

# Round Table on Pixel Time Stamping

## Panel

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# Round Table on Pixel Time Stamping

## Physics and Detector Requirements

M Battaglia



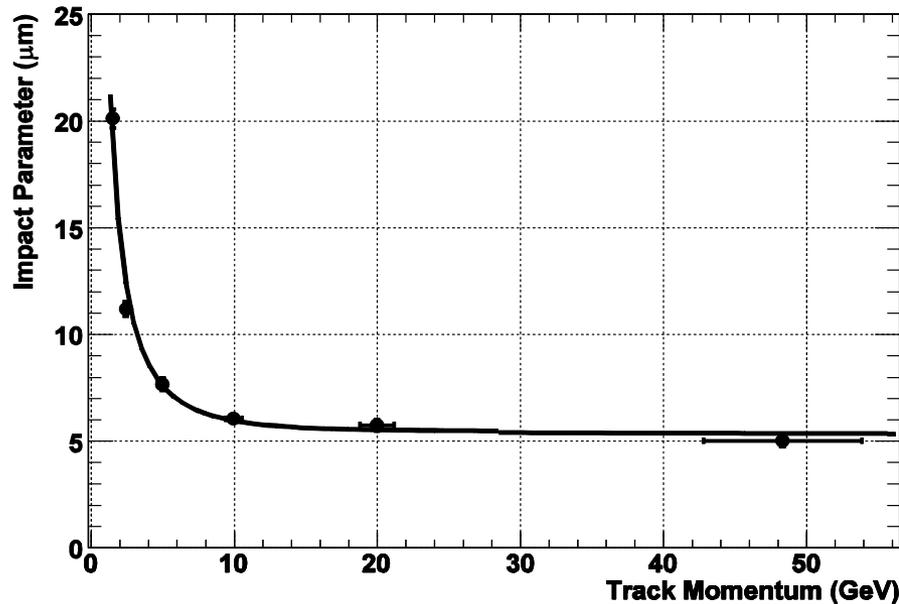
# Main Requirement & Constraints for Pixel Sensors at CLIC

- Pixel Size
  - track extrapolation resolution & spatial granularity
- Time stamping
  - time granularity
- Sensor Thickness
  - material budget
- Power Dissipation
  - material budget



# Space Granularity

## Track Extrapolation Resolution



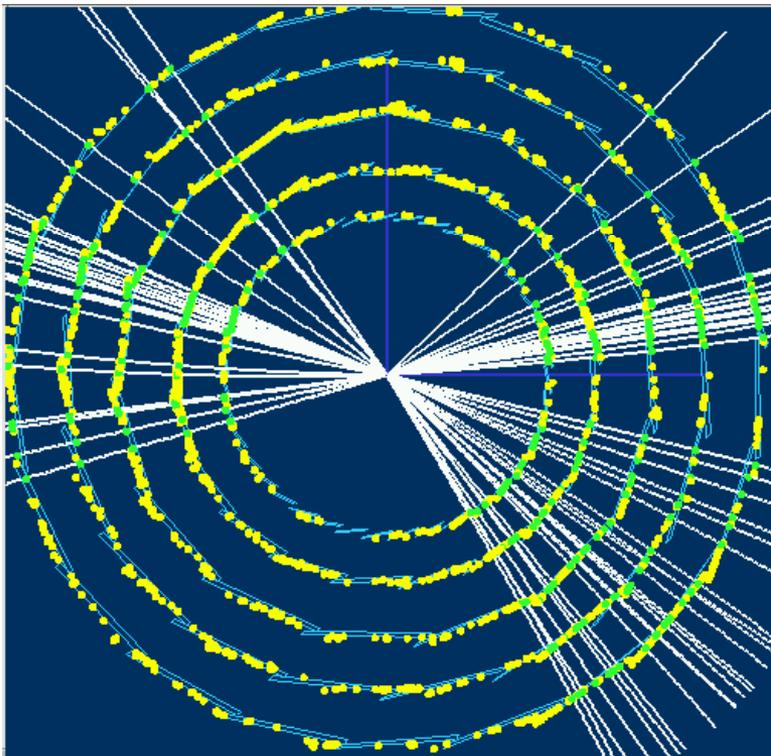
$$\sigma_{\text{IP}} \simeq 5 \mu\text{m} \oplus \frac{15 \mu\text{m}}{p_t(\text{GeV})}$$

Given CLIC constraints this can be achieved with a multi-layered VTX with single point resolution  $\sim 3 \mu\text{m}$ , i.e. a  $\sim 10 \mu\text{m}$  binary pixel or a 15-20  $\mu\text{m}$  analog pixel with charge interpolation

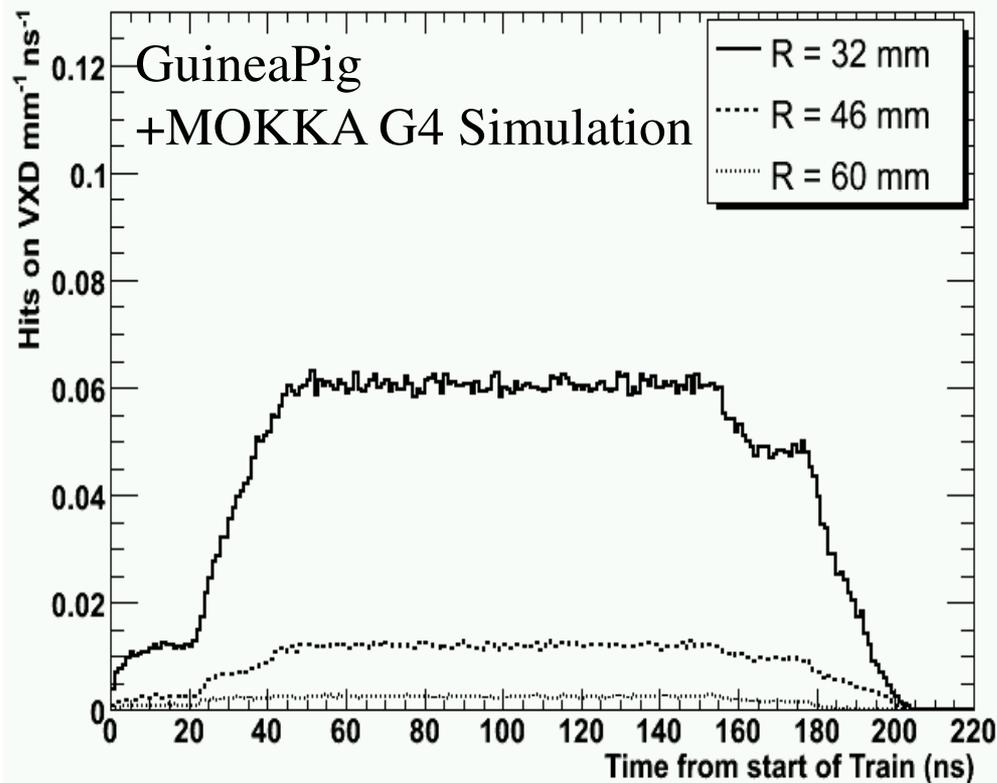
5-20  $\mu\text{m}$  pixel pitch appears feasible for CCDs and monolithic active pixels in various technologies and architectures, is/will be possible to implement fast time-stamping capabilities in such small footprint ?



# Space and Time Granularity Occupancy from Pair Background

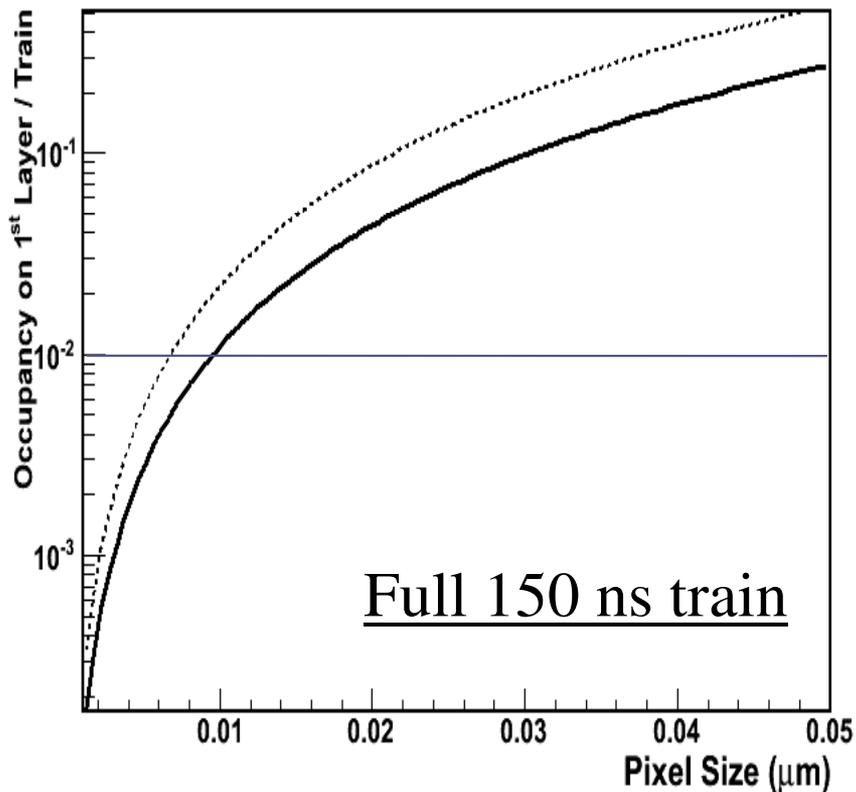


Hit Density on VTX vs time from start of train

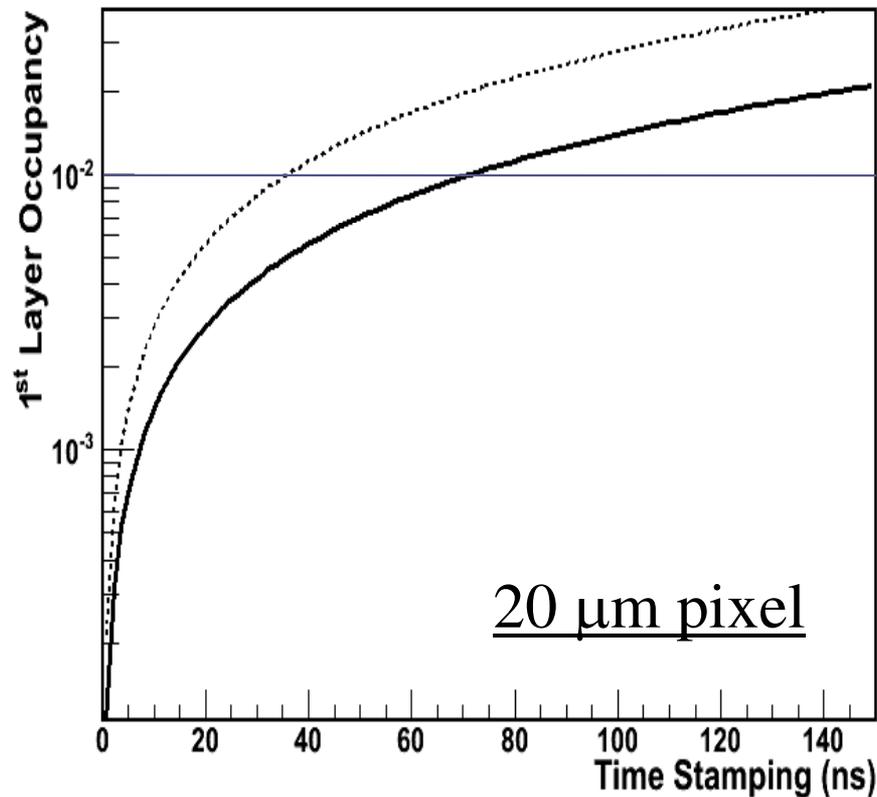


# Space and Time Granularity Occupancy from Pair Background

Train Occupancy vs. Pixel Size



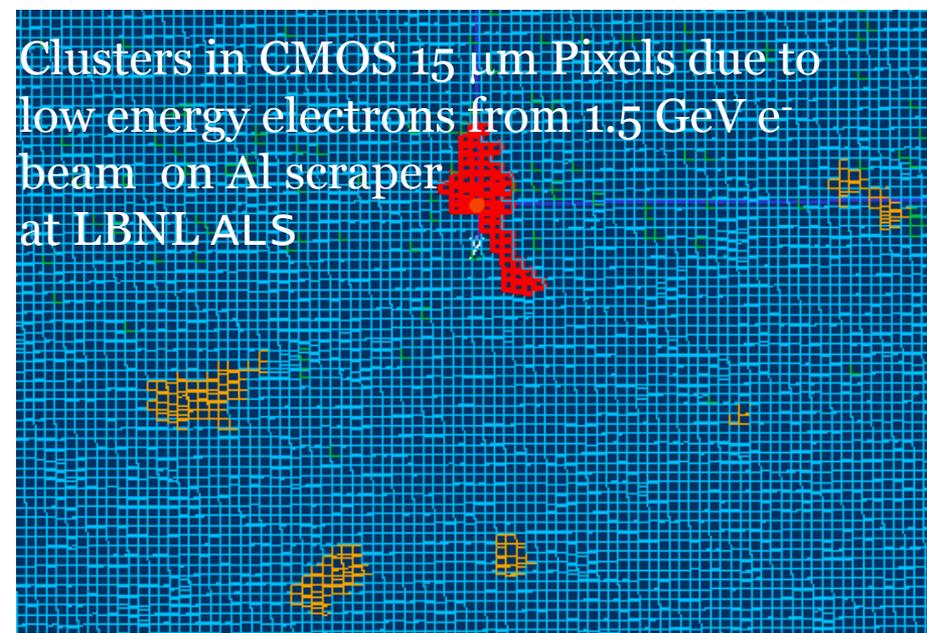
Occupancy vs. Time Stamping



# Space and Time Granularity

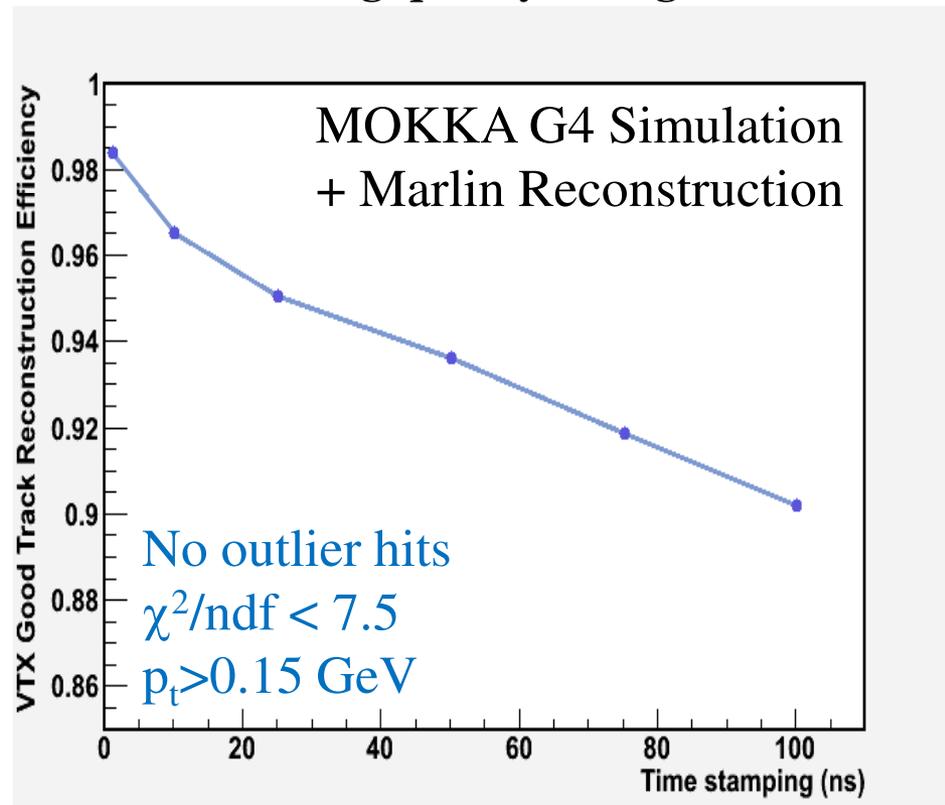
## Occupancy from Pair Background

Expect 0.06 hits/mm<sup>2</sup>/BX, but depending on technology and layout each hit involves few to > 10 pixels



Overlay pair hits to 3 TeV  $e^+e^-$  events and study standalone VTX pattern recognition efficiency/purity vs time stamping.

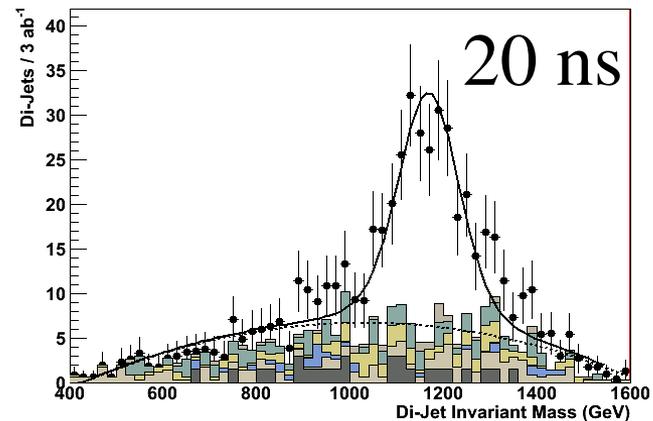
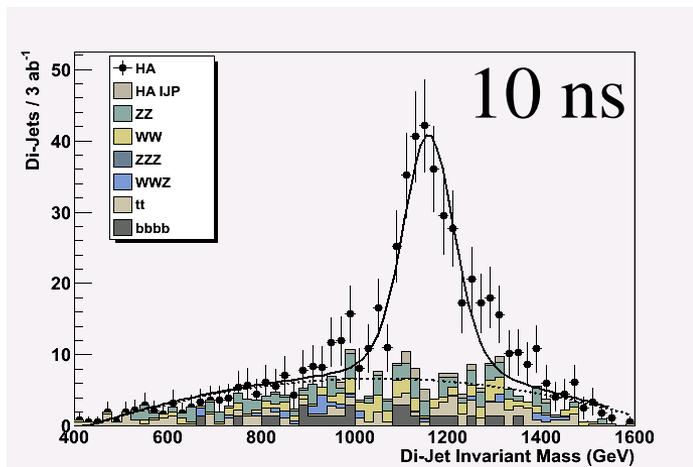
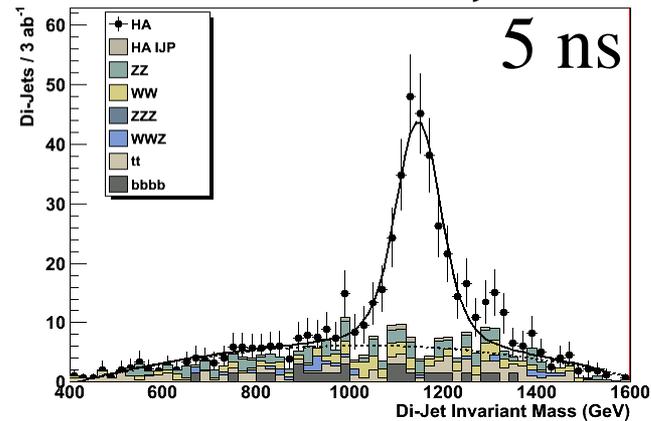
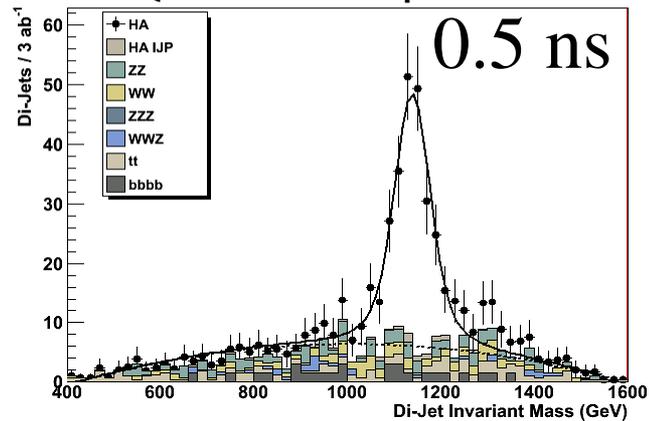
20  $\mu\text{m}$  pixel, depleted sensitive volume w/ average cluster size 2.5 pixels, single hit efficiency 99.5%. Plot efficiency for reco tracks fulfilling quality cuts given below:



# Time Granularity:

## Energy in $e^+e^-$ event from $\gamma\gamma \rightarrow$ hadrons background

Degradation of physics signal as function of background integrated in the detector  
(MOKKA G4 Simulation + Marlin Reconstruction)



Preliminary results of full G4+reco analyses indicate physics performance impacted for  $\Delta t > 10-15$  ns

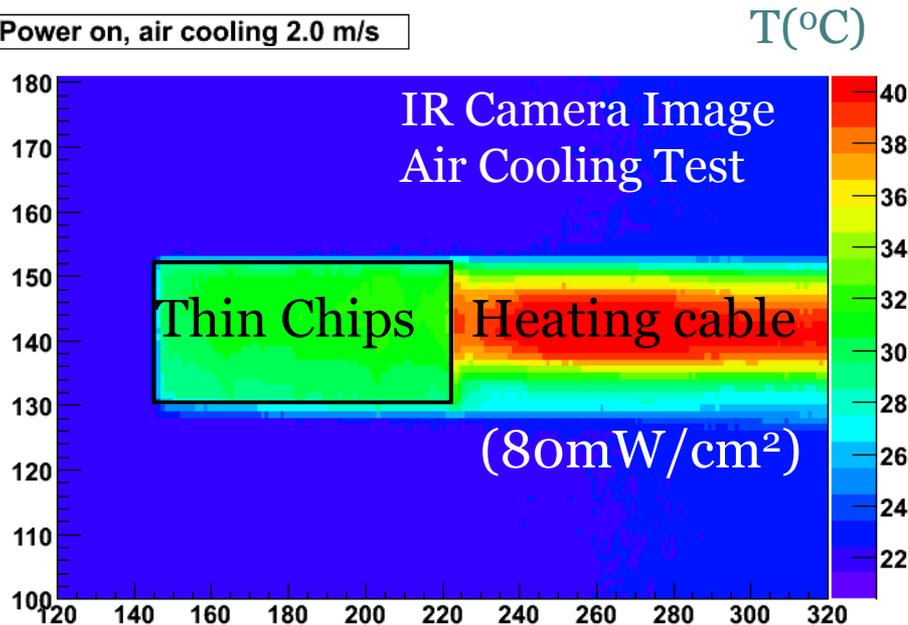


# Material Budget: Power Dissipation and Cooling

Material minimisation dictates passive cooling,

Preliminary tests with thin monolithic CMOS sensors on CFC ladder support structure in collaboration with STAR HFT indicate that 1-3 m/s airflow removes 70-100 mW/cm<sup>2</sup> without inducing large vibrations.

Power on, air cooling 2.0 m/s



Assuming power dissipation to be concentrated at the end of column, 20  $\mu\text{m}$  pixels and 1 cm column height, this corresponds to a limit of  $\sim 0.15 \text{ mW}/\text{column}$

This power budget appears to be realistic for a variety of monolithic pixel sensor technology, but is/will this be feasible when including time-stamping capabilities ?  
Is power pulsing at 50 Hz an option ?

