

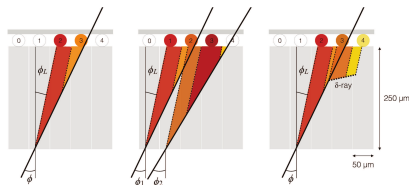
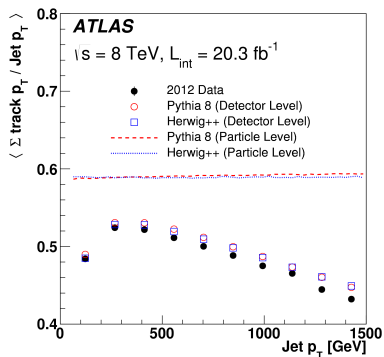
Highlights: Development and performance of track reconstruction algorithms at the energy frontier with the ATLAS detector

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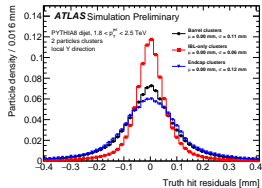
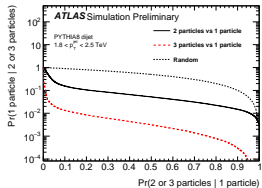
Tracking in dense environments



- ▶ Charged particles typically deposit charge in > 1 pixel or strip per layer
- ▶ **dense environments**: distance between particles close to detector granularity
 - ▶ e.g. high-pt b -hadron, τ decays or top quark jets
- ▶ Charge clusters can merge
- ▶ High $\sqrt{s} \rightarrow$ more dense environments \rightarrow difficult tracking!
- ▶ figures: [STDM-2014-17], [1406.7690]

Tracking in dense environments

- ▶ Use neural networks to estimate number of charged particles in clusters, measure the hit positions and associated errors



- ▶ Measure fraction of lost tracks in dense environments with single-particle clusters dE/dx fit using single- and multiple-particles templates

