AFP Trigger DAQ and DCS

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on behalf of TDAQ and DCS subsystems

agenda

LVL1 trigger

full system project

AFP2+0 installation

current status and development

DAQ

full system project

AFP2+0 installation

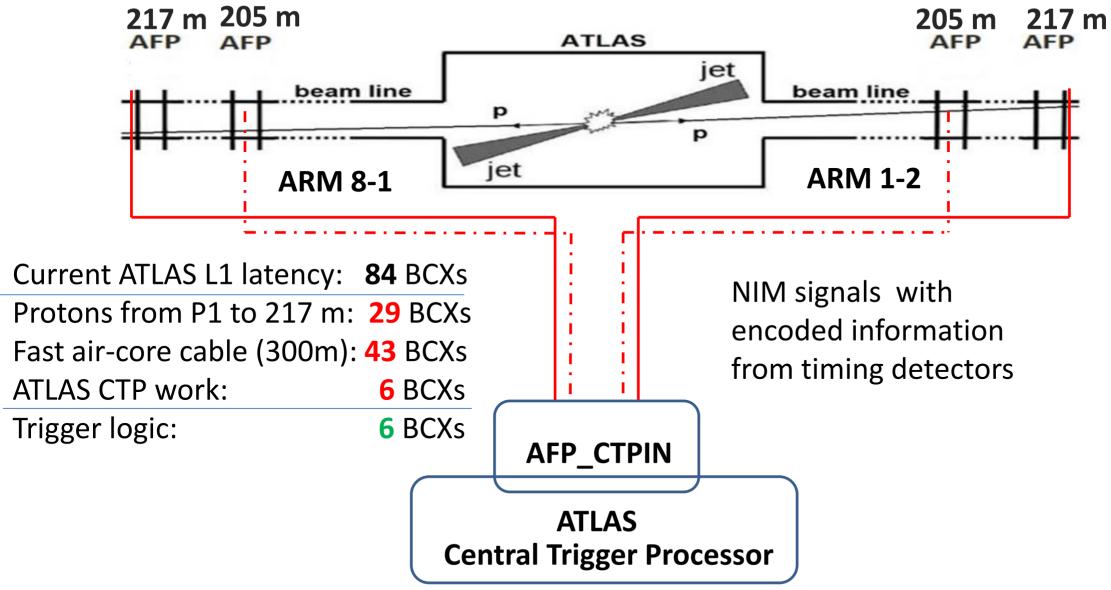
current status and development

DCS

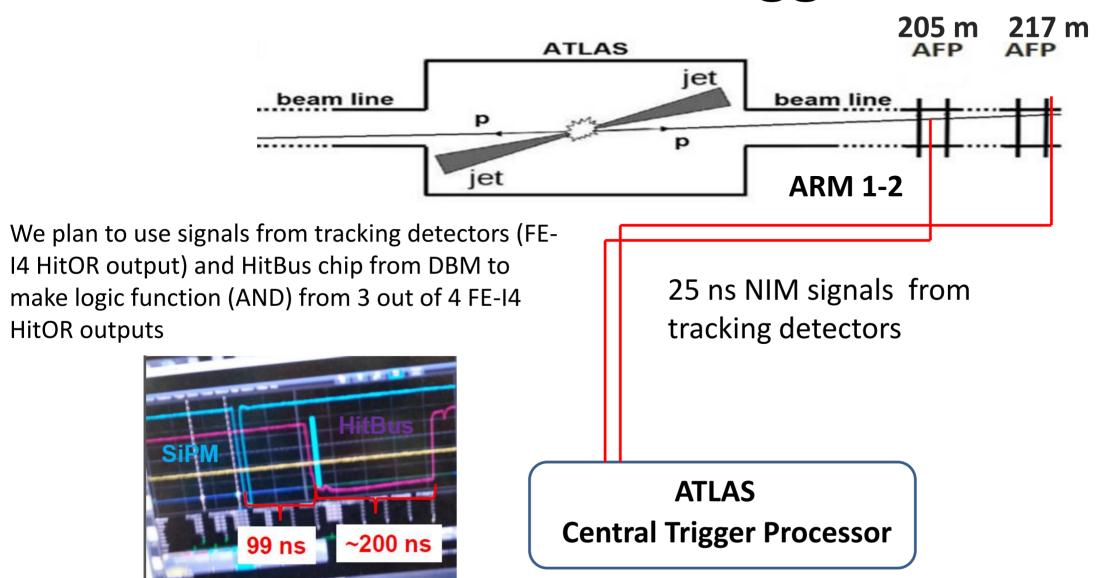
full system project

current status and development

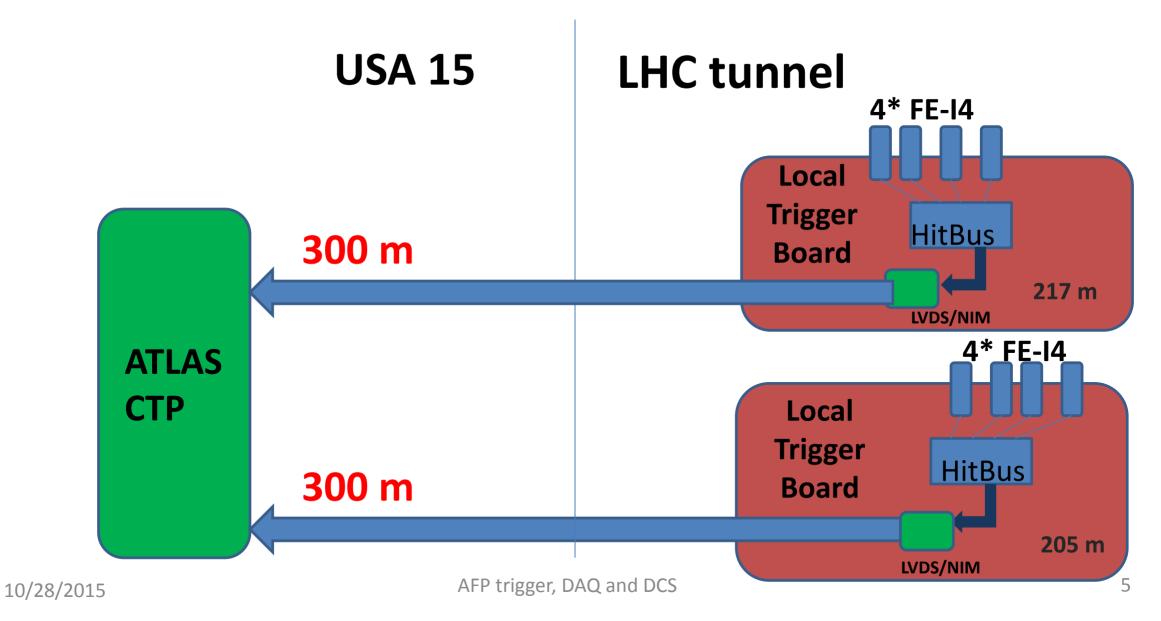
AFP LVL1 trigger



AFP2+0 LVL1 trigger



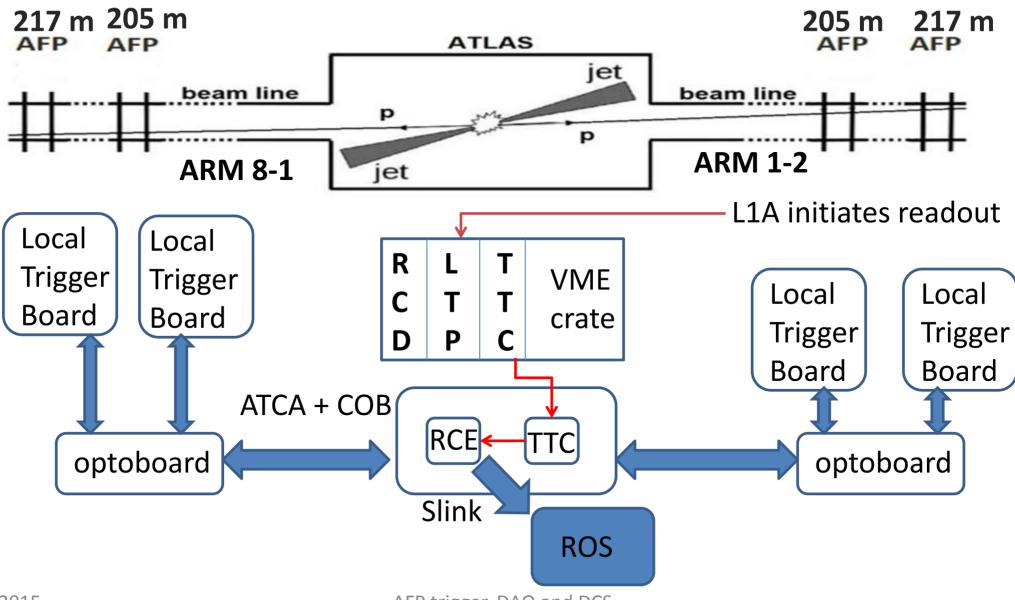
AFP0+2 LVL1 trigger setup

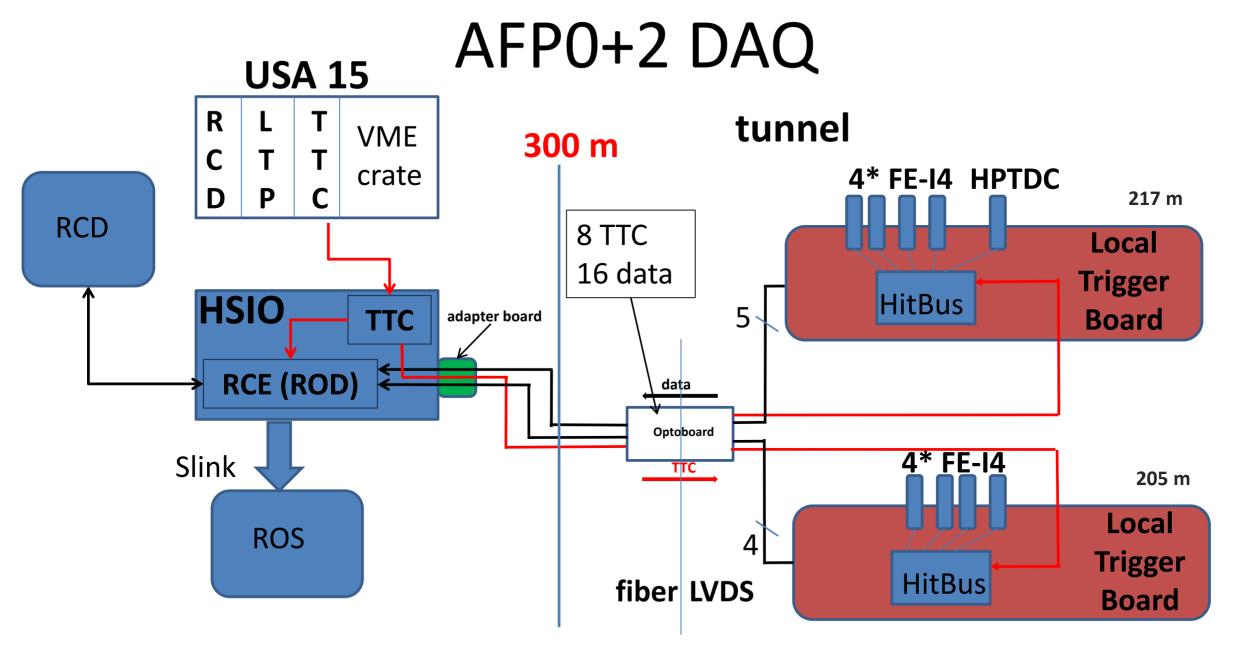


AFP LVL1 trigger status and development

- during the beam tests we performed standalone runs with prototype of the Local Trigger Board (LTB) and parts of the ATLAS TDAQ system
 - VME crate with LTP and TTCvi
 - NIM output from the LTB was used by the LTP to produce L1A and start readout
 - falling edge of the trigger was used to generate L1A
 - HitOR trigger signal spans over 10 BCXs
- new version of the LTB is being designed
- before installation of the air-core cables in the LHC tunnel we plan to send 25 ns pulses and verify signal quality at the other end of the cable

AFP DAQ

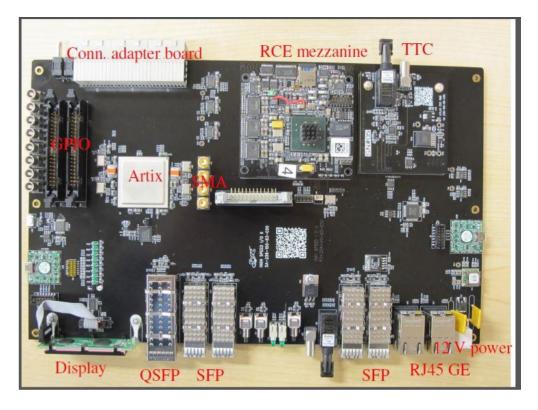




AFP DAQ status and development

- readout via HSIO:
 - integration with ATLAS TDAQ demonstrated during the beam tests
 - uses HSIO firmware (Artix) to serialize and format data before entering RCE
 - Event Building currently in software likely will be put in FPGA
 - firmware for S-link (ROS) exists in CSC needs to be ported to AFP
 - dedicated PC to run RCD controlling and monitoring RCE

HSIO board



• plan to build trigger/DAQ test setup in SR1

DCS: overview of AFP Final Hardware Structure

Hardware for both arms:

HV - ISEG crate with 2 modules

LV - 2 Wiener PL512 + 2 LVPP4

SC-OL – 1 block

IMC - 1 crate

in total 15 ELMB's

Vacuum and Cooling – PLC

Controlled

Positioning – similar to TOTEM

and ALFA

DAQ: final – ATCA RCE

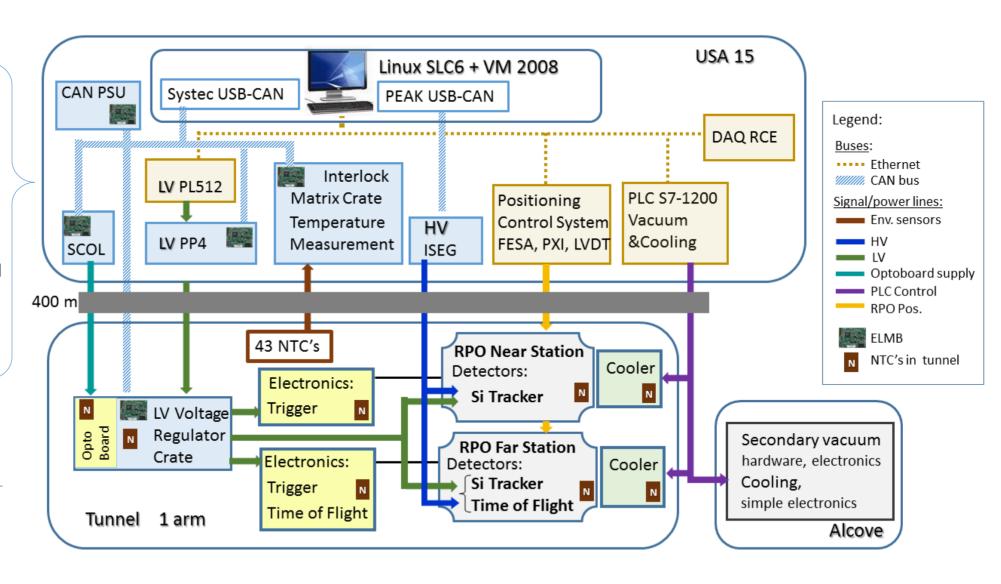
AF0+2 - HSIO RCE

Hardware for 1 arm

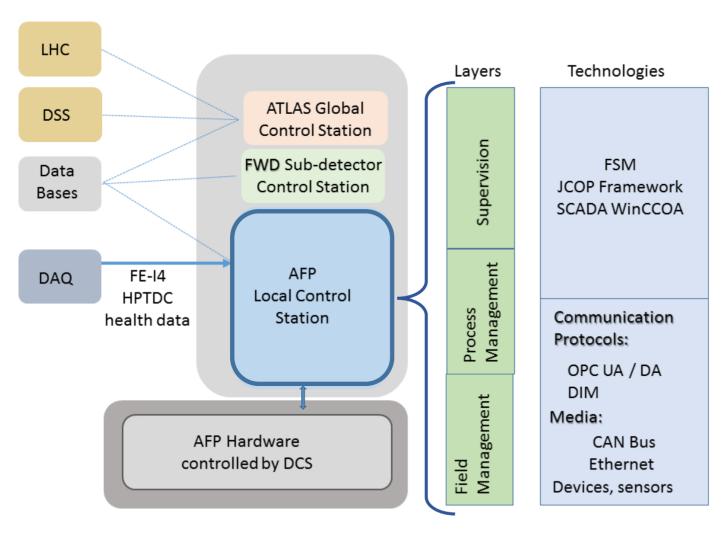
1 optobard

1 Vreg Crate – 1 ELMB

2 Cooler Stations



DCS software structure and integration in Central DCS



DCS Software

- WinCCOA 3.11 SCADA
- JCOP Framework Components
- Central ATLAS DCS Framework
 Components, rules and guidelines
- OPC servers as a middleware communication layer
- FSM for detector hierarchical representation, supervision and visualisation

AFP sub-detector is already defined in the ATLAS Central DCS structure

Present activity: DCS in SR1 AFP LAB

Goal: design, develop and test DCS software

DCS Machine Dell 1950:

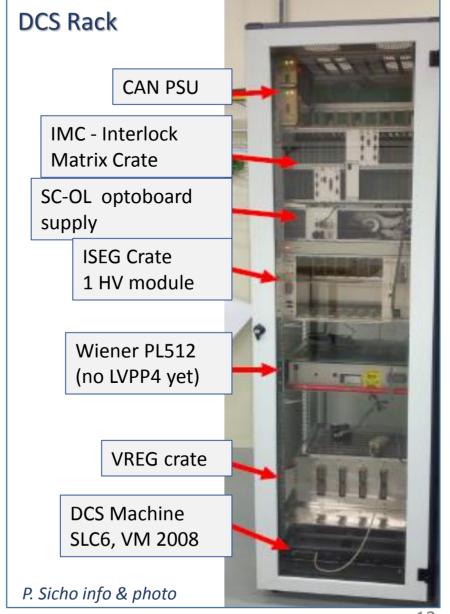
- SLC6 (WinCCOA + OPC UA servers + all DCS software) + VM2008 (WinCCOA + OPC DA servers)
- Will be kept in SR1 AFP LAB as Test Machine

Hardware in SR1 (as a pool of spare components):

- CAN PSU power supply for Can bus, crate + 2 modules
- Interlock Matrix Crate will be completed soon with modules
- VREG Voltage Regulator Crate cards to be provided
- ISEG HV crate + modules
- Wiener LV PL 512 will be delivered soon.

RCE in SR1 Rack area:

Used for development of FE Health Parameters embedded OPC UA server

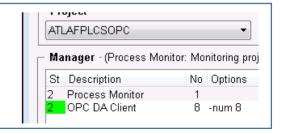


Status of software development in SR1

Software development ongoing:

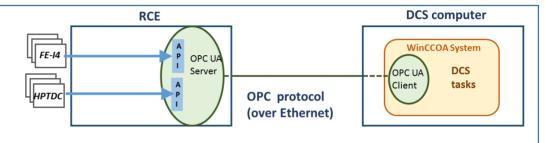
High Voltage

ISEG OPC DA Server (VM2008) and ISEG Framework component installed and tested, ready for final hardware (from Cracow) and further development



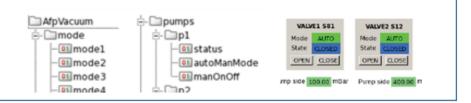
FE Chips health parameters

OPC UA server embedded in RCE will acquire health parameters via dedicated API's -> OPC UA server framework installed on RCE, ready for development



Secondary Vacuum

Preliminary datapoint structure and panels defined



ELMB-Controlled Equipment Ilock MC, SCOL, LVPP4, VREG framework-like software development (based on IBL/Pixel) on-going



DCS current status and plans

Status of final hardware:

- > HV ISEG crate and modules tested OK in Cracow, ready to be sent to CERN
- Wiener PL512 power supplies still waiting for delivery
- DCS production machine Dell R620 ready in USA15
- ELMB controlled equipment: partially ready in SR1
- ELMB's all needed (17) and some spares (3) available

Status of software:

- > AFP DCS added to Atlas Central DCS environment
- > DCS Project in SR1 exists and allows for concurrent developments
- Status of individual software parts is progressing

Plans:

- Continue software development in SR1: availability of detector parts will be necessary
- Install final production OS + necessary software packages in DCS P1 machine after TS3
- Start moving some parts of hardware and DCS software from SR1 to P1
- First tests in P1