

# *Sub-nanometer displacement measurements in seismic sensors.*

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**2<sup>nd</sup> PACMAN  
workshop**

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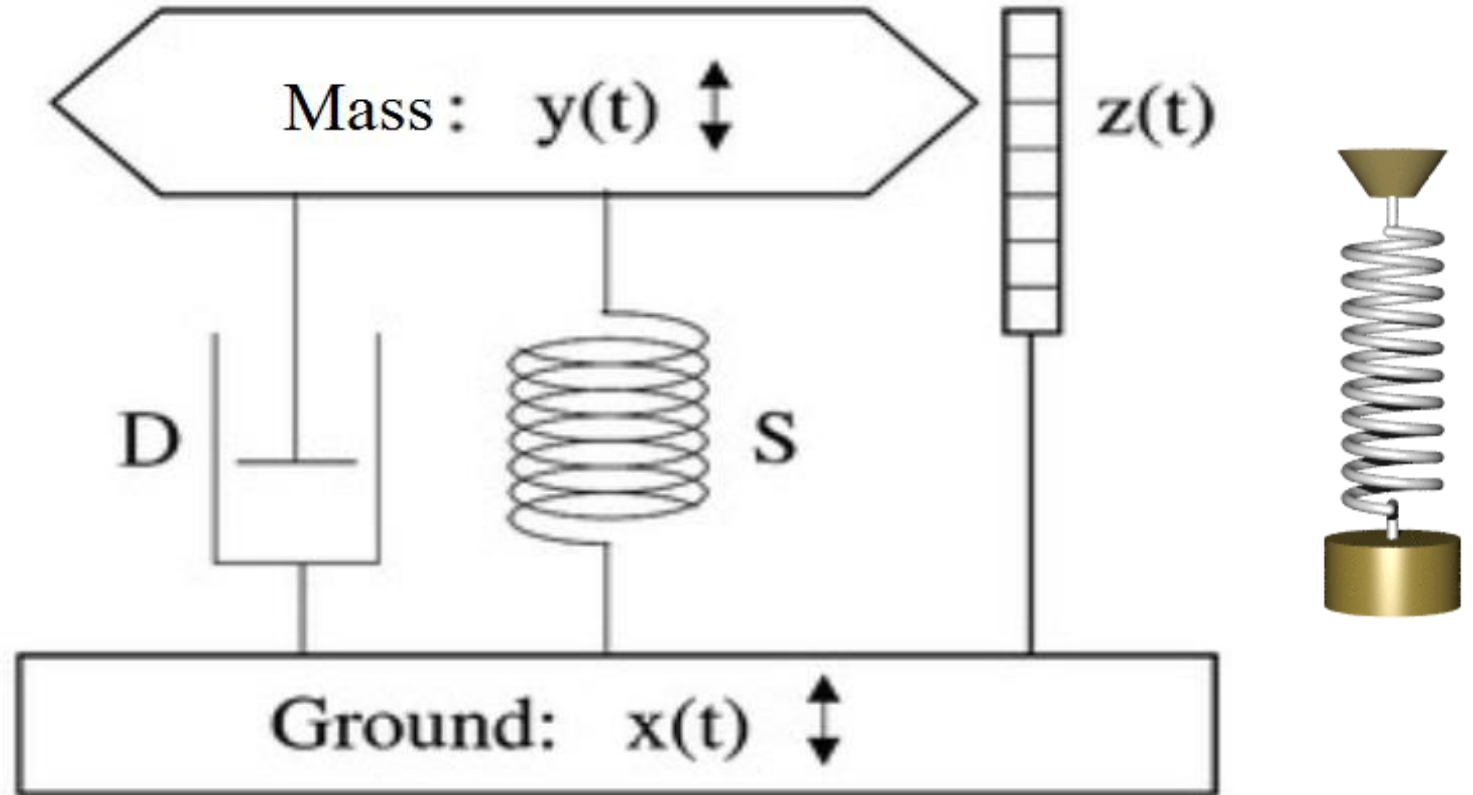
# Content

- What are seismic sensors.
- Seismic sensors in PACMAN.
- Limitations of state of the art sensors.
- Understanding the sensor resolution.
- Measurement of the sensor resolution.
- How to improve sensor resolution.



What are seismic sensors and their working principle.

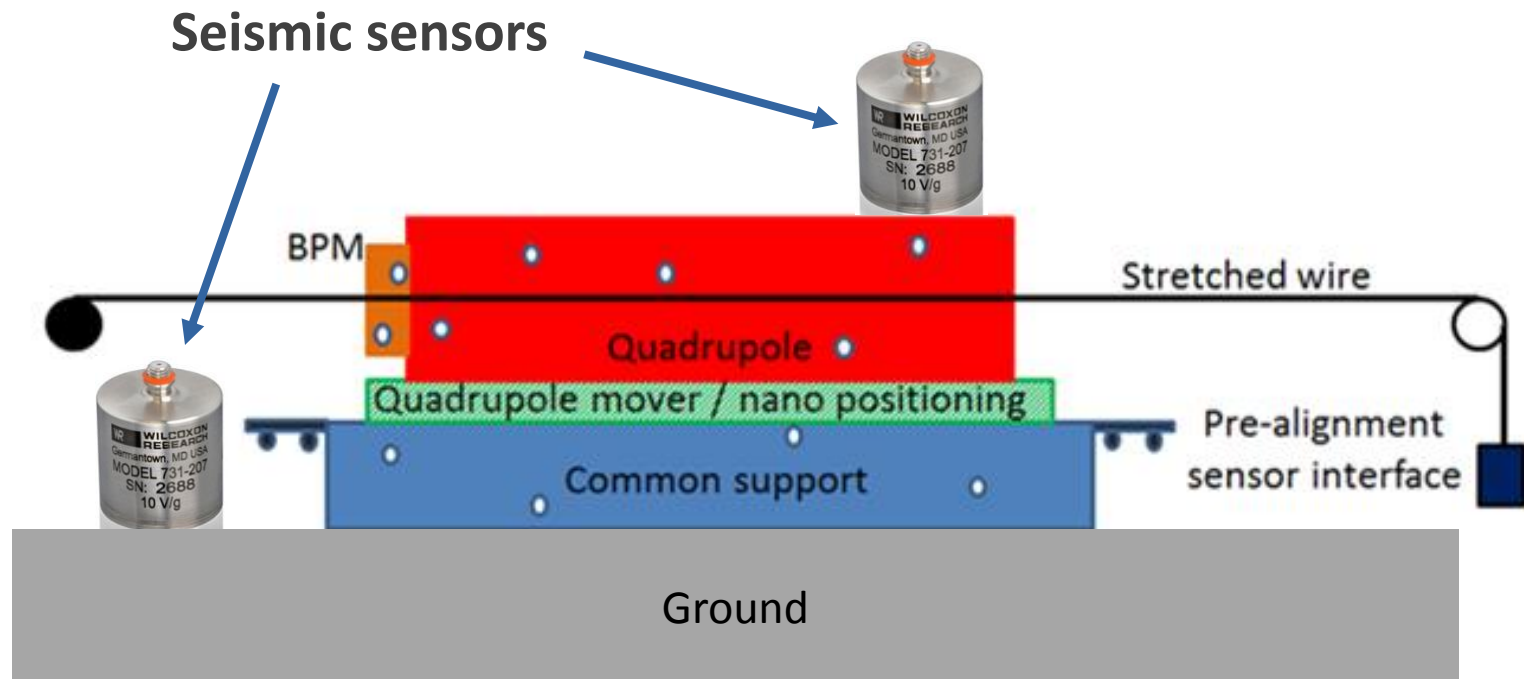
## Instruments which measures ground motion.



Not only earthquakes but also motion in nanometres.

# Why do we need seismic sensors in PACMAN?

- To know how ground motion influences characterization of BPM.



# Limitations of state of the art sensors for PACMAN.

## PACMAN requirements:

Bandwidth = 0.1 ~ 200 Hz

Resolution  $\leq 0.1\text{nm RMS@1Hz}$

Magnetic fields resistance



Seismometers

- × Bandwidth
- ✓ Resolution



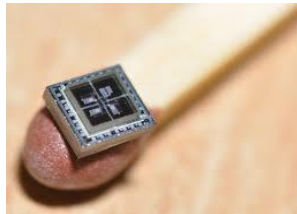
PZT Accelerometers

- ✓ Bandwidth
- × Resolution



Geophones

- × Bandwidth
- × Resolution



MEMS accelerometers

- ✓ Bandwidth
- × Resolution

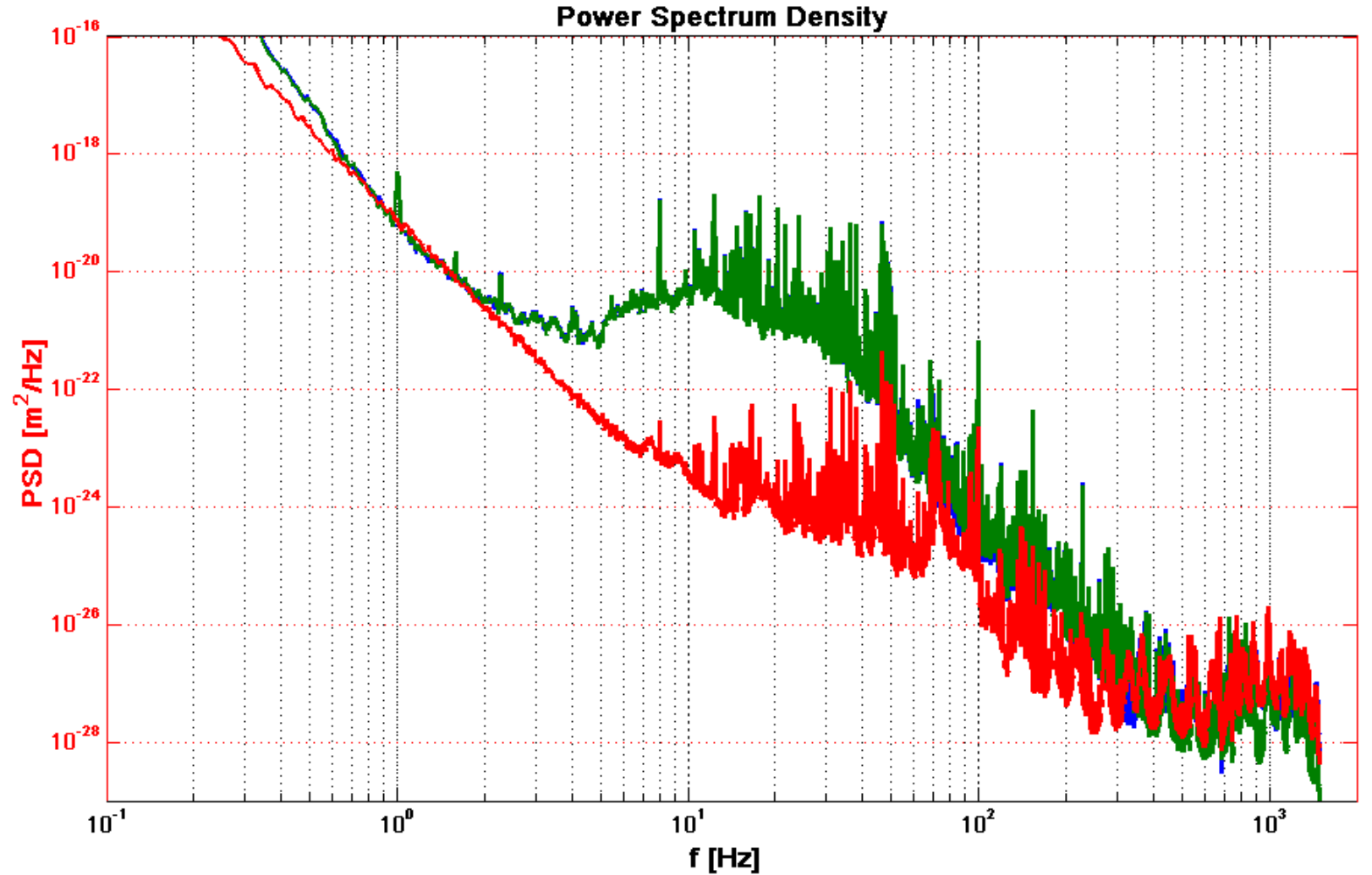
Force Balanced optical accelerometers

- ✓ Bandwidth
- ≈ Resolution



Main problem is that perfect quiet place doesn't exist!

How do we measure sensor's resolution?

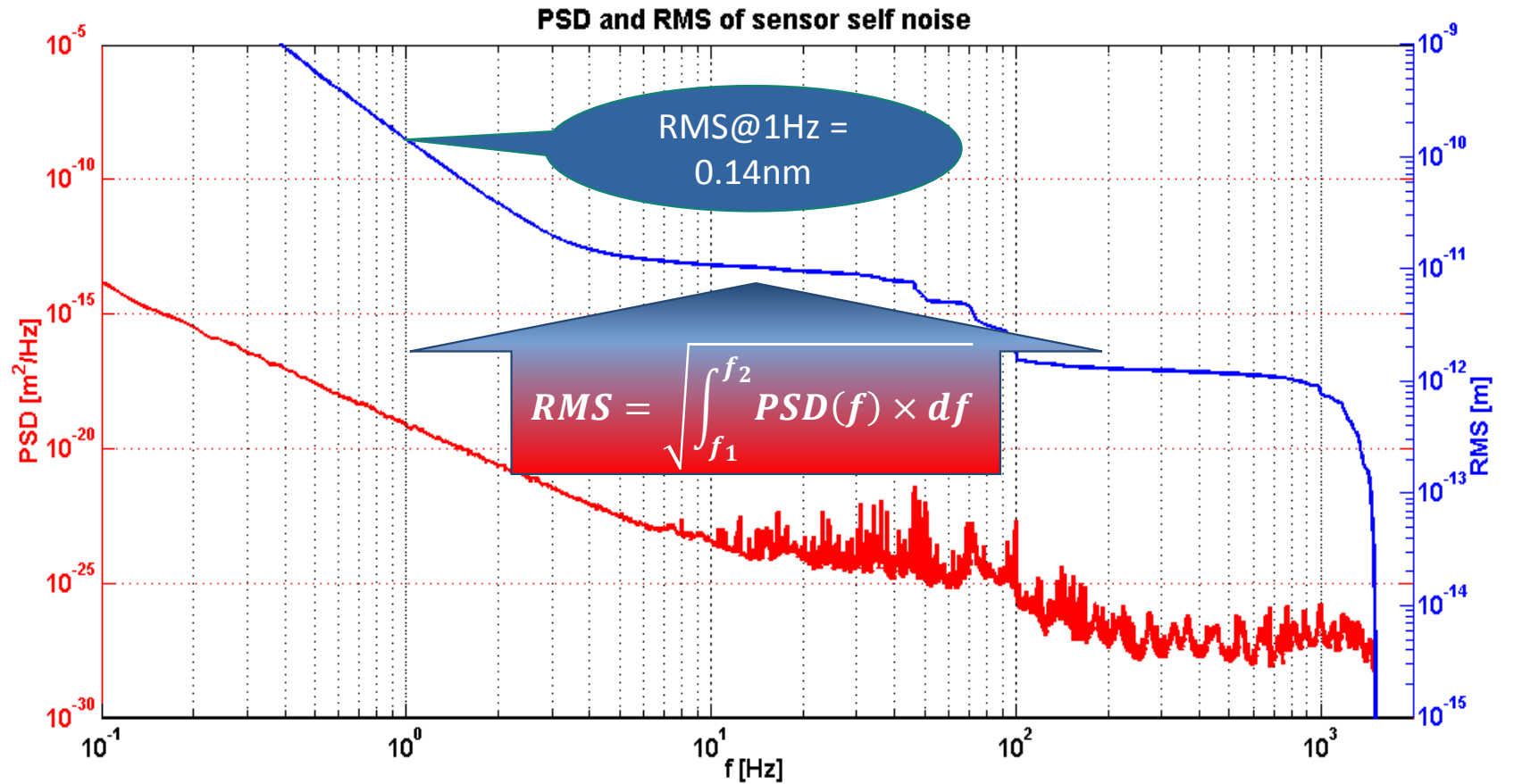


How do we understand resolution.

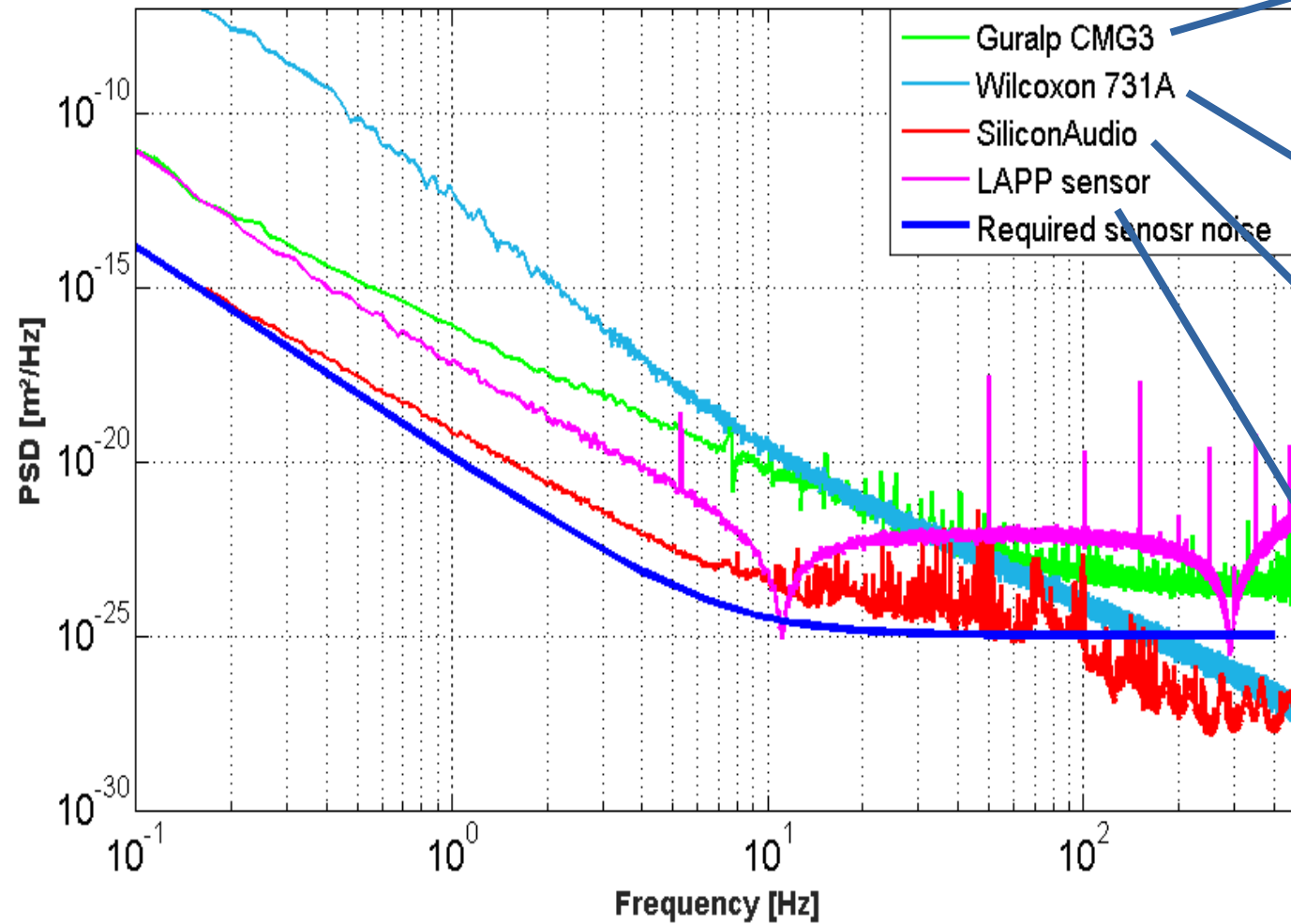
Bandwidth = 0.1 ~ 200 Hz

Resolution  $\leq 0.1\text{nm RMS@1Hz}$

RMS or “average” motion in the bandwidth of interest.



# PSD resolution of different sensors.





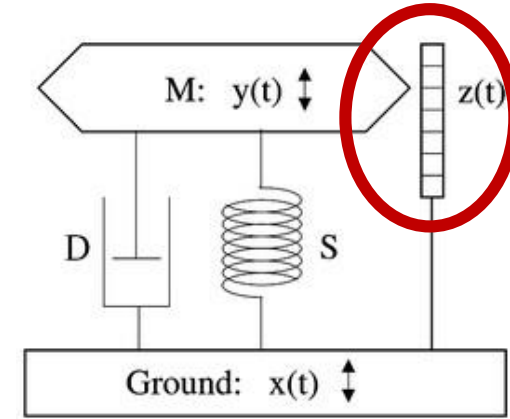
# How to improve sensor resolution?

- Implement high resolution sensor for displacement measurement



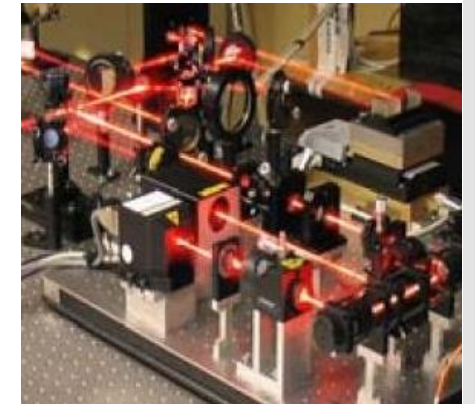
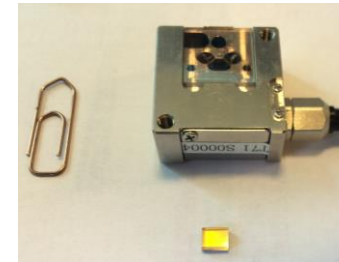
- Options:

- Resistive, Capacitive, LVDT, Optical encoders, Piezoelectric, Eddy current, Interferometers ...



- After applying following requirements:

- Contactless
- Sub-nanometer resolution
- Magnetic field resistance



# How to improve sensor resolution?

**All technologies implemented before but results are influenced by:**

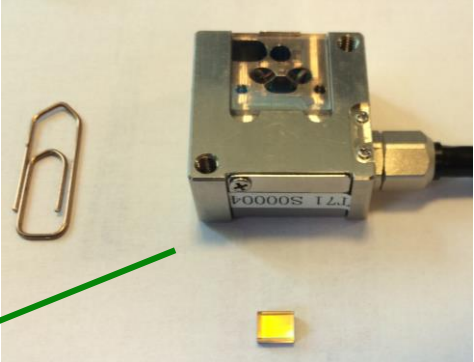
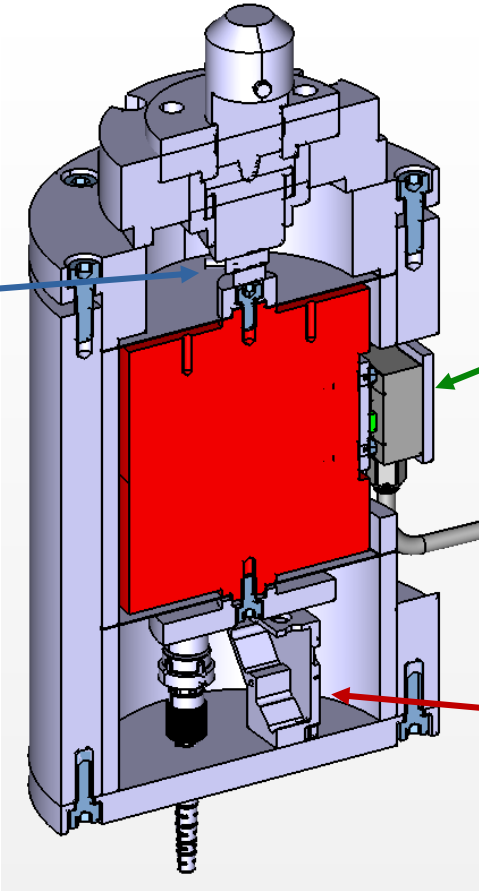
- Ambient environment (temperature, humidity, air refraction index, ...)
- Mechanical design
- Data acquisition hardware
- Signal processing algorithm

**This makes comparison very difficult and unclear.**

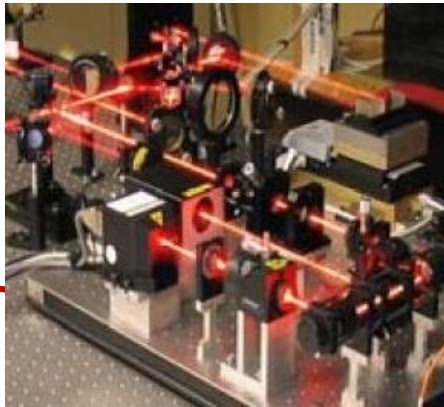


Implementation of displacement sensors to same mechanical body

# Direct comparison = no data ambiguity



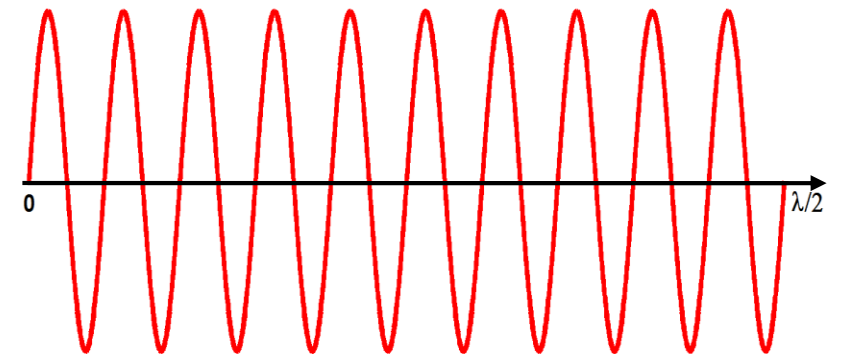
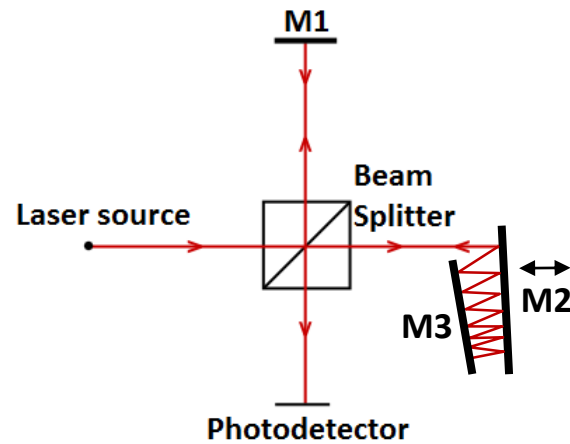
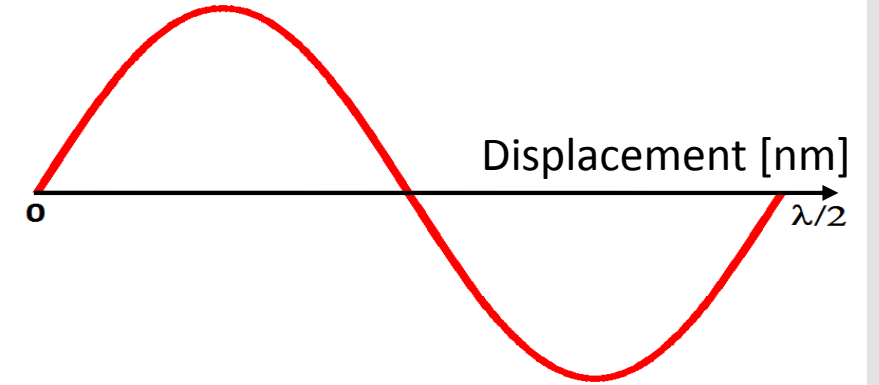
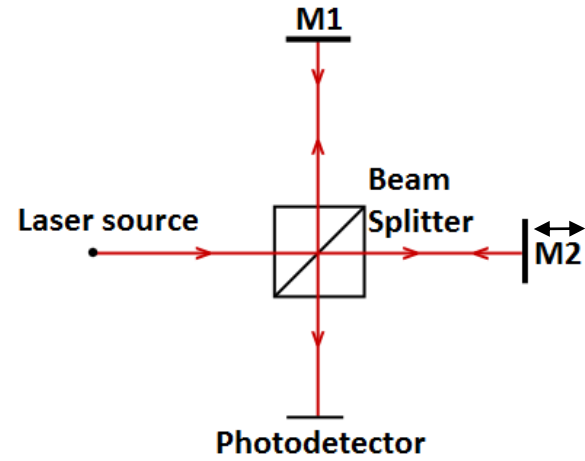
Optical encoder



Interferometer

Increasing sensitivity to improve resolution

## Implementation of multi-reflection Michelson interferometer



# Conclusions

- Seismic sensors will be used to check how ground motion influences BPM characterization.
- Resolution is the main limit for state of the art sensors.
- What we understand under RMS@1HZ resolution and how do we measure it.
- Direct comparison of sub-nm displacement sensors to overcome data ambiguity.
- Increasing the resolution with multi-reflection Michelson interferometer.

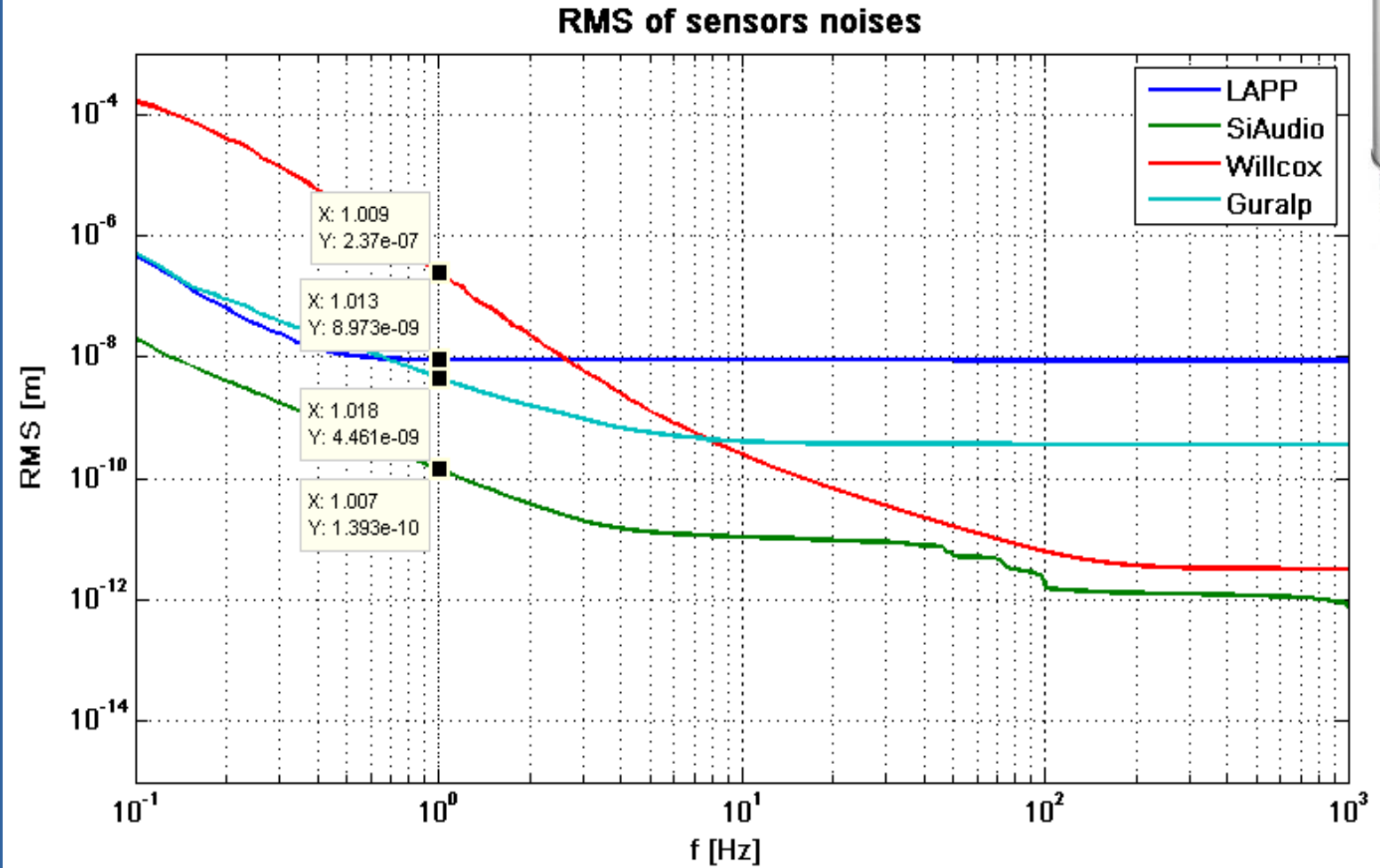


Thank you for your  
attention!

PACMAN



# RMS of sensors noises



# Self-noise measurement problem

- Mass locking vs. corrected difference??

