

The Application of SNIKER to the JUNO Simulation

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Outline

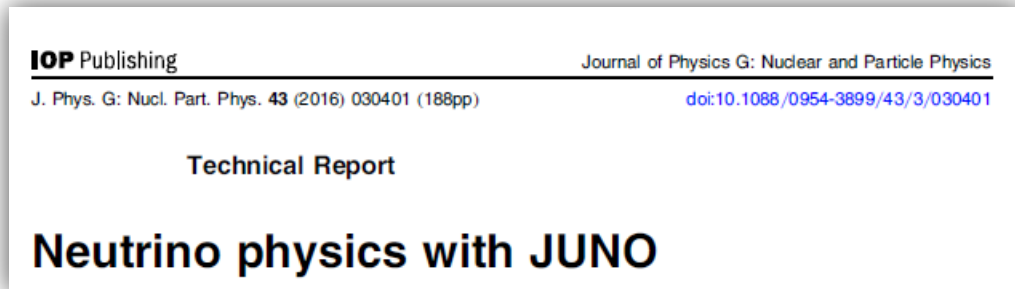
- Introduction
 - JUNO experiment
 - JUNO offline software and SNI^{PER}
- JUNO Detector Simulation Framework
- JUNO Electronics and Digitization Simulation
- Conclusion

JUNO Experiment



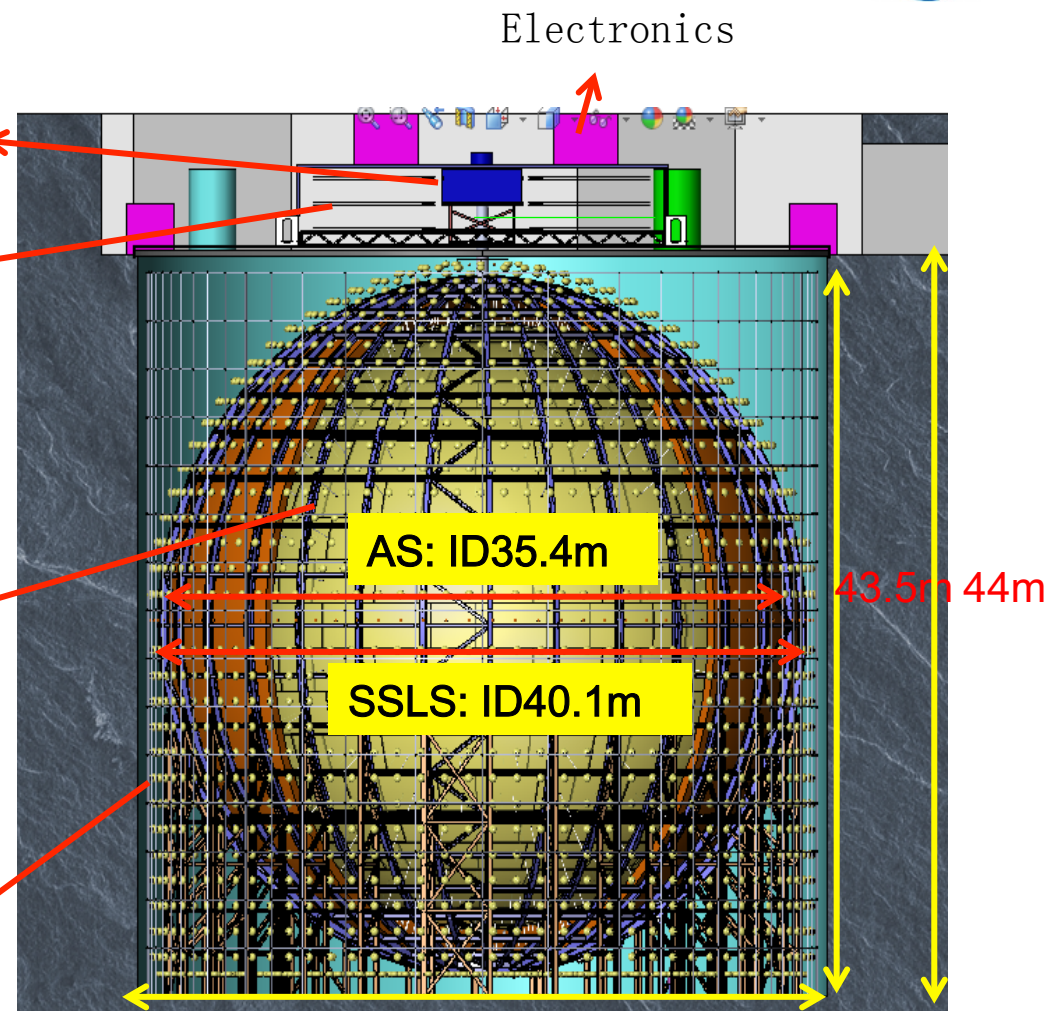
- **Location:**
Jiangmen,
Guangdong,
China
- **Status:**
Under Construction

J. Phys. G: Nucl. Part. Phys. 43 (2016) 030401



- Reactor Neutrinos (→ Mass hierarchy)
- Supernova Neutrinos
- Geo-neutrinos
- Solar Neutrinos
-

- Calibration
- Top Tracker
- Central detector
Acrylic sphere+
20kt Liquid Scin.+
~17,000 20" PMT+
~34,000 3" PMT
- Water Cherenkov
~2000 20" PMT



D43.5m
AS: Acrylic sphere;
SSLS: stainless steel latticed shell

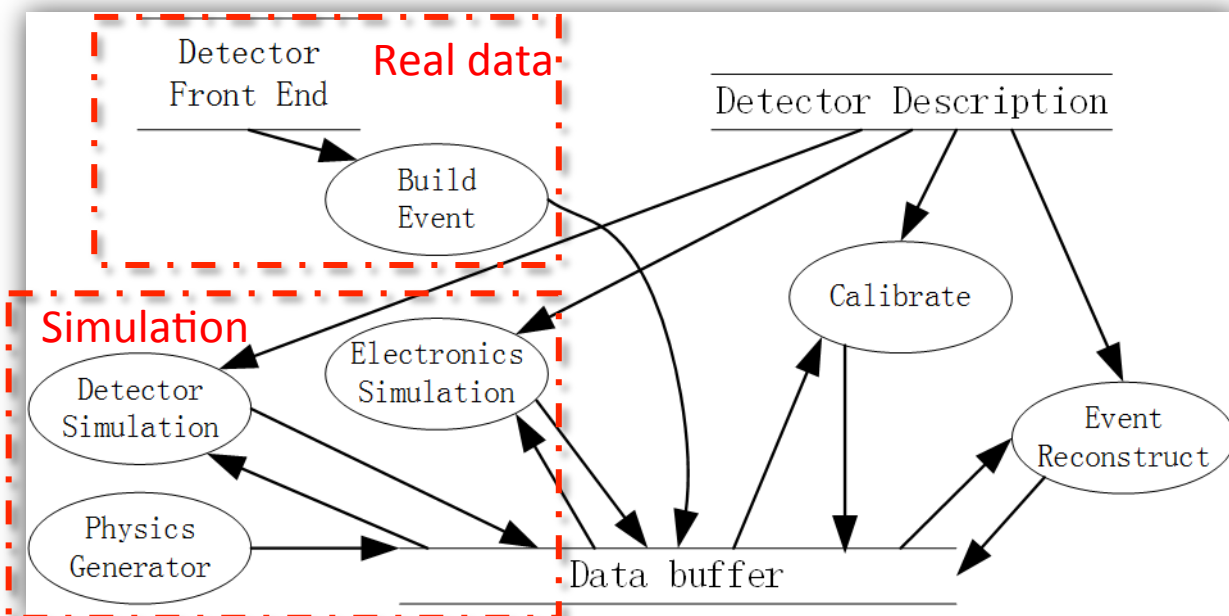
JUNO Offline Software

■ Mainly includes:

- Framework, Simulation, Calibration, Reconstruction

■ Software Development Environment

- Language: C++ and Python 2
- OS: Linux (Scientific Linux 6, gcc 4.4)
- Framework: SNIKER
- Simulation: Geant4 9.4
- Dependent: XercesC, CLHEP, HepMC
- Software management: CMT & SVN
- Installation Tool: junoenv (bash)



■ ~ 10 official versions have been released, the latest one is J16v2r1-Pre3

SNiPER [CHEP2015, ICHEP2016]

Software for Non-collider Physics Experiments

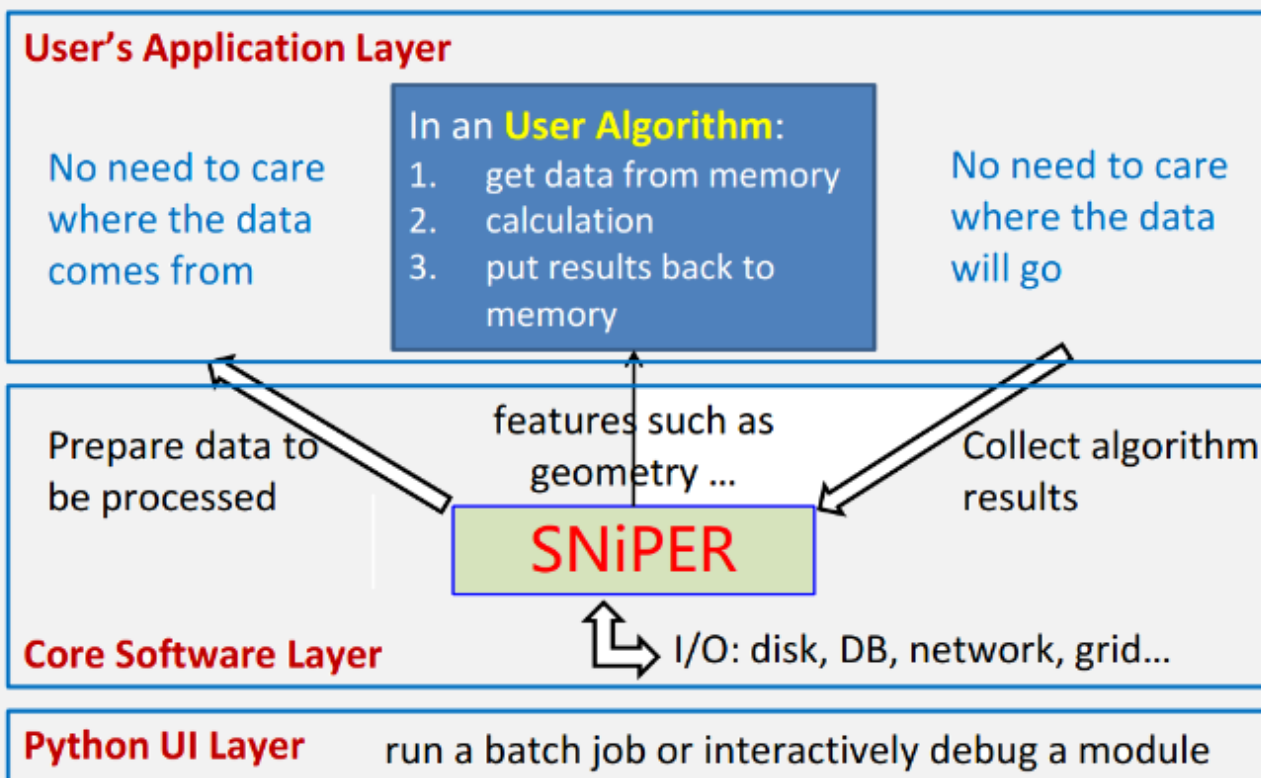


Figure 1: An overview of SNiPER

- **Task**, a lightweight application manager, controls Event Loop.
- Other tasks could be executed by **Incident** mechanism.

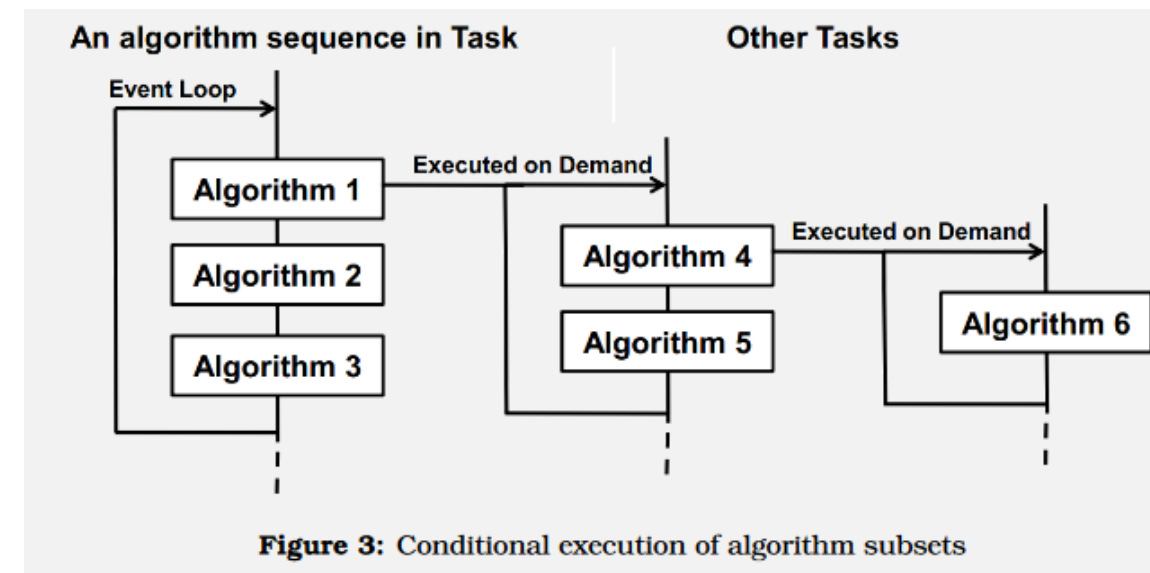
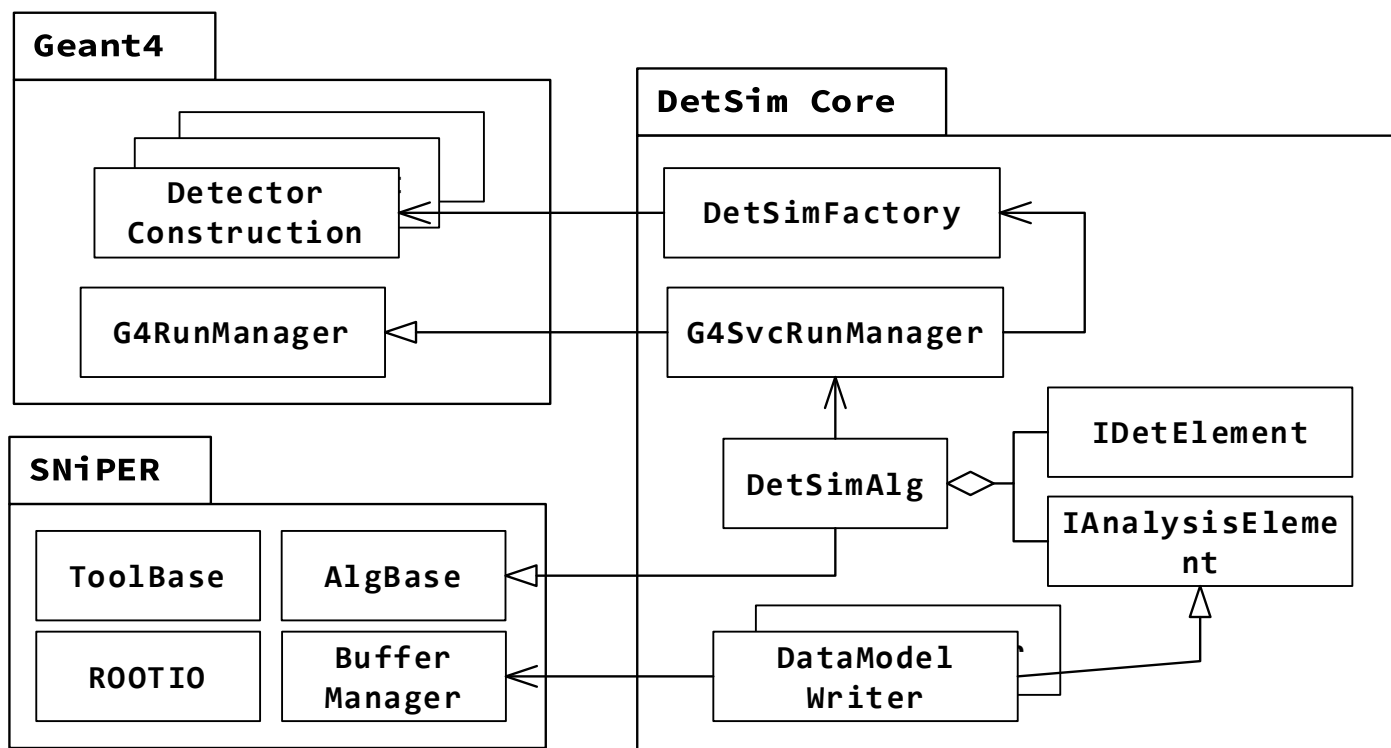


Figure 3: Conditional execution of algorithm subsets

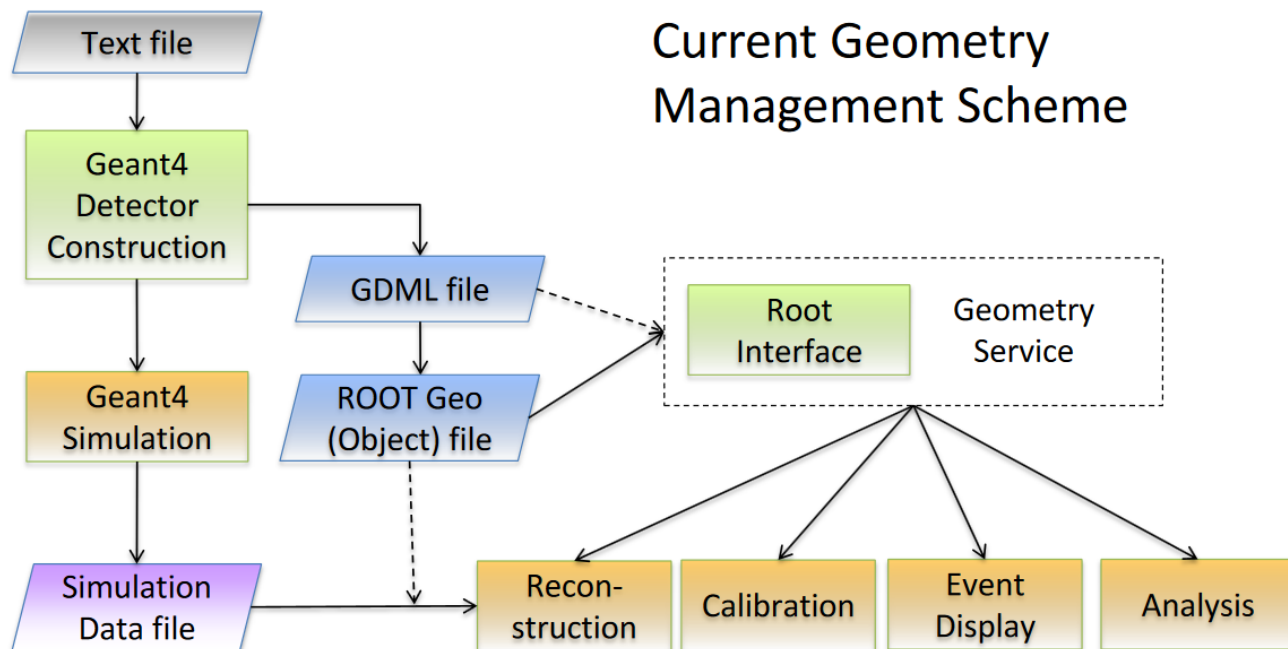
Detector Simulation Framework

■ Integrate SNIper & Geant4 (9.x).

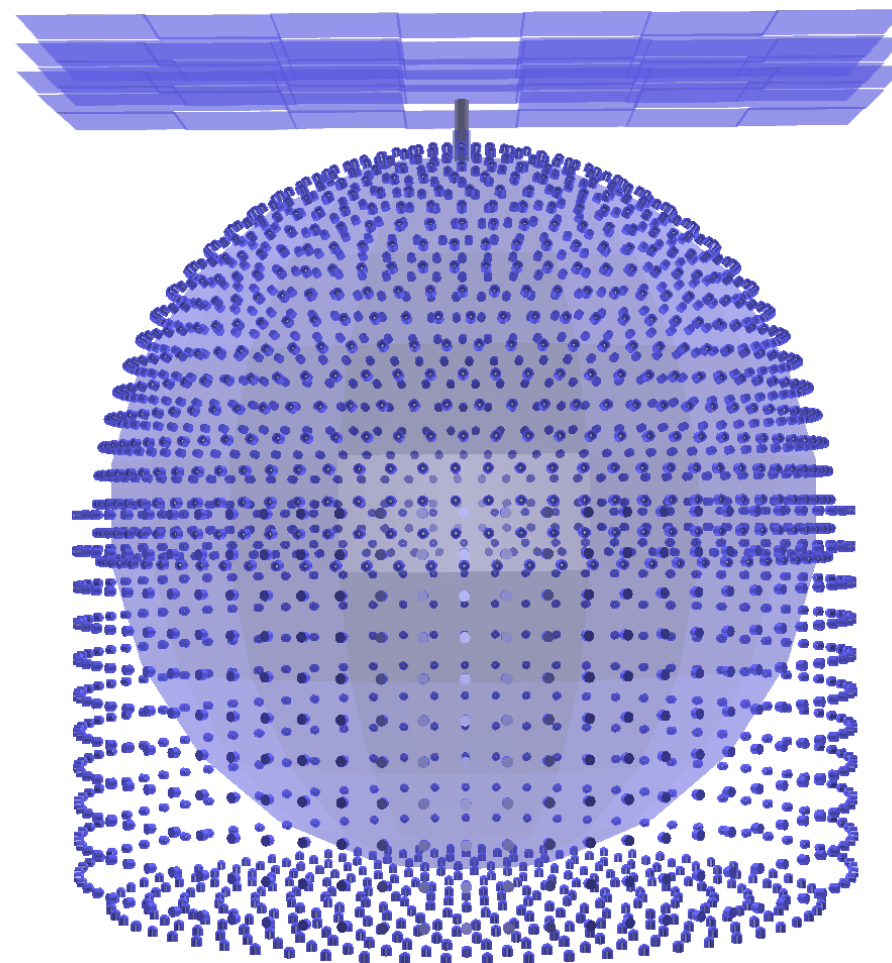


- Features:
 - Lightweight simulation framework.
 - Easy to migrate from standalone application.
 - Support both batch and interactive modes.
 - Support Geant4's macro files/commands in Python.
- Plan:
 - Supporting multi-threading Geant4 (10.x).

Geometry Management (1)



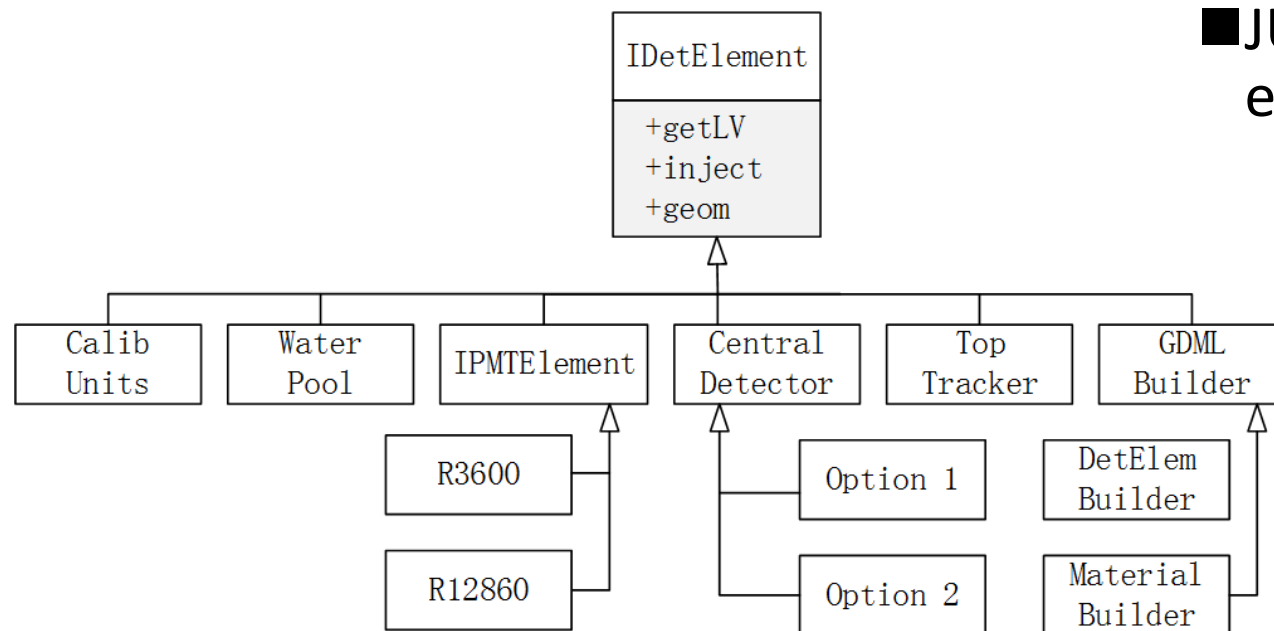
- GDML description including 3" PMTs, node size ~54k PMTs, ~330k nodes
- Geant4 generation and ROOT conversion time ~30 sec
- File size: GDML file 22 MB, ROOT file 3 MB



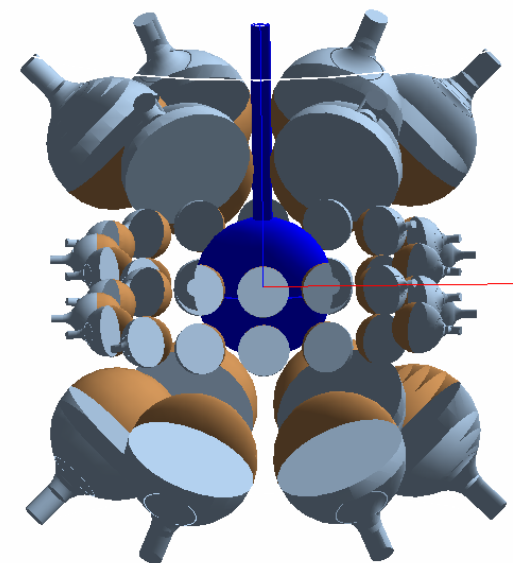
JUNO Veto PMTs, rendered using ROOT

Geometry Management (2)

- Most of detector elements is constructed from code.
 - Each part could be configured and constructed at runtime.
 - Useful for detector design and calibration units.



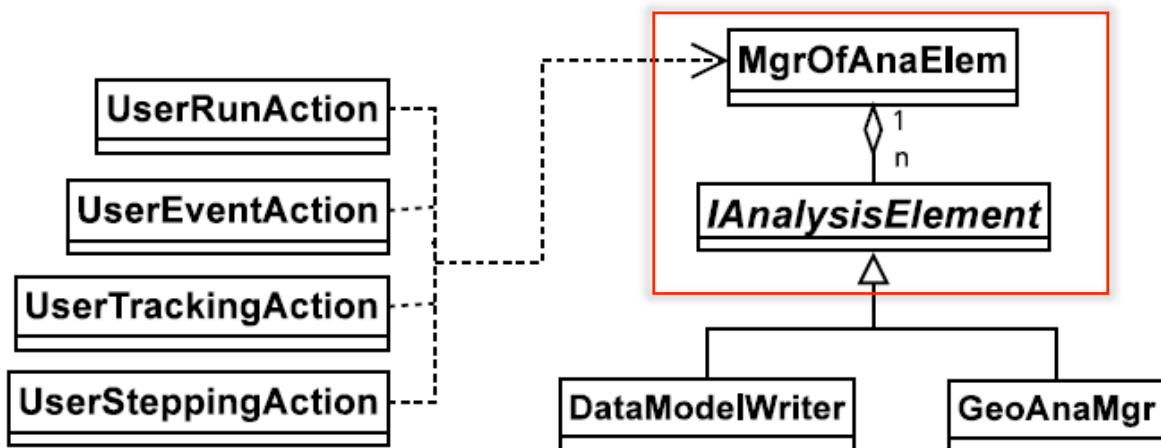
- JUNO prototype detector could be setup easily using the same simulation software.



MC Truth and User Action

■ Modular design of User Action.

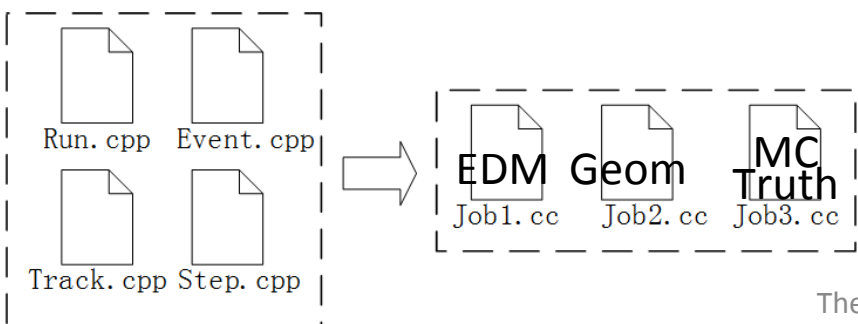
■ Event Data Model (ROOTIO)



- Separation of Header and Event, for lazy loading.

Physics Generator	HepMC
Detector Simulation	SimHeader
	SimEvent
	SimTrack
	SimPMTHit
	SimTTHit

- Design, Pluggable and configurable.



■ Other MC Truth are saved in plain TTrees using RootWriter.

Electronics and Digitization Simulation

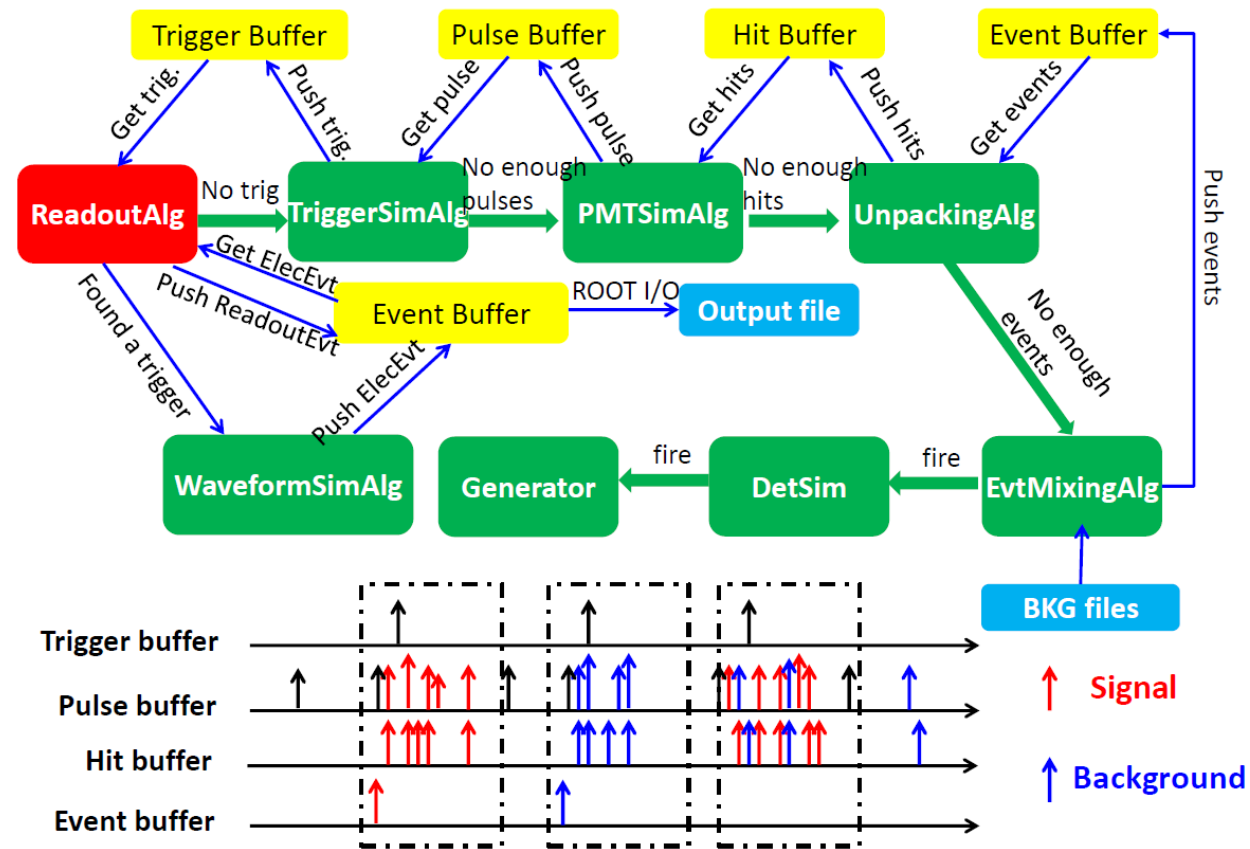
■ “PULL” workflow (data-driven)

- Starts from ReadoutAlg.
- Using SNIPEr’s Task+Incident to call TriggerSimAlg when buffer is empty.

■ Handle event mixing and event splitting gracefully.

- Such as IBD events (prompt and delay signals)

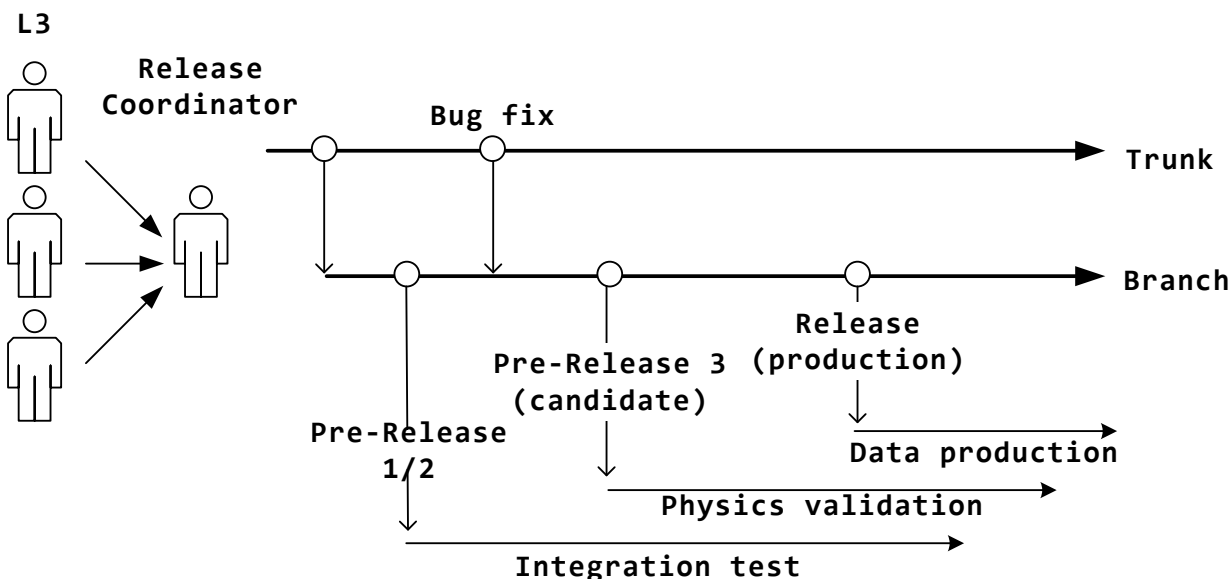
■ Each part is designed and implemented as a module.



```
python tut_det2elec.py \
--input IBD:ibd1.root \
--input U:u.root \
--rate IBD:1.0 \
--rate U:3.0
```

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Data validation and production



UPDATED Proposal: chains to test

- 3 chains to compare the outputs of:
 - 😊 (1) DetSim → “Calib” converter → Vtx+Ene rec (the ‘old’ way)
 - 😊 (2) DetSim → ElecSim in deterministic mode (no evt mixing) → Waveform rec → Vtx+Ene rec (the ‘new’ way)
 - no evt mixing, so that each simulated event is digitized 1-to-1 and can be inspected before and after ElecSim
 - 😊 (3) DetSim → ElecSim with evt mixing → Waveform rec → Vtx +Ene rec (the ‘new’ way)
 - with evt mixing, so that each simulated event is overlapped with bkgs as it happens in real life.
 - Bkgs = simulate natural ^{238}U + overlap Dark Noise at 50 KHz?

- “JunoTest Production” supports both validation and production.
- “.ini file” is used for configuration.

```
Validation.ini
[Chain]
seed = 42
evtmax = 500
njobs = 1
tags = e+_0.0MeV e+_1.398MeV
```

```
Production.ini
[Chain]
seed = 42
evtmax = 1000
njobs = 100
tags = e+_0.0MeV e+_1.398MeV
```

- Full chains of simulation and reconstruction are ready.
- First round validation is on going.
- Data Production will start soon.

Conclusions

- JUNO uses SNIKER as underlying framework.
- Based on SNIKER, simulation software was developed.
 - Detector simulation framework integrates SNIKER and Geant4.
 - Electronics simulation supports “PULL” workflow, allows hit level mixing.
- The full data processing chain is completed.
- MC Data challenge is preparing, will start soon.