

23 February 2016

Master Integrals technique for multi-loop computations: the Differential Equations approach.

HiggsTools Journal Club

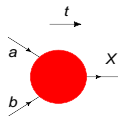
Elisa Mariani ^a

^a Nikhef,



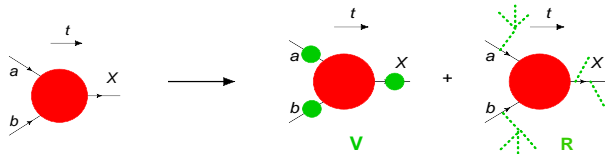
Perturbative QFT: higher-order corrections

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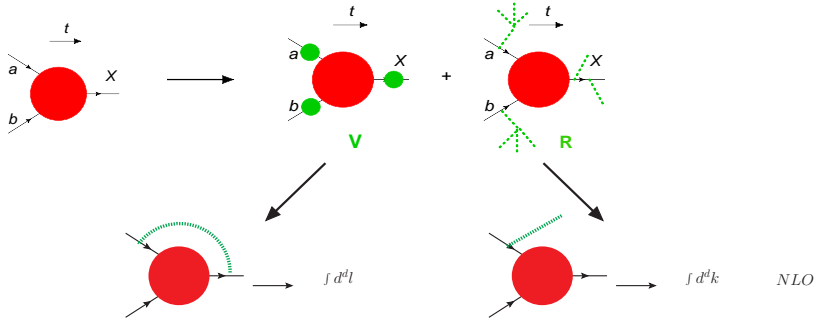
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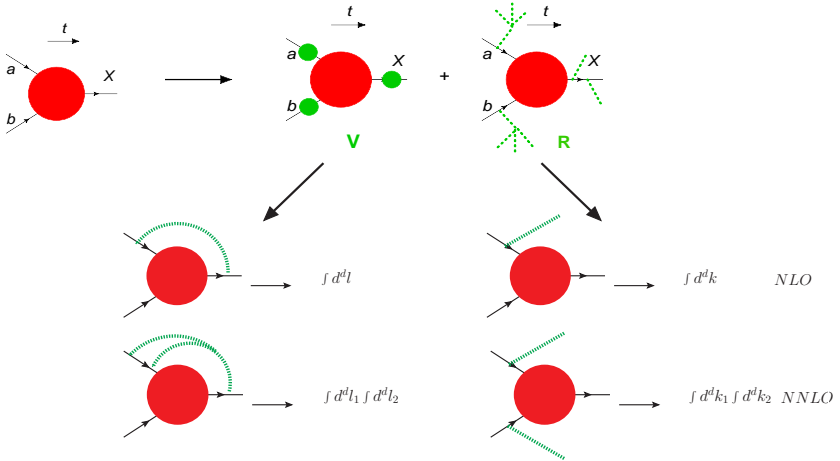
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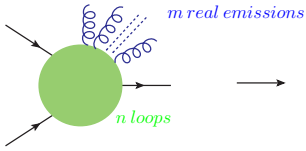
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The amount of integrals over real and virtual radiation becomes huge very quickly with increasing number of loops/legs.

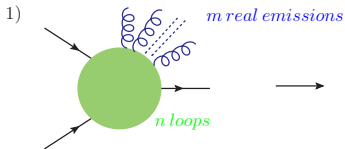
From Feynman Rules to Feynman Integrals

1)

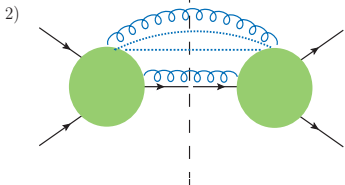


$$\propto \int d^d l_1 \dots d^d l_n A(l_1^{\mu_1}, \dots, l_n^{\mu_n}, k_1^{\nu_1}, \dots, k_m^{\nu_m}, p_a^\rho, p_b^\sigma)$$

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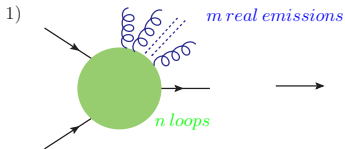


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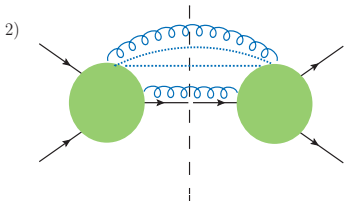


$$\propto \int d^d l_1 \dots d^d l_n \int d^d k_1 \dots d^d k_m |A|^2(l_i \cdot k_j, l_i \cdot p_j, k_i \cdot p_j) \times \prod_i \delta(k_i^2 - m_i^2) \times \delta((p_a + p_b - k_1 - \dots - k_m)^2 - m_X^2)$$

From Feynman Rules to Feynman Integrals



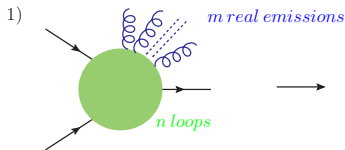
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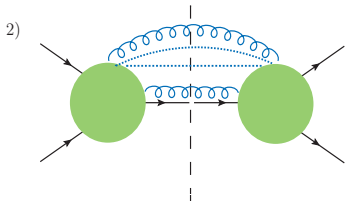
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$$\sigma \propto \int d^d l_1 \dots d^d l_n \int d^d k_1 \dots d^d k_m |A|^2(l_i \cdot k_j, l_i \cdot p_j, k_i \cdot p_j) \times \prod_i \frac{1}{(k_i^2 - m_i^2)_c} \times \frac{1}{((p_a + p_b - k_1 - \dots - k_m)^2 - m_X^2)_c}$$

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4)
$$\sigma(\vec{s}) \propto \sum_i c_i(\vec{s}) \mathcal{I}(\vec{s}, \{a_1^i, \dots, a_{N_P}^i\}), \quad \vec{s} = \{p_a \cdot p_b, m_a^2, m_b^2, m_X^2, p_j \cdot p_X\}$$

$$\mathcal{I}(\vec{s}, \{a_1, \dots, a_{N_P}\}) = \int d^d l_1 \dots d^d l_n \int d^d k_1 \dots d^d k_m \frac{1}{P_1^{a_1} \times \dots \times P_{N_P}^{a_{N_P}}}, \quad E_j = E_j(l_i \cdot k_j, l_i \cdot p_j, k_i \cdot p_j, m_{int_i}^2)$$

Master Integrals : Why and How?

In the calculation of multi-loop/multi-leg processes, the bottleneck is the huge amount of loop- and phase space- integrals.



MASTER INTEGRALS TECHNIQUE

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Part of the computation is automatized

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How?

1) **Reduction** of scalar matrix elements to a set of Master Integrals. → FIRE

2) Explicit **evaluation** of Masters *Feynman Calculus*.

3) "Cosmetics" and Renormalization of final expressions.

Integration by Parts Identities

$$\sigma(\vec{s}) \propto \sum_j^{N_I} c_j(\vec{s}) \mathcal{I}(\vec{s}; a_1^j, \dots, a_{n_p}^j) \xrightarrow{?} \begin{cases} \sigma \propto \sum_{j'}^{N'_I} c_{j'} \mathcal{I}(a_1^{j'}, \dots, a_{n_p}^{j'}), N' \ll N \\ \downarrow \\ \mathcal{I}(a_1^{j_1}, \dots, a_{n_p}^{j_1}) + \mathcal{I}(a_1^{j_2}, \dots, a_{n_p}^{j_2}) + \dots \stackrel{?}{=} 0 \end{cases}$$

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↓

IBPs for Feynman integrals: $\int d^d k_1 \dots \int d^d k_L \left[\frac{\partial}{\partial k_j} \cdot k_j \frac{1}{(k_1^2 - m_1^2)^{a_1} \dots (k_L^2 - m_L^2)^{a_L}} \right] = 0$

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$$2) \text{ Relation between integrals of the family: } I(a) = \frac{d - 2a + 2}{2(a - 1)m^2} I(a - 1)$$

$$3) \text{ Solve the recursion: } I(a) = \frac{(-1)^a (1 - d/2)_{(a-1)}}{(a - 1)! (m^2)^{a-1}} I_1, \quad (x)_a \equiv \frac{\Gamma(x + a)}{\Gamma(x)} = x(x + 1) \dots (x + a - 1)$$

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$$\sigma \propto \sum_m^{N_M} c_m \mathcal{M}(a_1^m, \dots, a_{n_p}^m), N_M \ll N$$

Solving the Masters: possible strategies

Set of MIs $\{\mathcal{M}_i\}$ is a **basis in the space of Feynman integrals** describing a certain process.

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- α /Feynman Parameters: $E(p, m^2) = \frac{i}{(p^2 - m^2 + i0)^{a_I}} \rightarrow \int_0^\infty d\alpha_I \alpha_I^{a_I - 1} e^{i(p^2 - m^2)a_I}$

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■ Differential Equations:

1 MIs are functions of the external scales \vec{s} governing the process

$$\vec{M} = (\dots M_i, \dots), \Rightarrow \vec{M} = \vec{M}(\vec{s})$$

2 They happen to satisfy coupled systems of (P)DEs, which set their dependence on such scales.

Generation of DE for a generic Feynman integral: 1-loop example

$$F^{ad}(x, 1, 1, \epsilon) = m^{2\epsilon} \int \frac{d^{4-2\epsilon} k}{(k^2 - m^2)(q-k)^2} = \text{---} \bigcirc \text{---} q, \quad x = \frac{q^2}{m^2}, \quad \frac{d}{dx} = -\frac{m^2}{x} \frac{d}{dm^2}$$

$$\begin{aligned} \frac{d}{dx} F^{ad}(x, 1, 1, \epsilon) &= -\frac{m^2}{x} \frac{d}{dm^2} \left[(m^2)^\epsilon \int \frac{d^{4-2\epsilon} k}{(k^2 - m^2)(q-k)^2} \right] \\ &= -\frac{1}{x} \left[\epsilon (m^2)^\epsilon \int \frac{d^{4-2\epsilon} k}{(k^2 - m^2)(q-k)^2} + (m^2)^{1+\epsilon} \int \frac{d^{4-2\epsilon} k}{(k^2 - m^2)^2 (q-k)^2} \right] \\ &= -\frac{1}{x} \left[\epsilon F^{ad}(x, 1, 1, \epsilon) + F^{ad}(x, 2, 1, \epsilon) \right] \end{aligned}$$

$$\text{IBPs} \quad F^{ad}(x, 2, 1, \epsilon) = \frac{1}{1-x} \left[(1-2\epsilon) F^{ad}(x, 1, 1, \epsilon) - (1-\epsilon) F^{ad}(x, 1, 0, \epsilon) \right]$$

$$\text{DE} \quad \frac{d}{dx} F^{ad}(x, 1, 1, \epsilon) = -\frac{1}{x} \left[F^{ad}(x, 1, 1, \epsilon) \left(\epsilon + \frac{1-2\epsilon}{1-x} \right) - \frac{(1-\epsilon)}{1-x} F^{ad}(x, 1, 0, \epsilon) \right]$$

..solvable in a bottom-up approach!

(Partial) Differential Equations for a set of Master Integrals

Given a set of masters \vec{M} describing a certain process governed by \vec{s}

$$1) \quad \vec{M}_{\mathcal{T}} = \{M^{(1)}, \dots, M^{(i)}, \dots, M^{(m)}\}, \quad M^{(i)} = M^{(i)}(\vec{s}; \epsilon), \quad \vec{s} = \{s_1, \dots, s_n\}.$$

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$$3) \quad \mathcal{I}(\vec{s}; \epsilon; \{a_1, \dots, a_m\}) \stackrel{IBPs}{=} \sum_i c_i(\vec{s}; \epsilon) M^{(i)}(\vec{s}; \epsilon)$$

Differential Equations: expansion around $\epsilon \rightarrow 0$

- D.E. systems are too complex to be integrated in closed form in ϵ .
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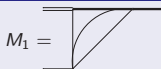
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Example from $[b + W^* \rightarrow t]_{2L}$



$$=? \quad \text{D.E. } \frac{d}{dy} M_1(y) = \frac{4(3 - (4 - 2\epsilon)(1 - y) - 4y)M_1(y)}{4y(1 + y)} + \frac{(-8 + 3(4 - 2\epsilon))M_2(y)}{4y(1 + y)}$$

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known!

$$M_2(y) = \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \end{array} \quad = \frac{m_2^{(-2)}(y)}{\epsilon^2} + \frac{m_2^{(1)}(y)}{\epsilon} + m_2^0(y) + m_2^{(1)}\epsilon(y) + m_2^{(2)}\epsilon^2(y) + \mathcal{O}(\epsilon^3)$$

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$$\mathcal{O}(\epsilon^{-2}) : \frac{d}{dy} m_{t_1,1}^{(-2)}(y) = \frac{m_{t_4,2}^{(-2)}(y) - m_{t_1,1}^{(-2)}(y)}{\epsilon^2 y(1+y)}$$

$$\mathcal{O}(\epsilon^{-1}) : \frac{d}{dy} m_{t_1,1}^{(-1)}(y) = \frac{-6m_{t_4,2}^{(-2)}(y) + 4m_{t_4,2}^{(-1)}(y) + 8(1-y)m_{t_1,1}^{(-2)}(y) - 4m_{t_1,1}^{(-1)}(y)}{4\epsilon y(1+y)}$$

$$\mathcal{O}(\epsilon^0) : \dots$$

... integrable with appropriate boundary conditions!

Differential Equations: Problematics and Bottlenecks

Masters can be computed as Laurent series in ϵ

$$M_i(\vec{s}; \epsilon) = \sum_{k=n_0}^n \epsilon^k M_i^{(k)}(\vec{s}) + \mathcal{O}(\epsilon^{n+1})$$

...this helps but does not solve problems..

Differential Equations: Problematics and Bottlenecks

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CANONICAL BASIS

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EXPANSION BY REGION

Canonical basis: philosophy (arXiv:1304.1806, J.Henn)

a) Basis \vec{M} of MIs can be freely chosen.

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No spurious divergences in the solution.

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Solution can be written in terms of **iterated integrals**,
and under certain conditions in terms of **Multiple Polylogarithms**.

Canonical basis: Factorization of ϵ and PDEs systems decoupling

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$$\mathcal{O}(\epsilon^{-4}) : \begin{cases} \partial_z m_1^{(-4)} = 0 \\ \partial_z m_2^{(-4)} = 0 \end{cases} \Rightarrow \begin{cases} m_1^{(-4)} = \text{const} \\ m_2^{(-4)} = \text{const} \end{cases}$$

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and so on ... \Rightarrow The system decouples order by order in ϵ

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- Higher-order computations imply performing a huge amount of complicated Feynman integrals
- \Rightarrow ad-hoc techniques are required
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2) Evaluation

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A powerful technique for analytic Evaluation is represented by Differential Equations.

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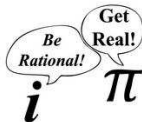
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... thank you for your attention.

Back-up slides

NUMERICAL METHOD for Feynman Integrals

Sector Decomposition - Philosophy

- Counterterms are needed to integrate numerically divergent integrals
- How to construct them when there are overlapping singularities?

$$\begin{aligned}
 I &= \int_0^1 dx \int_0^1 dy x^{-1-a\epsilon} y^{-b\epsilon} (x + (1-x)y)^{-1} = \\
 &= \int_0^1 dx \int_0^1 dy x^{-1-a\epsilon} y^{-b\epsilon} (x + (1-x)y)^{-1} [\Theta(x-y) + \Theta(y-x)] = \\
 &= \int_0^1 dx x^{-1-(a+b)\epsilon} \int_0^1 dt t^{-b\epsilon} (1 + (1-x)t)^{-1} + \\
 &\quad + \int_0^1 dy y^{-1-(a+b)\epsilon} \int_0^1 dt t^{-1-a\epsilon} (1 + (1-y)t)^{-1} \text{ (Ask Stephen for more info..)}
 \end{aligned}$$