

Effects of Element Misalignments on Accelerator Performance

Andrea Latina (CERN)

`andrea.latina@cern.ch`

2nd PACMAN Workshop - Debrecen, Hungary - June 13-15, 2016

Table of Contents

- ▶ Recap of beam dynamics
- ▶ Why is the emittance important?
- ▶ Effects of static misalignments
- ▶ Mitigation techniques
- ▶ Integrated performance
- ▶ Conclusions

Recap of beam dynamics (I) : Forces and kicks

Phase-space coordinates of a single particle:

$$\left(x, \quad x', \quad y, \quad y', \quad \Delta t, \quad \delta = \frac{P-P_0}{P_0} \right)^T$$

[m] [rad] [m] [rad] [m/c] [#]

with the transverse angles defined as:

$$x' = \frac{P_x \text{ [MeV/c]}}{P_z \text{ [MeV/c]}}; \quad y' = \frac{P_y \text{ [MeV/c]}}{P_z \text{ [MeV/c]}}$$

Recall the Lorentz force, $F = q(E + v \times B)$. A transverse force over a length Δs imparts a transverse momentum $\Delta P_{\perp} = F_{\perp} \Delta t$:

$$\Delta P_{\perp} \text{ [MeV/c]} = F_{\perp} \text{ [MeV/m]} \frac{1}{V_z \text{ [c]}} \Delta s \text{ [m]}$$

which translates into a transverse kick, e.g. $\Delta x'$ along the x axis:

$$x'_{(s+\Delta s)} = \frac{P_x + \Delta P_x}{P_z} = x'_{(s)} + \Delta x'$$

$$\text{with } \Delta x' \text{ [rad]} = \frac{\Delta P_x \text{ [MeV/c]}}{P_z \text{ [MeV/c]}}$$

Recap of beam dynamics (II) : Twiss parameters

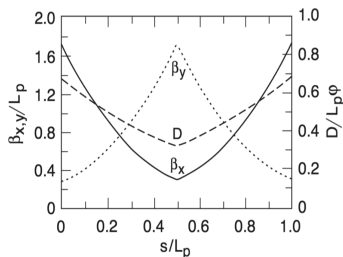
The particle motion in a periodic lattice is described via the solution of the Hill's equation:

$$x(s) = \sqrt{\varepsilon} \sqrt{\beta(s)} \cos(\mu(s) + \mu_0)$$

- ▶ $\beta(s)$, beta function, and $\mu(s)$, phase advance (see Twiss parameters), are lattice properties:

$$\mu(s) = \int_0^s \frac{ds'}{\beta(s')}$$

- ▶ μ_0 , the initial phase, and ε , the Courant-Snyder invariant (or "action"), are a particle properties



Particle transport:

$$\vec{X}_j = \underbrace{\begin{pmatrix} \sqrt{\frac{\beta_j}{\beta_i}} (\cos \mu + \alpha_i \sin \mu) & \sqrt{\beta_j \beta_i} \sin \mu \\ \frac{(\alpha_i - \alpha_j) \cos \mu - (1 + \alpha_i \alpha_j) \sin \mu}{\sqrt{\beta_j \beta_i}} & \sqrt{\frac{\beta_i}{\beta_j}} (\cos \mu - \alpha_j \sin \mu) \end{pmatrix}}_{M_{i \rightarrow j} \text{ (actually a } 6 \times 6 \text{ matrix)}} \cdot \left[\vec{X}_i + \begin{pmatrix} 0 \\ \Delta x' \\ 0 \\ \Delta y' \\ 0 \\ 0 \end{pmatrix} \right]_i$$

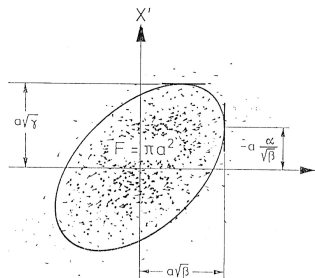
IMPORTANT: the β -function **amplifies** unwanted transverse kicks.

Recap of beam dynamics (III) : Beam emittance

The Twiss parameters define the beam ellipse:

$$\epsilon = \gamma x^2 + 2\alpha x x' + \beta x'^2$$

- ▶ The ellipse amplitude, ϵ , is a particle property (called Courant-Snyder invariant or “action”)
- ▶ For an ensemble of particles we define the (geometric) beam emittance, ϵ , a quantity proportional to the area of the ellipse



The geometric emittance, ϵ , is defined as:

$$\epsilon_{\text{geom}} = \sqrt{\det(\text{cov}(\mathbf{x}, \mathbf{x}'))} = \sqrt{\langle x^2 \rangle \langle x'^2 \rangle - \langle x x' \rangle^2}$$

From which we can compute beam size and divergence:

$$\sigma_x = \sqrt{\beta \epsilon_{\text{geom}}}$$

$$\sigma_{x'} = \sqrt{\frac{\epsilon_{\text{geom}}}{\beta}}$$

(recall the *normalised* emittance, $\epsilon_{\text{norm}} = \beta_{\text{rel}} \gamma_{\text{rel}} \epsilon_{\text{geom}}$)

Effects of kicks on the emittance

Nominal emittance:

$$\epsilon_0 = \sqrt{\langle x^2 \rangle \langle x'^2 \rangle - \langle x x' \rangle^2} = \sqrt{\langle x^2 \rangle \langle x'^2 \rangle} \quad (\text{if } x \text{ and } x' \text{ are uncorellated})$$

In presence of transverse kicks, $\Delta x'$, the emittance transforms $\epsilon_0 \rightarrow \epsilon$:

$$\begin{aligned} \epsilon &= \sqrt{\langle x^2 \rangle \langle (x' + \Delta x')^2 \rangle} \approx \sqrt{\underbrace{\langle x^2 \rangle \langle x'^2 \rangle}_{\epsilon_0^2} + \langle x^2 \rangle \langle \Delta x' \rangle^2} \\ &= \epsilon_0 \sqrt{1 + \frac{\langle x^2 \rangle \langle \Delta x' \rangle^2}{\langle x^2 \rangle \langle x'^2 \rangle}} \\ &\approx \epsilon_0 \left(1 + \frac{1}{2} \frac{\langle \Delta x' \rangle^2}{\langle x'^2 \rangle} \right) \end{aligned}$$

From which derives the emittance growth:

$$\frac{\Delta \epsilon}{\epsilon_0} = \frac{\epsilon - \epsilon_0}{\epsilon_0} = \frac{1}{2} \frac{\sigma_{\Delta x'}^2}{\sigma_{x'}^2} \Rightarrow \boxed{\Delta \epsilon \propto \sigma_{\Delta x'}^2}$$

For example a quadrupole:

$$\Delta x' = K_1 L_q \Delta x_{\text{misalign}} \equiv \frac{\Delta x_{\text{misalign}}}{f_{\text{length}}} \Rightarrow \boxed{\Delta \epsilon \propto \sigma_{\text{misalign}}^2}$$

Why is the emittance important?

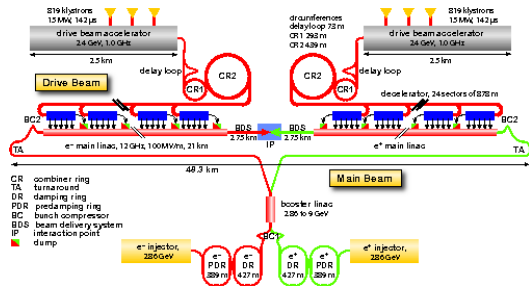
- In a **particle collider** the number of collision is given by the **luminosity**:

$$L = H_D \frac{N^2 n_b f_r}{4\pi\sigma_x^* \sigma_y^*}$$

with

$$\sigma_{\perp}^* = \sqrt{\beta_{\perp}^* \epsilon_{\perp} \text{geom}}$$

$$\perp = x \text{ or } y$$



- H_D , disruption parameter (enhances the luminosity) ; N , number of particles per bunch ; n_b , number of bunches per train ; f_r , repetition frequency ; $\sigma_{x,y}^*$ transverse beam sizes at the interaction point (IP)

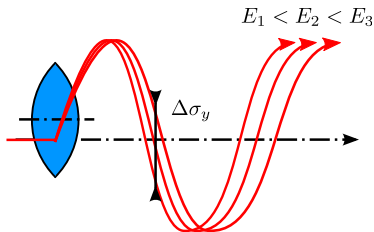
- CLIC emittance growth budgets, in the main linac, due to static misalignments:

$$\Delta\epsilon_x = 60 \text{ nm} \quad \text{and} \quad \Delta\epsilon_y = 10 \text{ nm}$$

in the horizontal and vertical axes, respectively.

Effect of magnet misalignments

- ▶ "Feed-down" effect: A misaligned magnet of order N behaves like a magnet of order $N - 1$:
 - ▶ a misaligned quadrupole gives a dipolar kick,
 - ▶ a misaligned sextupole gives a quadrupolar kick, etc. etc.
- ▶ Effect of a misaligned quadrupole (the most frequently used type of magnet!)



- ▶ deflects the beam trajectory, excites betatron oscillations, introduces unwanted dispersion
- ▶ **Unwanted dispersion is bad!**
Because it adds a position-momentum correlation, and increases the beam size:

$$x(s) \rightarrow x(s) + D(s) \frac{\Delta P}{P_0}$$
$$\sigma_x^2 \rightarrow \sigma_x^2 + \underbrace{D^2 \sigma_{\frac{\Delta P}{P_0}}^2}_{(\text{energy spread})^2}$$

Effect of accelerator structure misalignments

Particles traversing a structure with an offset excite Wakefields:

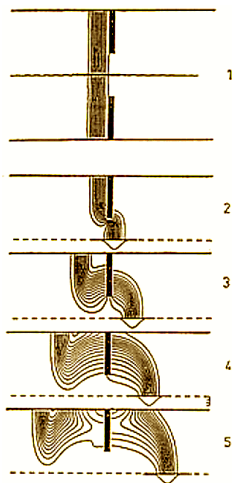
- ▶ transverse effect: z-dependent deflection

$$\Delta x' = \frac{W_{\perp}(z) N e^2 L_S}{P_0} \Delta x$$

- ▶ $W_{\perp}(z)$, transverse wakefield function, [V/pC/m/mm]
 - ▶ N , number of particles per bunch
 - ▶ L_S , structure length
 - ▶ z , particle distance from bunch head
 - ▶ Δx , transverse offset beam \longleftrightarrow structure
- ▶ longitudinal effect: z-dependent energy loss

$$\Delta P_z = W_{\parallel}(z) N e^2 L_S$$

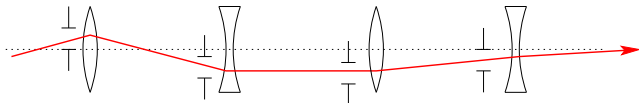
- ▶ $W_{\parallel}(z)$, longitudinal wakefield function, [V/pC/m]
 - ▶ independent from misalignment
- ▶ Their effect can be felt by particles at
 - ▶ short-range (same bunch) \rightarrow emittance growth
 - ▶ long-range (bunch to bunch) \rightarrow beam breakup



Effect of BPM misalignments

Misaligned BPMs affect the beam, indirectly:

- ▶ they do not deflect the beam, but can compromise the effectiveness of optimisation techniques



- ▶ (and actually they can also deflect the beam, e.g. high-resolution “cavity BPMs”, which can create Wakefields)

Besides, off-centred BPMs can display:

- ▶ loss of resolution, or scaling errors: $x_{\text{read}} = \alpha_{\text{scaling}} x_{\text{real}}$

⇒ **BBA, Beam-Based Alignment**, can cure this problem (e.g. **DFS, Dispersion-Free Steering**).

Other errors that affect all elements are:

- ▶ angle errors: offsets in $\Delta x'$ and $\Delta y'$
- ▶ roll errors: rotations around the beam axis $\Delta\phi$

Beam-based alignment techniques

1. Simplest:

- ▶ Quad-shunting: each quadrupole is moved until the magnetic centre is determined
- ▶ **One-to-one**: transverse kickers are used to steer the beam through the centre of the BPMs

2. **Dispersion-Free Steering** (DFS) / Wakefield-Free Steering (WFS)

- ▶ DFS: the presence of dispersion is detected and measured, and transverse kickers are used to counteract it
- ▶ WFS: the presence of wakefields is detected and measured, and transverse kickers are used to counteract it

3. **RF Alignment** (specific to CLIC)

- ▶ Relative beam offset in the accelerating structures is measured, and structures are moved to reduce it

- ▶ Others:
 - ▶ Emittance tuning bumps, coupling correction
 - ▶ MICADO: similar to one-to-one, but picks the best correctors
 - ▶ Kick-Minimisation: useful when DFS cannot easily be applied (e.g. ILC turnaround loops, ...)

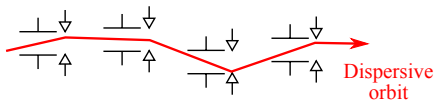
Example of emittance growth in the CLIC main linac

Misalignment of all components, $\sigma_{RMS} = 10 \mu\text{m}$

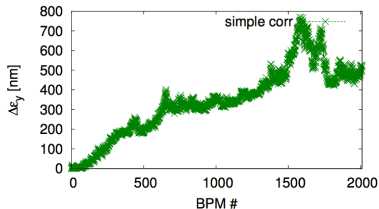
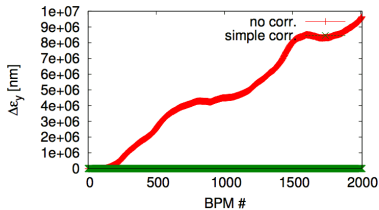
- ▶ Initial emittance is 10 nm
- ▶ Emittance growth is enormous...

One simple mitigation technique is used: “One-to-one” steering, but it’s far from being sufficient...

“One-to-one” steering:



- ▶ Each corrector is used to steer the beam through the centre of the following BPM
- ▶ Orbit makes its way through the accelerator, but dispersion is still present...



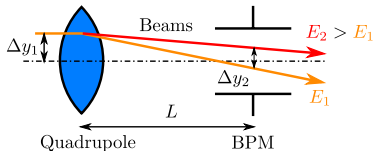
(PLACET Simulation, courtesy of D.Schulte)

Beam-based Alignment: Dispersion-Free Steering (DFS)

Principle of DFS:

1. Measure the dispersion by altering the beam energy (or scaling the magnets)
2. Compute the correction which minimise the dispersion

Graphically:



That is, minimise:

$$\chi^2 = \sum_{\text{bpms}} y_i^2 + \omega^2 \sum_{\text{bpms}} (y_{\Delta E, i} - y_i)^2 + \beta^2 \sum_{\text{corr}} \theta_m^2$$

In practice, one needs to solve the system of equations:

$$\underbrace{\begin{pmatrix} b - b_0 \\ \omega(\eta - \eta_0) \\ 0 \end{pmatrix}}_{\text{measured observables}} = \underbrace{\begin{pmatrix} \mathbf{R} \\ \omega \mathbf{D} \\ \beta \mathbf{I} \end{pmatrix}}_{\text{response matrices}} \underbrace{\begin{pmatrix} \theta_1 \\ \vdots \\ \theta_m \end{pmatrix}}_{\text{unknowns}}$$

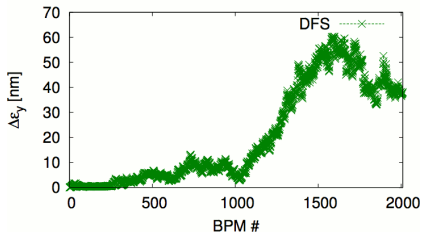
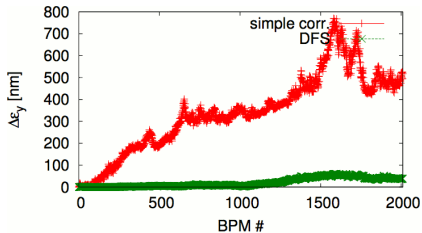
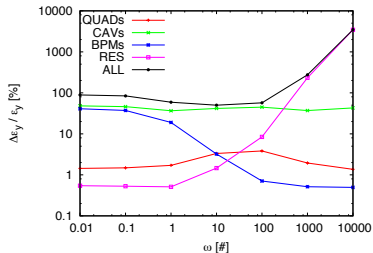
Example of DFS in the CLIC main linac

Minimise:

$$\chi^2 = \sum_{\text{bpms}} y_i^2 + \omega^2 \sum_{\text{bpms}} (y_{\Delta E, i} - y_i)^2 + \beta^2 \sum_{\text{corrs}} \theta_m^2$$

or, solve the system of equations:

$$\underbrace{\begin{pmatrix} b - b_0 \\ \omega(\eta - \eta_0) \\ \mathbf{0} \end{pmatrix}}_{\text{measured observables}} = \underbrace{\begin{pmatrix} \mathbf{R} \\ \omega \mathbf{D} \\ \beta \mathbf{1} \end{pmatrix}}_{\text{response matrices}} \underbrace{\begin{pmatrix} \theta_1 \\ \vdots \\ \theta_m \end{pmatrix}}_{\text{unknowns}}$$



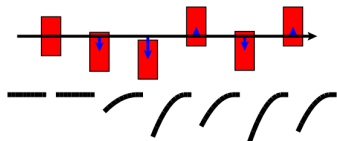
(PLACET Simulation, courtesy of D.Schulte)

Example of RF Alignment in the CLIC main linac

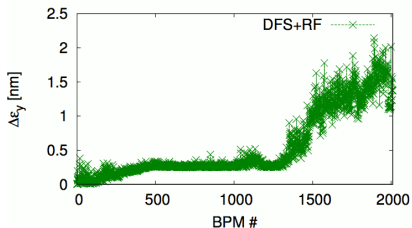
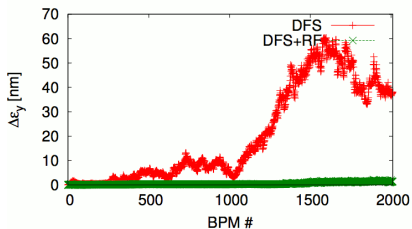
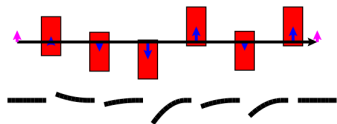
RF Alignment:

- ▶ Each structure is equipped with a wakefield monitor
- ▶ Up to eight structures on one movable girders

Before correction:



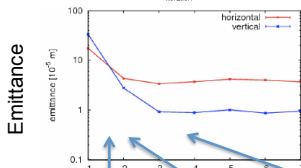
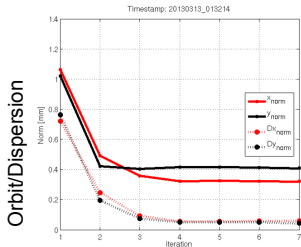
After correction:



(PLACET Simulation, courtesy of D.Schulte)

DFS Tests at FACET / SLAC

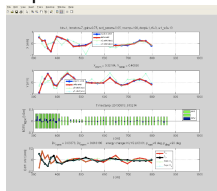
(A.Latina, E.Adli, J.Pfingstner, D.Schulte)



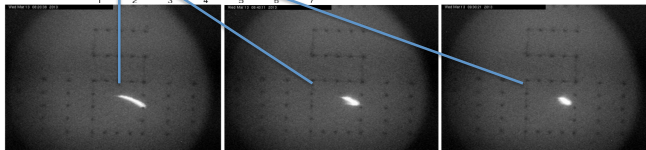
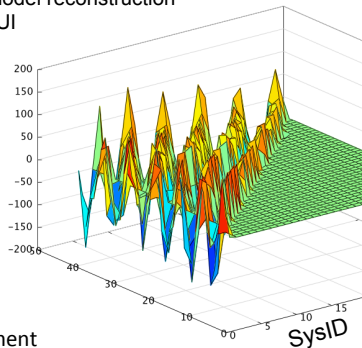
DFS correction applied to 500 meters of the SLC linac

- SysID algorithms for model reconstruction
- DFS correction with GUI
- Emittance growth is measured

Graphic User Interface:



Beam profile measurement



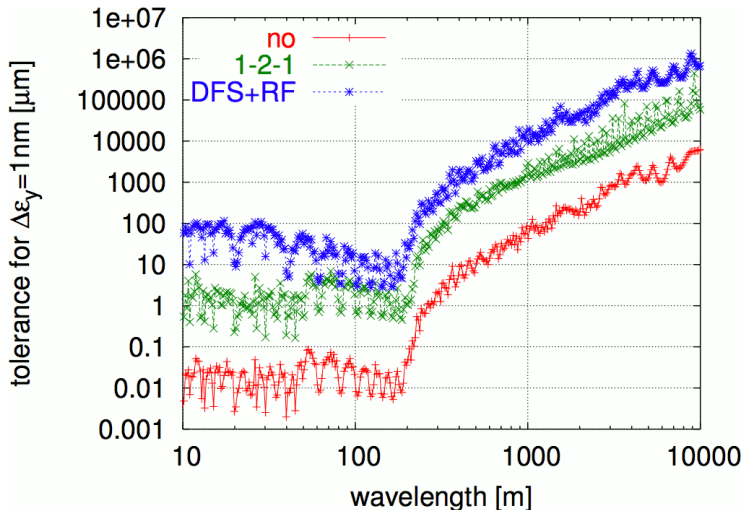
Before correction

After 1 iteration

After 3 iterations

Incoming oscillation/
dispersion is taken out and
flattened; emittance in L11
and emittance growth
significantly reduced.

Tolerance to long wavelengths



(courtesy of D.Schulte)

Tolerance Table

Element	error	with respect to	alignment	
			ILC	CLIC
Structure	offset	girder	300 μm	10 μm
Structure	tilts	girder	300 μradian	200(*) μm
Girder	offset	survey line	200 μm	9.4 μm
Girder	tilt	survey line	20 μradian	9.4 μradian
Quadrupole	offset	girder/survey line	300 μm	17 μm
Quadrupole	roll	survey line	300 μradian	$\leq 100 \mu\text{radian}$
BPM	offset	girder/survey line	300 μm	14 μm
BPM	resolution	BPM center	$\approx 1 \mu\text{m}$	0.1 μm
Wakefield mon.	offset	wake center	—	5 μm

(courtesy of D.Schulte)

Conclusions

- ▶ Element misalignments can greatly damage the beam, inducing emittance growth and beam breakup
 - ▶ CLIC budgets are very tight: $\Delta\epsilon_x = 60$ nm and $\Delta\epsilon_y = 10$ nm in the main linac
- ▶ Standard Pre-Alignment techniques are not sufficient to meet the CLIC requirements:
 - ▶ tightest tolerance is 14 μm over a window of 200 m
- ▶ Powerful beam-based techniques have been invented and tested experimentally
- ▶ **PACMAN** + Beam line design + Beam-based Alignment:

wonderful technical achievements!