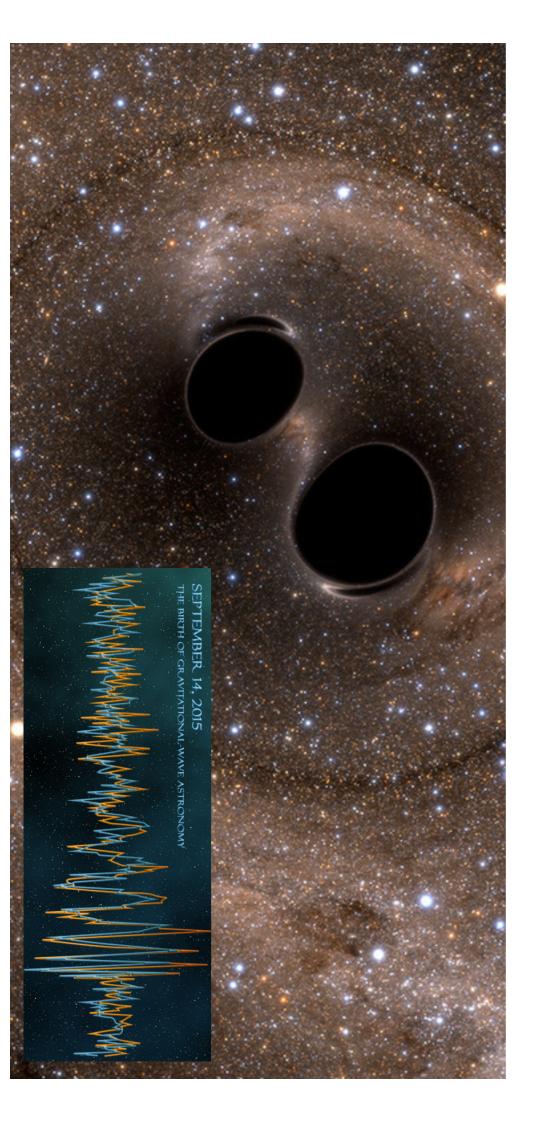


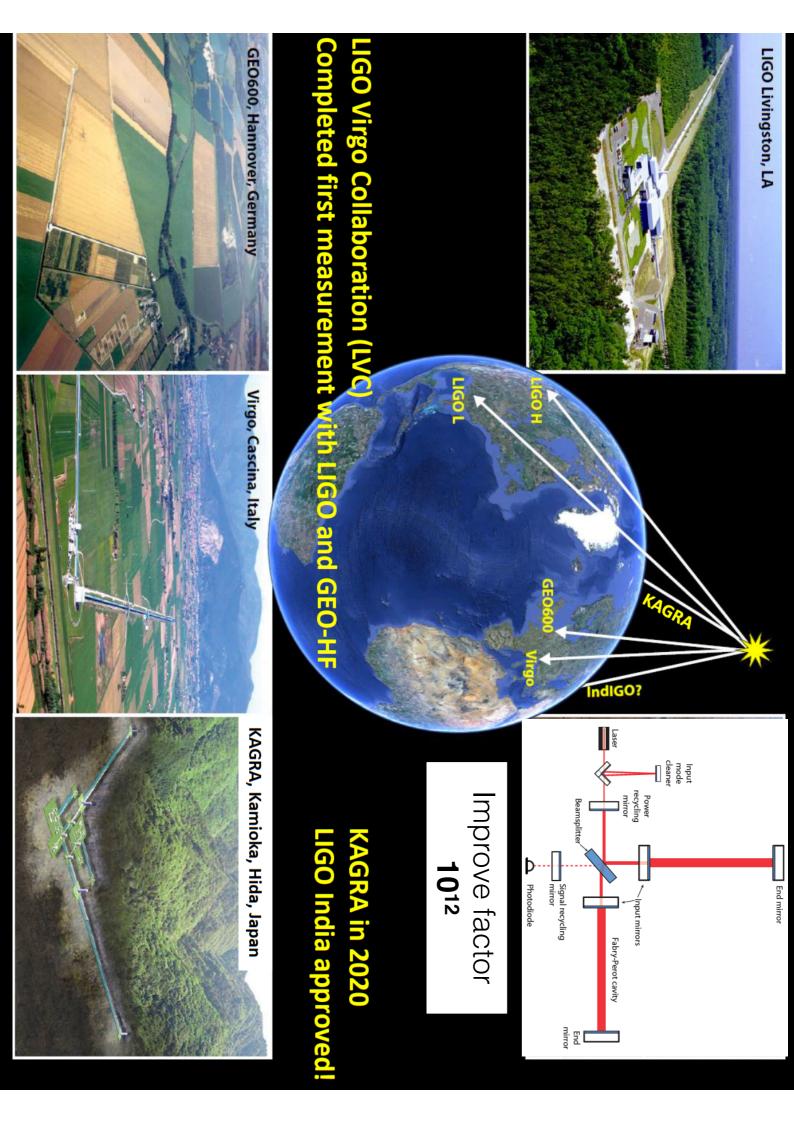


#### The sixth sense

## A new detector to observe the universe

N.A. van Bakel on behalf of the Nikhef R&D and Gravitational Physics groups

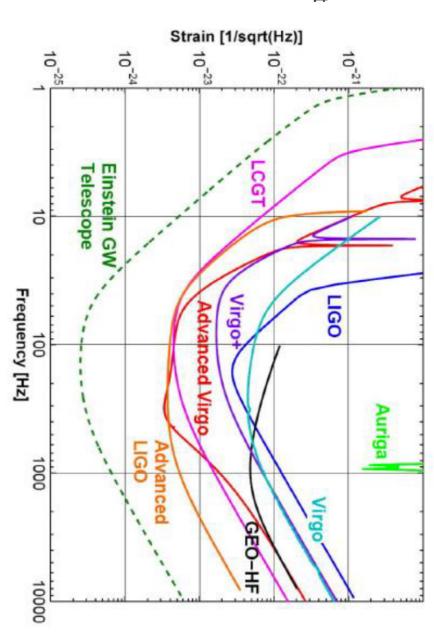


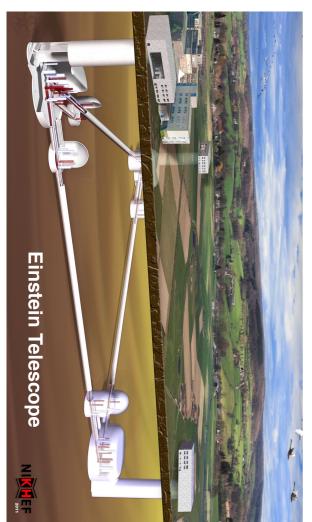


#### Sensitivity

Sensitivities of GW detectors from the first to the third generation

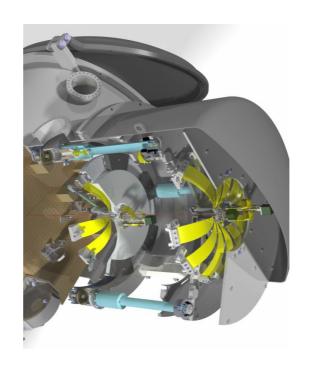
- High-freq (>300 Hz):
- ✓ Laser shot noise
- Increase laser power
- Mid-freq (40-300 Hz):
- √ Thermal noise
- Improve mirrors
- Low-freq (<40 Hz):
- ✓ Seismic noise
- Vibration isolation





### Vibration isolation

A suppression of seismic motion by about  $10^{10}$  is required: use anti-spring technology in the Advanced Virgo seismic noise filters to reduce the system stiffness



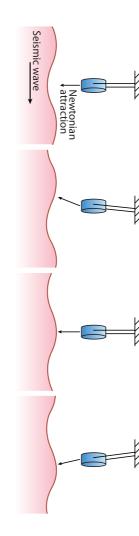


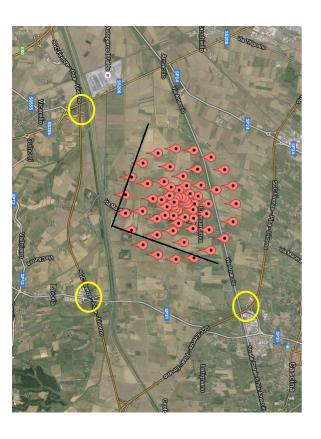


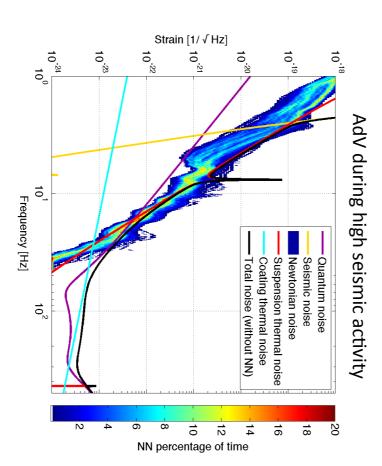
# Vibration monitoring - Newtonian Noise

No Newtonian noise model  $\Rightarrow$  to develop subtraction schemes, we have to measure the seismic wave fields with arrays of seismic sensors

Newtonian interaction between seismic wave field and interferometer mirrors



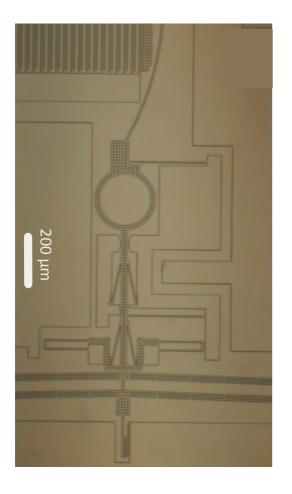


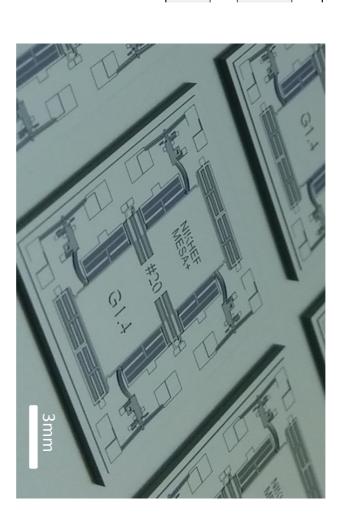


## Vibration monitoring - MEMS sensor

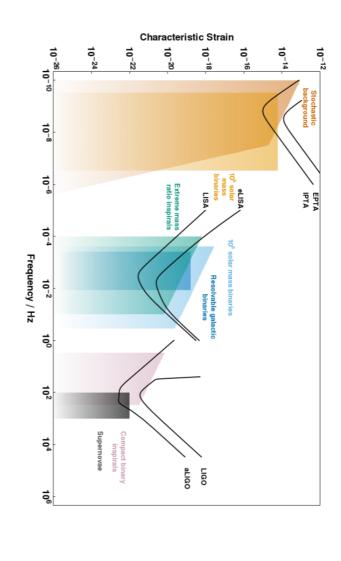
Our goal is to develop a new type of MEMS accelerometer with integrated readout electronics

~ 1 ng/vHz	< 10 µg/VHz	< 1 mg/VHz	Noise Floor
< 100Hz	DC-100Hz	DC-400Hz	Bandwidth
< ±1g	±12	±50g (airbag), ±2g (vehicle stability)	Full-scale Range
Seismic	Navigation	Automotive	Parameter





# "Sixth sense" - Detection of Gravitational Waves



- Build various gravitational detectors next 10 15 year: Einstein Telescope (ground based), eLISA (in space), ...
- Technological innovation lies in the combination of optomechanics, electronics and sensor systems
- Socio-economical impact

