TRANSFER LINES – PAPER STUDIES

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Outline



General beam transport

...moving from s_1 to s_2 through *n* elements, each with transfer matrix M_i



[1] B. Goddard, CAS (2004), URL http://cas.web.cern.ch/cas/Baden/PDF/transfer.pdf

Circular Machine



ne turn
$$\mathsf{M}_{1\to 2} = \mathsf{M}_{0\to L} = \begin{bmatrix} \cos 2\pi Q + \alpha \sin 2\pi Q & \beta \sin 2\pi Q \\ -\frac{1}{\beta} (1 + \alpha^2) \sin 2\pi Q & \cos 2\pi Q - \alpha \sin 2\pi Q \\ -\frac{1}{\beta} (1 + \alpha^2) \sin 2\pi Q & \cos 2\pi Q - \alpha \sin 2\pi Q \end{bmatrix}$$

• The solution is *periodic*

 \cap

- Periodicity condition for one turn (closed ring) imposes $\alpha_1 = \alpha_2$, $\beta_1 = \beta_2$, $D_1 = D_2$
- This condition *uniquely* determines $\alpha(s)$, $\beta(s)$, $\mu(s)$, D(s) around the whole ring

Circular Machine

- Periodicity of the structure leads to regular motion
 - Map single particle coordinates on each turn at any location
 - Describes an ellipse in phase space, defined by one set of a and b values \Rightarrow Matched Ellipse (for this location)



$$a = \gamma \cdot x^2 + 2\alpha \cdot x \cdot x' + \beta \cdot x'^2$$

$$\gamma = \frac{1 + \alpha^2}{\beta}$$

Circular Machine

 For a location with matched ellipse (a, b), an injected beam of emittance e, characterised by a different ellipse (a^{*}, b^{*}) generates (via filamentation) a large ellipse <u>with the original a, b, but larger e</u>



Transfer line Single pass: $\begin{vmatrix} x_2 \\ \vdots \\ x_2 \end{vmatrix} = \mathbf{M}_{1 \to 2} \cdot \begin{vmatrix} x \\ x \end{vmatrix}$ $\mathbf{M}_{1\to2} = \begin{vmatrix} \sqrt{\beta_2} / \beta_1 (\cos \Delta \mu + \alpha_1 \sin \Delta \mu) & \sqrt{\beta_1 \beta_2} \sin \Delta \mu \\ \sqrt{\beta_1 \beta_2} [(\alpha_1 - \alpha_2) \cos \Delta \mu - (1 + \alpha_1 \alpha_2) \sin \Delta \mu] & \sqrt{\beta_1 / \beta_2} (\cos \Delta \mu - \alpha_2 \sin \Delta \mu) \end{vmatrix}$

- No periodic condition exists
- The Twiss parameters are simply propagated from beginning to end of line
- At any point in line, $\alpha(s) \beta(s)$ are functions of $\alpha_1 \beta_1$

Transfer line

- On a single pass there is no regular motion
 - Map single particle coordinates at entrance and exit.
 - <u>Infinite number of equally valid possible starting ellipses for single particle</u>transported to infinite number of final ellipses...



Transfer Line

• The optics functions in the line depend on the initial values



- Same considerations are true for Dispersion function:
 - Dispersion in ring defined by periodic solution \rightarrow ring elements
 - Dispersion in line defined by initial D and D' and line elements

Transfer Line

• Initial a, b defined for transfer line by beam shape at entrance



- Propagation of this beam ellipse depends on line elements
- <u>A transfer line optics is different for different input beams</u>

Transfer Line

• Another difference....unlike a circular ring, <u>a change of an element in a</u> <u>line affects only the downstream Twiss values</u> (including dispersion)



Linking Machines

- Beams have to be transported from extraction of one machine to injection of next machine
 - Trajectories must be matched, ideally in all 6 geometric degrees of freedom (x,y,z,theta,phi,psi)
- Other important constraints can include
 - Minimum bend radius, maximum quadrupole gradient, magnet aperture, cost, geology



The Twiss parameters can be propagated when the transfer matrix M is known

$$\begin{bmatrix} x_2 \\ x_2 \end{bmatrix} = \mathbf{M}_{1 \to 2} \cdot \begin{bmatrix} x \\ x' \end{bmatrix} = \begin{bmatrix} C & S \\ C' & S' \end{bmatrix} \cdot \begin{bmatrix} x \\ x' \end{bmatrix}$$

$$\begin{bmatrix} \beta_2 \\ \alpha_2 \\ \gamma_2 \end{bmatrix} = \begin{bmatrix} C^2 & -2CS & S^2 \\ -CC' & CS' + SC' & -SS' \\ C'^2 & -2C'S' & S'^2 \end{bmatrix} \cdot \begin{bmatrix} \beta_1 \\ \alpha_1 \\ \gamma_1 \end{bmatrix}$$

Linking Machines

- For long transfer lines we can simplify the problem by designing the line in separate sections
 - Regular central section e.g. FODO or doublet, with quads at regular spacing, (+ bending dipoles), with magnets powered in series
 - Initial and final matching sections independently powered quadrupoles, with sometimes irregular spacing.



Outline



Survey

- Need coordinates and angles of points to be linked in a common coordinate system
- Linking CNGS to Gran Sasso in Italy the CERN reference frame had to be connected to the global systems of Switzerland and Italy – small rotations seen but negligible
- FCC study covers an area ten times bigger than existing installations





[2] N. Ibarrola and M. Jones, International Workshop of Accelerator Alignment (2016).

Survey vs MADX

• Clear definition of coordinate system with survey colleagues is essential!



[2] N. Ibarrola and M. Jones, International Workshop of Accelerator Alignment (2016).

Bending fields

• Magnetic and electric rigidity:

$$B\rho = \frac{p}{q} \longrightarrow B\rho [Tm] = 3.3356 \frac{A}{n} p [GeV/c]$$

A ... atomic mass number n ... charge state p ... average momentum per nucleon

$$E\rho = \frac{pv}{q} \longrightarrow E\rho \left[kV\right] = \frac{\gamma+1}{\gamma} \frac{A}{n} T \left[keV\right]$$

T ... average kinetic energy per nucleon

• Deflection angle:

$$\theta = \frac{Bdl}{B\rho}$$
 or $\frac{Edl}{E\rho}$

Where is the limit between electric and magnetic?

- Electric devices are limited by the applied voltage one can assume several 10s of kV as limit for reasonable accelerator apertures
- Magnets are limited by the field quality at low fields
 - Strong dependence on material properties
 - Remnant fields become important
 - Measuring the field becomes a challenge
- Example
 - 100 keV antiprotons
 - Electrostatic quadrupoles with 60 mm diameter require applied voltages of below 10 kV
 - Electrostatic bends of up to 30 kV

If you are in the energy grey zone...how to choose between magnetic and electric?

Pros and cons of electrostatic beam lines:

- Cheap element production
- Cheap power supplies and cabling
- Mass-independent
- No hysteresis effects (easy operation)
- No power consumption no cooling
- Transverse field shape easy to optimize

- Difficult to measure field shape effective length
- Diagnosis of bad connections
 - Inside vacuum
 - Large outgassing surface area
 - Vulnerable to dirt inside vacuum
 - Requires vacuum interlock for sparking and safety
 - Repair requires opening the vacuum
 - Limited choice of vacuum and bake-out compatible insulators

2D geometry



 [3] M Fraser et al. Beam Dynamics Studies of the ELENA Electrostatic Transfer Lines. (CERN-ACC-2015-340):MOPJE044. 4 p, 2015.

2D geometry

- 36 cm vertical height difference over several m
- 1-2 GeV





More complex 3D geometry

Several 100 m vertical, several km length, 3.3 TeV...distributed bending



Bending field limits

- So far we considered the bending fields in transfer lines limited solely by hardware
- A few 10 kV on electrostatic devices to avoid sparking
- 2 T for normal conducting magnets
- Something like existing LHC dipole reach 9-9.5 T for superconducting magnets
- But is there anything else which might limit the bending field?

Lorentz Stripping

- Transfer of H⁻ ions
- Extra electron binding energy is 0.755 eV
- A moving ion sees the magnetic field in its rest frame Lorentz transform gives electric field as

$$E\left[\frac{MV}{cm}\right] = 3.197 \cdot p\left[\frac{GeV}{c}\right] \cdot B[T]$$

Lifetime

$$\tau = \frac{A}{E}e^{(\frac{C}{E})}$$
 $A = 7.96 \cdot 10^{-14} \text{ s MV/cm}, C = 42.56 \text{ MV/cm}$

Example of PS2

- 4 GeV injection
- Fractional loss below 1e-4 limits magnetic field to 0.13 T



Example of Fermilab Project-X

- Was considered as proton source with 8 GeV H- into recycler ring for neutrino program
- Usual power loss limit in lines of ~1W/m
- Activation was found to be not acceptable for 8 GeV ions
- Reduction to 0.05 W/m power loss to meet radioprotection requirements
- In this regime also other loss processes become relevant...

 [4] D. Johnson. Challenges Associated with 8 GeV H- Transport and Injection for FERMILAB PROJECT-X *. (Proceedings of Hadron Beam 2008), 2008.

Black body radiation





 [6] D. Johnson. Challenges Associated with 8 GeV H- Transport and Injection for FERMILAB PROJECT-X *. (Proceedings of Hadron Beam 2008), 2008.

Black body radiation

Loss Rate vs Beam Pipe Temperature



Rest gas stripping

 Power loss due to stripping on rest gas per length l

Beam energy and intensity

 $\frac{d\sigma}{d\Omega} = \frac{7 \cdot 10^{-19}}{\beta^2} cm^2$ per atom of nitrogen or oxygen $\frac{d\sigma}{d\Omega} = \frac{1 \cdot 10^{-19}}{\beta^2} cm^2$ per atom of hydrogen

Electron loss $\propto \frac{1}{\beta^2}$



Example Fermilab Project X

- Loss rate from black body radiation at 300 K not acceptable
- Installing a cool beam screen (77 K)
 - Reduces black body radiation by factor ~16
 - Improves vacuum pumping (better than 1e-8 Torr)
- Lorentz stripping limits dipole fields to 0.05 T

Focussing structure

- Cell length optimised for dipole filling at extraction energy
- Can assume this as a good starting point for our transfer line
- For transfer lines often a 90 deg FODO structure is chosen
 - Good ratio of max/min in beta function
 - Same aperture properties
 - Provides good locations for trajectory correctors and instrumentation
 - Good phase advance for injection/extraction and protection equipment



SPS to LHC Transfer Line (3 km)

Quadrupole field

• What is needed to specify the quadrupole pole tip field:

$$B = g \cdot x \qquad B_{poletip} = g \cdot a$$

• Need to define quadrupole gradient g [T/m] and pole radius a [m]







 $\frac{L}{f} = 4\sin\frac{\mu}{2}$

Estimate required gradient of quadrupoles

[7] J. Rossbach and P. Schmueser. Basic Course on Accelerator Optics. (CAS), 1992.

FODO optics

$$\mu = 90^{\circ} \Rightarrow f = \frac{L}{2\sqrt{2}}$$



FODO stability



$$\frac{L}{f} = 4\sin\frac{\mu}{2}$$

$$\beta = \left(L + \frac{L^2}{4f}\right) / \sin \mu$$

Estimate required gradient of quadrupoles

Use maximum betatron function to estimate beam size and pole tip field of quadrupoles

[7] J. Rossbach and P. Schmueser. Basic Course on Accelerator Optics. (CAS), 1992.

Apertures

- Arbitrary choice and depends on beam energy (destructive?)
- While in a collider have O(10 sig + few mm)
- Less in TLs

•
$$A_{x,y} = \pm n_{sig} \cdot \sqrt{k_{\beta} \cdot \beta_{x,y} \cdot \frac{\epsilon_{x,y}}{\beta \gamma}} \pm D_{x,y} \cdot k_{\beta} \cdot \frac{\Delta p}{p} \pm CO \cdot \sqrt{\frac{\beta_{x,y}}{\beta_{xmax,ymax}}} \pm \text{align}$$

Apertures

- Arbitrary choice and depends on beam energy (destructive?)
- While in a collider have O(10 sig + few mm)
- Less in TLs



Optics uncertainty in TLs vs rings

Conservative approach But be aware when you specify minimum beam sizes

$$x = \theta \cdot \sqrt{\beta_1 \beta_2} \cdot \sin(\mu_2 - \mu_1)$$

Apertures

- Arbitrary choice and depends on beam energy (destructive?)
- While in a collider have O(10 sig + few mm)
- Less in TLs

•
$$A_{x,y} = \pm n_{sig} \cdot \sqrt{k_{\beta} \cdot \beta_{x,y} \cdot \frac{\epsilon_{x,y}}{\beta \gamma}} \pm D_{x,y} \cdot k_{\beta} \cdot \frac{\Delta p}{p} \pm CO \cdot \sqrt{\frac{\beta_{x,y}}{\beta_{xmax,ymax}}} \pm \text{align}$$





Aperture calculation examples

- Low energy transfer lines (100 keV, ELENA)
 - 10 mm trajectory variation • 4 mm alignment $\Sigma_{x,y}(95\%) = \sqrt{(\beta_{x,y}\kappa_{x,y}\epsilon_{x,y}(95\%))} + (D_{x,y}\kappa_{x,y}\frac{\delta p}{p}(95\%))$ $\kappa_{x,y} = 1.2$
- Medium energy (1-2 GeV, PS Booster)

•
$$A_{x,y} = \pm n_{sig} \cdot \sqrt{k_{\beta} \cdot \beta_{x,y} \cdot \frac{\epsilon_{x,y}}{\beta_{\gamma}}} \pm D_{x,y} \cdot k_{\beta} \cdot \frac{\Delta p}{p} \pm CO \cdot \sqrt{\frac{\beta_{x,y}}{\beta_{xmax,ymax}}} \pm \text{align}$$

• $n_{sig} = 3, k_{\beta} = 1.2, \text{CO} = 3 \text{ mm}, \text{ align} = 0 \text{ (usually ~2 mm)}$

- High energy transfer lines (0.45 3 TeV, LHC, FCC)
 - $n_{sig} = 6$, k_{eta} = 1.0, CO = 1.5 mm

First estimate of field error specification

- Impact of field errors on aperture requirements should be negligible
- Beam quality is the constraint emittance growth

 $Y_2 = Y_1 + D\cos\theta$

 $Y_2^2 = Y_1^2 + Y_1 D \cos \theta + D^2 \cos^2 \theta$

$$\langle Y_2^2 \rangle = \langle Y_1^2 \rangle + 2 \langle Y_1 D \cos \theta \rangle + \langle D^2 \cos^2 \theta \rangle$$



[5] P. Bryant. Beam Transfer Lines. (CAS), 1992.

First estimate of field error specification

$$2\left\langle Y_{1}D\cos\theta\right\rangle = 2\left\langle Y_{1}\right\rangle\left\langle D\cos\theta\right\rangle$$

D and Y₁ are uncorrelated

And averaging over the constant D gives 0

$$\langle Y_2^2 \rangle = \langle Y_1^2 \rangle + 2 \langle Y_1 D \cos \theta \rangle + \langle D^2 \cos^2 \theta \rangle$$

 $\langle Y_2^2 \rangle = \langle Y_1^2 \rangle + \frac{1}{2}D^2$

This is valid for any point P on any circle...

$$\epsilon_2 = \epsilon_1 + \frac{1}{2}D^2$$



First estimate of field error specification

$$D^{2} = (\Delta Y)^{2} + (\Delta Y'^{2}) = (\Delta y)^{2} \frac{1 + \alpha^{2}}{\beta} + (\Delta y')^{2} \beta$$







$$k = -\frac{\Delta Gl}{B\rho}$$

$$\epsilon_2 = \frac{1}{2} \left(k^2 \beta^2 + 2 \right) \epsilon_1$$





Combining errors

Averaging over a distribution of uncorrelated errors

$$\langle y^2 \rangle = \frac{\beta(s)}{2} \sum_n \beta_n \langle \delta_n^2 \rangle$$
 $\delta_n = \frac{\Delta Bl}{B_0 \rho_0}$ and $\delta_n = -lk\Delta y$

$$\langle y^2 \rangle = \frac{\beta_{aver} n \delta_{rms}}{2}$$

• But here we have to be very careful...



Combining errors example

| betx-bef-match | |
|--|--|
| bety-bef-match | |
| 10*dx-bef-match | |
| 10*dy-bef-match | |
| betx-LHC-match | |
| bety-LHC-match | |
| 10*dx-LHC-match | |
| 10*dy-LHC-match | |
| 3 sig envelope hor nominal, 1.4 Gev, present | |
| 3 sig envelope hor nominal, 1.4 Gev, upgrade | |
| Horizontal aperture | |
| | |



Typical specifications from correction studies

- Number of monitors and required resolution
 - Every ¼ betatron wavelength
 - Grid resolution: ~3 wires/sigma
- Number of correctors and strength
 - Every ½ betatron wavelength H same for V
 - Displace beam by few betatron sigma per cell
- Dipole and quadrupole field errors
 - Integral main field known to better than 1-10e-4
 - Higher order field errors < 1-10e-4 of the main field
- Dynamic errors from power converter stability
 - 1-10e-5
- Alignment tolerances
 - 0.1-0.5 mm
 - 0.1-0.5 mrad

Take values with caution!

They can strongly vary depending on energy, intensity, machine purpose, etc.

Summary

Before switching on a computer we can define for a transfer line:

- Number of dipoles and quadrupoles, correctors and monitors
- Dipole field and quadrupole pole tip field
- Aperture of magnets and beam instrumentation
- Rough estimate of required field quality and alignment accuracy

 Optics in a ring is defined by ring elements and periodicity – optics in a transfer line is dependent line elements and initial conditions



• Changes of the strength of a transfer line magnet affect only downstream optics



- Geometry calculations require a set of coordinates in a common reference frame
- Bending fields are defined by geometry and the magnetic or electric rigidity:

$$B\rho [Tm] = 3.3356 \frac{A}{n} p [GeV/c] \qquad E\rho [kV] = \frac{\gamma+1}{\gamma} \frac{A}{n} T [keV]$$

$$\theta = \frac{Bdl}{B\rho}$$
 or $\frac{Edl}{E\rho}$

- The choice between magnetic and electric depends mainly on the beam energy
- If you are in the grey zone, consider: field design and measurement, power consumption, vacuum, interlocking
- For the estimates of bending radii in lines remember to take into account the filling factor (~70%) and Lorentz-Stripping in case of H⁻ ions

 Quadrupole gradients and apertures can be estimated in case of simple focussing structure like FODO cells

$$\frac{L}{f} = 4 \sin \frac{\mu}{2} \qquad \longleftarrow \qquad \begin{array}{c} \text{Stability} \\ f > \frac{L}{4} \end{array} \implies \qquad \longrightarrow \qquad \begin{array}{c} & & \\ & & \\ & & \\ & & \\ \end{array}$$

 Aperture specifications require safety factors for the optics and constant contributions for trajectory variations and alignment errors

•
$$A_{x,y} = \pm n_{sig} \cdot \sqrt{k_{\beta} \cdot \beta_{x,y} \cdot \frac{\epsilon_{x,y}}{\beta_{\gamma}}} \pm D_{x,y} \cdot k_{\beta} \cdot \frac{\Delta p}{p} \pm CO \cdot \sqrt{\frac{\beta_{x,y}}{\beta_{xmax,ymax}}} \pm \text{alignment}$$

• Estimating tolerances from emittance growth:



Gradient errors:

$$\epsilon_2 = \frac{1}{2} \left(k^2 \beta^2 + 2 \right) \epsilon_1 \qquad \qquad k = -\frac{\Delta G l}{B \rho}$$

Thank you for your attention

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R. Baartman, D. Barna, M. Barnes, C. Bracco, P. Bryant, F. Burkart, V. Forte, M. Fraser, B. Goddard, C. Hessler, D. Johnson, V. Kain, T. Kramer, A. Lechner, J. Mertens, R. Ostojic, J. Schmidt, L. Stoel, C. Wiesner

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