Multicore Deployment Task Force report

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Alessandra Forti

Antonio Pérez-Calero Yzquierdo

Worldwide LHC Computing Grid



WLCG Multicore Deployment TF

Goals:

- Explore:
 - Multicore capabilities of local batch systems
 - Compatibility of approaches to multicore job distribution by different LHC Vos
- Produce guidelines for efficient multicore scheduling
- Get the sites to **run multicore** (together with VOs)

The multicore TF **period of higher activity** has been Jan-2014 to early 2015, well participated by sites (mainly from T1s) and experiments (ATLAS and CMS) representatives

Once **main objectives were achieved**, full deployment in charge of VOs, so the TF has been kept **open but in a latent state**

Full documentation:

Project twiki: https://twiki.cern.ch/twiki/bin/view/LCG/DeployMultiCore

CHEP2015 note: http://iopscience.iop.org/article/10.1088/1742-6596/664/6/062016/pdf

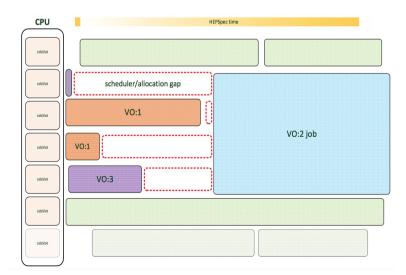
CHEP2015 slides: https://indico.cern.ch/event/304944/session/4/contribution/333/attachments/578522/796661/20150414-chep_mcore.pdf



Scheduling multicore jobs

Key problem: in order for a multicore job to start in a non-dedicated environment, a machine needs to be sufficiently *drained*

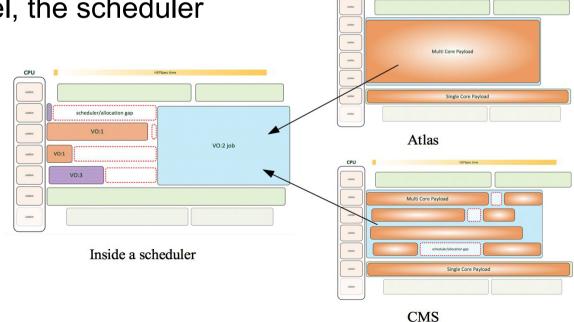
- Creating a multicore slot:
 - Prevent single core jobs from taking freed resources
 - draining = idle CPUs
- Conserving the multicore slot:
 - Higher priority single core jobs taking the resources, destroying mcore slots
 - wasted draining = need to start again
- Limiting draning:
 - As a protection of farm utilization
 - Slow ramp up of multicore jobs





Experiments submission models

- CMS and ATLAS are using different job submission models:
 - Both VOs still employ single core payloads together with multicore
- CMS:
 - moves the mixed scheduling inside the pilot
 - one pilot, multiple payloads
- ATLAS:
 - mcore and score in parallel, the scheduler does the job
 - one payload per pilot





With no backfilling available to reduce the draining penalty, reduce the level of draining to the required mcore job pressure and, once the cost of draining machines has been paid, avoid multicore slot destruction. **Recommendations**:

Experiments:

- Provide a continuous and stable supply of multicore jobs
 - vacated slots can be filled with new multicore jobs
 - avoid bursty submission patterns, which force the system to continue and re-adjust the level of draining
- Avoid short jobs, which increase the number of scheduling cycles, potentially leading to increased draining and wastage
- Different VOs should use a **common slot size** for shared sites.
 - the default value is **N_cores = 8**

Sites: Several techniques explored in the TF thanks to the contribution of participating Tier-1s

- Dynamic partitioning: Torque (Nikhef, PIC), LSF (CNAF)
- Dynamic scheduling with preferential mcore treatment and adaptable draining: HTCondor (**RAL**)
- Dynamic scheduling with capacity to limit the number of drained slots: SGE (**KIT**)
- Static partitioning not favored or recommended

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Passing parameters to the BS

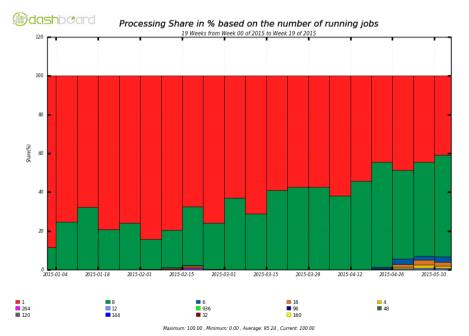
- Multicore TF has also investigated the submission chain, from brokering to kernel for the resource request parameters
 - Main interest from ATLAS
 - An agreement of what parameters should be used in each case has been reached (details in backup slide)
- Status:
 - ATLAS is enabling brokering and passing the parameters to the batch system
 - In particular RSS and walltime values
 - Cputime and vmem are considered at best not useful and at worst harmful.
 - Not in current CMS model: payload scheduling is performed inside the glideinWMS multicore pilots, not at the Batch System



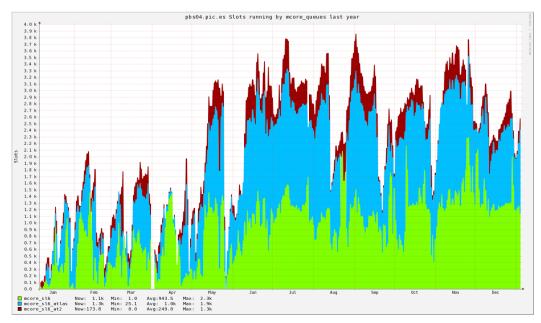
Results

- Main result: successful deployment and utilization of multicore resources
- Increased expertise of the community: sites and experiments

ATLAS jobs by Ncores (first months of 2015)



Mixed utilization of PIC CPUs for multicore by CMS and ATLAS (2015)





Main question

- The task force is currently open but inactive, having achieved the main goals
- **Specific tasks** in the hands of the experiments
 - CMS deployment to T1s complete but deployment to T2s ongoing
 - Effort on passing parameters for ATLAS model lead by the VO
- LHCb moving to multicore:
 - LHCb own multicore submission model to consider pros and cons understood from the comparison of the ATLAS and CMS models
 - Deployment to LHCb sites profit from TF experience

Should the task force continue open or be closed?

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Memory from brokering to kernel

Parameters table

	corecount	rss	rss+swap	vmem (address space)	cputime	walltime									
Torque/maui	ppn	mem	-	vmem	cput	walltime									
GE	-pe	s_rss	-	s_vmem	s_cpu	s_rt	https	://twi	ki.ceri	n.ch/twi	ki/bi	in/view	/LC(G/BSPas	singParame
UGE 8.2.0(*)	-pe	m_mem_free	h_vmem	s_vmem	s_cpu	s_rt	•								•
HTCondor(**)	RequestCpus	RequestMemory	No default (Recipe)	No default (Recipe)	Recipe	Recipe									
SLURM	ntasks,nodes	mem-per-cpu	-	No option	No option	time									
LSF	?	?	?	?	ř.	?	Experiments	corecount		rss+swap	vmem	cputime	walltime	comment	
	support enabled s a HTCondor ba		parameters which mail	ke it simpler			ALICE	•	-		-		•	-	
Vhat really hap	opens with the I	memory? i.e. what		So far it seems we can limit	only the ad	ress space if	ATLAS current	corecount	maxmemory	maxmemory	•	maxtime*ncores			
Batch system	rss rss+	swap vmem		do sensible things			ATLAS future	corecount	maxrss	maxrss+maxswap	•	maxtime*ncores	maxtime	maxrss+maxswap rea	lly usable only by cgroups enab
Torque/maui		RLIMIT_AS					CMS			•	•	•	-	-	
*GE	• •	RLIMIT_AS					LHCb	-						-	
UGE >=8.2.0	yes yes	RLIMIT_AS													
HTCondor SLURM	yes in 8.3		yes				\								
		- 1.1 RUMIT AS	yes Ves				\mathbf{N}								
LSF	in 9.1.1 in 9.		,				\mathbf{i}								
		1.1 RLIMIT_AS	,		rss+s	wap			vmem			cputime			walltime
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Experiments

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