# BREPS solids construction by surfaces of extrusion \& revolution 

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## OUTLINE

$\checkmark$ Introduction
$\checkmark$ B-Rep solids in Geant4
$\checkmark$ Surface of revolution
$\checkmark$ Surface of linear extrusion
$\checkmark$ Example
$\checkmark$ Conclusions and extensions

## B-Rep solids



Constructive model (CSG)


## Boundary REPresentation

$\checkmark$ Geometric entities: point, curve, surface
$\checkmark$ Topological entities: vertex, edge, face (boundaried surface), edge_loop
$\checkmark$ Elementary surfaces (plane, cylindrical s., ...) Advanced surfaces (swept s., ...)

## SMESt Surfaces

## (Generalized Cylinder)

$\checkmark$ Swept surfaces are generated by moving a 2D curve along a trajectory in 3D space.
$\checkmark$ Curve can also change its shape and orentation during sweeping.
$\checkmark$ Generalized cylinder is the shape generated when a 2D contour is swept along a 3D trajectory.
$\checkmark$ Contour define the cross-section of the object.
$\checkmark$ Trajectory is the axis of the object.


## Surfaces of revolution \& linear extrusion

$\checkmark$ In the geometrical modelling, like Computer-Aided Desing, are commonly used only two kinds of generalised cylinders.
$\checkmark$ These solids are obtained by extrusion or revolution of 2D contour.
$\checkmark$ For define these solids it's necessary use the corresponding surfaces.

$\checkmark$ Definition of swpet surface by generic curves can generate a surfaces with inifinite extension.
$\checkmark$ In this case, for generate a solids, is necessary trimming the surface along the swept direction and also should be limited the 2D curve by definition of the bounds.

## BREP in Geant4

$\checkmark$ G4BREPSolid is defined by a collections of boundaried surfaces

## G4Surface

$\checkmark$ Boundaries
$\checkmark$ Bounding box
$\checkmark$ Intersection with a ray
$\checkmark$ Point to surface distance
$\checkmark$ Normal vector to surface

Plane , cylindrical, conical, toroidal, bspline, bezier

## G4Curve

$\checkmark$ 3D point \& parameter value
$\checkmark$ Bounds
$\checkmark$ Bounding box
$\checkmark$ Intersection 2D curve with a ray
$\checkmark$ Tangent
$\checkmark$ (curve-curve intersection)

Conics, line, Bspline, composite

## Surface of linear extrusion

It's generated by a 2D contour swept along a segment of line.

$$
\sigma(u, v)=\lambda(u)+v V
$$

$\checkmark \lambda(u)$ parametrization of the swept curve
$\checkmark V \quad$ extrusion direction
$\checkmark-\infty<v<+\infty \quad$ parametrization range
In current implementation
$\checkmark$ 2D swept curve is defined on a ortogonal plane to extrusion axis and need be closed
$\checkmark$ z axis rapresents extrusion direction


G4SurfaceOfLinearExtrusion (const \&G4Curve curve, G4double length)

## Surface of linear extrusion

## Bounding box

- the BB of the boundaried swept curve must be included
- the bounding box of the surface is extendend by including also the BB translated along the extrusion axis



## Surface of linear extrusion

## Ray intersection

- 3D ray in local coordinate
- $r(t)=S+t \cdot D \quad t>0,|d|=1$
- the ray is projected on the plane where is definend the base curve
- 2D ray - curve intersection is determined
- the 2D intersection distance is mapped easly to a 3D intersection distance, given the direction and the source point of the ray



## Surface of revolution

$\checkmark$ It's generated by a 2D contour swept along a circular trajectory
$\checkmark$ Equivalently the solid can be generated by rotation of the 2D contour around an axis.
$\checkmark$ If the base curve isn't closed (usual case), it's alway possibile generate a solid by adding two circular planar surface for the bottom and the top of the solid.


## Solid of revolution

## Bounding box

- is computed by extend the bounding box of the base curve with its replications on each semi-axis (x pos/neg, y pos/neg)



## Surface of revolution

## Ray intersection

## $\checkmark$ Boundary Cylindrical Shell

$\checkmark$ This allow to limit z interval
$\checkmark$ The ray is "cylindrical proiected" on the plane that is swepted (cylindrical coordinate system $\left.x^{2}+y^{2}=r^{2}\right)$

$\checkmark$ The image of the ray is not a ray but is a hyperbola
$\checkmark$ The first intersection of the two curves is computed: $\left(r_{0}, z_{0}\right)$
$\checkmark$ With $z_{0}$ and ray equation we can obtain the 3D intersection point and the distance

## G4BREP solids

$\checkmark$ G4BREPSolidOfLinearExtrusion
$\checkmark$ G4BREPSolidOfRevolution
$\checkmark$ Inside operation
generates a ray from the point and check if it intersects one of the surfaces

## Example

## Conciusions

Actual implementation
$\checkmark$ Linear extrusion for base curves
$\checkmark$ Surfaces of revolution (not complete for bspline curves)

Incoming
$\checkmark$ Tangent computation for BSpline
$\checkmark$ Alternative technique for compute ray -
revolution surfaces intersection by binary subdivision of bo

Future work
$\checkmark$ Diagonal extrusion
$\checkmark$ Conical extrusion
$\checkmark$ Extrusion along an arbitrary curve
$\checkmark$ Revolution suface limitated by phy section


# BREPS solids construction by surfaces of extrusion \& revolution 

## END

Thanks

