



# A Geodetic Reference Frame for the Virgo Interferometer

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# OUTLINE

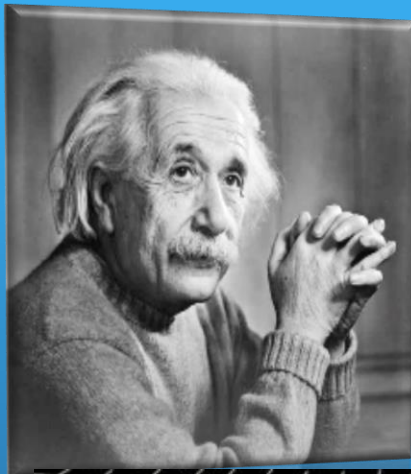
- Introduction: EGO and Gravitational Waves Network
- Surveying activities over years
- VRS network monumentation
- Establishment of VRS for Advanced Virgo
- Geographic Location of the detector
- 2011-16: Alignment Activities

A.Paoli - IWAA 2016 - ESRF Grenoble, 3-7 October 2016

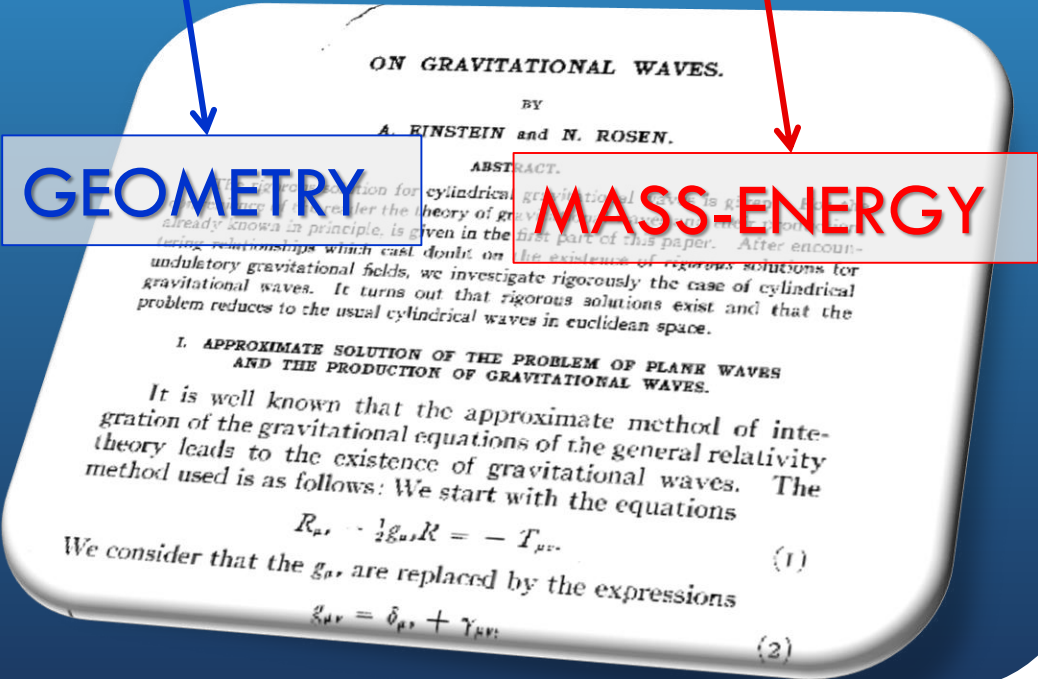
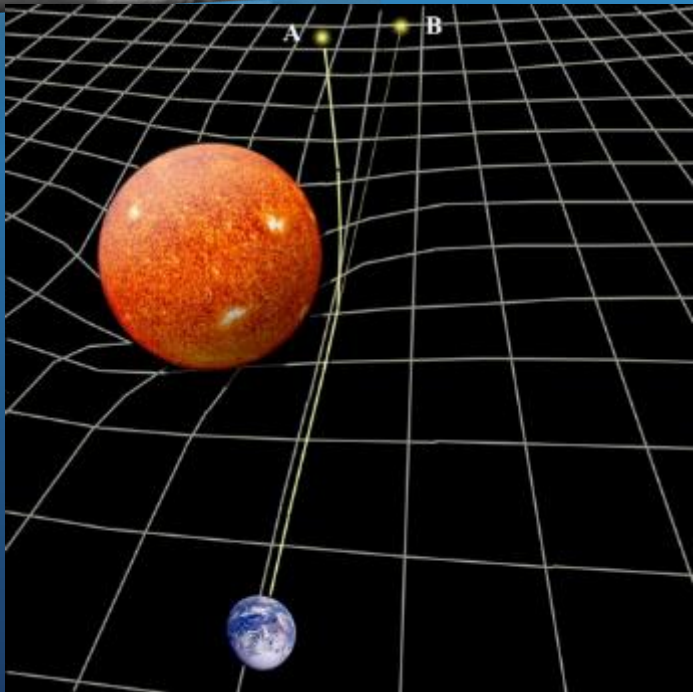
*The European Gravitational Observatory, site of the Virgo interferometer, is located in the countryside of the Comune of Cascina, a few kilometers from town of Pisa*



# GENERAL RELATIVITY



$$G_{mn} = \frac{8pG}{c^4} T_{mn}$$



# GW 150914: FACTSHEET

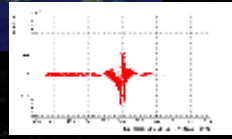
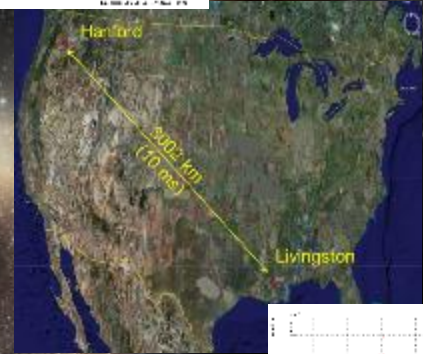
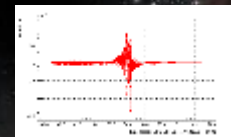
BACKGROUND IMAGES: TIME-FREQUENCY (HALL TOP) AND TIME-SERIES (BOTTOM) IN THE TWO DETECTORS; SIMULATION OF BLACK HOLE HORIZON (MIDDLE TOP); BEST-FIT WAVEFORM (MIDDLE-BOTTOM)

observed by	LIGO WA, LA	arrival time delay between WA and LA	7 ms
source type	black hole (BH) binary	signal-to-noise ratio	24
date	14 Sept 2015	false alarm prob.	$< 2 \times 10^{-7}$
time	09:50:45 UTC	false alarm rate	1 in 200,000 yr
distance	1.3 Gly, 410 Mpc	coalescence rate	2-400 Gpc <sup>3</sup> yr <sup>-1</sup>
redshift	0.09	peak strain	$1 \times 10^{-21}$
<b>Detector Frame Masses <math>M_{\odot}</math></b>			
total mass	70	peak displacement of interferometers arms	0.004 Fmms
chirpmass	30	peak amp. frequency	150 Hz
primary BH	39	peak speed of black holes	$\sim 0.6 c$
secondary BH	31	peak luminosity	$3.6 \times 10^{56} \text{ erg s}^{-1}$
remnant BH	67	radiated energy	3 $M_{\odot}$ , 5% of mass
<b>Source Frame Masses <math>M_{\odot}</math></b>			
total mass	65	remnant BH ringdown frequency	250 Hz
chirpmass	28	remnant BH damping time	4 ms
primary BH	36	mass ratio	0.8
secondary BH	29	duration from 30 Hz	200 ms
remnant BH	62	# cycles from 30 Hz	10
primary BH spin	$< 0.7$	consistent with general relativity	Yes
secondary BH spin	$< 0.9$	graviton mass bound	$< 1.2 \times 10^{-22} \text{ eV}$
remnant BH spin	0.7	online trigger latency	2 minutes
spin in orbital plane	0	offline analysis pipelines used	5
remnant size, area	180 km, $2.5 \times 10^5 \text{ km}^2$	CPU hours consumed	$\sim 50$ million
orientation	face-on/off	papers on Feb 11, 2016	13
sky location	southern hemisphere	no. of researchers	$\sim 3000$ in 16 countries
resolved to	600 sq. deg.		

1<sup>st</sup> Detection - September 14, 2015 at 09:50:45 UTC  
 Observation of Gravitational Waves from a Binary Black Hole Merger

2<sup>nd</sup> Detection - December 26, 2015 at 03:38:54 UTC

The era of gravitational wave astronomy has started!



## GW Network



H1- Hanford – Washington State



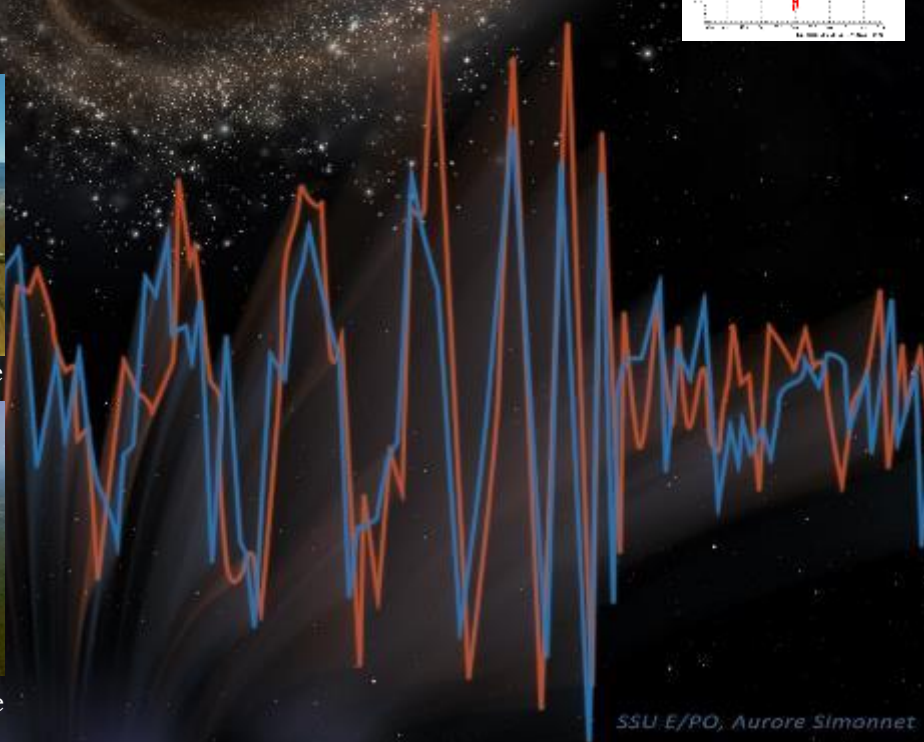
Virgo – Cascina (Pisa) – EGO Site



GEO600 – Hannover - Germany



L1- Livingston – Louisiana State



# SURVEYING ACTIVITIES OVER YEARS

*Realization of civil engineering works: Experimental Buildings, Tunnels, Technical Buildings, Office Buildings, Roads, Bridges, Site Layout Works*

*Main issue: realization of the 3+3km orthogonal tunnels with earth curvature correction*

Tunnels and Bridges



West End Building



Central Building



Site Layout Works



Construction of Tunnels



Inside Tunnel



EGO Main Building



# SURVEYING ACTIVITIES OVER YEARS

- 1994-95: 1<sup>st</sup> levelling/GPS surveys of the Virgo Area
- 1998-99: Alignment of the central interferometer
- 2000-02: Alignment of the vacuum tubes and End Towers
- 2003-16: Monitoring of buildings/tunnel displacements
- 2011-16: Alignment of Advanced Virgo

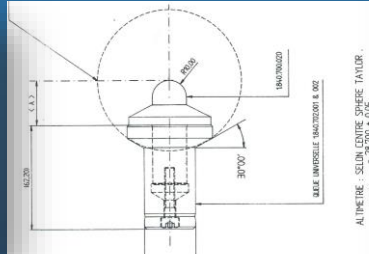


# NETWORK MONUMENTATION

VRS (Virgo Reference System) network used for surveying activities developed over years and periodically checked and maintained

It includes ~500 internal main reference points, materialized with accurate centering system and monographed:

- ~80 located in 4 Experimental Buildings
- 200 + 11 GPS in the North Tunnel
- 200 + 11 GPS in the West Tunnel



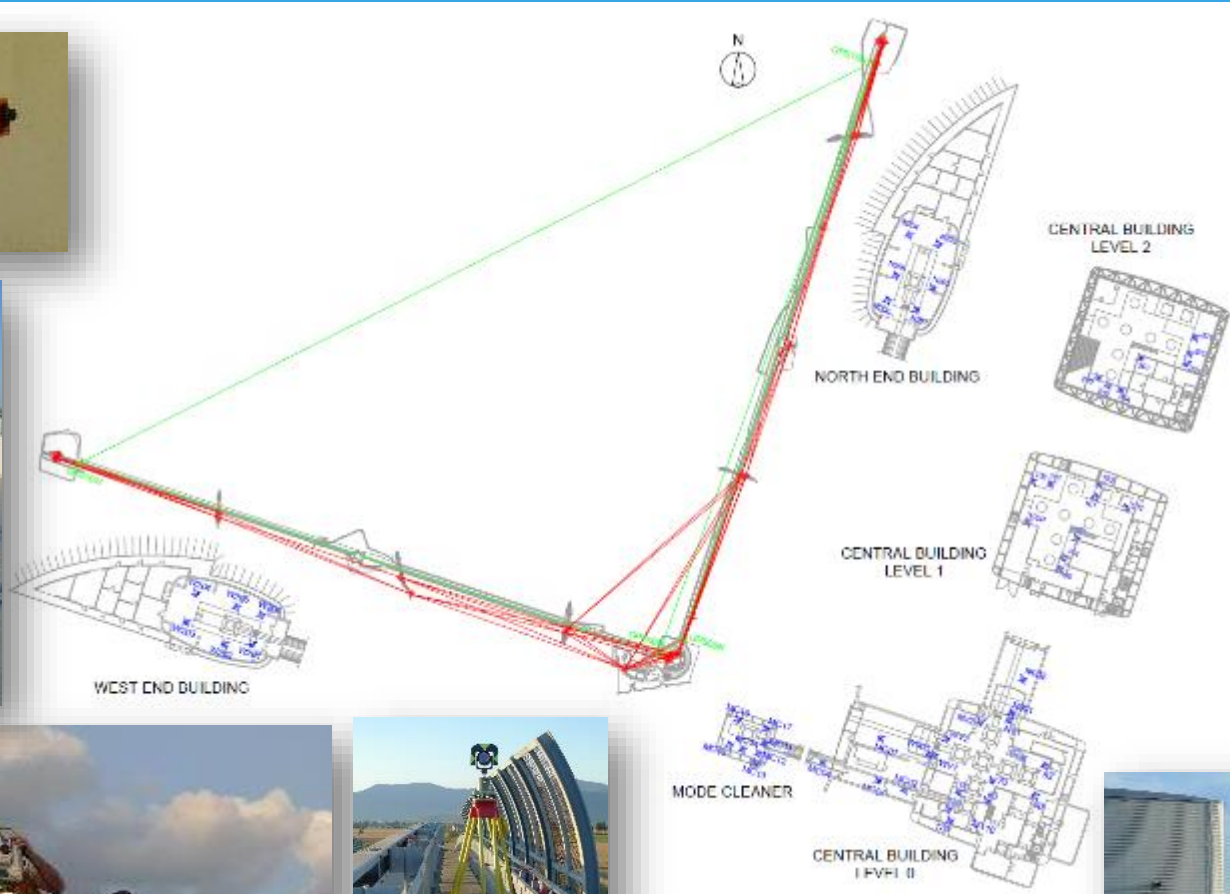
External network made of ~30 concrete pillars distributed along the tunnels and at the experimental building areas





# VRS NETWORK SURVEY

- 2011-14: Installation, survey and establishment of VRS
- Integrating TS measurements (red) with GNSS baselines (green)
- Trimble GNSS receivers; Leica TM50 & TDA5000 + Wild NL plummet



# VRS ESTABLISHMENT

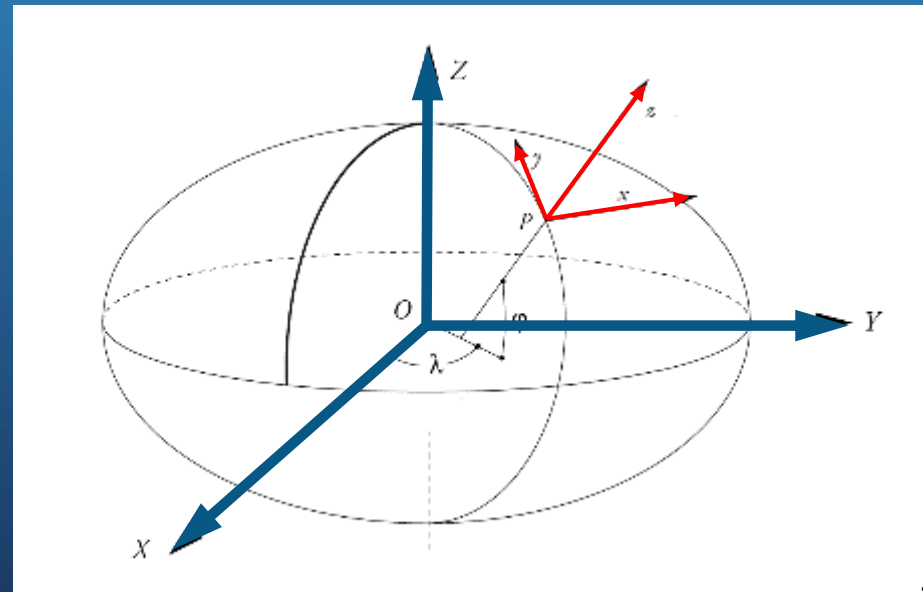
- **5** GNSS stations – 3 session each lasting 24h processed separately (Bernese) - network solution including 10 permanent stations  
*3 solutions averaged both for the coordinates and the corresponding errors*  
 $\sigma_X \sigma_Y \sigma_Z$
- ~ **65** internal + **30** external stations TM50 (TDA5000)
  - 3 (pos.I) + 3 (pos.II) obs. each point
  - Slope distance values corrected for the refraction taking into account the atmospheric parameters (T, p, RH) provided by EGO meteo station
  - Azimuthal and Zenithal measurements corrected to refer them to the ERS (Eulerian Reference System) using formula of Brovelli M. et al. (1989)

ETRF Geocentric Cartesian Reference System

ERS Eulerian Reference System

*Appr. pos.  $O(x,y,z)$  ERS in correspondence of the center of Virgo interferometer*

*$\phi_0, \lambda_0$  and  $(X_0, Y_0, Z_0)$  rotation angles and translation parameters ETRF  $\rightarrow$  ERS*

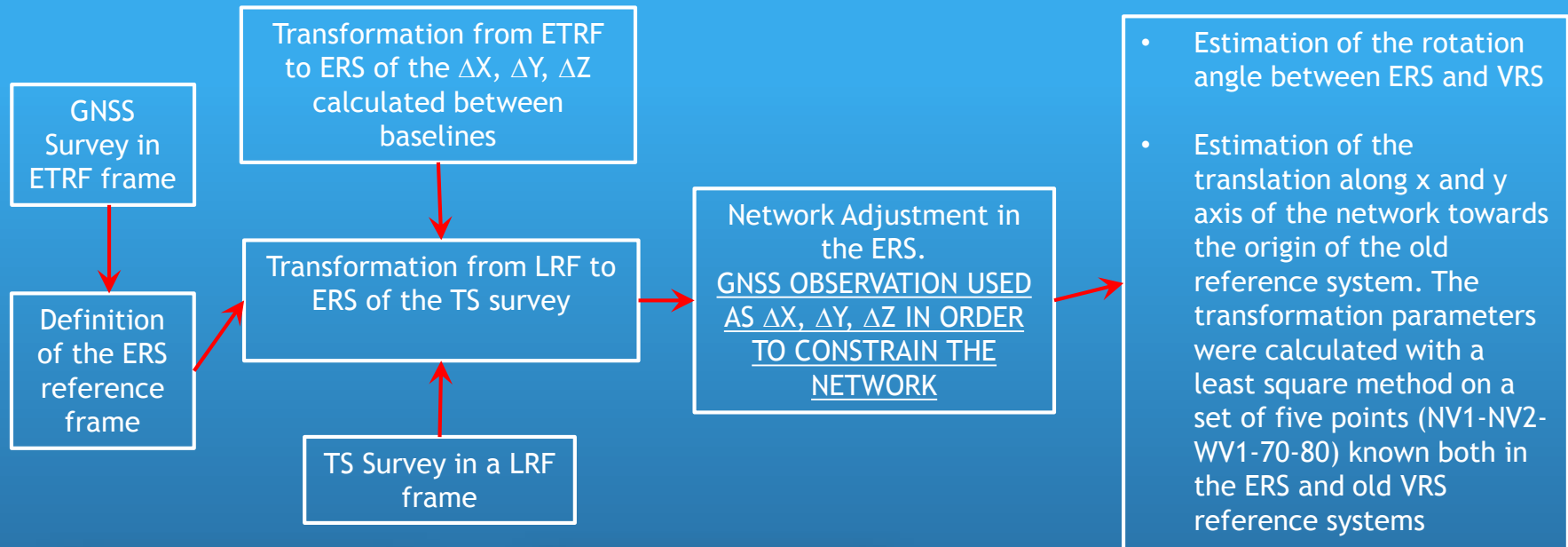


# VRS ESTABLISHMENT

- Network adjustment in ERS using both TS and GNSS observations; GNSS baselines used to constrain the network using the associated rms ( $\sigma_{\Delta x}$ ,  $\sigma_{\Delta y}$  1mm;  $\sigma_{\Delta z}$  2mm)
- Network adjustment performed using both the scientific software CALGE and the commercial software StarNet (MicroSurvey Inc.)
- ERS coordinates finally rototranslated to VRS (Virgo Reference System) oriented in accordance with the laser beam directions ( $X_{\text{VRS}} = \text{-West beam}$ ;  $Y_{\text{VRS}} = \text{North beam}$ )

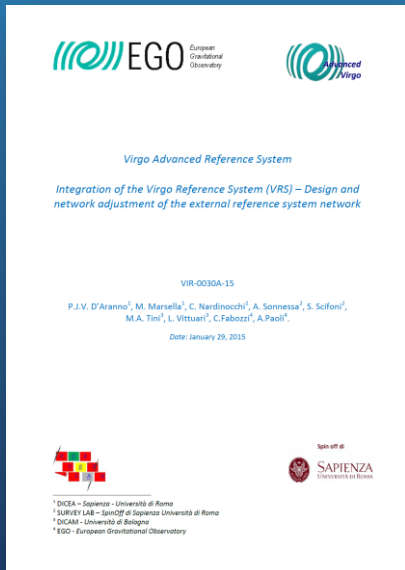
Achieved accuracy of the computed VRS coordinates			
	$\sigma_x$ [mm]	$\sigma_y$ [mm]	$\sigma_z$ [mm]
Average	0.91	0.86	1.42
St.Dev.	0.61	0.52	1.05

# VRS ESTABLISHMENT – process scheme



- Estimation of the rotation angle between ERS and VRS
- Estimation of the translation along x and y axis of the network towards the origin of the old reference system. The transformation parameters were calculated with a least square method on a set of five points (NV1-NV2-WV1-70-80) known both in the ERS and old VRS reference systems

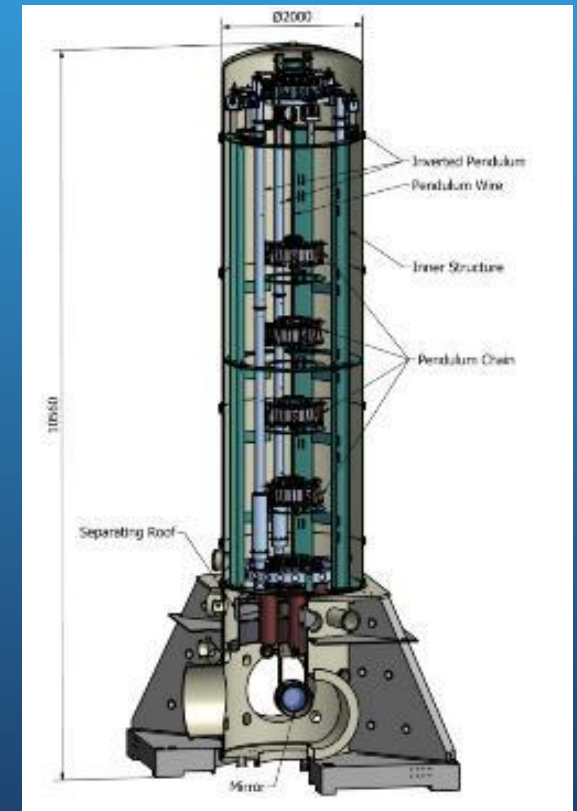
Shift in the Z direction, calculated as the average of the differences between 70-80-NV1-NV2-WV1-108P point height, belonging to the Central Building and the corresponding heights determined by previous surveys.



# GEOGRAPHIC LOCATION

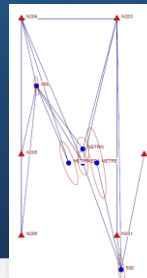
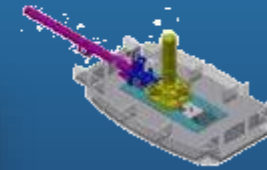
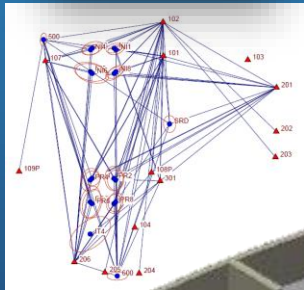
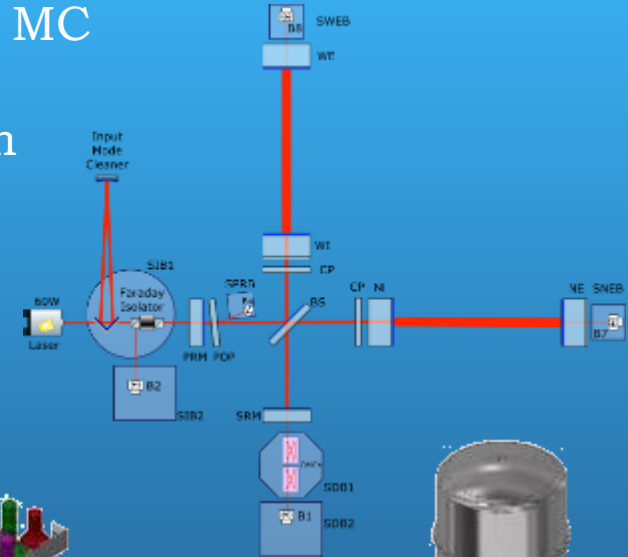
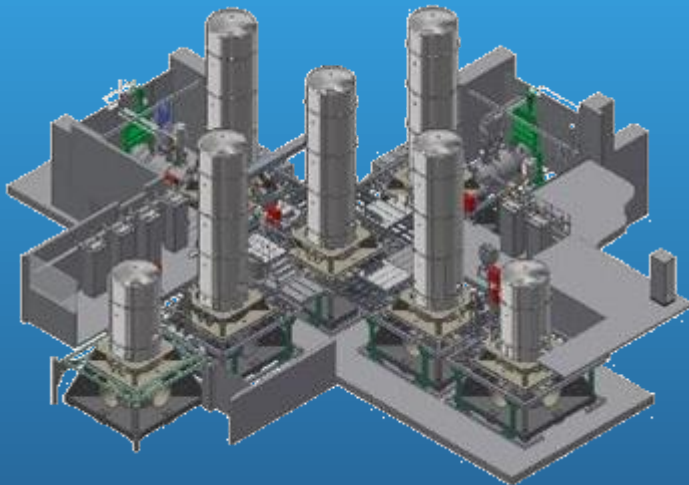
- Establishing VRS reference frame and the transformation parameters ETRF → VRS allowed the calculation of the position of the Virgo vertexes, i.e the centers of the suspended mirrors, not directly visible
- Coordinates calculated by the inverse transformation VRS → ETRF
- Geographic location and orientation of Advanced Virgo respect the other detectors are fundamental informations for the contemporary detection of GW signals

Point ID	LAT	LONG	h (m)
BS	43° 37' 53".1061 N	10° 30' 16".2095 E	53.089
NE	43° 39' 24".9464 N	10° 31' 00".8387 E	52.899
WE	43° 38' 25".4873 N	10° 28' 09".7533 E	51.575



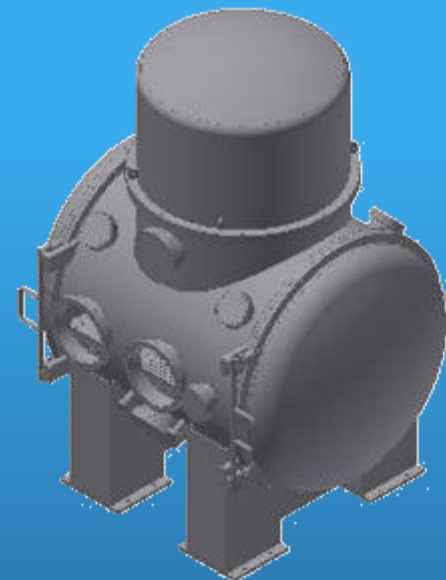
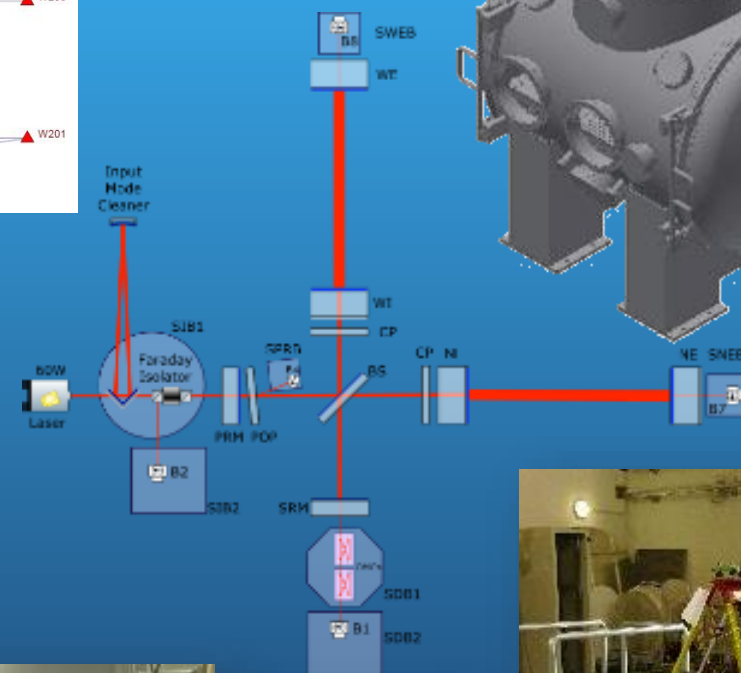
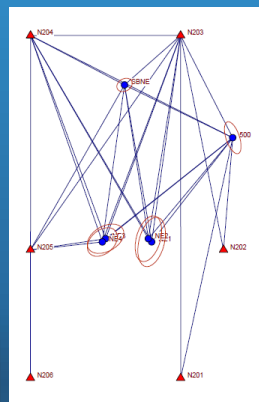
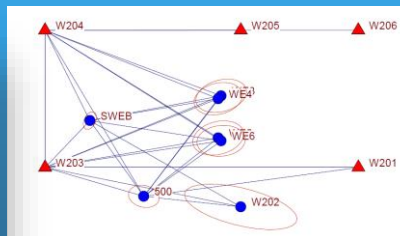
# ADVANCED VIRGO - SURVEY ACTIVITY

- Displacement and alignment of large vacuum chambers:
  - 7 “long” towers (11m H; ~30 tons): BS, NI, WI, PR, SR, NE, WE
  - 3 “short” towers (6.5m H; ~20 tons): IT, DT, MC
- Displacement range for AdV: from 2 to 626mm



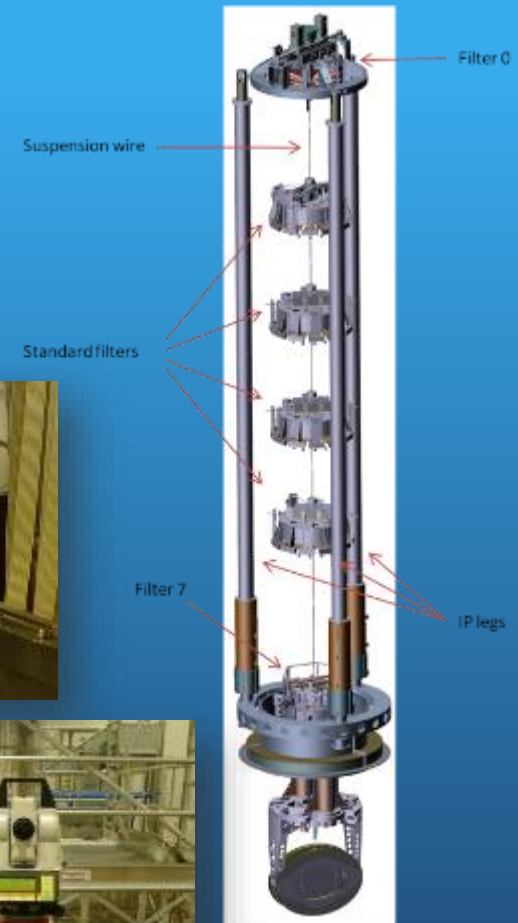
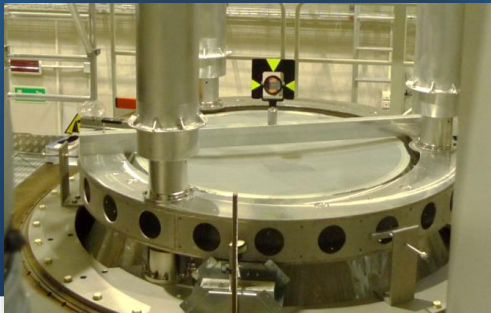
# ADVANCED VIRGO - SURVEY ACTIVITY

- Alignment of 5 new vacuum chambers “minitowers”:
  - SIB2, SDB2, SPRB in Central Building
  - SNEB, SWEB in North and West End Building



# ADVANCED VIRGO - SURVEY ACTIVITY

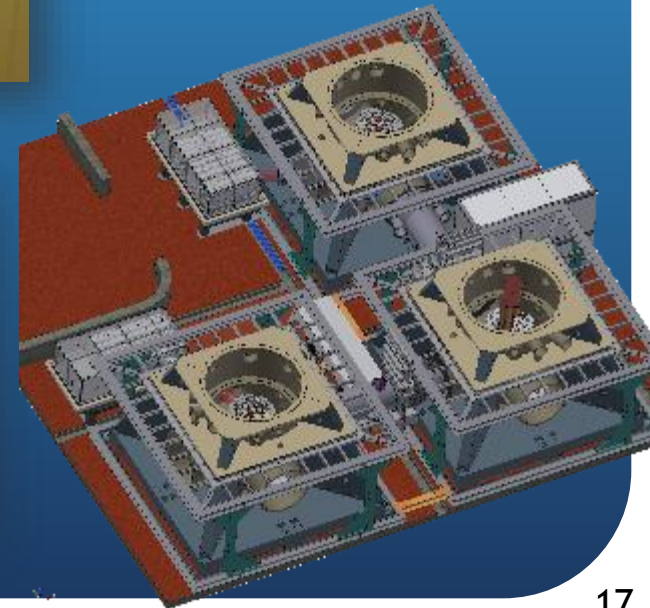
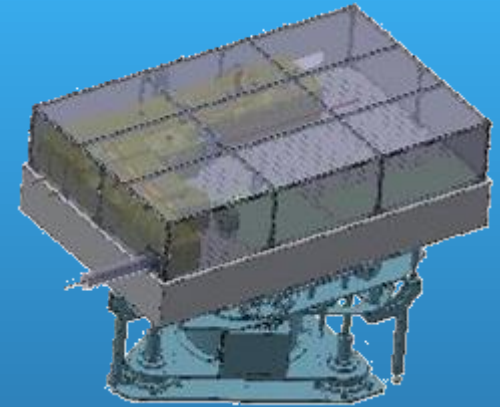
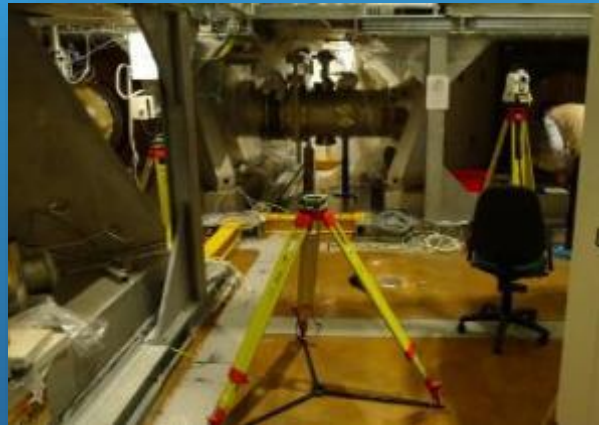
- Alignment of mirror suspensions:
  - 7 “long” towers: BS, NI, WI, PR, SR, NE, WE
  - 3 “short” towers: IT, DT, MC





# ADVANCED VIRGO - SURVEY ACTIVITY

- Alignment of 7 in-air and 2 in-vacuum optical benches:
  - Injection System: LB, IB, EIB
  - Detection System: DB, EDB
  - Thermal Compensation System: NI, WI, NE, WE



# ADVANCED VIRGO - SURVEY ACTIVITY

- Alignment of external references for ITF pre-commissioning activity:
  - Central Building: PRF, NIF, SRF, WIF
  - North End Building: NEF, SNEBF
  - West End Building: WEF, SWEBF



# ADVANCED VIRGO - SURVEY ACTIVITY

- Local networks around the surveyed points, including max possible number of VRS benchmarks
- Observations of sD, H and Z of each point repeated 3 times in both pos.I + pos.II and averaged
- High redundancy of observations for the network adjustment
- Network adjustment performed using the commercial software StarNet (MicroSurvey Inc.)
- Most part of the coordinates obtained for the surveyed points with rms  $(\sigma_x, \sigma_y, \sigma_z) \leq 0.2$  mm

...THANKS for your attention

A.Paoli - IWAA 2016 - ESRF Grenoble, 3-7 October 2016

ALMA MATER STUDIORUM  
UNIVERSITÀ DI BOLOGNA  
DIPARTIMENTO DI INGEGNERIA CIVILE,  
CHIMICA, AMBIENTALE E DEI MATERIALI



SAPIENZA  
UNIVERSITÀ DI ROMA

SPARE SLIDES

# MONITORING SOIL SETTLEMENTS AT THE VIRGO SITE

# MONITORING of BUILDINGS

Since the end of the construction a significant subsidence of the tunnels was observed

The interferometer must be in a plane

Virgo and its vacuum tubes are designed for re-alignment of the modules

Our reference is the Central Building (CB)  
Relative displacements for both the tunnel  
ref. pts. (H) and the GPS pts. (plan.)

Accurate levelings: 205 stations/tunnel  
15m distance between each station  
and 7.5m for the staff

Not big variation of T and RH

Tunnel are not ventilated

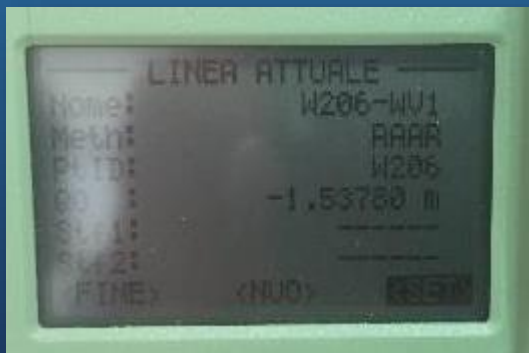


Period	Frequency of monitoring	Instrument
2001	Initial survey	TDA5000
2002÷2006	6 months	NA2+GPM3; DNA03
2007÷2011	12 months	DNA03
2012÷2015	24 months	DNA03

# TUNNEL MONITORING

## Leveling parameters

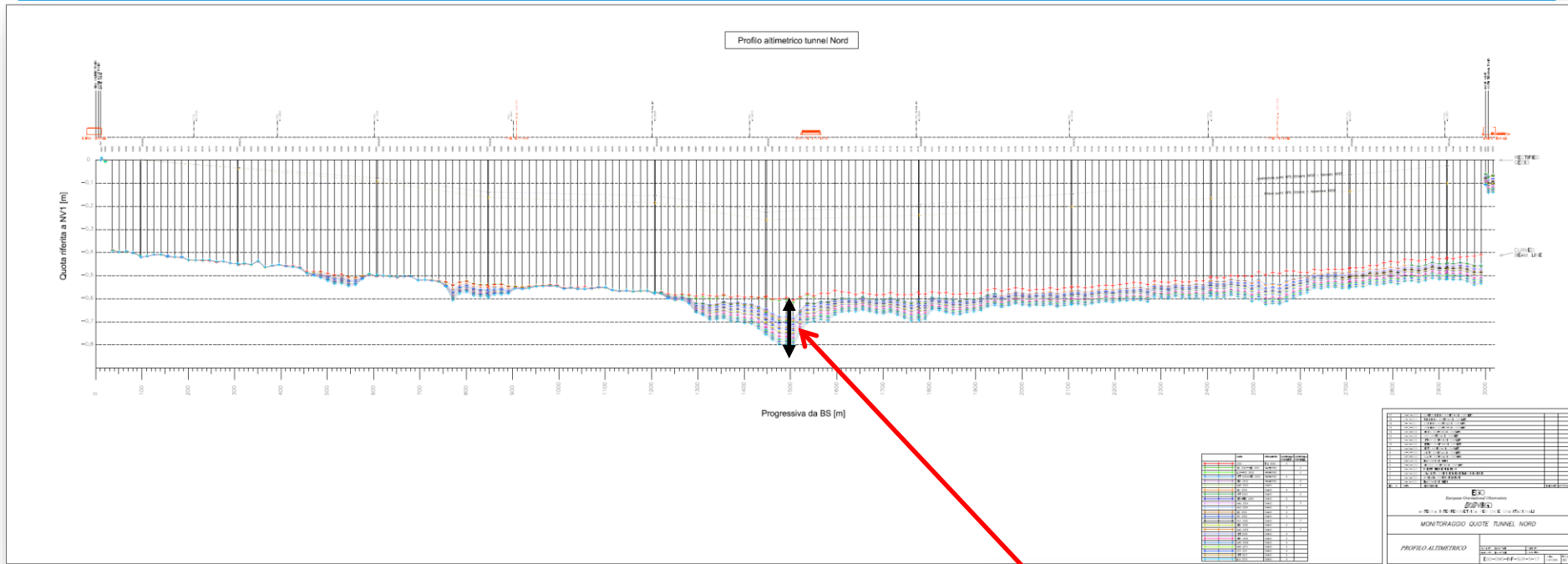
L [m]	3006/line
method (NA2)	NV1(WV1)→N206 (W206); N206→NV1
method (DNA03)	BF NV1(WV1)→N206 (W206); N206→NV1
method (DNA03)	BFFB, aBFFB
n. stations	205/line
starting point	NV1 (WV1), N206 (W206)
measure type	Avg 3 of 5; $chk \sigma/20m < 0.00005 \text{ m}$
tolerances	St > 0.5m; DBal < 0.5 m; Dmax 8m
max closure error (NA2)	4.42 mm
min closure error (NA2)	3.76 mm
max closure error (DNA03)	0.98 mm
min closure error (DNA03)	0.04 mm



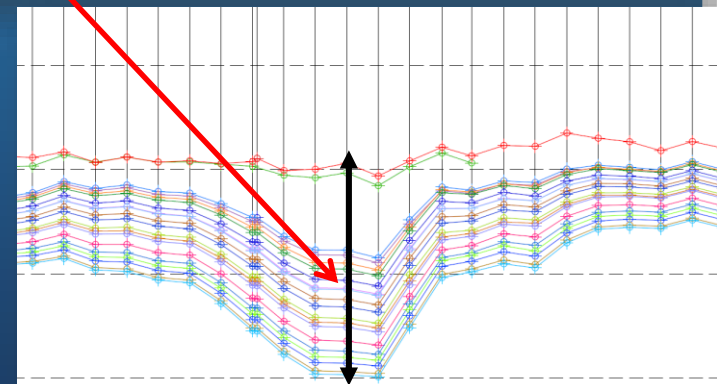


# TUNNEL MONITORING

## North Tunnel

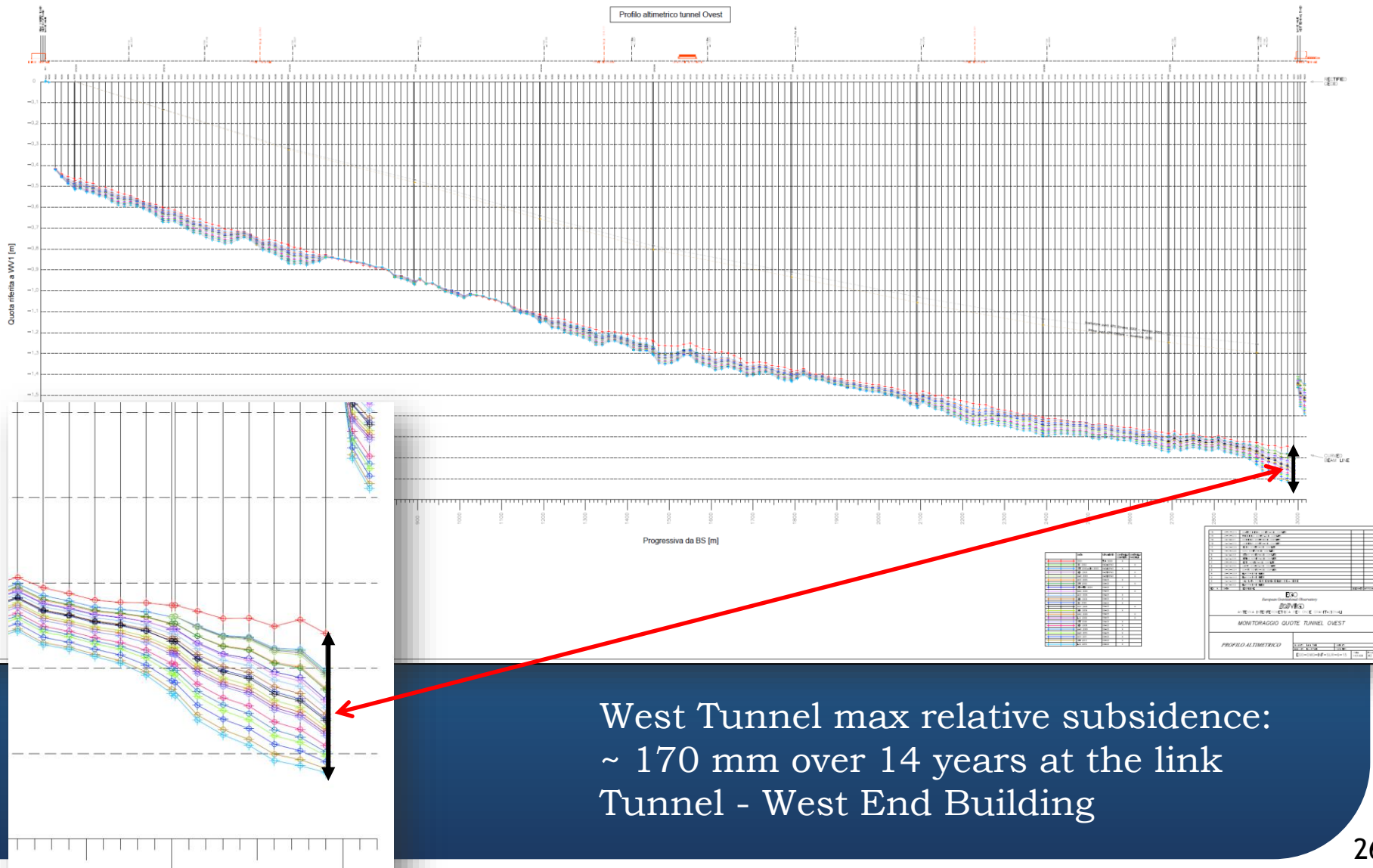


North Tunnel max relative subsidence:  
~ 205 mm over 14 years at middle of  
the Tunnel



# TUNNEL MONITORING

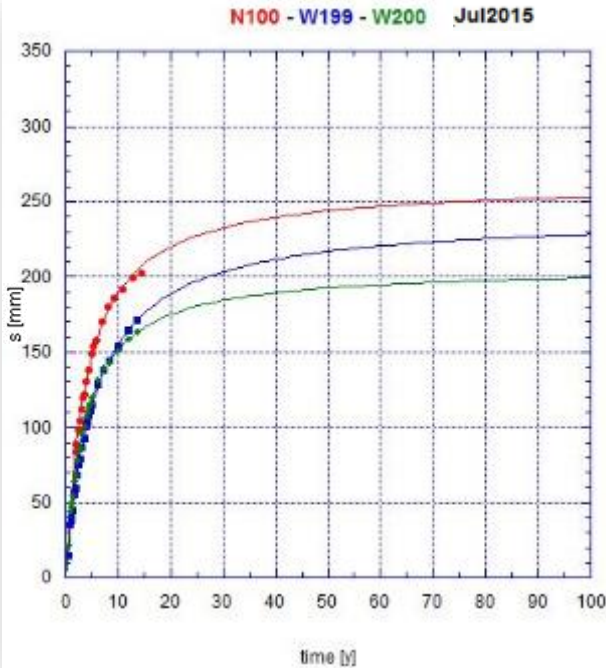
## West Tunnel



West Tunnel max relative subsidence:  
~ 170 mm over 14 years at the link  
Tunnel - West End Building

# TUNNEL MONITORING

## Trendlines for the major displacements observed



$$y = m1 \cdot x / (m2 + x)$$

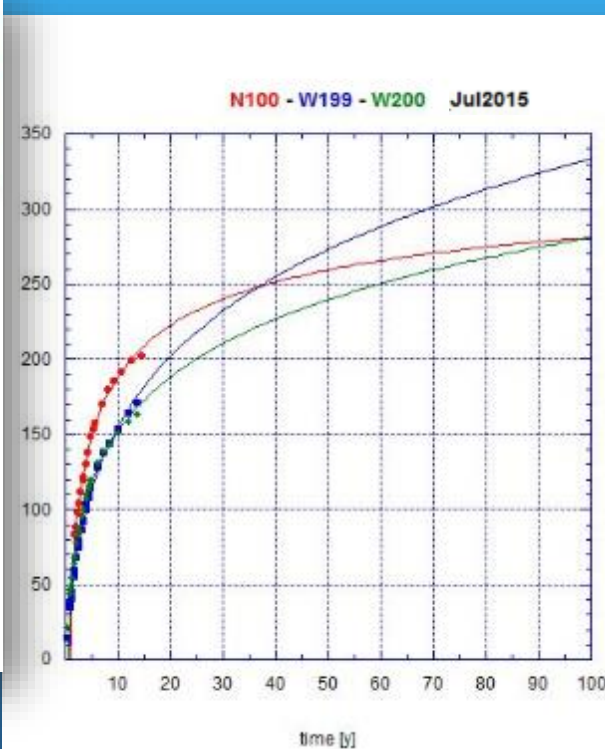
	Value	Error
m1	263.08	2.6928
m2	3.9333	0.099495
Chisq	70.999	NA
R <sup>2</sup>	0.99725	NA

$$y = m1 \cdot x / (m2 + x)$$

	Value	Error
m1	240.83	2.4282
m2	5.5361	0.11246
Chisq	44.475	NA
R <sup>2</sup>	0.99897	NA

$$y = m1 \cdot x / (m2 + x)$$

	Value	Error
m1	206.53	1.6525
m2	3.63	0.06823
Chisq	42.082	NA
R <sup>2</sup>	0.9988	NA



$$y = m1 + m2 \cdot \log(x) + m3 \cdot (\log(x))^2$$

	Value	Error
m1	33.848	4.6338
m2	184.5	14.188
m3	-30.442	9.8457
Chisq	124.32	NA
R <sup>2</sup>	0.99518	NA

$$y = m1 + m2 \cdot \log(x) + m3 \cdot (\log(x))^2$$

	Value	Error
m1	36.894	0.84716
m2	87.009	3.109
m3	30.568	3.089
Chisq	112.03	NA
R <sup>2</sup>	0.99741	NA

$$y = m1 + m2 \cdot \log(x) + m3 \cdot (\log(x))^2$$

	Value	Error
m1	46.381	0.94099
m2	92.897	3.4533
m3	12.252	3.4311
Chisq	138.22	NA
R <sup>2</sup>	0.99607	NA

Analysis for max displacement at  $t=\infty$   
 in the range 200÷300 mm  
 Several fit curves: best R<sup>2</sup> according  
 logarithmic law (order 2) or  $m_1 \cdot x / (m_2 + x)$

No big problem: settlements compatible  
 with the realignment system (...and the  
 roof of the tunnel!)

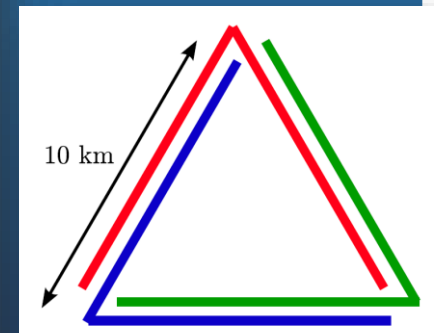
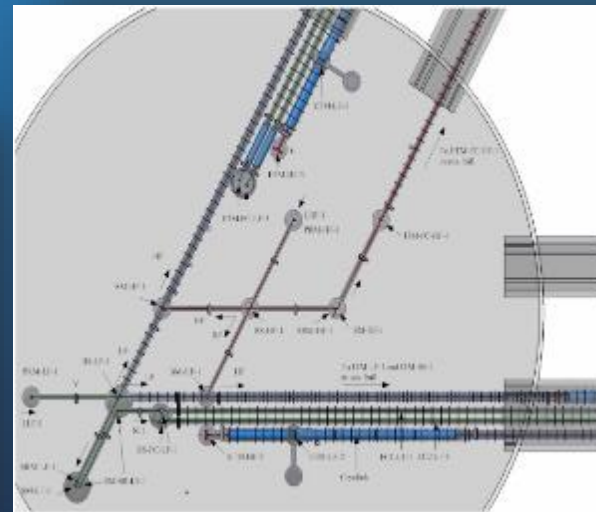
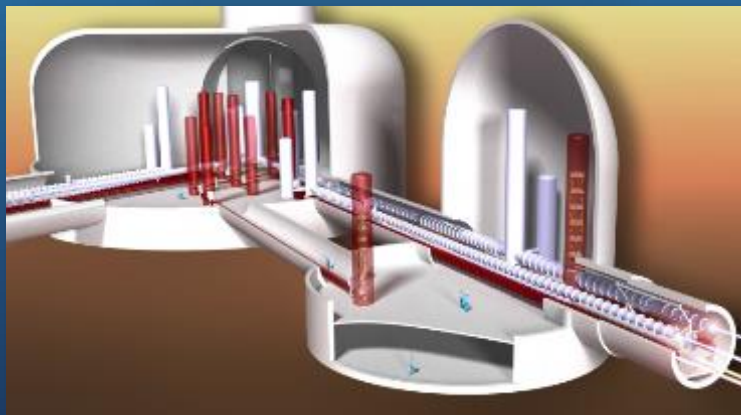
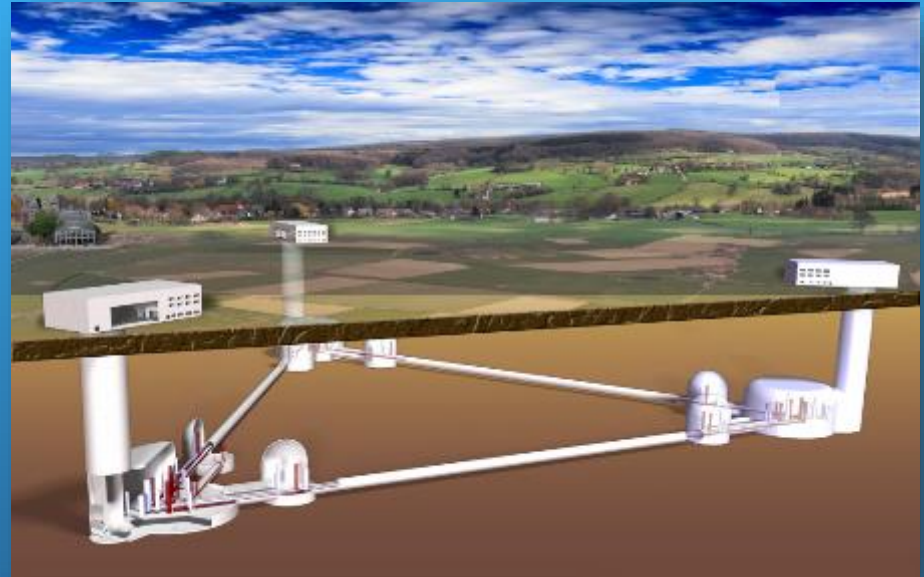
Left curves more coherent with  
 geotechnical studies available in literature

Hypothesis with constant external factors  
 (i.e. no large variations of the water deep  
 stratum height or loading of the adjoining  
 soil)

# FUTURE GRAVITATIONAL WAVES PROJECT

# GEODESY & METROLOGY for FUTURE PROJECTS

## *Einstein Telescope*



# EINSTEIN TELESCOPE

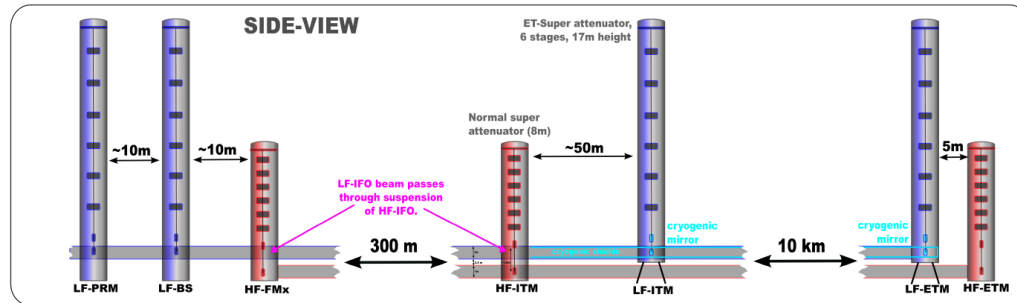
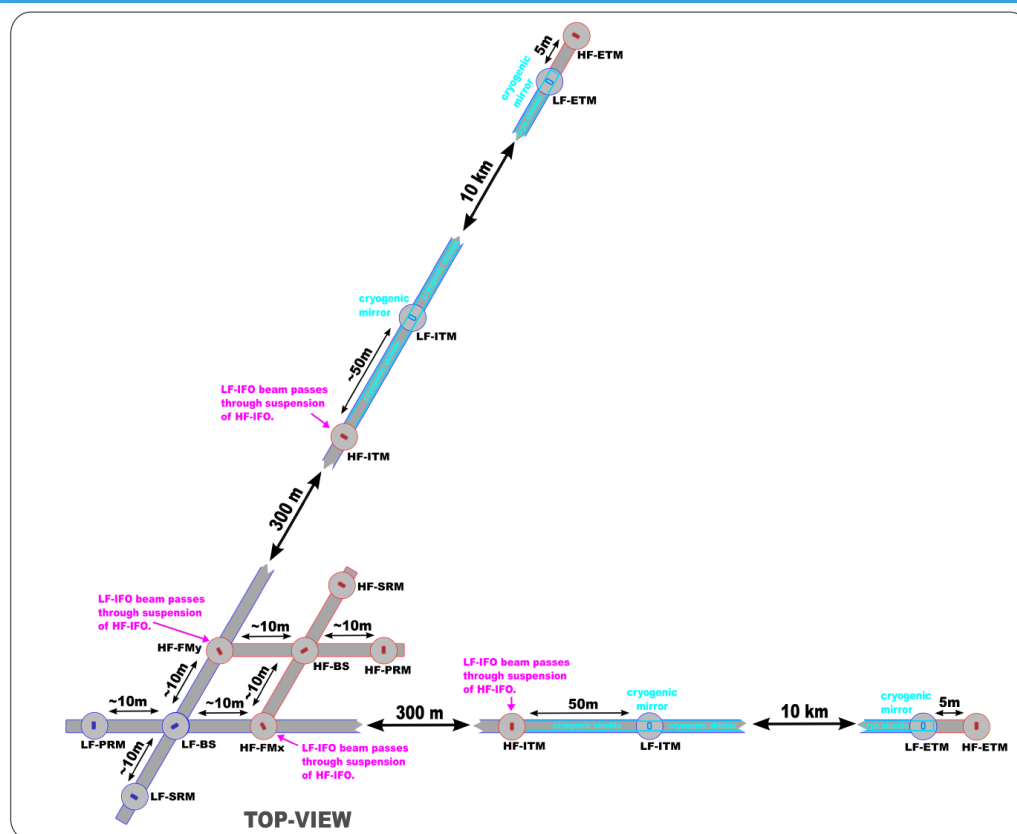
## *Conceptual Design*

### *Main features and infrastructure facilities*

- 3 nested detectors arranged in a triangular shape with 10 km side
- from 100m to 200m depth underground (hopefully > 200m?)
- Xylophone scheme up to 6 folded interferometer
- 3 interferometer for Low frequency – 3 for High frequency
- LF interferometer → cryogenic test masses
- HF interferometer → high power laser
- 3 underground corner caverns (Ø 65m, H 30m) and 6 satellite caverns (Ø 30m, H 30m)
- Tunnel inner Ø 5.5÷6.0m; double tunnel (300m) linking corner and satellite caverns
- Surface facilities and vertical shafts (in relation to the site location)

# EINSTEIN TELESCOPE

*Scheme of LF and HF core interferometers of a single ET detector*







# EINSTEIN TELESCOPE

*...thinking to the start of the Tech Design*

- *Design of surface and underground Reference Network*
- *Materialization of the reference points network*
- *Definition of specifications and planning for surveys and monitorings*
- *Transfer of the surface network to underground: technologies, study and design*
- *“Fiducialisation” and optimization of the reference point network; design for the different components of the LF and HF interferometers*
- *Integration of the fiducials in the mechanics, vacuum and optics*
- *.....and many other topics!*