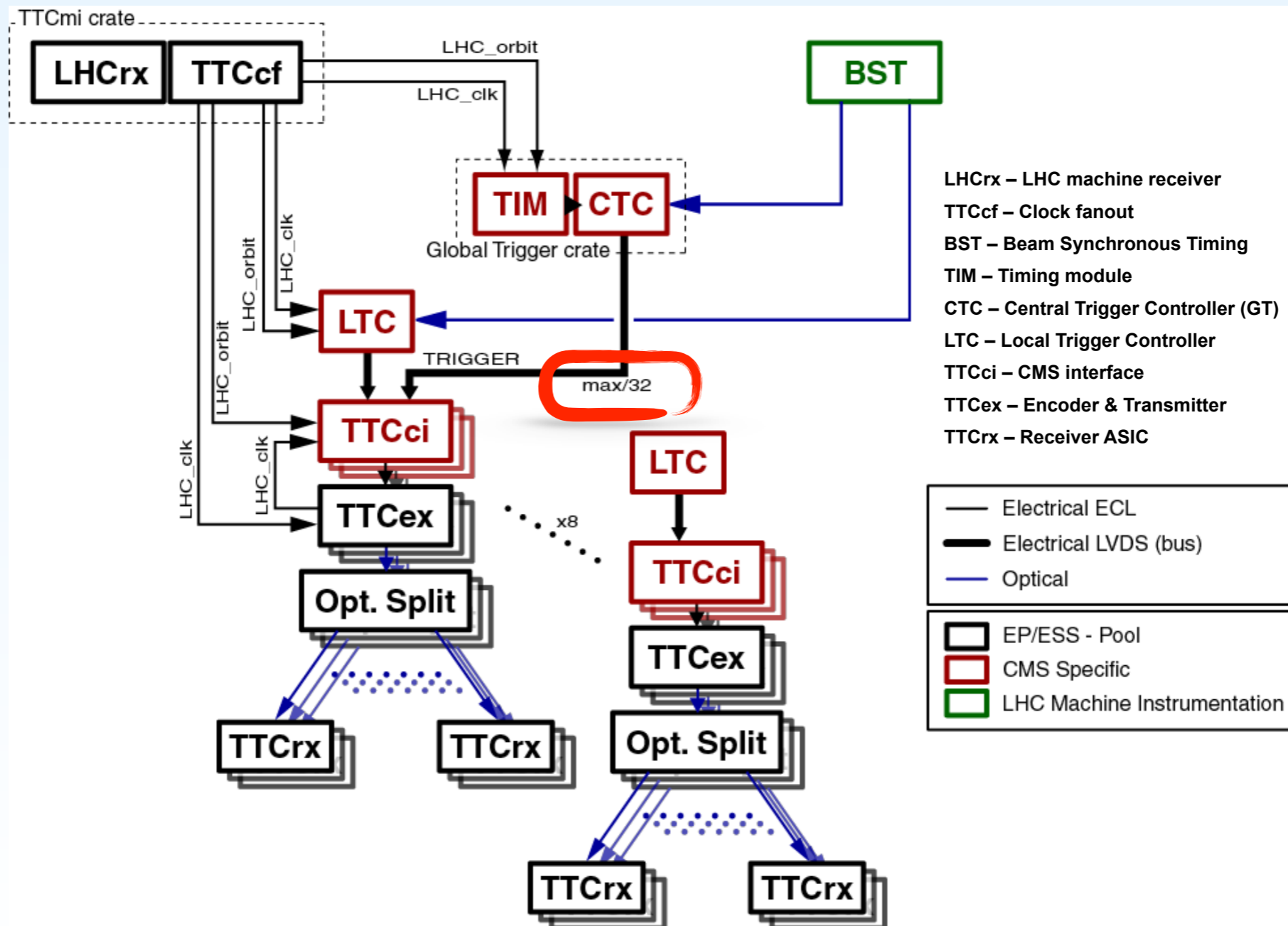
- Signals received per beam:
 - F_{rev} a.k.a. “Orbit”: 11 kHz
 - Bunch clock: 40.079 MHz

CMS Timing system for Run 1

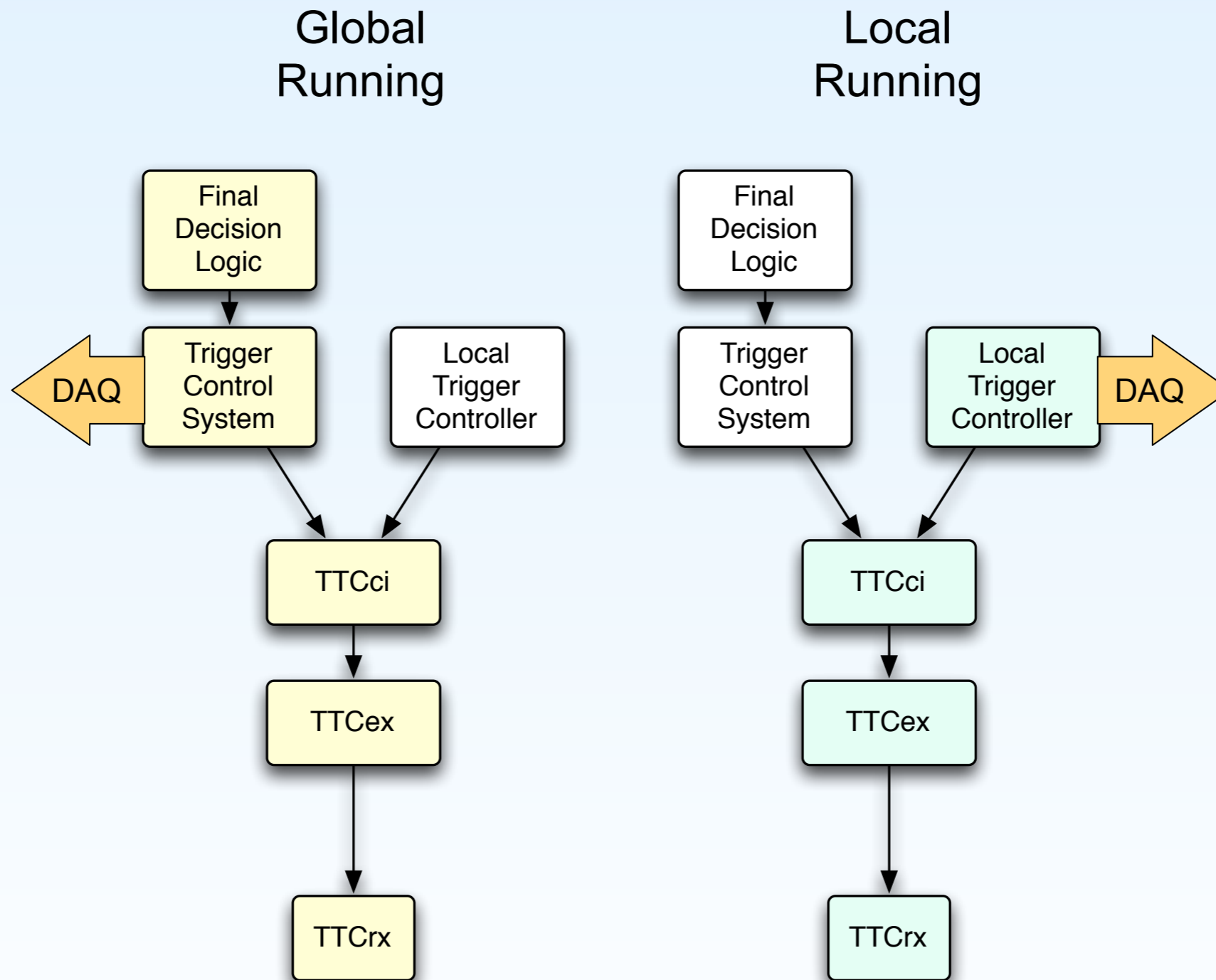
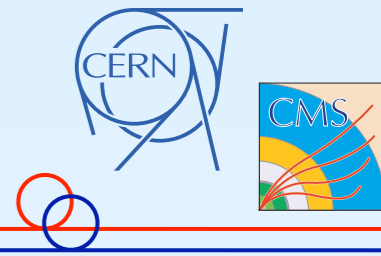


- Based upon RD12 TTC system
 - CMS-specific interface module (TTCci)

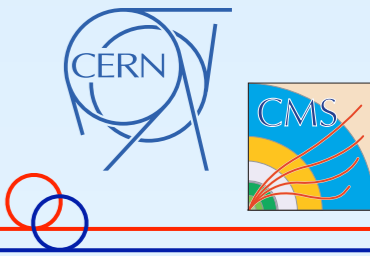
Signal Distribution only



Operation of Run 1 system

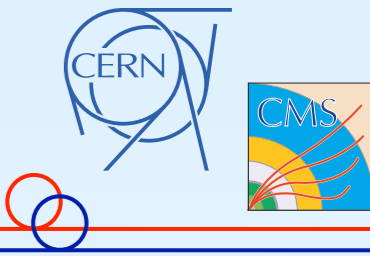


Why replace the timing distribution?

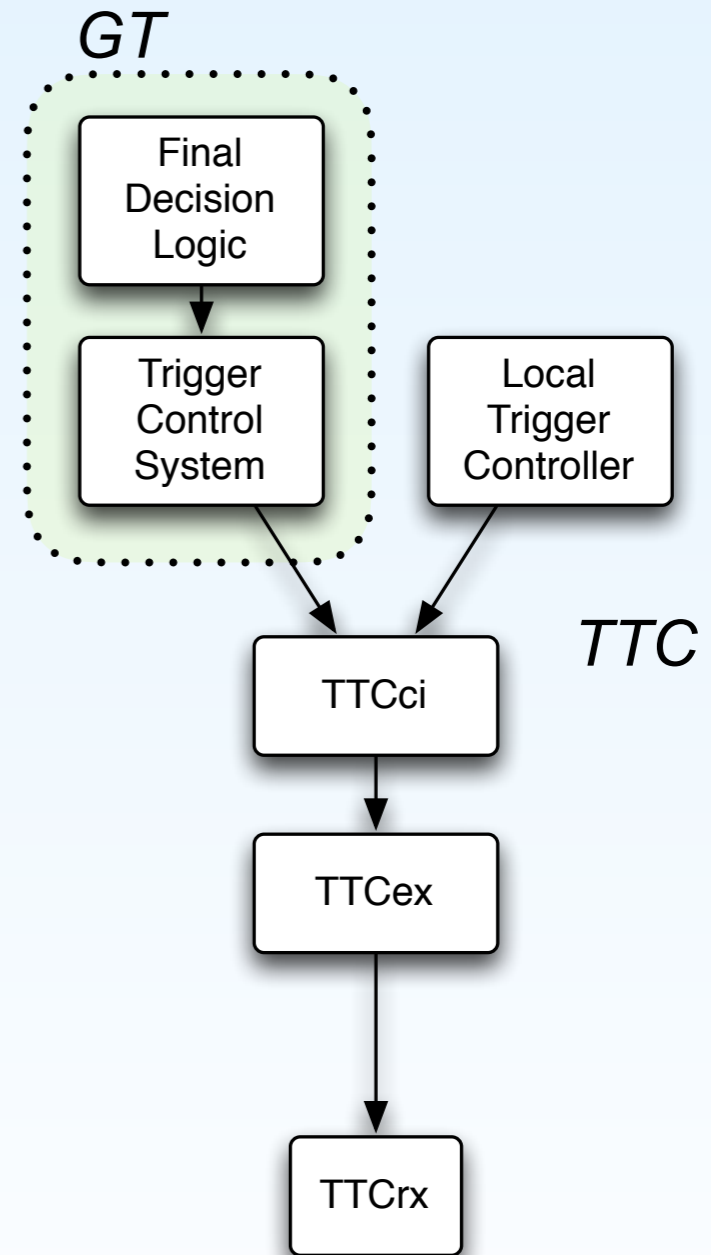


- CMS did not have enough partitions available in the existing system to service all requests coming out of LS1
 - 40 partitions requested

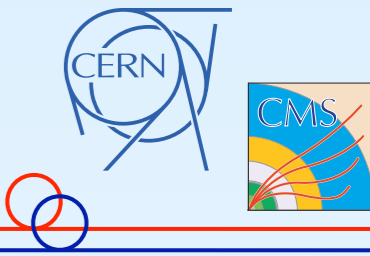
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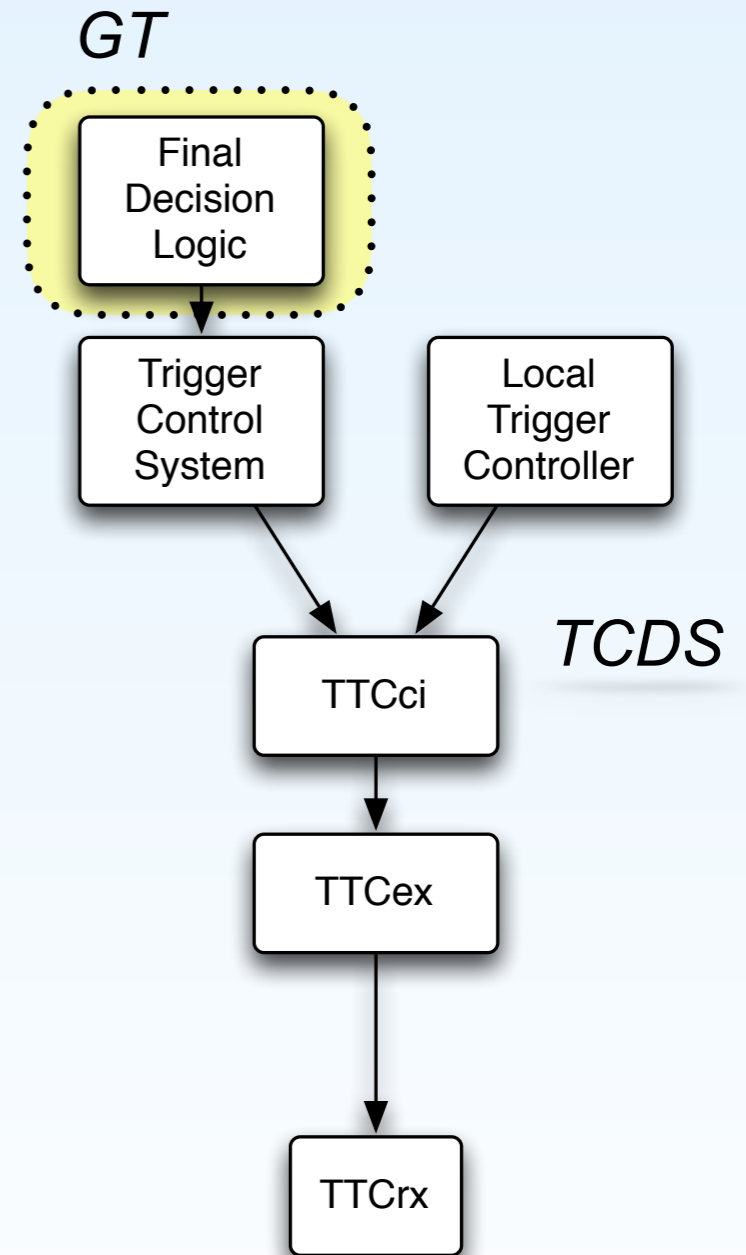
- CMS did not have enough partitions available in the existing system to service all requests coming out of LS1
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- Upgrade of CMS Global Trigger provided opportunity to revisit functional split
 - Physics Event Selection (FINOR)
 - Trigger Control System
 - Trigger and Timing Distribution



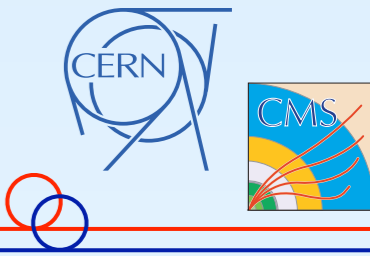
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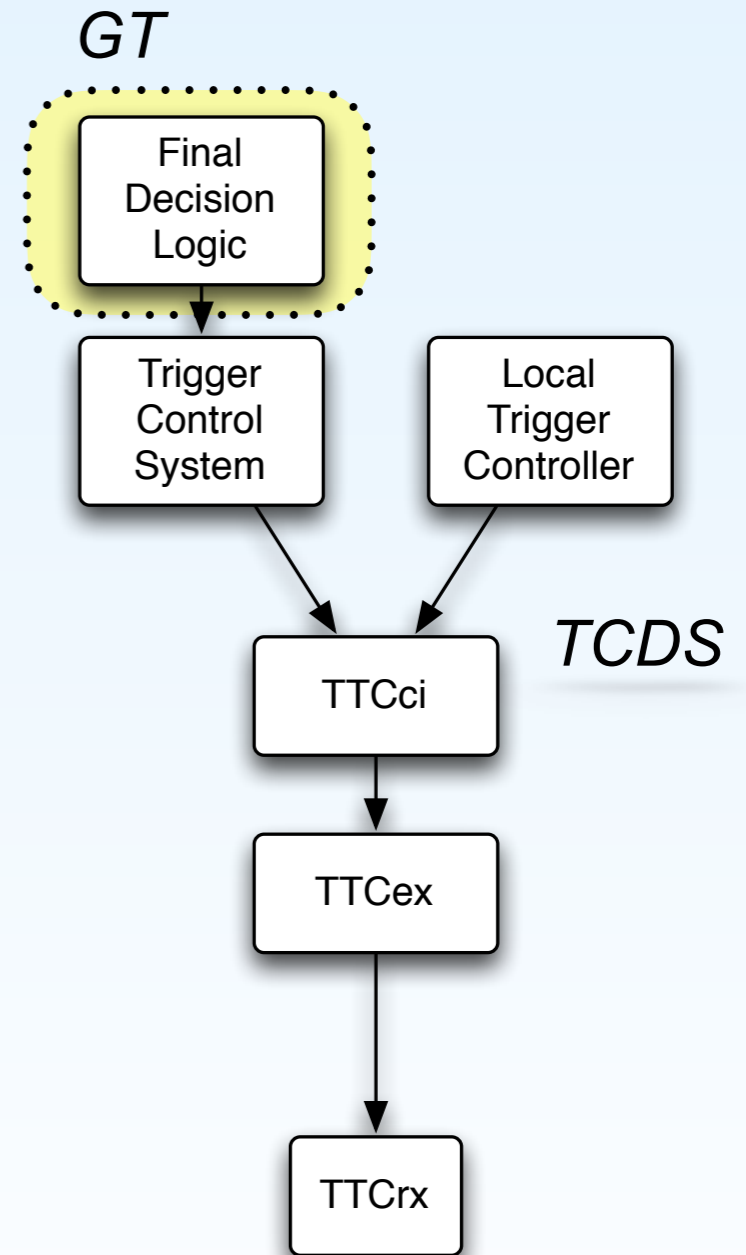
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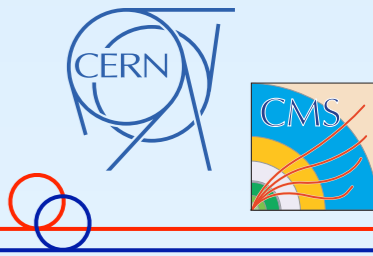
Why replace the timing distribution?



- CMS did not have enough partitions available in the existing system to service all requests coming out of LS1
 - 40 partitions requested
- Upgrade of CMS Global Trigger provided opportunity to revisit functional split
 - Physics Event Selection (FINOR)
 - Trigger Control System
 - Trigger and Timing Distribution
- Upgrade provided opportunity for new functionality
 - LumiDAQ synchronization
 - New Trigger rules, B-Gos

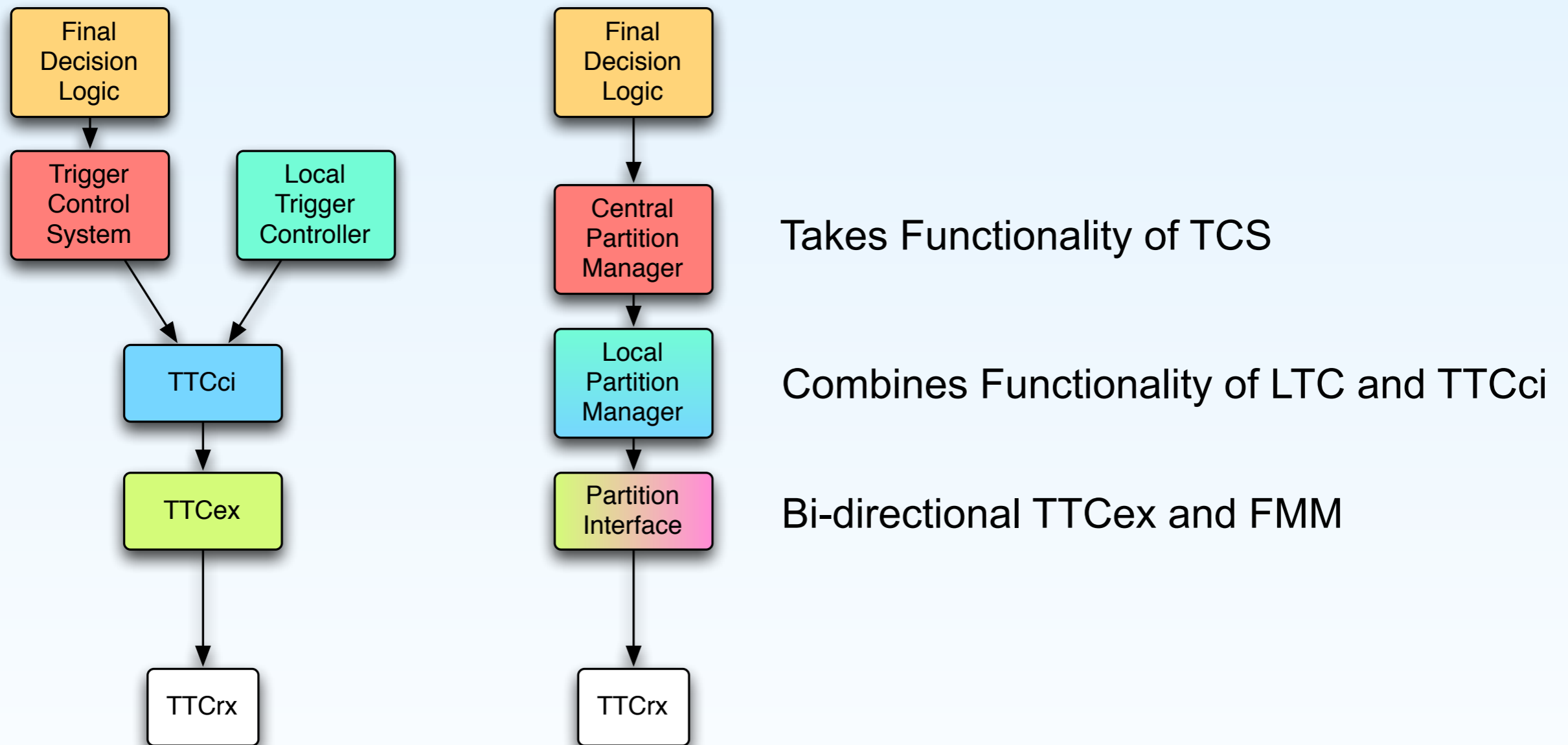
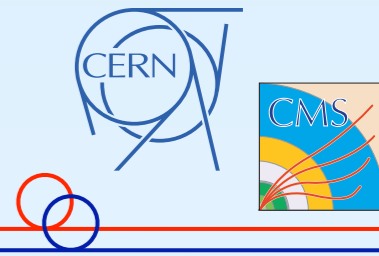


Basic ingredients for LS1 upgrade



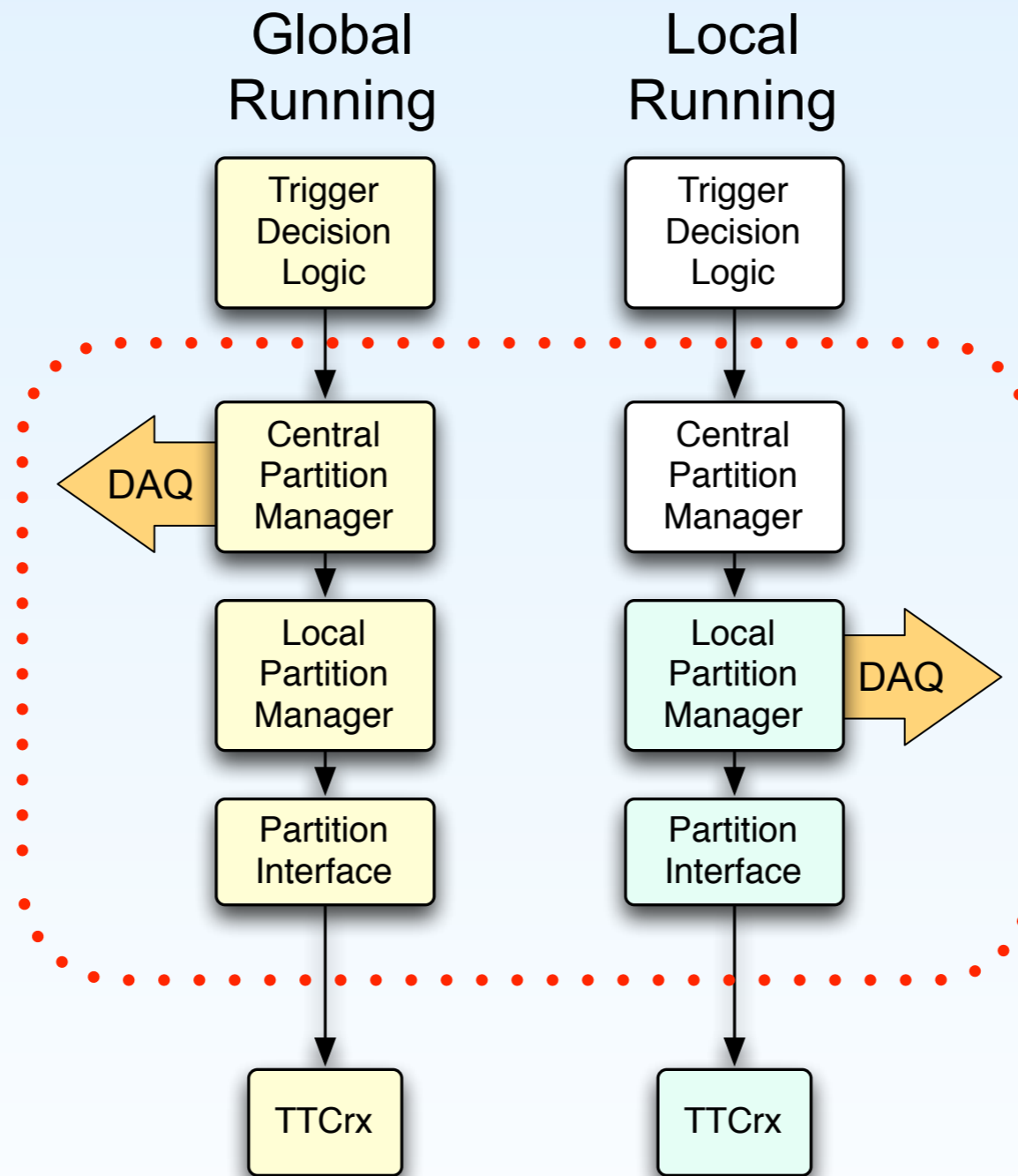
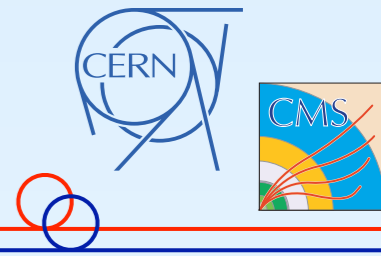
- **μTCA system**
 - Opportunity to exploit the use of backplane for distribution of synchronisation signals
- **Larger, more modern, FPGAs**
 - Kintex 7 series
 - More logic resources
 - Std i/o up to Gb/s
 - High-speed serial i/o up to 10 Gb/s
- **Common AMC designs used in multiple CMS systems**
 - FC7, AMC13
 - Customized “only” i/o FMCs and firmware

TCDS system Board overview

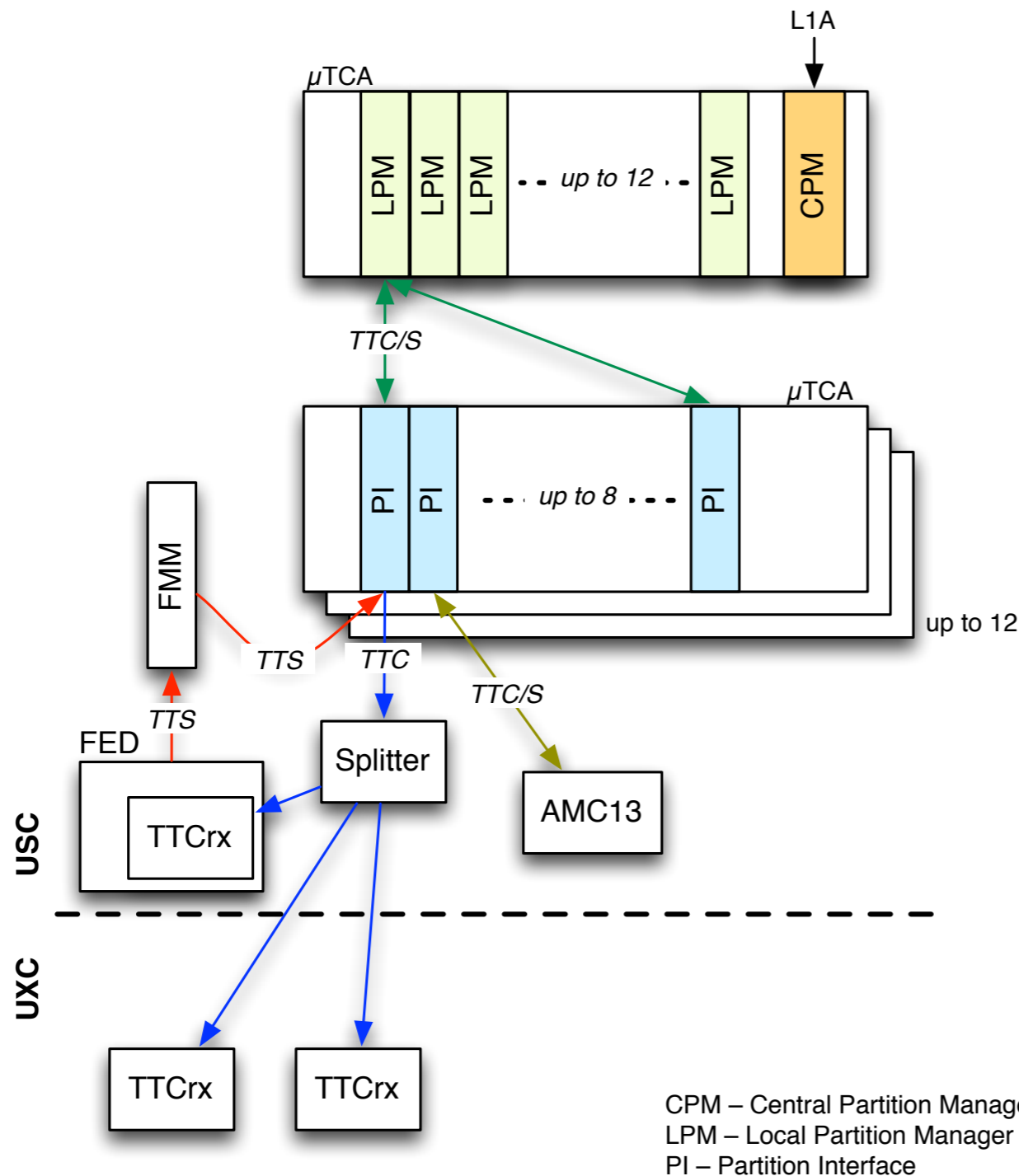
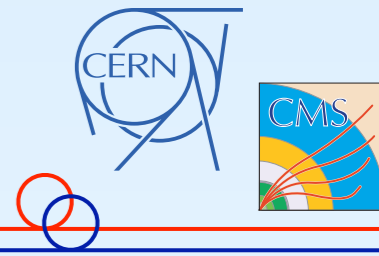


TCDS leverages μ TCA backplane comms

TCDS System Operation



TCDS System Diagram



- Overall system can have
 - Up to 12x LPMs
 - Up to 8x PIs per LPM
 - Total 96 partitions
- It is possible to add a redundant PM crate
 - For debugging, (sub-) system commissioning

AMC13 – CMS μ TCA readout board

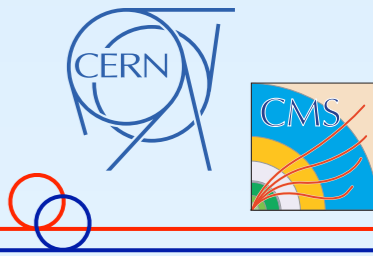
FMM – Fast Merging Module

TTC – Timing, Trigger & Control

TTCrx – TTC Receiver ASIC

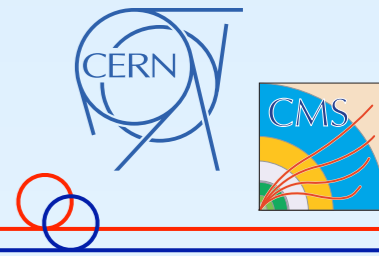
TTS – Trigger Throttling System

Overview



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Implementation: AMCs



- Based as far as possible on existing or already in development hardware
 - Double-width AMC: FC7
 - Single-width AMC and “crate controller”: AMC13



TWEPP-14
Aix en Provence, France |
22-26 September 2014

the FC7 AMC for
DAQ & control applications in CMS

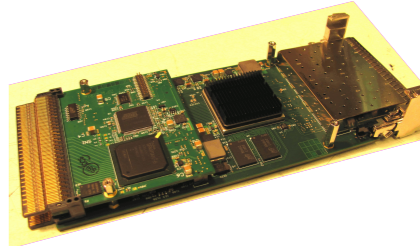

Mark Pesaresi (Imperial College), Paschalis Vichoudis (CERN)

Magnus Hansen, Manoel Barros Marin, Francois Vasey (CERN)
Greg Iles, Sarah Greenwood, Andrew Rose, Geoff Hall (Imperial College)



AMC13 Module
CMS MicroTCA Overview
E. Hazen – Boston University

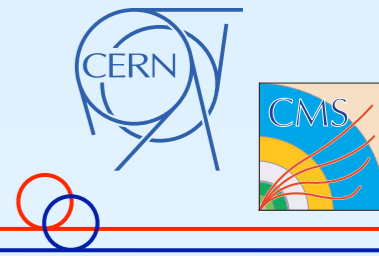
Representing the work of J. Rohlf, S.X. Wu, A. Heister, C. Hill, D. Zou, C. Woodall
at Boston University
and the CMS Collaboration worldwide



See <http://www.amc13.info> for detailed documentation

26 Sept 2013 E. Hazen - TWEPP 2013 1 / 40

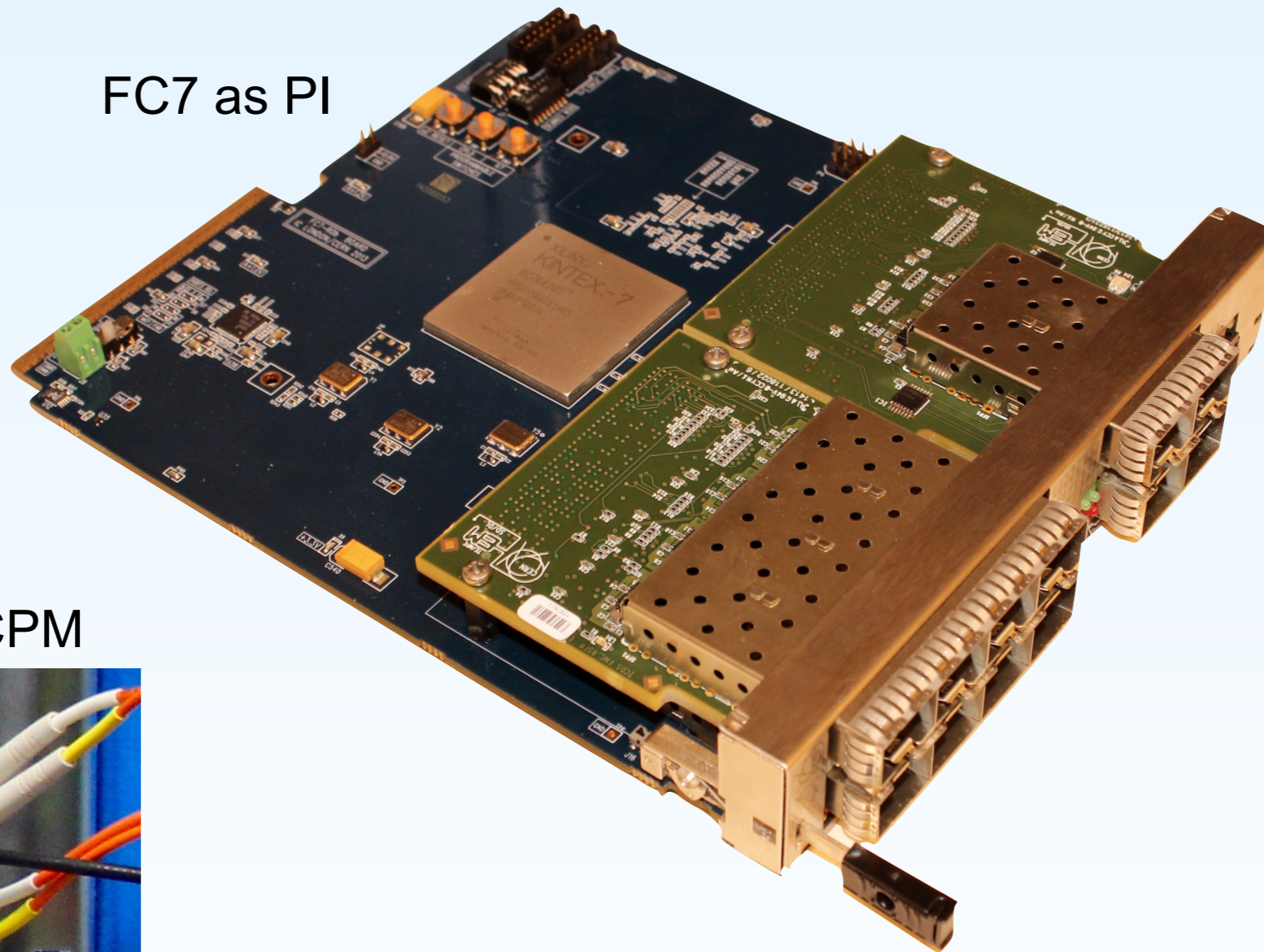
Implementation: mezzanine boards



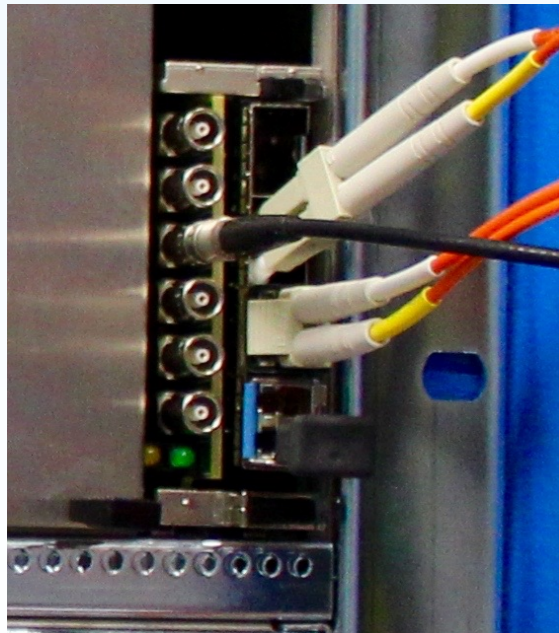
- Both FC7 and AMC13 customised through the addition of mezzanine boards
- FMCs for FC7
 - 8x SFP connected to FMC std. i/o for distribution of timing signals and reception of front-end status (TTS)
 - 4x SFP & 1x RJ45 connected to FMC std. i/o for distribution of timing signals and reception of front-end status (TTS)
 - 6x Lemo for clock, orbit, and local trigger inputs; plus 2x SFP+ connected to SerDes for DAQ interface
- Tongue-3 mezzanine for AMC13
 - 6x Lemo for clock, orbit, and trigger inputs, debug output

Finished AMCs

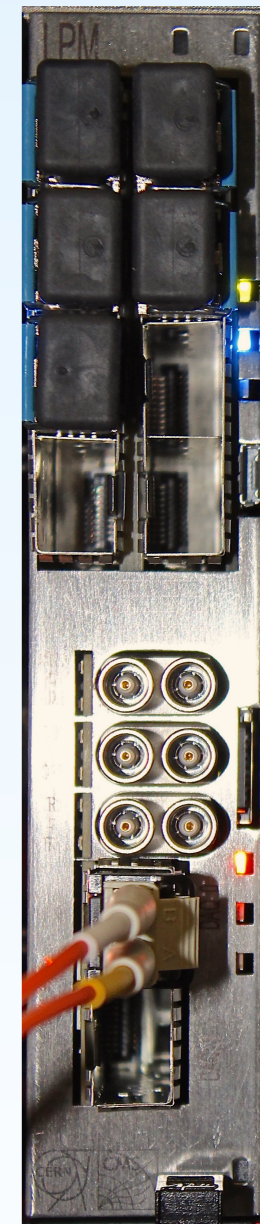
FC7 as PI



AMC13 as CPM

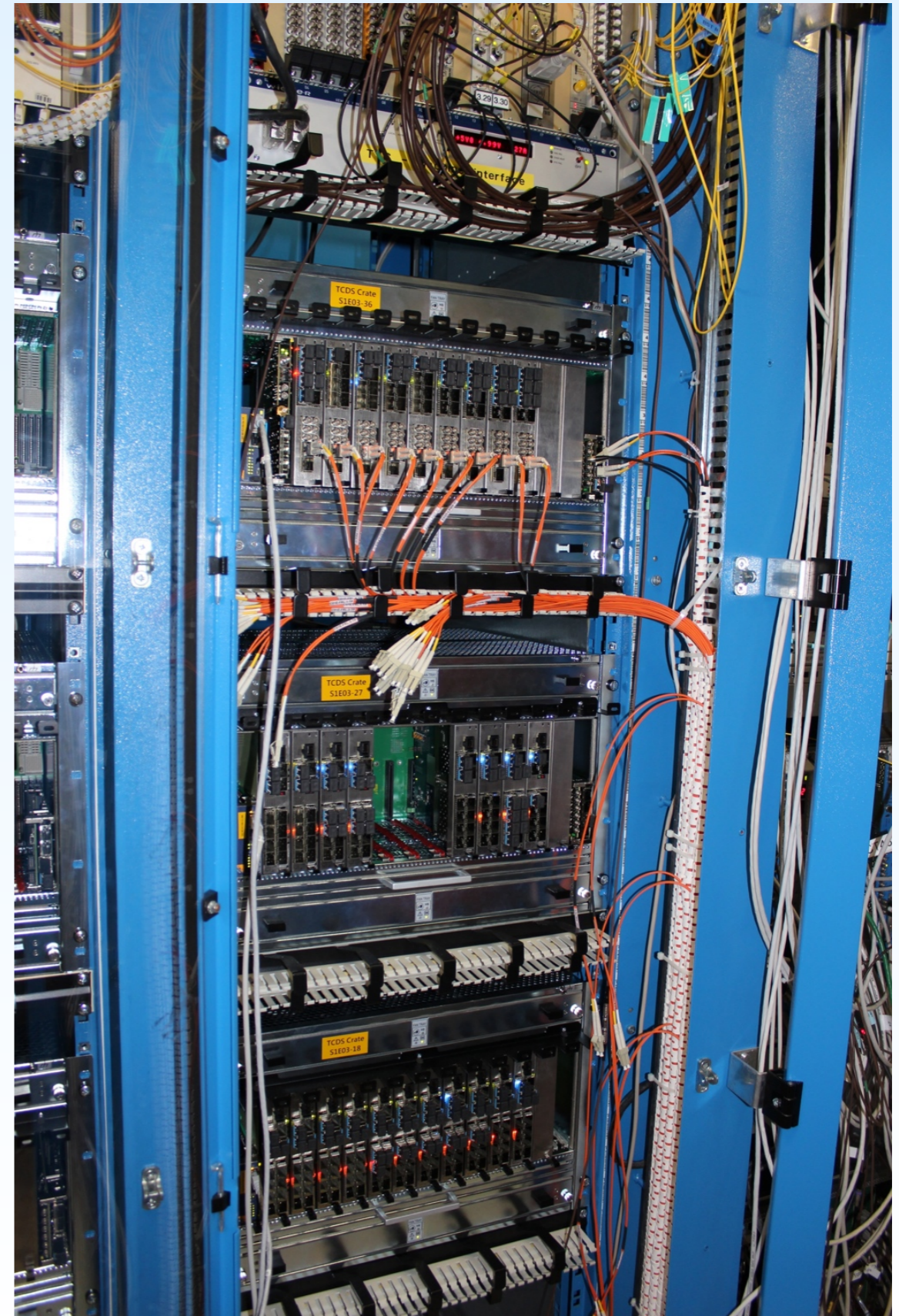


FC7 as LPM

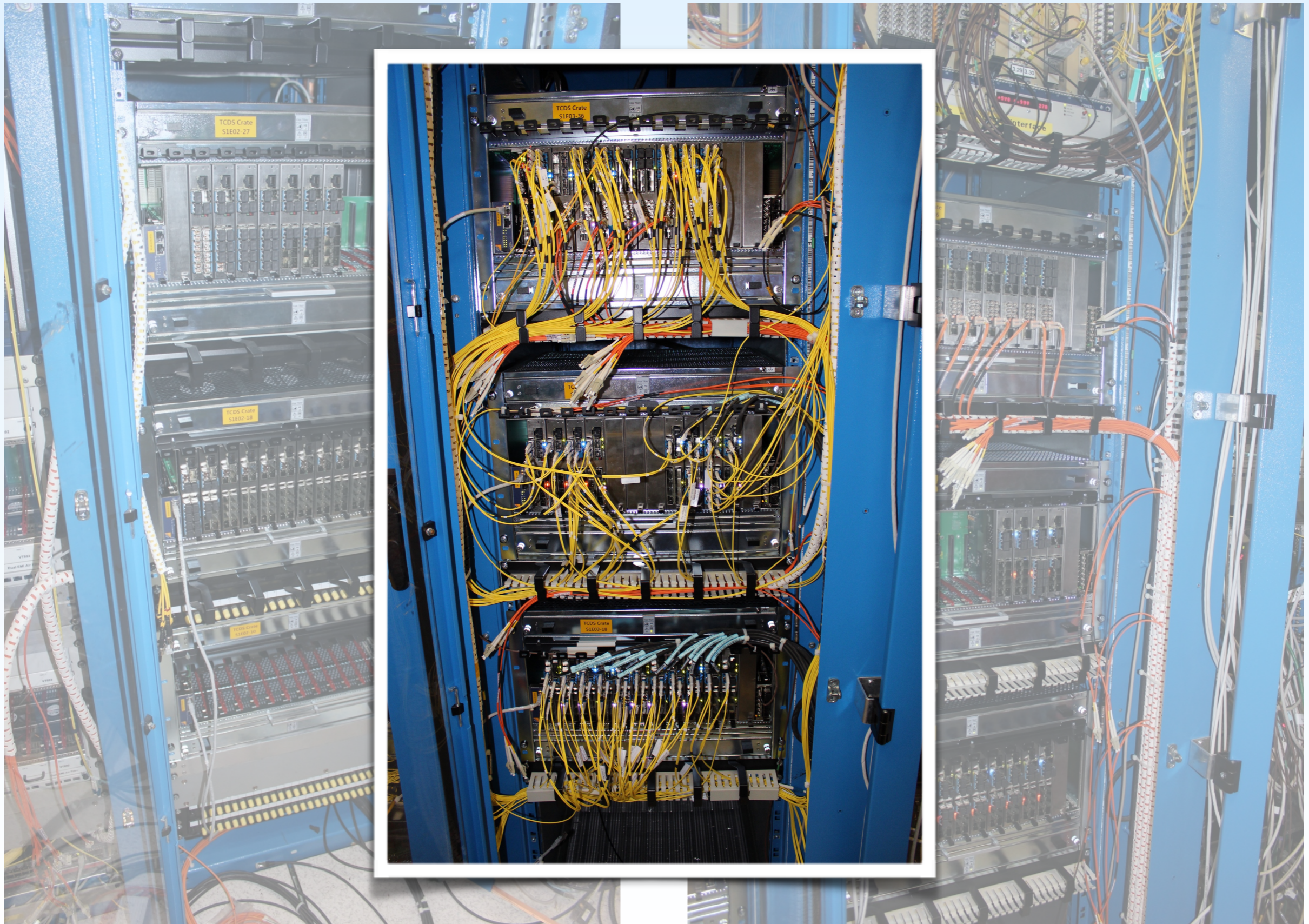
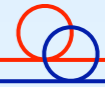


- **μTCA chassis from Schroff**
 - Custom development for redundant powering at full AMC power
 - 2x front-facing & 4x rear-facing Power Module (PM) slots
 - 12x full-height, double-width AMC slots
 - 2x redundant MCH slots
- **μTCA PMs (NAT-DC-840)**
 - 48 V DC input, 840 W per module
 - using 2 PMs per chassis
- **μTCA MCH (NAT-MCH)**
 - Basic version, no additional switch- or clocking modules
- **AC-DC converter (PowerOne Aspiro)**
 - 4x converter modules enabling 1 in 3 redundancy

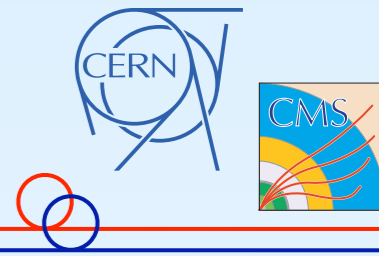
Installed system



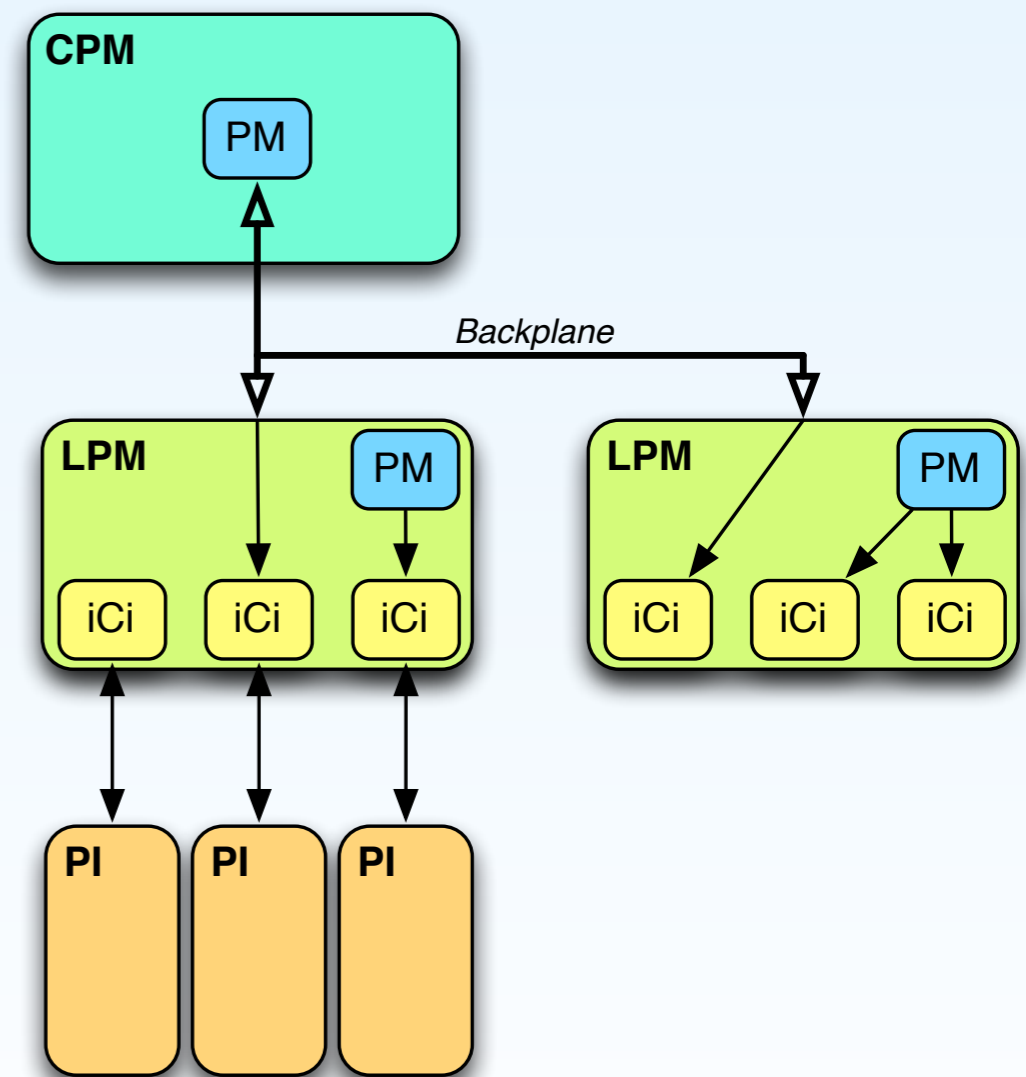
Installed system



Firmware overview

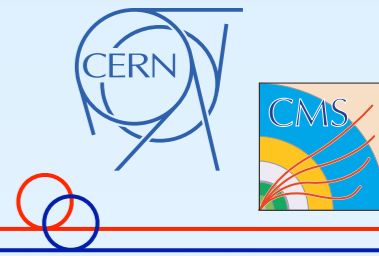


- Make use of common f/w modules across whole project
 - Partition Manager (PM)
 - CMS Interface (iCi) from Run 1 TTC
 - Core library containing generators, DAQ interface, etc.
- Board-specific f/w (CPM, LPM, PI) built on top of this
- Allows similar and thus simplified mapping to control software



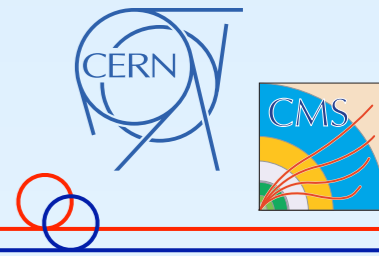
- TCDS control software
 - Based on the CMS XDAQ online software framework
 - TCDS 'sub-framework' developed
 - Provides uniform look and feel
 - Abstracts away hardware details from the application level
- Division of labour
 - Each TCDS component has a corresponding software component, implemented as a linux service
 - Service applications maintained centrally
 - CMS RunControl takes care of Partition Manager configuration
 - Subsystems maintain full control of the configuration of 'their' iCIs and PIs (via SOAP)

Overview

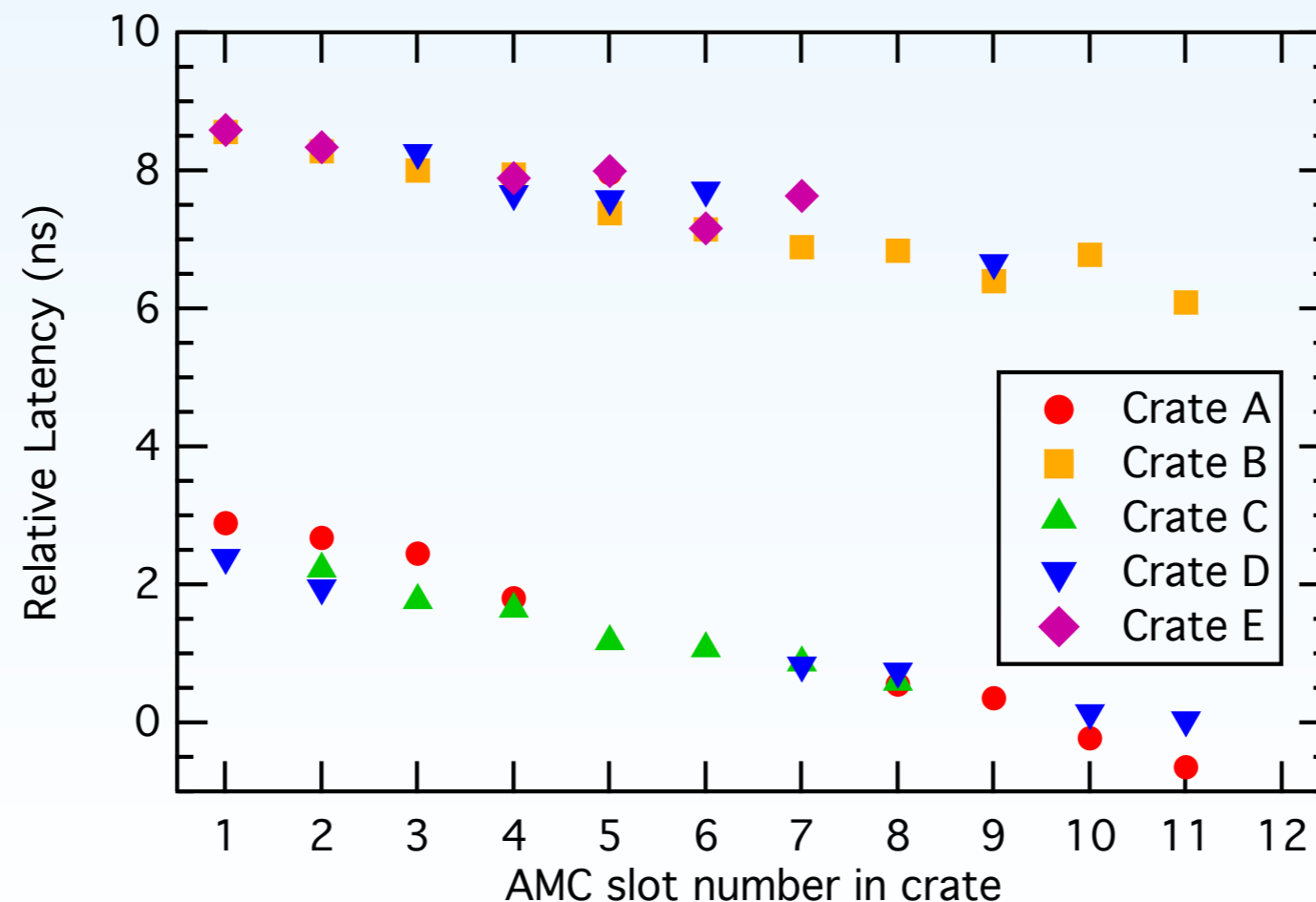


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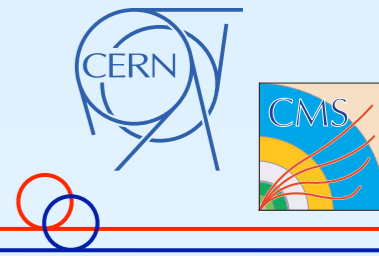
System performance: latency



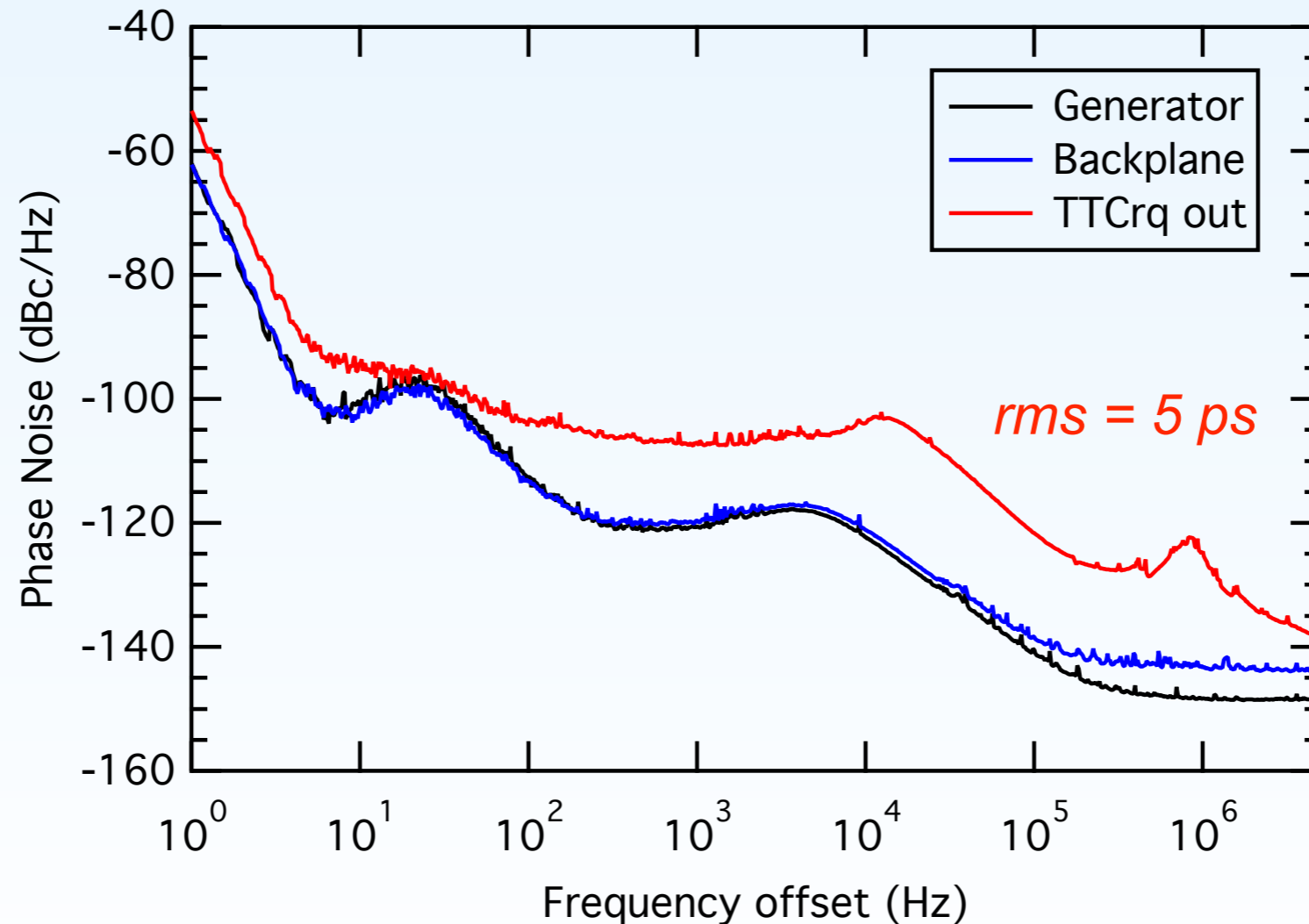
- Overall CMS trigger latency after TCDS system integration increased by 2 bx
 - Extra latency required to communicate signal between GT and TCDS
- Good uniformity across all partitions



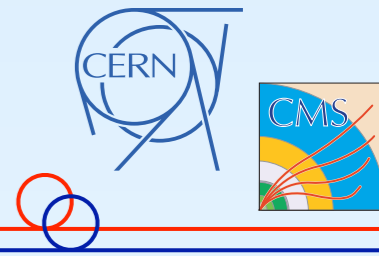
System performance: Jitter



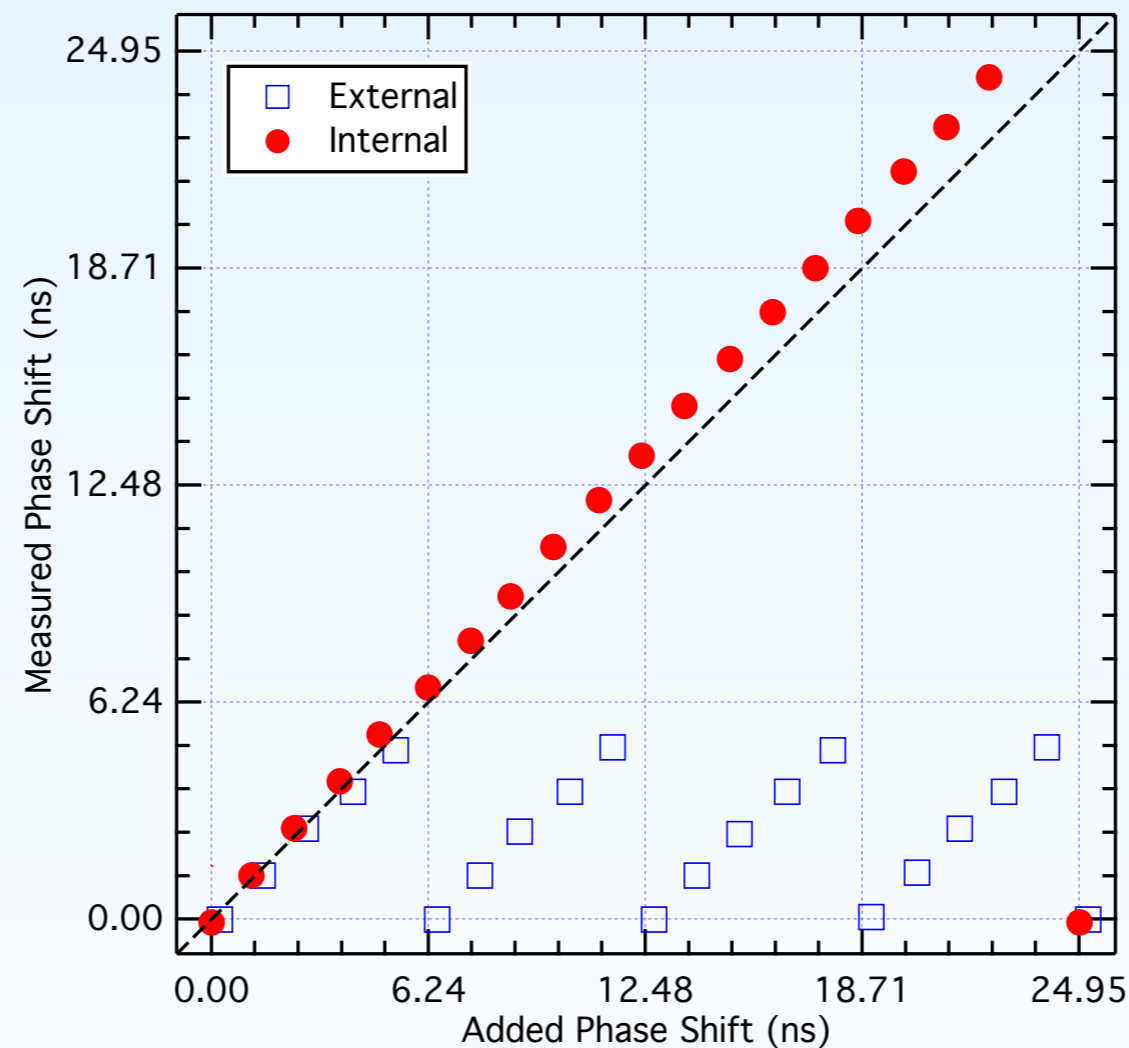
- System jitter performance not degraded by TCDS system
 - Dominated by TTCrx/QPLL



System monitoring: Phase

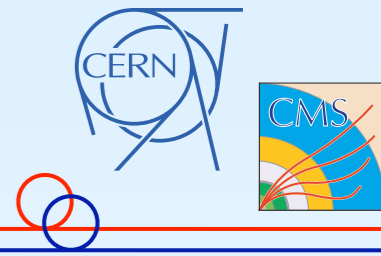


- Concern over FPGA internal PLL phase stability
 - Implemented internal phase measuring circuit

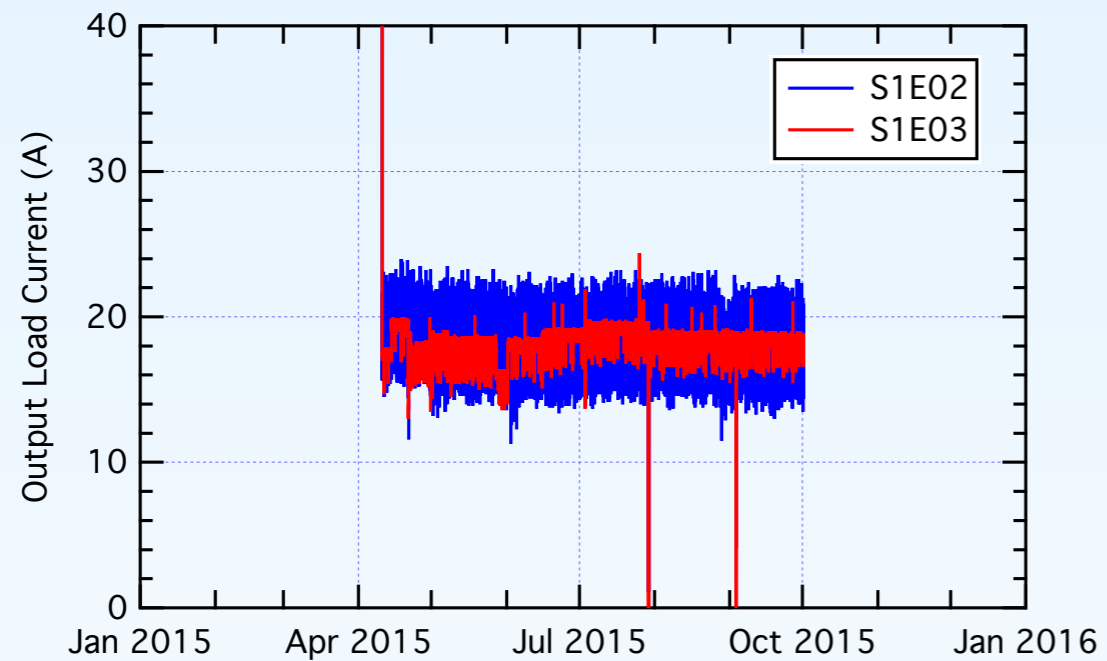


- Comparison to external measurement rather good
 - External measurement only sees up to 1/4 period (TTC stream at 160 Mb/s)

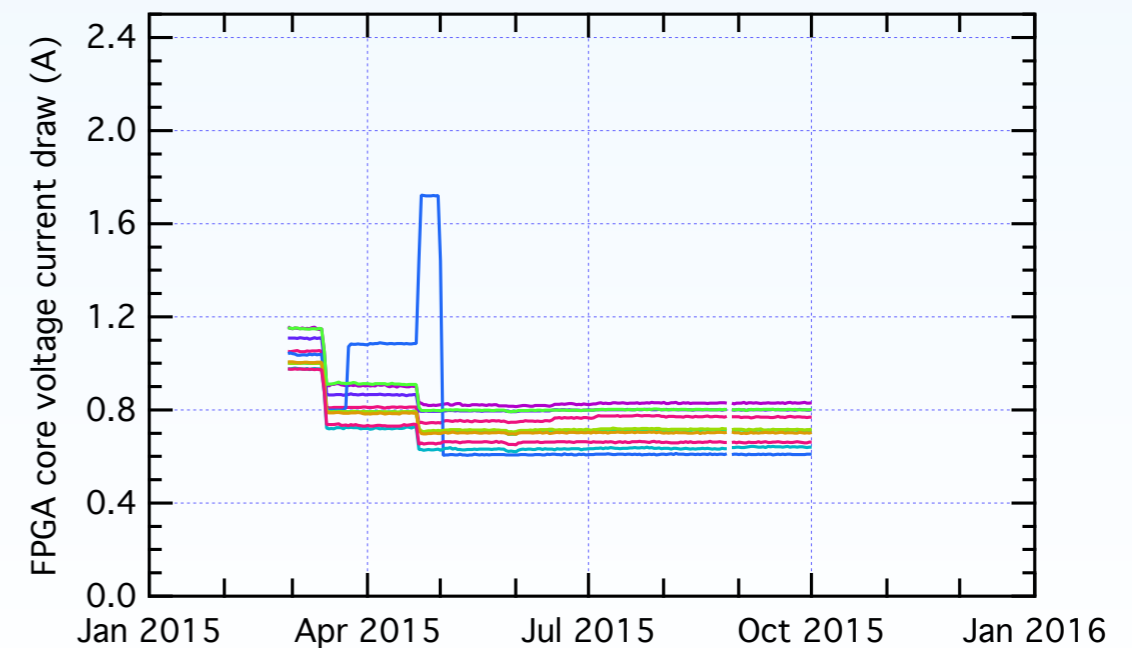
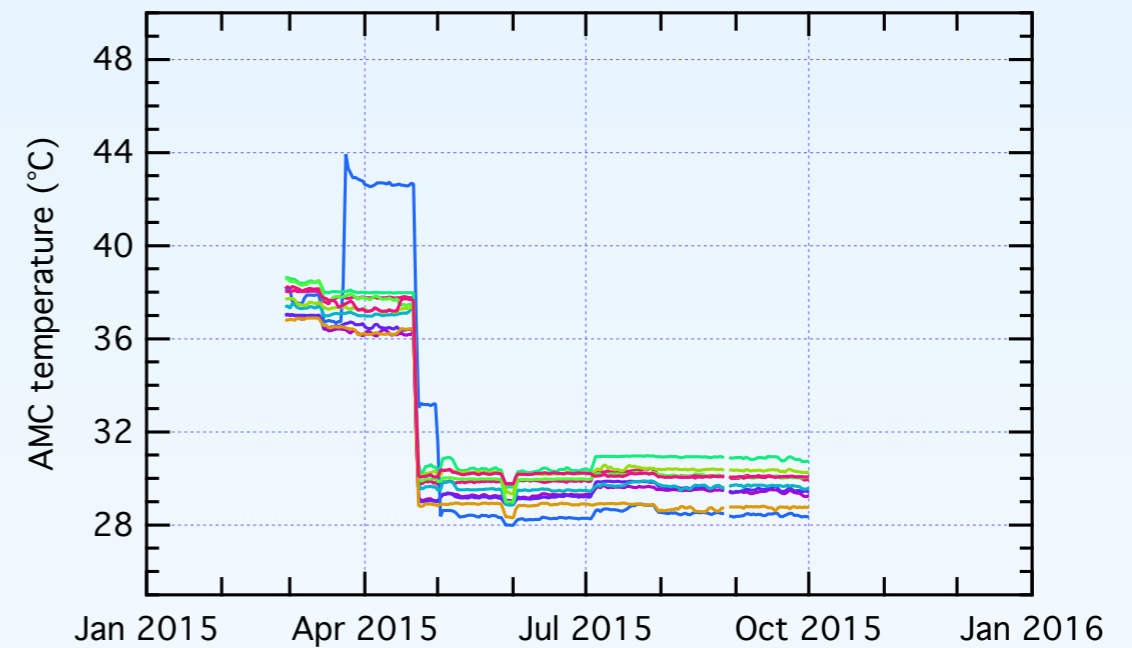
System health monitoring



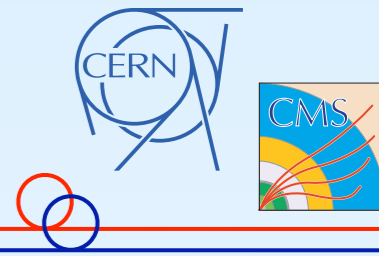
AC/DC Converters



AMC Sensors

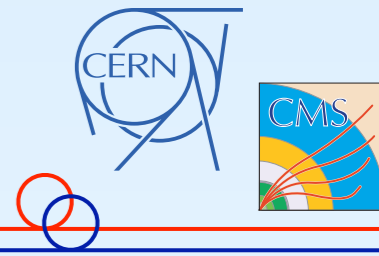


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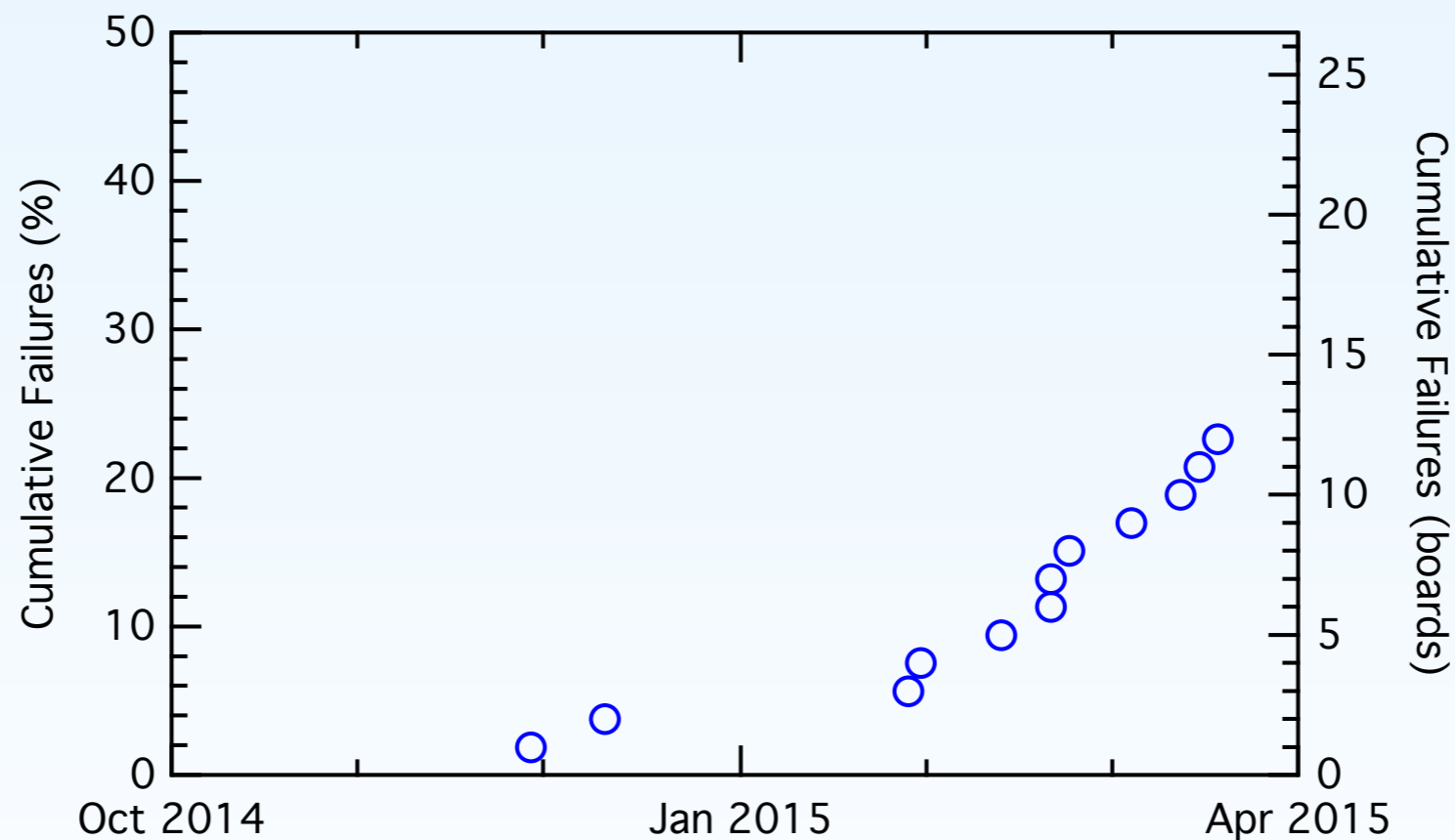


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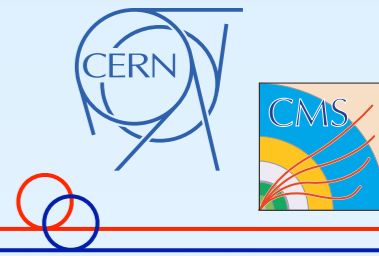
Operational experience



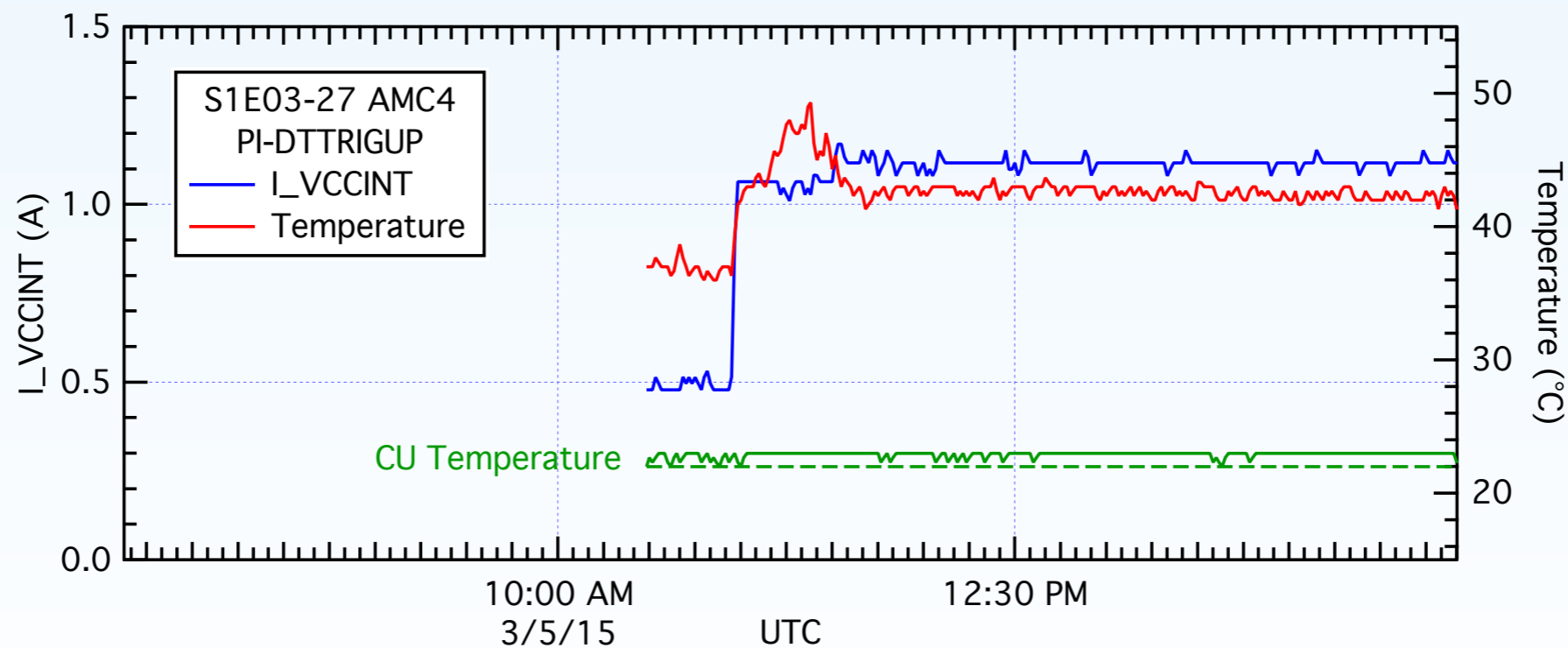
- The CMS TCDS system sustained a very high failure rate of AMCs after ~3 months of operation



FC7 failure monitoring

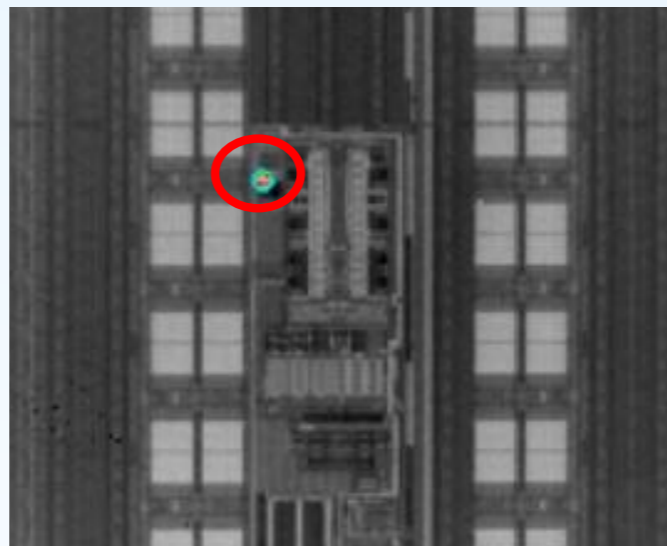


- AMC sensors provided diagnostics
 - Board failure accompanied with increased current drawn on FPGA core voltage
- Increased current an abrupt failure
 - within one monitoring interval (1 minute)

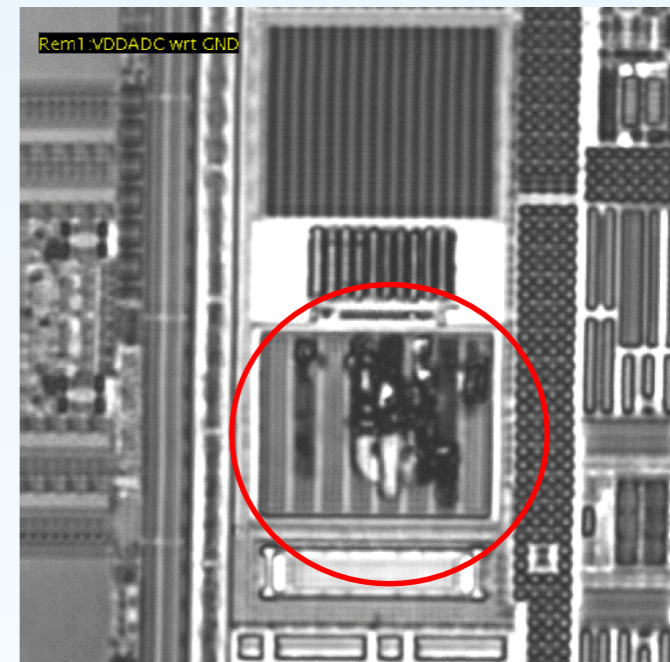


Failure analysis

- Lengthy investigations inc. Failure analysis by Xilinx on failed FPGAs
 - Schematic error identified - incorrect XADC supply voltage caused EOS failure of configuration memory



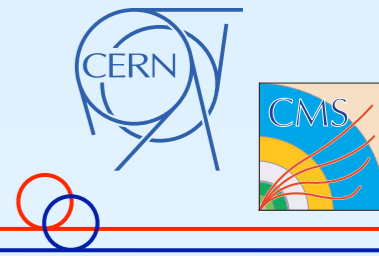
Thermal imaging - hotspot



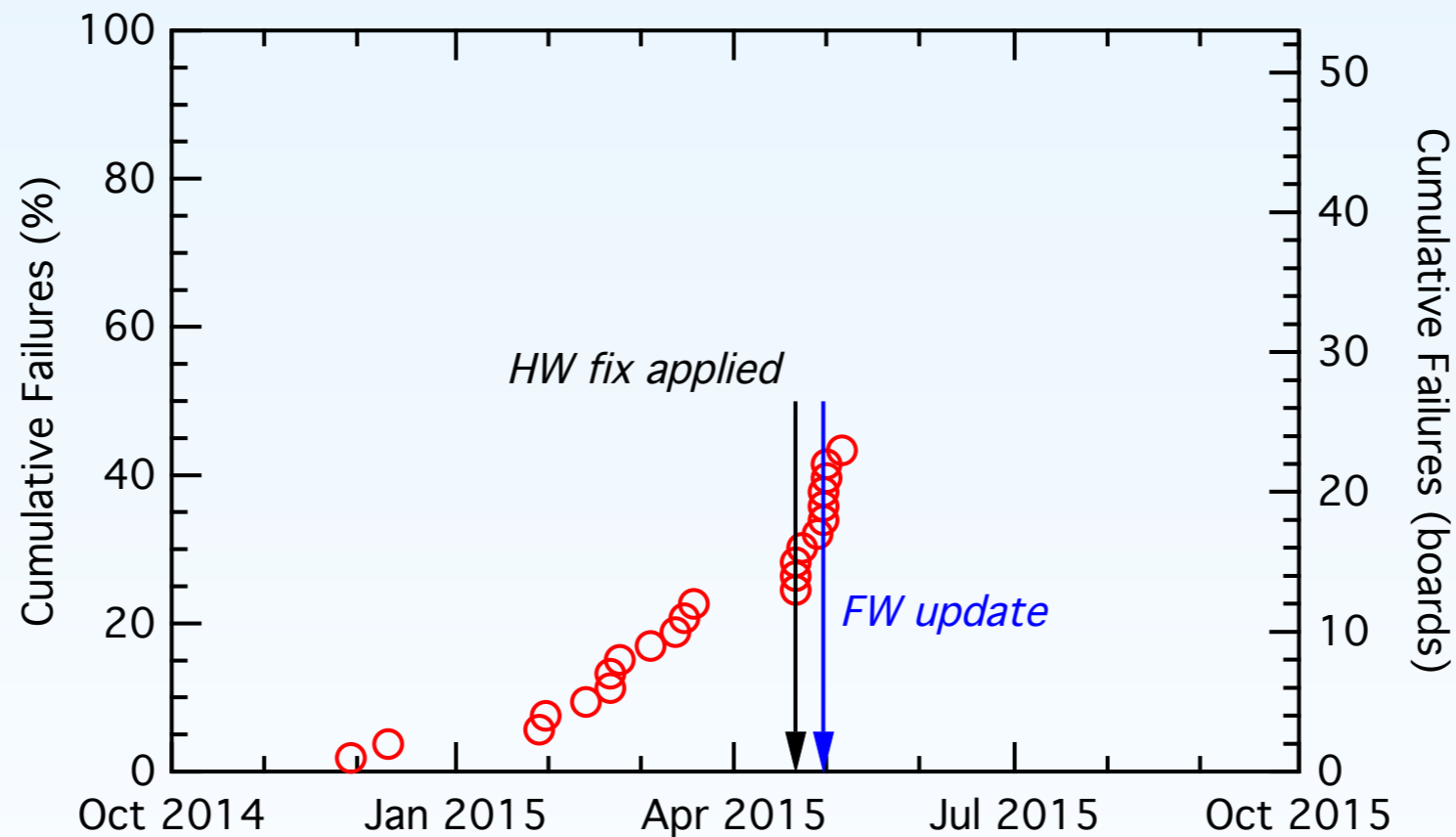
Catastrophic damage

- Simple fix possible with white wire
 - Applied to all boards in April 2015

Failure trend cont.



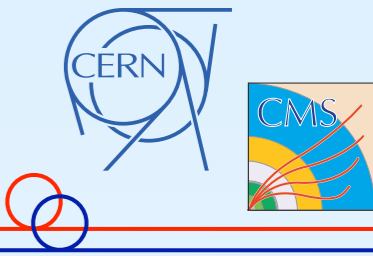
- Problem solved
 - As long as firmware not updated...



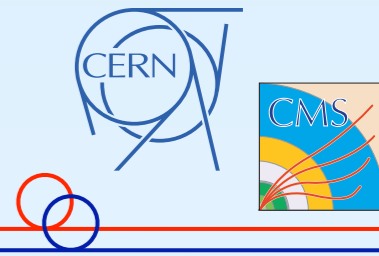
All AMCs will be replaced with new ones after end of this year's run

- CMS Timing system completely replaced during LS1
 - Project development -> deployment in 2 yrs
- Good performance achieved
 - Overall latency within limits
 - Timing jitter maintained at level of previous system
- Large effort for all CMS subsystems to integrate new system
 - Re-learned & re-visited many idiosyncrasies of the systems
- Operational difficulties due to board failures
 - Eventually solved by Xilinx failure analysis
- System now fully operational

Backup



Feature summary



| Feature | <i>CMS Note 2002/033</i> | <i>present TCS</i> | <i>present LTC</i> | <i>LPM</i> | <i>CPM</i> |
|---|--------------------------|--------------------|--------------------|------------|------------|
| Number of partitions | 32 | 32 | 6 | 8 | 96 |
| Number of partition groups | 8 | 8 | 1 | 1 | 2 |
| Number of DAQ EVM interfaces | 1 | 1 | 1 | 1 | 2 |
| LHC clock input | • | • | • | • | • |
| LHC orbit input | • | • | • | • | • |
| BST input | • | • | • | | • |
| Number of B-Gos | 10 | 16 | 16 | 32 | 32 |
| Number of TTS States | 7 | 7 | 7 | 16 | 16 |
| B-Go and TTS sequence definition | FW | FW | SW | SW | SW |
| Active BX mask | • | • | • | • | • |
| Resonant Trigger Cancellation | | | | • | • |
| External Front-end Emulator | • | • | • | | |
| Internal Front-end Emulator | | | | • | • |
| LumiDAQ sync signals | | | | • | • |
| <i>Counters active between Start & Stop</i> | | | | | |
| Orbits | • | • | • | • | • |
| BXs with L1A inhibited | • | • | | • | • |
| BXs with L1A inhibited L1A True | • | • | | • | • |
| BXs with L1A inhibited L1A False | • | • | | • | • |
| Active BXs with L1A inhibited | • | • | | • | • |
| Active BXs with L1A inhibited L1A True | • | • | | • | • |
| Active BXs with L1A inhibited L1A False | • | • | | • | • |
| Active BXs with L1A inhibited, per condition | • | • | | • | • |
| Physics Triggers | • | • | • | • | • |
| Physics Triggers distributed | • | • | • | • | • |
| Calibration or Test Triggers distributed | • | • | • | • | • |
| All Triggers distributed | • | • | • | • | • |