

ROOT Planning

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Releases

- v6.06/02 released two weeks ago
- Plus a dev release v6.07/04 (tagged master)

Current Work

- Cristina: pointer check, enable for all interactivity; tab completion
- Vassil: PCMs
- Danilo, Axel: ATLAS

ATLAS Tier0 Update

- Reduced heap below 5.34
 - sadly most improvements ATLAS-specific (e.g. for “lying” templates such as DataVector)
- RSS comparable
- PSS larger
- Still improving while waiting for “verdict”

Release Schedule

- Driven by clang upgrade / GCC ABI
- Would prefer to release “once ready” (feature release) instead of scheduled release
- Still 2016!
- Requirements?