

# Lecture 4: Quenching and Protection

## Plan

- the quench process
- decay times and temperature rise
- propagation of the resistive zone
- computing resistance growth and decay times
- mini tutorial
- quench protection schemes
- LHC quench protection



# Magnetic stored energy

**Magnetic energy density**  $E = \frac{B^2}{2\mu_0}$  at 5T  $E = 10^7$  Joule.m<sup>-3</sup> at 10T  $E = 4 \times 10^7$  Joule.m<sup>-3</sup>

**LHC dipole magnet (twin apertures)**  $E = \frac{1}{2}LI^2$   $L = 0.12$ H  $I = 11.5$ kA  $E = 7.8 \times 10^6$  Joules

the magnet weighs 26 tonnes

so the magnetic stored energy is equivalent to the kinetic energy of:-

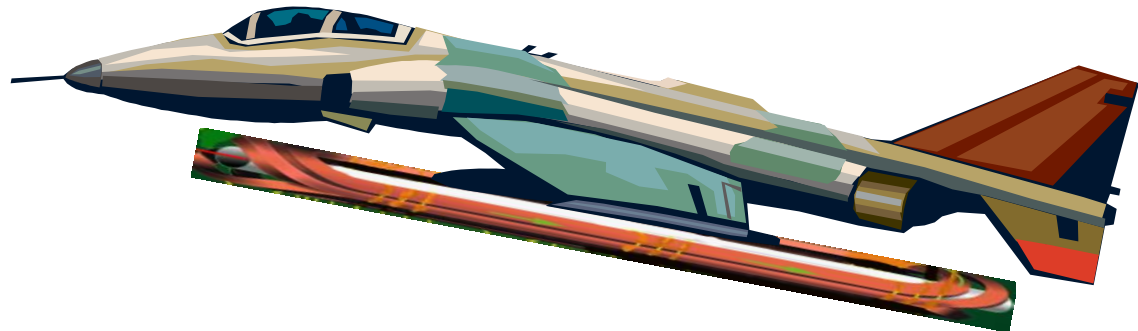
**26 tonnes travelling at 88km/hr**



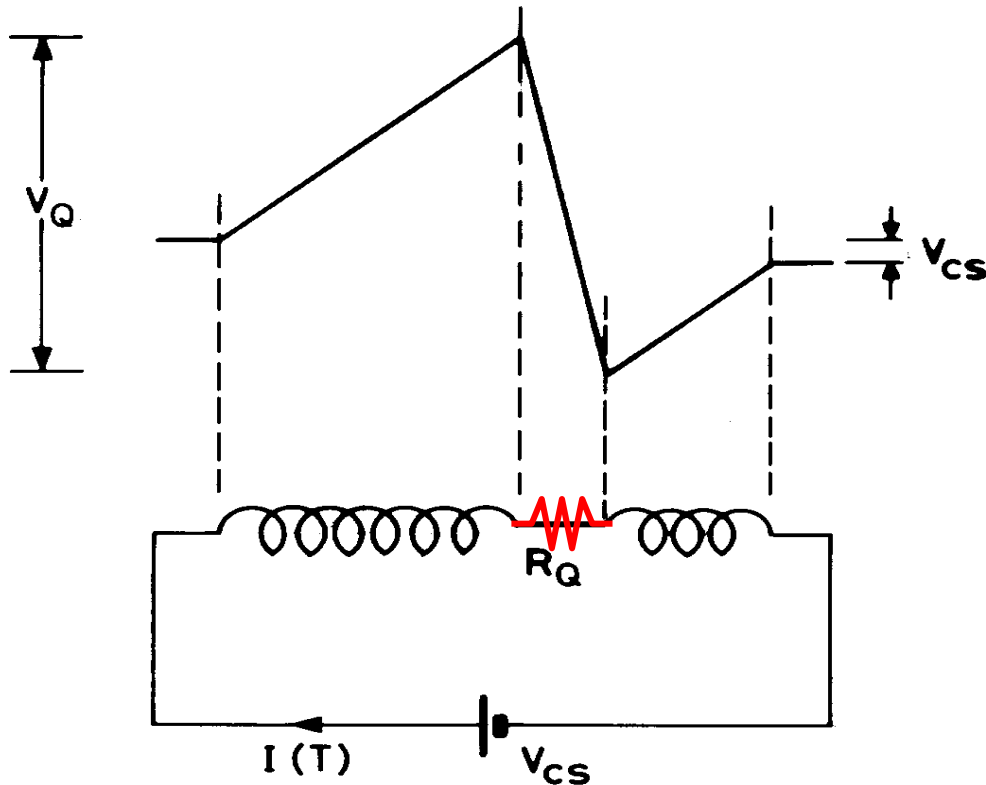
coils weigh 830 kg

equivalent to the kinetic energy of:-

**830kg travelling at 495km/hr**



# The quench process



- resistive region starts somewhere in the winding  
at a **point - this is the problem!**
- it grows by thermal conduction
- stored energy  $\frac{1}{2}LI^2$  of the magnet is dissipated as heat
- greatest integrated heat dissipation is at point where the quench starts
- maximum temperature may be calculated from the current decay time via the  $U(\theta)$  function (adiabatic approximation)
- internal voltages much greater than terminal voltage ( $= V_{CS}$  current supply)

# The temperature rise function $U(\theta)$

- Adiabatic approximation

$$J^2(T)\rho(\theta)dT = \gamma C(\theta)d\theta$$

$J(T)$  = overall current density,

$T$  = time,

$\rho(\theta)$  = overall resistivity,

$\gamma$  = density

$\theta$  = temperature,

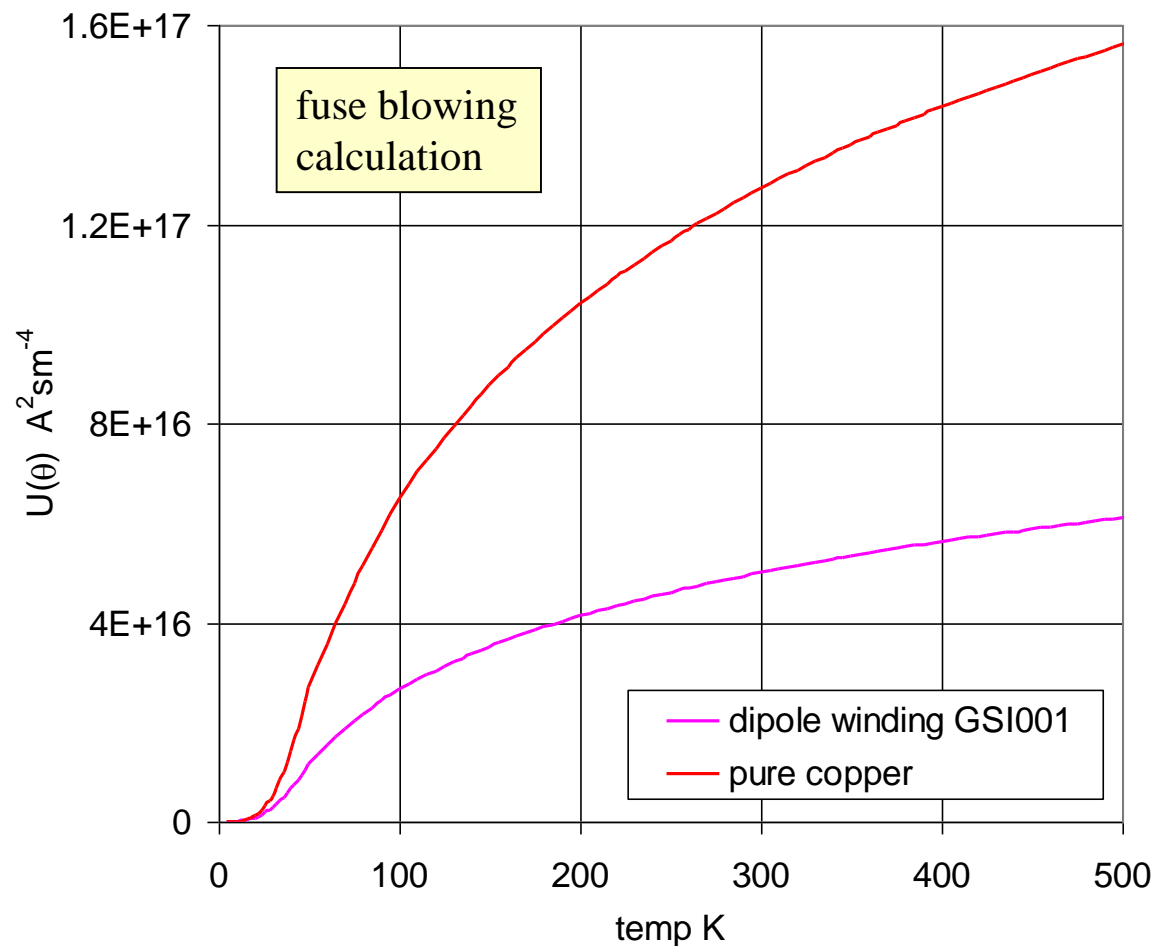
$C(\theta)$  = specific heat,

$T_Q$  = quench decay time.

$$\int_0^\infty J^2(T)dT = \int_{\theta_0}^{\theta_m} \frac{\gamma C(\theta)}{\rho(\theta)} d\theta = U(\theta_m)$$

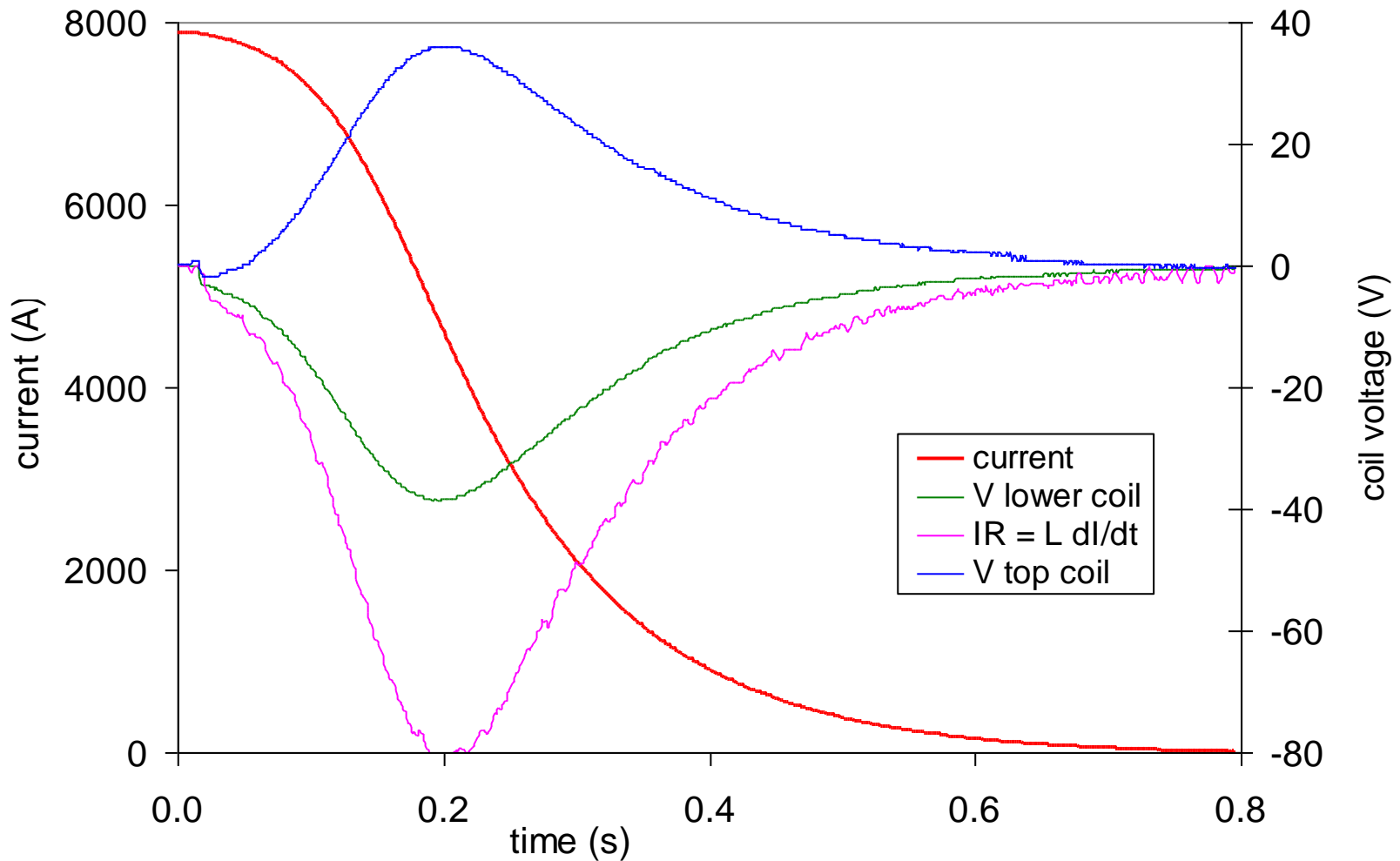
$$J_o^2 T_Q = U(\theta_m)$$

- GSI 001 dipole winding is  
50% copper, 22% NbTi,  
16% Kapton and 3% stainless steel
- NB always use **overall** current density



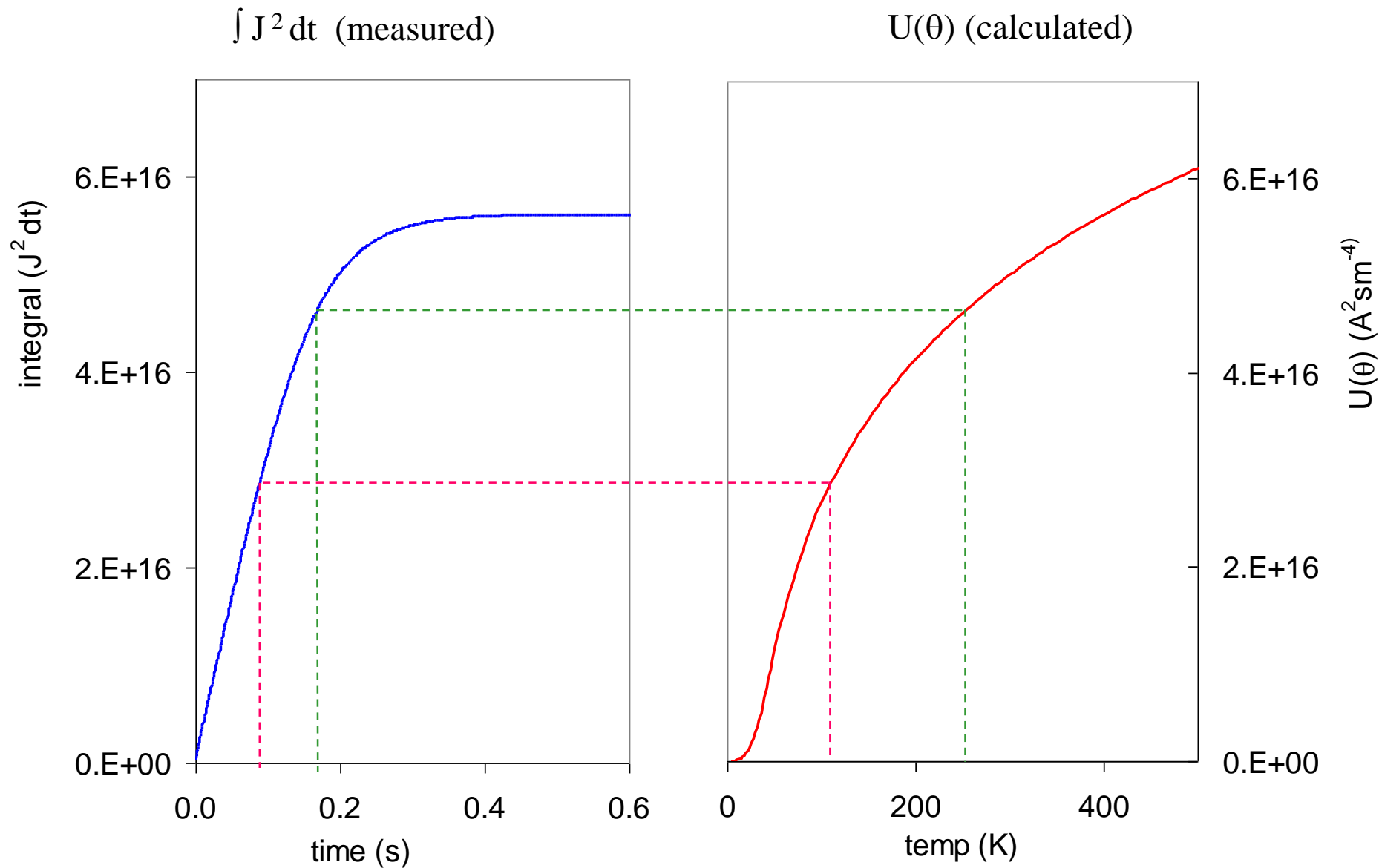
household fuse blows at 15A,  
area = 0.15mm<sup>2</sup>  $J = 100Amm^{-2}$   
NbTi in 5T  $J_c = 2500Amm^{-2}$

# Measured current decay after a quench

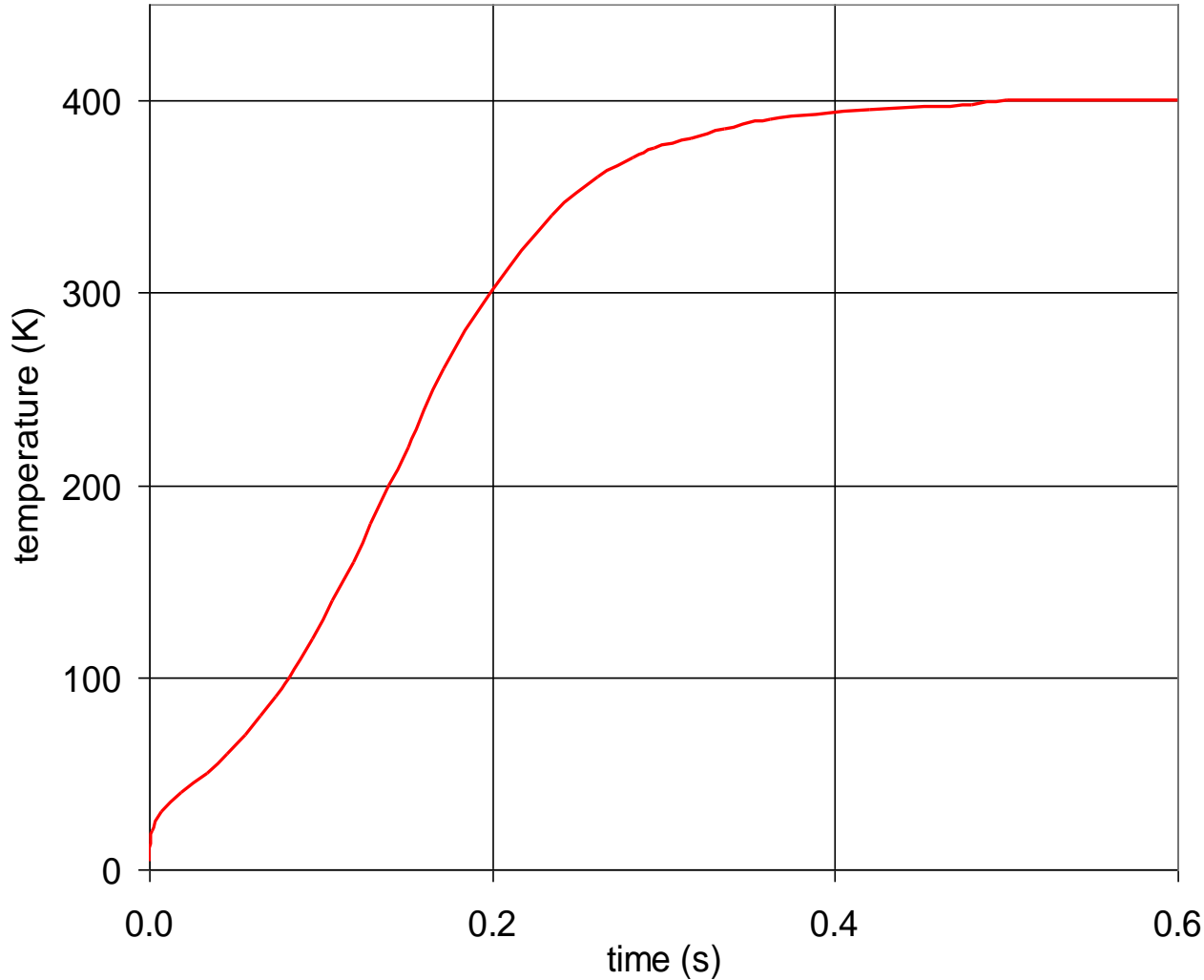


*Dipole GSI001 measured at Brookhaven National Laboratory*

# Calculating temperature rise from the current decay curve

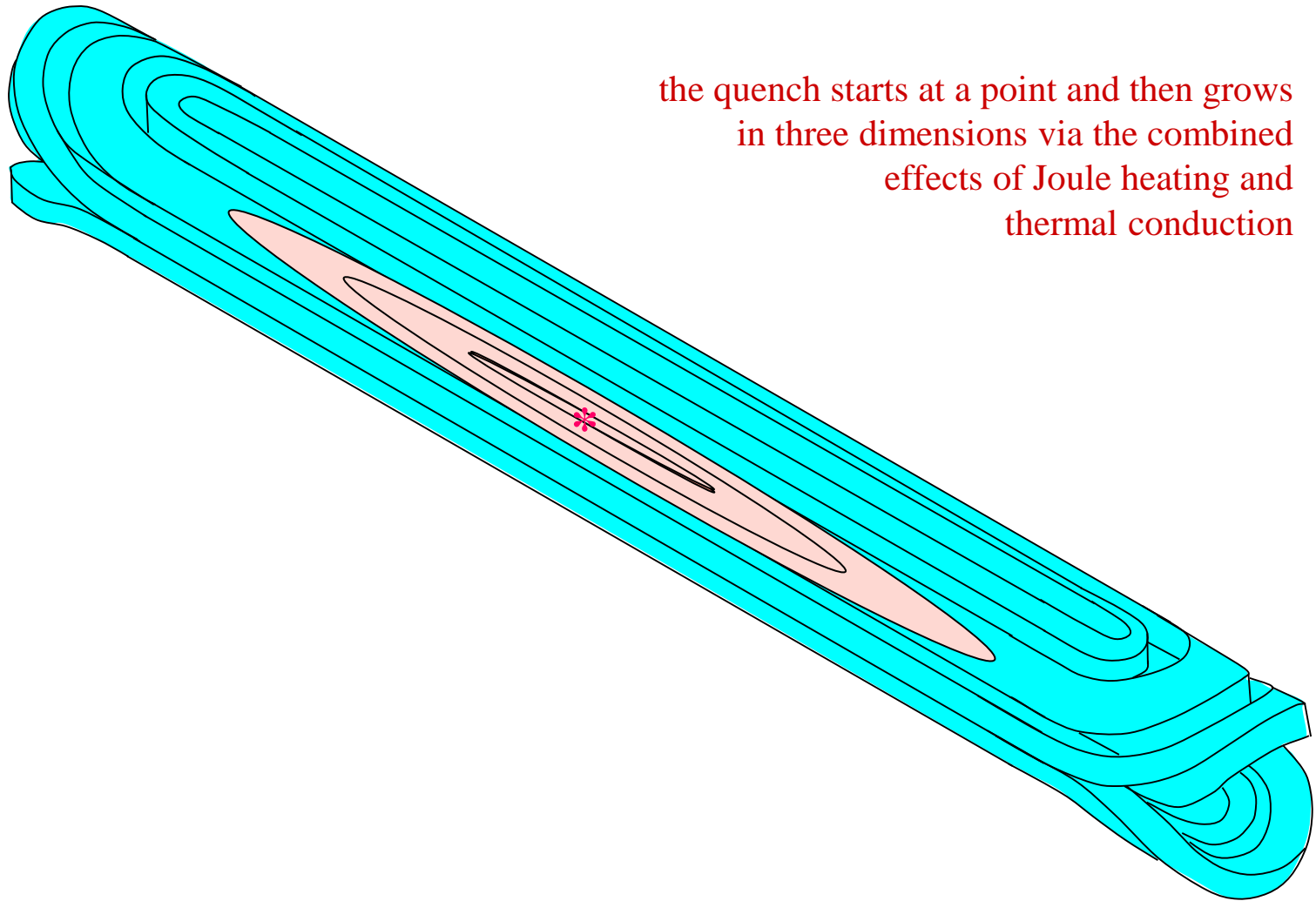


# Calculated temperature



- calculate the  $U(\theta)$  function from known materials properties
- measure the current decay profile
- calculate the maximum temperature rise at the point where quench starts
- we now know if the temperature rise is acceptable  
- but only after it has happened!
- need to calculate current decay curve before quenching

# *Growth of the resistive zone*

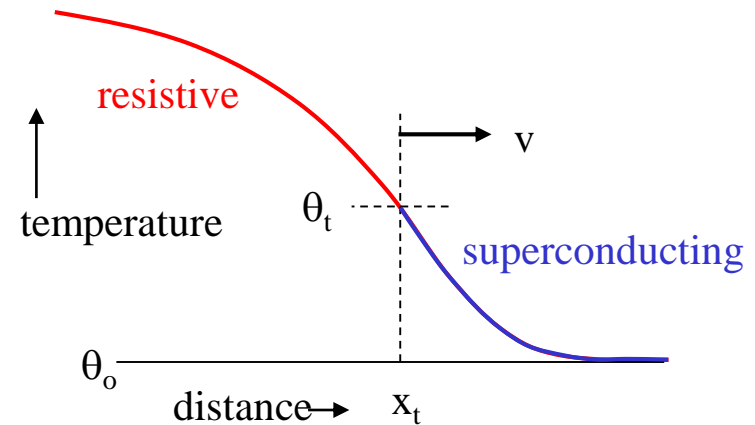


the quench starts at a point and then grows  
in three dimensions via the combined  
effects of Joule heating and  
thermal conduction



# Quench propagation velocity 1

- resistive zone starts at a point and spreads outwards
- driving it forward is heat generation in the resistive zone and heat conduction along the wire
- heat conduction equation with resistive power generation  $J^2\rho$  per unit volume.



$J^2\rho$  at left side

$\rho = 0$  at right

$$\frac{\partial}{\partial x} \left( kA \frac{\partial \theta}{\partial x} \right) - \gamma CA \frac{\partial \theta}{\partial t} - hP(\theta - \theta_0) + J^2 \rho A = 0$$

where:  $k$  = thermal conductivity,  $A$  = area occupied by a single turn,  $\gamma$  = density,  $C$  = specific heat,  $h$  = heat transfer coefficient,  $P$  = cooled perimeter,  $\rho$  = resistivity,  $\theta_0$  = base temperature

**Note:** all parameters are averaged over  $A$  the cross section occupied by one turn

assume  $x_t$  moves to the right at velocity  $v$  and take a new coordinate  $\varepsilon = x - x_t = x - vt$

$$\frac{d^2 \theta}{d\varepsilon^2} + \frac{v\gamma C}{k} \frac{d\theta}{d\varepsilon} - \frac{hP}{kA} (\theta - \theta_0) + \frac{J^2 \rho}{k} = 0$$

# Quench propagation velocity 2

when  $h = 0$ , the solution for  $\theta$  which gives a continuous join between left and right sides at  $\theta_t$  gives the **adiabatic propagation velocity**

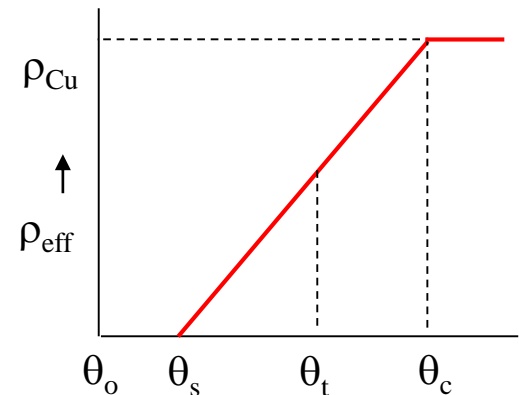
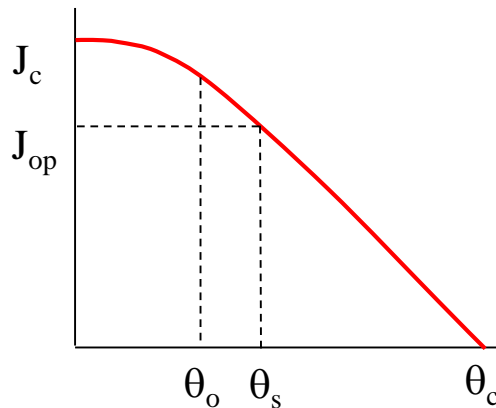
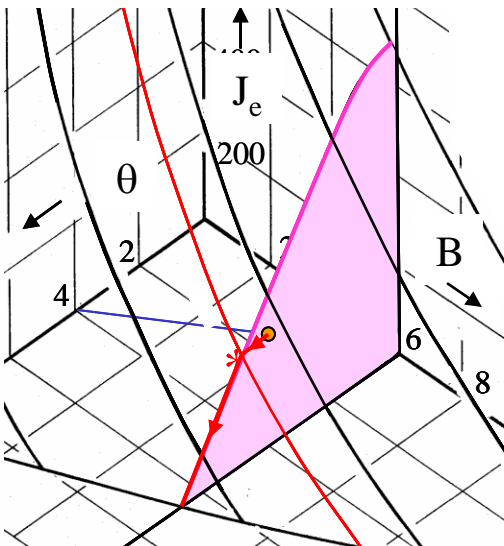
$$v_{ad} = \frac{J}{\gamma C} \left\{ \frac{\rho k}{\theta_t - \theta_0} \right\}^{\frac{1}{2}} = \frac{J}{\gamma C} \left\{ \frac{L_o \theta_t}{\theta_t - \theta_0} \right\}^{\frac{1}{2}}$$

recap Wiedemann Franz Law  $\rho(\theta).k(\theta) = L_o \theta$

## what to say about $\theta_t$ ?

- in a single superconductor it is just  $\theta_c$
- but in a practical filamentary composite wire the current transfers progressively to the copper

- current sharing temperature  $\theta_s = \theta_o + margin$
- zero current in copper below  $\theta_s$  all current in copper above  $\theta_c$
- take a mean transition temperature  $\theta_t = (\theta_s + \theta_c)/2$



# Quench propagation velocity 3

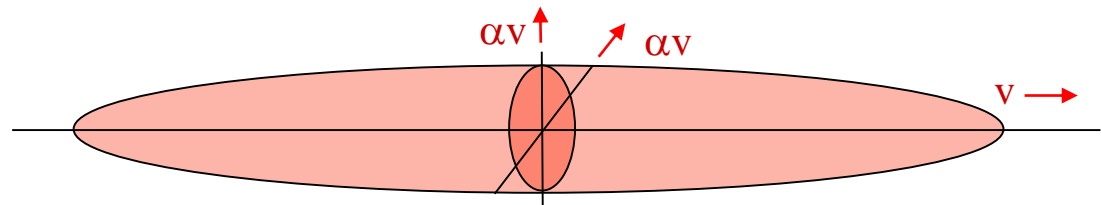
- resistive zone also propagates sideways through inter-turn insulation (much more slowly)
- similar calculation  $\Rightarrow$  velocity ratio  $\alpha$

$$\alpha = \frac{v_{trans}}{v_{long}} = \left\{ \frac{k_{trans}}{k_{long}} \right\}^{\frac{1}{2}}$$

## Typical values

$$v_{ad} = 5 - 20 \text{ ms}^{-1} \quad \alpha = 0.01 - 0.03$$

so the resistive zone advances in the form of an ellipsoid, with its long dimension along the wire



## Some corrections for a better approximation

- because  $C$  varies so strongly with temperature, it is better to calculate an averaged  $C$  by numerical integration

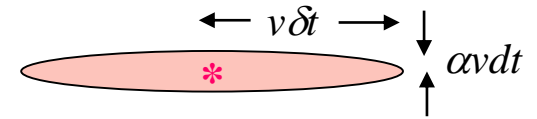
$$C_{av}(\theta_g, \theta_c) = \frac{\int_{\theta_g}^{\theta_c} C(\theta) d\theta}{(\theta_c - \theta_g)}$$

- heat diffuses slowly into the insulation, so its heat capacity should be excluded from the averaged heat capacity when calculating longitudinal velocity - but not transverse velocity
- if the winding is porous to liquid helium (usual in accelerator magnets) need to include a time dependent heat transfer term
- can approximate all the above, but for a really good answer must solve (numerically) the three dimensional heat diffusion equation - or even better measure it!

# Resistance growth and current decay - numerical

start resistive zone 1

in time  $\delta t$  zone 1 grows  $v \cdot dt$  longitudinally and  $\alpha \cdot v \cdot dt$  transversely

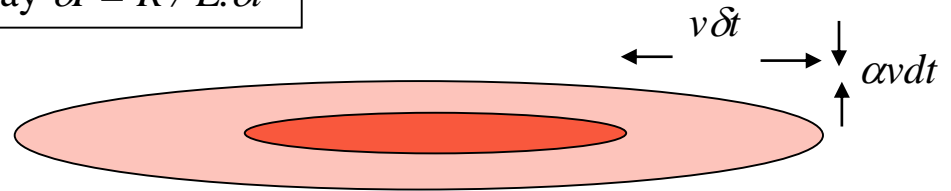


temperature of zone grows by  $\delta\theta_1 = J^2 \rho(\theta_1) \delta\tau / \gamma C(\theta_1)$

resistivity of zone 1 is  $\rho(\theta_1)$

calculate resistance and hence current decay  $\delta I = R / L \cdot \delta t$

in time  $\delta t$  add zone n:  
 $v \cdot \delta t$  longitudinal and  $\alpha \cdot v \cdot \delta t$  transverse



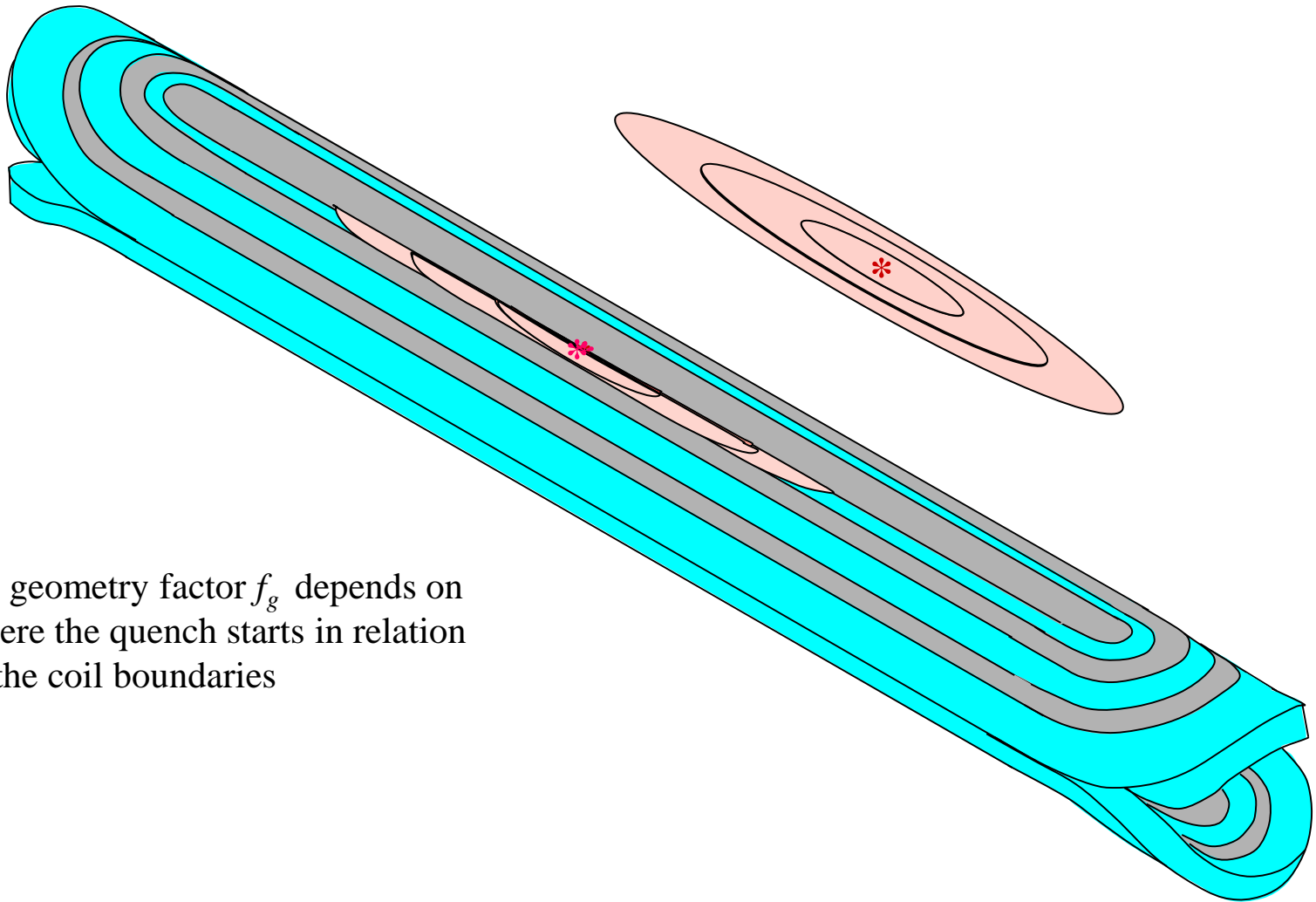
temperature of each zone grows by  $\delta\theta_1 = J^2 \rho(\theta_1) \delta t / \gamma C(\theta_1)$   $\delta\theta_2 = J^2 \rho(\theta_2) \delta t / \gamma C(\theta_2)$   $\delta\theta_n = J^2 \rho(\theta_n) \delta t / \gamma C(\theta_n)$

resistivity of each zone is  $\rho(\theta_1)$   $\rho(\theta_2)$   $\rho(\theta_n)$  resistance  $r_1 = \rho(\theta_1) * f_{g1}$  (geom factor)  $r_2 = \rho(\theta_2) * f_{g2}$   $r_n = \rho(\theta_n) * f_{gn}$

calculate total resistance  $R = \sum r_1 + r_2 + r_{n..}$  and hence current decay  $\delta I = (IR/L) \delta t$

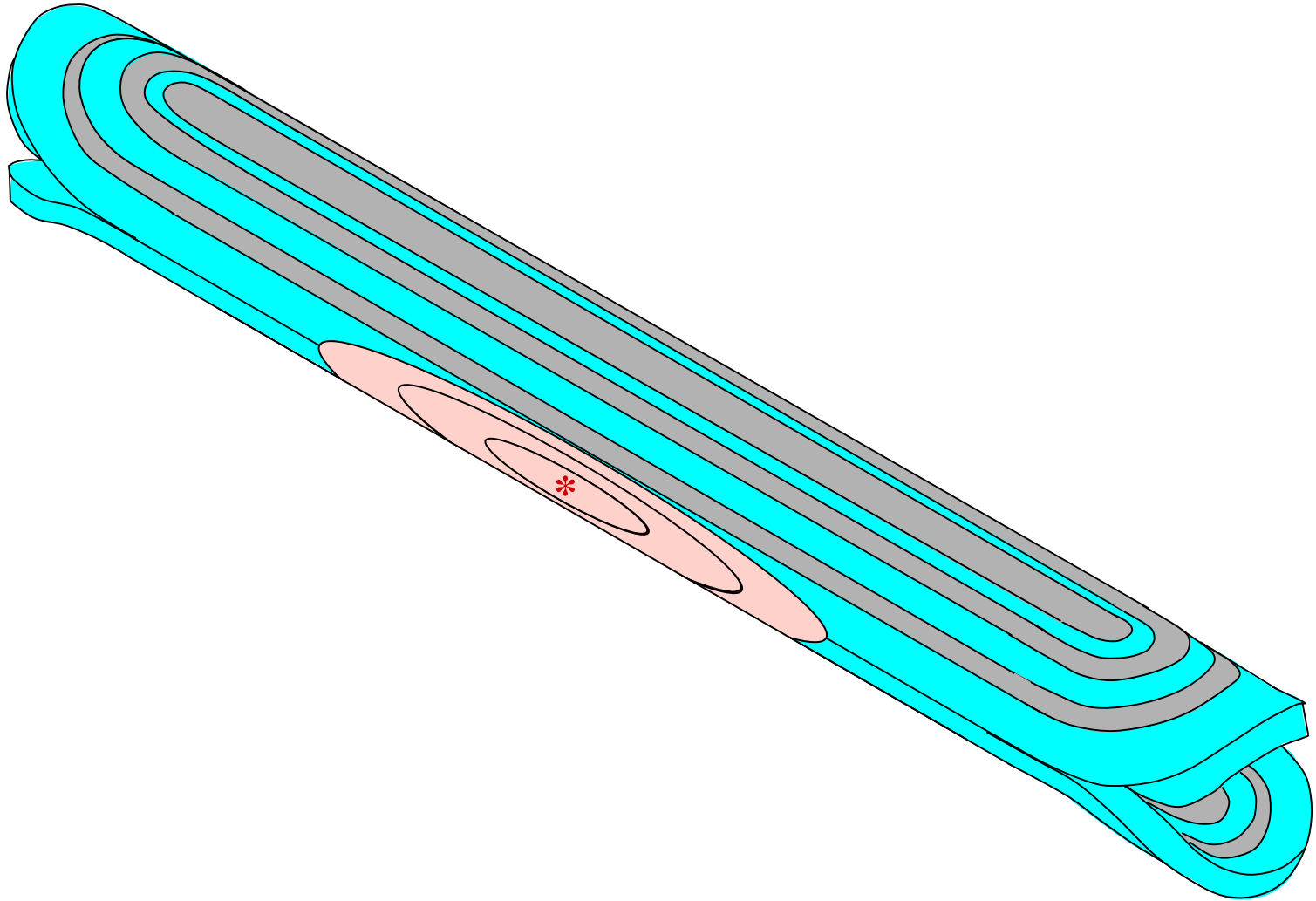
when  $I \Rightarrow 0$  stop

# Quench starts in the pole region

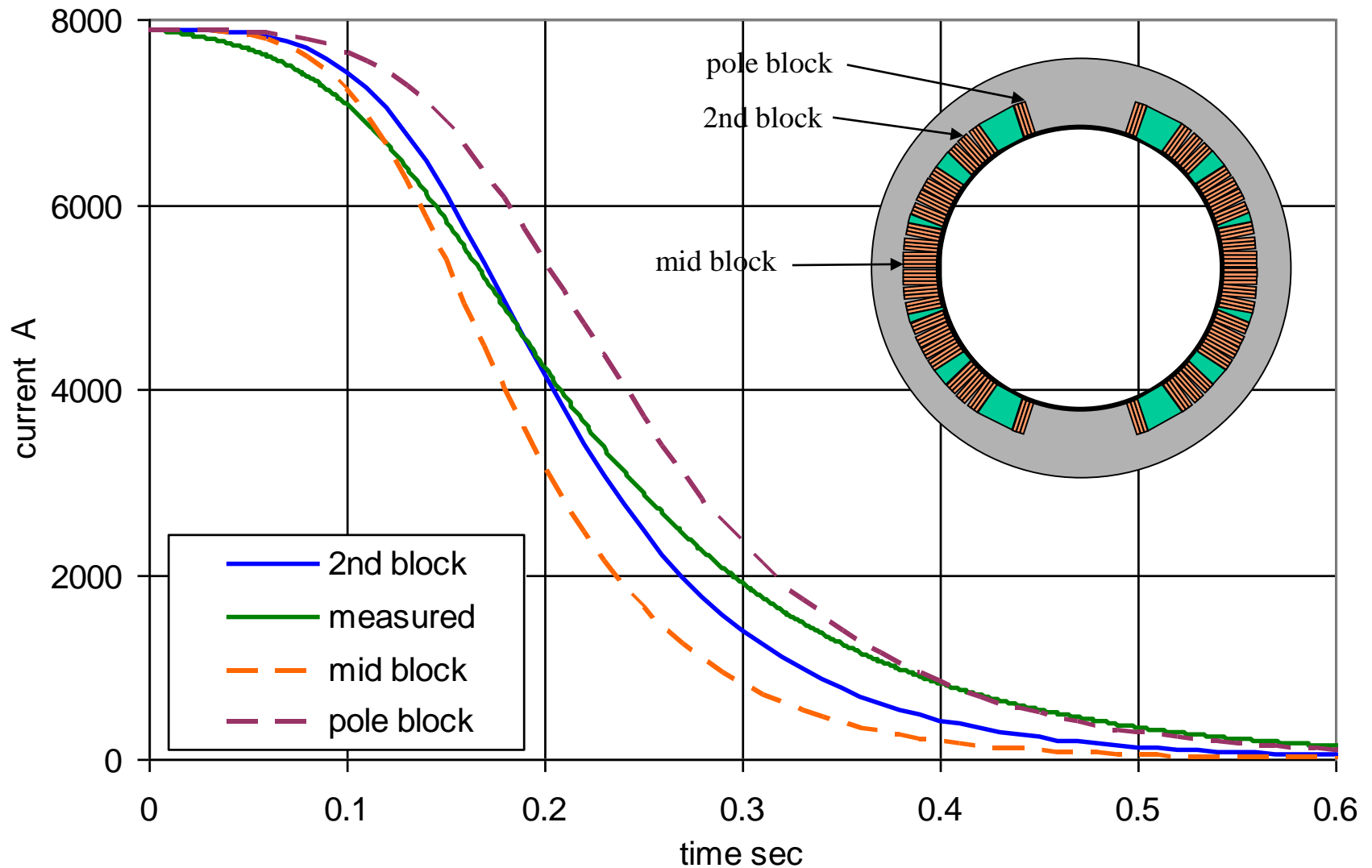


the geometry factor  $f_g$  depends on where the quench starts in relation to the coil boundaries

# Quench starts in the mid plane

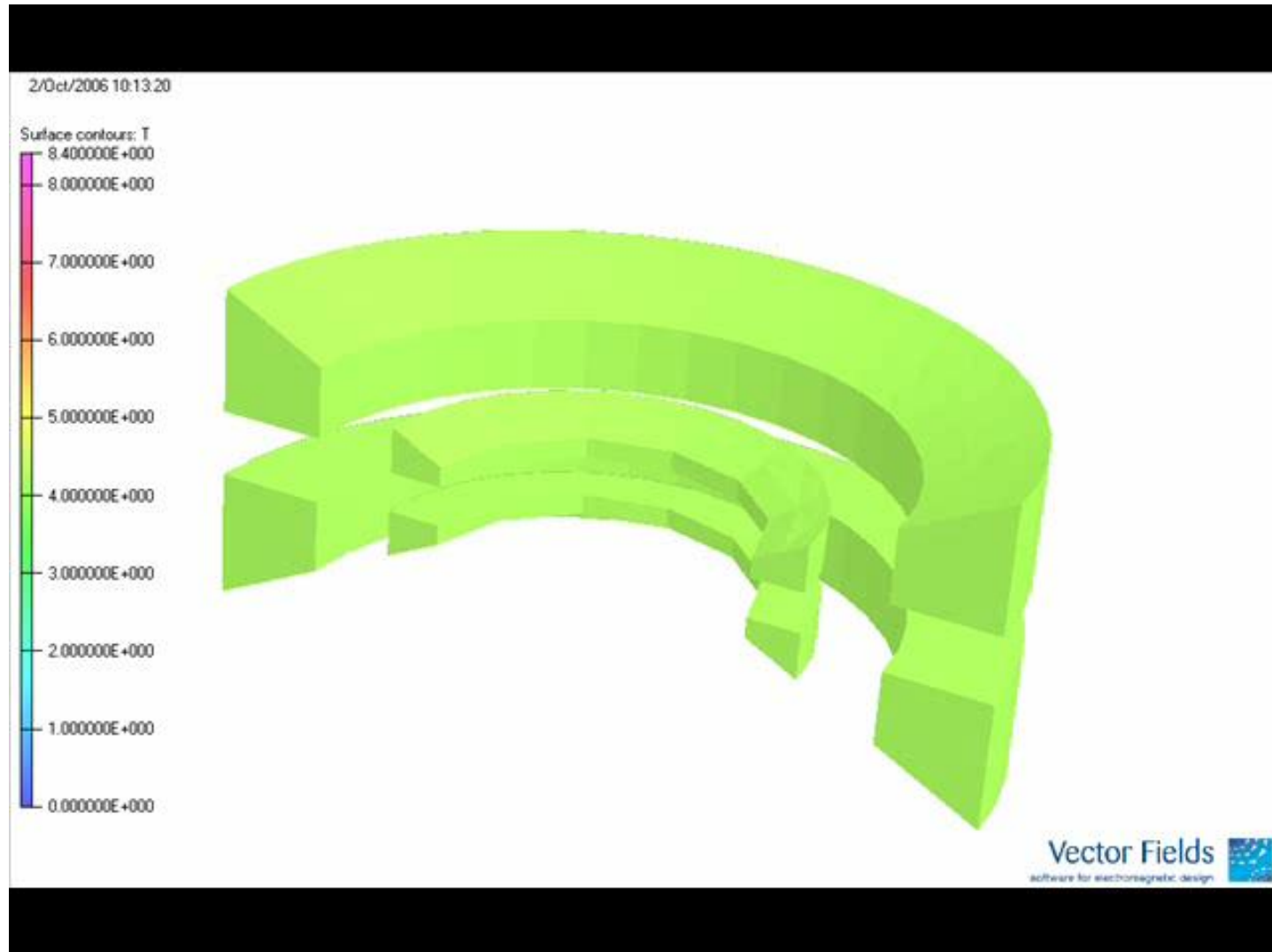


# Computer simulation of quench (dipole GSI001)



# OPERA: a more accurate approach

solve the non-linear heat diffusion & power dissipation equations for the whole magnet

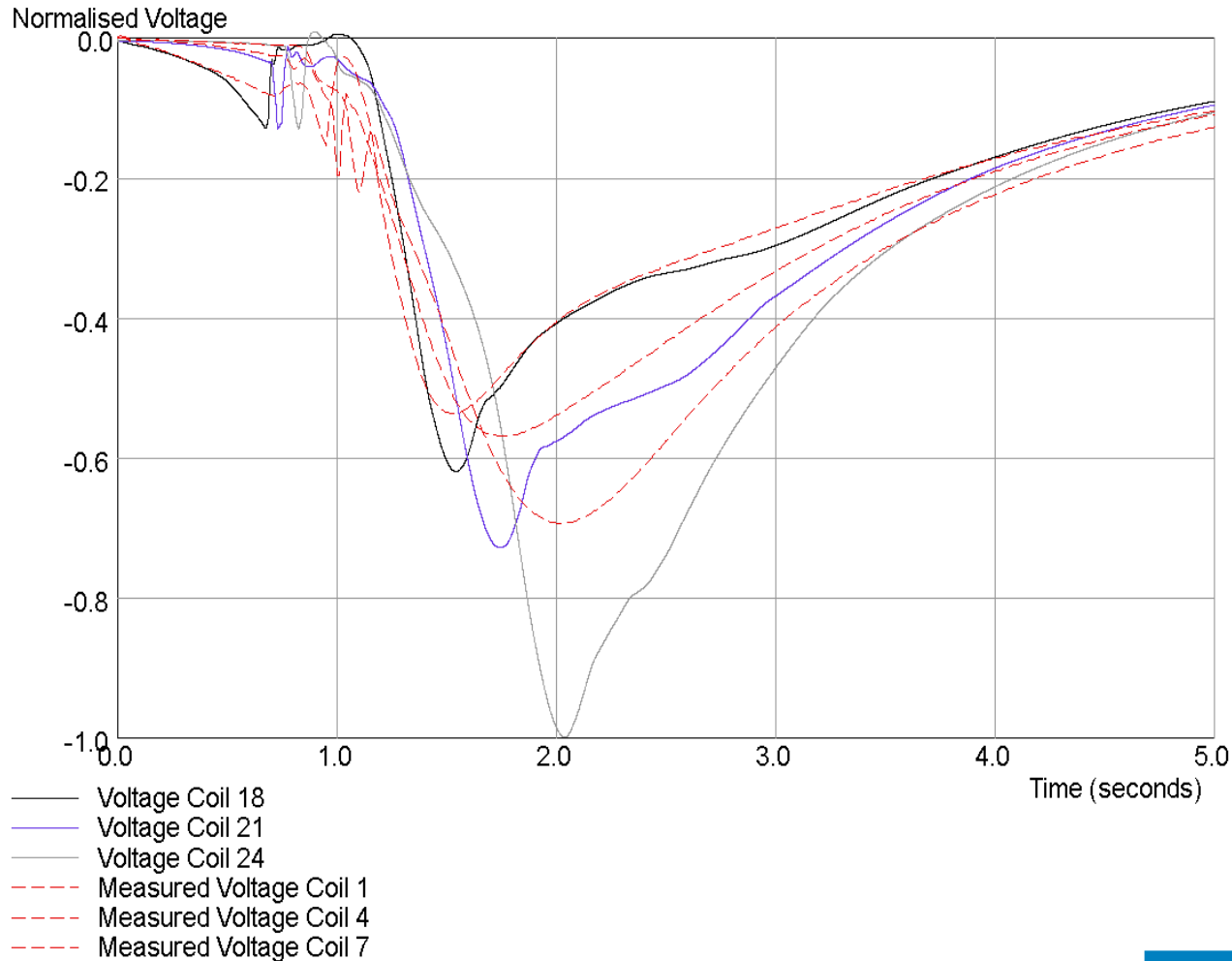




# Compare with measurement

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C:\u\js\Data\Impdahma\TestBedB-HTS\test\_c17\_limited\_loss\_p2w\_sn2alp8.log



can include

- ac losses
- flux flow resistance
- cooling
- contact between coil sections

but it does need a lot of computing

Opera

*Coupled transient thermal and electromagnetic finite element simulation of Quench in superconducting magnets C Aird et al Proc ICAP 2006 available at [www.jacow.org](http://www.jacow.org)*

# Mini Tutorial: $U(\theta)$ function

It is often useful to talk about a magnet quench decay time, defined by:

$$\int_{\theta_o}^{\theta_m} J^2 dt = J_o^2 T_d$$

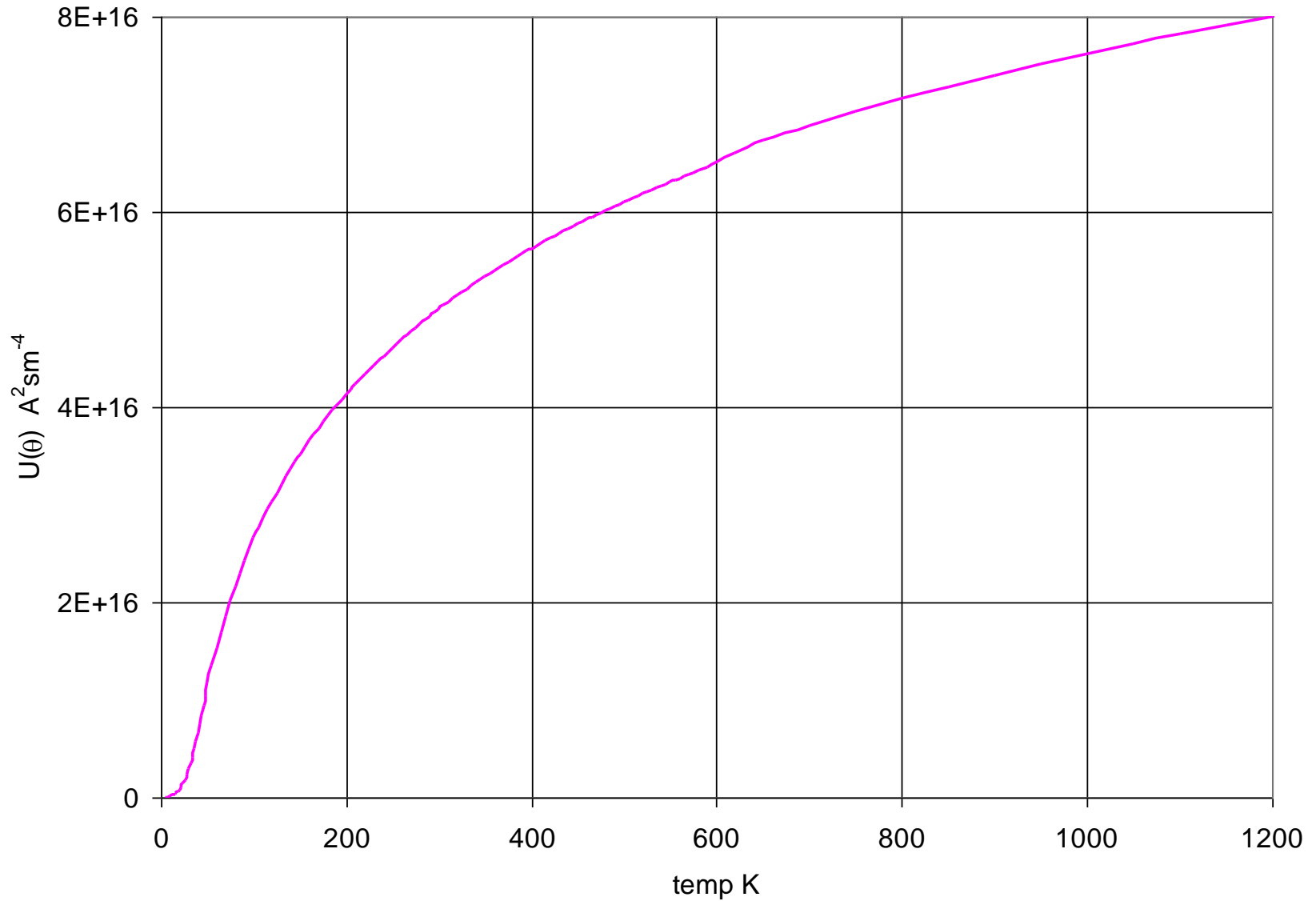
- i) For the example of magnet GSI001, given above,  $T_d = 0.167$  sec  
Use the  $U(\theta_m)$  plot below to calculate the maximum temperature.
- ii) This was a short prototype magnet. Supposing we make a full length magnet and compute  $T_d = 0.23$  sec. - should we be worried?
- iii) If we install quench back heaters which reduce the decay time to 0.1 sec, what will the maximum temperature rise be?

## Data

Magnet current  $I_o = 7886$  Amps

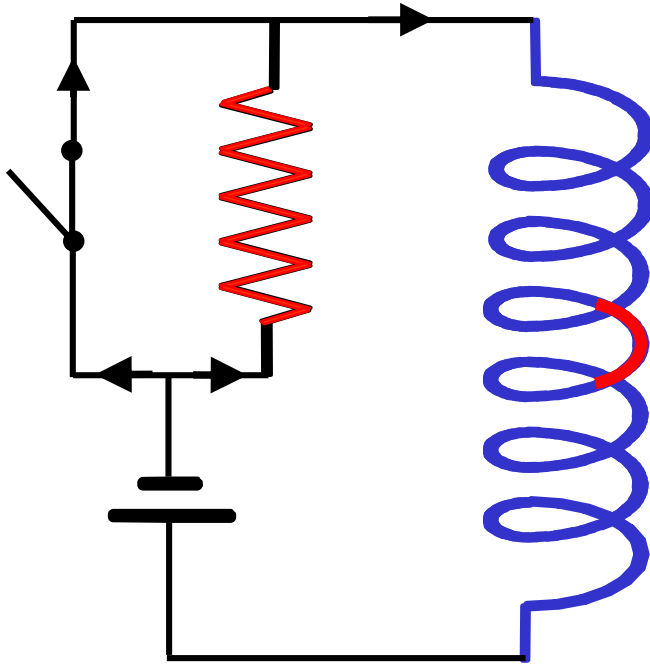
Unit cell area of one cable  $A_u = 13.6$  mm<sup>2</sup>

# $U(\theta_m)$ function for dipole GSI001



# Methods of quench protection:

## 1) external dump resistor



- detect the quench electronically
- open an external circuit breaker
- force the current to decay with a time constant  $\tau$

$$I = I_o e^{-\frac{t}{\tau}} \quad \text{where} \quad \tau = \frac{L}{R_p}$$

- calculate  $\theta_{\max}$  from

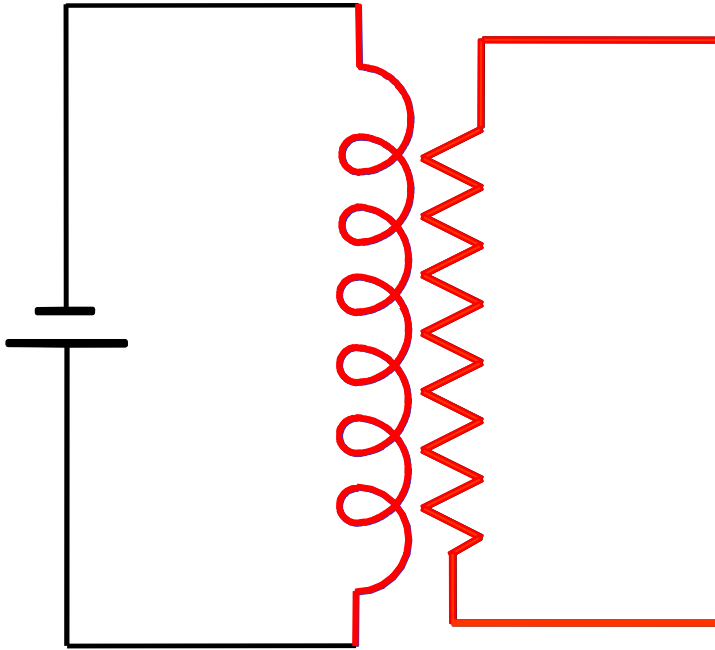
$$\int J^2 dt = J_o^2 \frac{\tau}{2} = U(\theta_m)$$

$$T_Q = \frac{\tau}{2}$$

**Note:** circuit breaker must be able to open at full current against a voltage  $V = I.R_p$  (expensive)

# Methods of quench protection:

## 2) quench back heater



*Note: usually pulse the heater by a capacitor, the high voltages involved raise a conflict between:-*

- *good thermal contact*
- *good electrical insulation*

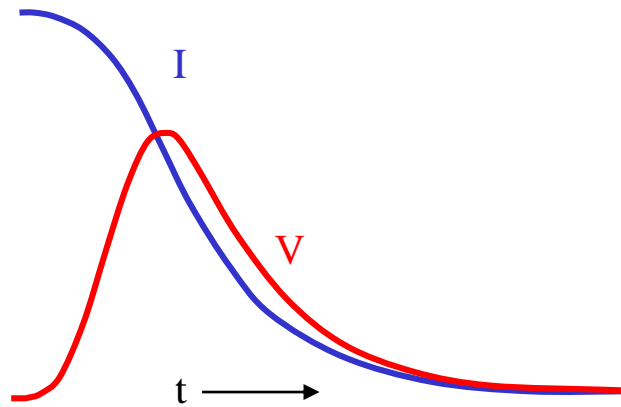
- detect the quench electronically
- power a heater in good thermal contact with the winding
- quenches other regions of the magnet, forcing normal zone to grow more rapidly
  - ⇒ higher resistance
  - ⇒ shorter decay time
  - ⇒ lower temperature rise at the hot spot

⇒ spreads inductive energy over most of winding

*method most commonly used in accelerator magnets ✓*

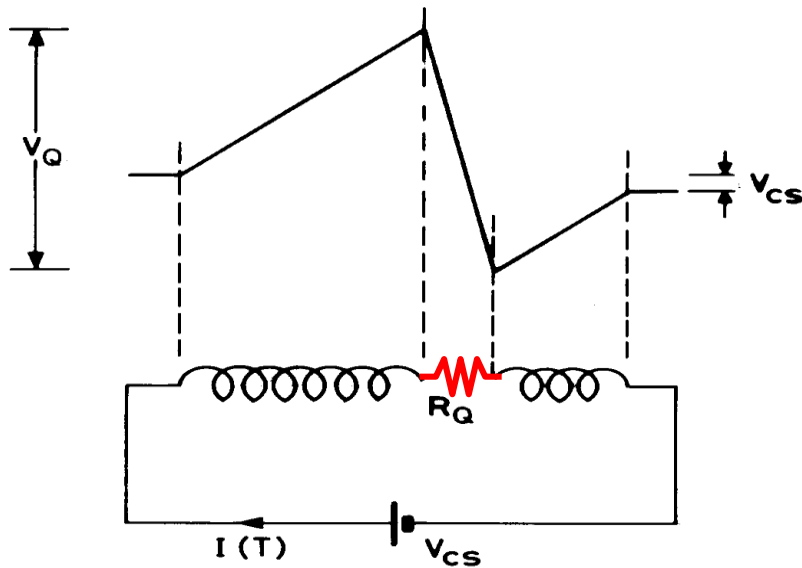
# Methods of quench protection:

## 3) quench detection (a)



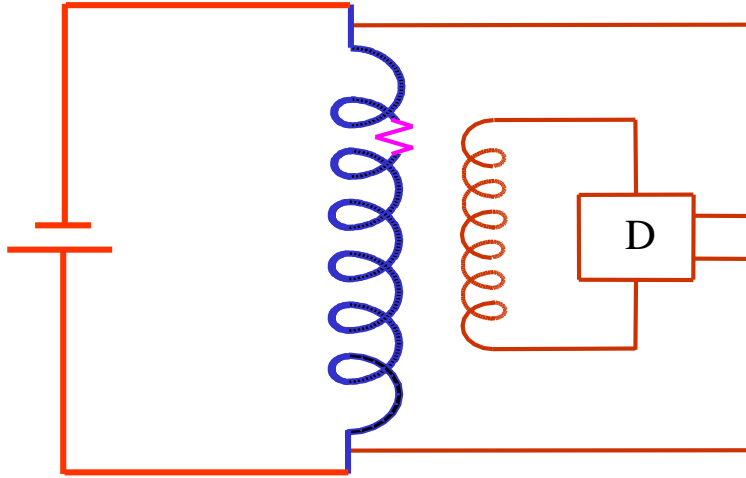
internal voltage after quench 
$$V = IR_Q = -L \frac{dI}{dt} + V_{cs}$$

- not much happens in the early stages - small  $dI/dt \Rightarrow$  small  $V$
- but important to act soon if we are to reduce  $T_Q$  significantly
- so must detect small voltage
- superconducting magnets have large inductance  $\Rightarrow$  large voltages during charging
- detector must reject  $V = LdI/dt$  and pick up  $V = IR$
- detector must also withstand high voltage - **as must the insulation**



# Methods of quench protection:

## i) Mutual inductance



detector subtracts voltages to give

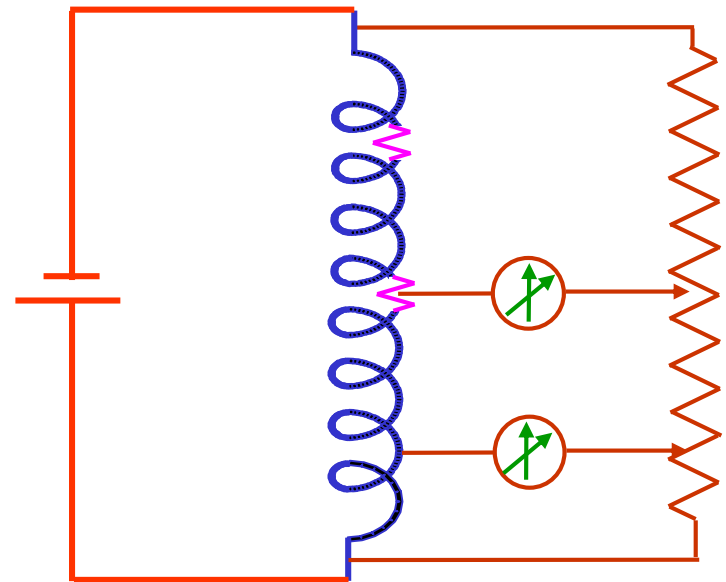
$$V = L \frac{di}{dt} + IR_Q - M \frac{di}{dt}$$

- adjust detector to effectively make  $L = M$
- $M$  can be a toroid linking the current supply bus, but must be linear - no iron!

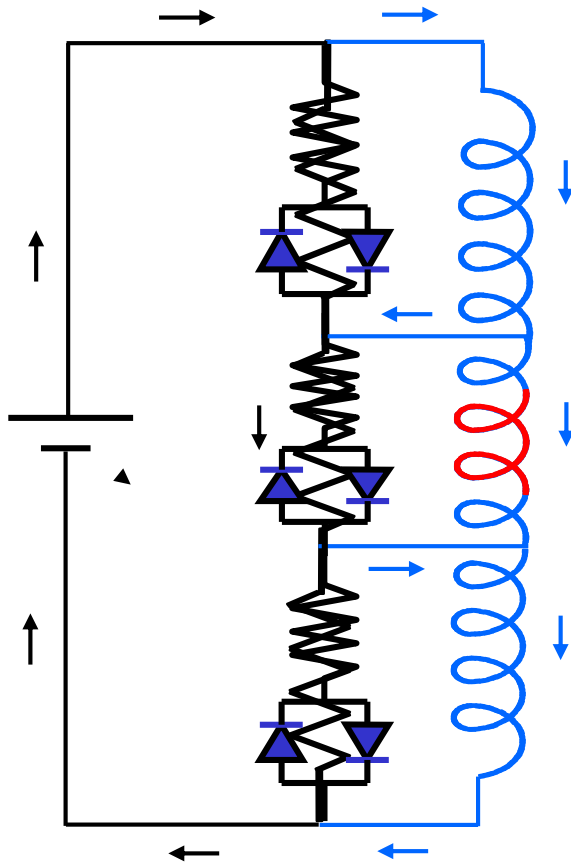
## 3) quench detection (b)

### ii) Balanced potentiometer

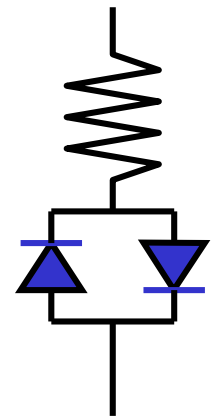
- adjust for balance when not quenched
- unbalance of resistive zone seen as voltage across detector D
- if you worry about symmetrical quenches connect a 2<sup>nd</sup> detector at a different point



# Methods of quench protection: 4) Subdivision

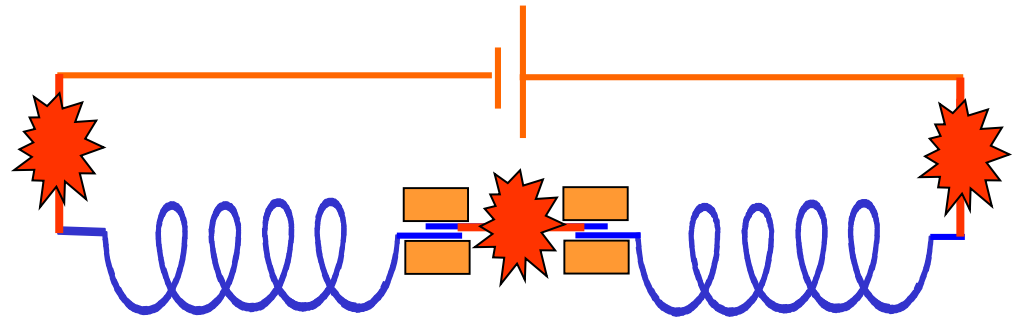


- resistor chain across magnet - cold in cryostat
- current from rest of magnet can by-pass the resistive section
- effective inductance of the quenched section is reduced
  - ⇒ reduced decay time
  - ⇒ reduced temperature rise
- current in rest of magnet increased by mutual inductance
  - ⇒ quench initiation in other regions
- often use cold diodes to avoid shunting magnet when charging it
- diodes only conduct (forwards) when voltage rises to quench levels
- connect diodes 'back to back' so they can conduct (above threshold) in either direction



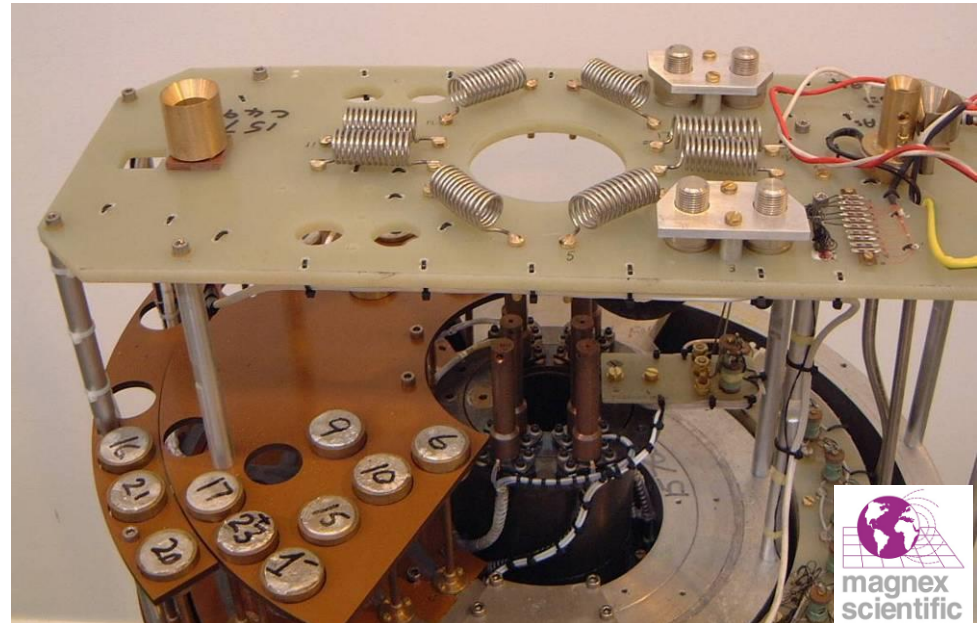


# Inter-connections can also quench



any part of the inductive circuit is at risk

- coils are usually connected by superconducting links
- joints are often clamped between copper blocks
- link quenches but copper blocks stop the quench propagating
- inductive energy dumped in the link
- current leads can overheat



# *LHC dipole protection: practical implementation*

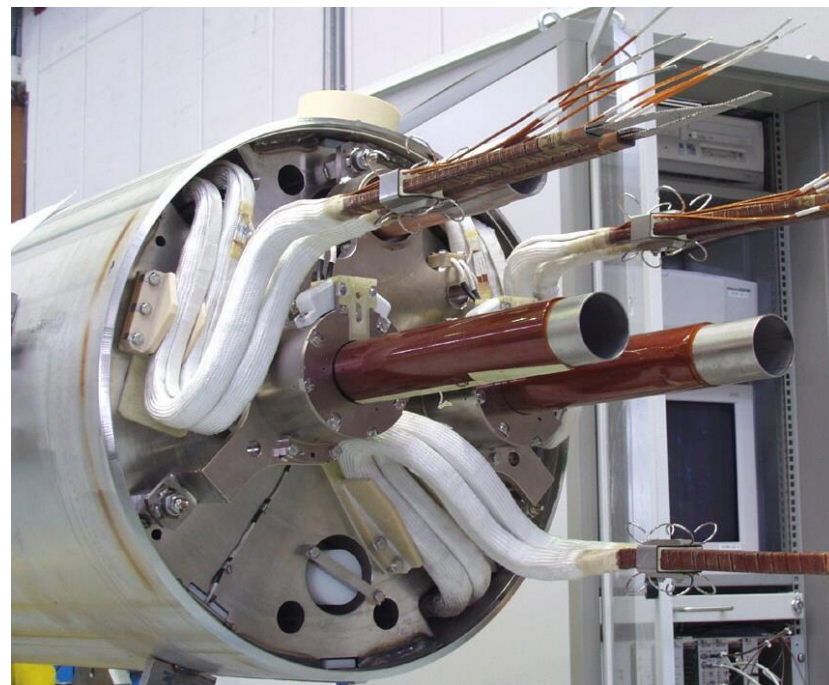
**It's difficult! - the main challenges are:**

## **1) Series connection of many magnets**

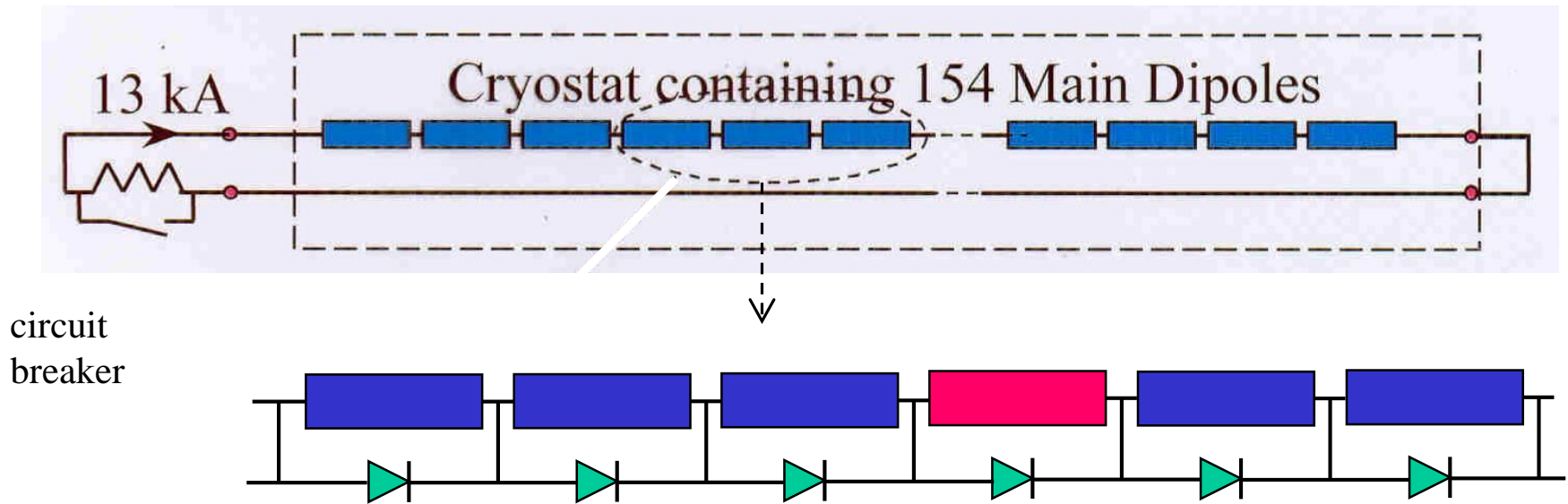
- In each octant, 154 dipoles are connected in series. If one magnet quenches, the combined energy of the others will be dumped in that magnet  $\Rightarrow$  vaporization!
- **Solution 1:** cold diodes across the terminals of each magnet. Diodes normally block  $\Rightarrow$  magnets track accurately. If a magnet quenches, its diodes conduct  $\Rightarrow$  octant current by-passes.
- **Solution 2:** open a circuit breaker onto a resistor (several tonnes) so that octant energy is dumped in  $\sim 100$  secs.

## **2) High current density, high stored energy and long length**

- Individual magnets may burn out even when quenching alone.
- **Solution 3:** Quench heaters on top and bottom halves of every magnet.



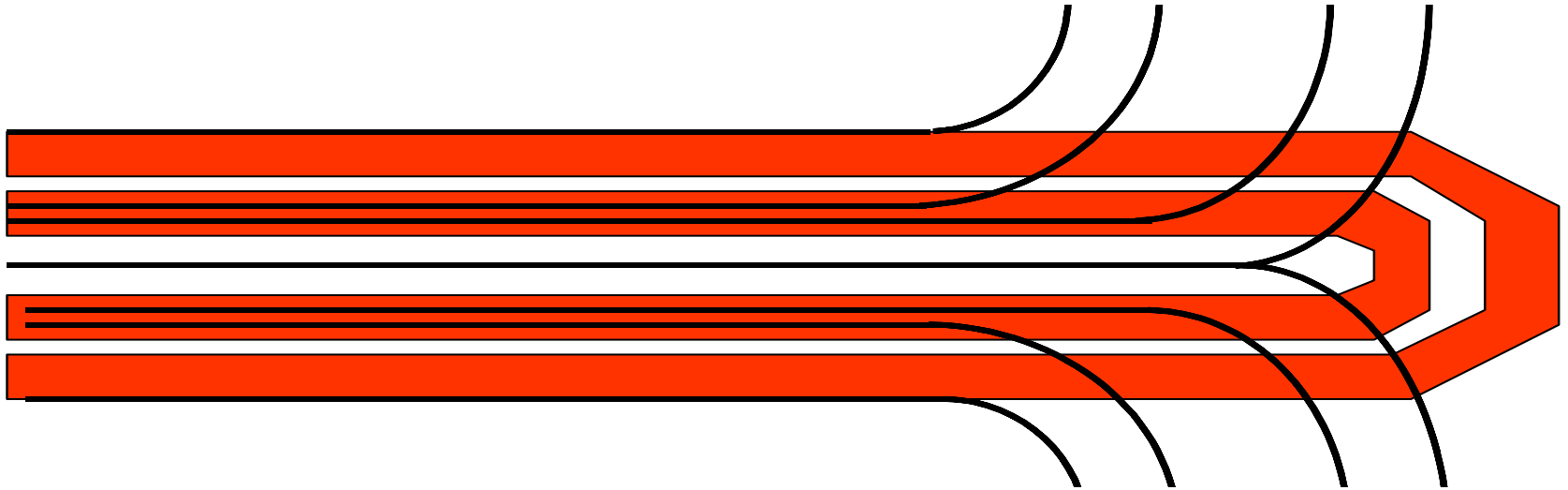
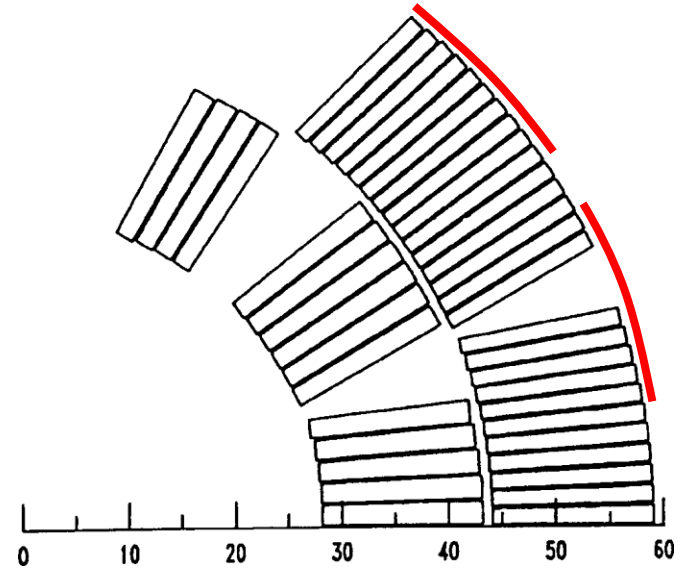
# LHC power supply circuit for one octant



- in normal operation, diodes block  $\Rightarrow$  magnets track accurately
- if a magnet quenches, diodes allow the octant current to by-pass
- circuit breaker reduces to octant current to zero with a time constant of 100 sec
- initial voltage across breaker = 2000V
- stored energy of the octant = 1.33GJ

# LHC quench-back heaters

- stainless steel foil 15mm x 25  $\mu\text{m}$  glued to outer surface of winding
- insulated by Kapton
- pulsed by capacitor 2 x 3.3 mF at 400 V = 500 J
- quench delay - at rated current = 30msec  
- at 60% of rated current = 50msec
- copper plated 'stripes' to reduce resistance





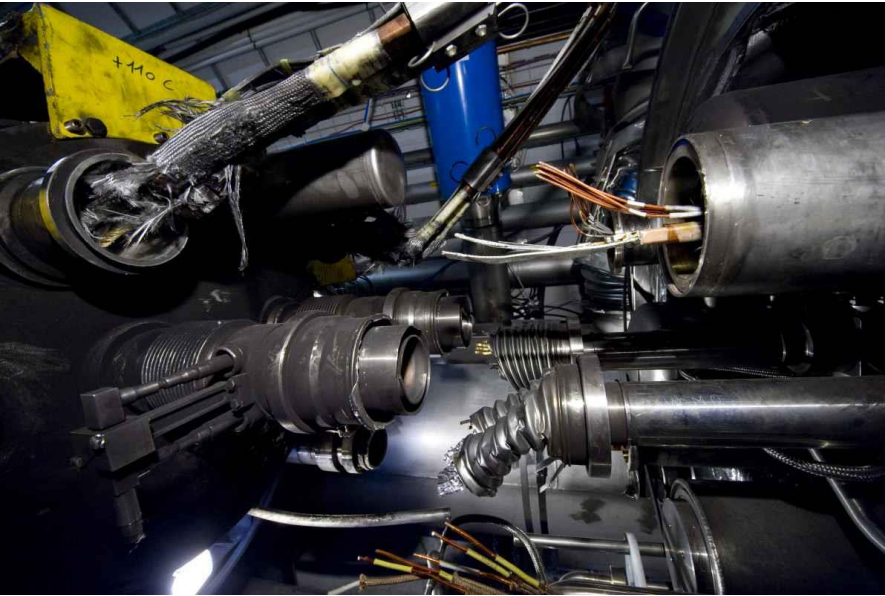
# *Diodes to by-pass the main ring current*

Installing the cold diode package on the end of an LHC dipole





# *Inter-connections can also quench!*



# Quenching: concluding remarks

- magnets store large amounts of energy - during a quench this energy gets dumped in the winding  
⇒ intense heating ( $J \sim$  fuse blowing)                      ⇒ possible death of magnet
- temperature rise and internal voltage can be calculated from the current decay time
- computer modelling of the quench process gives an estimate of decay time  
– but must decide where the quench starts
- if temperature rise is too much, must use a protection scheme
- active quench protection schemes use quench heaters or an external circuit breaker  
– need a quench detection circuit which rejects  $LdI/dt$  and is **100% reliable**
- passive quench protection schemes are less effective because  $V$  grows so slowly at first  
– but **are** 100% reliable
- don't forget the inter-connections and current leads

**always do quench  
calculations before  
testing magnet ✓**





china eu india japan korea russia usa

**ITER**  
 Cadarache  
 France  
 first plasma 2020?  
 $B_{\text{maxTF}} = 11.8\text{T}$   
 $R_0 = 6.2\text{m}$   
 $B_{\text{maxCS}} = 13\text{T}$   
 $E_{\text{TF}} = 41\text{GJ}$   
 output power  
 500MW

