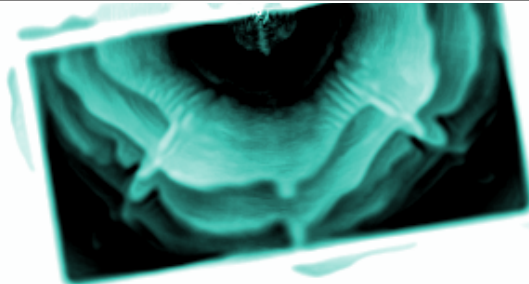


A Parallelized Vlasov-Fokker-Planck Solver for Desktop PCs

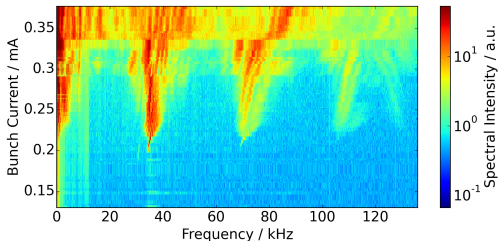
Patrik Schönfeldt | 8th of February 2016

Institute for Photon Science and Synchrotron Radiation

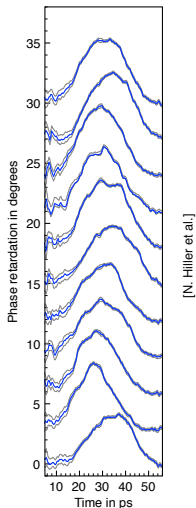


- Multitude of bursting measurements for different machine settings
- Map dynamics, for all the settings
- Nonlinear dynamics explains
 - Coherent synchrotron radiation
 - Above threshold substructures self-amplify
 - Microbunches in longitudinal phase space
- Vlasov-Fokker-Planck solvers well tested
- Speed up to use Desktop PCs

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[M. Brosi et al.]



Vlasov-Fokker-Planck Equation

$$\frac{\partial \psi}{\partial t} + \frac{\partial H}{\partial p} \frac{\partial \psi}{\partial q} - \frac{\partial H}{\partial q} \frac{\partial \psi}{\partial p} = \frac{2}{\tau_D} \left(\frac{\partial}{\partial p} (p\psi) + \frac{\partial^2 \psi}{\partial p^2} \right)$$

describes longitudinal beam dynamics

$\psi(q, p, t)$: Charge density

t : Time

p : Energy coordinate

q : Space coordinate

τ_D : Damping time

Hamiltonian

$$\begin{aligned} H(q, p, t) &= \underbrace{H_e(q, p, t)}_{\text{external fields}} + \underbrace{H_c(q, t)}_{\text{collective effects}} \\ &= \frac{1}{2} (q^2 + p^2) + Q_c \times V_c(Z_c, q, t) \end{aligned}$$

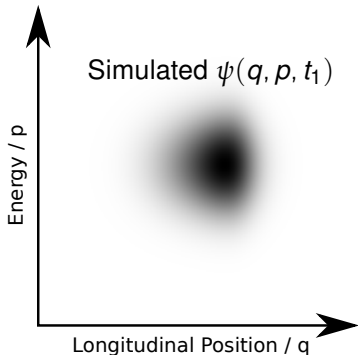
Q_c : Charge

V_c : Potential

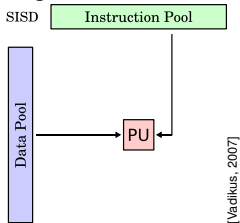
Z_c : Impedance

$$\frac{\partial \psi}{\partial t} + \frac{\partial H}{\partial p} \frac{\partial \psi}{\partial q} - \frac{\partial H}{\partial q} \frac{\partial \psi}{\partial p} = \frac{2}{\tau_D} \left(\frac{\partial}{\partial p} (p\psi) + \frac{\partial^2 \psi}{\partial p^2} \right)$$

- Well established algorithm by Warnock and Ellison (2000)
- For small time steps solve sequentially:
 - 1 LHS: Harmonic Oscillator (Rotation)
 - 2 RHS: Damping and Diffusion
 - 3 Perturbation due to wake field
- Direct implementation:
One run takes days
- Parallelize and optimize each substep

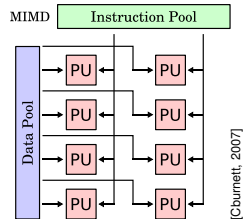


Typical Single-Core Workload:

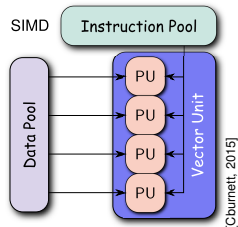


- Sequential programming:
One computation at a time
- Parallel programming:
 - Multiple Data and/or
 - Multiple Instructions
- New/extended programming language needed

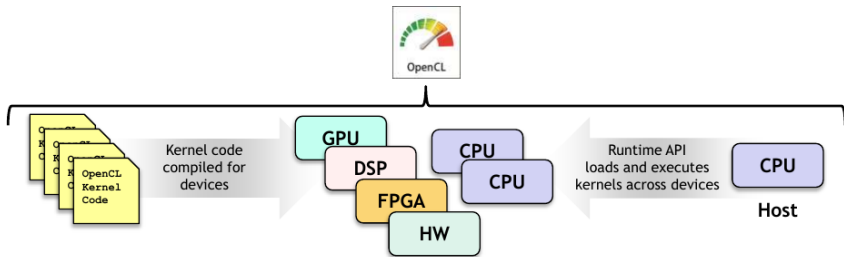
Typical Multi-Core Workload:



Typical GPU Workload:



- C-library for parallel programming
- High level interface to query, select, and initialize devices
- Abstract handling of devices (like GPU, Multi-Core CPU)
- OpenCL C language for parallel code, automatic adaption
- Same code runs on any supported hardware



[Khronos Group, 2015]

Optimize three steps of Vlasov-Fokker-Planck Solver

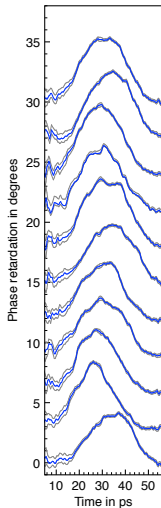
- 1 Rotation
- 2 Damping and Diffusion
- 3 Perturbation due to wake field

- Reduce computation time

Optimize three steps of Vlasov-Fokker-Planck Solver

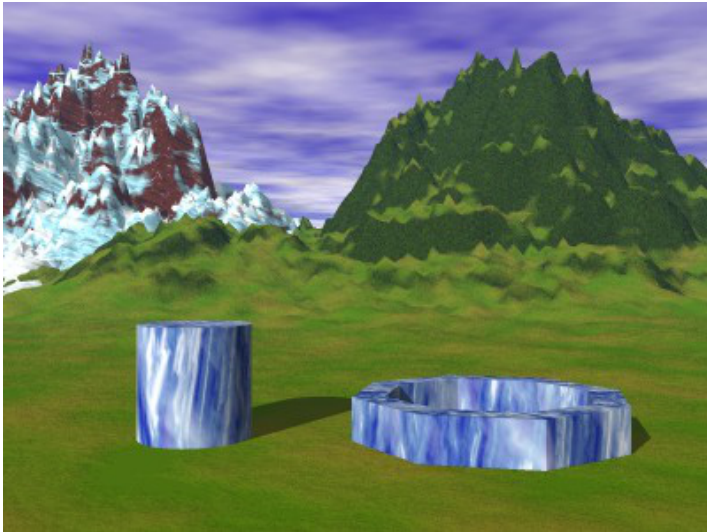
- 1 Rotation
- 2 Damping and Diffusion
- 3 Perturbation due to wake field

- Reduce computation time
- Avoid numerical artifacts



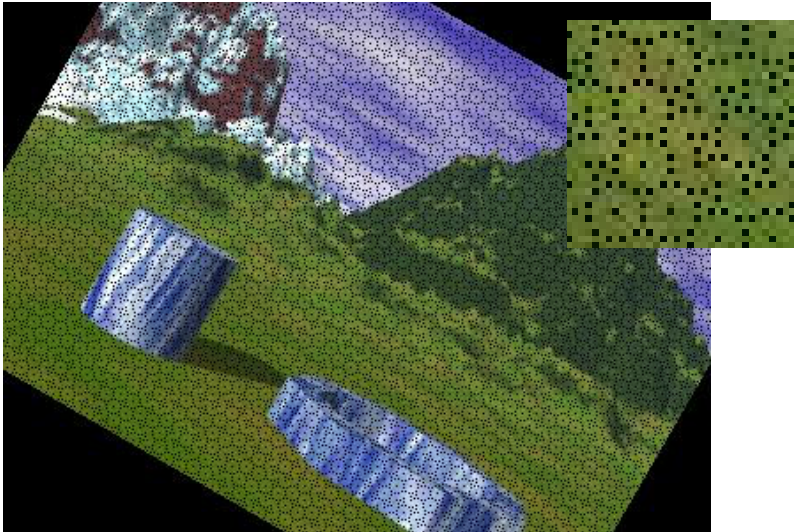
[N. Hiller et al.]

Rotation



[<http://polymathprogrammer.com/2008/10/06/image-rotation-with-bilinear-interpolation/>]

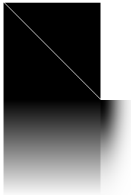
Rotation – Rotation Matrix and Rounding



[<http://polymathprogrammer.com/2008/10/06/image-rotation-with-bilinear-interpolation/>]

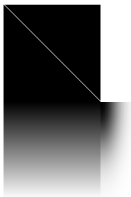
Rotation – Linear Interpolation

Test Pattern

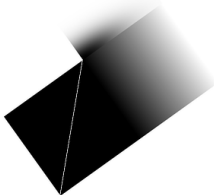


Rotation – Linear Interpolation

Test Pattern

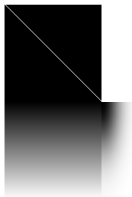


Ideal Rotation

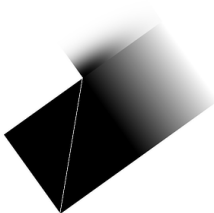


Rotation – Linear Interpolation

Test Pattern



Ideal Rotation

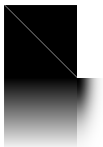


Linear Interpolation



Rotation – Quadratic/Cubic Interpolation

Test Pattern



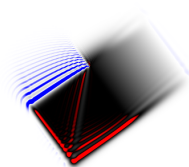
- Higher order interpolation polynomials

- Less Diffusion

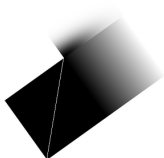
- Added Structures

- Highlighted: Values exceed range of test pattern

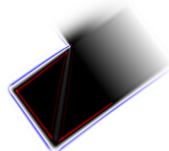
Quadratic Interpolation



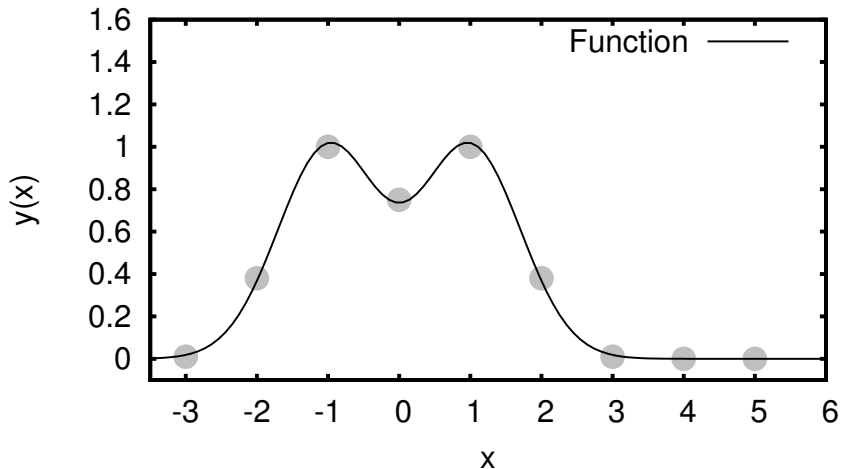
Ideal Rotation



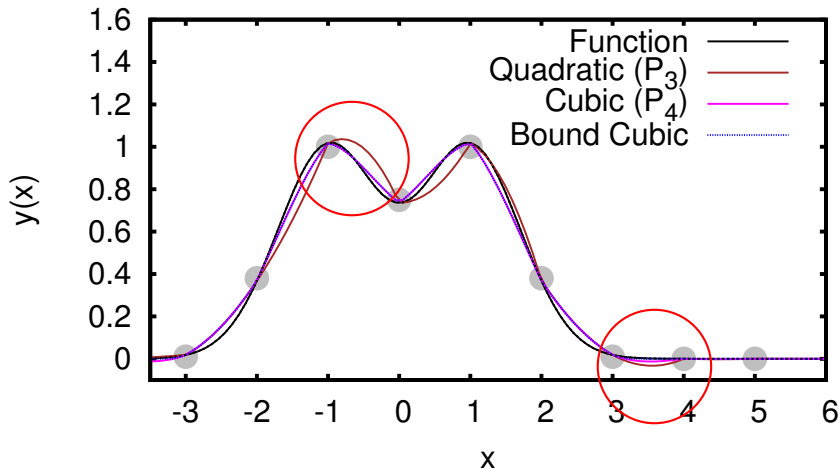
Cubic Interpolation



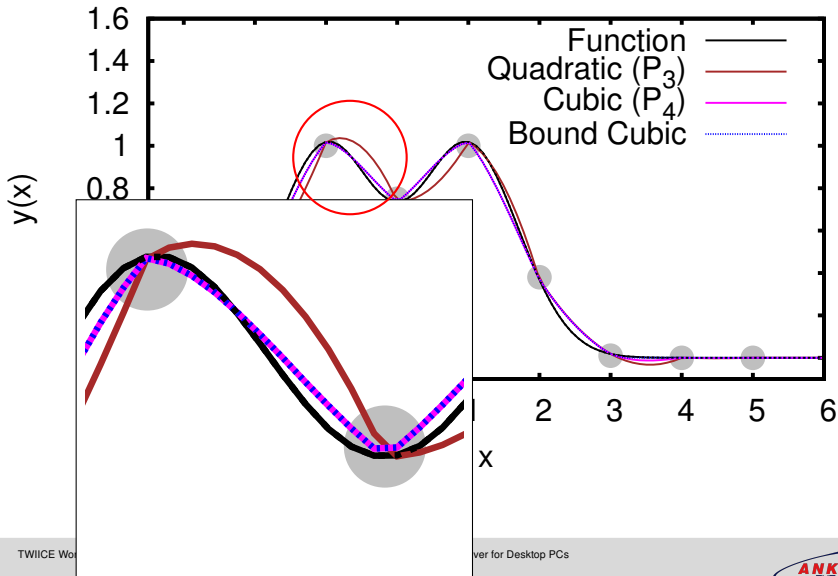
Over-/ Undershooting



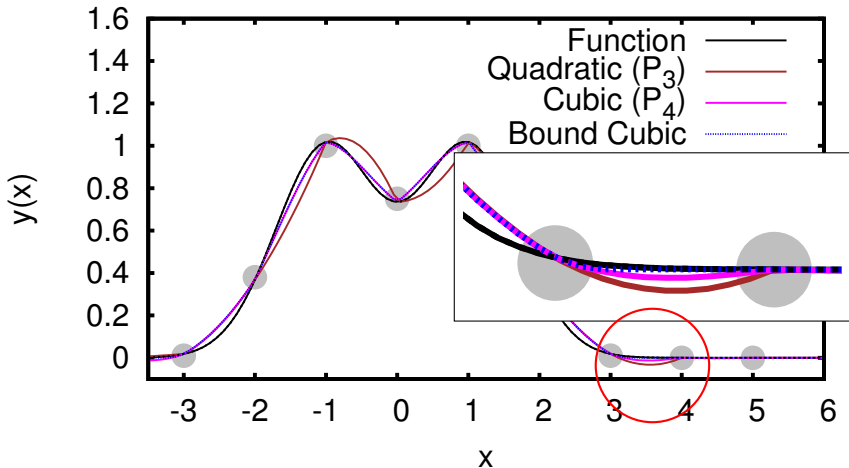
Over-/ Undershooting



Over-/ Undershooting

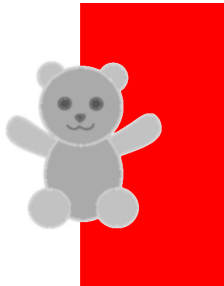


Over-/ Undershooting



Damping

- Damping reduces vertical size
- Integral is preserved
- Red background to improve contrast

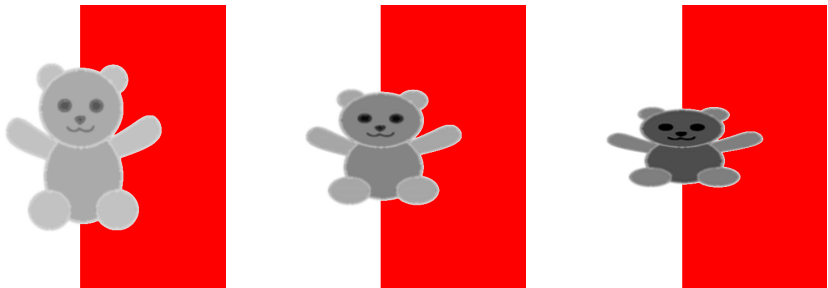


Damping



$$\left. \frac{\partial f(x)}{\partial x} \right|_{x=x_0} \approx \frac{f(x_0 + \Delta x) - f(x_0 - \Delta x)}{2\Delta x} \left(= \left. \frac{\partial P_3(x)}{\partial x} \right|_{x=x_0} \right)$$

Damping



$$\left. \frac{\partial f(x)}{\partial x} \right|_{x=x_0} \approx \frac{-2f(x_0 - \Delta x) - 3f(x_0) + 6f(x_0 + \Delta x) - f(x_0 + 2\Delta x)}{6\Delta x}$$

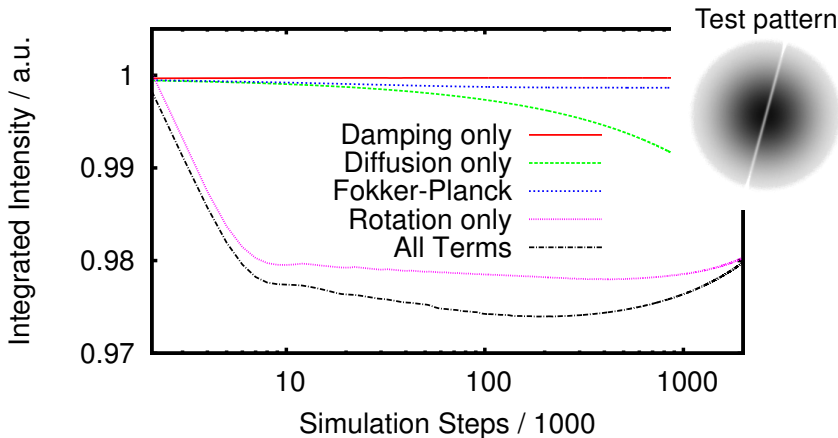
$$\left(= \left. \frac{\partial P_4(x)}{\partial x} \right|_{x=x_0} \right)$$

Diffusion



$$\left. \frac{\partial^2 f(x)}{\partial x^2} \right|_{x=x_0} \approx \frac{f(x_0 - \Delta x) - 2f(x_0) + f(x_0 + \Delta x)}{(\Delta x)^2}$$

Stability of Different Terms



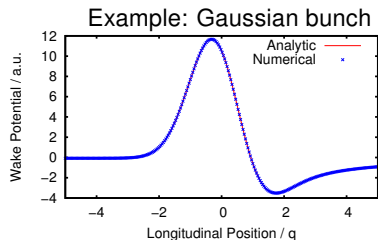
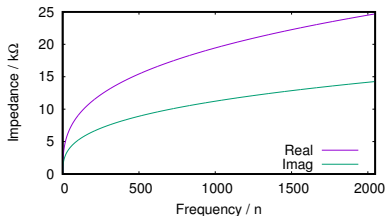
■ Interpolation leads to losses at sharp edges

■ Numerically stable state after 10 steps

Wake Potential – Frequency Domain

$$V_c(q, t) = \Re \left(\int_0^{\infty} dk Z(k) \int_{-\infty}^{\infty} dq' \rho(q', t) e^{-ikq'} e^{ikq} \right)$$

[Khan, 2006]



- Impedances known analytically
- All functions continuous
- Fourier transform algorithms are optimized

Benchmark: Convergence

- Arbitrary pattern
- Charge below instability threshold
- Expected to find physical equilibrium



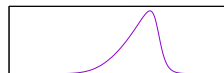
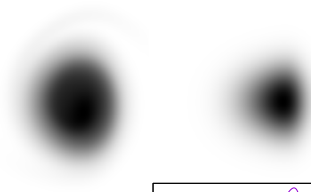
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Benchmark: Convergence

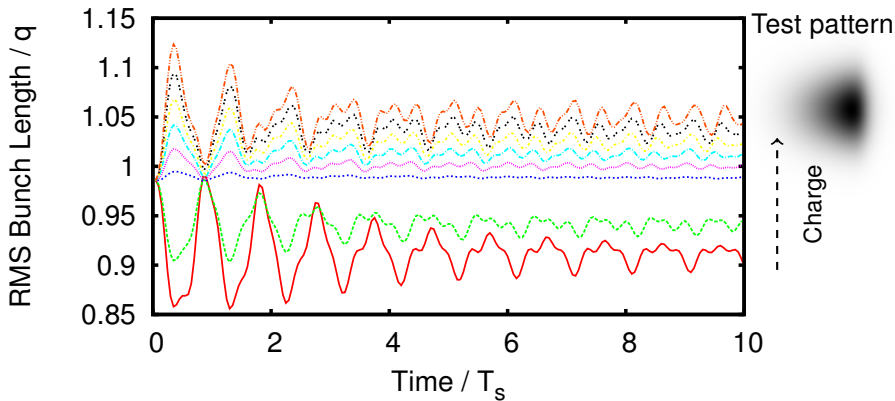
- Arbitrary pattern
- Charge below instability threshold
- Expected to find physical equilibrium ✓



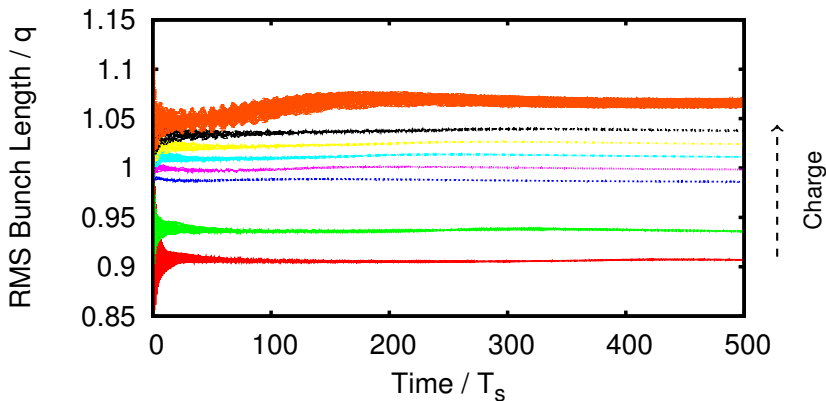
Haissinsky Distribution

Benchmark: Convergence

- Same starting distribution
- Varied bunch charge
⇒ different steady state



Benchmark: Convergence



■ Varied bunch charge
⇒ different steady state ✓

■ Microbunching not simulated
(no seed applied)

Benchmark: Computation Times

Benchmark Scenario

- 500 synchrotron periods
- 512×512 mesh points
- 4000 steps per period

CPU-time for different tasks

- 59% Synchrotron Oscillation
- 23% Collective Force
- 18% Damping and Diffusion

Non-optimized program: 222h53' (> 9 days)

Benchmark: Computation Times

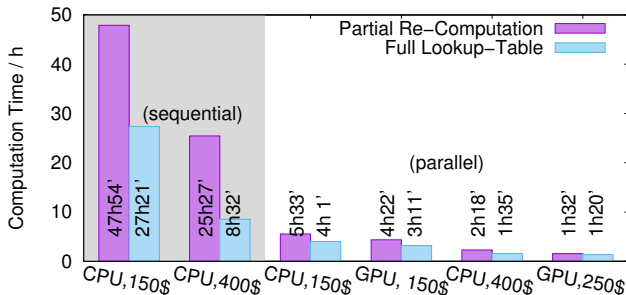
Benchmark Scenario

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Non-optimized program: 222h53' (> 9 days)



Acknowledgements

- **KIT THz-Team** (from IBPT, IMS, IPE, IPS and LAS):

M. Balzer, E. Blomley, A. Borysenko, M. Brosi, E. Bründermann, M. Caselle, C. Chang*, N. Hiller, S. Höniger, M. Hofherr, E. Huttel, K.S. Ilin, V. Judin*, B. Kehrer, M. Klein*, S. Marsching, Y.-L. Mathis, M.J. Nasse, G. Niehues, A. Plech, J. Raasch, P. Rieger*, L. Rota, R. Ruprecht, M. Schedler, A. Scheuring, P. Schönfeldt, M. Schuh, P. Schütze*, M. Schwarz, M. Siegel, N.J. Smale, B. Smit, J. Steinmann, P. Thoma*, S. Walter, M. Weber, S. Wuensch, M. Yan, and A.-S. Müller

**THz-Alumni*

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F. Caspers (CERN), S. Khan (DELTA), P. Peier, B. Steffen (DESY), H.-W. Hübers, A. Semenov (DLR), P. Kuske, G. Wüstefeld (HZB), V. Schlott (PSI), Y. Cai, J. Corbett, R. Warnock (SLAC), S. Bielawski, C. Evain, E. Roussel, C. Szwaj (U. Lille)

Summary

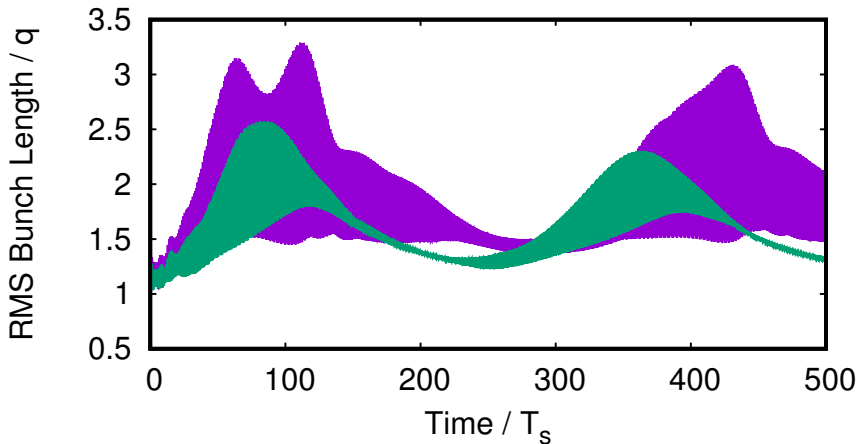
- Individually optimized terms to reduce artifacts
- Speedup of more than factor 150 (80 minutes instead of 9 days)
- Tested with free space CSR impedance
- Microbunching not simulated (no seed applied)
- Should be applicable for arbitrary impedances

Outlook

- Use other impedances than free space CSR
- Implement a seeding mechanism
- Maybe: Improve program latency/waiting times

Backup

Simulated Non-Equilibrium



Needed Accuracy

