

Timing, Synchronization & Longitudinal Aspects

I



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**CAS Course on
Beam Injection, Extraction and Transfer**

13 March 2017

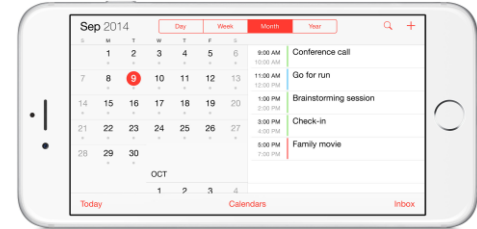
Outline

- **Introduction**
- **General concepts**
 - **Signals with noise, transmission of RF signals**
 - **Phase detectors and dividers**
- **Beam transfer**
 - **Fundamental periodicity**
 - **Transfer between circular lepton accelerators**
- **Transfer between hadron accelerators**
 - **Beam phase loop, bucket numbering**
 - **Transfer process: Synchronization, transfer triggers**
 - **Longitudinal matching**
- **Summary**

Introduction

Introduction

- **Two or more people must be synchronized to meet**
 - **Calendar item: date, time and location**



- **Typical uncertainty: some minutes**

- **Slightly more precision required to have a meeting with a particle beam**

- **Typical uncertainty: some nanoseconds down to femtoseconds**

→ **To be at the right time in the right place**

→ **Set conditions and generate timings and RF signals with a given time relation with respect to the beam**

→ **Make beam feel comfortable in its new accelerator**

Timescales



**Proton synchrotrons
at medium energy**

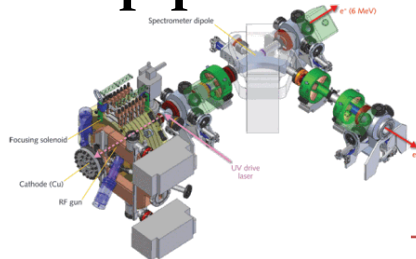


**Electronics
Low-level RF systems**

SASE FELs



Pump-probe FELs



10 ns

1 ns

100 ps

10 ps

1 ps

100 fs

10 fs

**Proton bunches in low
energy synchrotrons**



Hadron colliders

Electron storage rings



**Plasma wakefield
experiments**



→ Geometrical size: few meters to some km

Synchronization for beam transfer

- How to get the beam through the accelerator?



- How to transfer beam from accelerator A to B?



- Beam passes many elements on its way:

→ RF structures → **Must be in phase**

→ Septa, bumper and kicker magnet → **Trigger**

→ Fast beam instrumentation → **Trigger**

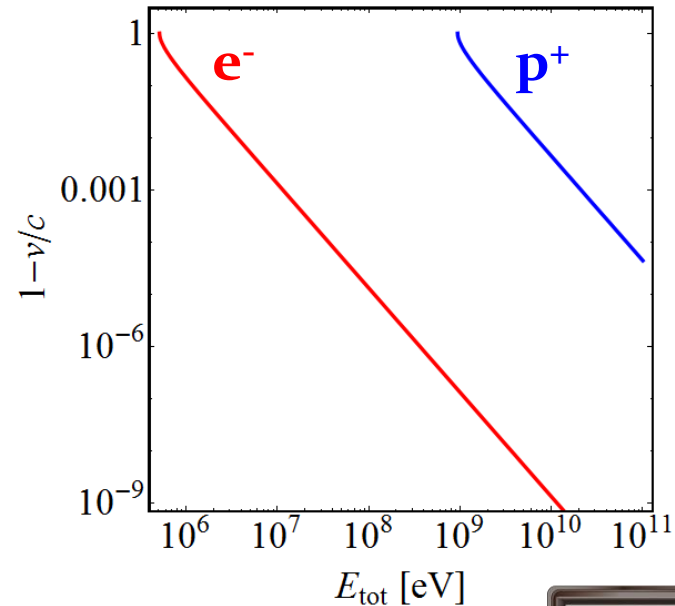
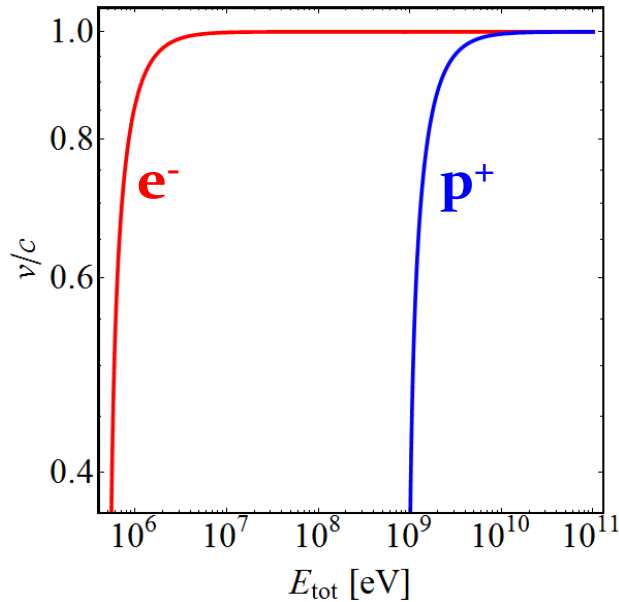
→ RF systems in source and target accelerator →

Correct phase with respect to beam



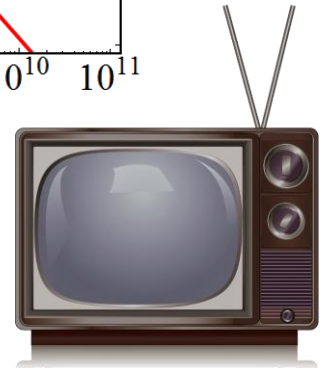
Particle velocity

- Particle velocity depends on its type: $\beta = v/c = \sqrt{1 - (E_0/E)^2}$





- Old television set (30 kV): **Electrons** at 30% of c_0
Protons just at 0.7%
- Small synchrotron (500 MeV): **Electrons** at 99.99995%
Protons at 75.8%

→ Many electron accelerators at 'fixed' frequency



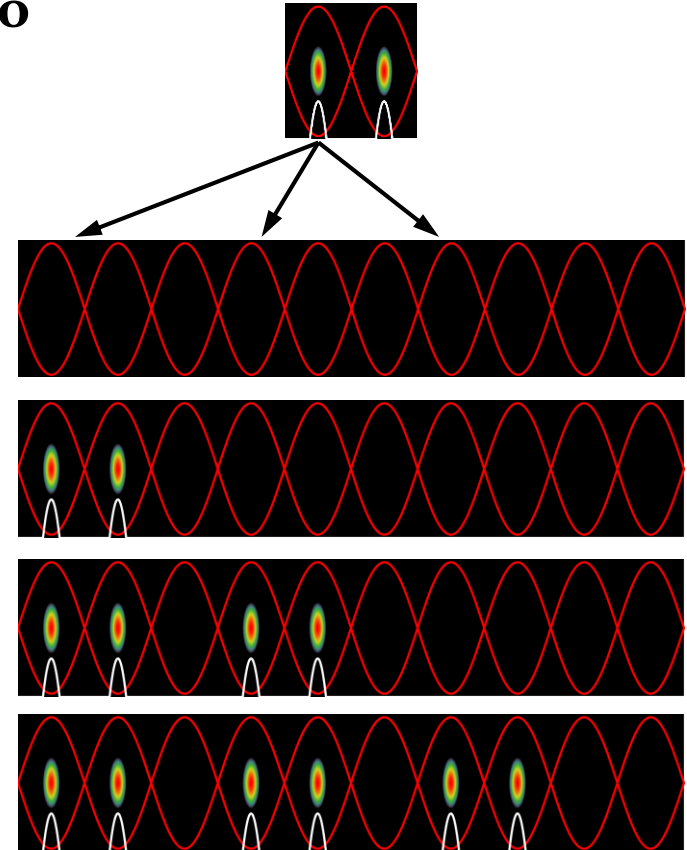
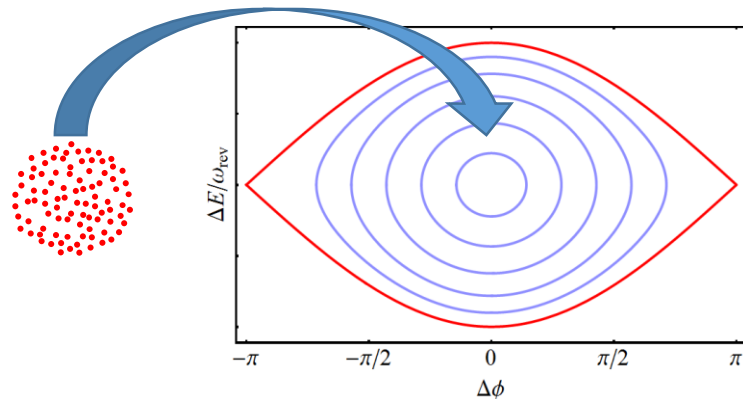
Synchronization needs for particle types

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Lepton accelerators	Hadron accelerators
<ul style="list-style-type: none">• Velocity $v \approx c$ in high energy accelerators• Synchrotron radiation damping (mainly circular accelerators)• Short bunches<ul style="list-style-type: none">• Storage rings: ~10...100 ps• Linear free electron lasers: 50...200 fs	<ul style="list-style-type: none">• Slow, even velocity change relevant to the multi-GeV range• Negligible or small damping from synchrotron radiation• Long bunches<ul style="list-style-type: none">• Synchrotrons: 1...1000 ns (depends on RF frequency)• Linear accelerators: typically few ns
 <ul style="list-style-type: none">→ Fixed frequencies→ High precision	 <ul style="list-style-type: none">→ Variable (sweeping) frequencies→ Moderate precision

Bunch-to-bucket transfer

- Bunch from sending accelerator into the bucket of receiving



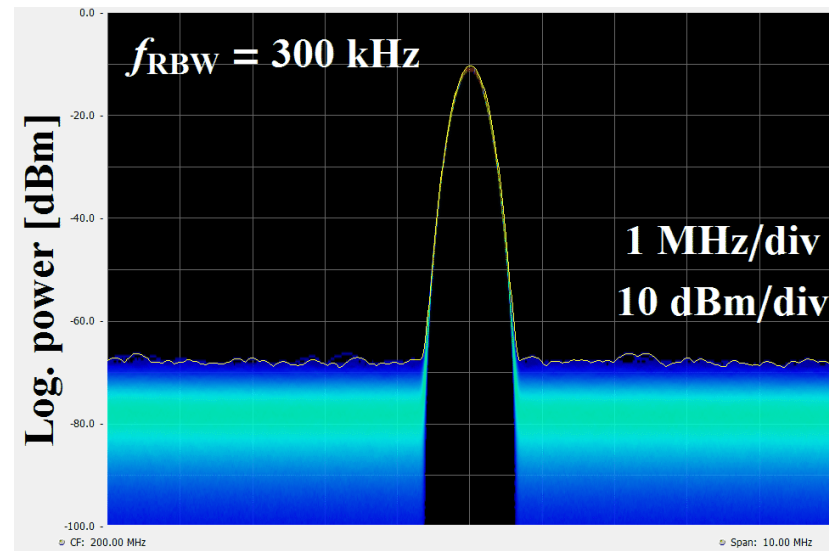
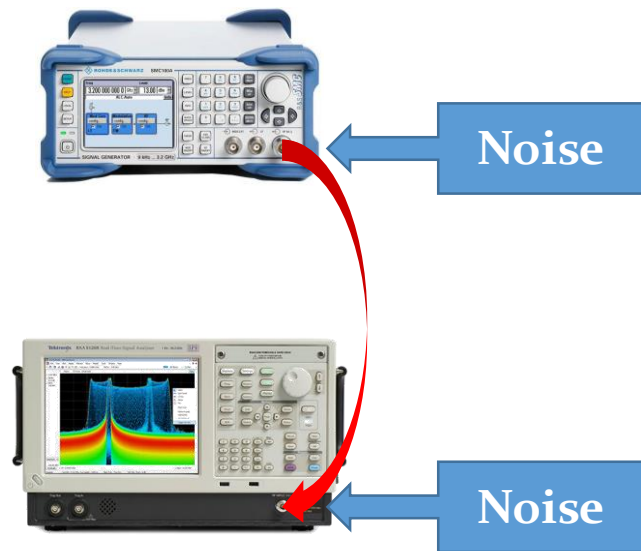
Advantages:

- Particles always subject to **longitudinal focusing**
- **No need for RF capture of de-bunched beam** in receiving accelerator
- **No particles at unstable fixed point**
- **Time structure of beam preserved** during transfer to the next

Noise on signals

Noisy signals

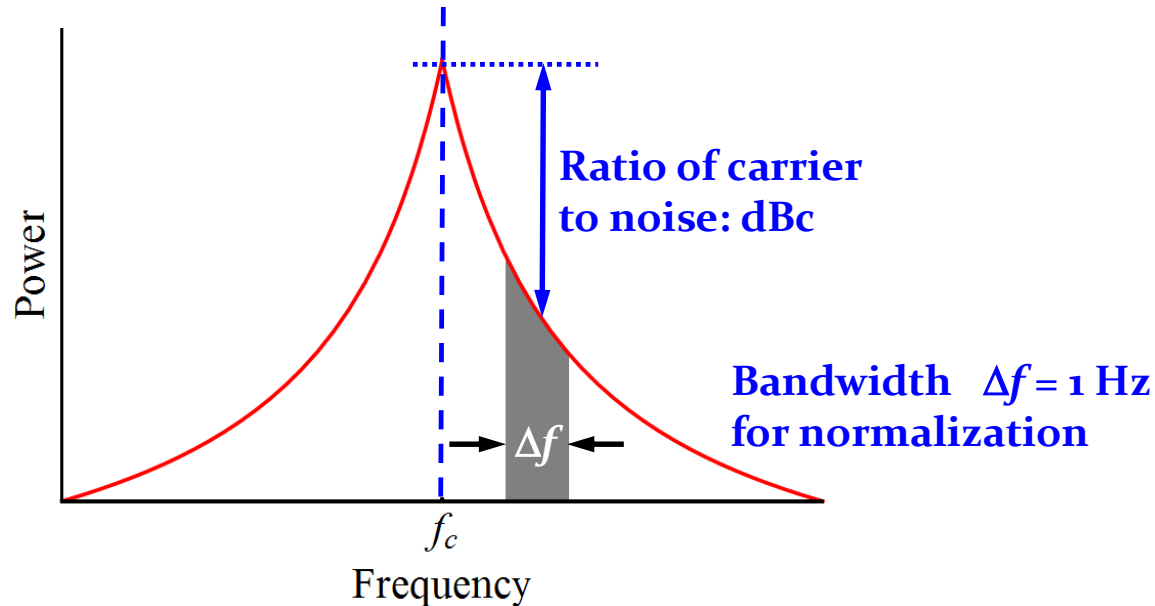
- Degradation of signal quality due to noise
 - Amplitude and/or phase jitter
- What is the difference between a coherent signal and noise?



- Amplitude of **coherent**, quasi **monochromatic** signal (at 200 MHz) is **independent of observation bandwidth**
- Incoherent **noise power** (dominated by spectrum analyzer front-end amplifier/mixer) is **proportional to bandwidth**
- Thermal noise power $\frac{P}{\Delta f} = k_B T = 1.38 \cdot 10^{-23} \text{ J/K} \cdot 296 \text{ K} \simeq -174 \text{ dBm/Hz}$

Analysis of phase noise

- Compare noise power with carrier power as reference



- **Noise power density** $\mathcal{L}(f) = \frac{\text{Power density}}{\text{Carrier power}} \left[\frac{\text{dBc}}{\text{Hz}} \right] = \frac{1}{2} S_\phi(f)$

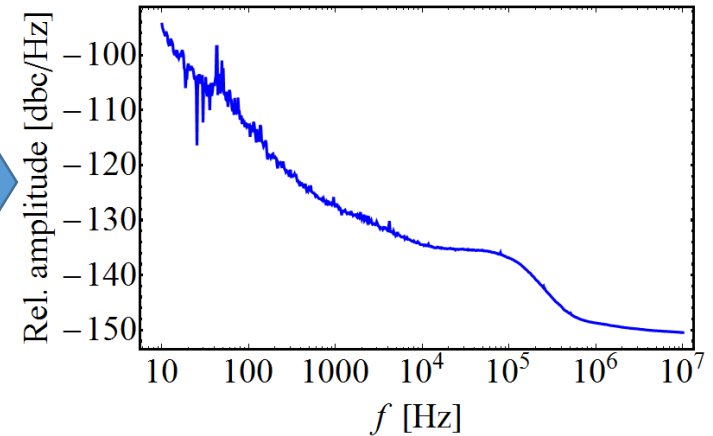
→ Its integral is the phase jitter and using $\Delta t = \frac{\Delta\phi}{2\pi f_c}$

the jitter in time becomes

$$\Delta t_{\text{rms}} = \frac{1}{2\pi f_c} \sqrt{\int_{f_1}^{f_2} S_\phi(f) df}$$

Typical phase noise plots

- Measure phase noise of a synthesized lab generator



→ Note: jitter values can be added as square root of quadratic sum

$$\Delta t_{\text{rms}} = \sqrt{\Delta t_{\text{rms},1}^2 + \Delta t_{\text{rms},2}^2 + \dots}$$

→ Convenient split to relevant ranges

Frequency range	Δt_{rms} [fs]
10...100 Hz	12.4
100 Hz ...1 kHz	5.4
1...10 kHz	5.4
10...100 kHz	11.1
100 kHz...1 MHz	13.0
Total	31.0

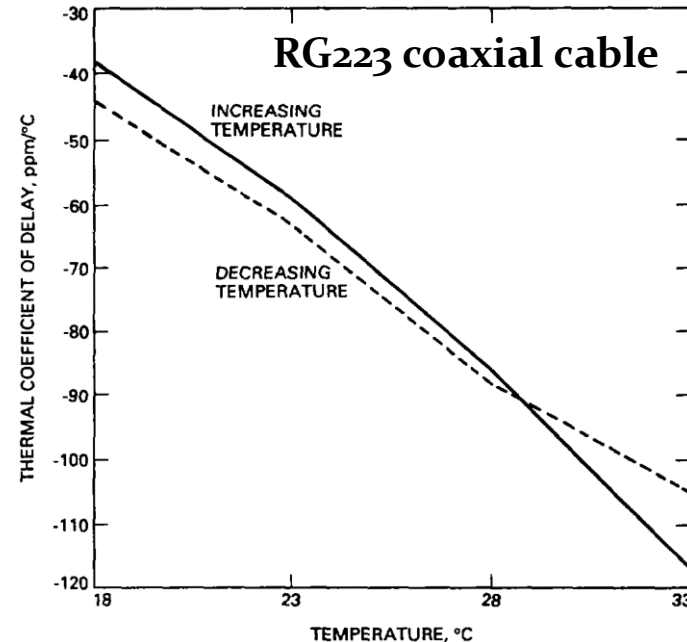
Signal transmission

Transmission of reference signals

- Thermal drift of long coaxial cables or optical fibres

- Thermal coefficient of delay:

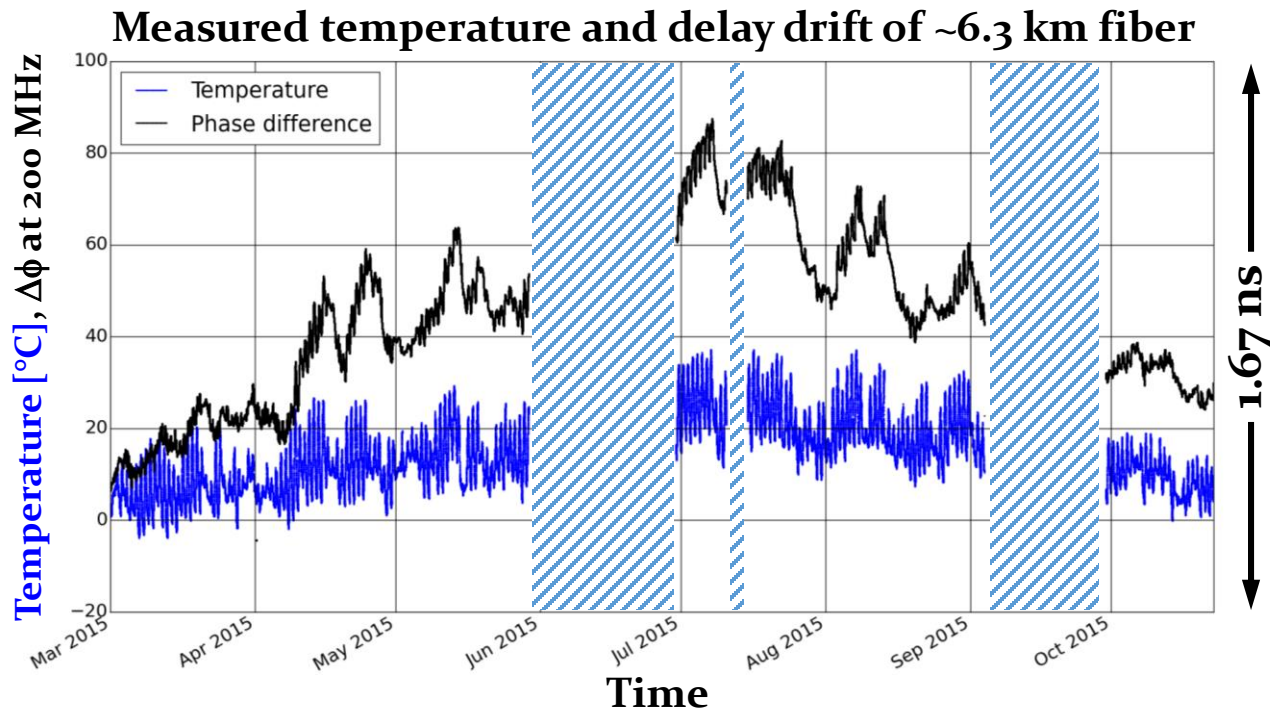
$$\text{TCD} = \frac{\Delta\tau}{\tau} \cdot \frac{1}{\Delta T} = \frac{\Delta\phi}{\phi} \cdot \frac{1}{\Delta T}$$



- Example: 2 km long RG223 cable with ~10 μs delay
 - ΔT of only 1° C (room temperature) changes delay by ~0.5 ns
 - 1.8° at 10 MHz (CERN PS), but 73° at 400 MHz (LHC)
- Optical fibres are typically 10...100 times more stable
- What to do if this is still not sufficient?

Transmission of reference signals

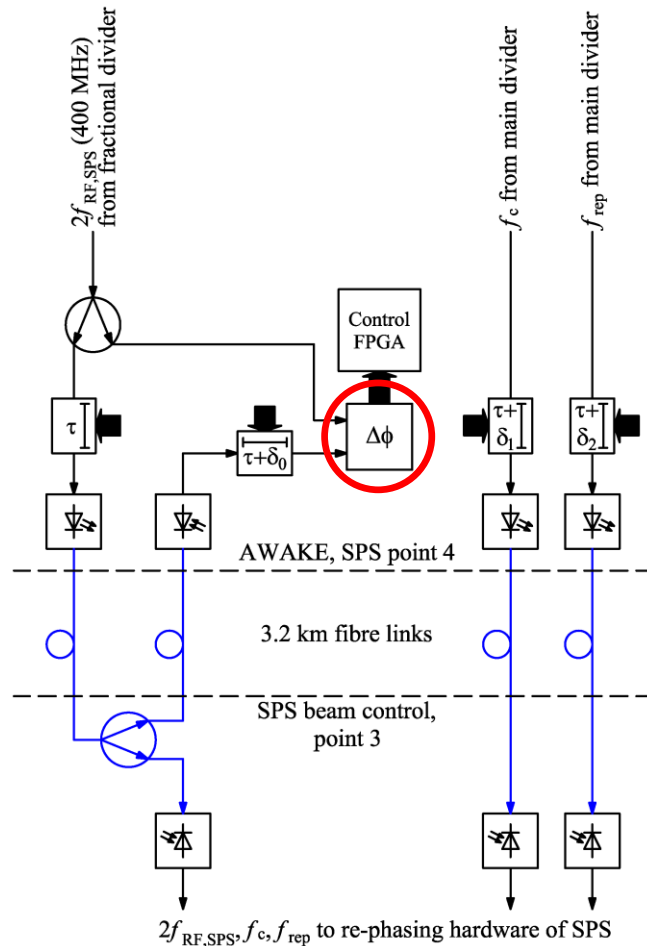
- Measured drift of optical fibres over long distance standard optical fibre



- Drift by about 1 ns insufficient for requirements of setup
→ **Active compensation of delay**

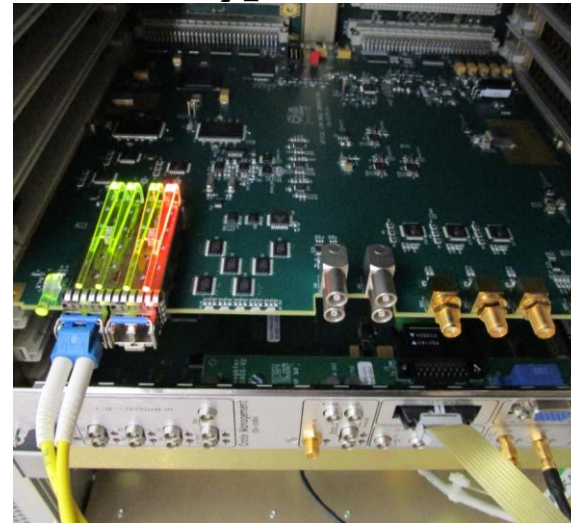
Example: Active drift compensation

Simplified diagram



- Precise synchronization of proton beam from CERN SPS with plasma wake-field experiment AWAKE

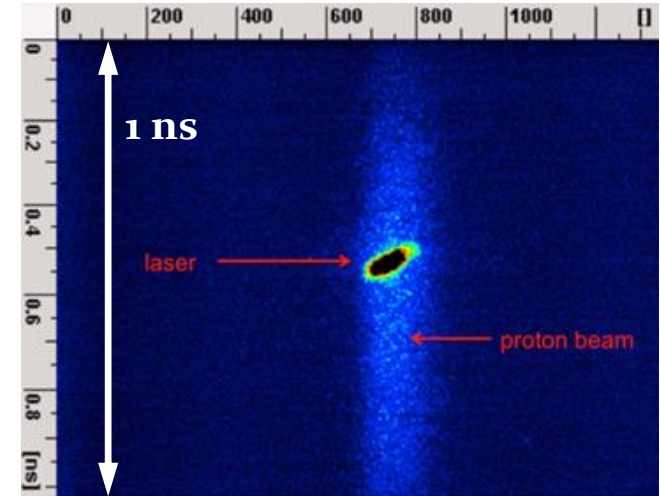
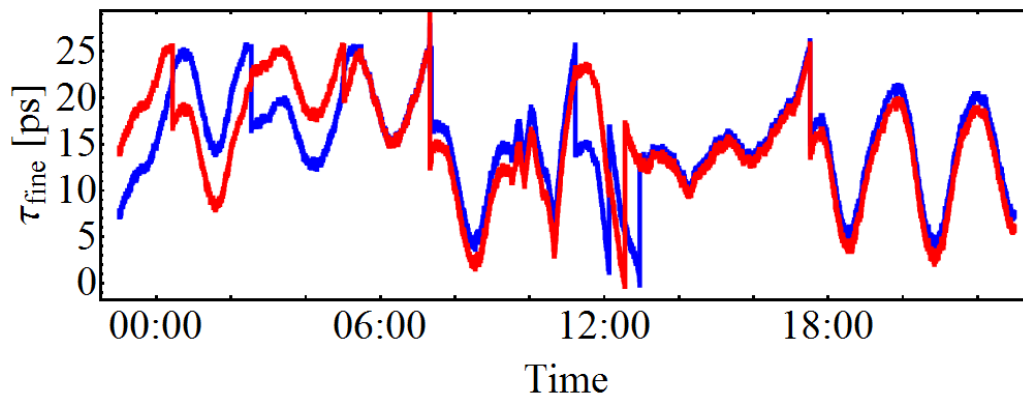
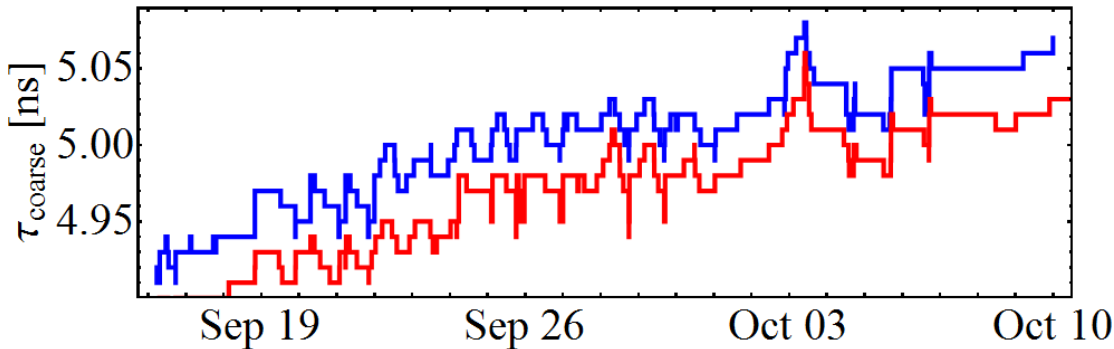
Prototype hardware



→ Expect picosecond precision over several kilometres

Transmission of reference signals

- Total delay composed of coarse (steps of 10 ps) and fine ~ 30 ps range: $\tau = \tau_{\text{coarse}} + \tau_{\text{fine}}$



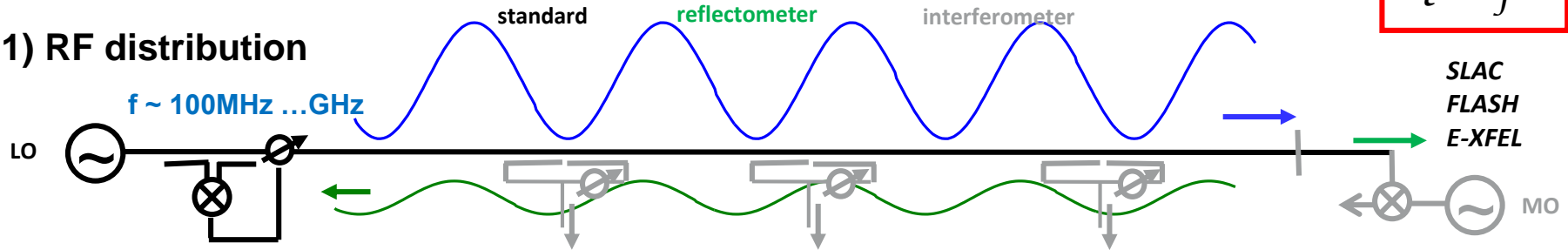
- Precision difficult to evaluate without 2nd 'reference' link
- Arrival of two beams in AWAKE experiment **stable to better ~ 100 ps over months**

Overview of transmission methods

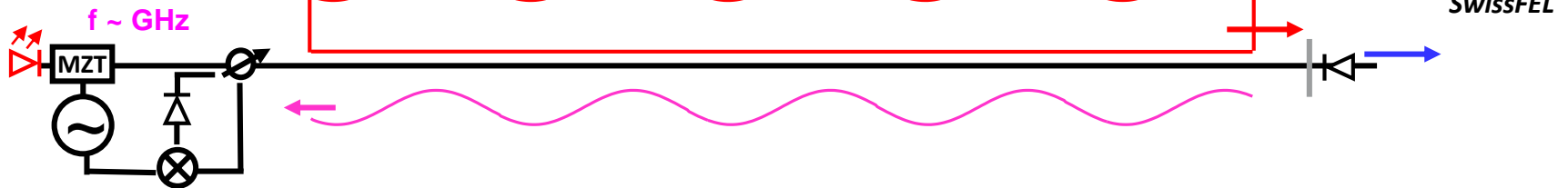
Various approaches:

$$\frac{\Delta t}{t} = \frac{\Delta f}{f}$$

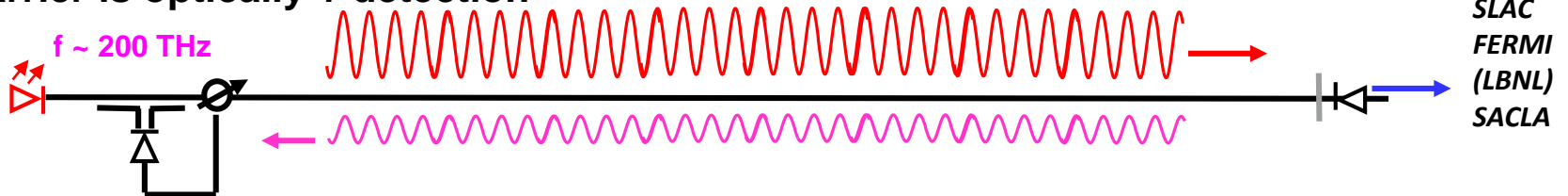
1) RF distribution



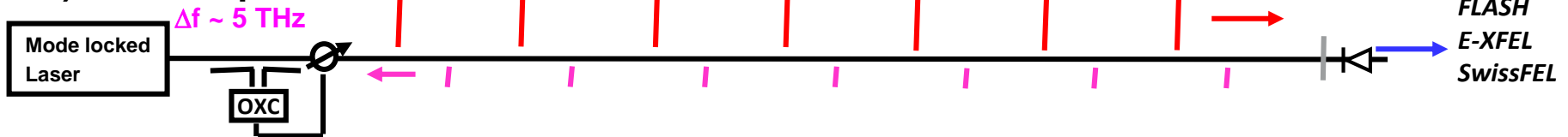
2) Carrier is optically



3) Carrier is optically + detection



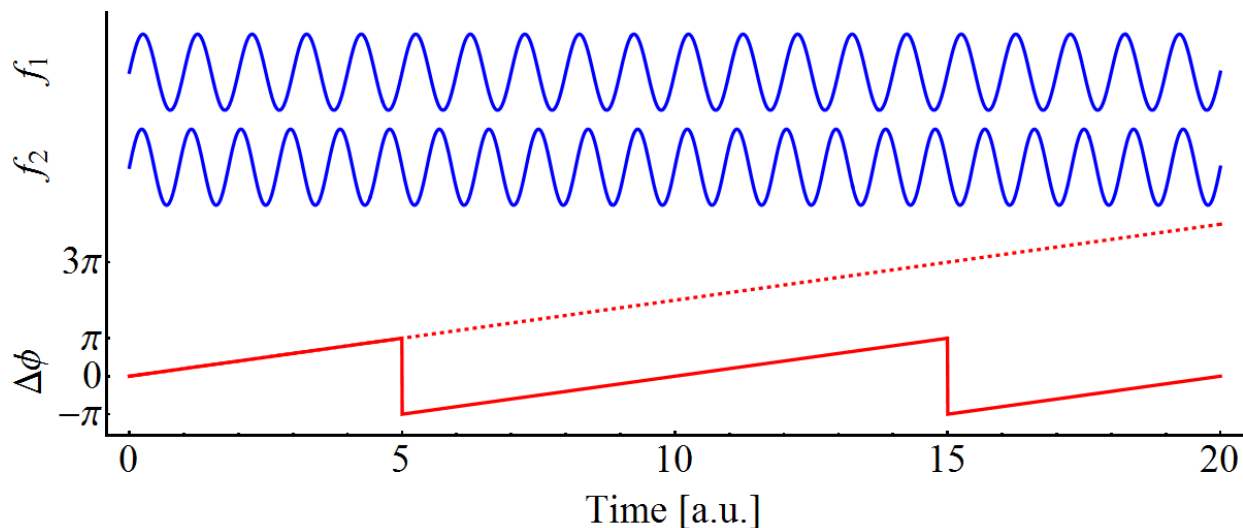
4) Pulsed optical source



Phase detection

Frequency and phase

- Two signals at different frequencies ω_1 and ω_2



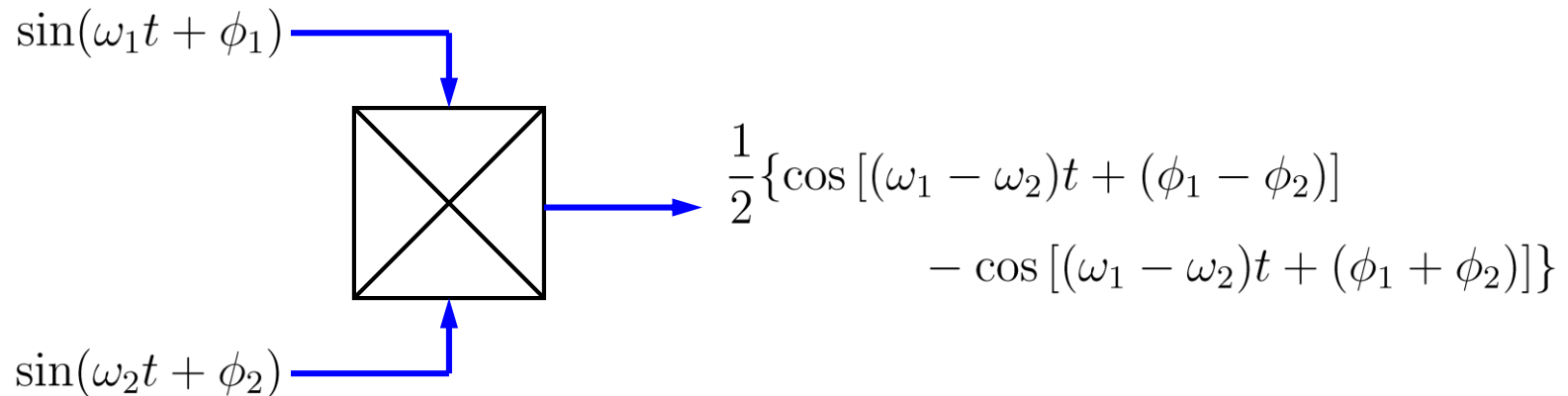
- **Phase difference, $\Delta\phi$, between both signals changes linearly**
- **Ambiguity to distinguish between $\Delta\phi = -\pi, \pi, -3\pi, 3\pi, \dots$**
- **Saw-tooth in phase means constant frequency difference**

→ **Equivalence of frequency and phase**

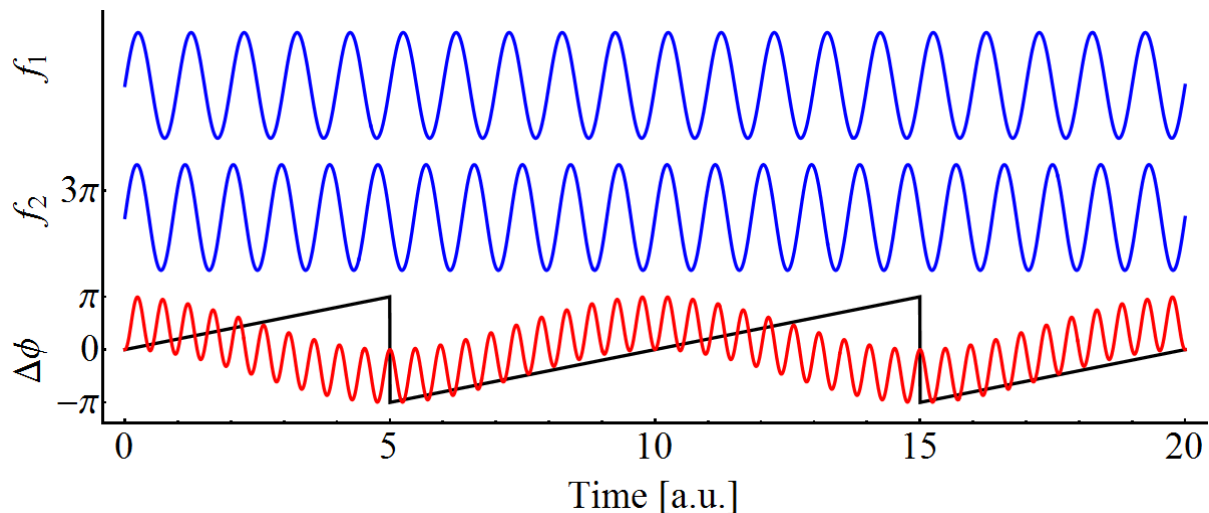
$$\omega = \frac{d\phi}{dt} \quad \Leftrightarrow \quad \phi = \int \omega dt$$

How to detect phase differences?

- **Example: analogue 4 quadrant multiplier and low pass filter**

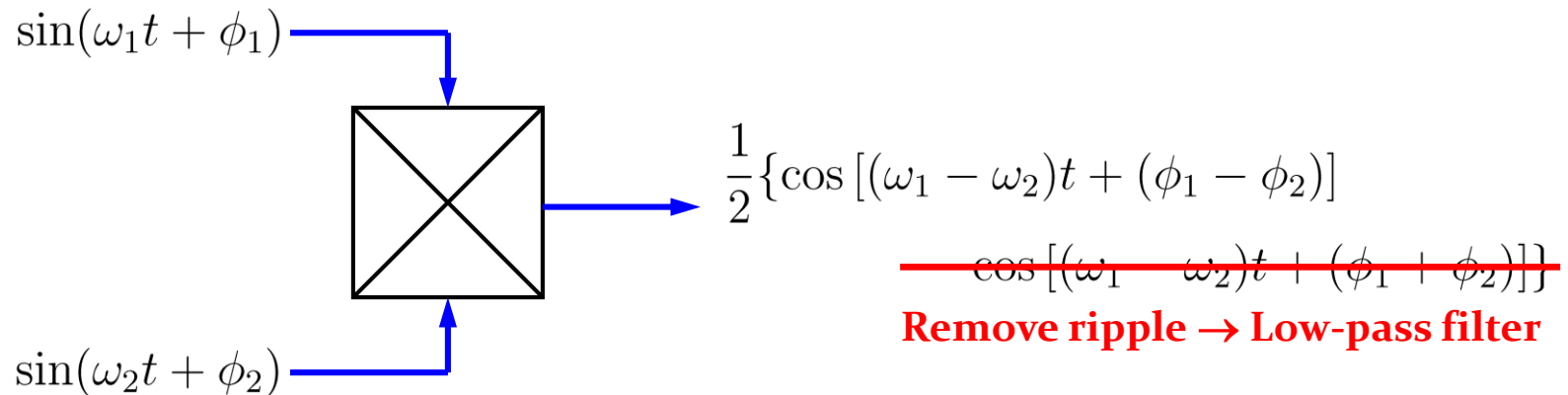


- **Signals:**

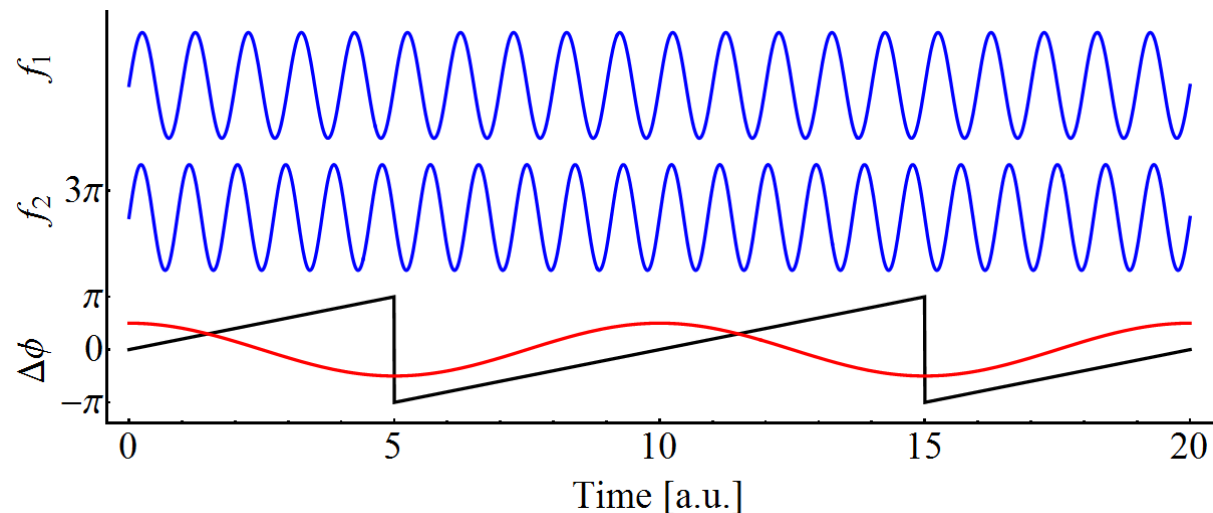


How to detect phase differences?

- **Example: analogue 4 quadrant multiplier and low pass filter**

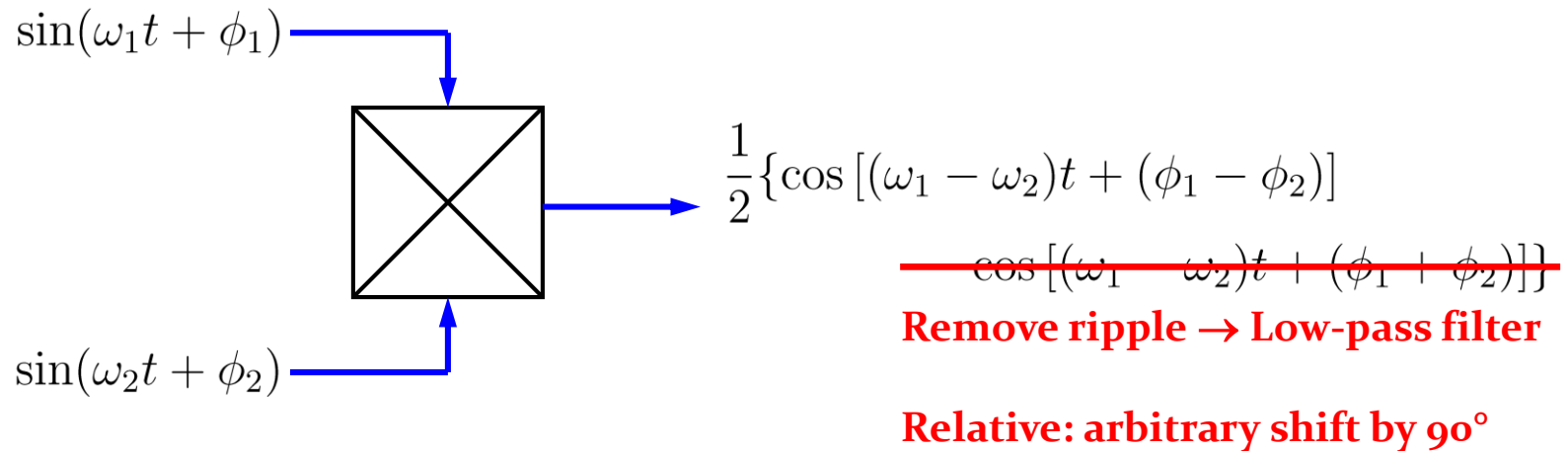


- **Signals:**

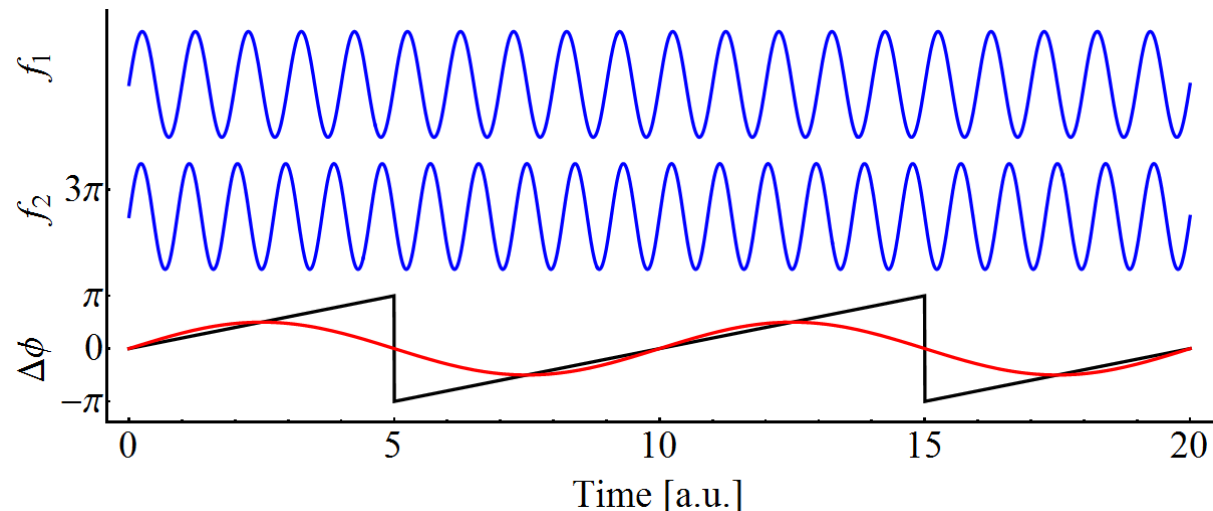


How to detect phase differences?

- **Example: analogue 4 quadrant multiplier and low pass filter**



- **Signals:**

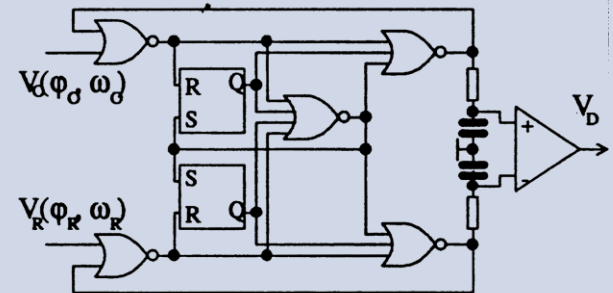


- **Phase discriminator in approximately $\pm 90^\circ$ range**

Further phase detection techniques

Multitude of different phase discriminators

Type	Range	Behavior
Analogue 4 quadrant multiplier	π	Sinusoidal: $s_{\text{out}} \sim \cos \phi$
Exclusive OR gate	π	Linear: $s_{\text{out}} \sim \phi - 3\pi/2$, or $s_{\text{out}} \sim -\phi + \pi/2$
Sample and hold	π	Sinusoidal: $s_{\text{out}} \sim \sin \phi$
Flip-flop phase detector	π	Linear: $s_{\text{out}} \sim \phi - \pi$
Tri-state double flip-flop	2π	Linear: $s_{\text{out}} \sim \phi$
Balanced optical microwave phase detector (Sagnac loop)	$< \pi$	Sinusoidal: $s_{\text{out}} \sim \sin \phi$ (clipped)

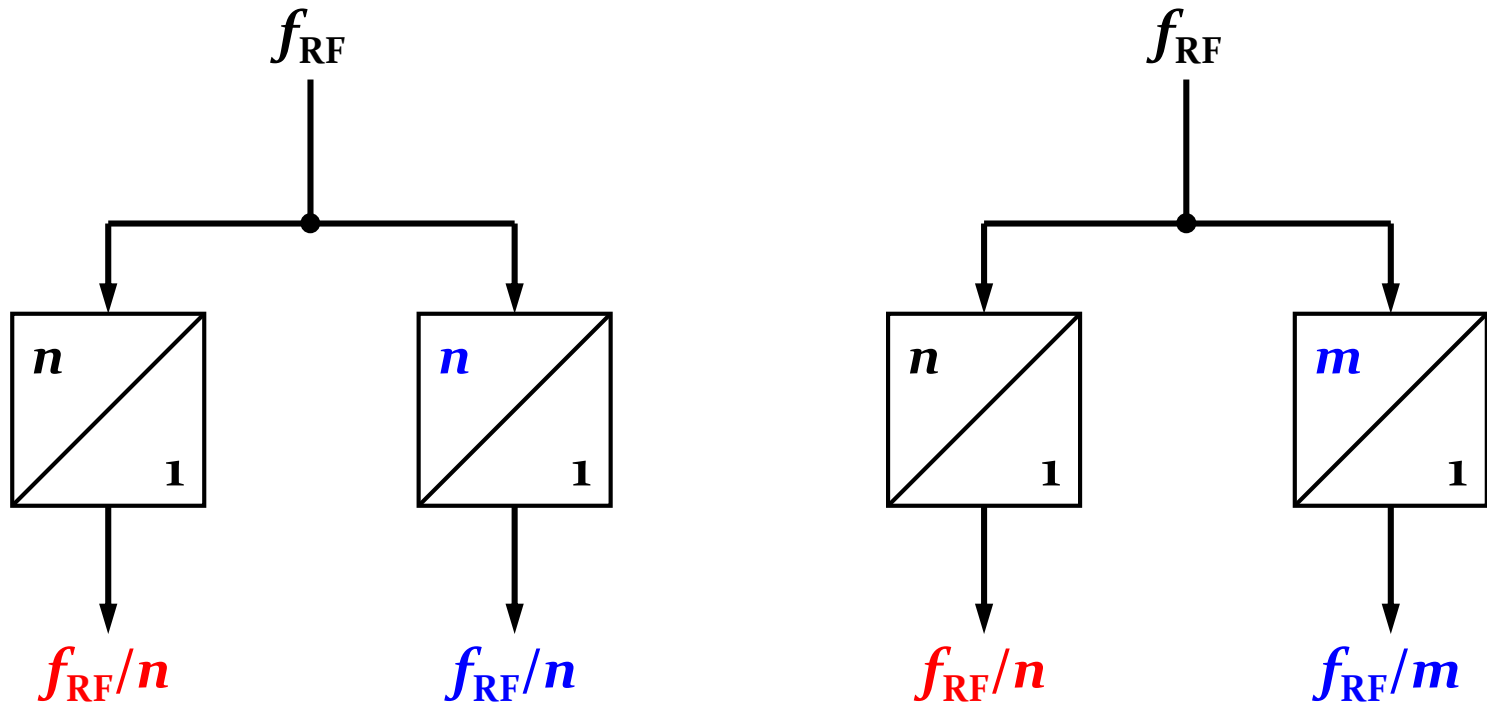


- Full phase coverage of 2π range excludes ambiguity of $\pm\pi$
- Avoids locking of phase loop with unwanted offset
- Measure phase at high frequencies for precision

Dividers

Frequency dividers

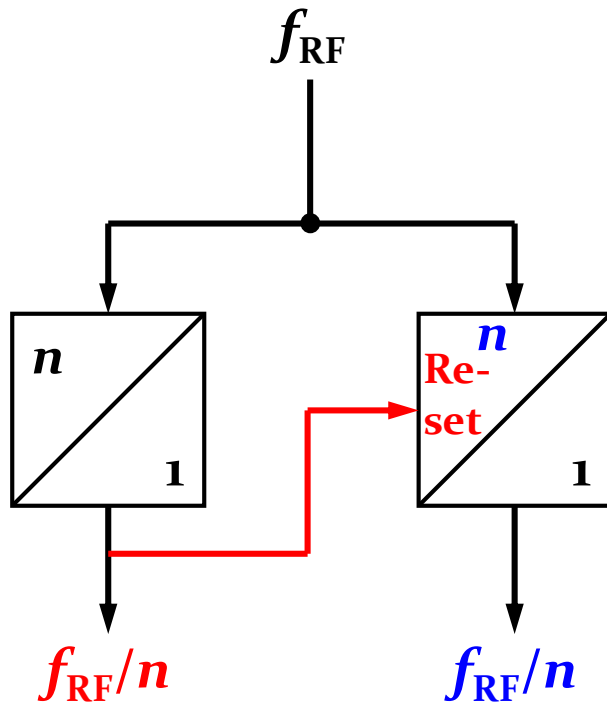
- Generate signals using frequency division from f_{RF}



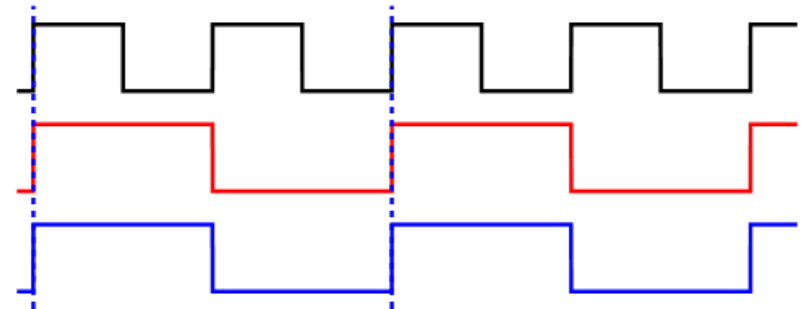
- Works (well, on paper), so what is the problem?
 → Dividers are nothing but counters! **Initial value?**

Synchronizing multiple dividers

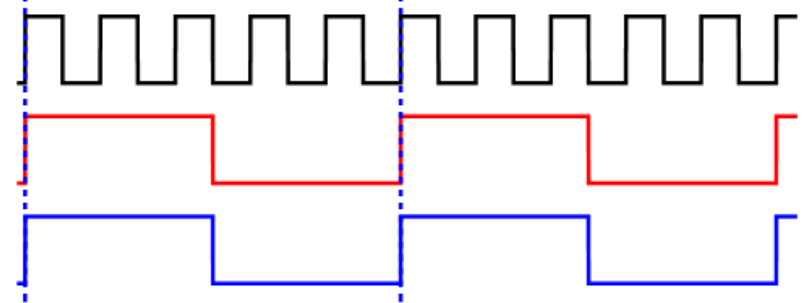
- Generate signals using frequency division from f_{RF}



$n = 2$:



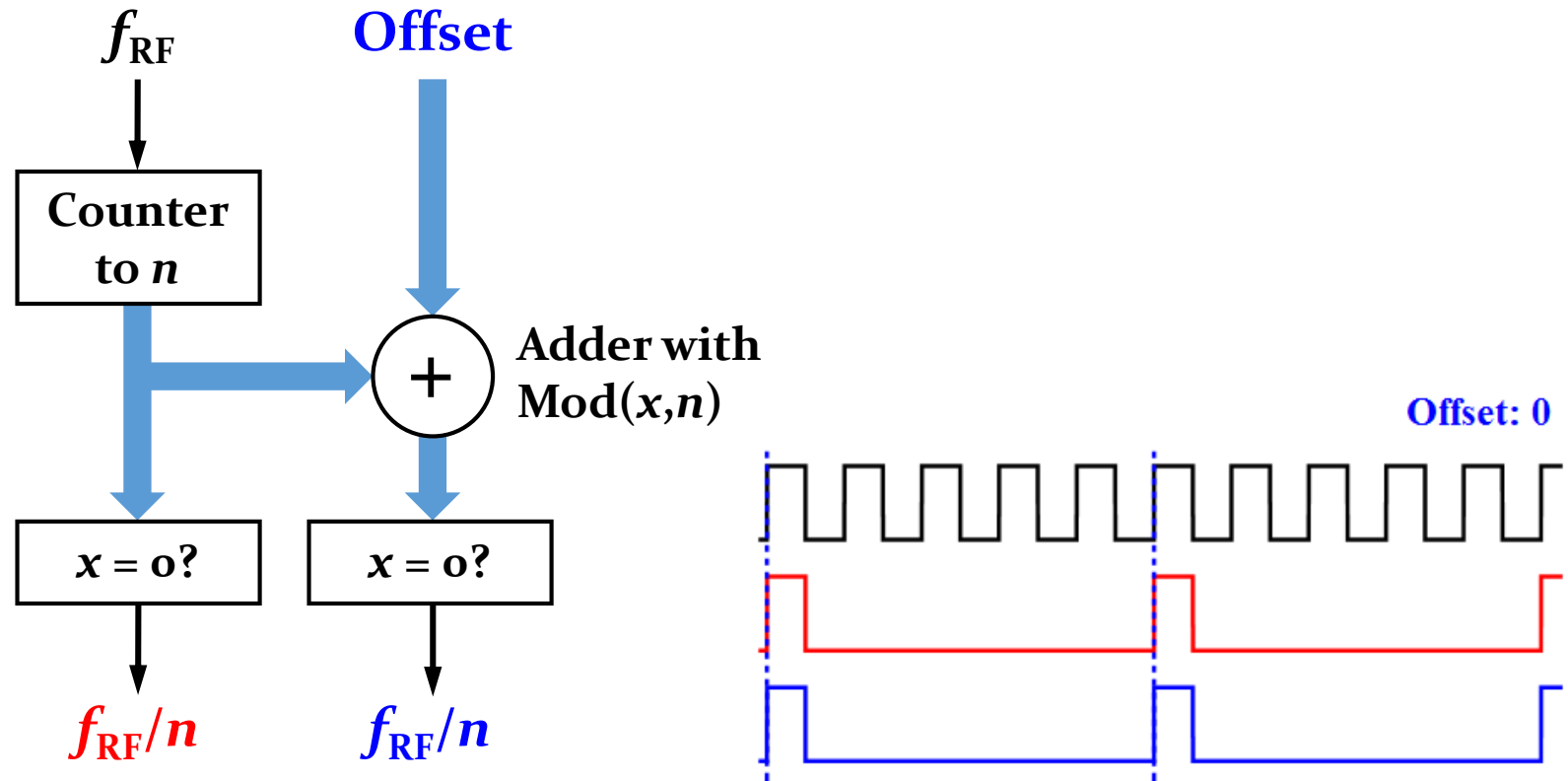
$n = 5$:



- How to fix?
- Reset from master to slave divider(s) to force initial condition
→ **Never more than one divider without reset!**

Multiple divider with counting offset

- Counter with programmable offset value

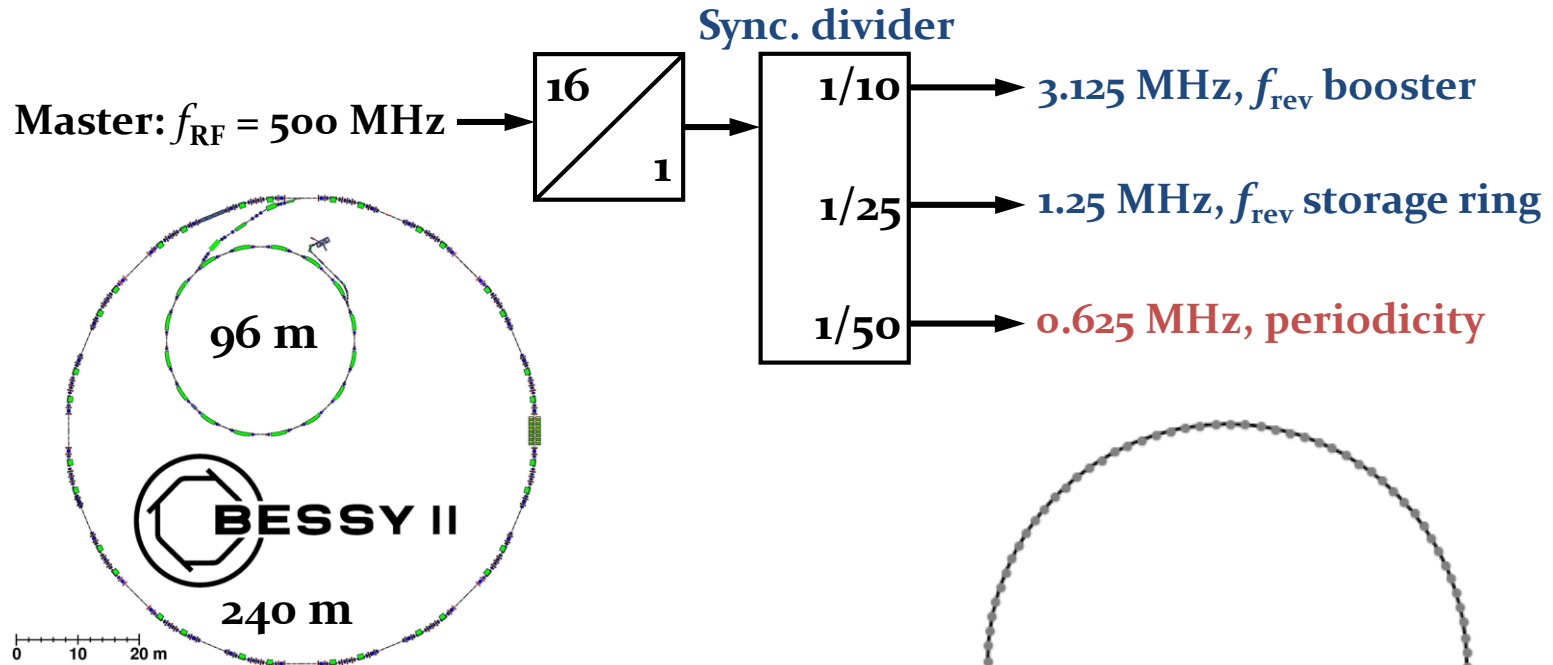


- Single counter/divider split in two output branches
- Impossible to lose relative phase of outputs
- More complicated set-up allows also f_{RF}/m and f_{RF}/n , etc.

Fundamental periodicity

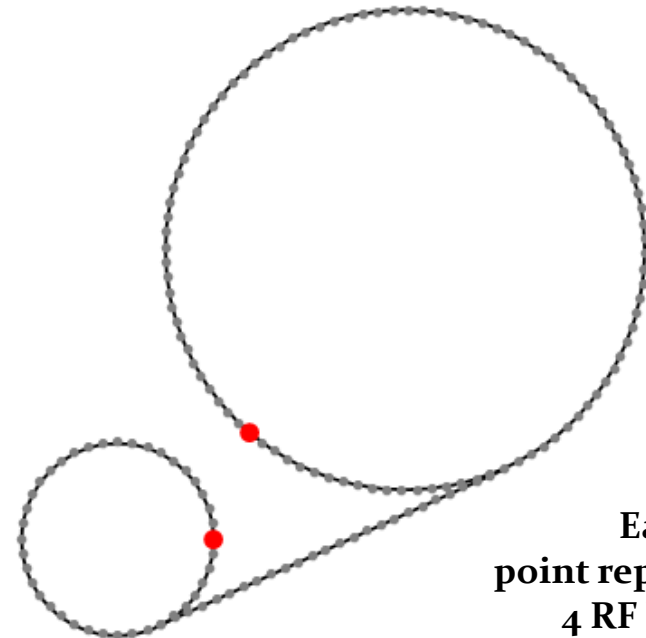
Example: BESSY II booster and storage ring

- Storage ring circumference 240 m, $f_{\text{RF}} = 499.6$ MHz
- Circumference ratio of Booster and storage ring: **2/5**



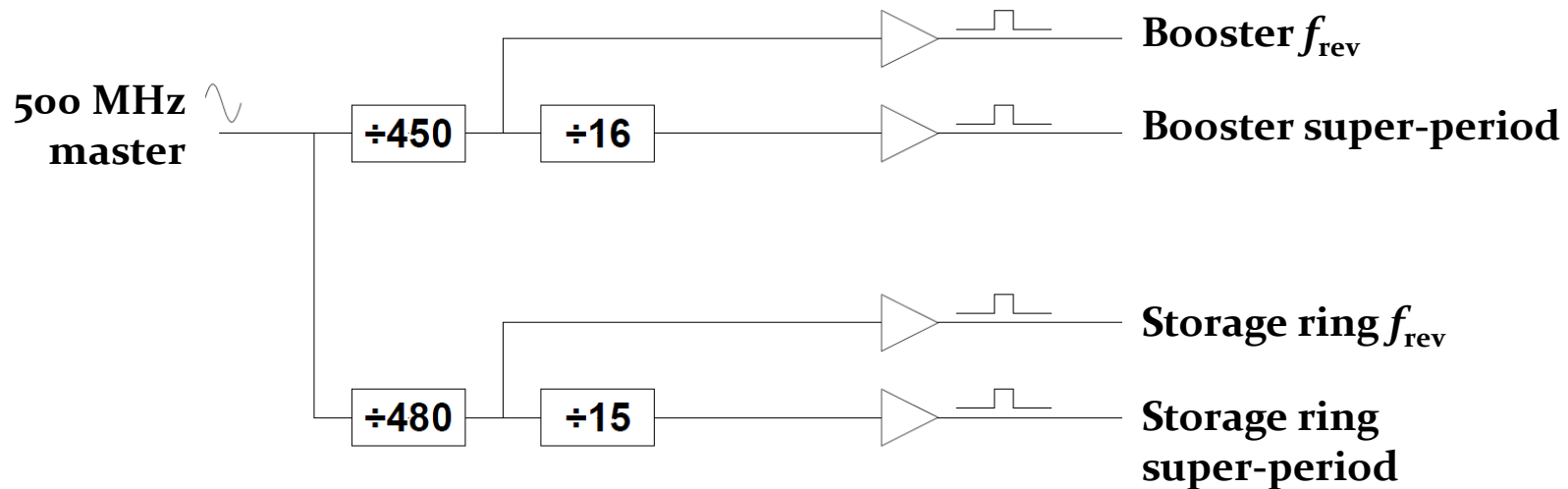
→ Everything repeats with periodicity of

- 5 turns in booster
- 2 turns in storage ring



Example: SLS booster and storage ring

- Storage ring circumference 288 m, $f_{RF} = 499.6$ MHz
- Circumference ratio of Booster and storage ring: **15/16**



→ Fundamental periodicity (super-period)

16 turns of booster corresponding to 15 turns in storage ring

Fundamental periodicity for transfer

- Two accelerators with revolution periods $T_{\text{rev},1}$ and $T_{\text{rev},2}$

$$T_{\text{rev},2} = \frac{m}{n} T_{\text{rev},1} \quad \rightarrow \quad T_{\text{super}} = T_{\text{common}} = T_{\text{fiducial}} = mT_{\text{rev},1} = nT_{\text{rev},2}$$

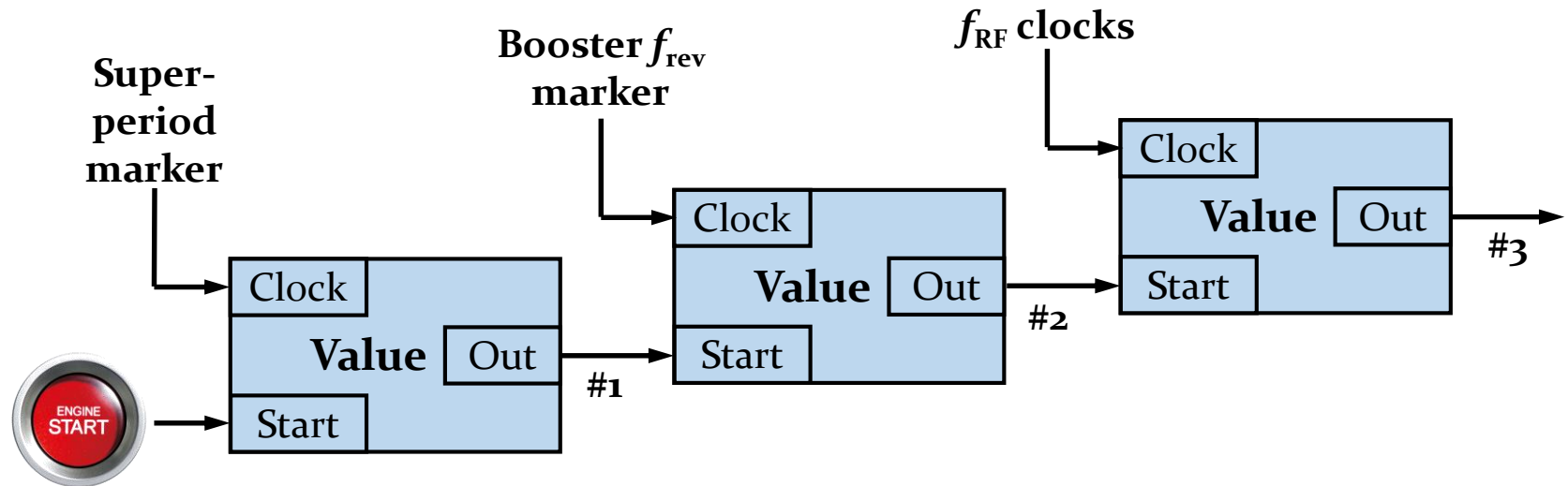
- Beam transfer may take place at every period $mT_{\text{rev},1}$ or $nT_{\text{rev},2}$
- This periodicity is, depending on the accelerator and laboratory, called **super-period**, **common** or **fiducial period**
- In case of **integer ratio** of revolution frequencies, beam can be transferred once every turn of the larger accelerator

Sending	Receiving	Ratio	Remark
BESSY booster	BESSY SR	2/5	Fixed frequency
SLS booster	SLS SR	15/16	Fixed frequency
J-PARC RCS	J-PARC MR	2/9	Profit from ratio for bucket selection
PS booster	PS	1/4	
PS	SPS	1/11	
PS	AD	3/1	Particle type and energy change at transfer
SPS	LHC	7/27	f_c as low 1.6 kHz

Synchronous triggers

How to generate beam synchronous triggers?

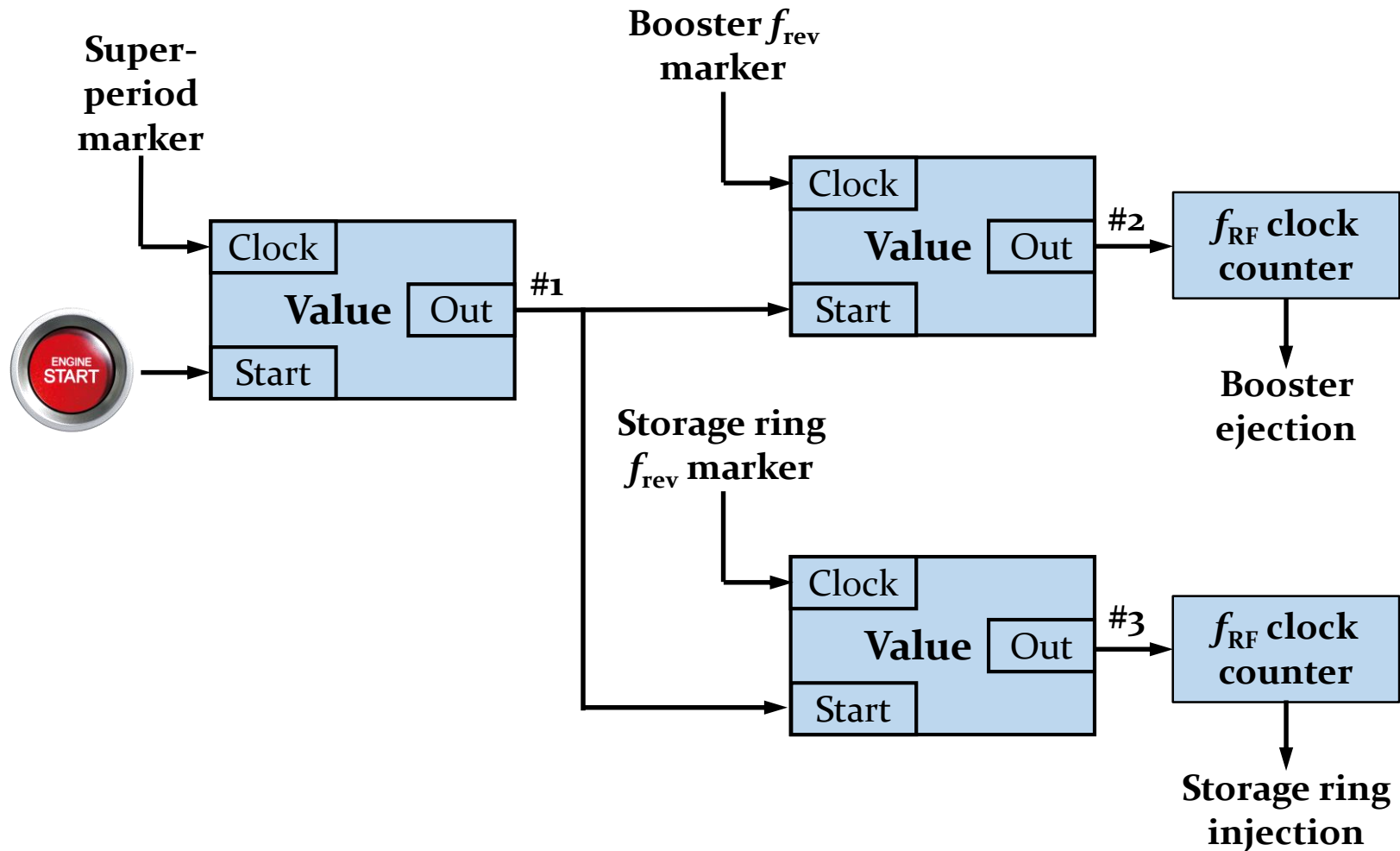
→ Chains of counters to re-synchronize timings



Each step re-synchronizes with respect counter clock

- 'Start engine button' synchronous to nothing
- Complete system of two accelerators periodic with timing #1
- Timing #2 marks, e.g., a delay in number of turns
- Timing #3 counts f_{RF} clocks to fine adjust, e.g., bucket number

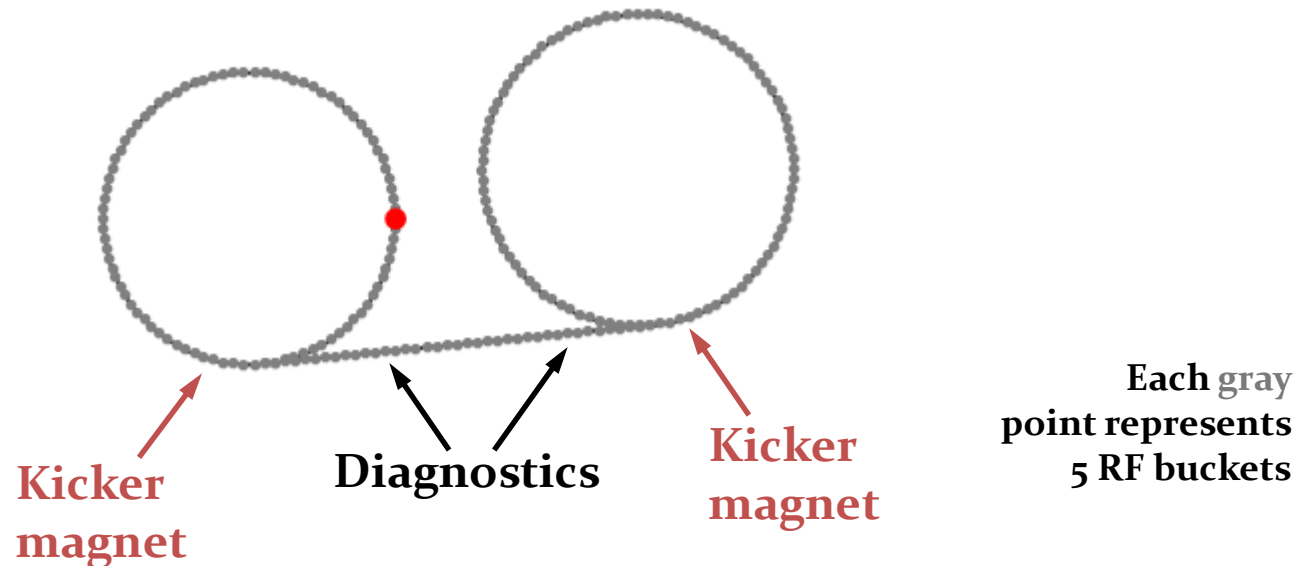
Synchronous trigger trees



- Timing counters may use different clocks, as long as the clocks are derived **from the same source**
- Reproducible delay between clock #2 and #3
- Tree structures of timings

Circular electron/lepton accelerators

- Simplification for most electron accelerators:
 - Leptons are **practically at speed of light**
 - Synchrotron radiation **damping forces bunches into buckets**
 - Beam synchronous **timing triggers** can be derived **by counting RF master clock** (or its sub-multiples)
 - **Everything is predictable from the beginning**



→ Let's get frequencies moving

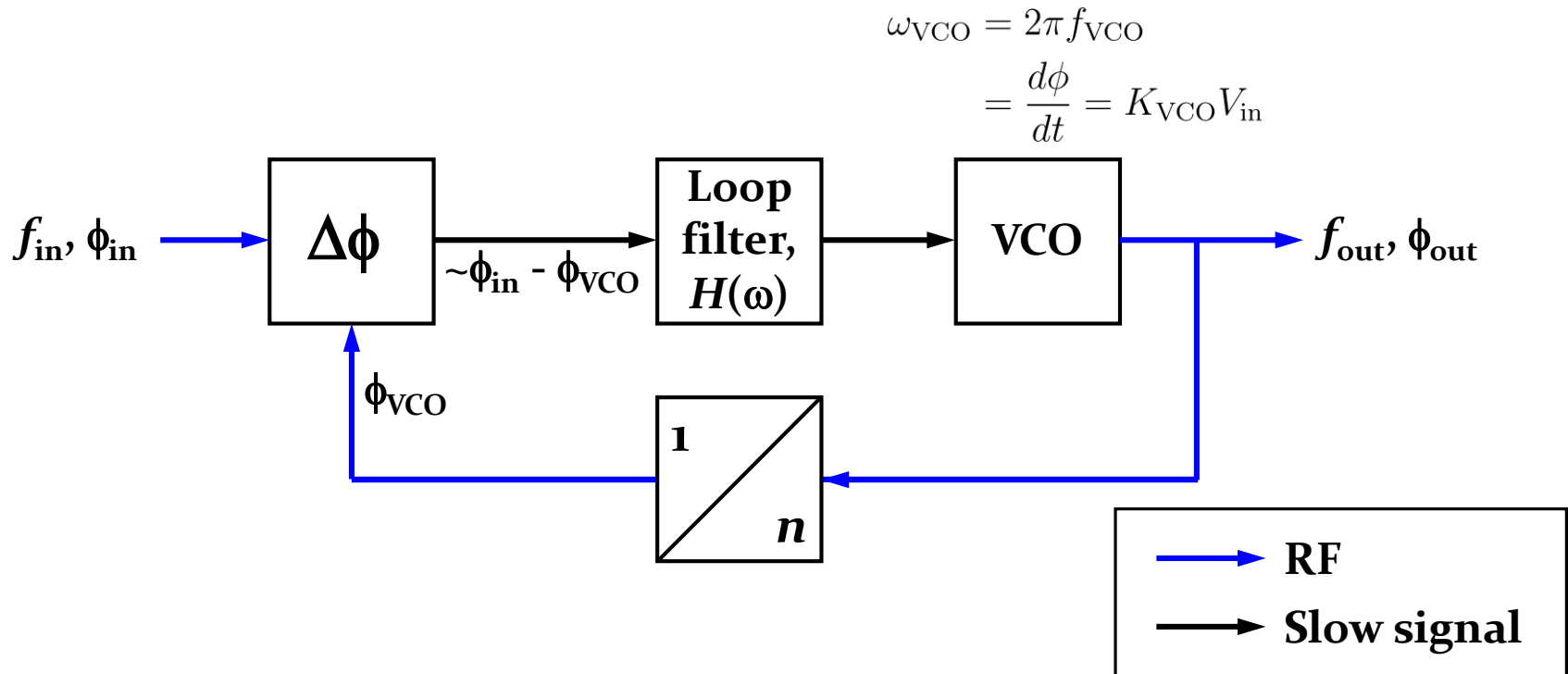
Transfer between hadron accelerators

Synchronous triggers and bucket counting

- **Circular hadron accelerators: master clock sweeps**
- **Need again synchronous timings with respect to beam**
 - **Kicker magnets**
 - **Beam instrumentation**
- **RF manipulations require bunches in certain buckets**
 - **Beating pattern due to multiple RF harmonics**
 - **Splits behaviour for different buckets**
 - **Bucket numbering**
- **Need to know longitudinal beam position for transfer**
 - **Where (in phase/in time) is the beam?**

Phase-locked loop

- Frequency re-generation and multiplication
- Voltage controlled oscillator (VCO) locked in phase to input



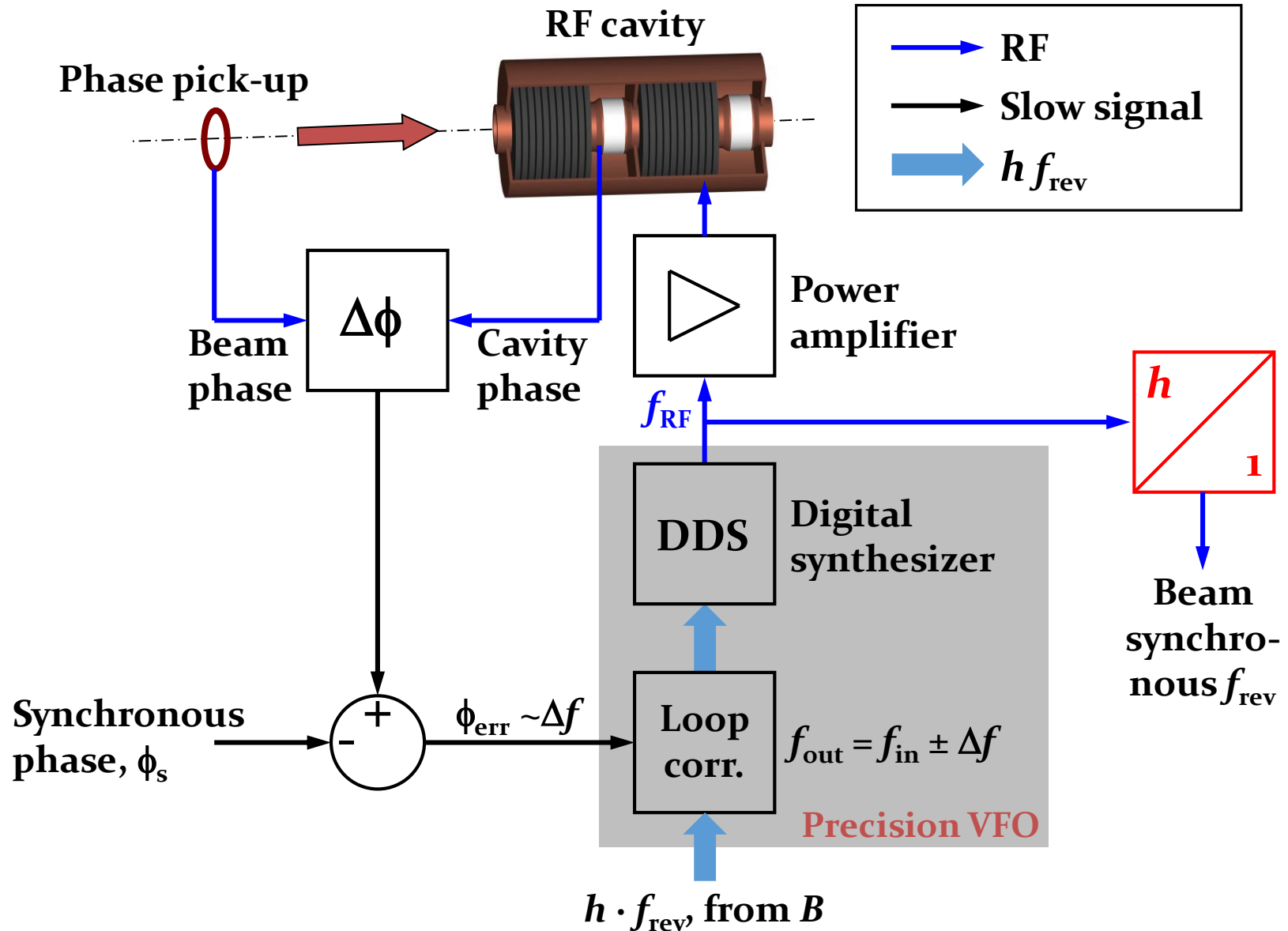
→ Fixed phase relationship:

$$\phi_{\text{out}}/n - \phi_{\text{in}} = \text{const.}$$

→ Optional divider:

$$f_{\text{out}} = n \cdot f_{\text{in}}$$

Beam phase loop

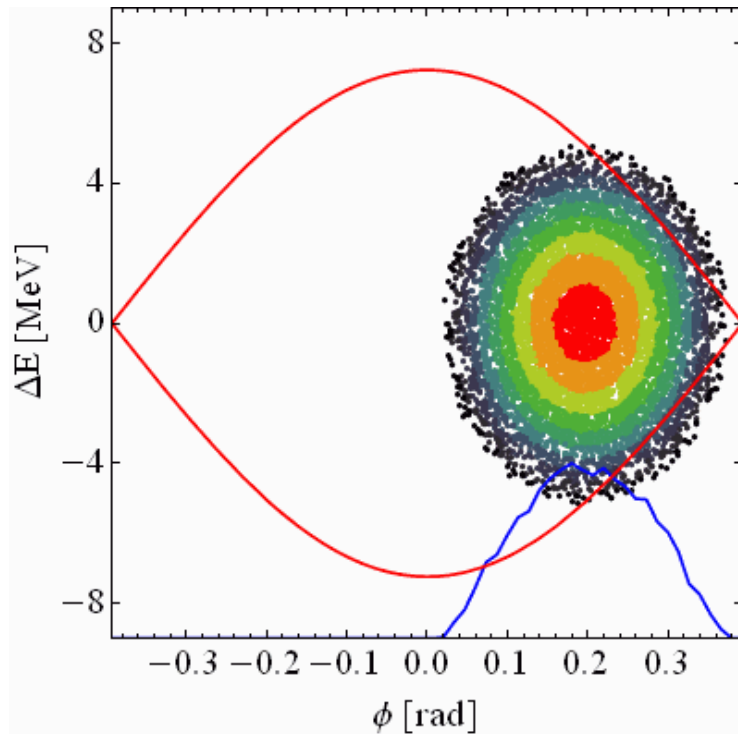


→ Phase-locked loop with beam phase as reference for RF system

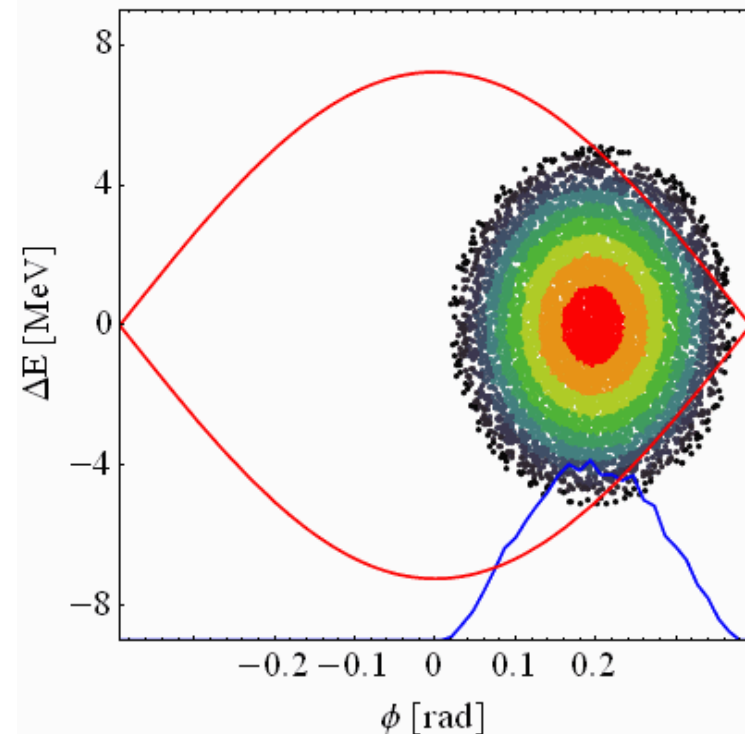
Benefits of beam phase loop at transfer

- Adapt RF phase to bunch phase **before beam blows-up**
- Fast compared to **timescale of synchrotron frequency, f_s**

Rigid RF, no phase loop

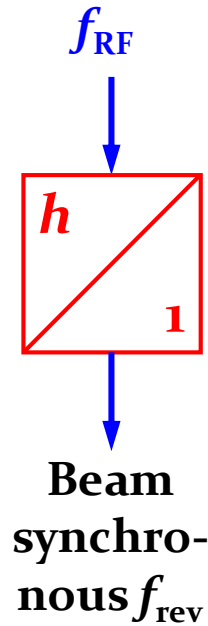


With phase loop



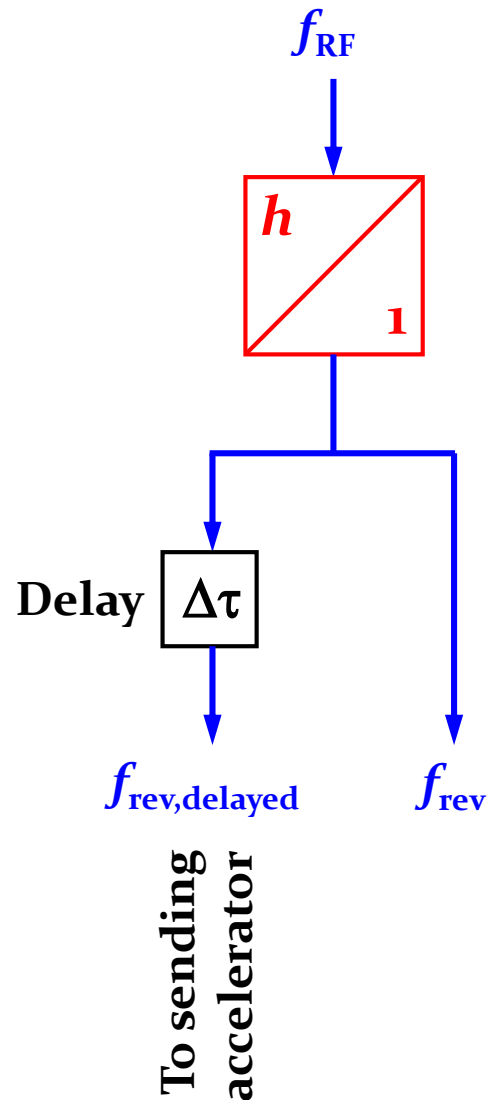
- Even large transients (injection, transition) can be controlled
- Small longitudinal emittance blow-up

Start counting with injection



- Start of divider/counter?
 - Get it right from injection
 - Use output from divider as reference for incoming beam

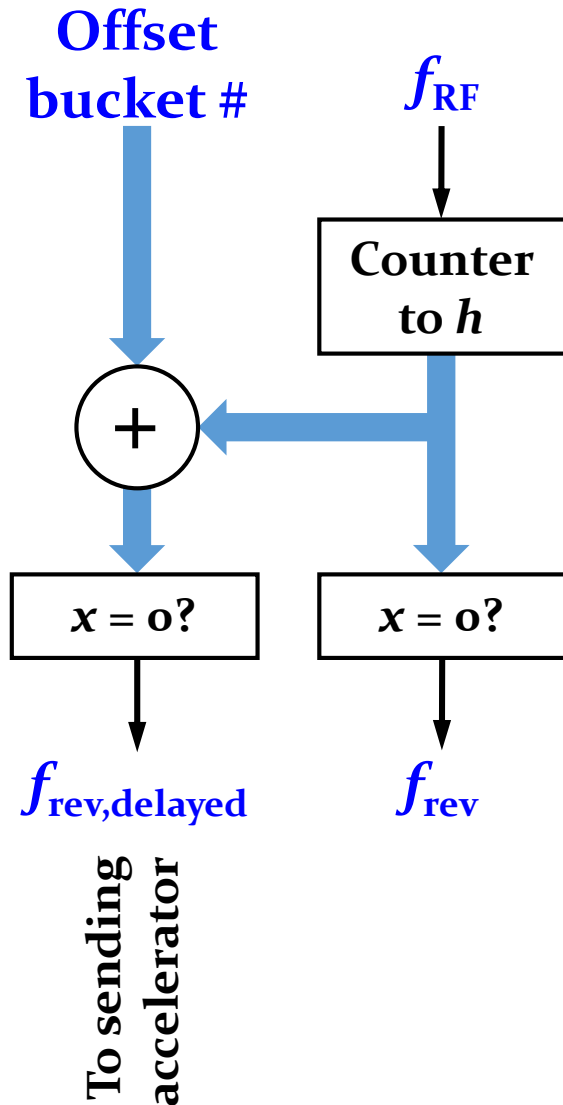
Start counting with injection



- Start of divider/counter?
 - Get it right from injection
 - Use output from divider as reference for incoming beam

- Before injection:
 - Distribute delayed revolution frequency to sending accelerator
 - Bunches are injected synchronously with $f_{rev,delayed}$
 - **Shifted** with respect to f_{RF} and f_{rev}

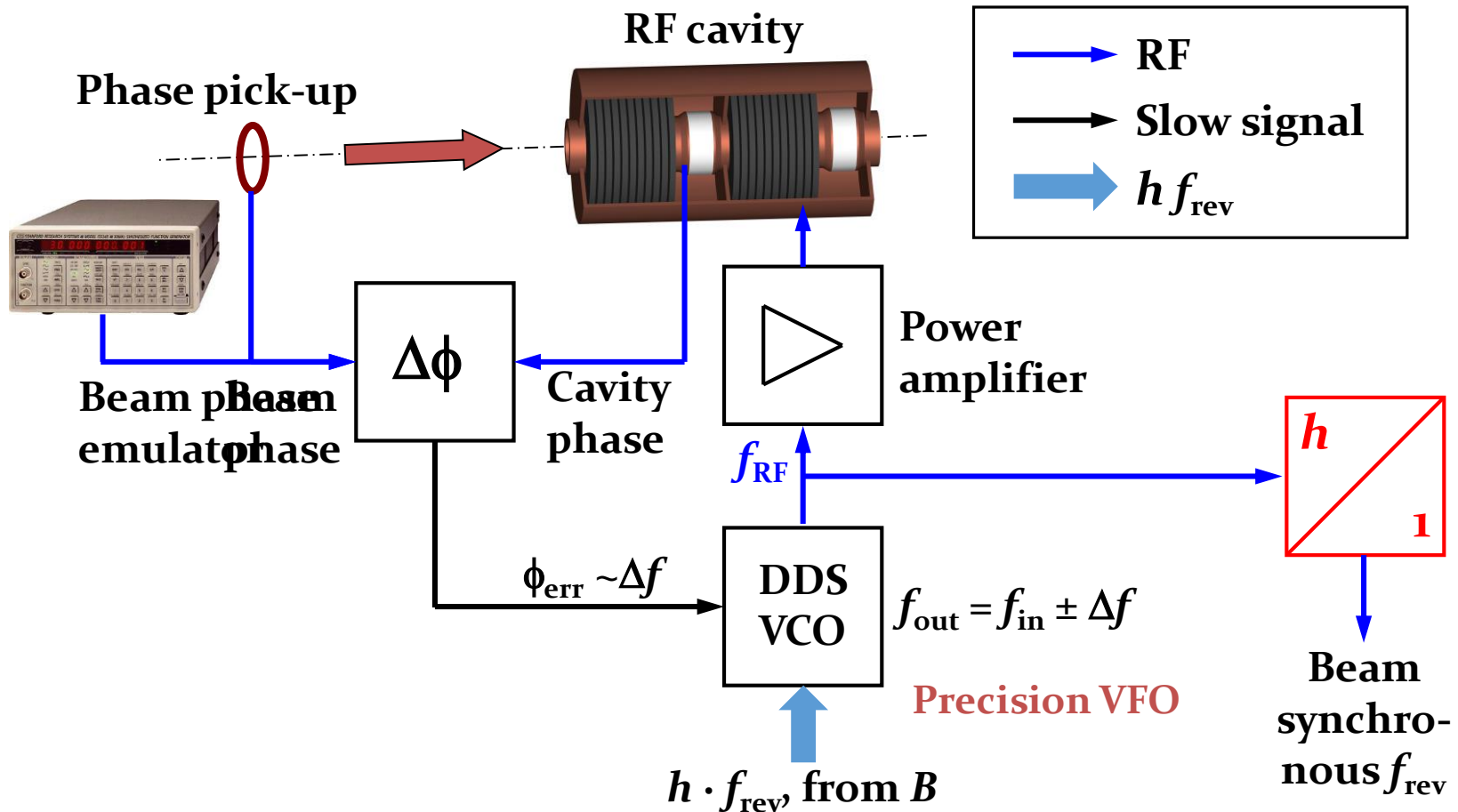
Start counting with injection



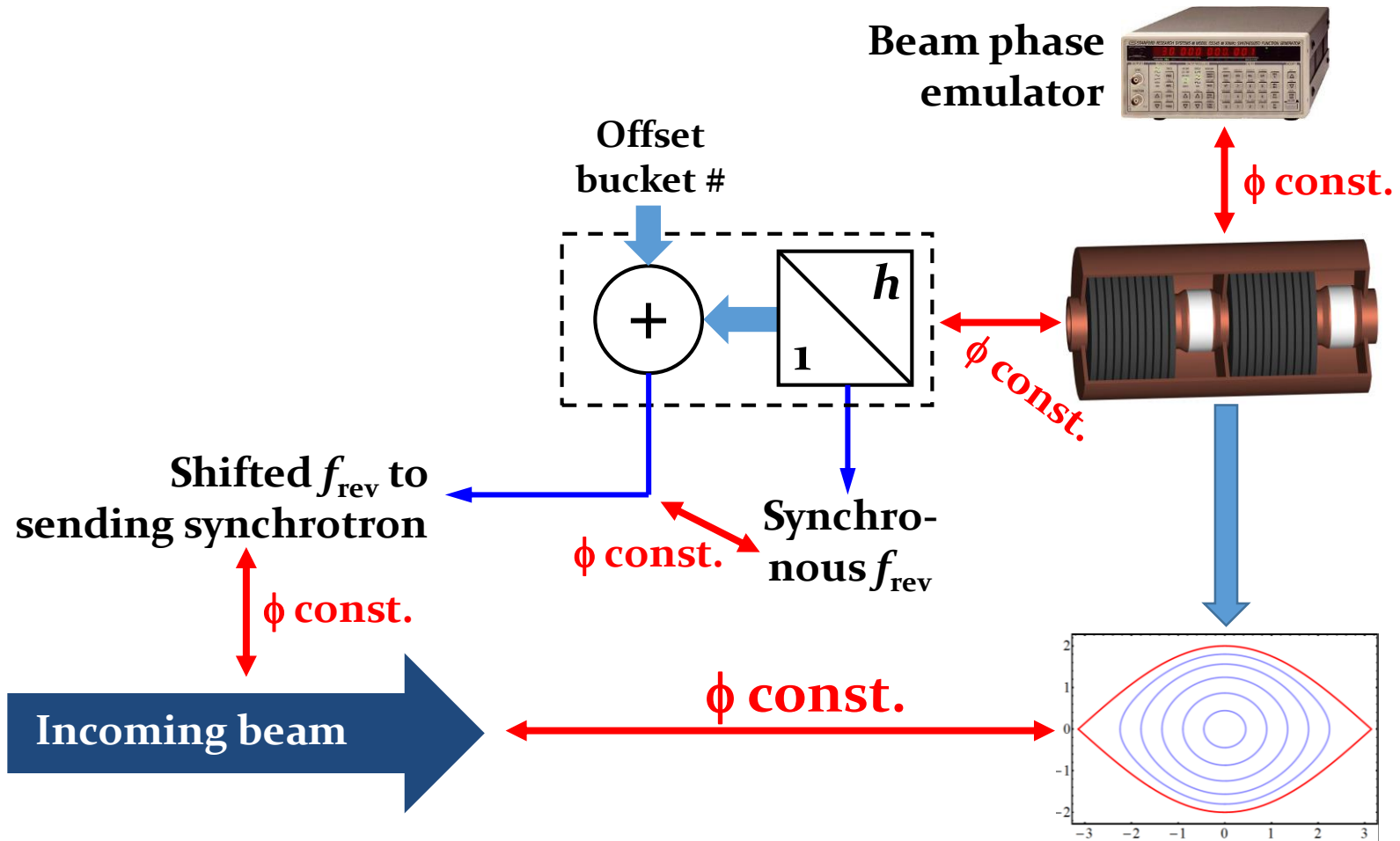
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- Before injection:
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 - **Shifted** with respect to f_{RF} and f_{rev}

Beam phase loop without beam?

→ Just replace beam by a simple RF generator!

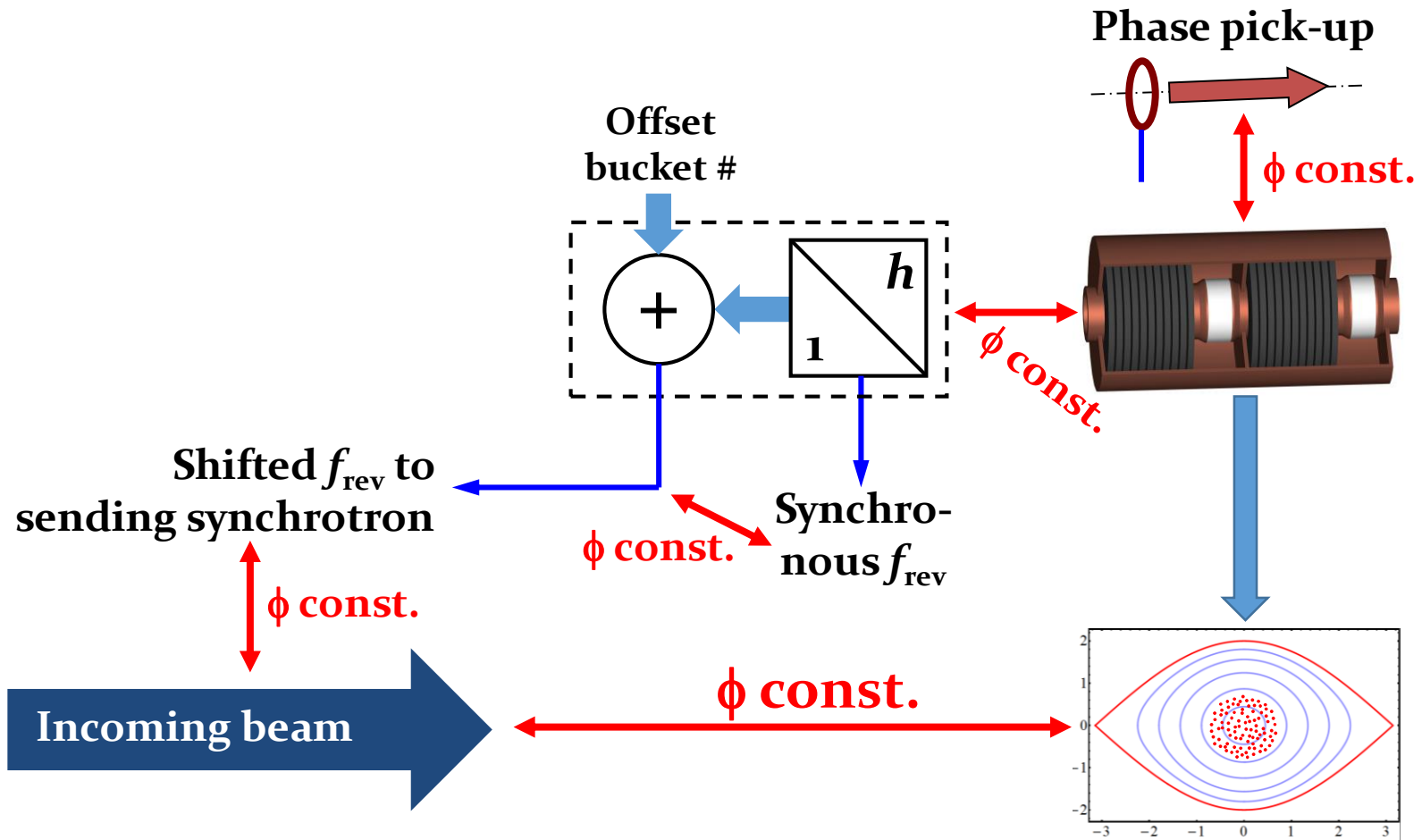


Synchronization chain for bucket counting



- **Incoming beam** has reproducible phase with respect to **RF bucket**, **synchronous f_{rev}** and beam phase emulating **generator**
→ **Straightforward switch** to beam signals, **already locked in phase**


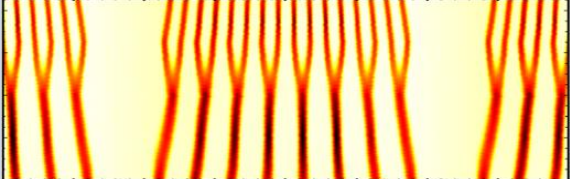
Synchronization chain for bucket counting

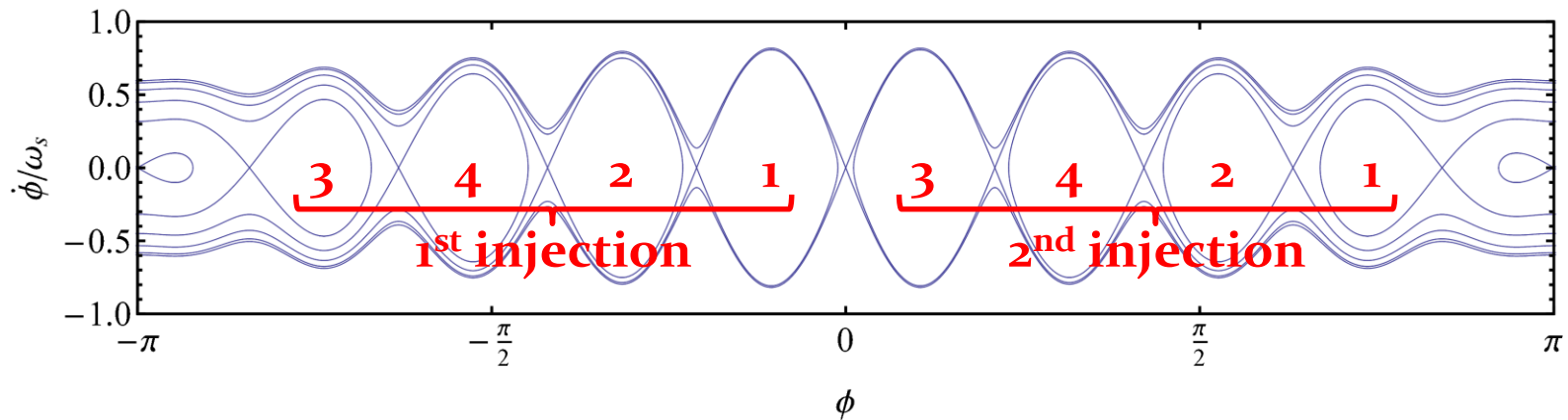


- Incoming beam has reproducible phase with respect to RF bucket, synchronous f_{rev} and beam phase emulating generator
- Straightforward switch to beam signals, already locked in phase
- Beam phase with respect to f_{rev} always known

Bucket numbering

Bucket numbering for RF manipulations

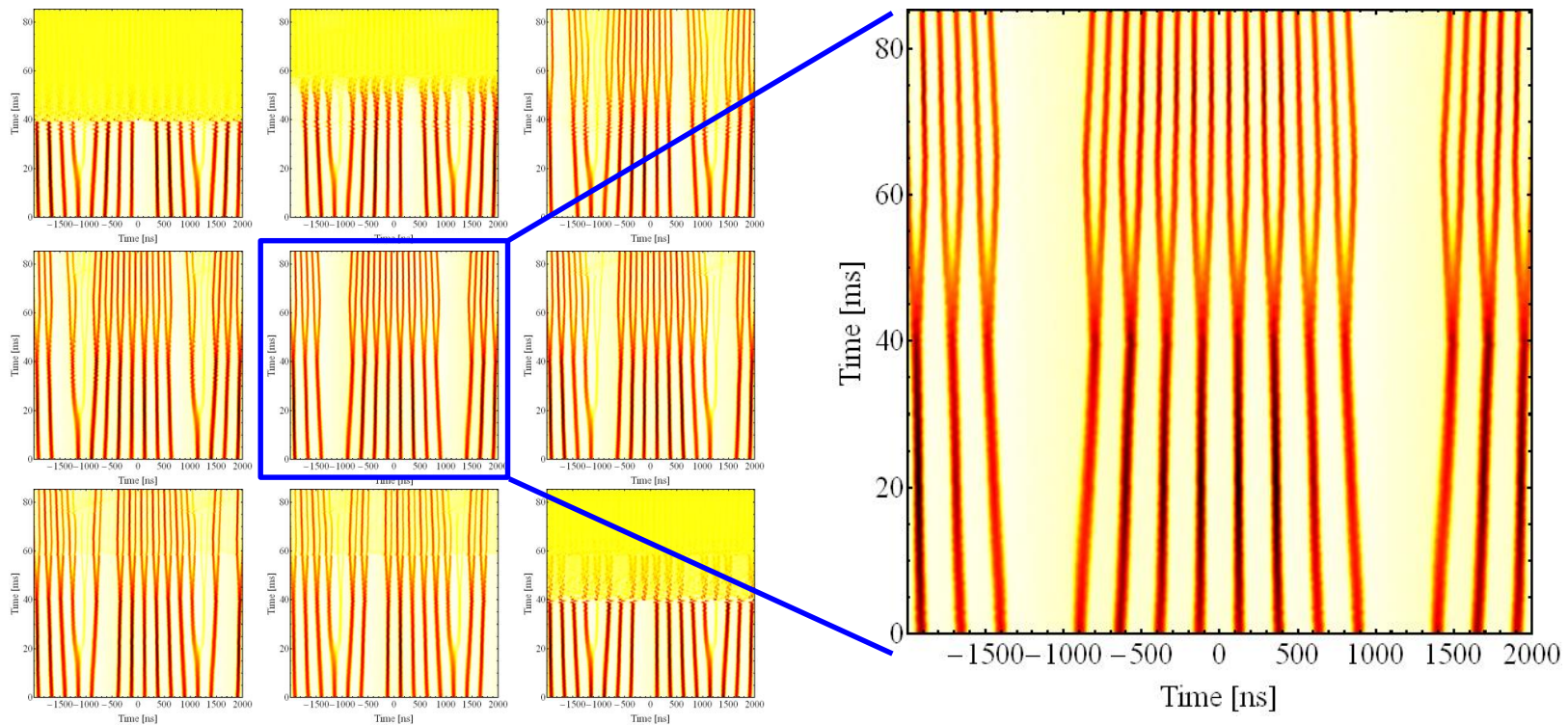
	Triple splitting	Batch compression
Injection harmonic		
Periodicity of RF manipulation	Every bucket	Only one beating along circumference
Injection bucket selection	4 buckets difference between both injections	Both injections into independently defined buckets



→ Must inject into the correct bucket numbers

Example: PS injection bucket selection

- Bunches must be placed into the correct buckets numbers
- Harmonic number change only for **even number of bunches**



→ Bucket number control during both transfers PSB → PS

→ How to handle changing number of bunches?

Intermediate summary

- **Basic techniques of signal synchronizations**
 - **Beware of dividers**
- **Beam transfer between circular lepton accelerators**
 - **Constant frequency**
 - **Predictable, independently from beam**
 - **Fundamental periodicity**
- **Beam transfer between circular hadron accelerators**
 - **Beam is reference, keep track**

Timing, Synchronization & Longitudinal Aspects

II



H. Damerou
CERN



**CAS Course on
Beam Injection, Extraction and Transfer**

13 March 2017

Outline

- Introduction
- General concepts
 - Signals with noise, transmission of RF signals
 - Phase detectors and dividers
- Beam transfer
 - Fundamental periodicity
 - Transfer between circular lepton accelerators
- **Transfer between hadron accelerators**
 - Beam phase loop, bucket numbering
 - **Transfer process: Synchronization, transfer triggers**
 - **Longitudinal matching**
- **Summary**

Synchronization and transfer

Steps of beam transfer synchronization

1.

- Set bending fields in both accelerators the to same magnetic rigidity

2.

- Synchronize sending or receiving accelerator

→ Ready for transfer

3.

- Start counting clock of fundamental periodicity
- Trigger bump and septum elements

4.

- Start counting f_{rev} clock (sending/receiving accelerator)
- Start counting bucket clock

5.

- Fine delay
- Ejection and injection kickers triggers

→ Transfer

Match bending field of both accelerator

- Same magnetic rigidity ρB of sending (1) and receiving (2) accelerators

$$F_Z = F_L \quad \rightarrow \quad \frac{p}{q} = \rho B$$

$$\rho_1 B_1 = \rho_2 B_2$$

- **No rule without exception: Particle type change at transfer**
- Proton to anti-proton conversion, e.g.,
120 GeV/c \neq 8 GeV/c (Fermilab), 26 GeV/c \neq 3.6 GeV/c (CERN),
 - Charge state change at transfer, e.g. LHC ion injector chain
Pb₅₄₊ in LEIR/PS → Pb₈₂₊ (in SPS)

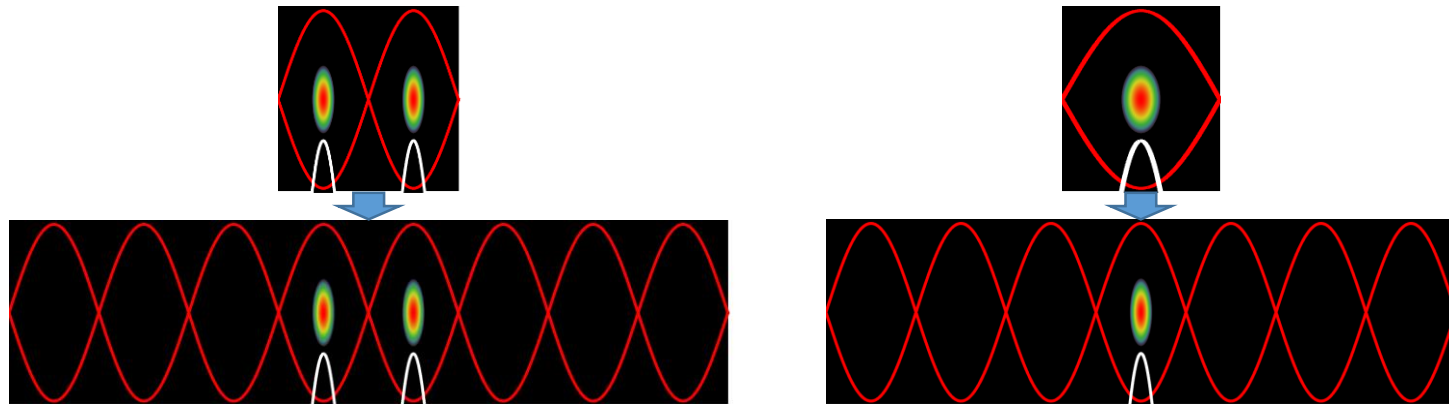
Match RF frequencies

- RF frequencies of both accelerators must have appropriate ratio assuming that the beam velocity is unchanged

$$f_{\text{rev}} = \frac{f_{\text{RF}}}{h} = \frac{\beta c}{2\pi R}$$

$$\beta c = 2\pi R_1 f_{\text{rev},1} = 2\pi R_2 f_{\text{rev},2} \rightarrow$$

$$R_1 \frac{f_{\text{RF},1}}{h_1} = R_2 \frac{f_{\text{RF},2}}{h_2}$$

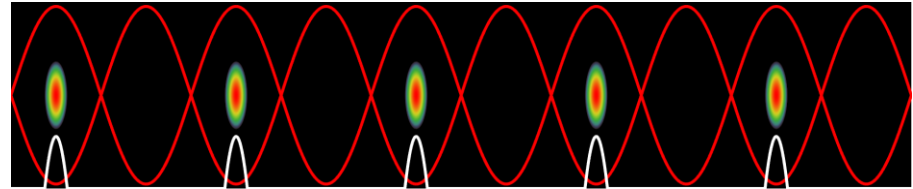


- Common choice of most circular electron accelerators $f_{\text{RF},1} = f_{\text{RF},2}$
- Harmonic number, h , proportional to circumference, $2\pi R$
- **Again no rule without exception: Production of antiprotons in target in transfer line**

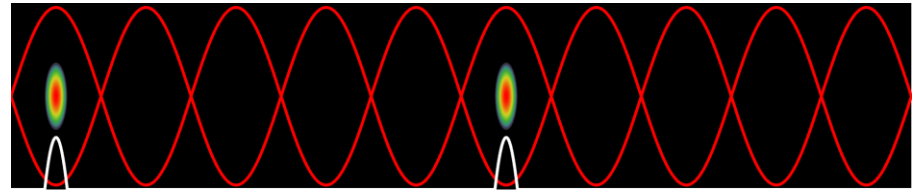
Distance between bunches

- Distance of bunches (bunch spacing, τ_{bunch}) from source accelerator must match distance of buckets

- Example: $\tau_{\text{bunch}} = 2/f_{\text{RF}}$



- Example: $\tau_{\text{bunch}} = 5/f_{\text{RF}}$



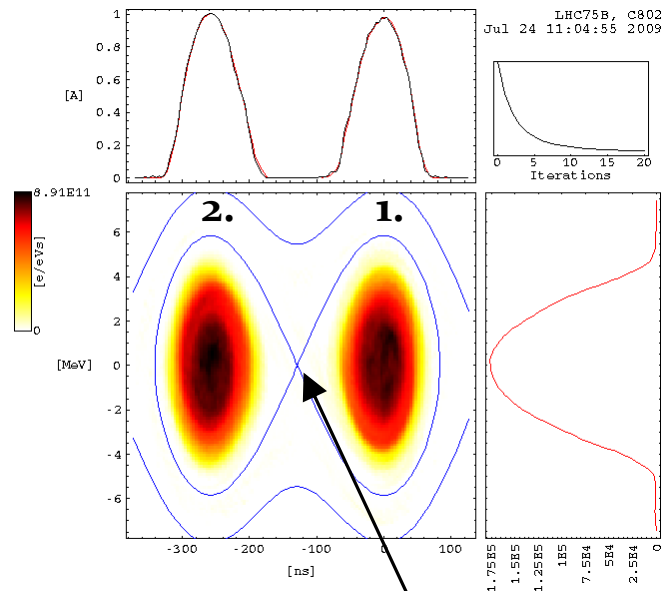
- Common case: $f_{\text{RF},2} = n \cdot f_{\text{RF},1}$
 $\rightarrow f_{\text{RF,LHC}} = 2 \cdot f_{\text{RF,SPS}}$ and $f_{\text{RF,SPS}} = 5 \cdot f_{\text{RF,PS}}$

\rightarrow **Several exceptional cases:**

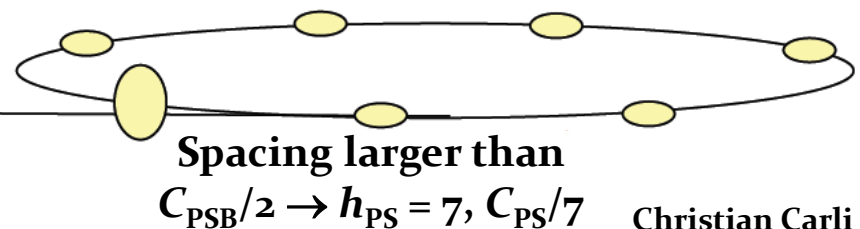
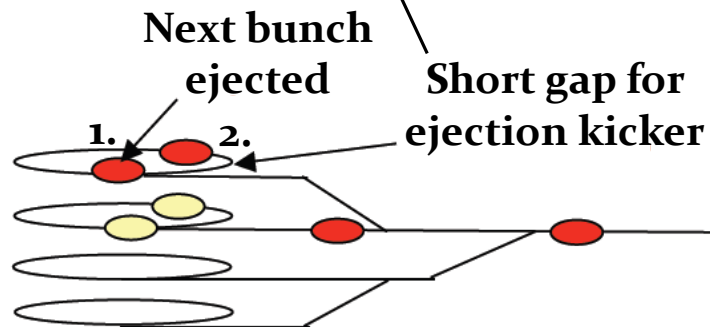
- \rightarrow No bunch distance with single bunch \rightarrow more flexibility
- \rightarrow Adjust bunch spacing using multiple RF systems

Exception: double-harmonic RF at transfer

- Was used at CERN PSB-to-PS to transfer 2 bunches at once
- Circumference ratio $C_{PS}/C_{PSB} = 4$
- Ratio virtually moved to 2/7: use $h_{RF} = 2 + 1$



1. Add h_1 component such that bunches approach to 245 ns (small spacing) → big spacing becomes **327 ns**
2. Synchronize on h_1 to the PS
3. Trigger extraction kicker in-between the small spacing
4. **Eject two bunches per ring at a distance of 327 ns**



Steps of beam transfer synchronization

1.

- Set bending fields in both accelerators to the same magnetic rigidity

2.

- **Synchronize sending or receiving accelerator**

→ Ready for transfer

3.

- Start counting clock of fundamental periodicity
- Trigger bump and septum elements

4.

- Start counting f_{rev} clock (sending/receiving accelerator)
- Start counting bucket clock

5.

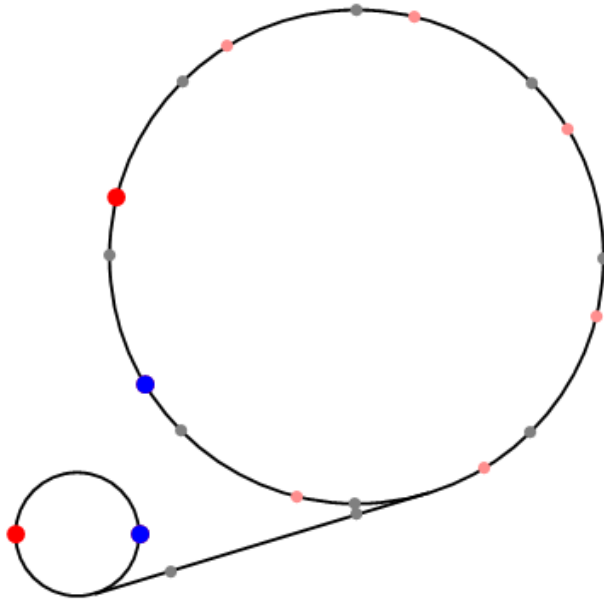
- Fine delay
- Ejection and injection kickers triggers

→ Transfer

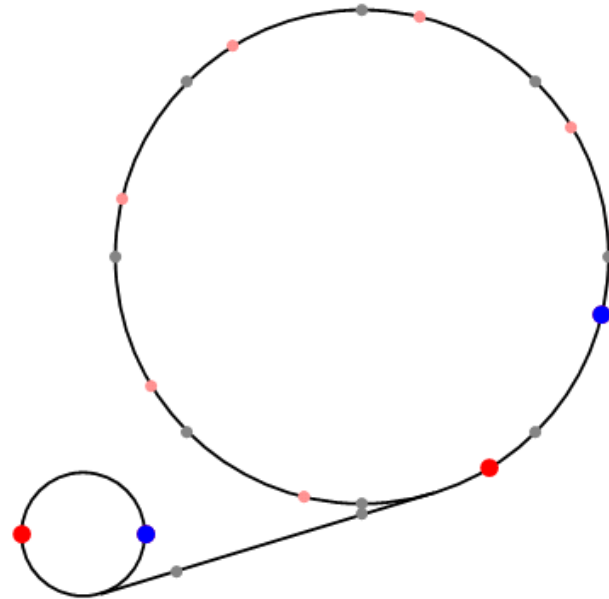
Before synchronization

- Even with magnetic rigidity matched: **revolution frequencies not at theoretical ratio due to imperfections**
→ **Bunches and buckets slip in phase**

Slippage of bunches and bucket



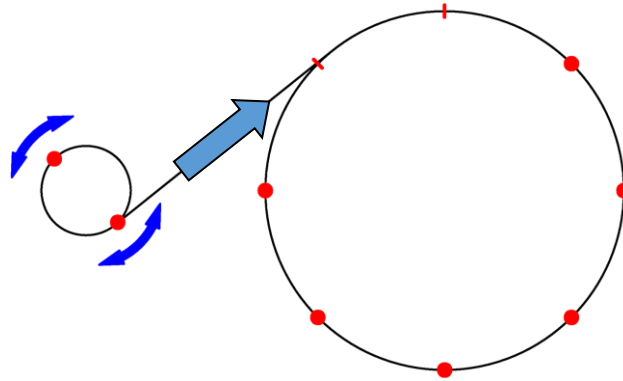
Rotation in source accelerator subtracted



But: important question left unanswered!

Who is the boss?

- Transfer beam to a downstream machine: **Bunch-to-bucket**
- 1. Protons between synchrotrons → **Synchronize accelerators**



- 2. Move **relative phase of RF together with beam** between both machines to hit the empty buckets

**Sending
accelerator is,
the boss?**



**Receiving
accelerator is
the boss?**

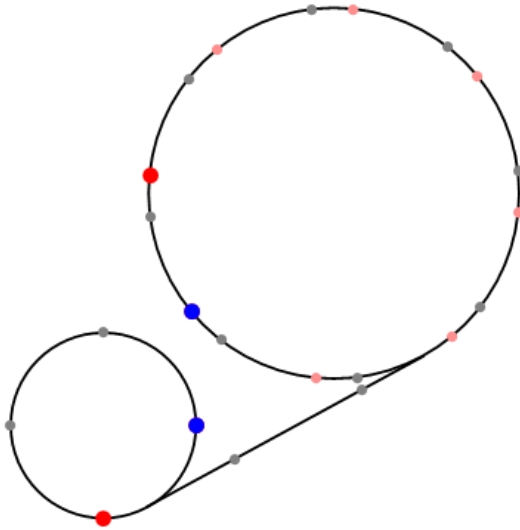
Choice of master for transfer synchronization⁶²

- **Sending accelerator is master of transfer**
 - Receiving accelerator adapts to incoming beam
 - Common choice when receiving accelerator **has no beam** before transfer
 - Interesting for only single beam transfer, e.g., protons from PS → AD for antiproton production
- **Receiving accelerator is master of transfer**
 - Sending accelerator adapts to incoming beam
 - Common choice when receiving accelerator **has already beam** before transfer (multiple injections)
 - Most common at CERN, e.g., proton injector chain PSB → PS → SPS → LHC

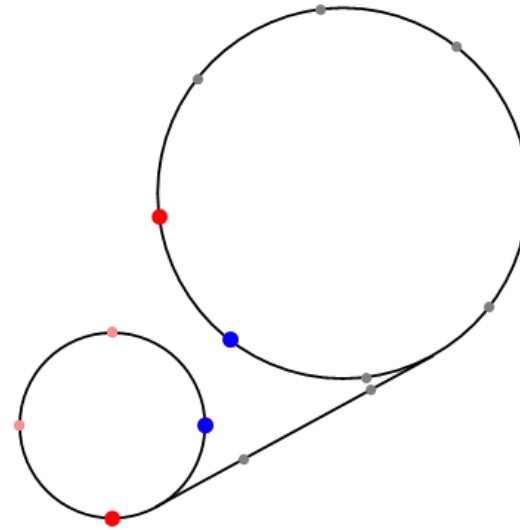
Before synchronization

- Simple test case of circumference ratio 2: $C_2 = 2C_1$

Source accelerator is
master at transfer



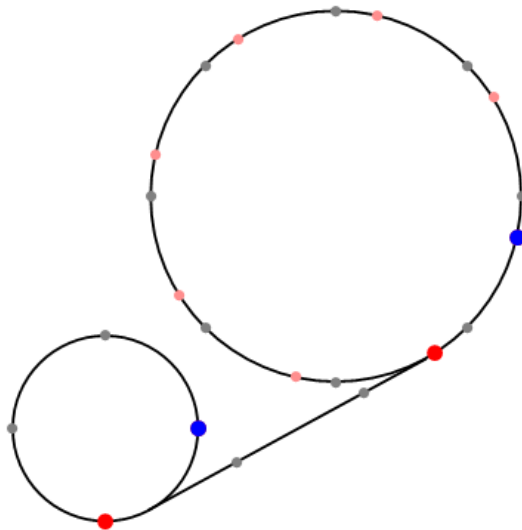
Target accelerator is
master at transfer



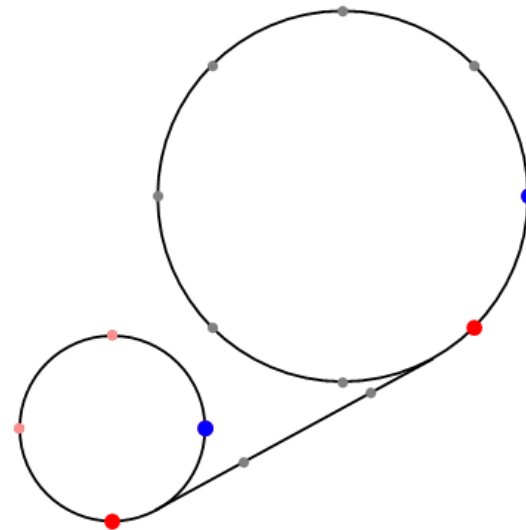
Before synchronization

- Simple test case of circumference ratio 2: $C_2 = 2C_1$

Source accelerator is
master at transfer



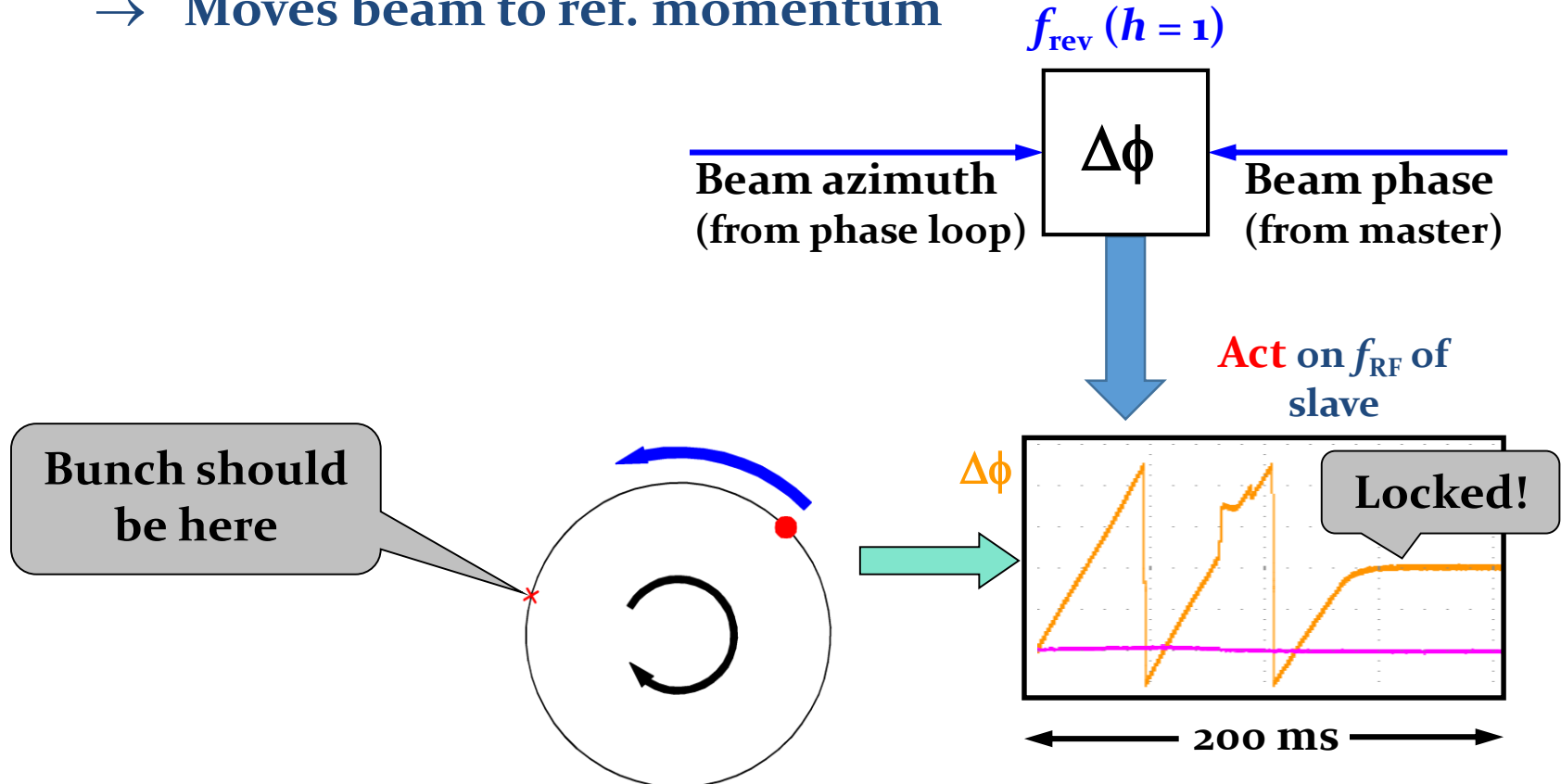
Target accelerator is
master at transfer



→ Synchronize both accelerator to force: $f_{\text{rev},1} = 2f_{\text{rev},2}$

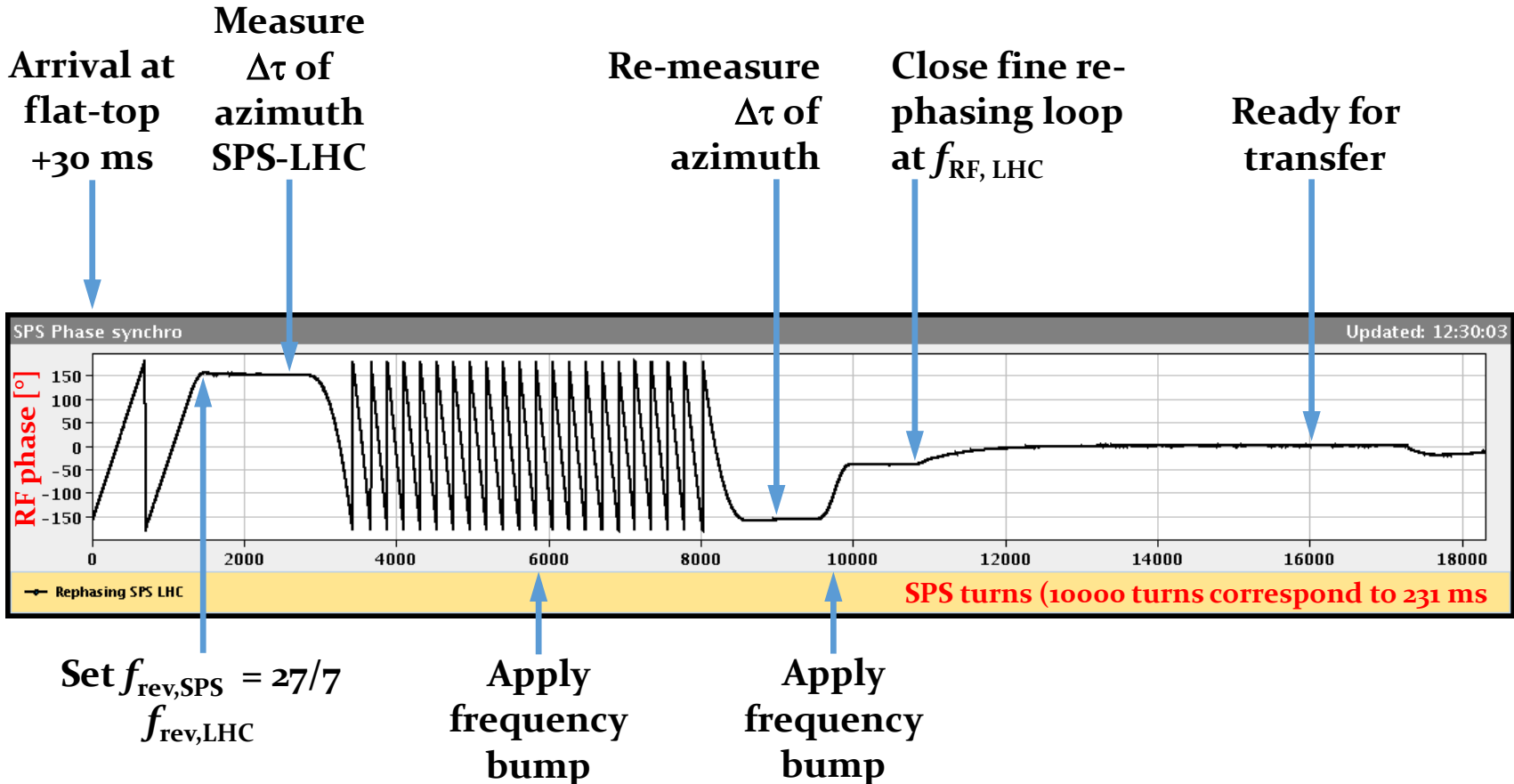
Simple synchronization process

1. Move beam to off-momentum (B const.): $\frac{df}{f} = \frac{\gamma_{tr}^2 - \gamma^2}{\gamma^2 \gamma_{tr}^2} \frac{dp}{p}$
 - Well defined frequency difference between accelerators
2. Measure azimuth error, when beam at correct azimuth
 - Close synchronization loop
 - Moves beam to ref. momentum



Example: Synchronization of SPS to LHC

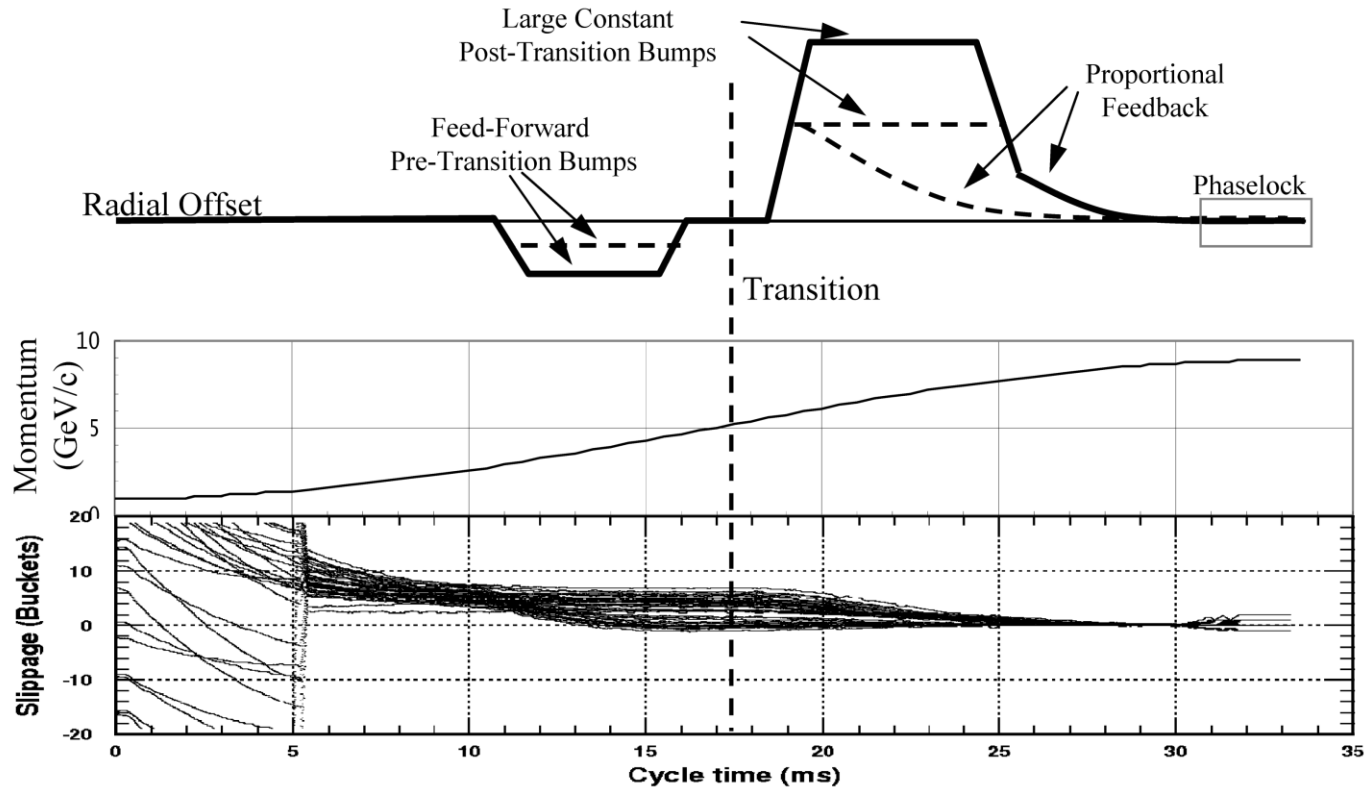
→ **LHC is master** for beam transfer from SPS



- Coarse and fine re-phasing to perfectly align bunches with respect to target buckets (400 MHz, 2.5 ns) in LHC
- Complete synchronization process **takes about 500 ms**

Example: Fast cogging of booster at FNAL

- Rapid cycling synchrotron from 400 MeV to 8 GeV
- Total **cycle length is only 25 ms** → **How to synchronize fast?**

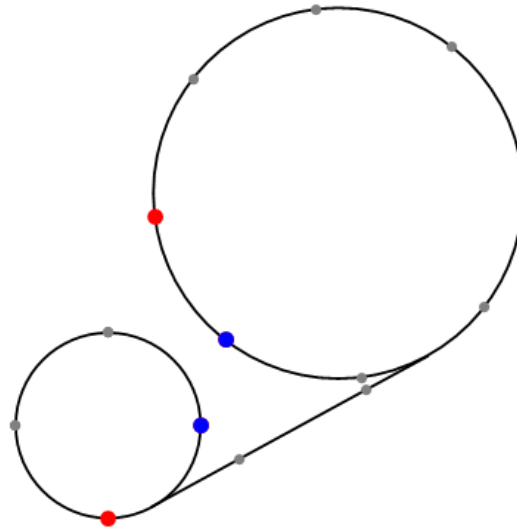


1. Measure beam phase early in the cycle and **predict azimuth at flat-top**
2. Apply **radial/frequency bumps** already during acceleration

After synchronization

- Simple test case of circumference ratio 2: $C_2 = 2C_1$

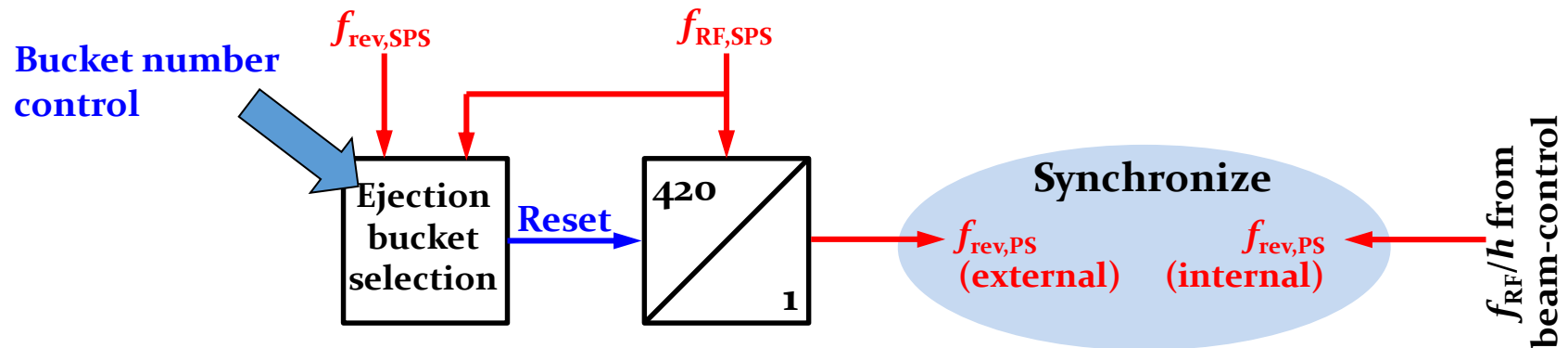
Source or target accelerator
is **master** at transfer



- Revolution frequencies coupled: $f_{\text{rev},1} = 2f_{\text{rev},2}$
- Transfer can be triggered **every turn of the target accelerator**

Example: Ejection bucket numbering in PS

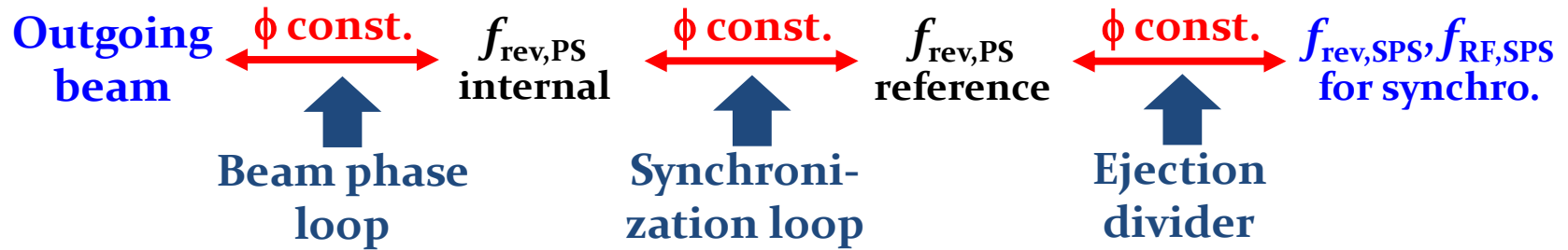
- Azimuthal position of 1st bunch ambiguous after RF manipulations
- **Number of buckets and bunches changes during acceleration**
- **But: Synchronous $f_{\text{rev,PS}}$ signal with reproducible phase to beam**
- 'Re-numbering' of buckets by shifting reference from SPS



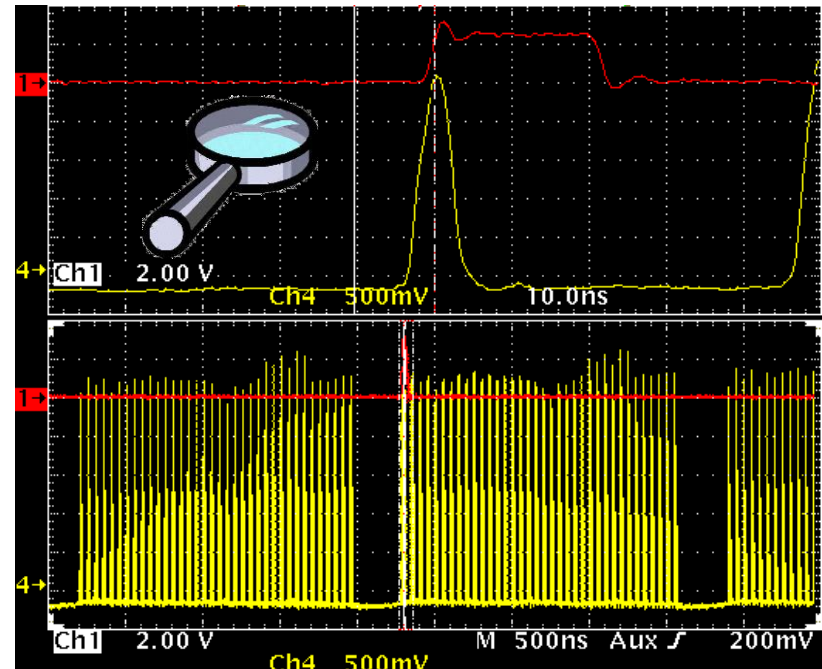
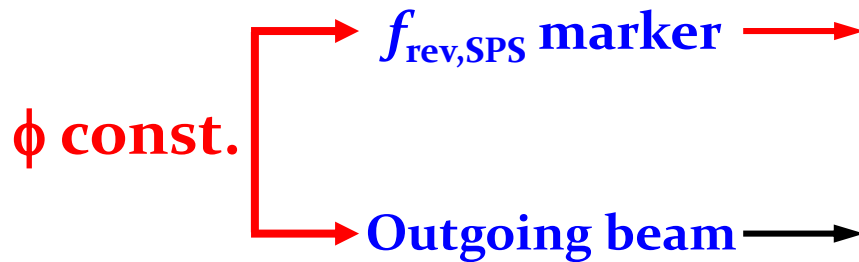
- Shift of external reference $f_{\text{rev,PS}}$ adjustable in SPS bucket units
- Synchronize external and beam synchronous $f_{\text{rev,PS}}$

Example: Ejection synchronization chain

→ Multiple 'batches' are transferred from PS to 11 times larger SPS



Last turn before PS → SPS transfer



→ Beam phase with respect to f_{rev} always **known**

Steps of beam transfer synchronization

1.

- Set bending fields in both accelerators to the same magnetic rigidity

2.

- Synchronize sending or receiving accelerator

→ Ready for transfer

3.

- Start counting clock of fundamental periodicity
- Trigger bump and septum elements

4.

- Start counting f_{rev} clock (sending/receiving accelerator)
- Start counting bucket clock

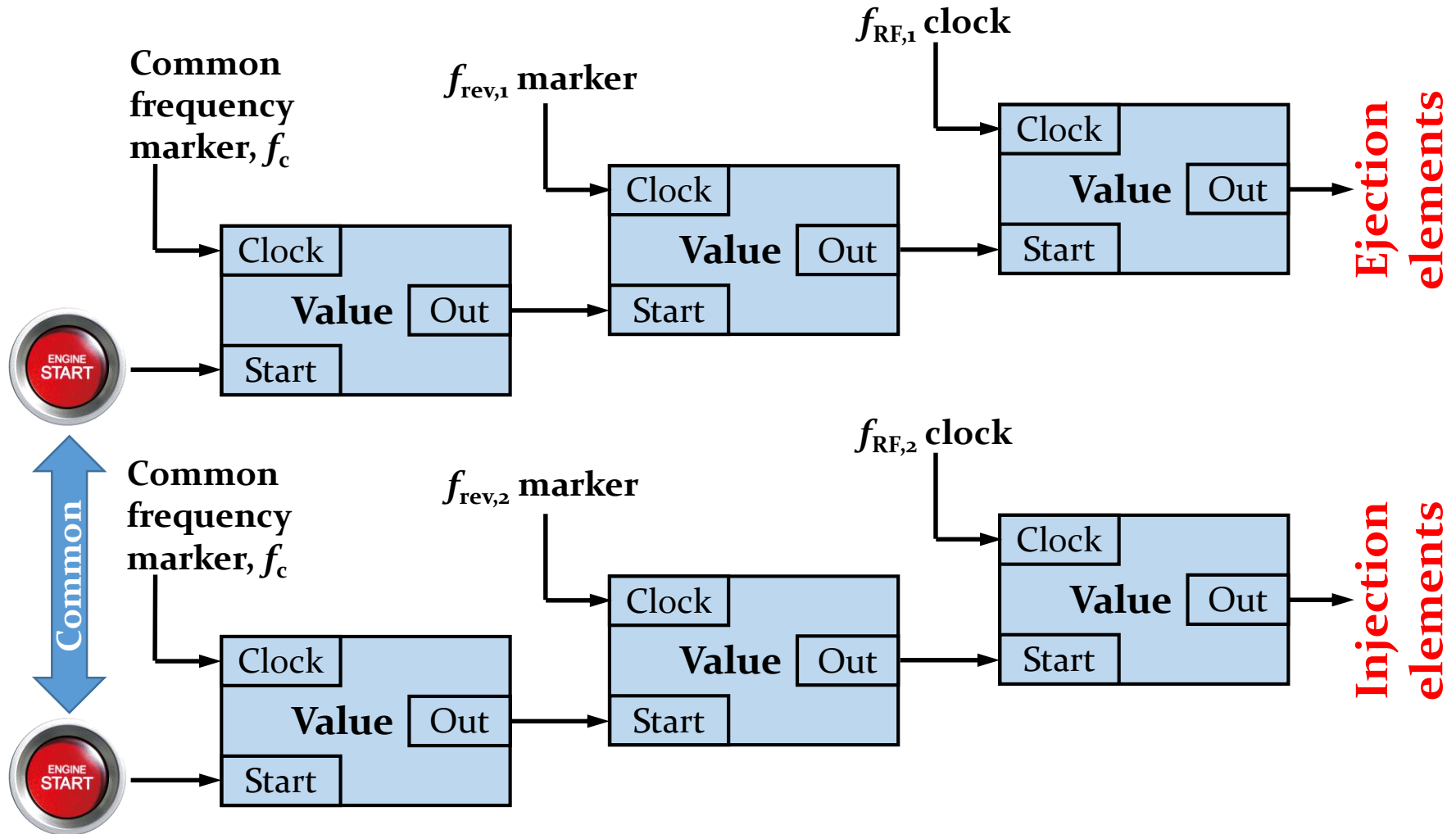
5.

- Fine delay
- Ejection and injection kickers triggers

→ Transfer

Synchronous triggers

- Cascade of trigger counters for fast transfer elements
- Very similar to transfer with lepton synchrotrons



Steps of beam transfer synchronization

1.

- Set bending fields in both accelerators to the same magnetic rigidity

2.

- Synchronize sending or receiving accelerator

→ Ready for transfer

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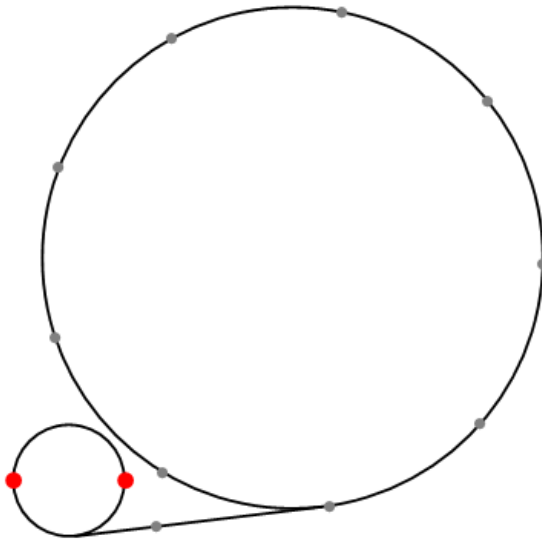
- Fine delay
- Ejection and injection kickers triggers

→ Transfer

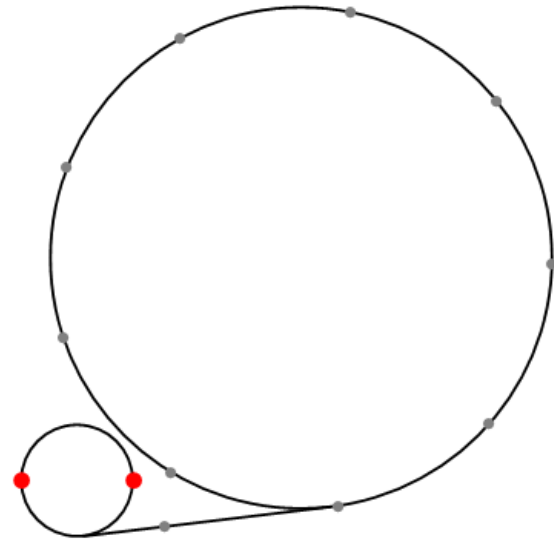
Example: Turn count control at extraction

- J-PARC rapid cycling synchrotron and main ring ratio: 4.5
- Transfer possible once every two turns of main ring
- Transfer of 4 times two bunches

Counter on f_{rev} of source
(RCS) set normally



Counter on f_{rev} of source
(RCS) **delayed by one turn**



- Beam synchronous timing can also be used to control target azimuth (bucket number) of transferred beam

Energy matching

Energy matching of incoming beam

- **Ideal beam** circulates with the expected revolution frequency ($\Delta f = 0$) on the central orbit ($\Delta R = 0$) $\rightarrow \Delta p = 0$
- **Real beam** behaviour is calculated using

Variables	Equations
B, p, R	$\frac{dp}{p} = \gamma_{\text{tr}}^2 \frac{dR}{R} + \frac{dB}{B}$
f, p, R	$\frac{dp}{p} = \gamma^2 \frac{df}{f} + \gamma^2 \frac{dR}{R}$
B, f, p	$\frac{dB}{B} = \gamma_{\text{tr}}^2 \frac{df}{f} + \frac{\gamma^2 - \gamma_{\text{tr}}^2}{\gamma^2} \frac{dp}{p}$
B, f, R	$\frac{dB}{B} = \gamma^2 \frac{df}{f} + (\gamma^2 - \gamma_{\text{tr}}^2) \frac{dR}{R}$

Energy matching of incoming beam

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- **Real beam** behaviour is calculated using

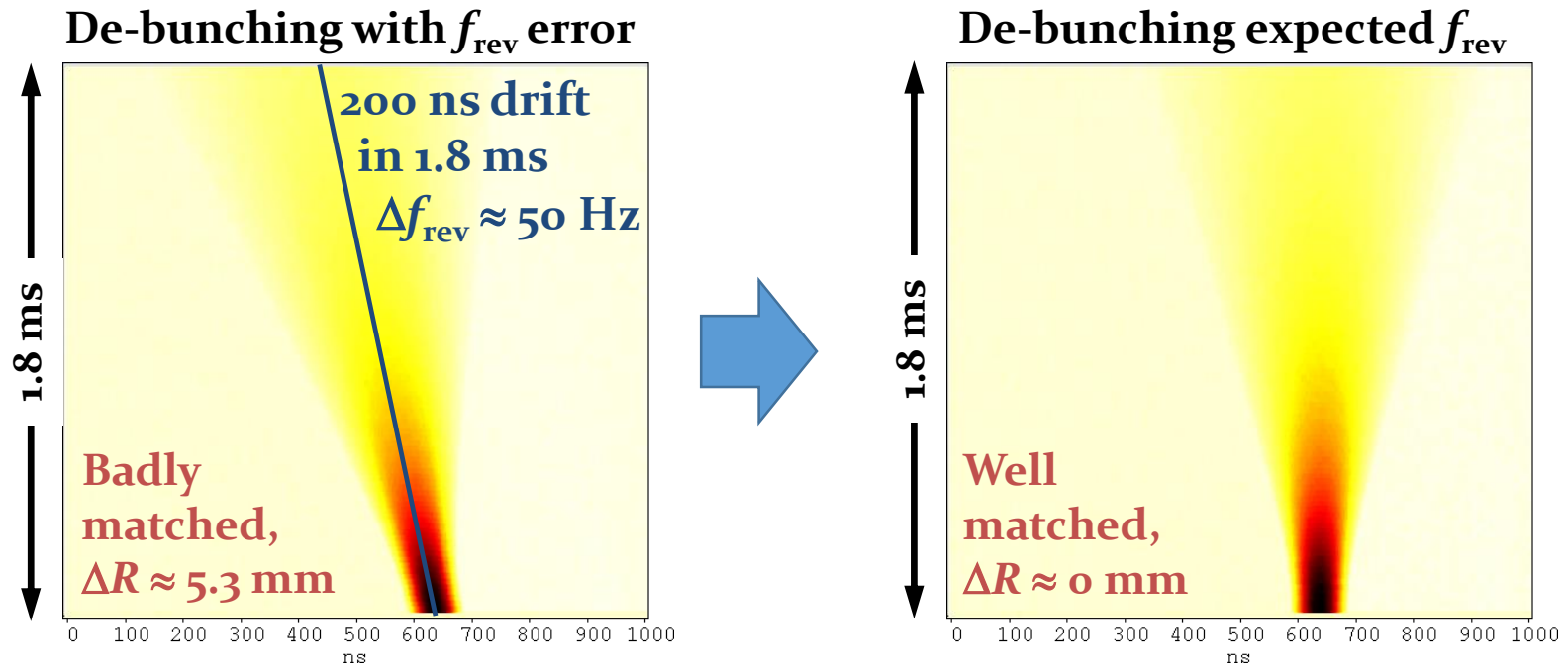
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B, f, p	$\frac{dB}{B} = \gamma_{\text{tr}}^2 \frac{df}{f} + \frac{\gamma^2 - \gamma_{\text{tr}}^2}{\gamma^2} \frac{dp}{p}$
B, f, R	$\frac{dB}{B} = \gamma^2 \frac{df}{f} + (\gamma^2 - \gamma_{\text{tr}}^2) \frac{dR}{R}$

Choice of **two** parameters from B, p, R, f **directly** constrains all others

\rightarrow Example: at **fixed** magnetic field ($\Delta B = 0$), revolution frequency and radial position are directly linked

Energy matching without RF

- Observe de-bunching (no RF) with periodic trigger at $n \cdot f_{\text{rev}}$
 → Does the beam circulate with the expected f_{rev} ?
 at the central orbit?



- Changing B alone insufficient, since f_{rev} and R linked (const. p)
 → Change two parameters to fix the others, e.g., B and p or B and f
 → All parameters are constrained

Longitudinal matching equations

Recap of longitudinal beam dynamics (1)

For a single harmonic RF system

$$\eta = \frac{1}{\gamma^2} - \frac{1}{\gamma_{tr}^2}$$

$$H\left(\phi, \frac{\Delta E}{\omega_{rev}}\right) = -\frac{1}{2} \frac{h\eta\omega_{rev}}{pR} \left(\frac{\Delta E}{\omega_{rev}}\right)^2 + \frac{qV}{2\pi} [\cos\phi - \cos\phi_0 + (\phi - \phi_0) \sin\phi_0]$$

with $\phi = \phi_0 + \Delta\phi$ it becomes

$$H\left(\Delta\phi, \frac{\Delta E}{\omega_{rev}}\right) = -\frac{1}{2} \frac{h\eta\omega_{rev}}{pR} \left(\frac{\Delta E}{\omega_{rev}}\right)^2 + \frac{qV}{2\pi} [\cos(\phi_0 + \Delta\phi) - \cos\phi_0 + \Delta\phi \sin\phi_0]$$

using $\cos(\phi_0 + \Delta\phi) = \cos\phi_0 \cos\Delta\phi - \sin\phi_0 \sin\Delta\phi$

$$\simeq \cos\phi_0 \left(1 - \frac{1}{2}\Delta\phi^2\right) - \sin\phi_0 \Delta\phi$$

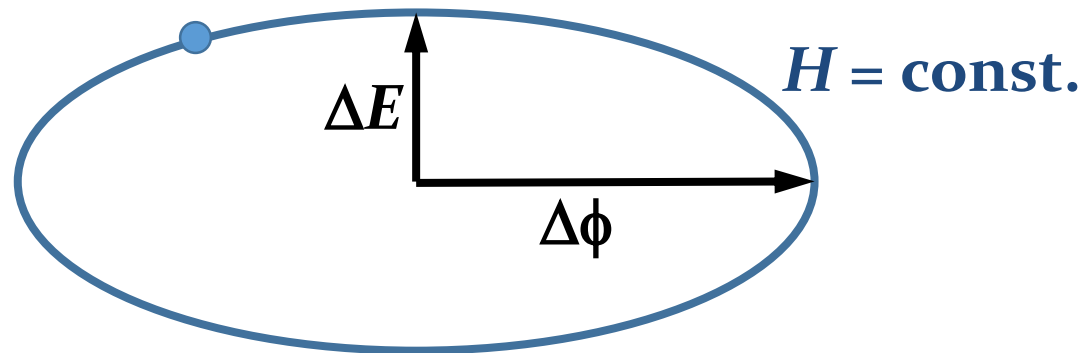
The Hamiltonian simplifies to

$$H\left(\Delta\phi, \frac{\Delta E}{\omega_{rev}}\right) \simeq -\frac{1}{2} \frac{h\eta\omega_{rev}}{pR} \left(\frac{\Delta E}{\omega_{rev}}\right)^2 - \frac{1}{2} \frac{qV}{2\pi} \Delta\phi^2 \cos\phi_0$$

Recap of longitudinal beam dynamics (2)

$$H \left(\Delta\phi, \frac{\Delta E}{\omega_{\text{rev}}} \right) \simeq -\frac{1}{2} \frac{h\eta\omega_{\text{rev}}}{pR} \left(\frac{\Delta E}{\omega_{\text{rev}}} \right)^2 - \frac{1}{2} \frac{qV}{2\pi} \Delta\phi^2 \cos\phi_0$$

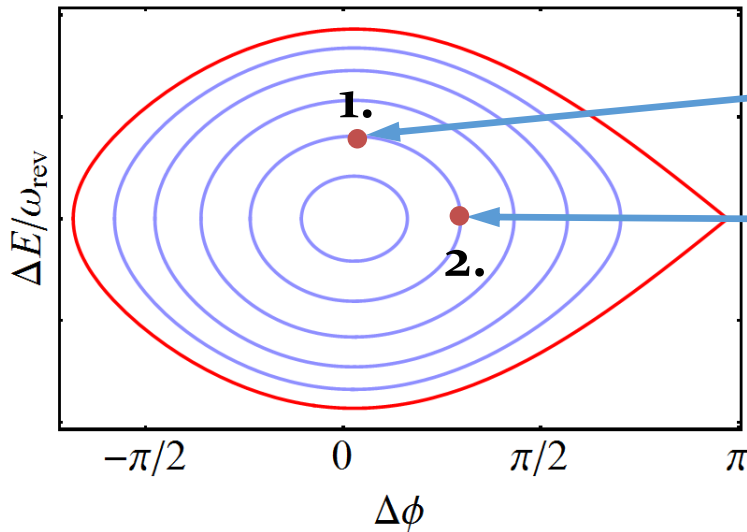
- In the centre of the bucket, particles move on elliptical trajectories in $\Delta\phi$ - ΔE phase space
- Hamiltonian is constant on these trajectories



→ Aspect ratio of the elliptical trajectories must be identical in sending and receiving accelerator

Physical aspect ratio of bucket trajectories (1)⁸²

- Compare two particles on the same trajectory
 1. No phase deviation
 2. No energy deviation



$$H \left(\Delta\phi = 0, \frac{\Delta E}{\omega_{\text{rev}}} \right) = -\frac{1}{2} \frac{h\eta\omega_{\text{rev}}}{pR} \left(\frac{\Delta E}{\omega_{\text{rev}}} \right)^2$$

$$H \left(\Delta\phi, \frac{\Delta E}{\omega_{\text{rev}}} = 0 \right) = -\frac{1}{2} \frac{qV}{2\pi} \Delta\phi^2 \cos \phi_0$$

→ $\Delta\phi$ depends on frequency → use physical duration $\Delta\tau$ instead

$$\Delta\phi = 2\pi f_{\text{RF}} \Delta\tau = h\omega_{\text{rev}} \Delta\tau$$

→ Also replacing $pR = \frac{E\beta^2}{\omega_{\text{rev}}}$

Physical aspect ratio of bucket trajectories (2)⁸³

→ Hamiltonian equal for both extreme particles, hence

$$-\frac{1}{2} \frac{h\eta\omega_{\text{rev}}^2}{E\beta^2} \left(\frac{\Delta E}{\omega_{\text{rev}}} \right)^2 = -\frac{1}{2} \frac{qV}{2\pi} h^2 \omega_{\text{rev}}^2 \Delta\tau^2 \cos \phi_0$$

which can be simplified to

$$\left(\frac{\Delta E}{\Delta\tau} \right)^2 = \frac{qV}{2\pi} E\beta^2 h\omega_{\text{rev}}^2 \frac{\cos \phi_0}{\eta}$$

→ This aspect ratio $\Delta E/\Delta\tau$ must remain unchanged at transfer

Matched bunch-to-bucket transfer

→ Equating $\left(\frac{\Delta E}{\Delta \tau}\right)^2 = \frac{qV}{2\pi} E \beta^2 h \omega_{\text{rev}}^2 \frac{\cos \phi_0}{\eta}$ for sending (1) and receiving (2) accelerator gives a **general** matching condition

$$q_1 V_1 E_1 \beta_1^2 h_1 \omega_{\text{rev},1}^2 \frac{\cos \phi_{0,1}}{\eta_1} = q_2 V_2 E_2 \beta_2^2 h_2 \omega_{\text{rev},2}^2 \frac{\cos \phi_{0,2}}{\eta_2}$$

→ For most cases (fixed energy and no particle type change)

$$q_1 = q_2 \quad \beta_1 = \beta_2 \quad E_1 = E_2 \quad \cos \phi_{0,1} = \cos \phi_{0,2} = 1$$

It simplifies to the **voltage ratio between RF systems**:

$$\frac{V_1}{V_2} = \left(\frac{R_1}{R_2}\right)^2 \left| \frac{\eta_1}{\eta_2} \right| \frac{h_2}{h_1}$$

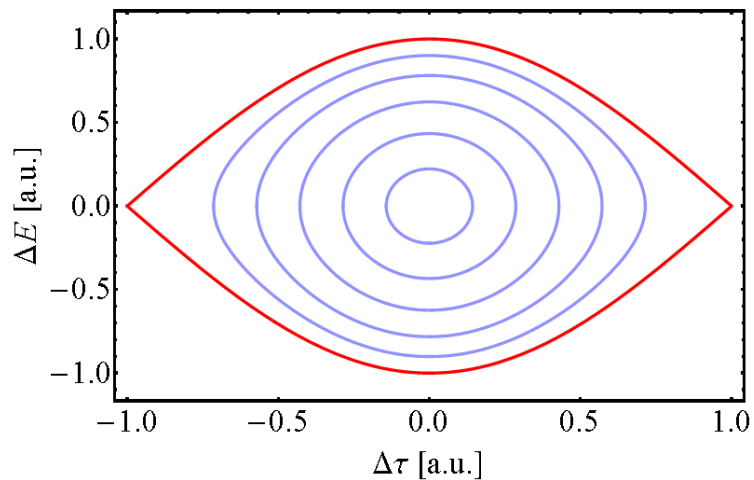
Simple matched transfer example

- Transfer between two accelerators with $f_{RF,2} = f_{RF,1}/2$

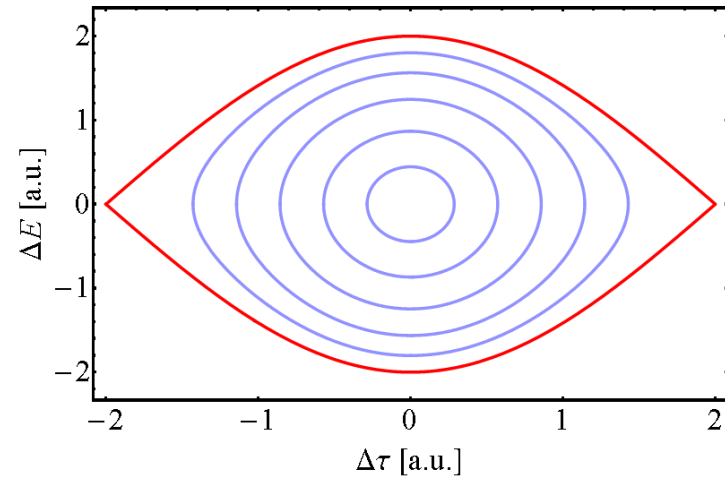
→ Phase space aspect ratio:

$$\Delta E = \beta \omega_{\text{rev}} \sqrt{\frac{qV}{2\pi} E h \left| \frac{\cos \phi_0}{\eta} \right|} \cdot \Delta \tau$$

Source (1) bucket



Target (2) bucket

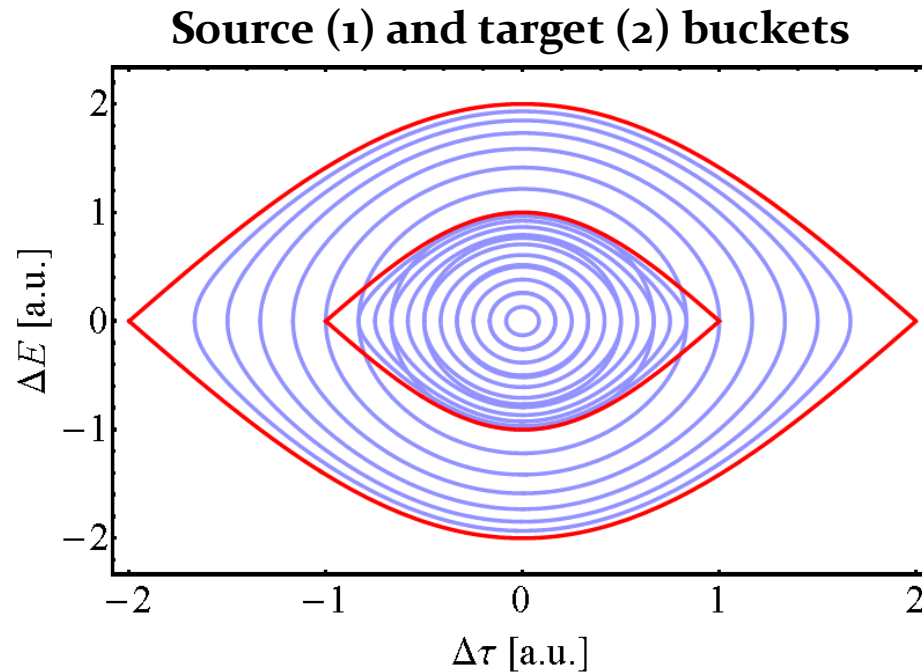


Simple matched transfer example

- Transfer between two accelerators with $f_{RF,2} = f_{RF,1}/2$

→ Phase space aspect ratio:

$$\Delta E = \beta \omega_{\text{rev}} \sqrt{\frac{qV}{2\pi} E h \left| \frac{\cos \phi_0}{\eta} \right|} \cdot \Delta \tau$$



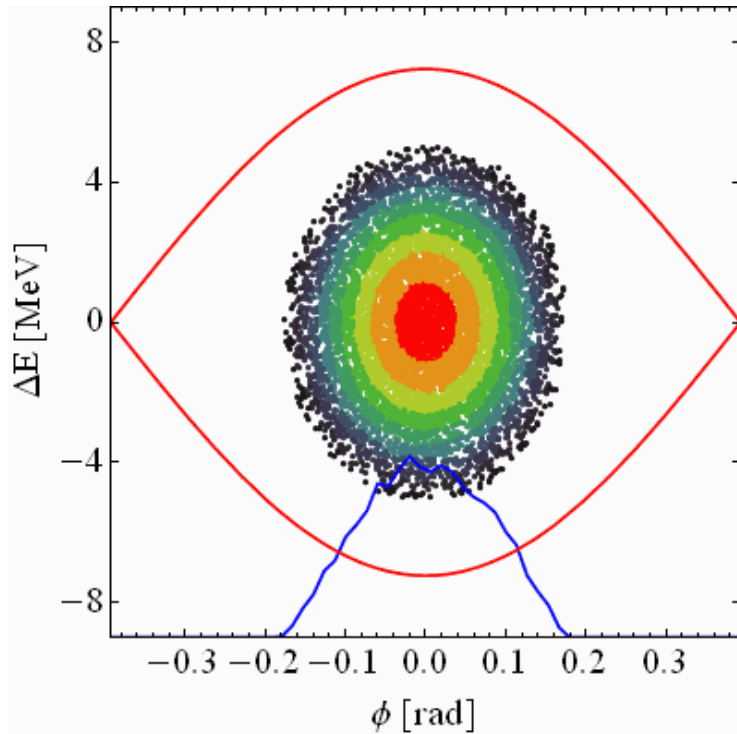
→ Obvious case of matched bunch-to-bucket transfer

Longitudinal matching

Longitudinal matching at injection

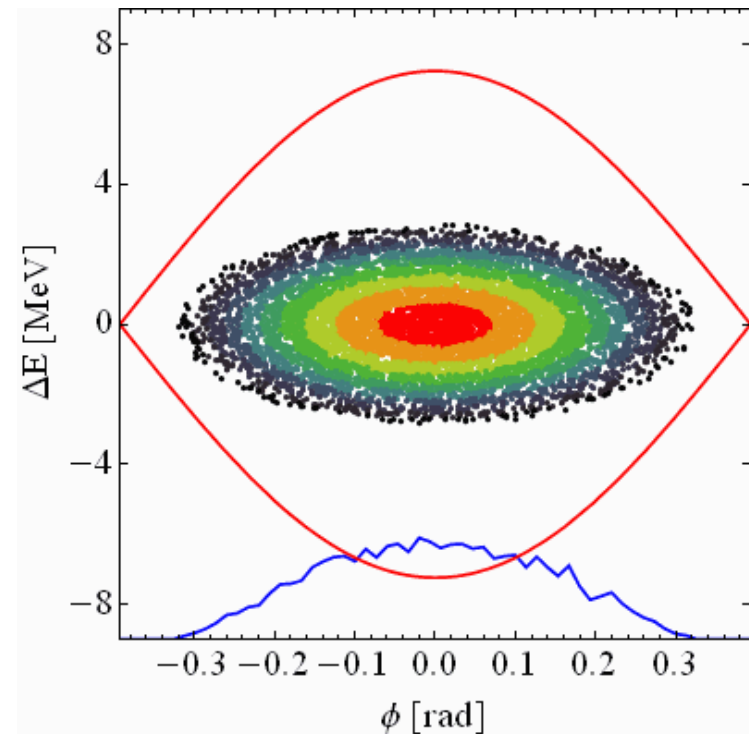
- Long. emittance is only preserved for **correct RF voltage**

Matched case



→ Bunch is fine,
longitudinal emittance
remains constant

Longitudinal mismatch

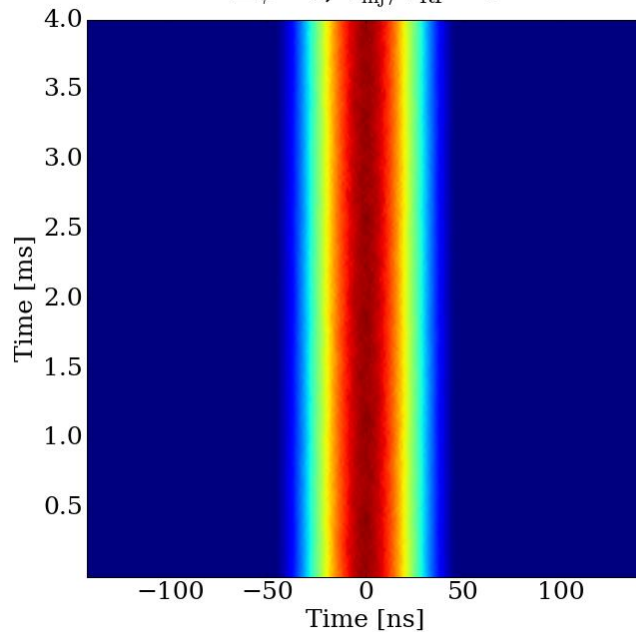


→ Dilution of bunch results
in increase of long.
emittance

Longitudinal matching

Matched case

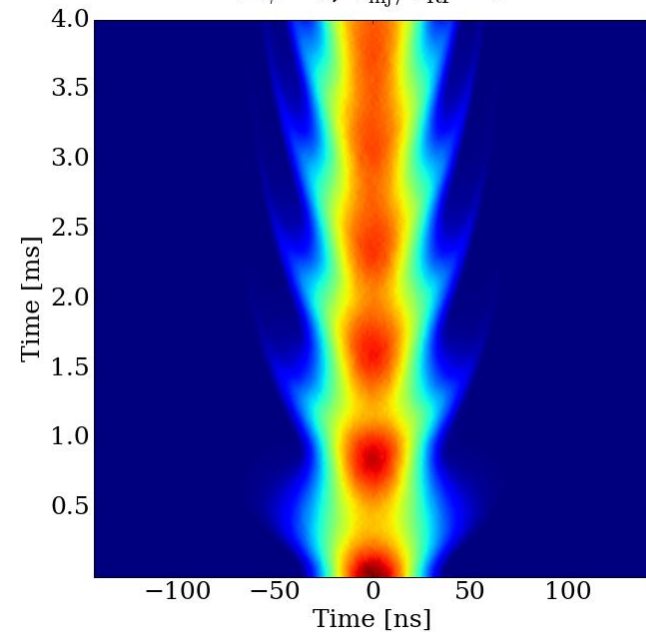
$$\Delta\phi = 0, V_{\text{inj}}/V_{\text{RF}} = 1$$



→ Bunch is fine,
longitudinal emittance
remains constant

Longitudinal mismatch

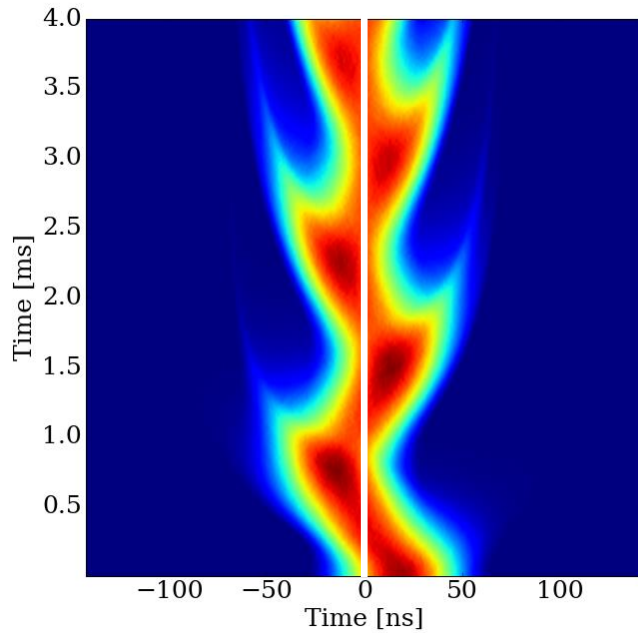
$$\Delta\phi = 0, V_{\text{inj}}/V_{\text{RF}} = 2$$



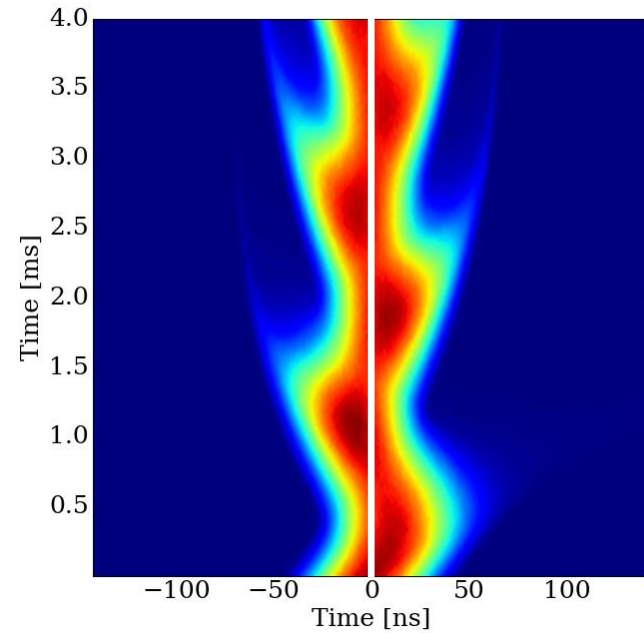
→ Dilution of bunch results
in increase of long.
emittance

Matching of phase and energy

- What is the difference?



- -45° phase error at injection
- Can be easily corrected by bucket phase

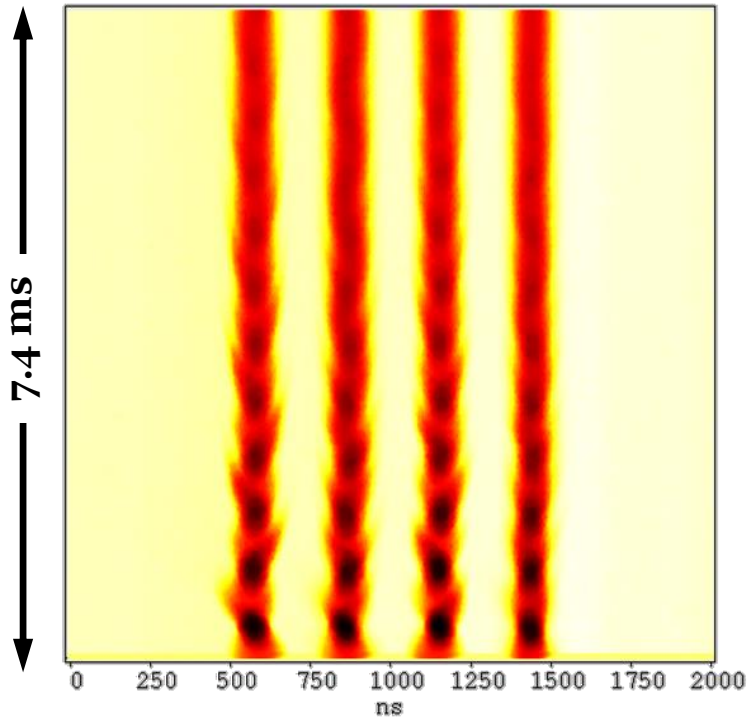


- Equivalent energy error
- Phase does not help: requires beam energy change

Example: mismatch at injection to PS

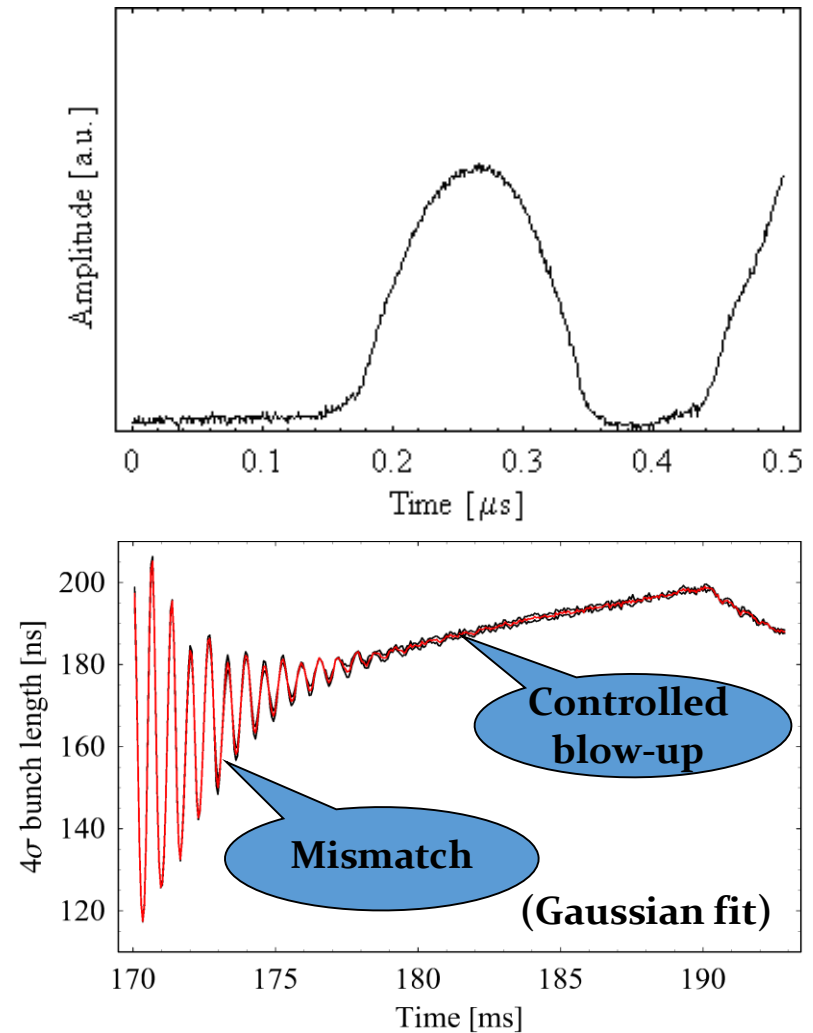
- Deliberate longitudinal mismatch at injection for blow-up

Mountain range



→ Intentional mismatch contributes to controlled longitudinal blow-up

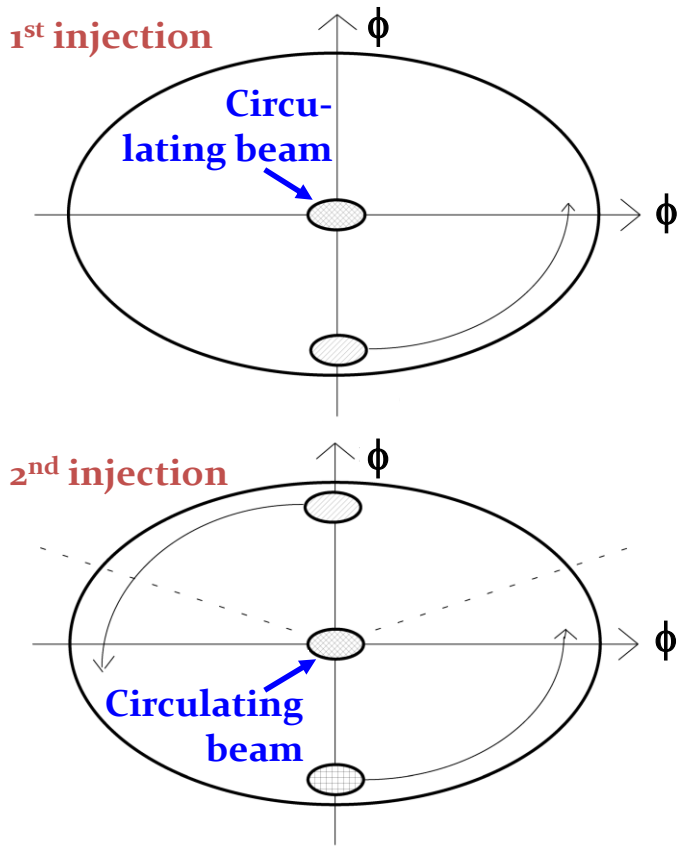
Bunch length evolution



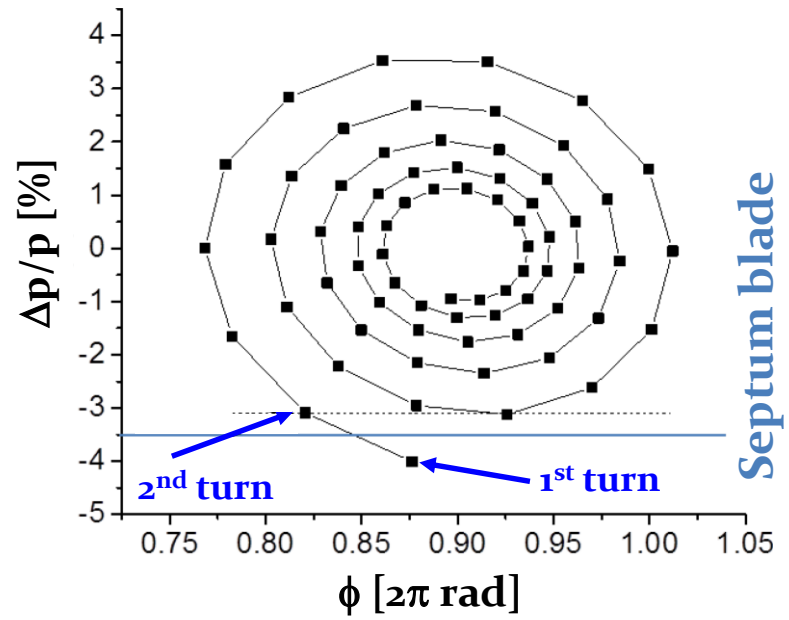
No problem with electron accelerators

- Synchrotron radiation damping matches bunches by itself
- Phase and energy oscillations decay

LEP synchrotron injection



Proposed FCC-ee injection



→ Mismatched injection can be a useful tool

Summary

- **Basic techniques of signal synchronizations**
 - **Beware of dividers**
- **Beam transfer between circular lepton accelerators**
 - **Constant frequency**
- **Beam transfer between circular hadron accelerators**
 - **Variable frequency**
 - **Moving target**
- **Follow the beam**
 - **No need to measure → keep track**
 - **Matching between accelerators**

A big Thank You

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Normalized Hamiltonian representation

- **For a single harmonic RF system**

$$H(\phi, \dot{\phi}) = \frac{1}{2} \dot{\phi}^2 + \frac{\omega_s^2}{\cos \phi_0} [\cos \phi_0 - \cos \phi + (\phi - \phi_0) \sin \phi_0]$$

with $\phi = \phi_0 + \Delta\phi$ **it becomes**

$$H(\Delta\phi, \dot{\phi}) = \frac{1}{2} \dot{\phi}^2 + \frac{\omega_s^2}{\cos \phi_0} [\cos \phi_0 - \cos(\phi_0 + \Delta\phi) - \Delta\phi \sin \phi_0]$$

using $\cos(\phi_0 + \Delta\phi) = \cos \phi_0 \cos \Delta\phi - \sin \phi_0 \sin \Delta\phi$

$$\simeq \cos \phi_0 \left(1 - \frac{1}{2} \Delta\phi^2 \right) - \sin \phi_0 \Delta\phi$$

this simplifies to $H(\Delta\phi, \dot{\phi}) \simeq \frac{1}{2} \dot{\phi}^2 + \frac{1}{2} \omega_s^2 \Delta\phi^2$