

Survey of the Fermilab NOvA Detectors

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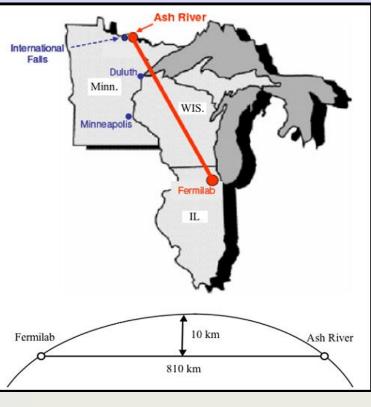
The NOvA Experiment

NOvA: NuMI Off-Axis v_e Appearance Experiment v_e = electron neutrino

- North America's most advanced neutrino experiment
- The NOvA project includes accelerator upgrades to bring the NuMI (Neutrino at Main Injector) beam intensity from 400 kW to 700 kW
- Uses two detectors to look for changes in the neutrino beam as it travels:
- Far Detector in Ash River, Minnesota
- **Near Detector** at Fermilab
- The NOvA detectors are sited 14.6 mrad off the center of the NuMI beam axis
- Mostly active liquid scintillator Near and Far Detectors and PVC plastic
- Full operation began in October 2014
- Scheduled to Run at least till 2021

MINOS Far Detector (Soudan, MN

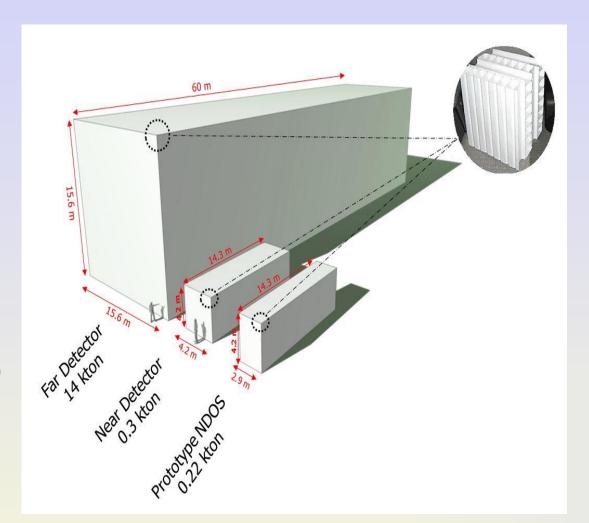
Far Detector Site



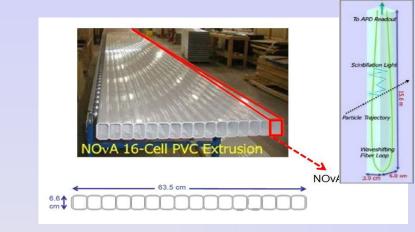
- This site is at 810 km from Fermilab, about 11.8 km off-axis from NuMI beam
- The Ash River site, near Canadian border, is the farthest available site from Fermilab in the U.S. along the NuMI beamline

NOvA Detectors

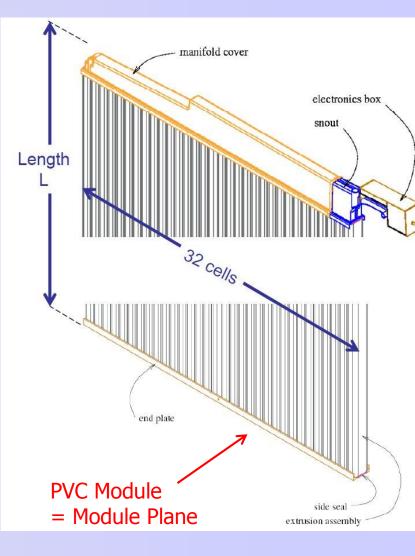
- A 14 kton Far Detector at a distance of 810 km from the NuMI Target (Completed at Ash River in July 2014)
- A 0.33 kton Near Detector identical to the Far Detector at a distance of 1 km from the NuMI Target (Completed at Fermilab in February 2014)
- An 0.22 kton prototype NDOS (Near Detector On the Surface) identical to the Near Detector sited on the surface 107 mrad off the NuMI beam axis at Fermilab (Completed in 2010 and operated till January 2013)



NOvA Detector Module



- NOvA detectors are constructed from planes of PVC modules
- Extrusions have a cellular structure, with 16 isolated cells per extrusion
- A module of 32 cells is constructed from two 16cell PVC extrusions glued together L = 15.6 m for Far Detector L = 4.2 m for Near Detector
- Each cell contains liquid scintillator and light measuring fiber optics
- Modules are capped by a Manifold and an End Cap to contain the liquid volume



NOvA Detector Module

- NOvA Detector is constructed from alternating planes of vertical and horizontal PVC extrusion modules, connected together by glue between planes
- 12 extrusion modules are glued together side by side on a flat assembly table to form one plane (or layer) of the Far Detector
- 3 extrusion modules are glued together for the Near

NOvA Near Detector Block

- 24 planes make 1 NOvA **block** for Near Detector
- NOvA Near Detector block (B) configuration is as follows:
- $B = h_0 v_1 h_2 v_3 h_4 v_5 h_6 v_7 h_8 v_9 h_{10} v_{11} h_{12} v_{13} h_{14} v_{15} h_{16} v_{17} h_{18} v_{19} h_{20} v_{21} h_{22} v_{23}$

where **v** are vertical planes and **h** are horizontal planes of modules; number of planes is counted from 0 through 23

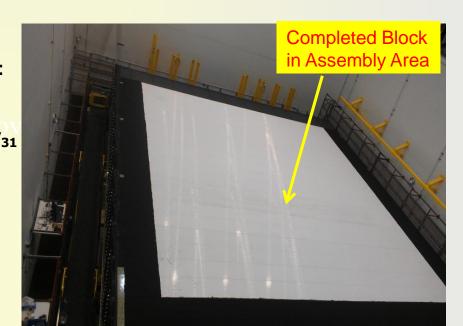
- Block assembly starts from plane-23 (v₂₃) on the assembly table and ends with plane-0 (h₀)
- All planes in each block are glued together in a horizontal orientation on a block assembly table

NOvA Far Detector Block

- 32 planes make 1 NOvA block for Far Detector
- NOvA Far Detector block **(B)** configuration is as follows:
- $B = h_0 v_1 h_2 v_3 h_4 v_5 h_6 v_7 h_8 v_9 h_{10} v_{11} h_{12} v_{13} h_{14} v_{15...}$ $... h_{16} v_{17} h_{18} v_{19} h_{20} v_{21} h_{22} v_{23} h_{24} v_{25} h_{26} v_{27} h_{28} v_{29} h_{30} v_{31}$

where **v** are vertical planes and **h** are horizontal planes of modules; number of planes is counted from 0 through 31

- Block assembly starts from plane-31 (**v**₃₁) on the assembly table and ends with plane-0 (\mathbf{h}_0)
- All planes in each block are glued together in a horizontal orientation on a block assembly table



NOvA Far Detector

• Far Detector (**FD**) consists of 28 blocks:

$FD \rightarrow B_0B_1B_2B_3B_4B_5....B_{23}B_{24}B_{25}B_{26}B_{27}$

where the number of blocks is counted 0 through 27

- Each block is 15.6 m wide by 15.6 m high by 2.141 m thick.
- The PVC in a 32-plane block weighs 177.7 metric tons
- The weight of a 32-plane block is 487.5 metric tons when filled with liquid scintillator

Block assembly starts at the glue machine where glue

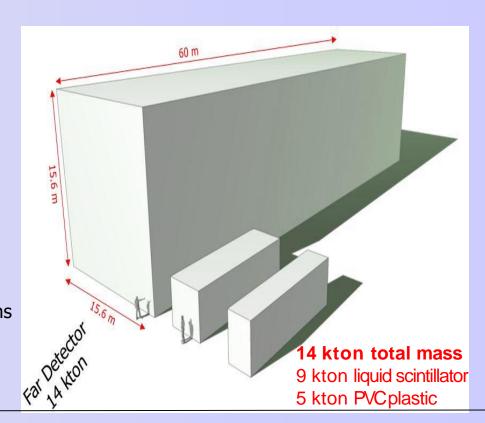
Modules are then transported to the assembly table by the vacuum lifting fixture to be glued to the next

Block assembly starts in the horizontal position from

Far Detector consists of 896 planes

is applied to the extrusion modules

modules to form planes (layers)



NOvA Near Detector

• The Near Detector (**ND**) consists of 8 blocks:

$ND \rightarrow B_0B_1B_2B_3B_4B_5B_6B_7$

where the number of blocks is counted 0 through 7

• Each block is 4.2 m wide by 4.2 m high by 2.136 m thick

The PVC in a 24-plane block weighs 5 metric tons

- The weight of a 24-plane block is 13.75 metric tons
- The NOvA Near Detector consists of 192 planes

• Once a block has been finished, the Pivoter is used to

• It then pivots 90° to set the block upright to the ideal

The block is then filled with Liquid Scintillator

the south wall

move the block into place within the detector building to

when filled with liquid scintillator

NOvA Near Detector Cavern



The surface of each module plane of the

NOvA Block is scanned with the HDS6100

directly above the Pivoter Assembly Table

• Relative 2 mm (Horizontal) edge to edge;

Scanner located on the ceiling inverted

• Relative 0.75 mm or better (Vertical)

• Angular tolerance of $\pm 2 \text{ mm}/15.6 \text{ m}$

between adjacent module pieces

 $= \pm 0.13$ mrad

AT401 Tracker

☐ Overall Block Survey Tolerance:

- Plan view
- Near Detector similar to the Far Detector
- Located on the Fermilab site about 1 km from the NuMI target
- Cavern is 105 m underground adjacent to the MINOS access tunnel, downstream of the MINOS shaft
- The cavern is 6.0 m wide by 20.5 m long by 6.0 m high

NOvA Far Detector Building

Near Detector Plane Measurements



- The Block Assembly area houses the NOvA Block Pivoter machine and the Assembly Table that is used to build all the blocks
- Each block is assembled on the assembly table while it is in its horizontal position

Groove measurements on Block will be made

at specified locations by placing the SMR where

• The bottom of the SMR will sit in the horizontal

groove while the one side of the SMR touches the

• SMR will be placed on every third groove from

the left (-13) and right (+13) edges of the

module, and on the middle groove (0)

the horizontal module grooves intersect the

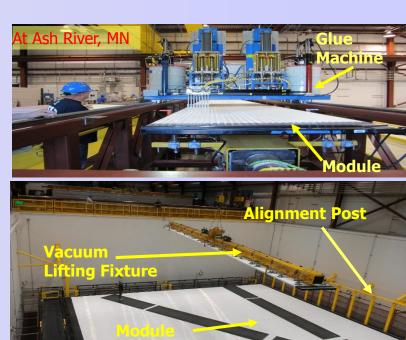
extreme end of the vertical plane



sunk 16 m below the existing grade into granite rock

The Detector Hall will house all the 28 NOvA blocks

- Detector Hall at the south end Block Assembly area at the north end
- plane-31 (\mathbf{v}_{31}) on the assembly table and ends with plane-0 (\mathbf{h}_0).



Far Detector Block Assembly Table Survey

Far Detector Block Assembly

- Block Assembly Table surface measured with the API Tracker using 61 cm x 61 cm grids
- Measurements made with the Table in the horizontal position using the API Laser Tracker
- Measurement results are used for shimming the Table surface before block installation
- Surface elevation differences range from -20 mm to 30 mm

Block0 and Block1 surveyed with and

Block2 through Block6 surveyed with

Block13 through Block27 surveyed with

Survey was completed in March 2014

Block7 through Block12 surveyed

without filled liquid scintillator

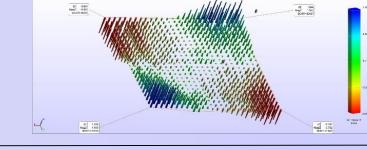
without filled liquid scintillator

filled liquid scintillator

filled liquid scintillator

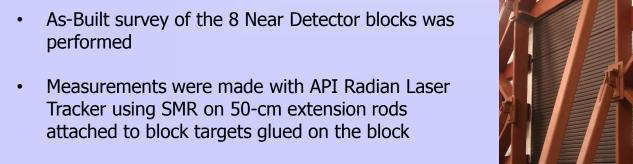






Last Di-Block Instrumented July 29, 2014

- Established a GPS surface geodetic control network that connects points at Fermilab to Ash River
- Tie surface control network to the National Geodetic Survey's Continuously Operating Reference Stations (CORS) precision geodetic network
- and vertically
- The network based on the NAD83 (North American Datum) 1983) for horizontal datum and the NAVD88 (North American Vertical Datum 1983) for vertical datum



Near Detector Block Survey

• Each block has 8 targets – 4 on the Top, 2 on the West side and 2 on the East side

Far Detector Surface Geodetic Network

Far Detector Block Assembly

- All long baselines are known to better than 1 cm horizontally



0.21 kton liquid scintillato

0.12 kton PVCplastic

Detector Hall Control Network



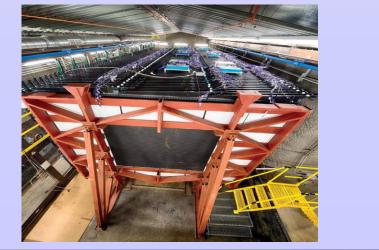
Far Detector Plane Measurements

- the Far Detector using the API Laser Tracker Extended control network on the four levels of the west wall of the Detector hall using the

Near Detector Block Survey

- Block0 through Block7 surveyed with and without filled liquid scintillator

• Survey was completed in March 2014



Far Detector Block Survey

up near the ceiling of the Far Detector hall Measurements made with AT401 Tracker

AT401Tracker on a wall bracket mounted

vertical plane

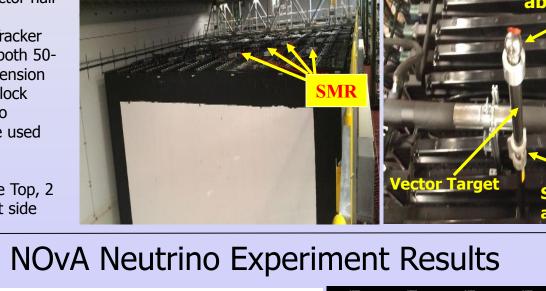
- using a vector target with SMR at both 50cm and 75-cm above target on extension rods. The Rods were attached to block targets glued on the block. The two measurements at each target were used for vector computation
- Each block has 8 targets 4 on the Top, 2 on the West side and 2 on the East side

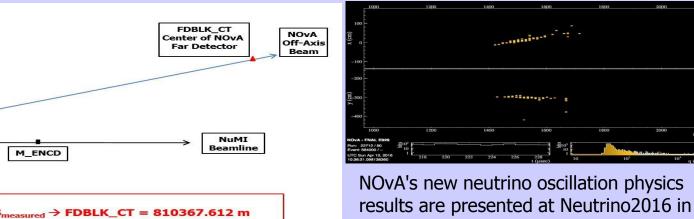
NDBLK_CT Center of NOvA Near Detector

M_ENCD

measured > MCZERO = 170.399 m

asured = 14.5578 milliradians





Acknowledgment

Far Detector Block Survey

- ☐ We would like to thank
- Alignment and Metrology Department members who participated in the NOvA Detector survey, especially Gary Crutcher and Chuck Wilson
- Dr. Pat Lukens and Dr. Ting Miao of the NOvA Collaboration



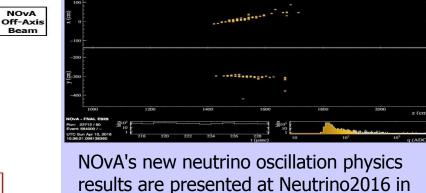
28 blocks of PVC modules are assembled and installed in place

14 kilotons = 28 NOvA Blocks

28 blocks are filled with liquid scintillator

•Tied the new building control network to the Established a precision control network surface network using the Geodimeter Total in the Far Detector building for positioning

 Precision control network in the Near Detector Cavern just completed using the API Tracker



https://www-nova.fnal.gov/

London on July 4, 2016.