

MICE ANALYSIS USER SOFTWARE

DURGA RAJARAM

ILLINOIS INSTITUTE OF TECHNOLOGY, CHICAGO

ADAM DOBBS

IMPERIAL COLLEGE, LONDON

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SAN FRANCISCO



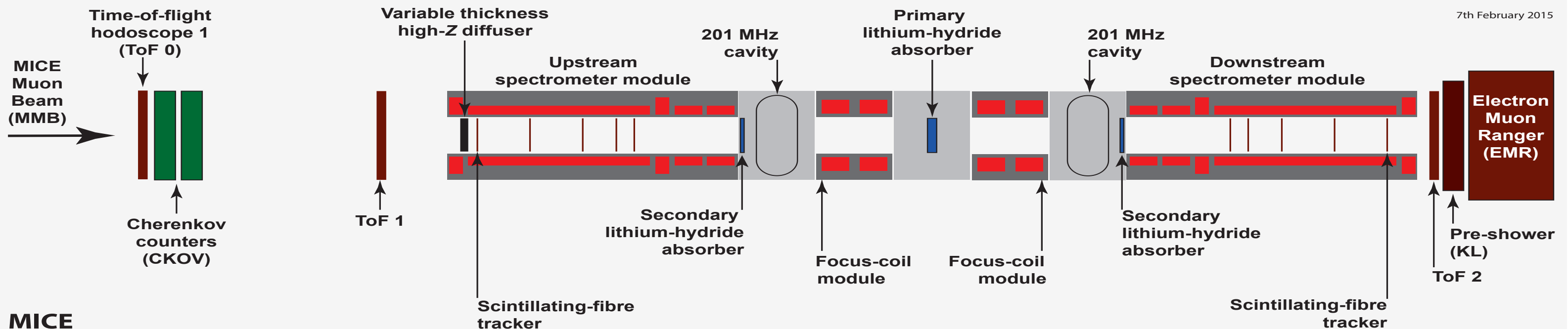
OUTLINE

- MICE
- Software Requirements
- Implementation
 - Design
 - Framework
 - Online
- Performance
- Conclusions



MUON IONIZATION COOLING EXPERIMENT

- Muon cooling: essential for future high-luminosity μ -colliders & high-intensity ν -factories
- μ from π decays have large emittance & must be cooled (reduce phase space volume)
- Traditional beam cooling techniques too slow due to the short μ lifetime
- **Ionization Cooling** is the only practical means:
 - Reduce momentum by dE/dX in absorber, followed by RF reacceleration to restore p_{\parallel}
- Design, build & commission a realistic section of cooling channel to precisely measure emittance reduction – Lessons => the design of a full cooling channel for a ν Factory/ μ Collider



7th February 2015

MICE

October 10, 2016

CHEP 2016

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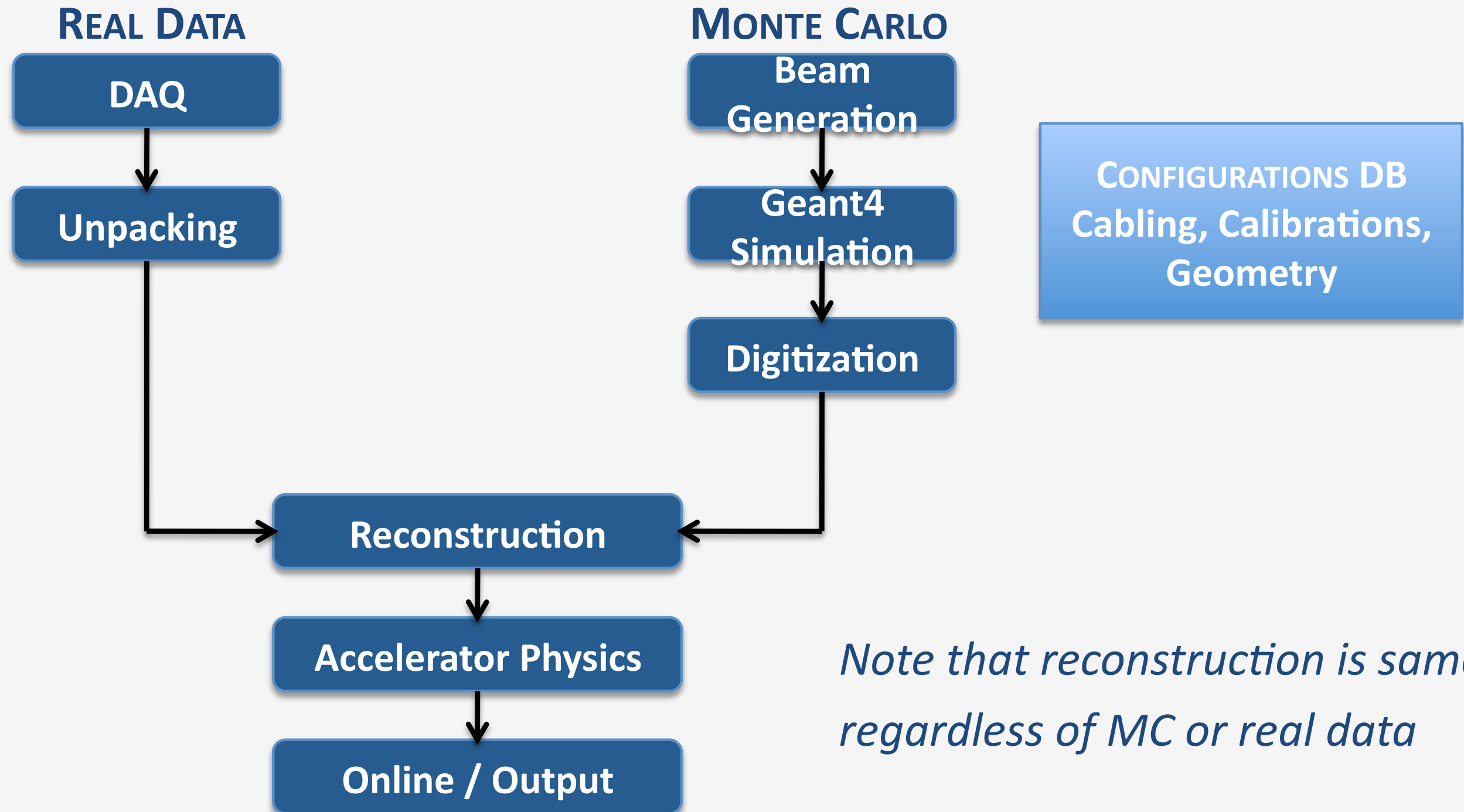


MICE Software Goals

- MICE is both an accelerator physics & a particle physics experiment
 - Beam simulations, emittances, transfer matrices, Twiss parameters
 - Traditional HEP detectors: simulation, track reconstruction, particle identification
 - Need common software scope
- Online reconstruction & monitoring during data-taking
- Wide range of geometries, configurations to book-keep
- Framework for analysis tools
- Code testing, Issue tracking, documentation
- Long-term maintainability: MICE is built & operated in stages



DATA FLOW



Note that reconstruction is same regardless of MC or real data



MAUS:

MICE ANALYSIS AND USER SOFTWARE

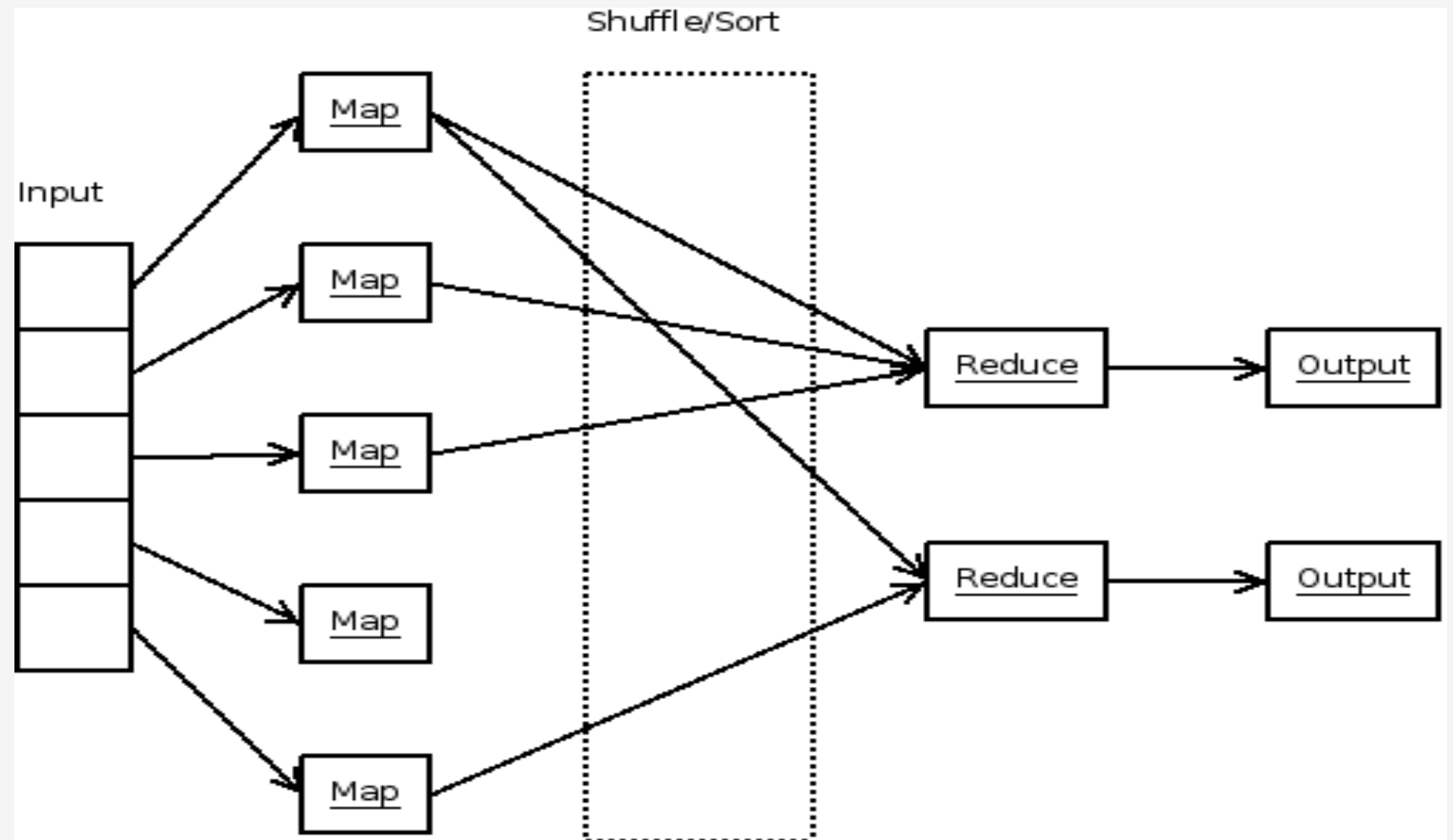
- Design inspired by MapReduce

- Map

- Operate on a single event
- Can run in parallel
- e.g. Simulate, reconstruct

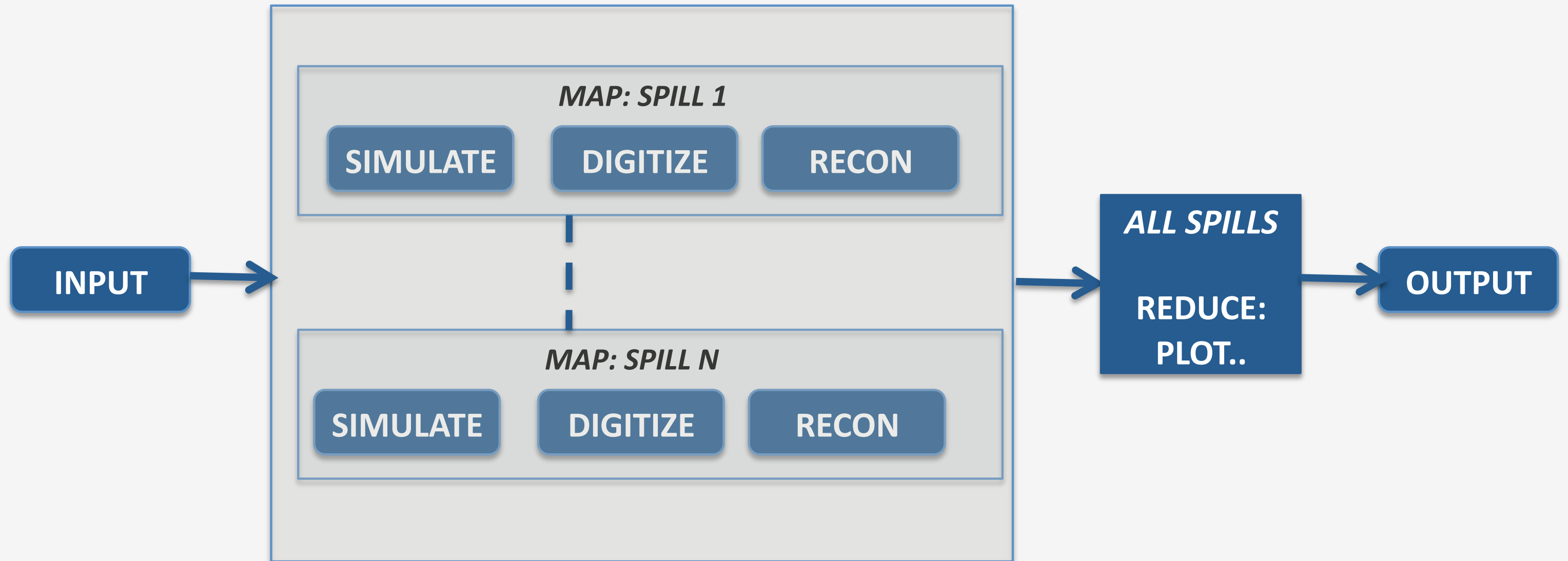
- Reduce

- Operate on a collection of events
- e.g., Summary histograms





MAUS DESIGN





MAUS: MICE ANALYSIS AND USER SOFTWARE

- MapReduce
 - *Technically, in MAUS: Input-Transform-Merge-Output*
- **INPUT:** Read in data
 - DAQ data file, I/O stream, beam library for Monte Carlo
- **MAP:** Process spills & return modified data
 - A spill is the primary data block & consists of several event triggers
 - Monte Carlo simulation, Detector reconstructions
 - Mappers have no internal state & can operate in parallel
- **REDUCE:** Process accumulated data from *all* mapped spills
 - Summary histograms, run performance plots, etc
- **OUTPUT:** Save data
 - Write out in ROOT/JSON format



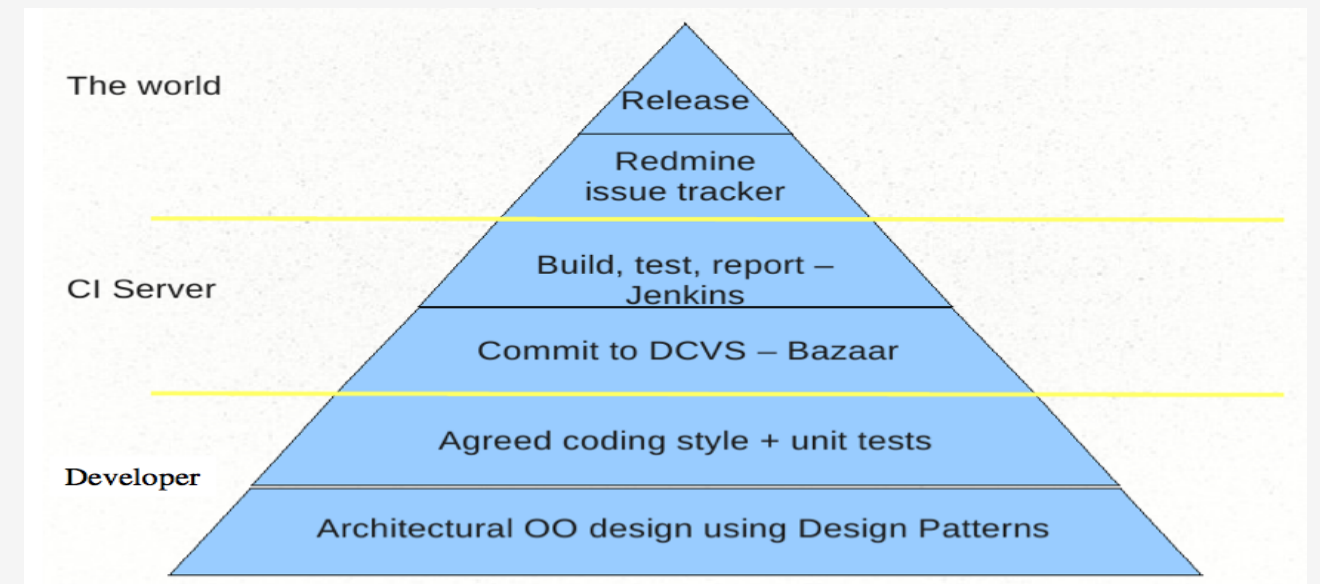
MAUS FRAMEWORK

- Framework built on plug-in modules
- Developers write modules in C++ or Python
 - Python for higher-level algorithms, or where development time is a factor
 - C++ for lower-level computationally intensive algorithms: particle tracking, fits, likelihoods
 - C++11 support
 - Python-C++ bindings handled by wrappers
- Data representation: ROOT, JSON
 - Default is ROOT, but developers find JSON quite useful for quick debugging
 - Mapper modules are templated to a data type
 - conversion between data types handled by API
 - Significant performance speedup by removing JSON-C++ conversions



CODE MANAGEMENT

- 10-15 developers in the UK, Europe, USA
 - Headed by Adam Dobbs @ Imperial College
- Distributed version control
 - Bazaar repository, hosted on Launchpad
- SCons build system
- QA:
 - Python/C++ style guidelines
 - Unit testing & integration testing
 - Code monitored for line & function coverage: aim $\geq 70\%$ line coverage
- Redmine wiki & issue tracker
- Scientific Linux 6 is officially supported OS
- Several external dependencies
 - Python, ROOT, Geant4, G4Beamline, XBoa ...
 - Dependencies built as “third party” libraries during installation; build scripts come with MAUS





CONTINUOUS INTEGRATION

- Unit tests
 - Test individual modules/pieces of code
- Integration tests
 - Test if units work together and with external libraries
- Jenkins CI test server with multiple slaves at RAL and Brunel University
 - Developers run jobs on the test servers, validate & test their user branch before proposing to merge in the mainline trunk

The screenshot shows the Jenkins dashboard at test.mice.rl.ac.uk. The main area displays a table of build jobs. The table has columns for status (S for success, W for warning, F for failure), job name, last success time, last failure time, and last duration. The jobs listed include MAUS_build_and_unit_test, MAUS_per_commit_third_party_heplnm071, MAUS_geometry_download, MAUS_full_install, MAUS_per_commit_third_party_heplnv157, MAUS_per_commit_third_party_brunel_test_box, MAUS_per_commit_third_party, MAUS_rogers_load_tests, MAUS_online, MAUS_integration_tests, MAUS_sl64, adobbs_merge_candidate, MAUS_karadzkov, and MAUS_release.

S	W	Name	Last Success	Last Failure	Last Duration
●	☀	MAUS_build_and_unit_test	5 hr 21 min - #357	1 day 5 hr - #356	46 min
●	☀	MAUS_per_commit_third_party_heplnm071	16 hr - #171	1 day 7 hr - #170	2 hr 54 min
●	☀	MAUS_geometry_download	19 hr - #173	N/A	3 hr 22 min
●	☀	MAUS_full_install	1 day 5 hr - #607	19 days - #596	2 hr 54 min
●	☀	MAUS_per_commit_third_party_heplnv157	1 day 7 hr - #58	22 days - #51	4 hr 9 min
●	☀	MAUS_per_commit_third_party_brunel_test_box	1 day 13 hr - #45	7 mo 5 days - #22	2 hr 31 min
●	☀	MAUS_per_commit_third_party	1 day 13 hr - #224	19 days - #218	2 hr 44 min
●	☀	MAUS_rogers_load_tests	4 days 21 hr - #125	N/A	1 day 0 hr
●	☁	MAUS_online	6 days 6 hr - #201	13 hr - #203	5 hr 41 min
●	☁	MAUS_integration_tests	6 days 6 hr - #324	1 day 2 hr - #326	1 day 9 hr
●	☀	MAUS_sl64	6 days 11 hr - #114	N/A	6 hr 11 min
●	☀	adobbs_merge_candidate	7 days 17 hr - #1	N/A	4 hr 9 min
●	☁	MAUS_karadzkov	12 days - #106	2 days 17 hr - #111	2 hr 36 min
●	☀	MAUS_release	12 days - #71	8 mo 19 days - #63	5 hr 45 min



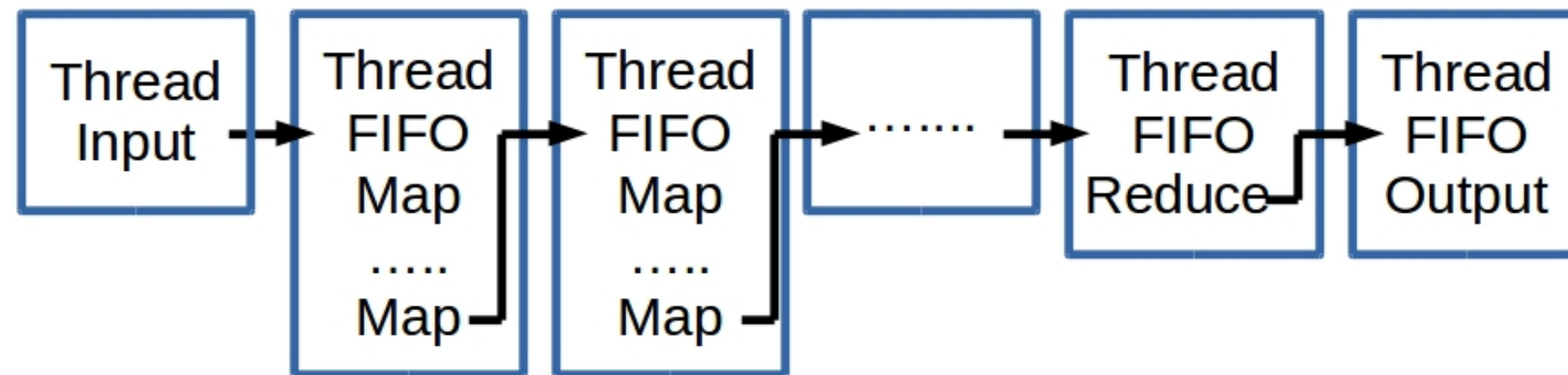
Database

- Varying configurations & running conditions
 - Beam momentum, cooling channel magnets, absorbers, calibrations
 - Must be monitored (Controls & Monitoring – EPICS) & stored
- Configuration DB holds
 - Run conditions from data-taking
 - Beamline settings
 - Electronics cabling maps
 - Calibration constants
 - Geometry models
- Postgres DB
- Master DB within control-room LAN, public read-only slave at RAL
- Most APIs in Python, some in C (multi-threaded EPICS does not like Python)
- *See talk by J. Martyniak on Wednesday*



MAUS Online

- In classic MapReduce, map operations have to terminate before reduction
- However, for online reconstruction:
 - Want to visualize/plot (reduce) continuously as data flows (~after each map operation)
 - Speed was also an issue with more computationally intensive modules coming into MAUS
- New parallel C++ API developed:
 - Interfaces with MAUS modules
 - Jobs distributed by conveyer-like implementation
- Allows either single or multi-threaded
 - Multi-threaded mode during live data-taking

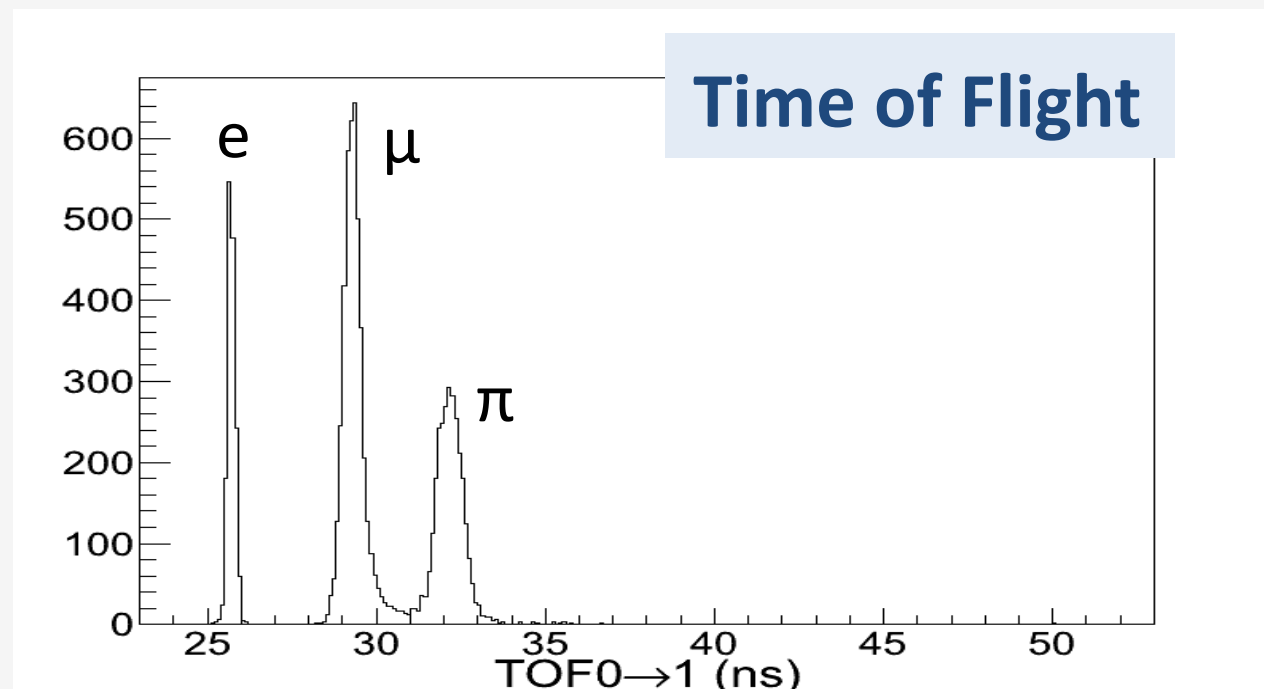




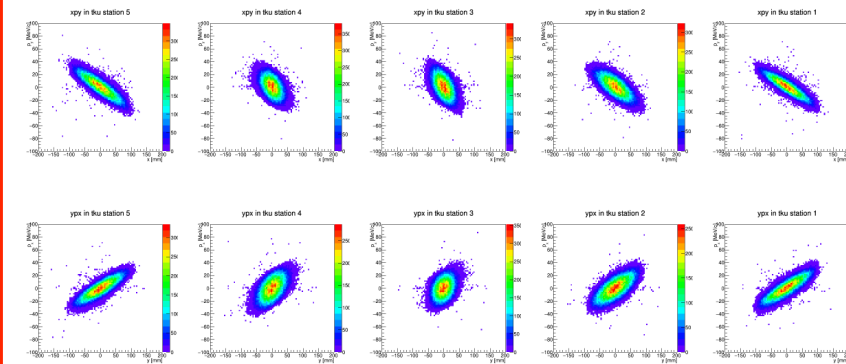
MAUS In Action

- Offline reprocessing & simulation with MAUS performed on GRID
 - Batch production & re-processing on Tier-2 sites
 - MAUS installation for GRID via CVFMS at RAL
- During data-taking, “live” reconstruction happens on a dedicated resource in the control room
 - Reconstruction speed ~ data-taking rate

RECONSTRUCTION PERFORMANCE



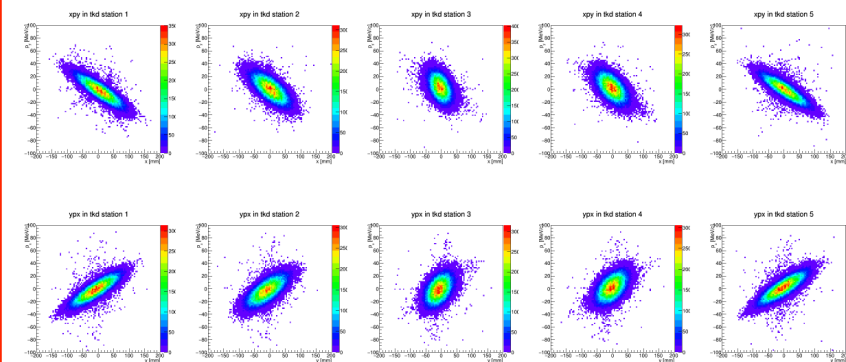
Polarity in the upstream tracker



$$\hat{L} = \langle xp_y \rangle - \langle yp_x \rangle < 0 \quad (3)$$

→ Anticlockwise rotation, **normal** polarity

Polarity in the downstream tracker



$$\hat{L} = \langle xp_y \rangle - \langle yp_x \rangle < 0 \quad (4)$$

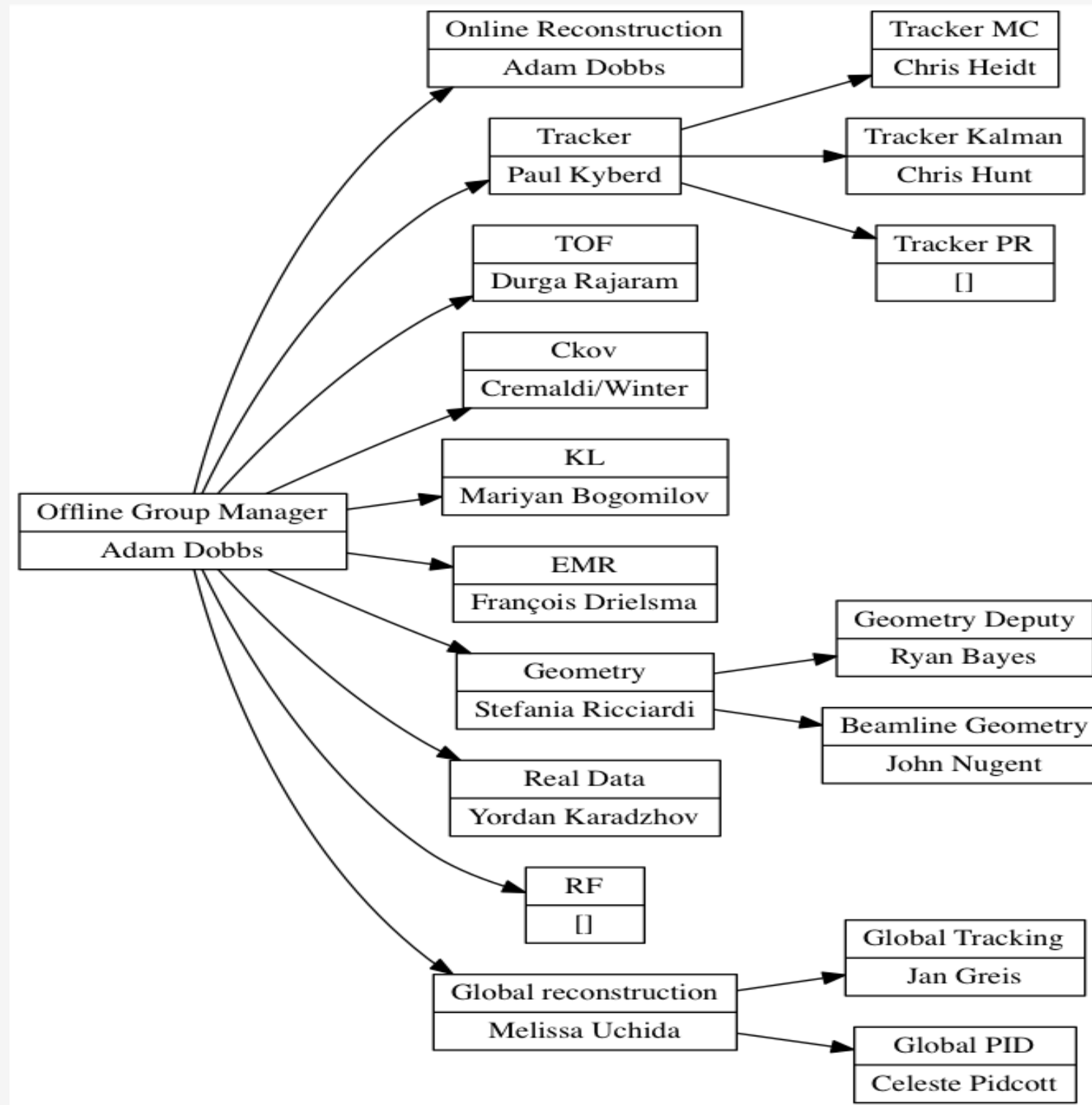
→ Anticlockwise rotation, **normal** polarity



SUMMARY

- MAUS provides a simulation, reconstruction, and accelerator physics analysis framework for MICE
- Implemented based on MapReduce
- Online parallel processing capabilities
- Well-defined & yet flexible framework
- Several industry-standard QA practices adopted
 - Code coverage, continuous integration testing
- Simulation and reconstruction software in place
- Data-taking underway & MAUS is in action feeding analysis

THANKS TO ALL MAUS DEVELOPERS



And many more..