

Data-driven analysis of the temperature and momentum dependence of the heavy-quark transport coefficient

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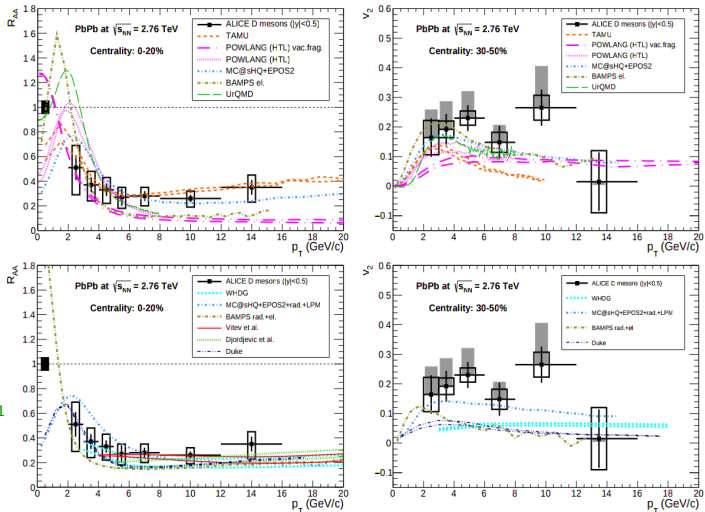
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In collaboration with :
Shanshan Cao
Marlene Nahrgang
Steffen A. Bass

HQ in-medium evolution

a challenge for simultaneously describing R_{AA} and v_2 results!

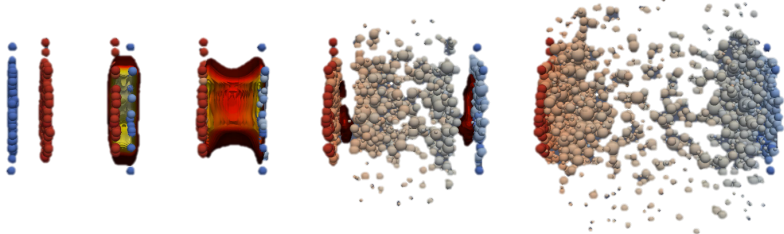


arxiv: 1506.03981

Figure : PbPb collision at the LHC: comparison between models and experimental observables

HQ transport model

figure credit: Hannah Petersen(Au-Au collisions)



initial condition

spatial IC: $T_{R}ENT_{o}$
momentum IC: pQCD

HQ in-medium

HQ transport:
 Langevin (col + rad)
medium:
 hydrodynamic

hadronization

hybrid model:
 fragmentation +
 recombination

initial condition

position space: T_RENTo (A parametric IC model)

- entropy deposition proportional to reduced thickness function

$$\left. \frac{ds}{dy} \right|_{\tau=\tau_0} \propto \left(\frac{T_A + T_B}{2} \right)^{1/p}$$

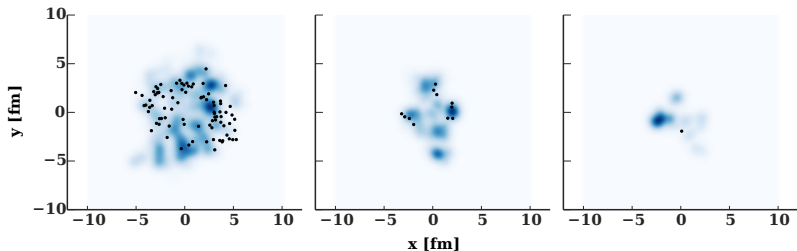
J.S.Moreland, J.Bernhard, and S.A.Bass,
Phys.Rev.C 92, 011901(2015)

- $p = 0$ (geometric mean), $\frac{ds}{dy} \propto \sqrt{T_A T_B}$ (mimic the behavior of IP-glasma model)

- heavy quark initial production probability: $\left. \frac{dN}{dy} \right|_{\tau=\tau_0} \propto T_A T_B$

momentum space: Leading order pQCD

- parton distribution function: CTEQ5 S.Cao, G.Qin, and S.A.Bass,
Phys.Rev.C 92, 024907(2015)
- nuclear shadowing effect: EPS09



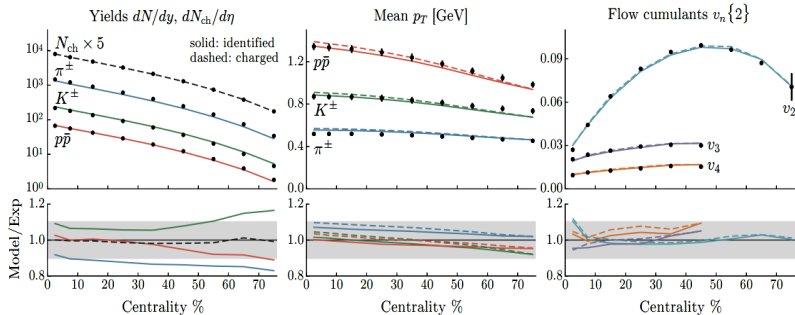
calibration of the medium

medium evolution

- (2+1)D viscous hydro: iEbE-VishNU
- temperature-dependent shear vis + bulk vis correction
- $(\eta/s)(T) = (\eta/s)_{min} + (\eta/s)_{slope}(T - T_c)$
- all the initial/medium related parameters are calibrated by Bayesian model-to-data comparison with experimental observables (yields, mean p_T , flow cumulants $v_n\{2\}$)

H.Song and U.W.Heinz,
Phys.Rev.C 77, 064901(2008)

J.Bernhard,J.S.Moreland,S.A.Bass,
J.Liu, and U.Heinz
Phys.Rev.C 94, 024907(2015)





HQ in-medium evolution

HQ propagation

S.Cao, G.Qin, and S.A.Bass,
Phys.Rev.C 92, 024907(2015)

- improved Langevin transport model

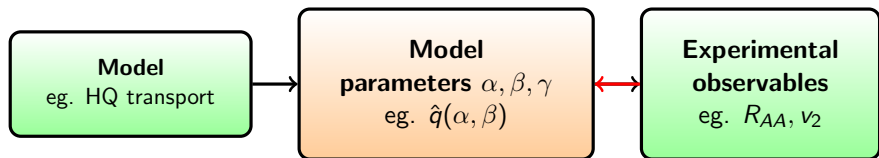
$$\frac{d\vec{p}}{dt} = -\eta_D(p)\vec{p} + \vec{\xi} + \vec{f}_g \quad (1)$$

- drag force: $\eta_D(p) = \kappa/(2TE)$
- thermal random force: $\langle \xi^i(t)\xi^j(t') \rangle = \kappa\delta^{ij}\delta(t-t')$
- recoil force from gluon radiation: $\vec{f}_g = -d\vec{p}_g/dt$
- gluon emission probability:

$$\frac{dN_g}{dxdk_{\perp}^2 dt} = \frac{2\alpha_s P(x)\hat{q}_g}{\pi k_{\perp}^4} \sin^2\left(\frac{t-t_i}{2\tau_f}\right) \left(\frac{k_{\perp}^2}{k_{\perp}^2 + x^2 M^2}\right)^4 \quad (2)$$

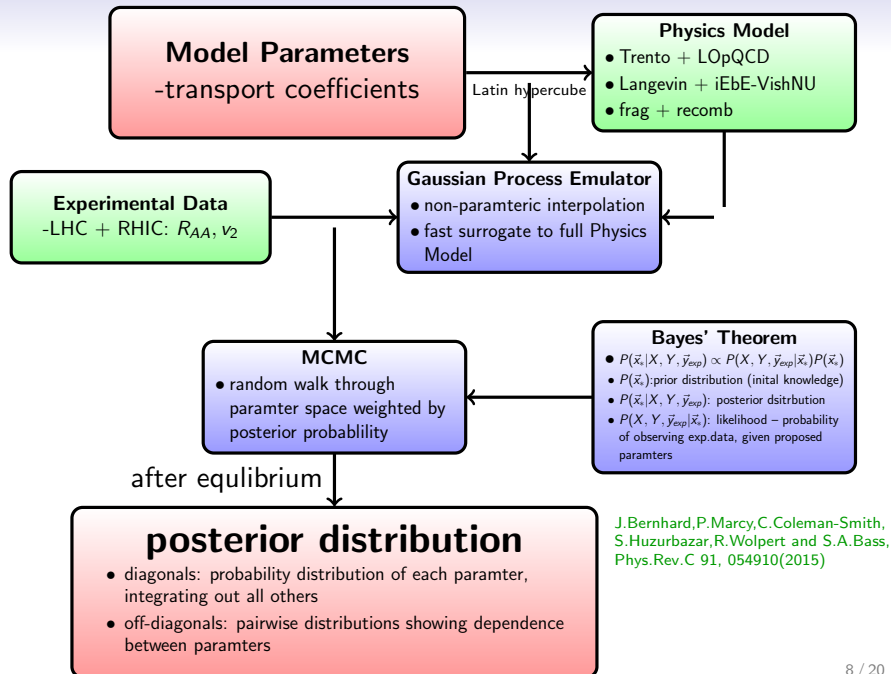
- $\hat{q}_g = \hat{q}C_A/C_F = 2\kappa C_A/C_F$, $D_s = 2T^2/\kappa$

Bayesian model-to-data analysis



Bayesian analysis:

- physical properties of the system encapsulated in parameters of the model
- Bayesian analysis allows us to simultaneously calibrate all model parameters through model-to-data comparison
- find the optimal parameters such that the model best describes the experimental observables
- extract the probability distribution of all parameters



temp-dependent parameterization of diffusion coefficient

$$D_s = T^2 / \hat{q}, \quad \hat{q} = \hat{q}_{pQCD} * preK * \left(1 + K_T e^{-\frac{(T-T_c)^2}{2\sigma_T^2}}\right)$$

difficulties

HQ transport model run \propto 2hrs
for 10 events produced;
10000 events needed for
event-by-event study $\Rightarrow O(10^4)$
CPU hours to evaluate one input
 \vec{x}_*

param	k_T	σ_T	preK
range	0-5	0.001-0.5	0.1-1.4

Latin hypercube design

120 input parameters $X = (\vec{x}_1, \vec{x}_2, \dots, \vec{x}_{120})$

Model

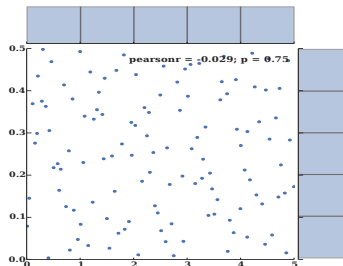
$$y(\vec{x}) = Model(\vec{x})$$

Physical process

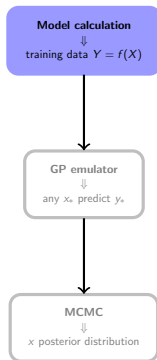
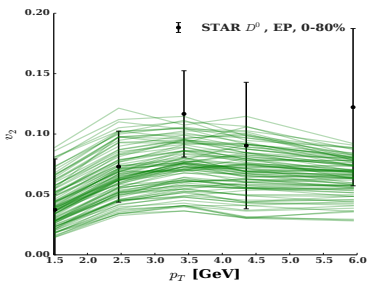
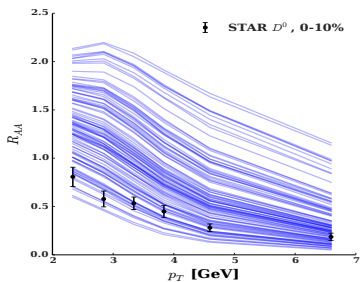
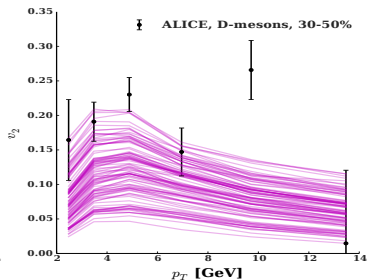
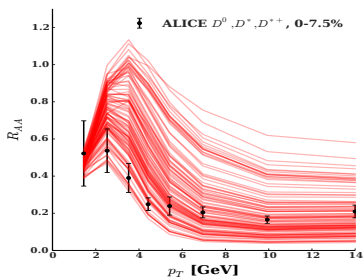
$$y_{exp}$$

Gaussian Process

$$GP(\vec{x}) = Model(\vec{x})$$



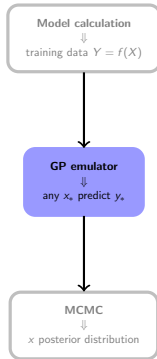
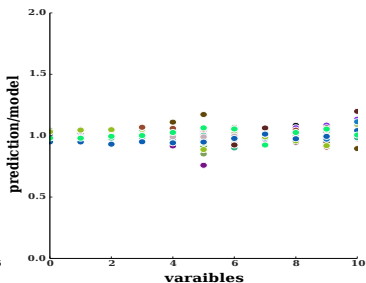
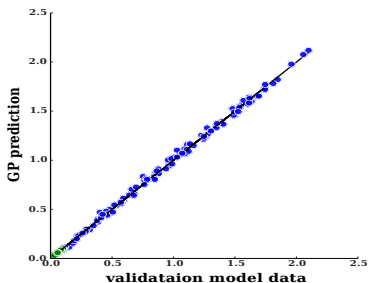
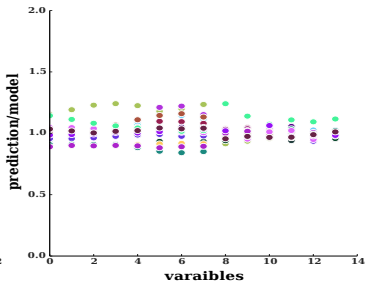
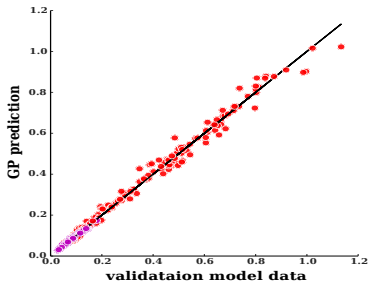
T-dependence results: Model outputs





T-dependence results: GP training

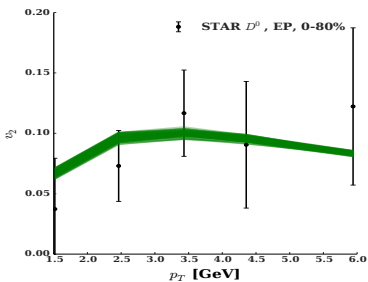
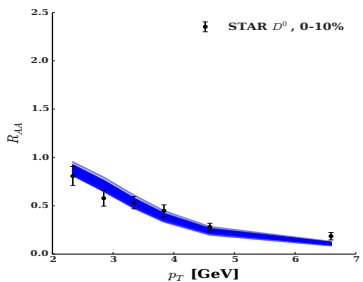
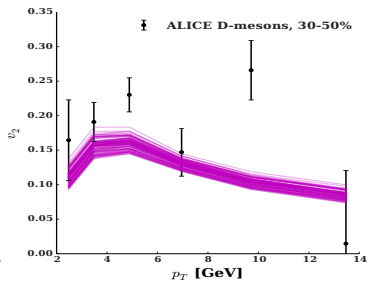
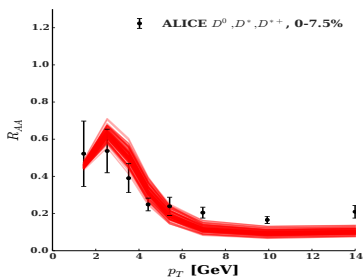
GP emulator prediction, validated by model outputs





T-dependence results: calibration

outputs after calibration



Model calculation
 \downarrow
 training data $Y = f(X)$

GP emulator
 \downarrow
 any x_i , predict y_i

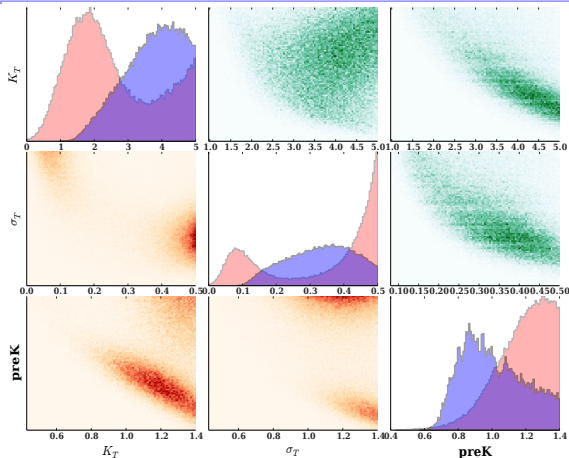
MCMC
 \downarrow
 x posterior distribution

T-dependence results: MCMC (calibration)



posterior probability distribution of parameters

param	range	80% CR (PbPb)	80%CR (AuAu)	mean (PbPb)	mean(AuAu)
k_T	0-5	1.08 - 2.51	2.51-4.73	2.52	3.71
σ_T	0.001-0.5	0.07-0.48	0.19-0.45	.033	0.33
prek	0.1-1.4	0.96-1.36	0.78-1.28	1.18	1.00

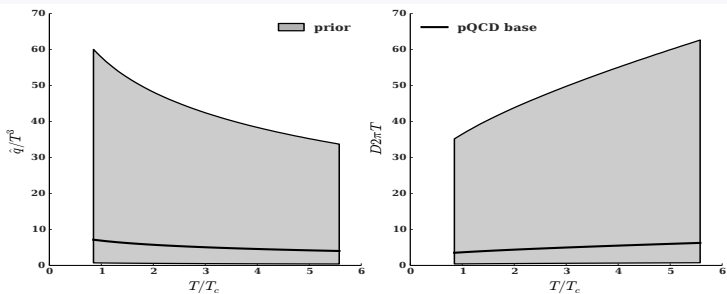


Model calculation
 \downarrow
 training data $Y = f(X)$

GP emulator
 \downarrow
 any x_i predict y_i

MCMC
 \downarrow
 x posterior distribution

(momentum) diffusion coefficient – prior range

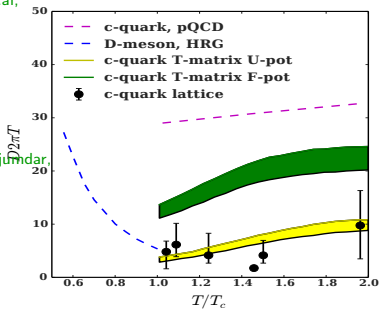


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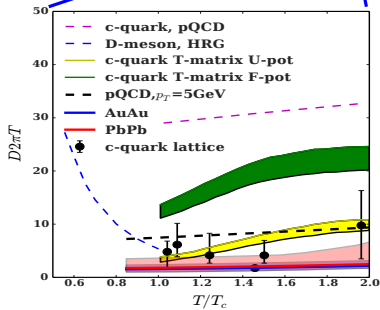
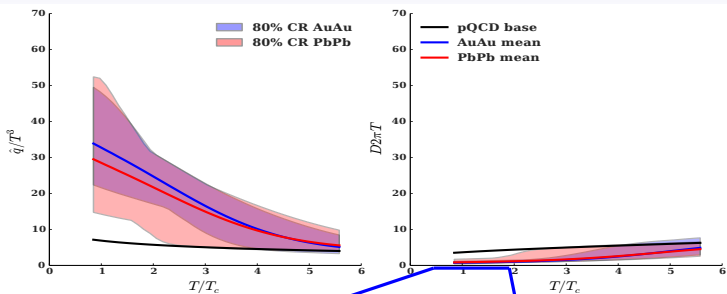
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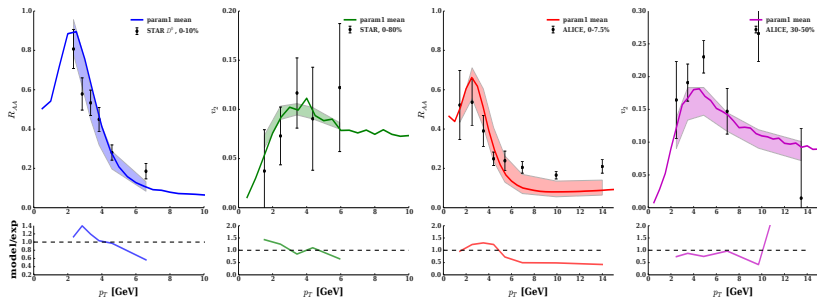
(momentum) diffusion coefficient– posterior range





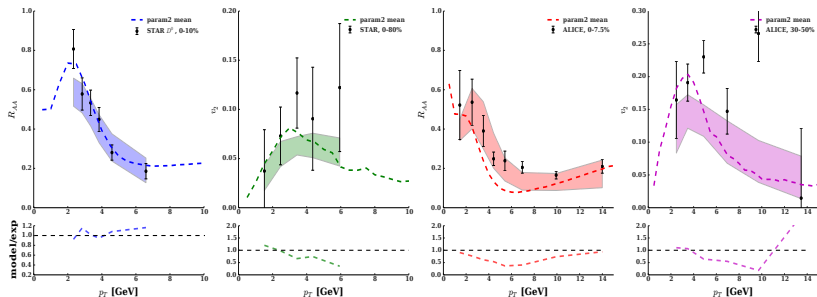
other parameterization

- T-dependence: $\hat{q} = \hat{q}_{pQCD} * preK * (1 + K_{TE} e^{-\frac{(T-T_C)^2}{2\sigma_T^2}})$
- p-dependence: $\hat{q} = \hat{q}_{pQCD} * preK * (1 + K_{pe} e^{-\frac{|p|^2}{2\sigma_p^2}})$
- T,p-dependence: $\hat{q} = \hat{q}_{pQCD} * preK * (1 + K_{pe} e^{-\frac{|p|^2}{2\sigma_p^2}}) * (1 + K_{TE} e^{-\frac{(T-T_C)^2}{2\sigma_T^2}})$



other parameterization

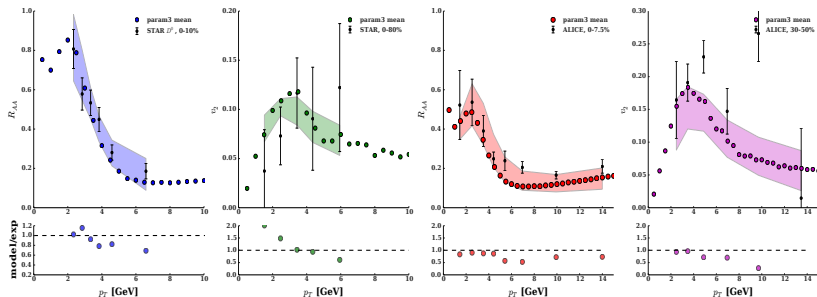
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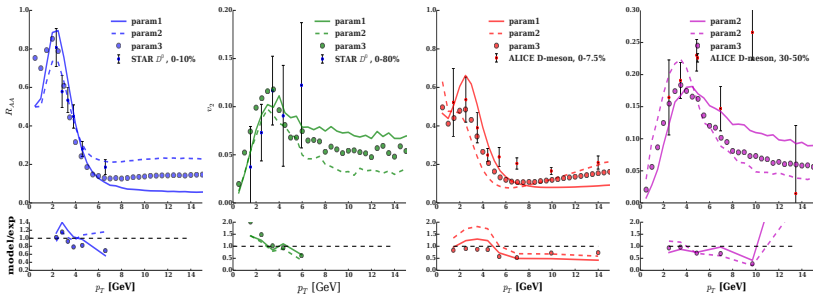
other parameterization

- T-dependence: $\hat{q} = \hat{q}_{pQCD} * preK * (1 + K_{TE} e^{-\frac{(T-T_C)^2}{2\sigma_T^2}})$
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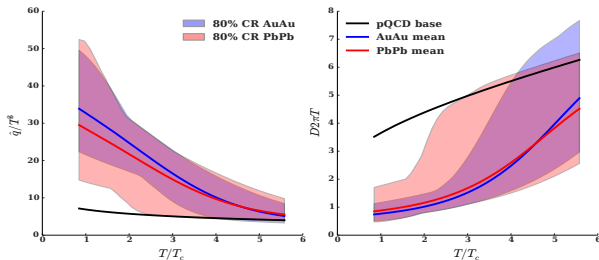
other parameterization

- T-dependence: $\hat{q} = \hat{q}_{pQCD} * preK * (1 + K_T e^{-\frac{(T-T_C)^2}{2\sigma_T^2}})$
- p-dependence: $\hat{q} = \hat{q}_{pQCD} * preK * (1 + K_p e^{-\frac{|p|^2}{2\sigma_p^2}})$
- T,p-dependence: $\hat{q} = \hat{q}_{pQCD} * preK * (1 + K_p e^{-\frac{|p|^2}{2\sigma_p^2}}) * (1 + K_T e^{-\frac{(T-T_C)^2}{2\sigma_T^2}})$



summary

- By applying Bayesian model-to-data analysis, we are able to extract the temperature and momentum dependence of \hat{q} , D_s from data



- Simultaneous agreement of R_{AA} and v_2 compared to data
- Discrepancies of the parameter posterior distribution between RHIC and the LHC energies:
possible hint of temperature and momentum dependence that is not fully captured in our parameterization
- Improve uncertainty analysis (systematic/statistic error);
more extension on other experimental observables, etc..

backups

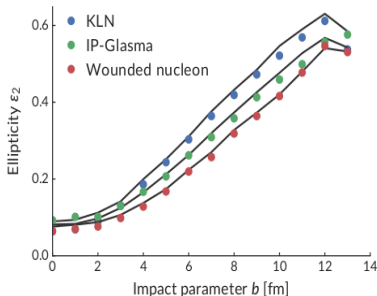
T_RENTo (A parametric IC model)

Ansatz:

entropy density proportional to generalized mean of local nuclear density:

$$s \propto \left(\frac{T_A^p + T_B^p}{2} \right)^{1/p}$$

- $p = -1, \frac{2T_A T_B}{T_A + T_B}$
- $p = 0, \sqrt{T_A T_B}$
- $p = 1, \frac{T_A + T_B}{2}$



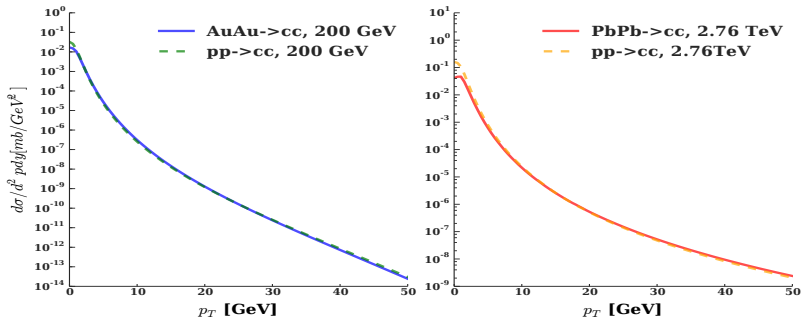
initial condition

position space: T_RENTo (A parametric IC model)

- entropy deposition: $\frac{ds}{dy} \propto \sqrt{T_A T_B}$

momentum space: Leading order pQCD

- parton distribution function: CTEQ5
- nuclear shadowing effect: EPS09



$$P(\vec{x}_* | X, Y, \vec{y}_{exp}) \propto P(X, Y, \vec{y}_{exp} | \vec{x}_*) P(\vec{x}_*) \quad (3)$$

- $X = (\vec{x}_1, \vec{x}_2, \dots, \vec{x}_m)$: input parameters
 $Y = (\vec{y}_1, \vec{y}_2, \dots, \vec{y}_m)$: output of the model
- $P(\vec{x}_* | X, Y, \vec{y}_{exp})$: posterior possibility distribution for \vec{x}_* for given X, Y, \vec{y}_{exp}
- $P(X, Y, \vec{y}_{exp} | \vec{x}_*)$: likelihood

$$P(X, Y, \vec{y}_{exp} | \vec{x}_*) \propto \exp \left(-\frac{1}{2} (\vec{y}_* - \vec{y}_{exp})^T \Sigma^{-1} (\vec{y}_* - \vec{y}_{exp}) \right) \quad (4)$$

- $P(\vec{x}_*)$: prior possibility distribution of \vec{x}_* (Our initial knowledge of the input parameters)
- with experimental statistical error as uncertainty: $\Sigma = \text{diag}(\sigma_{exp}^2 \mathbf{y}_{exp}^{\rightarrow})$

Bayesian model-to-data comparison

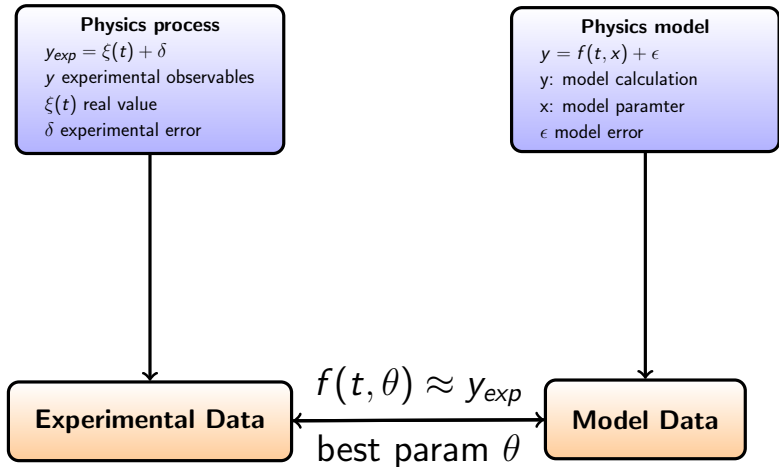
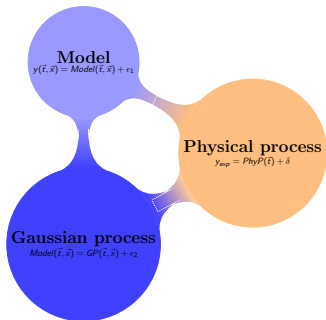


Figure : find the 'true' paramter θ , extract the shape of paramters by doing model-to-data analysis

A substitution of the model to rapidly calculate the output

- physics process: $y_{exp} = PhyP(\vec{t}) + \delta$,
 \vec{t} is known variables , eg. $\sqrt{s_{NN}}$
- model simulation:
 $y = Model(\vec{t}, \vec{x}) + \epsilon_1 \Rightarrow y_{exp} \sim Model(\vec{t}, \vec{\theta})$
- Gaussian process emulator:
 $Model(\vec{t}, \vec{x}) = GP(\vec{t}, \vec{x}) + \epsilon_2$
 $\Rightarrow y \sim GP(\mu(\vec{x}), \sigma(\vec{x}, \vec{x}'))$
- $\delta, \epsilon_{1,2}$ are the errors(sys, stats)
- $\mu(\vec{x})$ mean vector, $\sigma(\vec{x}, \vec{x}')$ the covariance function of each pair (\vec{x}, \vec{x}')



Definition:

A Gaussian process is a collection of random variables, any finite number of which have a joint Gaussian distribution.

- Stochastic function: $\vec{x} \rightarrow y$
- \vec{x} : n-dimensional input vector; y : normally distributed output
- specified by:
 - mean function $\mu(\vec{x})$
 - covariance function $\sigma(\vec{x}, \vec{x}')$
 - this study: $\sigma(\vec{x}, \vec{x}') = \sigma_{GP}^2 \exp\left[-\frac{\vec{x}-\vec{x}'}{2l^2}\right] + \sigma_n^2 \delta_{xx'}$

Given: training inputs points X and training outputs Y at X
predict: $\vec{x}_* \Rightarrow y_*$

The predictive distribution at arbitrary test points \vec{x}_* is the multivariate-normal distribution

- $y_* = N(\mu, \Sigma)$
- $\mu = \sigma(X, X_*)\sigma(X, X)^{-1}y$
- $\Sigma = \sigma(X, X_*) - \sigma(X_*, X)\sigma(X, X)^{-1}\sigma(X, X_*)$

Likelihood function:

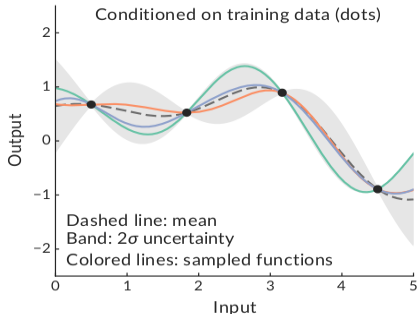
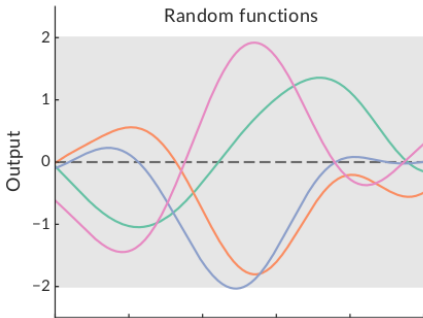
$$\log P(Y|X, \vec{\theta}) = -\frac{1}{2} Y^T \Sigma^{-1}(X, \vec{\theta}) Y - \frac{1}{2} |\Sigma(X, \vec{\theta})| - \frac{N}{2} \log(2\pi)$$

(5)

Gaussian Process emulator

Gaussian Process:

- stochastic function: maps inputs to normally-distributed outputs
- specified by mean and covariance functions
- non-parametric interpolation
- predicts probabilities distributions: narrow near training points, wide in gaps
- fast surrogate to real physical model



principle component analysis

Many highly correlated outputs \Rightarrow principle component analysis

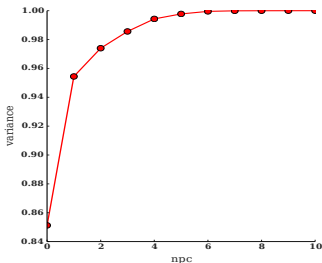
PCs = eigenvectors of outputs covariance matrix

$$Y = USV^T \quad (6)$$

$$Y^T Y = V \Lambda V^T \quad (7)$$

transform data into orthogonal, uncorrelated linear combinations:

$$Z = \sqrt{m} Y V, \quad Y = \frac{1}{\sqrt{m}} Z V^T \quad (8)$$



posterior distribution is sampled with MCMC method

- Random walk in parameter space, where each step is accepted or rejected based on a relative likelihood
- Converges to posterior distribution as number of steps $N \rightarrow \infty$
- acceptance fraction α_f of steps measures the quality of random walk
 - $\alpha_f \simeq 0 \Rightarrow$ walker "stuck"
 - $\alpha_f \simeq 1 \Rightarrow$ pure random walk
 - aim for 0.2-0.5
- autocorrelation time = Number of steps between independence samples "Burn-in" takes a few correlations, gathering enough samples $\simeq 0(10)$ autocorrelations

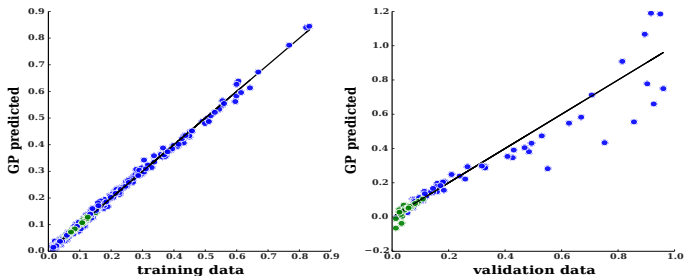
input parameters \vec{x} :

- $\hat{q} = \hat{q}_{pQCD} * preK * (1 + K_p e^{-\frac{|p|^2}{2\sigma_p^2}})$
- $\hat{q} = \hat{q}_{pQCD} * preK * (1 + K_T e^{-\frac{(T-T_c)^2}{2\sigma_T^2}})$
- $\hat{q} = \hat{q}_{pQCD} * preK * (1 + K_p e^{-\frac{|p|^2}{2\sigma_p^2}}) * (1 + K_T e^{-\frac{(T-T_c)^2}{2\sigma_T^2}})$

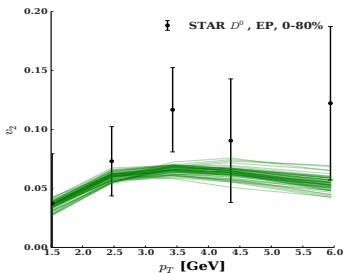
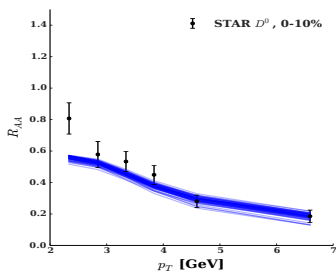
param	range1	range2	range3
k_p	N/A	0-15	0-12
σ_p	N/A	0.1-10.5	0.1-10.5
k_T	0-5	N/A	1-5
σ_T	0.001-0.5	N/A	0.001-0.5
$preK$	0.1-1.4	0.1-2.0	0.3-1.4

param 2 results: GP training

20 validation $\vec{x} \Rightarrow \vec{y} = Model(\vec{x})$ compare with $\vec{y} = GP(\vec{x})$

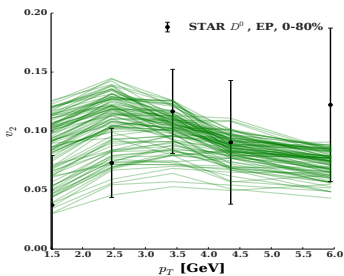
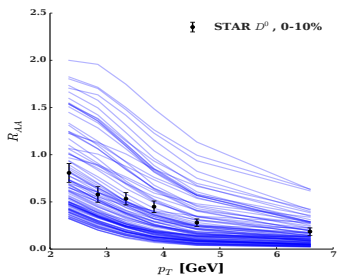
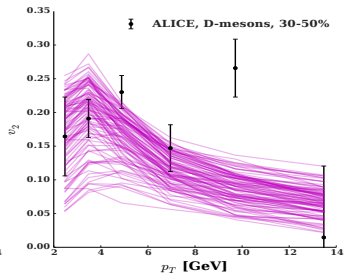
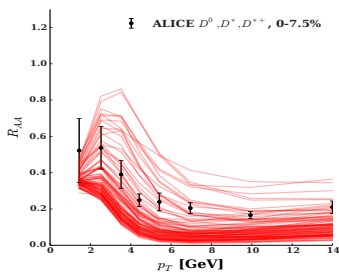


output from calibration \vec{y}^* :



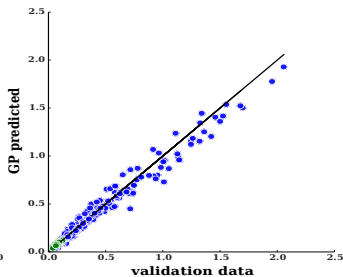
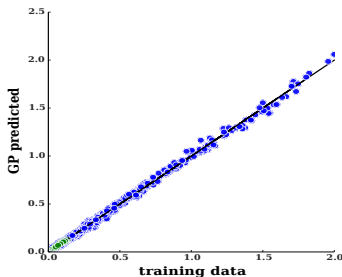
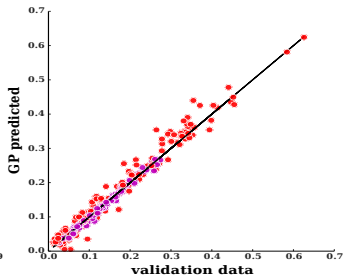
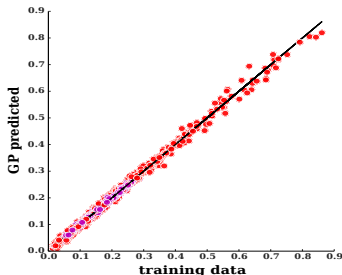
param 3 results: model output

output from the model \vec{y} : training data

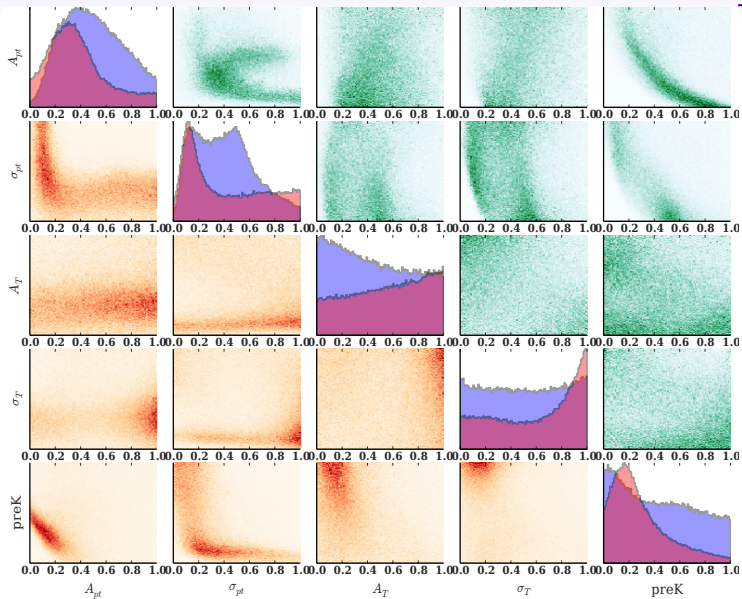


param 3 results: GP training

20 validation $\vec{x} \Rightarrow \vec{y} = Model(\vec{x})$ compare with $\vec{y} = GP(\vec{x})$



param 3 results: MCMC (calibration)



param 3 results: calibration output

output from calibration \vec{y}^* :

