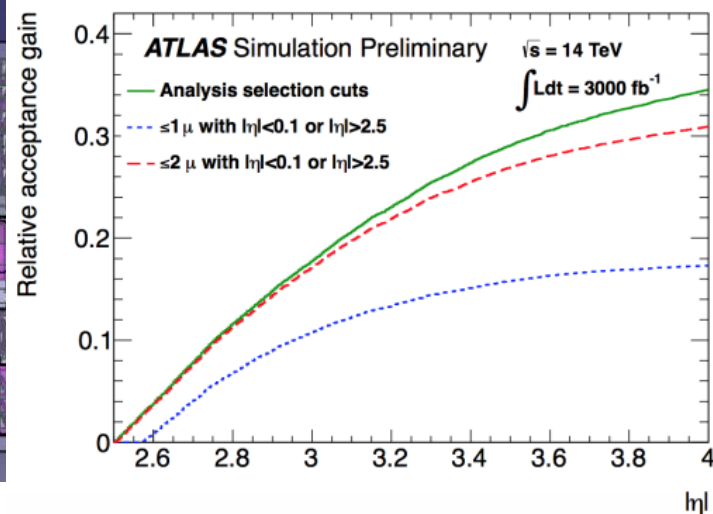
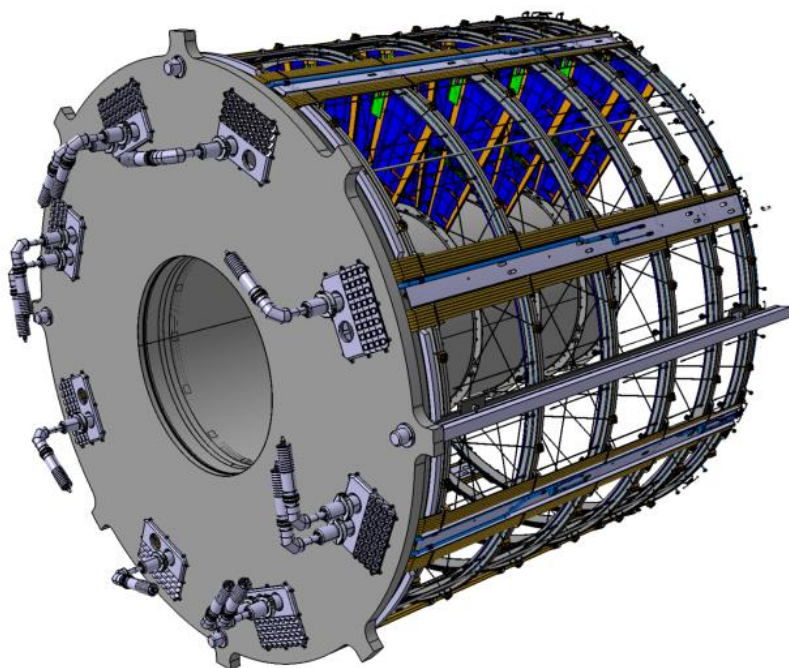
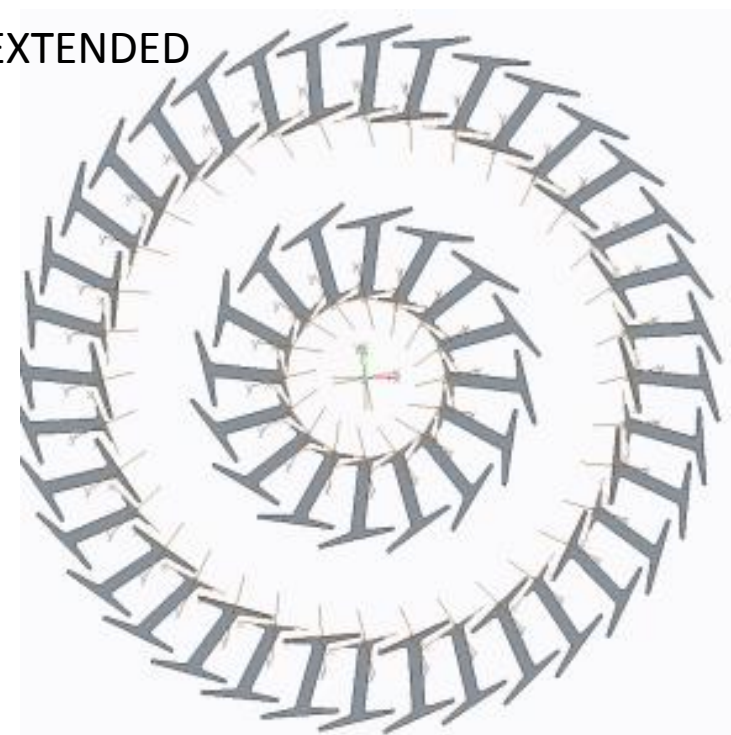


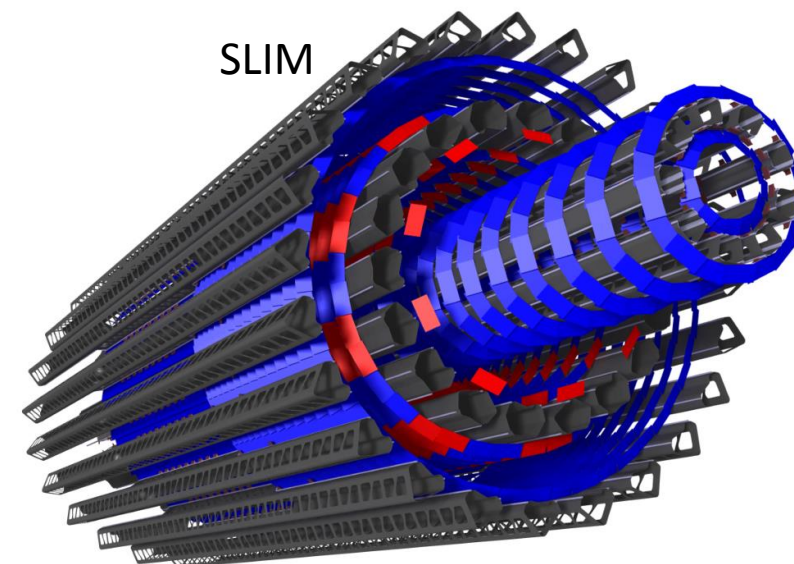
ALPINE



EXTENDED



SLIM



The Layout of the ITk

S. McMahon

RAL/Oxford

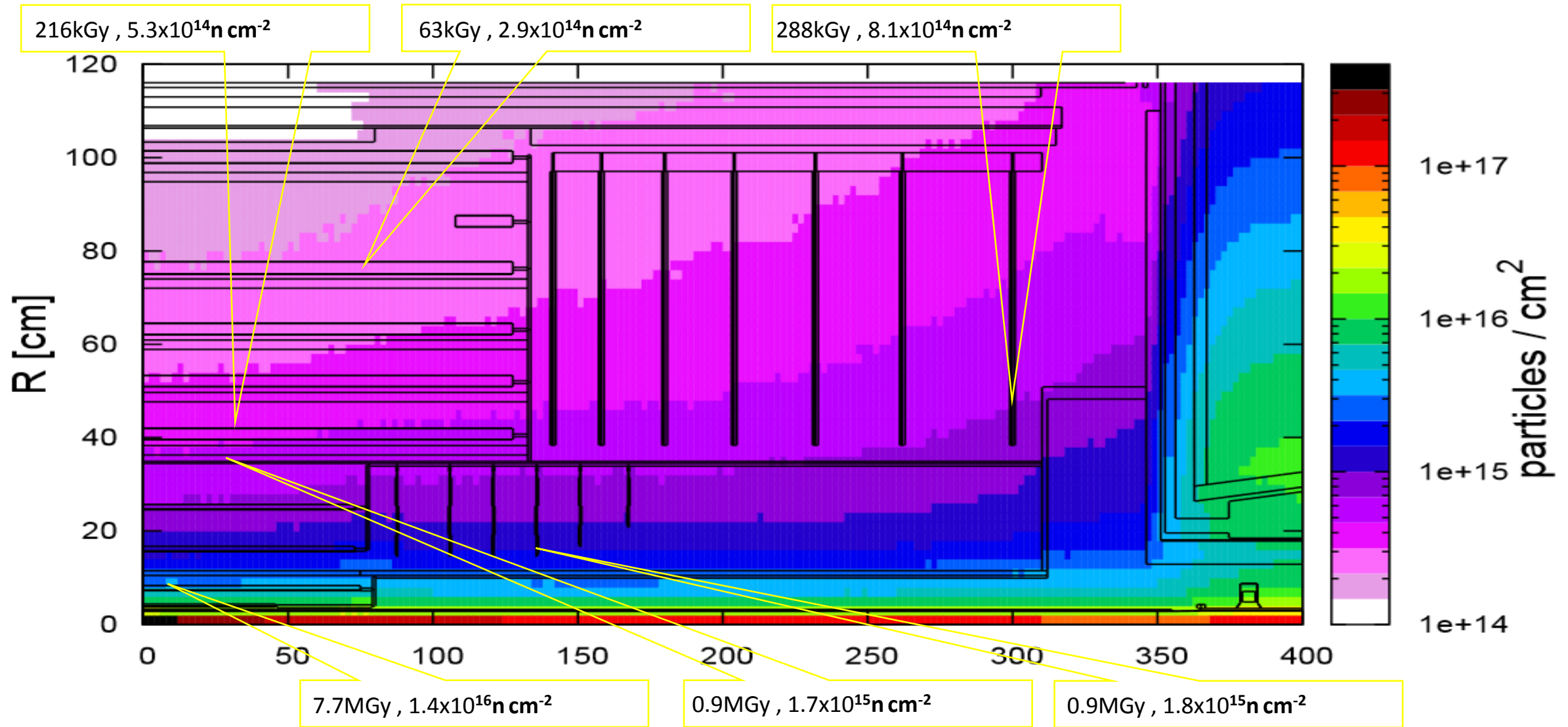
on behalf of the ITk project

ACES, CERN, 9th March 2016

Requirements for phase II tracker

- Record a total integrated luminosity of $3,000 \text{ fb}^{-1}$
 - Places stringent requirements on the radiation tolerance of components (particularly sensors).
 - $2 \times 10^{15} \text{ 1MeV } n_{\text{eq}}/\text{cm}^{-2}$ for strips and 10 times this for pixels, TID of 1 GRad
- Maximum instantaneous luminosity of $7.5 \times 10^{34} \text{ cm}^{-2}\text{s}^{-1}$ ($\langle \mu \rangle \sim 200$)
- Reconstruct vertices of pile-up events & associate vertex with the hard scatter
- Identify secondary vertices in b-jets with high efficiency and purity
- Measure the tracks in the cores of high energy jets with high efficiency
- Ensure a low rate for reconstruction of fake tracks
- Reconstruct the tracks associated with converted photons
- Be able to reconstruct and trigger on tracks out to the largest pseudo-rapidity
- Minimize the inactive material in the detector volume
- Input to a track trigger run at Level-1 (talk by Nikos yesterday)

ITk - Radiation Fluences : 1 MeV n_{eq} cm^{-2}



Simulations with FLUKA to 3,000 fb⁻¹

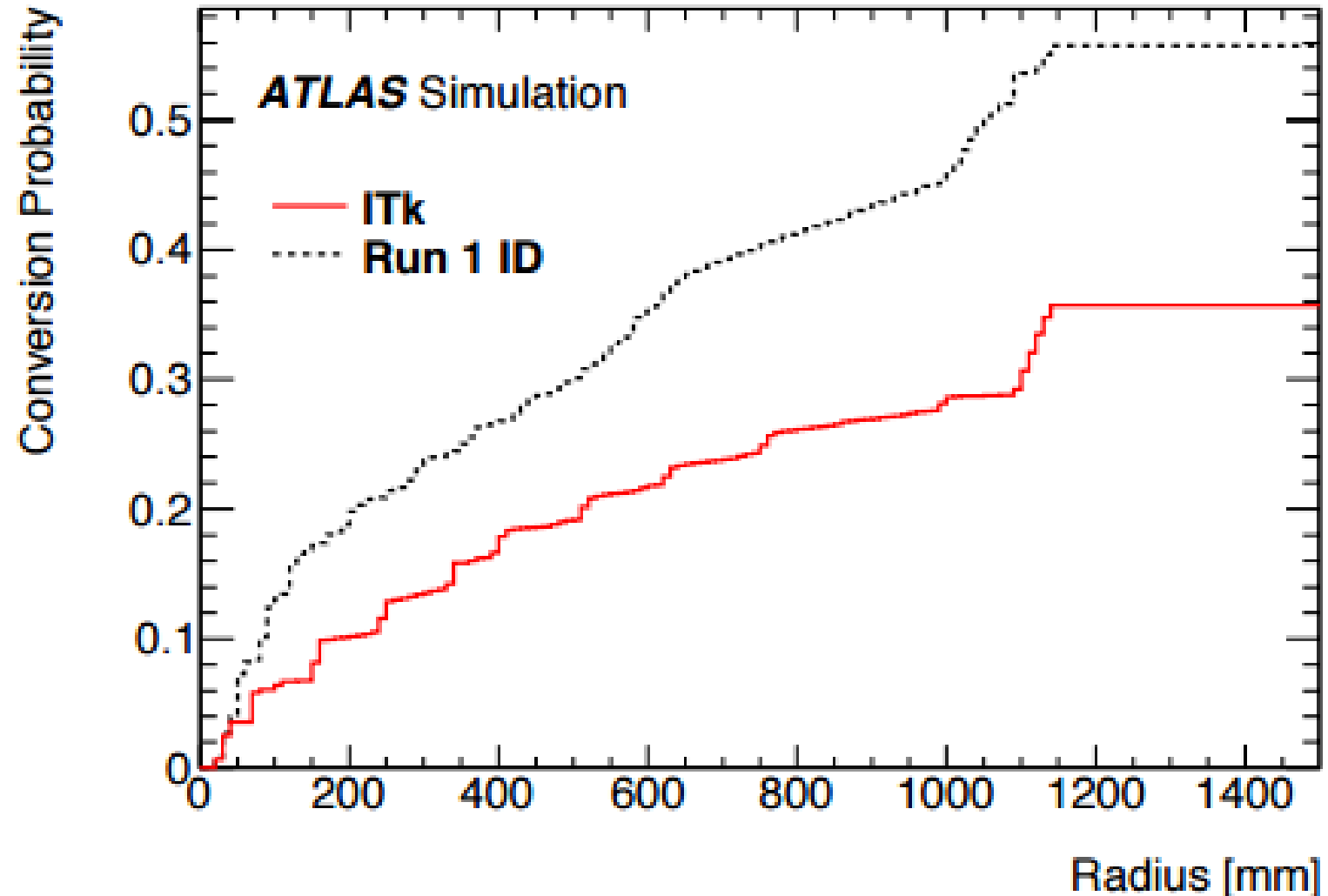
McMahon : Layout of the ITk; ACES 16

ITk Design builds on experience with existing tracker

- However,
 - The pattern recognition, tracking reconstruction and performance requirements at Phase II are more challenging
 - The ITk will be an all silicon design and extend to higher rapidities
 - It will be more radiation tolerant
 - It might use new sensor technologies possibly including CMOS/MAPS (talk by Tobias)
 - It will use lower power electronics (130nm GF-strips and 65nm TSMC-pixels, Alex, Tobias)
 - Exploit DC-DC and Serial Powering for Front-End electronics (talks Laura and Peter yesterday)
 - HV multiplexing (talk by Peter yesterday)
 - Challenges in data transmission at low mass (talk by Martin yesterday)
 - More efficient use of higher bandwidth optical links
 - It will use CO2 cooling (new environmental challenges)
 - ***Lower mass construction***
 - It will use new readout technologies and architecture
 - It has to be installed differently
 - The access and maintenance constraints are more challenging
 - ...

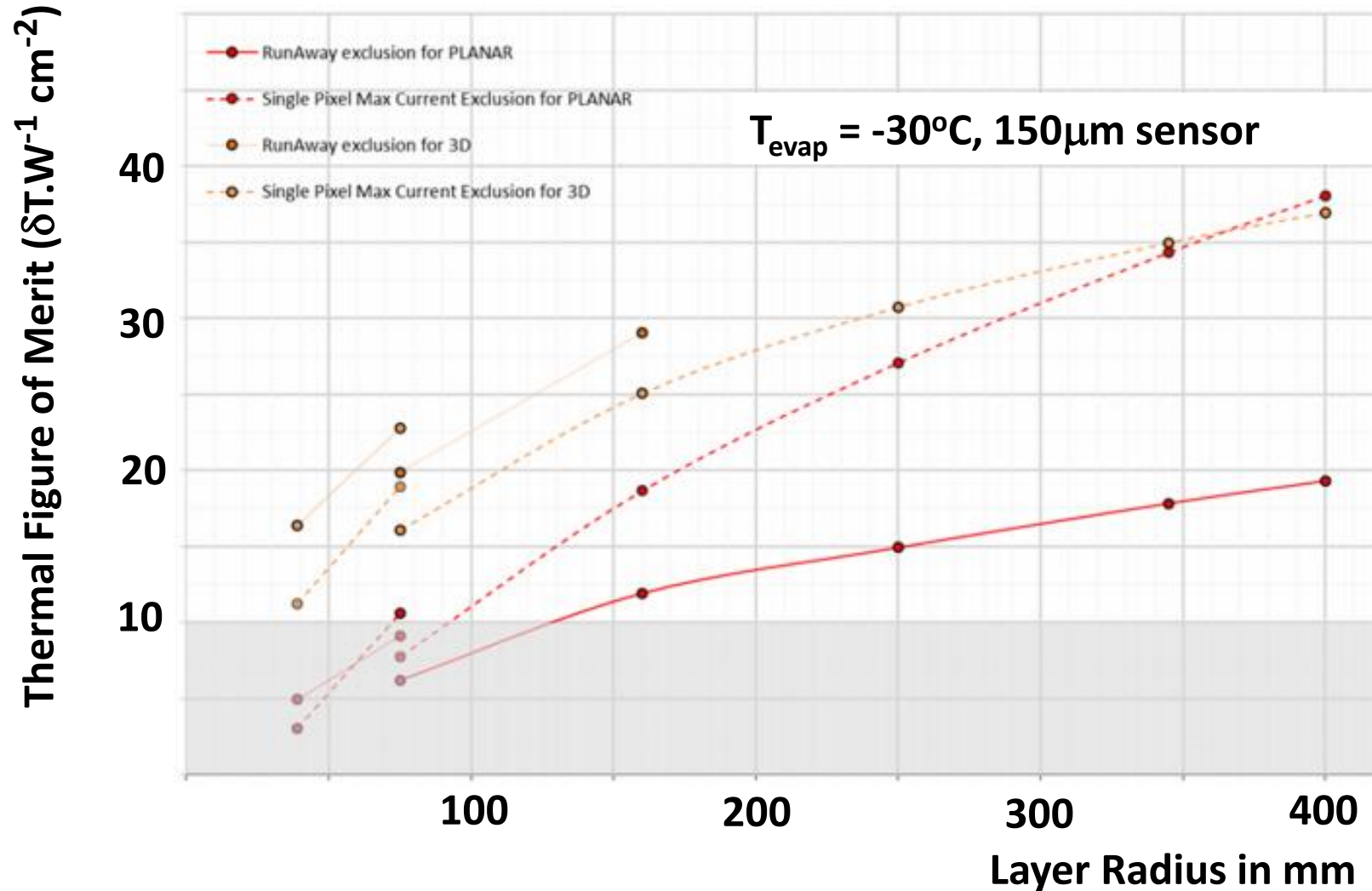
ITk Design builds on experience with existing tracker

- However,
 - The pattern recognition more challenging
 - The ITk will be an all silicon
 - It will be more radiation
 - It might use new sensor
 - It will use lower power
 - Exploit DC-DC and Serial
 - HV multiplexing (talk by)
 - Challenges in data trans
 - More efficient use of hig
 - It will use CO2 cooling (i
 - ***Lower mass constructio***
 - It will use new readout t
 - It has to be installed diff
 - The access and mainten
 - ...



Detector Challenges: cooling at small radius...

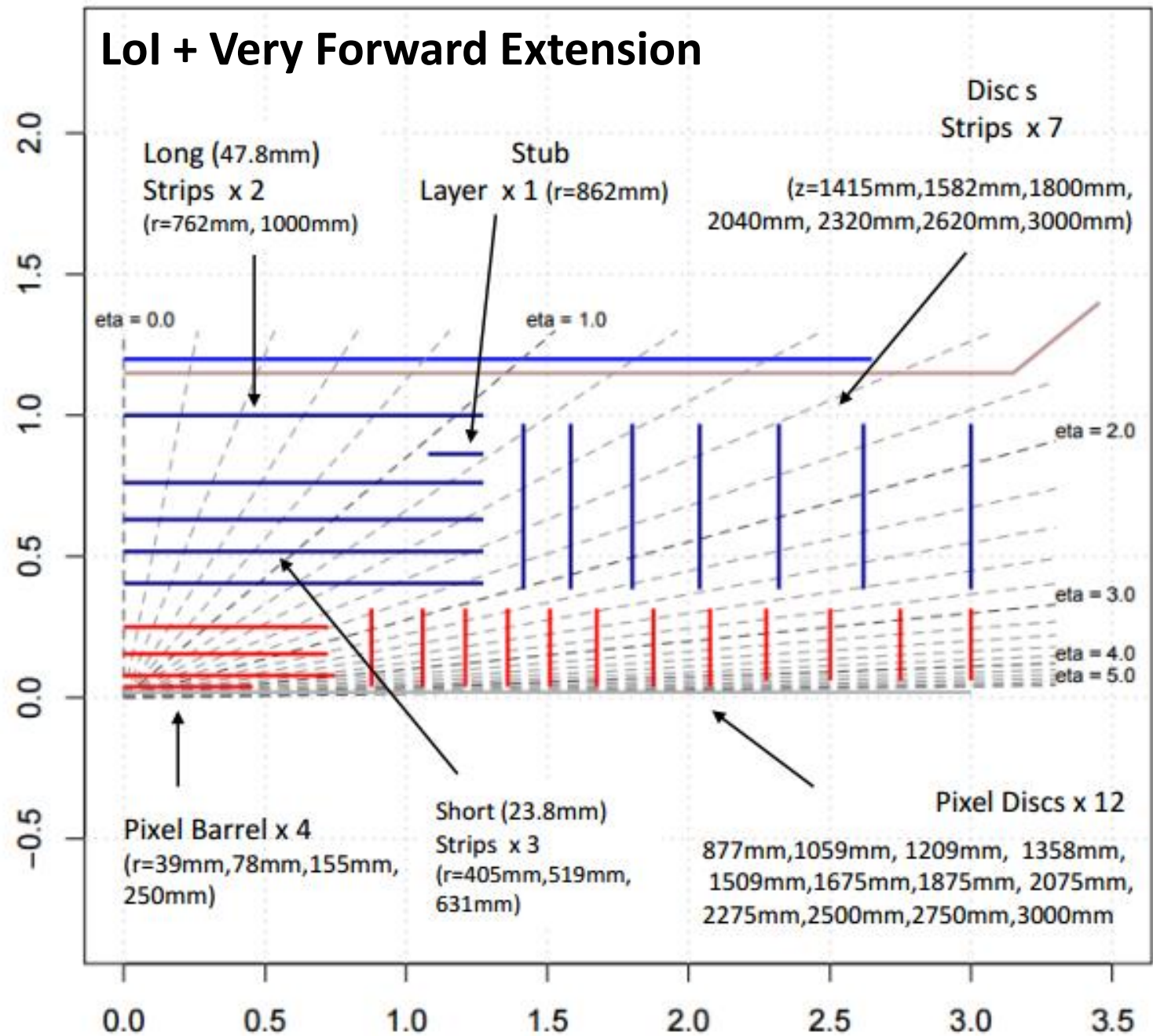
Bad
↑
↓
Good



Evolution of ITK including layouts

- Phase II - Letter of intent (December 2012)
<http://cds.cern.ch/record/1502664?ln=en>
- ATLAS ITk Initial Design Report (Internal-October 2014)
Internal
- ATLAS Scoping document (September 2015)
<https://cds.cern.ch/record/2055248?ln=en>
Cost vs performance of tracker studied in detail
Compare 3 tracking detectors

The refered tracking detector presented in the scoping document : <https://cds.cern.ch/record/2055248?ln=en>



Motivations for the extension in acceptance

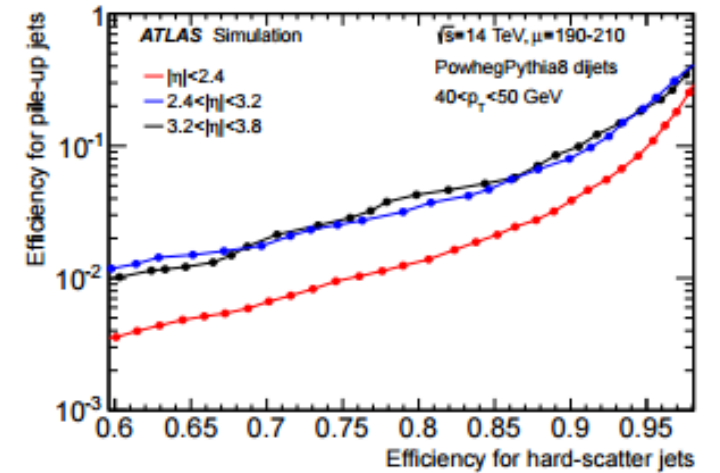
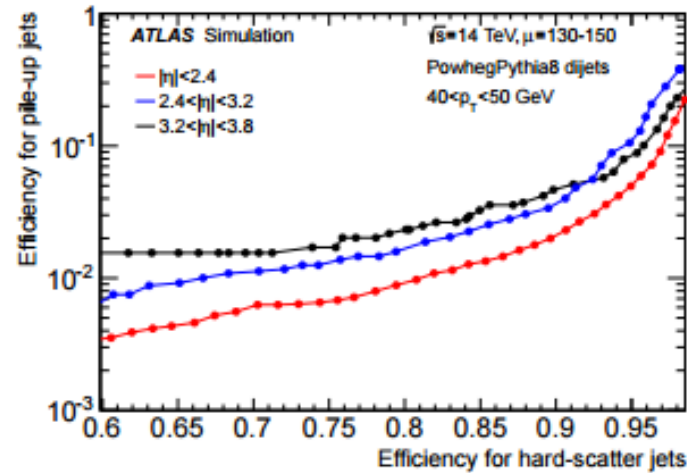
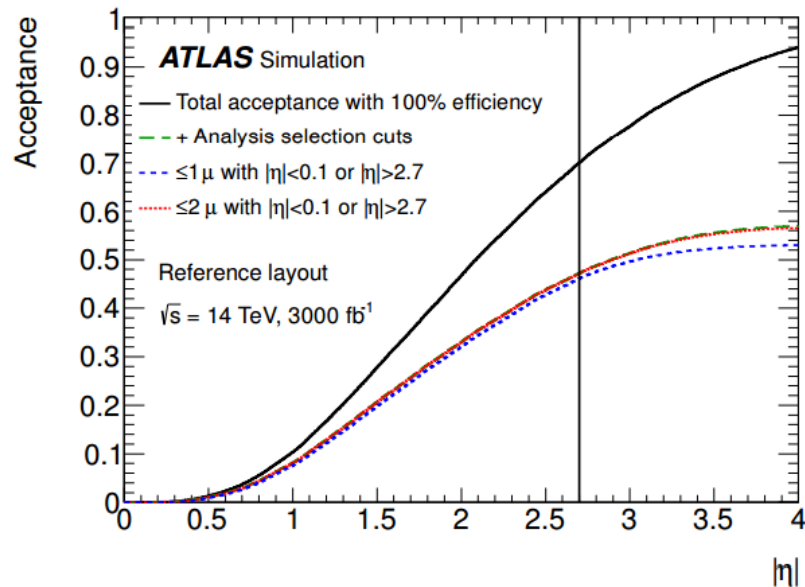
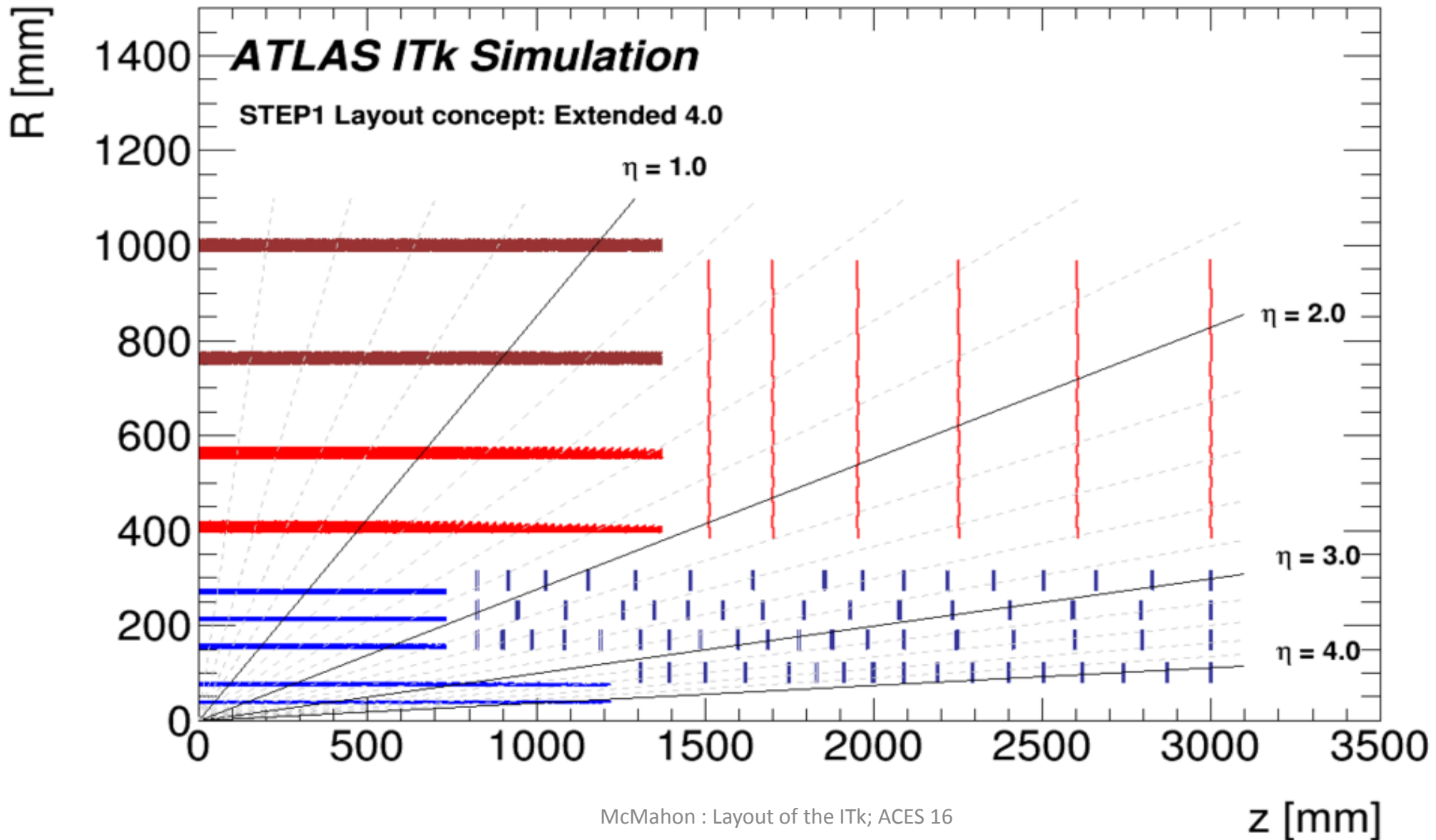
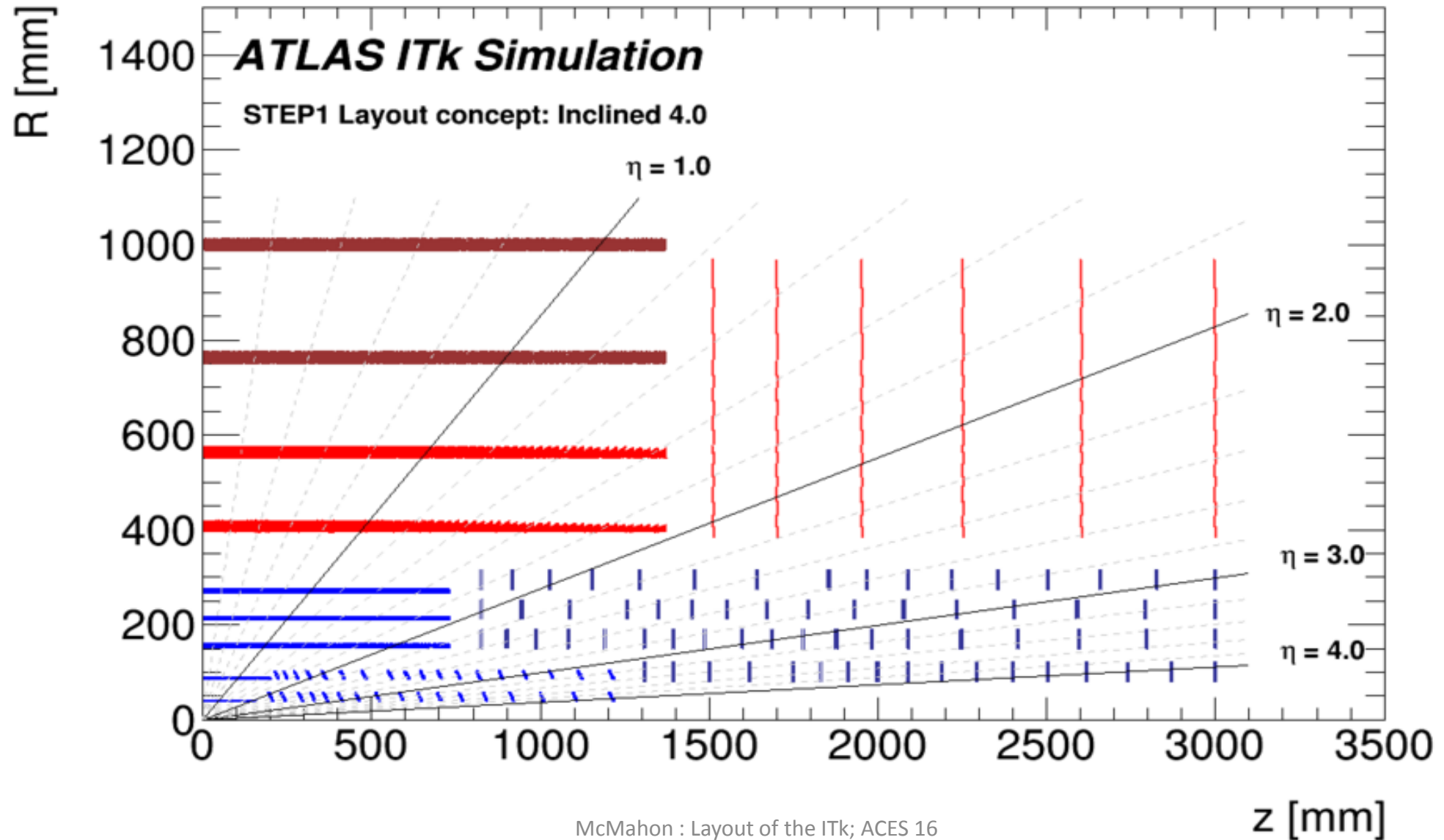


Figure 87. The efficiency for pile-up jets as a function of the efficiency for hard-scatter jets with $40 < p_T < 50 \text{ GeV}$ using a track-matching algorithm for $\mu = 140$ (left) and $\mu = 200$ (right). The algorithm can be applied in $|\eta| < 2.4$ the Low scenario, $|\eta| < 3.2$ in the Middle scenario and $|\eta| < 3.8$ in the Reference scenario.

New Layouts : Extended 4.0 (3.2 also under study)



New Layouts : Inclined 4.0 (3.2 also under study)



ITk Strips

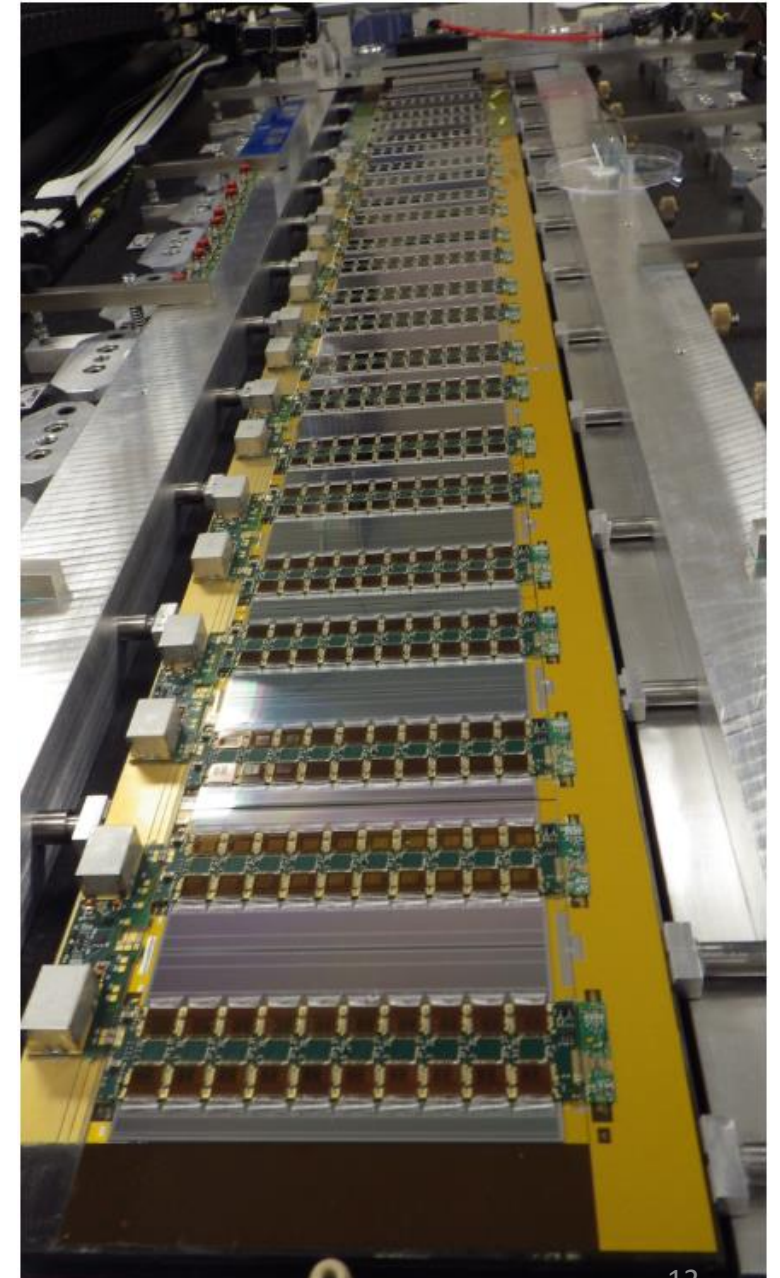
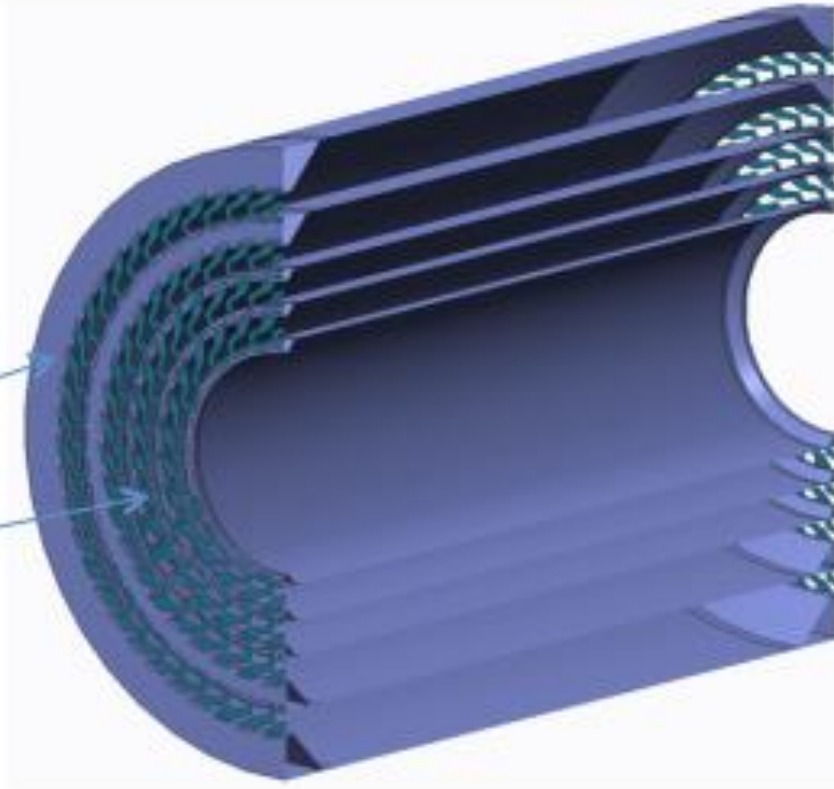


Barrel support points

Barrel end flange
(size varies)

Interlinks, one per
stave all identical

Barrel reinforcement
rings not shown



See talk by Alex Grillo later this morning

McMahon : Layout of the ITk; ACES 16

ITk Strips

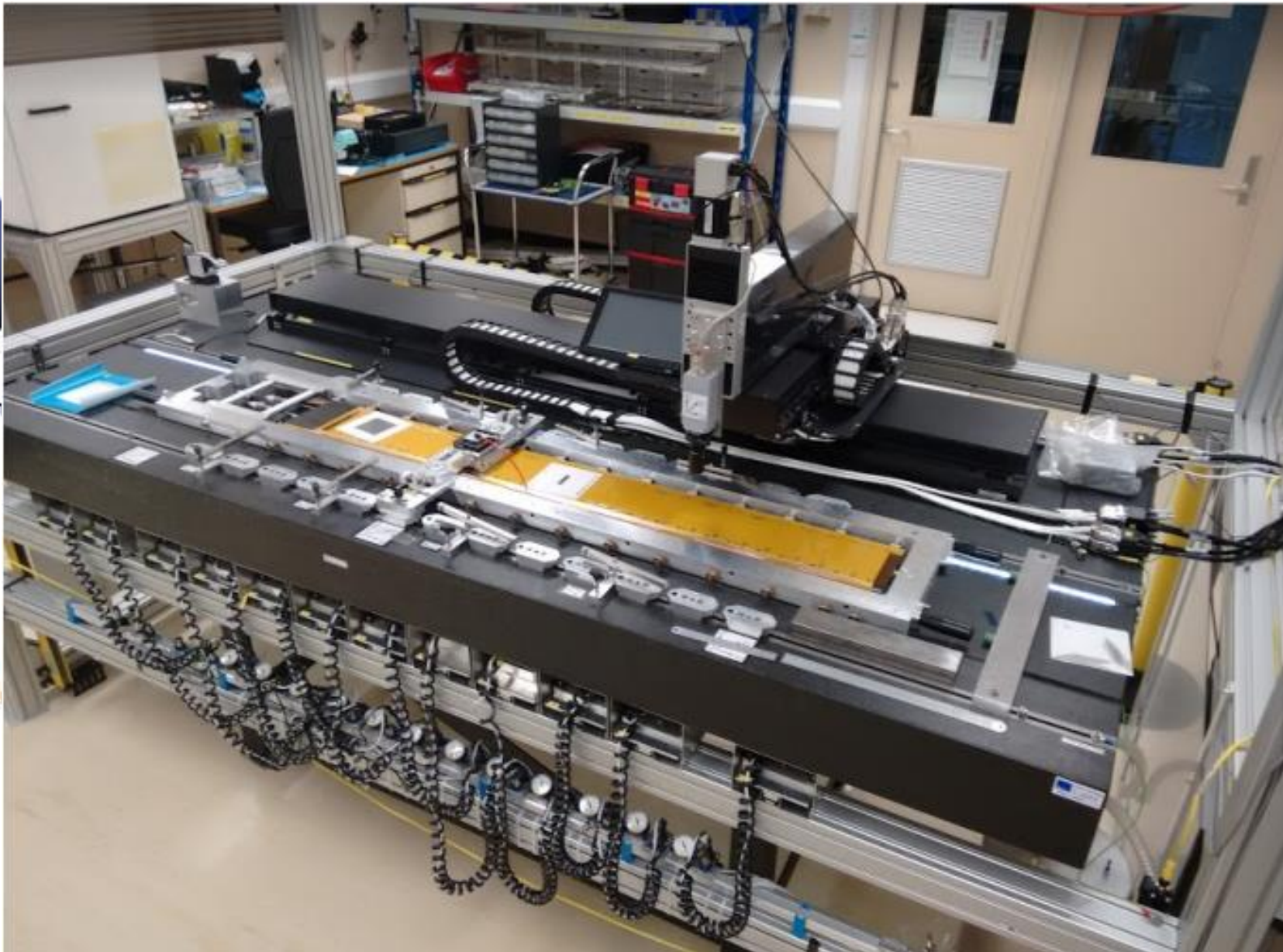


Barrel support point

Barrel end flange
(size varies)

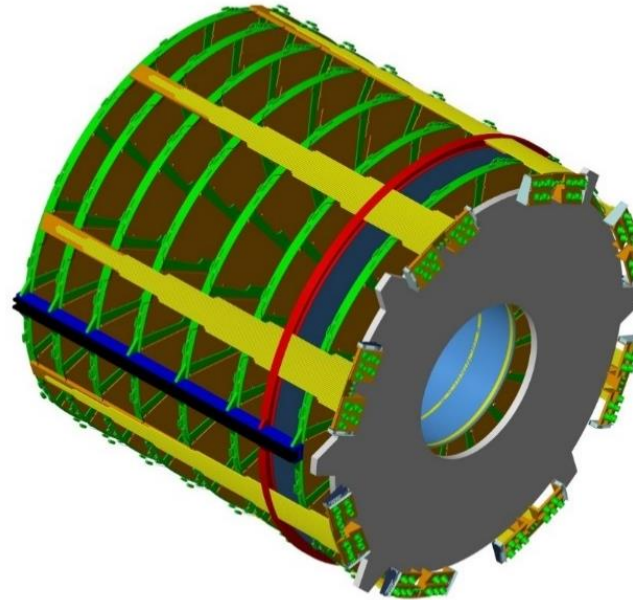
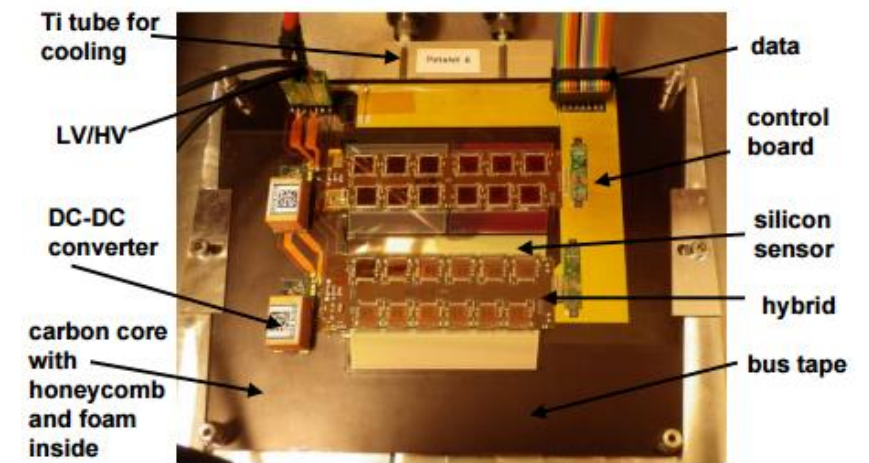
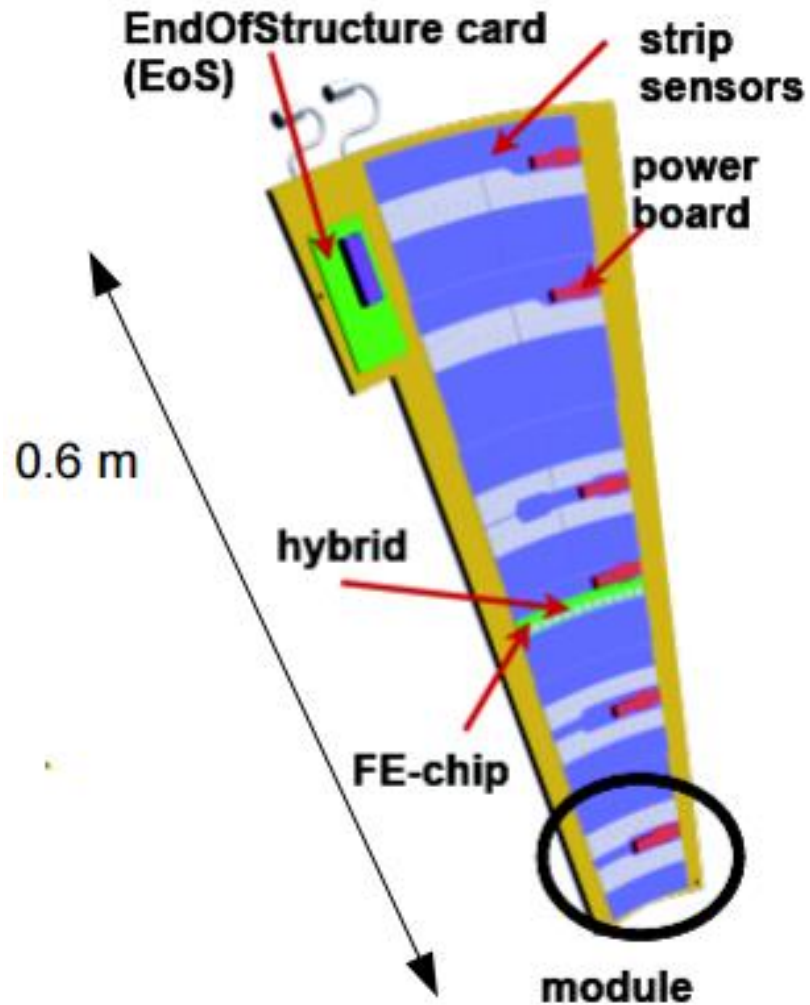
Interlinks, one per
stave all identical

Barrel reinforcement
rings not shown

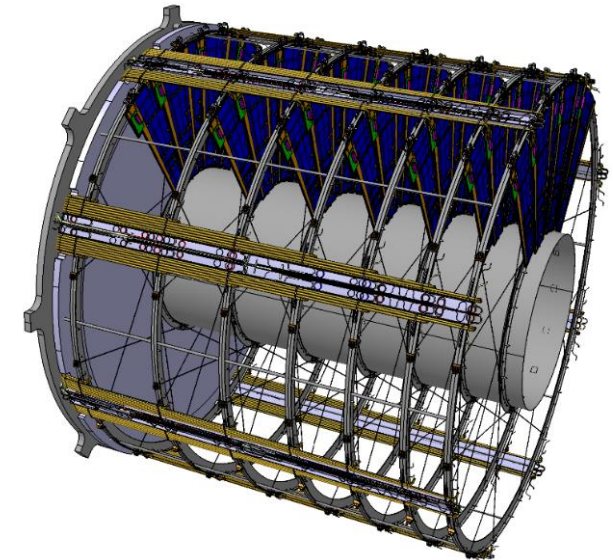


See talk by Alex Grillo later this morning

ITk Strips



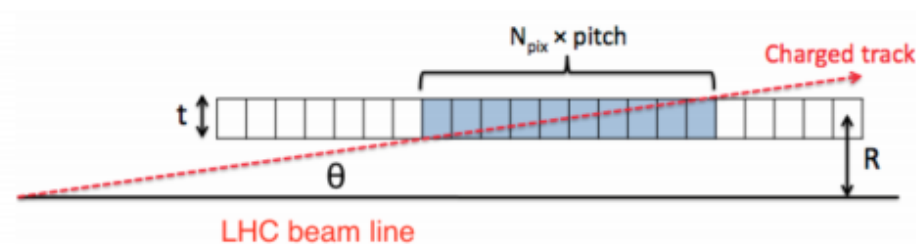
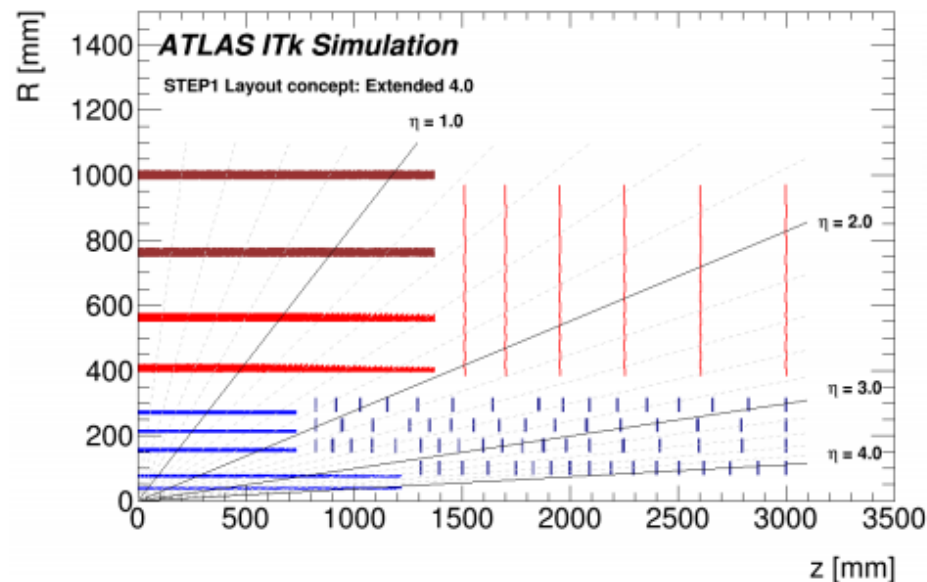
CF blades are single units.
CF structure to hold blades.



CF wheels with spokes are single units.
Wheels are put on inner tube.
Petals are mounted on wheels.

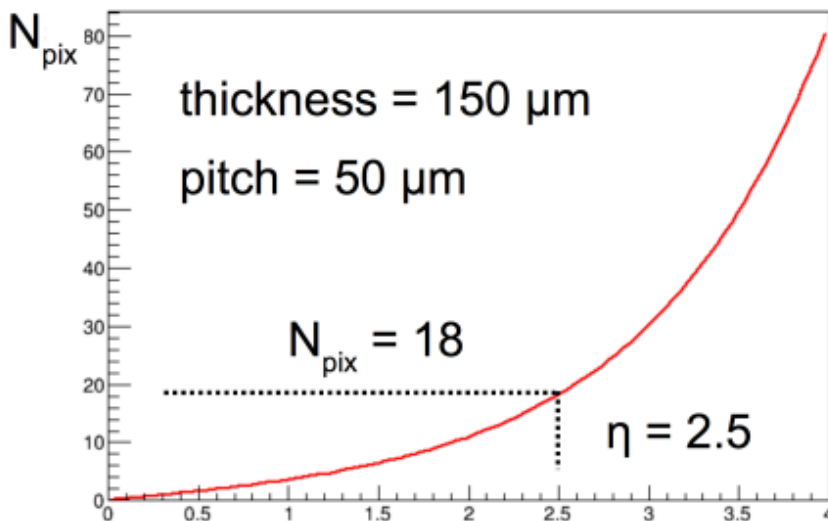
See talk by Alex Grillo later this morning

The Extended Pixel Barrel Option



$$\tan \theta = \frac{t}{(N_{pix} - \delta) \times p}, \quad \delta \approx 1$$

- **Main idea:** long clusters = “tracklets”, providing initial precise estimates of θ and z_0
 - Seed pattern recognition
 - Potential to reduce fake rate
 - Potential to reduce CPU time



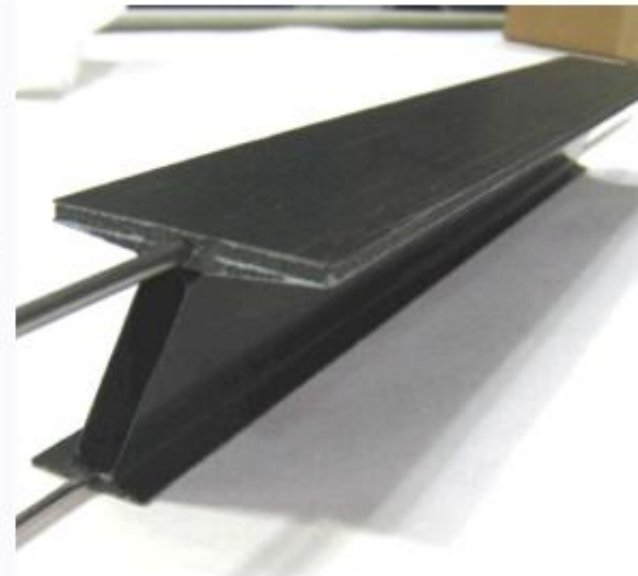
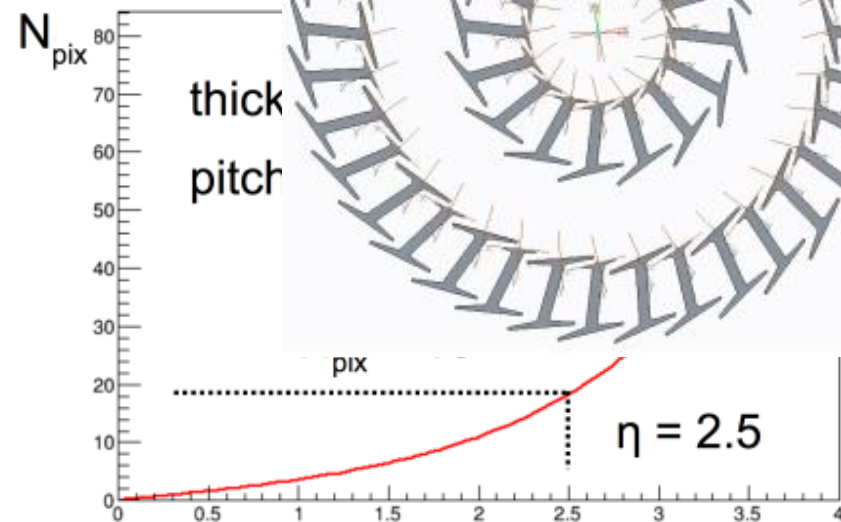
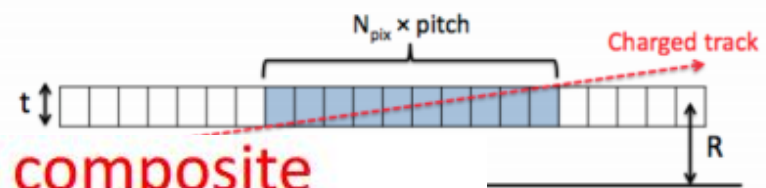
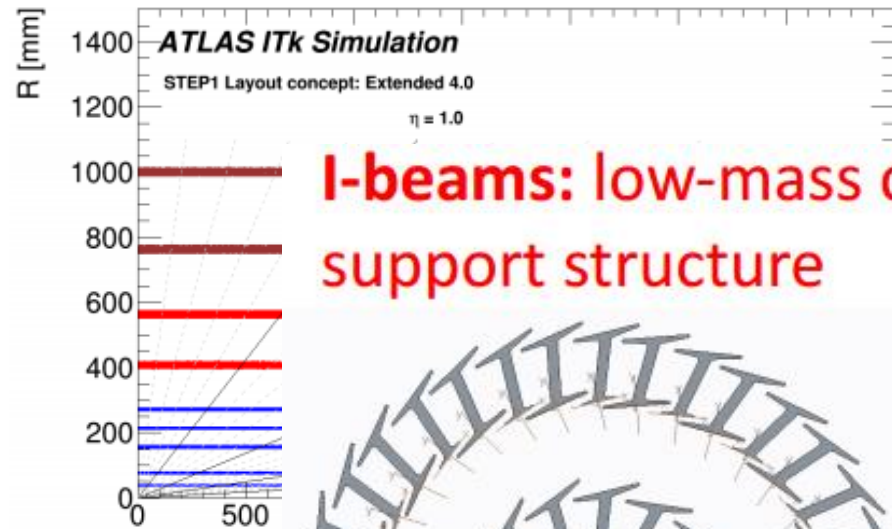
Basic information about sensors:

Barrel Layer-0,1 & inner end-cap ring: 50×50×100 μm^3

Barrel Layer-2,3,4 & end-cap: 50×50×150 μm^3

Courtesy Sasha Pranko

The Extended Pixel Barrel Option



≈ 1
"tracklets",
timates of θ

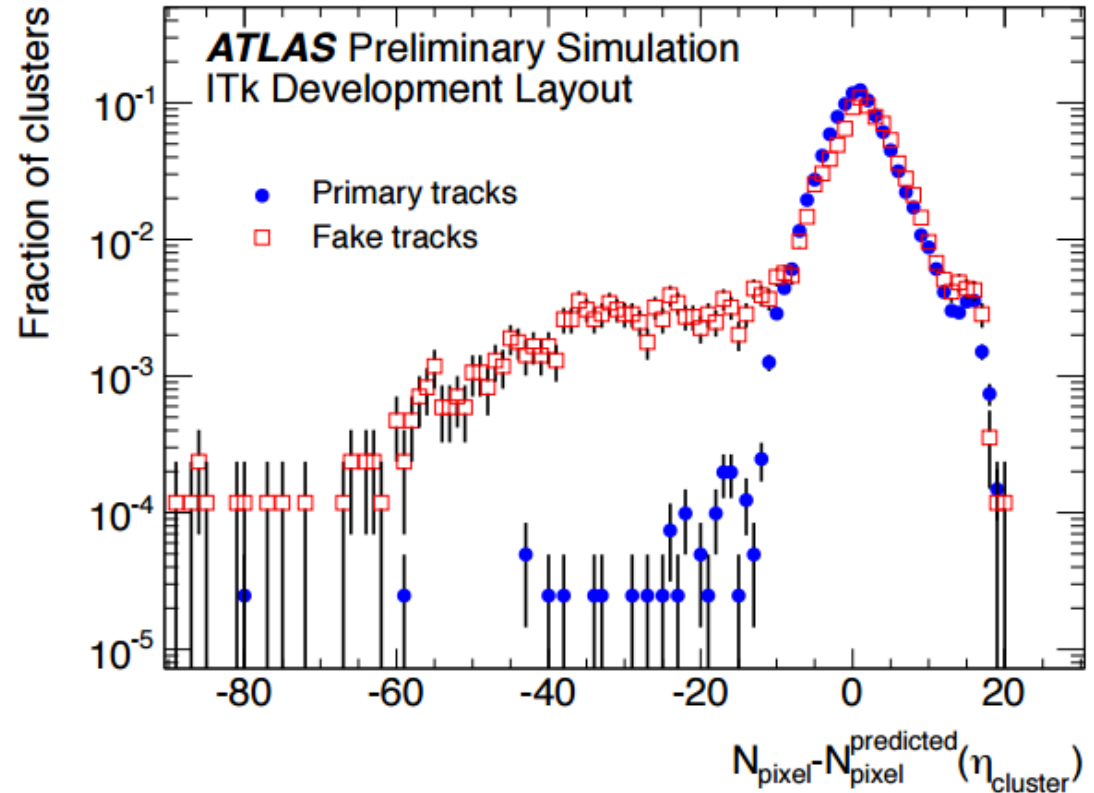
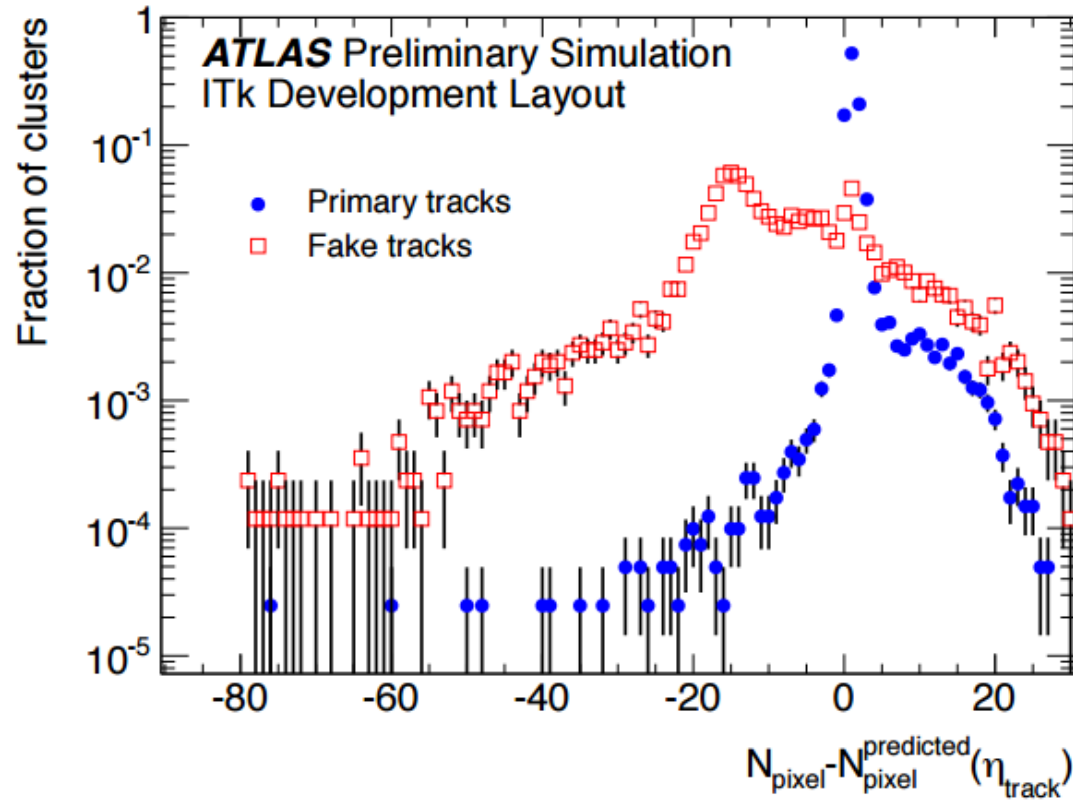
rate
time

$0 \times 50 \times 100 \mu\text{m}^3$

Barrel Layer-2,3,4 & end-cap: $50 \times 50 \times 150 \mu\text{m}^3$

Courtesy Sasha Pranko

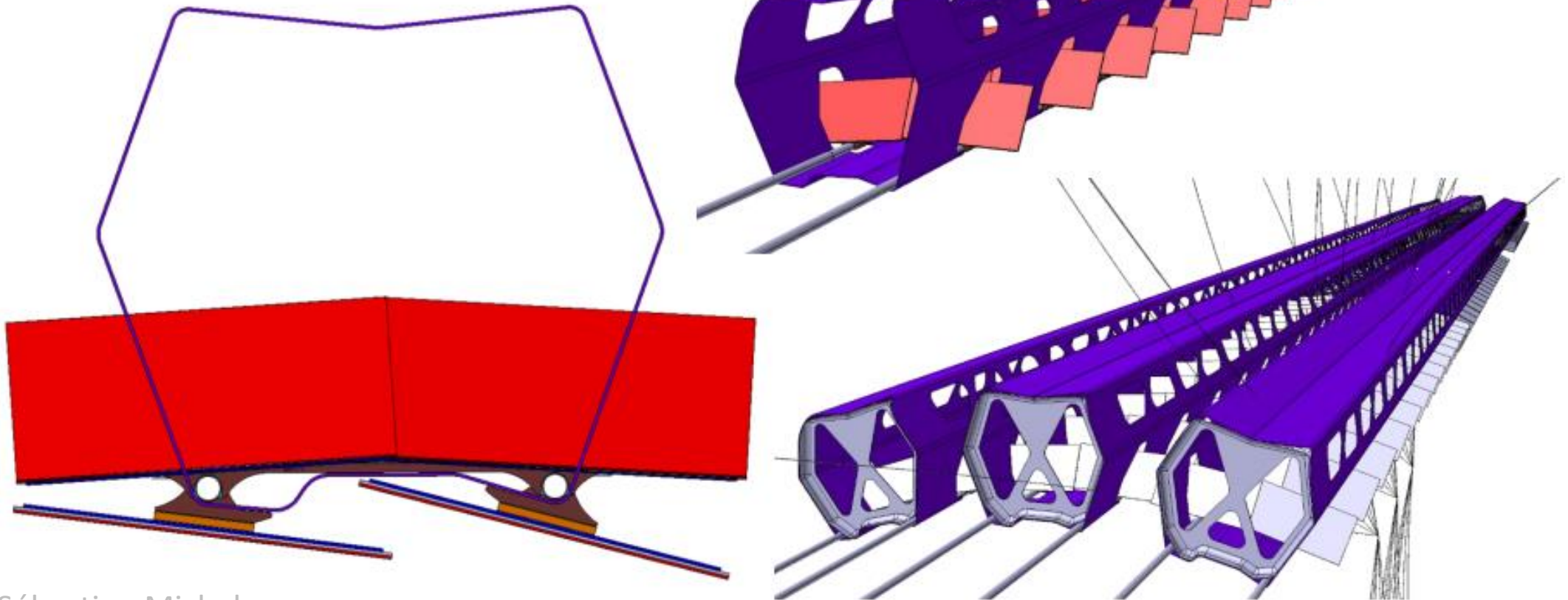
The Extended Pixel Barrel Option



Courtesy Sasha Pranko

Inclined Sensor Option for Pixels: SLIM

- Single skin CFRP 0.325 mm thick [0, 45, 90, -45, 0]
- 2 meters long (5th layer)
- ~180 gr CFRP skin



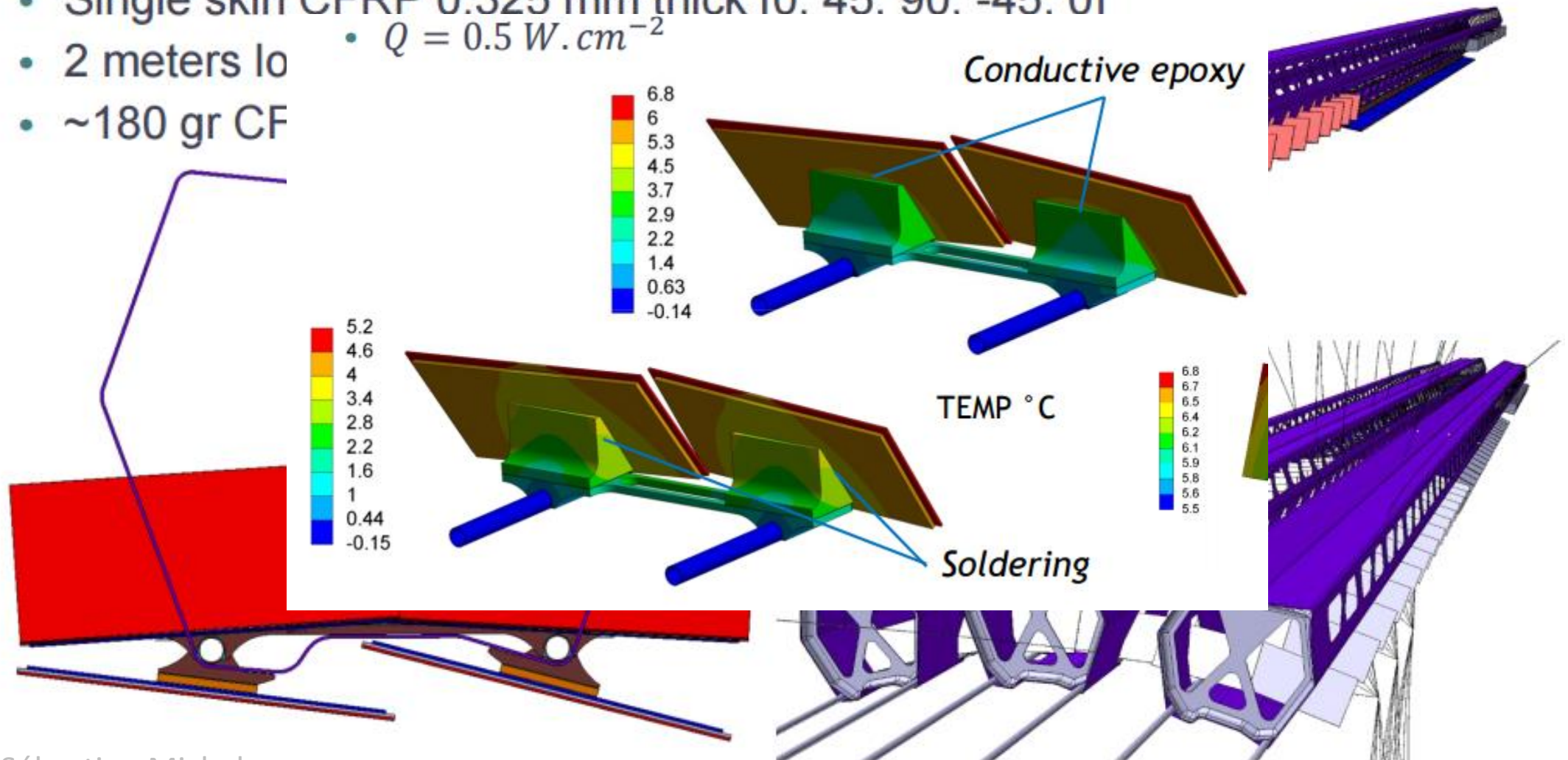
Courtesy Sébastien Michal

McMahon : Layout of the ITk; ACES 16

Inclined Sensor Option for Pixels: SLIM

- Single skin CFRP 0.325 mm thick [0. 45. 90. -45. 0]
- 2 meters long
- ~180 gr CF

$$Q = 0.5 \text{ W.cm}^{-2}$$



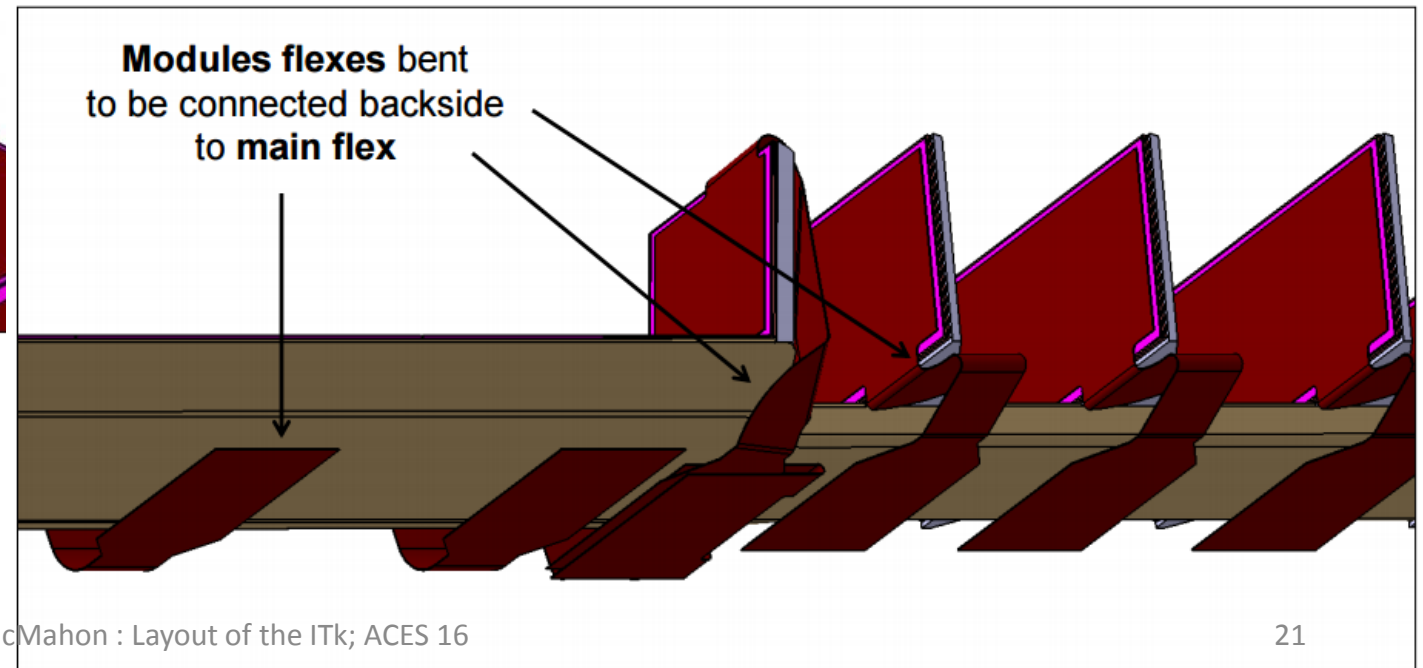
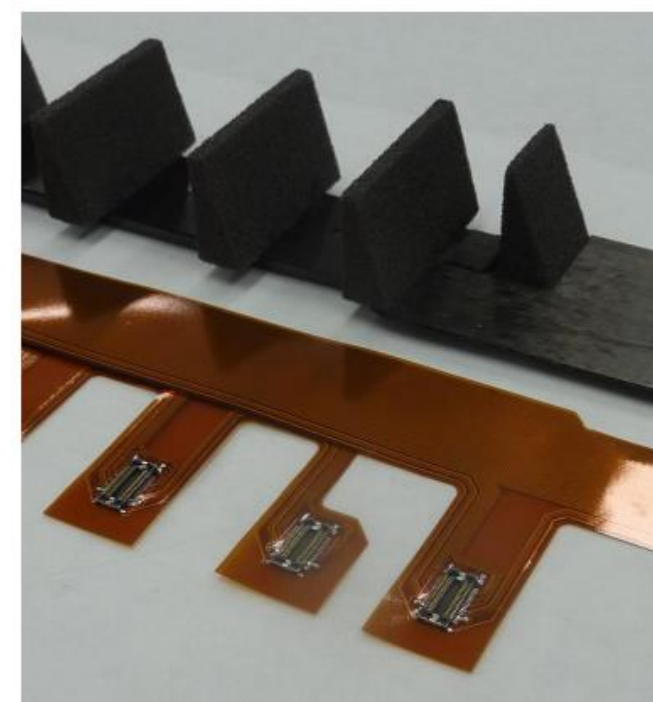
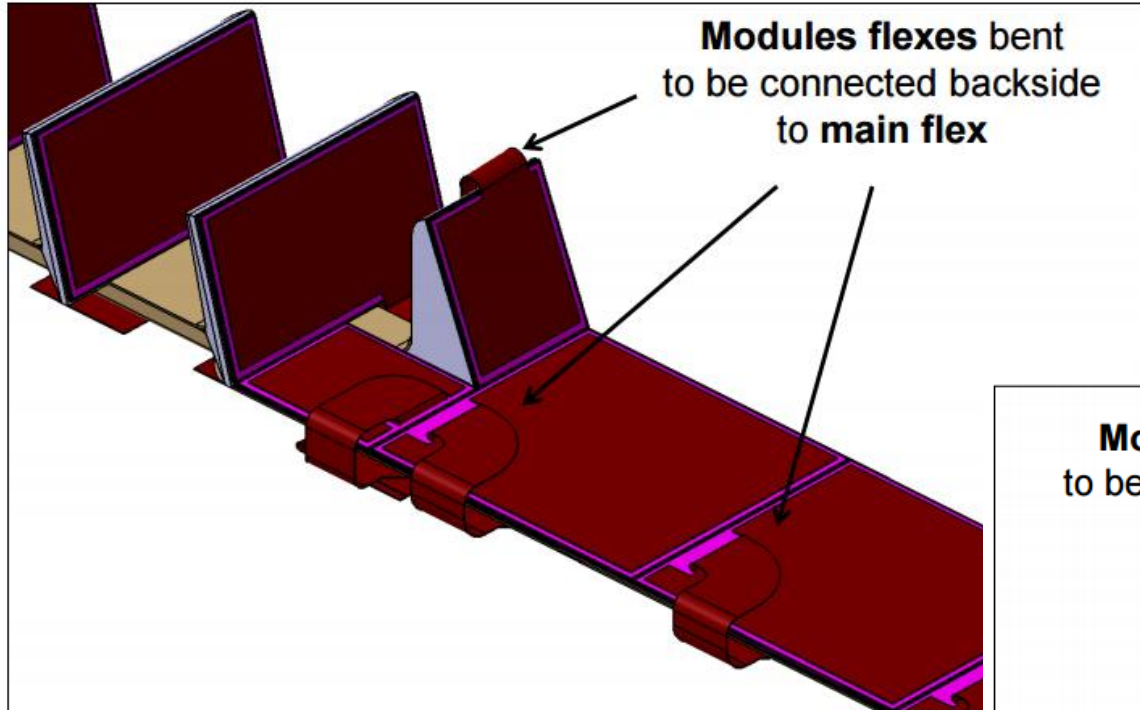
Inclined Sensor Option for Pixels: SLIM



Courtesy Sébastien Michal

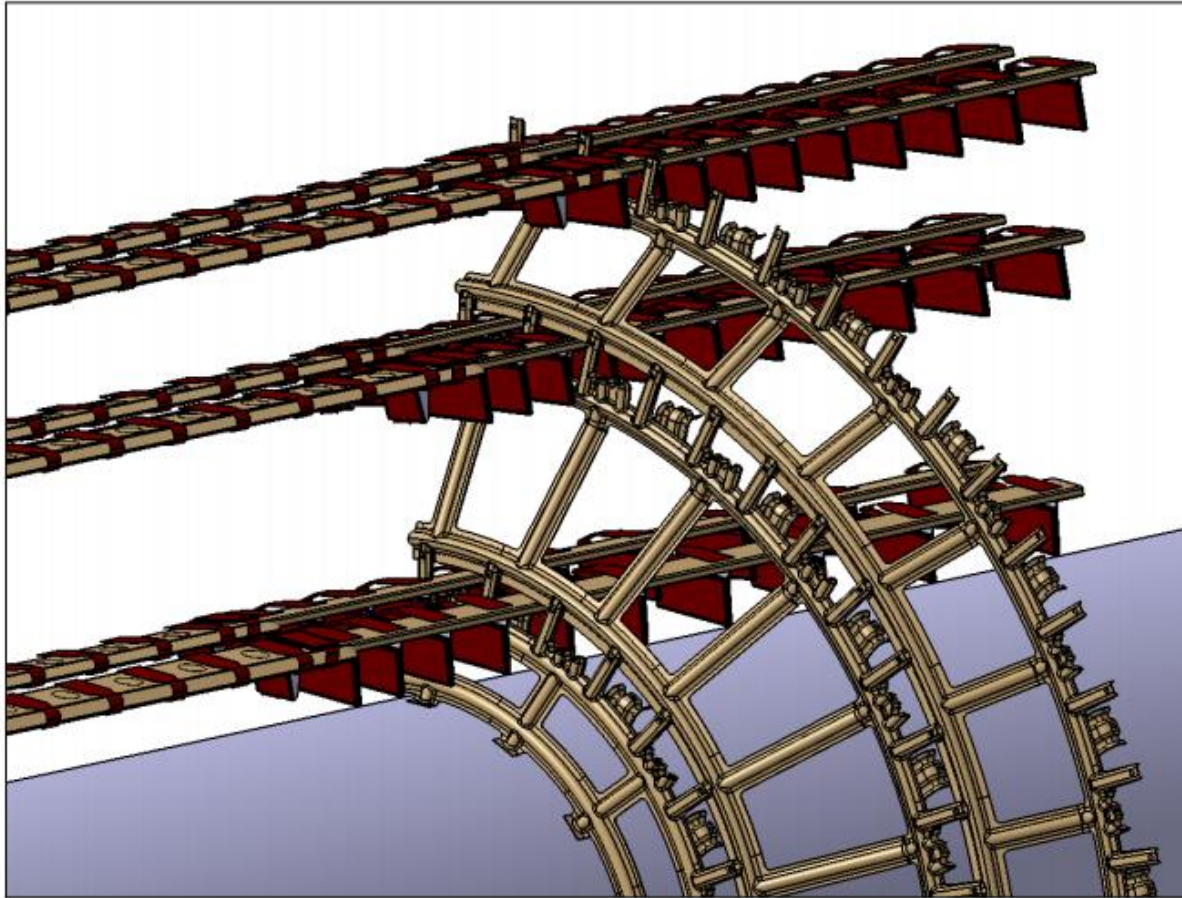
McMahon : Layout of the ITk; ACES 16

ITk Pixel Inclined Sensor Option: ALPINE



Courtesy ALPINE team

ITk Pixel Inclined Sensor Option: ALPINE

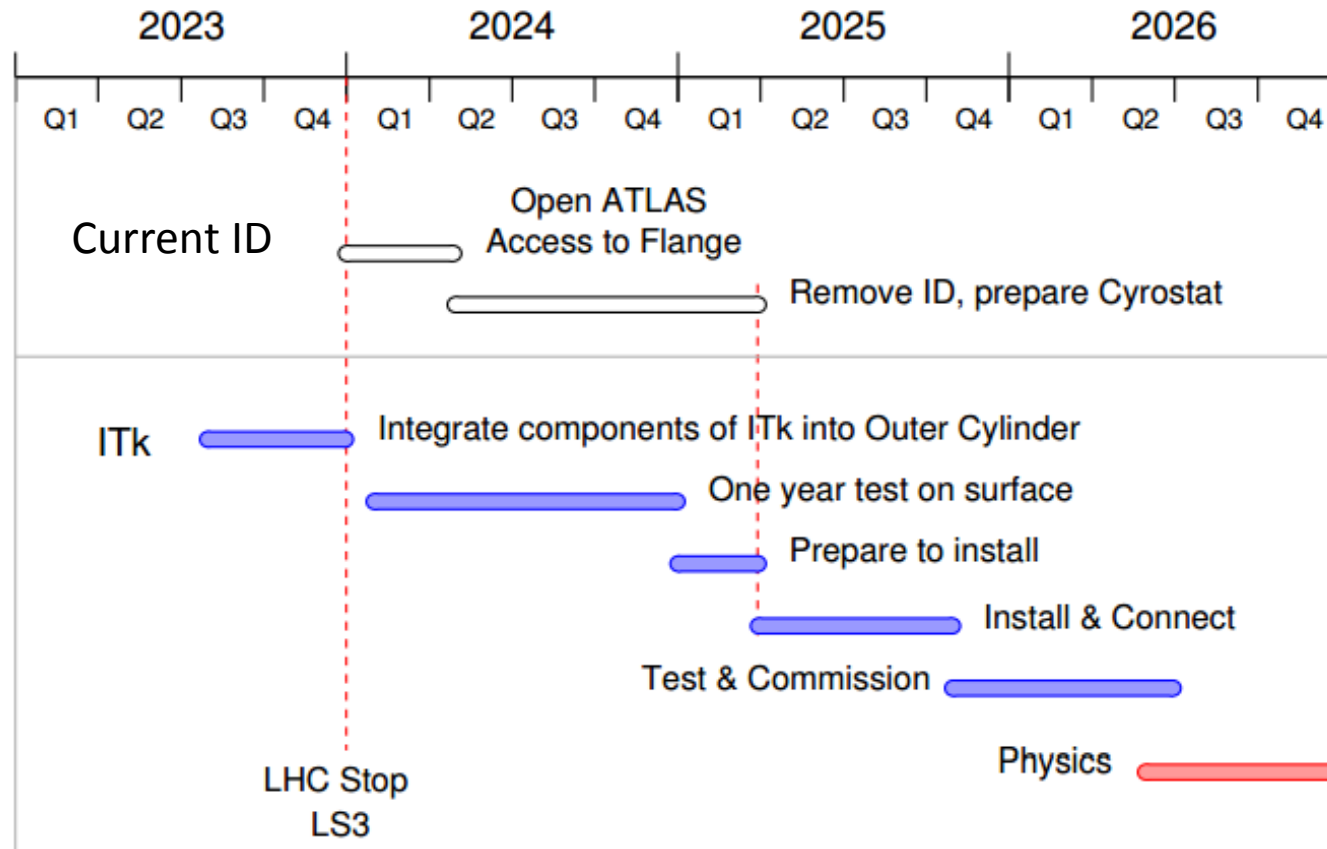


Courtesy ALPINE team

McMahon : Layout of the ITk; ACES 16

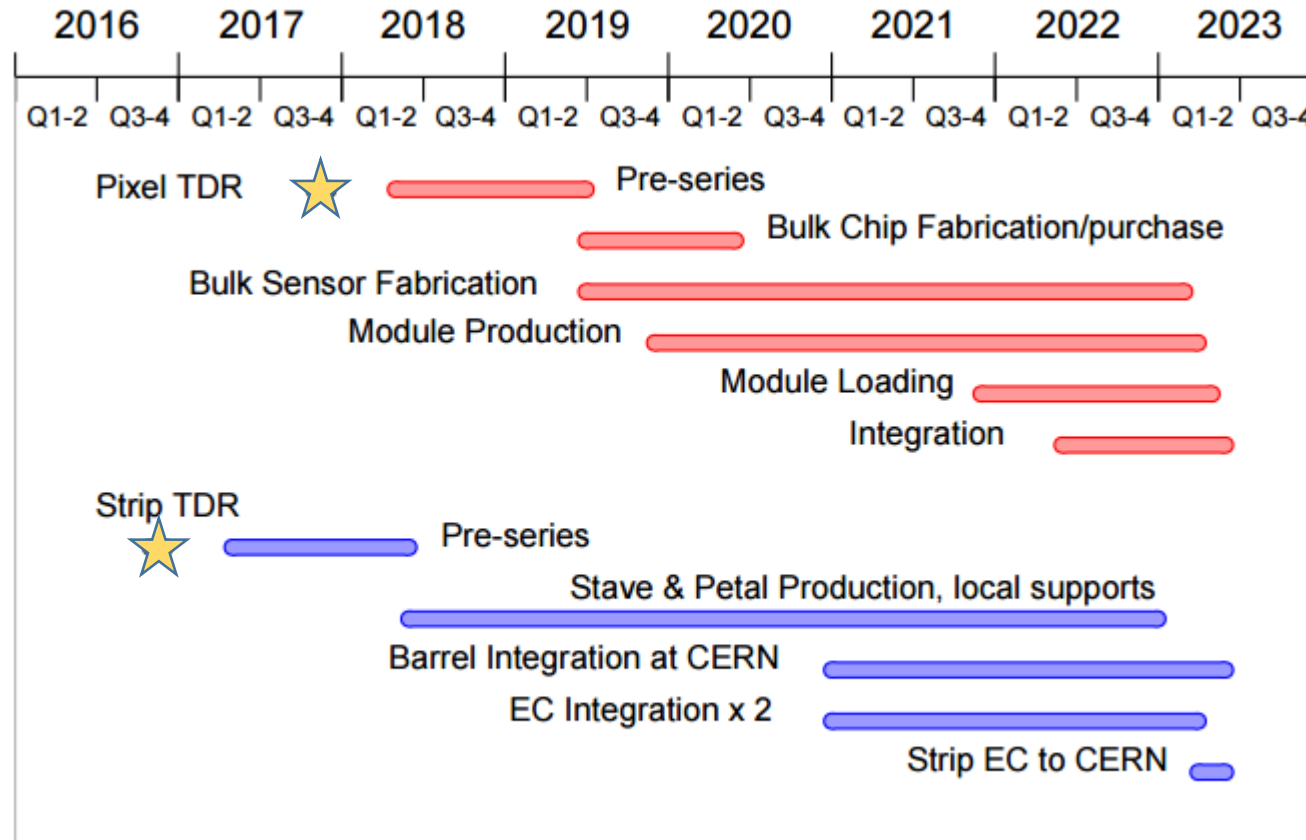
ITk Timeline

- Timeline : End-Game



ITk Timeline

- Timeline : TDRs and into production ...



Conclusion

- ITk design builds on the positive experience accumulated in the construction of the existing Inner Detector and its operation in Run-1
- However, the new design responds to the unique new challenges that are presented for a tracker to exploit the physics at Phase II
- Development is going very well
 - See talks of Alex and Tobias
- First stage of layout decisions will take place in 2016 (ahead of strip TDR)
- Preparing for TDRs in 2016 and 2017
- Will also deliver an ID decommissioning report at the end of 2017