

Design Study on High Frequency Magnets for Magnetic Hyperthermia Applications

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Introduction

Research objective

Discussion of the engineering feasibility of **high frequency magnet systems** for the magnetic hyperthermia cancer therapy.

Target specifications for a short time cancer therapy

- **0.06 T** and **200 kHz** of the AC peak magnetic field
- **300 s (5 minutes)** of the continuous or intermittent operation time
- Current status: **0.02 T (18 kA/m)** and **100 kHz**
MFH 300 F (MagForce Nanotechnologies AG, Berlin, Germany)

Technical challenges and Feasible solutions

- **Dielectric breakdown** in magnet windings (should be less than 10 kV)
➔ Reduction of the ampere-turns based on a **iron core coil design**
- **Skin effects** and **magnet losses** due to the high frequency operation
➔ Use of **Litz wires** and the feasibility of **water cooling magnets**
- Required capacity of **high frequency power converter** system
➔ Compensation of the magnet reactance using **series capacitors**

Thermal Design Analysis

Joule heat loss distribution of high frequency magnets

$$U_{\text{Joule}} = (1 - \eta)U_{\text{Cu}} + \eta U_{\text{water}}$$

Heat capacity Water cooling

η : Water cooling ratio

$$U_{\text{Joule}} = \int_0^{t_{\text{op}}} R I_{\text{rms}}^2 dt$$

$$U_{\text{Cu}} = \int_0^{T_{\text{max}}} M C_{\text{pCu}} dT$$

$$U_{\text{water}} = \int_0^{t_{\text{op}}} \dot{m} C_{\text{pH}_2\text{O}} \Delta T dt$$

Function of a current density J_{op}

Max. magnet temperature

$$T_{\text{max}} = \frac{(1 - \eta) \rho_e t_{\text{op}} J_{\text{op}}^2}{2 \rho_m C_{\text{pCu}}} + T_0$$

Water flow rate

$$\dot{m} = \frac{\eta \pi \rho_e a N t_{\text{op}} I_{\text{peak}}}{C_{\text{pH}_2\text{O}} \Delta T} J_{\text{op}}$$

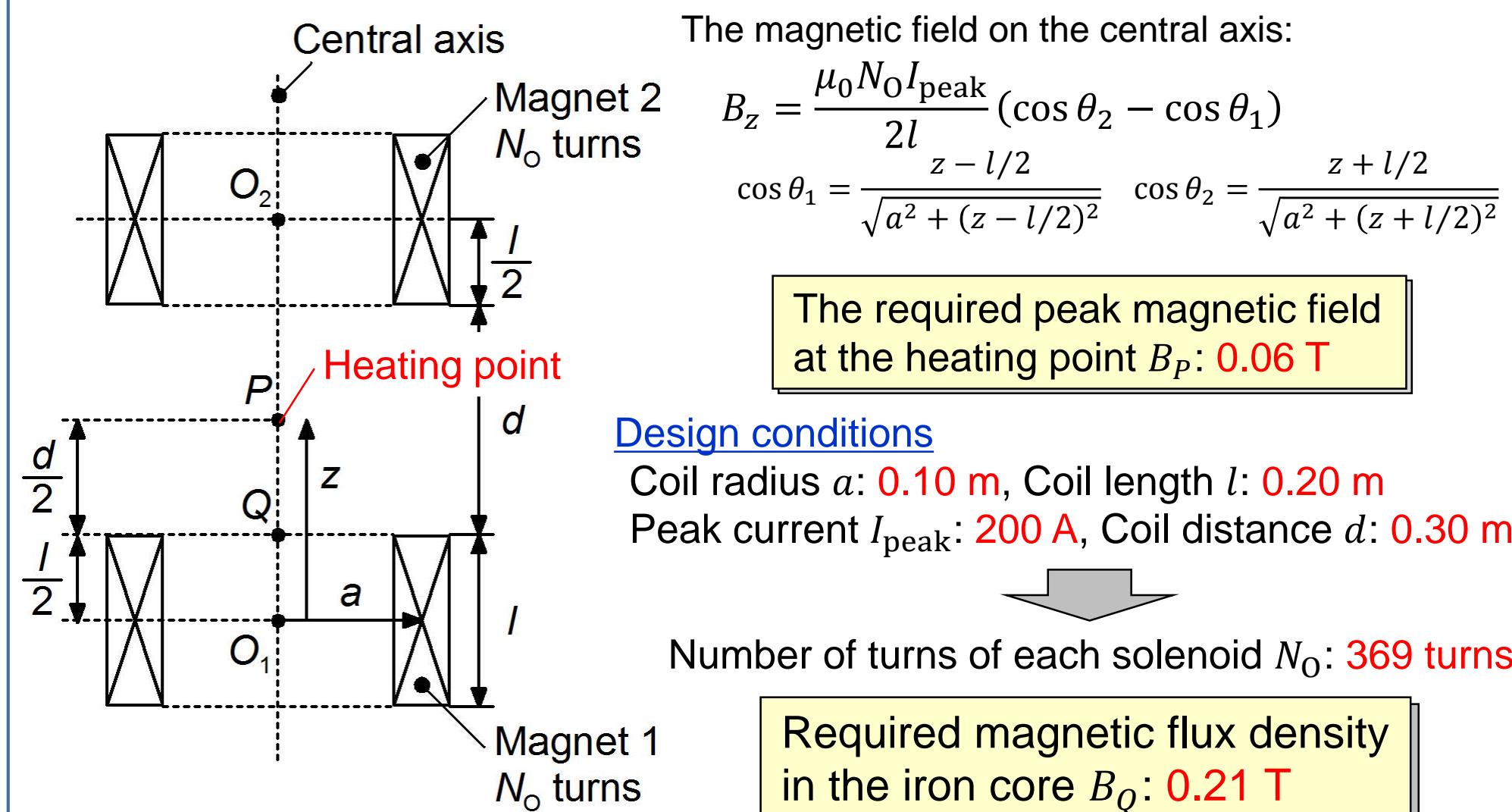
Design conditions

Operating time t_{op} : **300 s**
Coil radius a : **0.10 m**
Peak current I_{peak} : **200 A**
($I_{\text{rms}} = I_{\text{peak}}/\sqrt{2} = 141 \text{ A}$)
Number of turns N : **260 turns**

Initial temperature T_0 : **293.15 K (20 °C)**
Resistivity of conductors ρ_e : **$2.06 \times 10^{-8} \Omega\text{m}$**
Mass density of conductors ρ_m : **$8.96 \times 10^3 \text{ kg/m}^3$**
Heat capacity of copper C_{pCu} : **$3.86 \times 10^2 \text{ J/kg}\cdot\text{K}$**
Heat capacity of water $C_{\text{pH}_2\text{O}}$: **$4.18 \times 10^3 \text{ J/kg}\cdot\text{K}$**

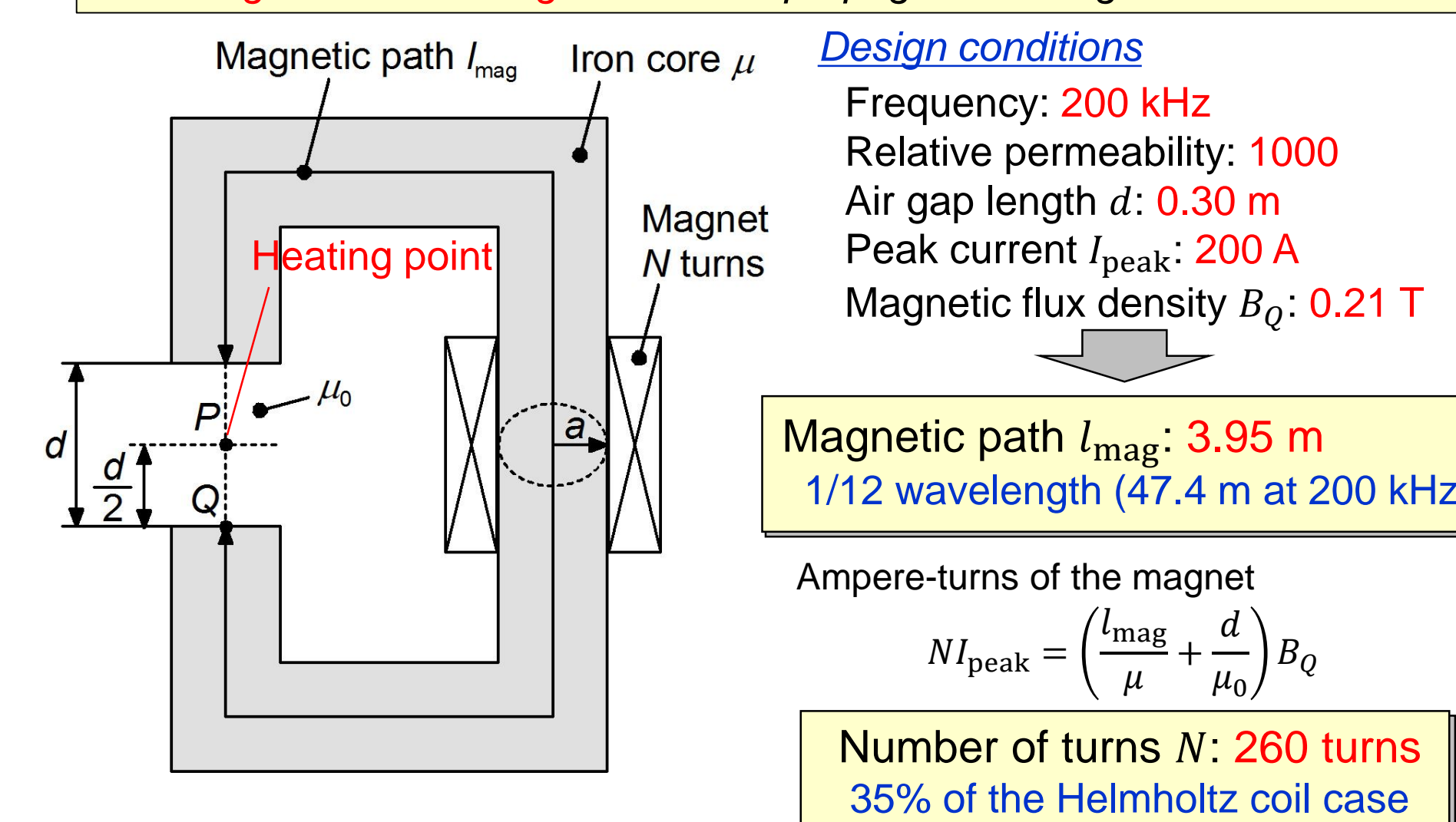
Estimation of the Required Magnetic Flux Density

The required magnetic flux density in the iron core is estimated from a Helmholtz coil arrangement.

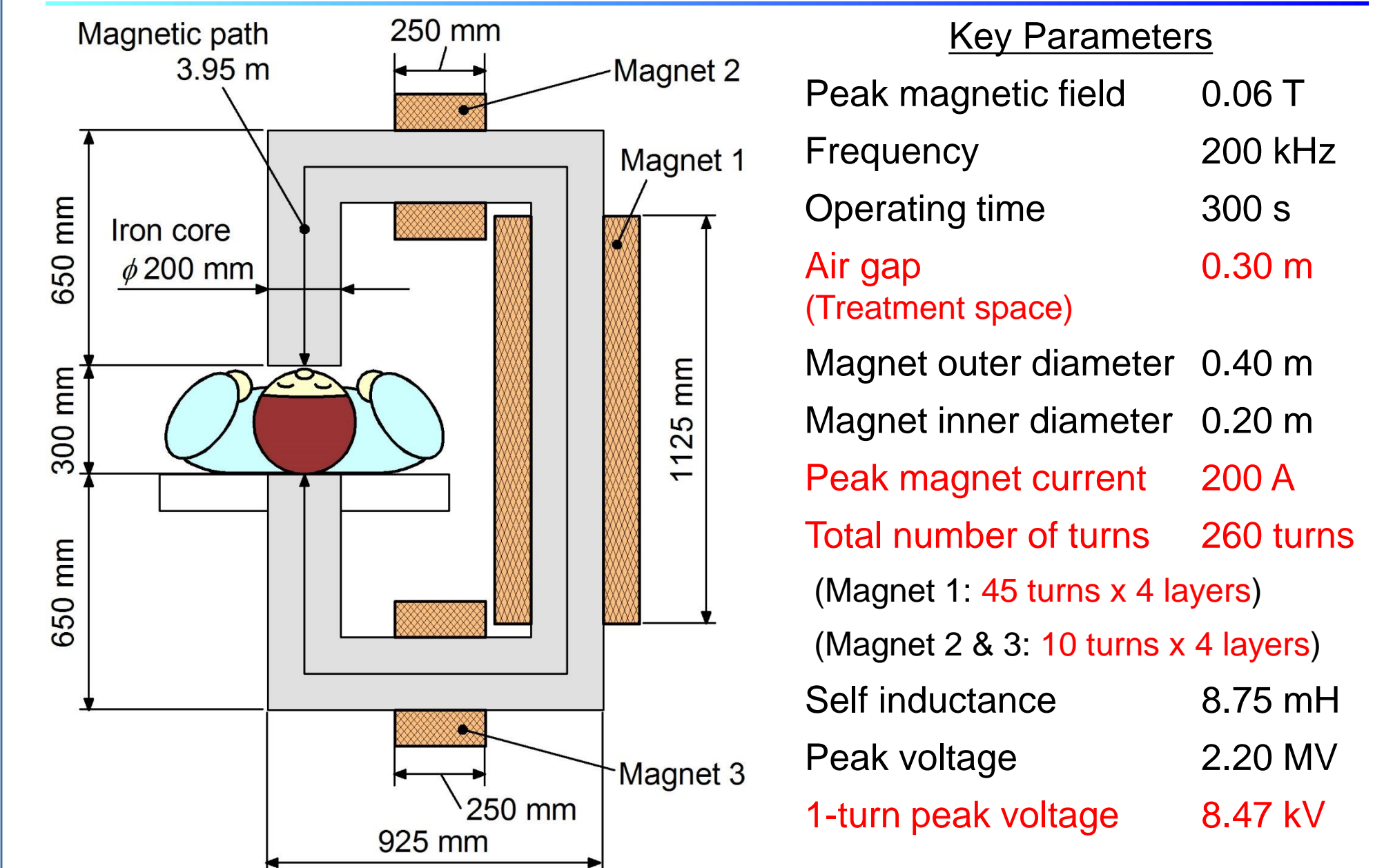


Iron Core Magnet Design

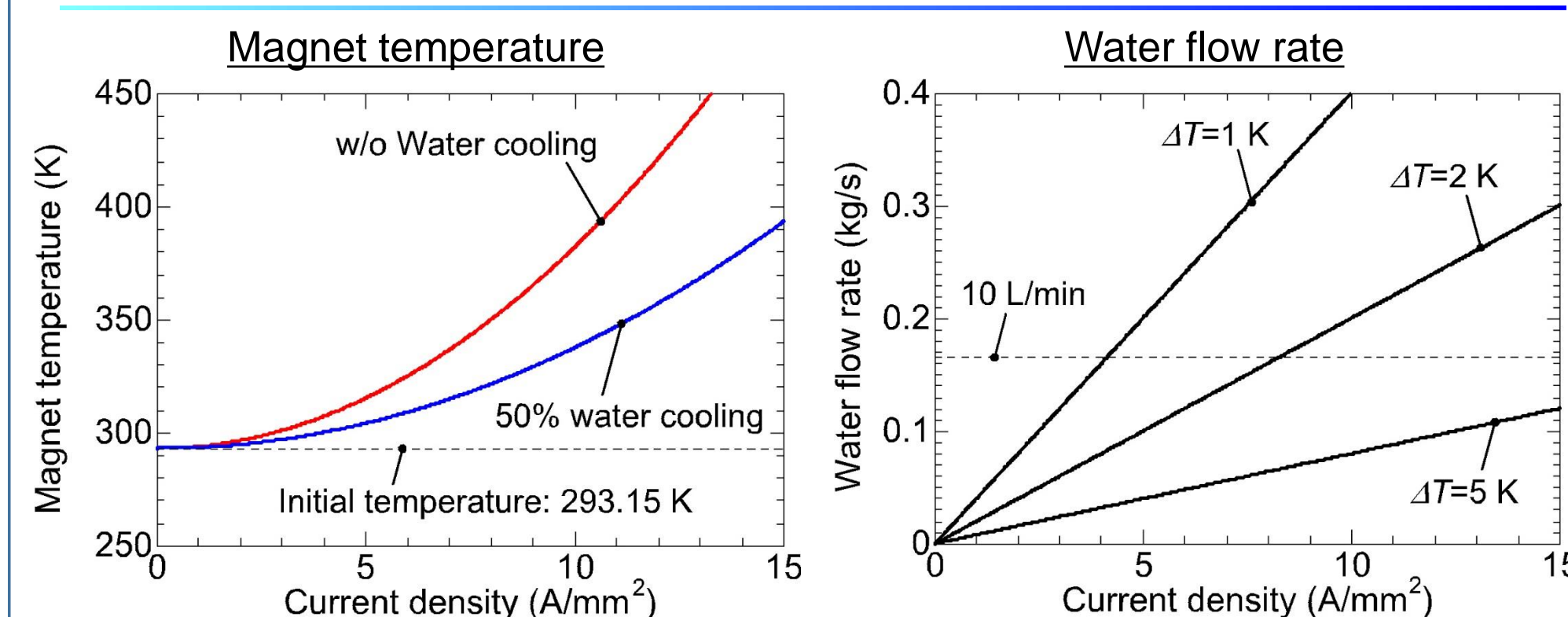
The magnetic path length should be designed while taking into account the wavelength of electromagnetic waves propagated through the iron core.



Overview of the Hyperthermia Magnet System



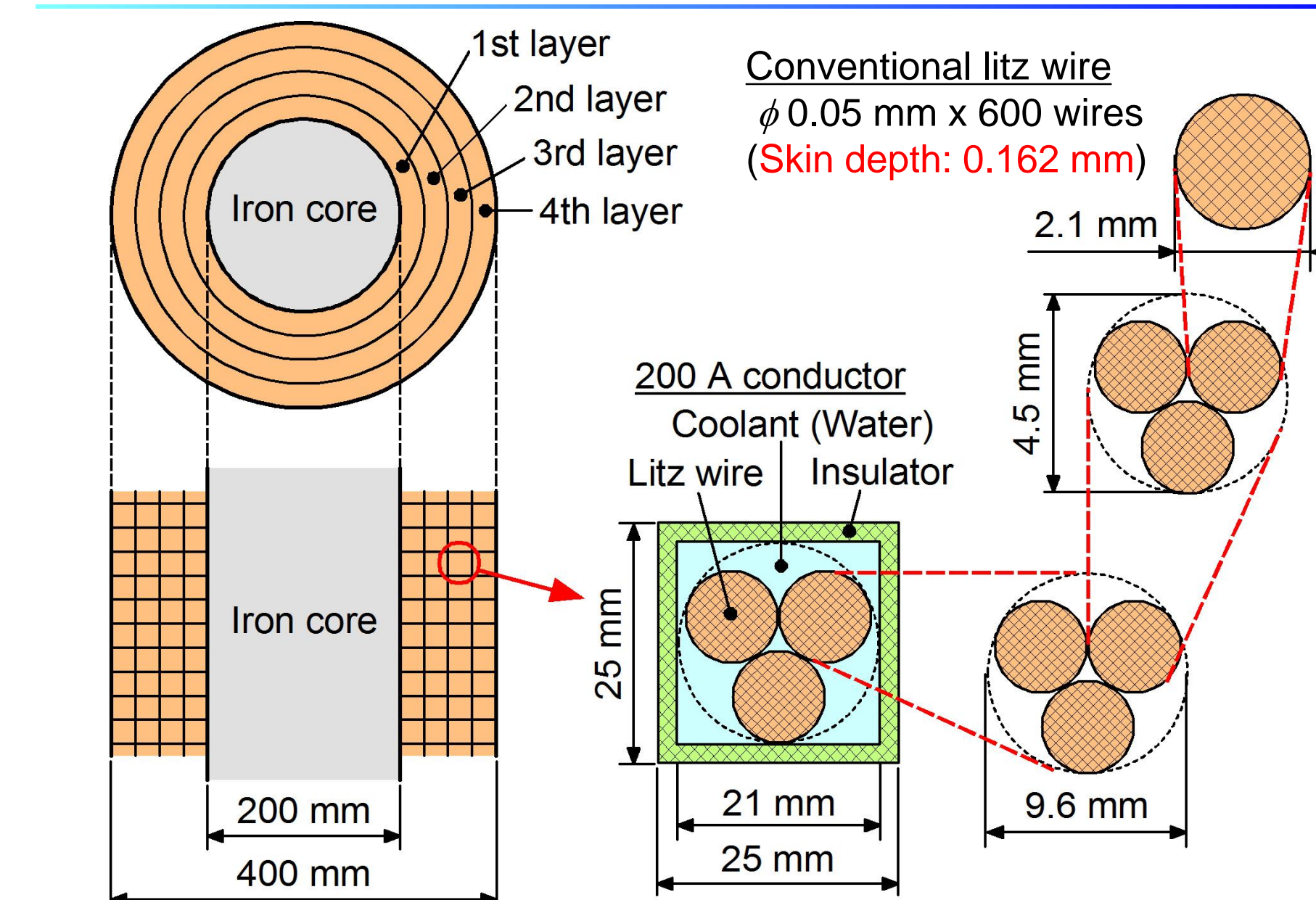
Thermal Properties vs. Current Density



Magnet design parameters

Operating current density: **6.3 A/mm^2** , Joule loss: **2.1 kW**
Magnet temperature
w/o Water cooling: **329 K (55 °C)**, 50% water cooling: **311 K (38 °C)**
Water flow rate: **15 L/min.** ($\Delta T = 1 \text{ K}$), **7.6 L/min.** ($\Delta T = 2 \text{ K}$)
Conventional chillers are available for the water cooling magnet.

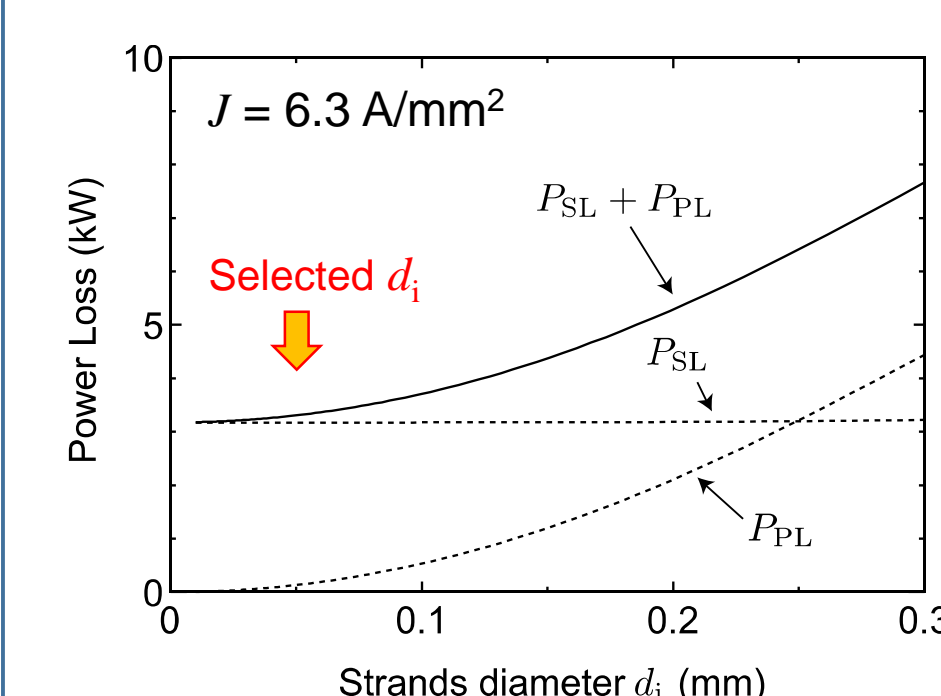
High Frequency Magnet Windings



Loss Calculation

Winding Loss

P_{SL} : Loss by dc resistance + skin effect
 P_{PL} : Loss by proximity effect



Winding Loss $P_{\text{loss,w}}$: **3.31 kW**

Core Loss

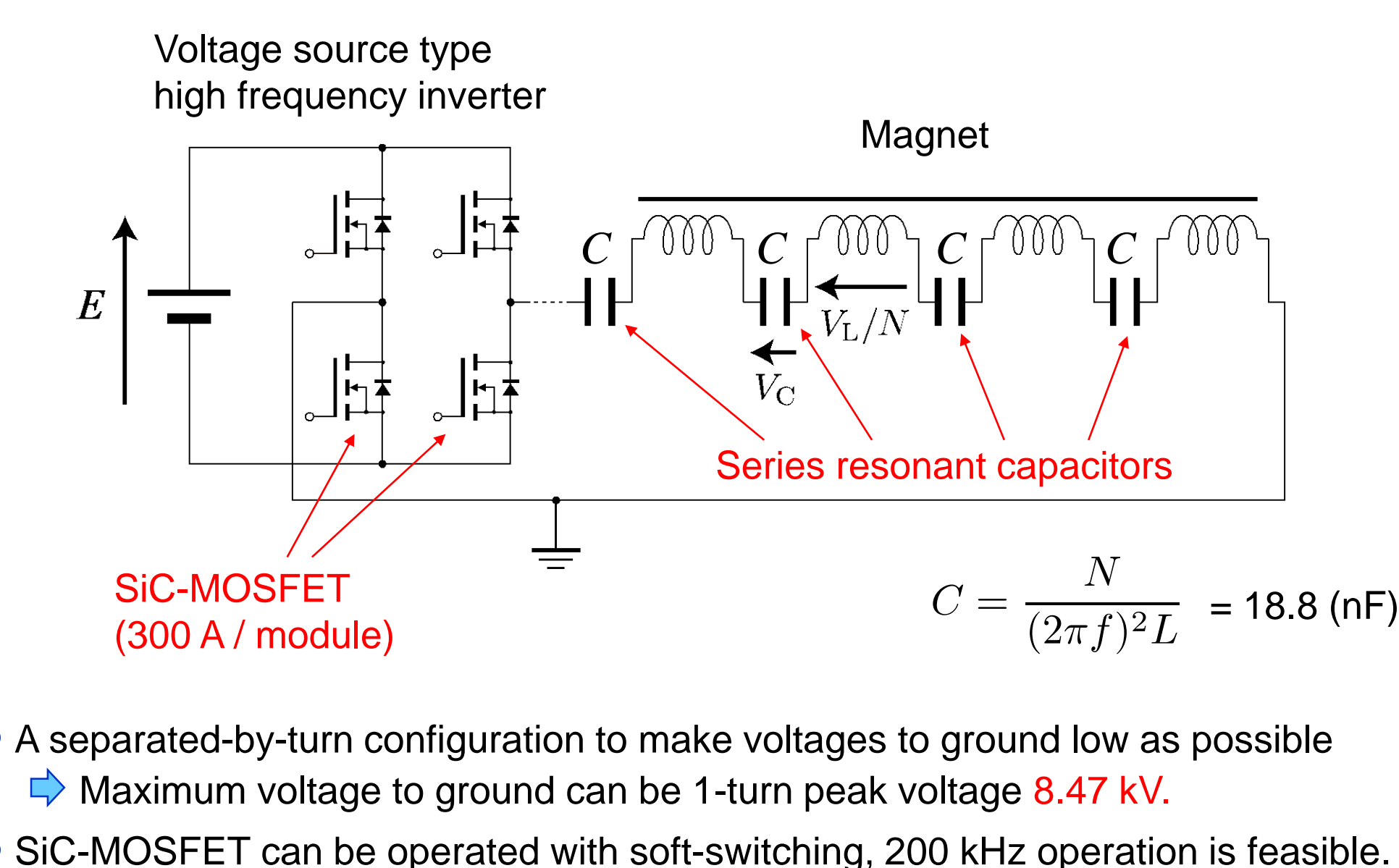
Empirical Steinmetz equation
 $P_{\text{core}} = k_C \cdot f^\alpha \cdot B_{\text{peak}}^\beta \cdot A_C \cdot l_C$
 A_C : Effective core cross-sectional area
 l_C : Effective core length

Selected Core

Core material: **TPW33 (Soft Ferrite)**
Saturation flux density: **0.52 T**
Parameter k_C : **0.0682 W/m^3**
Parameter α : **1.74**
Parameter β : **2.81**

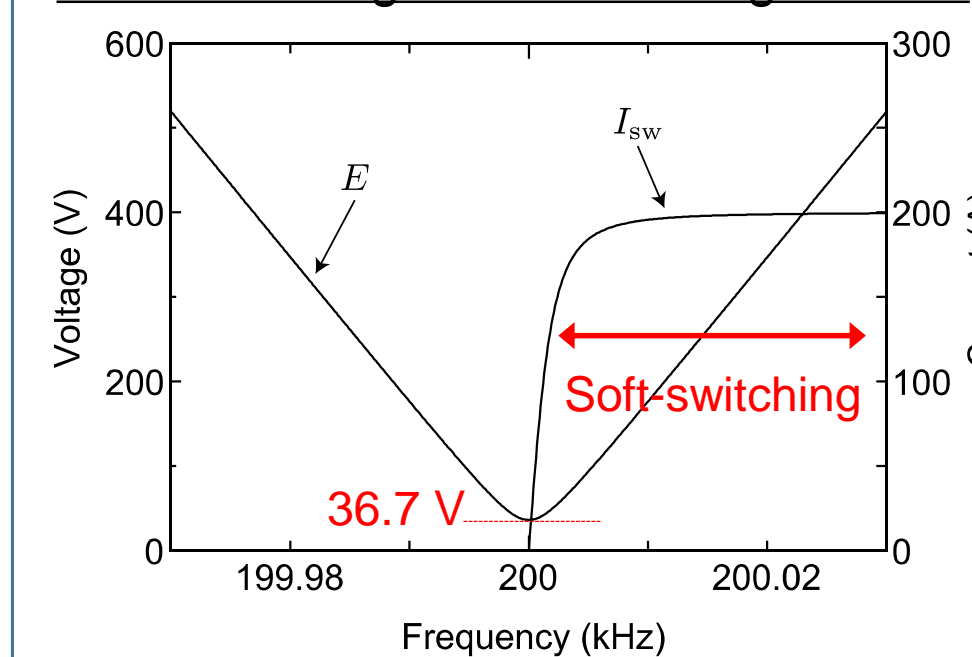
Core Loss P_{core} : **1.33 kW**

Power Supply System



Design and Control

Inverter Voltage and Switching Current

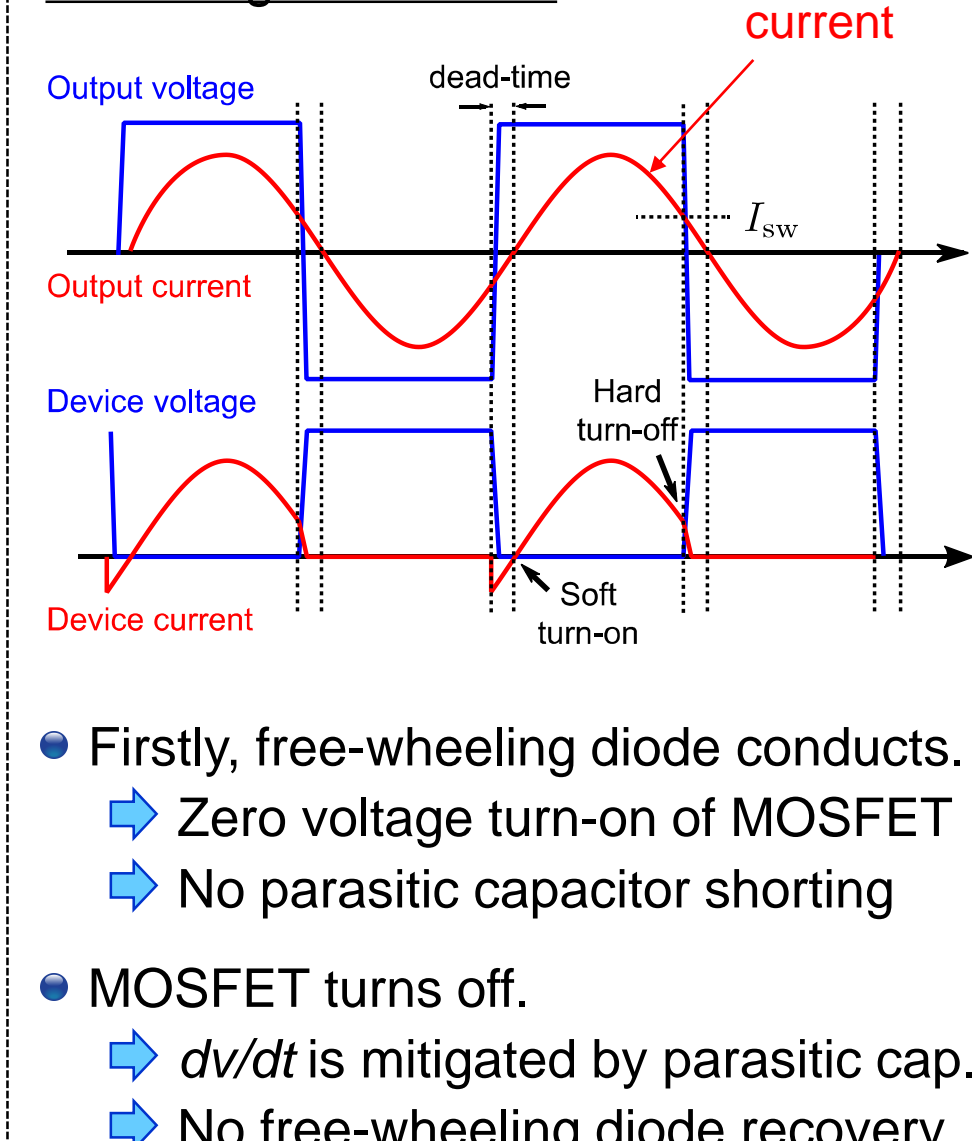


Inductance L : **8.75 mH**
Equivalent resistance $R_{\text{loss,all}}$: **0.232 Ω**

$Z = \sqrt{\left(\omega' L - \frac{1}{\omega' C_{\text{total}}} \right)^2 + R_{\text{loss,all}}^2}$, $I = \frac{V_{\text{inv}}}{Z}$

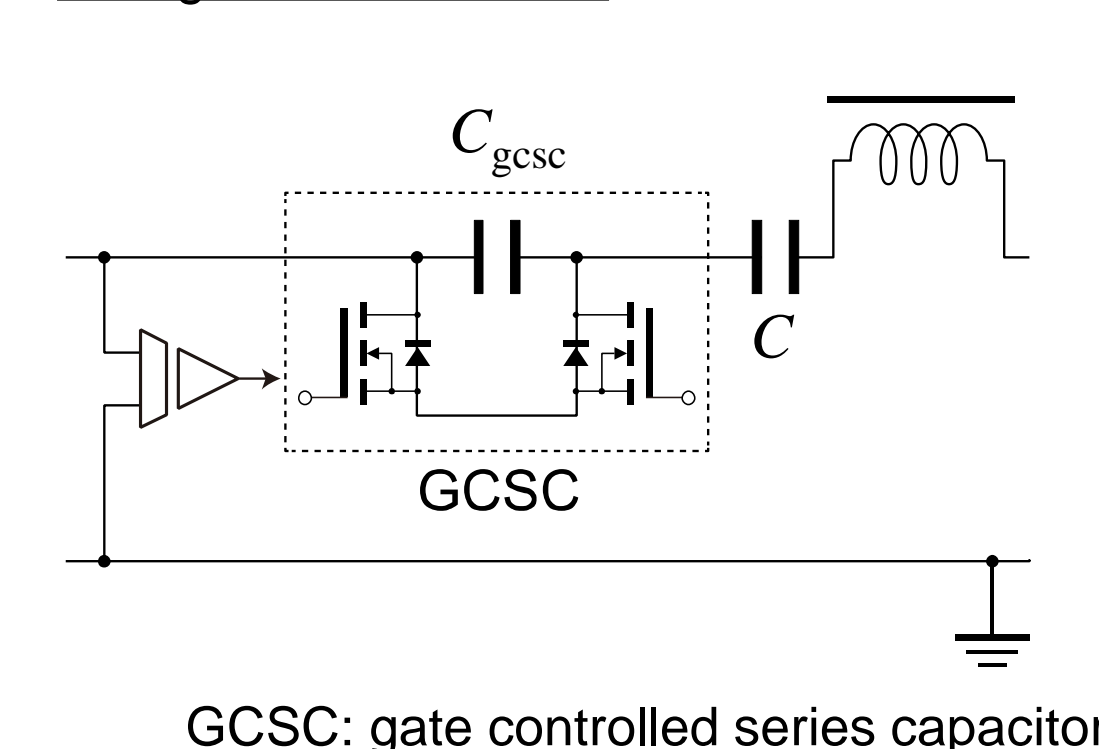
- Highly frequency sensitive system
➔ Inverter voltage control is applied.

Switching Waveforms

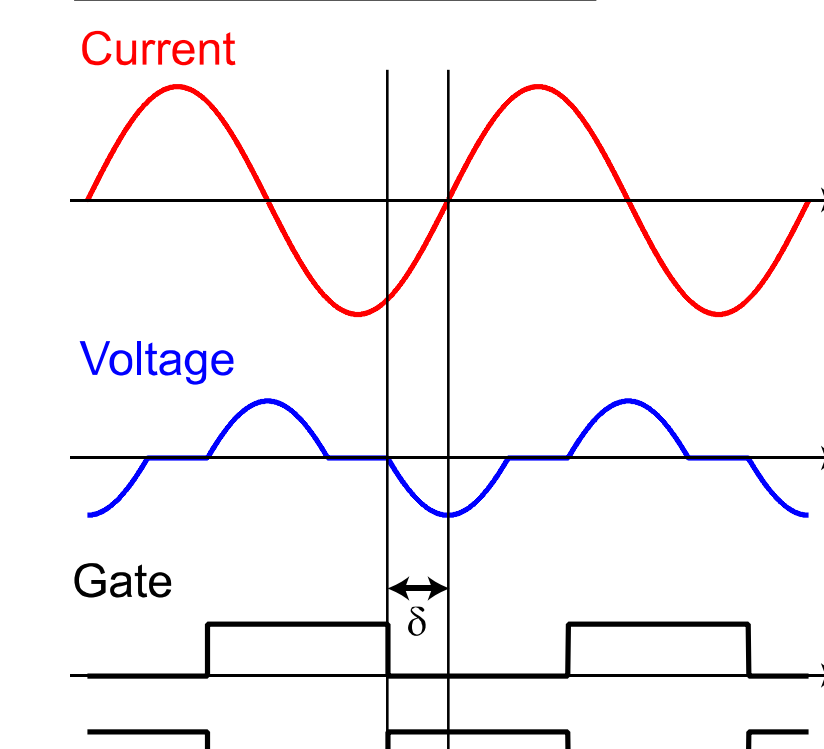


Voltage Balancer

Voltage balancer circuit



Schematic waveforms



Equivalent reactance

$X_{\text{GCSC}} = X_C \left(\frac{2\delta}{\pi} - \frac{\sin 2\delta}{\pi} \right)$
 X_C : Reactance of equipped capacitor

- GCSC works as variable capacitor.
- Total compensation voltage for 1-turn coil can be partially controlled.
- Controlling voltage to ground not to be high

Conclusions

Results of the Design Study

- One turn voltage of the winding can be reduced to **8.47 kV** even when the magnet is excited up to **0.06 T** of the peak magnetic field with **200 kHz** of the operating frequency.
- The winding loss is **3.3 kW**, which result suggests that the magnet can be operated without a water cooling system. Even if the magnet cooled by water, conventional chillers are available.
- Single voltage source high frequency inverter using commercially available **SiC-MOSFET (< 1.2 kV)** can drive the magnet with balancer circuits.

Engineering feasibility of a **0.06-T, 200-kHz** Hyperthermia magnet

Future works

- Developing laboratory proto-type for particles and medical investigations
➔ Experimental verifications of the proposed design principles of the system