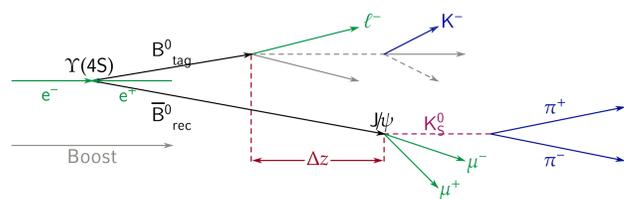


The Belle II Experiment

An electron positron collider with asymmetric energies located in Japan to test the standard model with high precision.

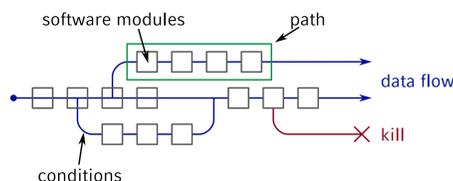


- ▶ start in 2018, collect 50 ab⁻¹ till 2024
- ▶ record 4 × 10¹¹ events, 100 PB of data
- ▶ generate simulated data with at least the same statistics

Software Framework

Software framework written from scratch using experience from Belle and other HEP experiments.

- ▶ core framework implemented in C++11 and including the boost libraries
- ▶ use ROOT 6 framework for serialization of event data, Geant4 for simulation
- ▶ python 3 interface for configuration and high level program steering
- ▶ different algorithms (called modules) are executed sequentially for each event



Conditions Data at Belle II

Conditions data is configuration/calibration data which depends on the conditions during data taking.

- ▶ database contains information on *run* granularity
- ▶ finer granularity to be handled on client side
- ▶ should be transparent to the user
- ▶ needs to work on closed DAQ network without outside connection

▶ See Wood et al, "Conditions Database for the Belle II Experiment", Monday 14:30, for details on the server

▶ See Dosset et al, "Status of the Calibration and Alignment Framework at the Belle II Experiment", Monday 15:15, for details calibration procedure.

Design Decisions

- ▶ use ROOT objects for conditions data
- ▶ identify by name
- ▶ default name is the class name

Read Access of Conditions Objects

Two template classes which always provide pointer to correct payload

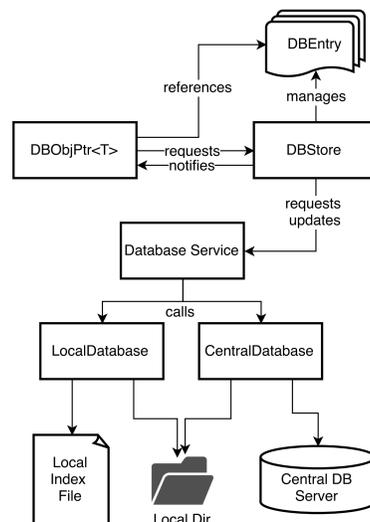
- ▶ DBObjPtr for single objects
- ▶ DBArray for arrays of objects
- ▶ shallow class, just points to common area

```
class MyConditionsClass: public TObject {
public:
    MyConditionsClass(const std::string &string):
        TObject(), m_string(string) {}
    const std::string& getString() const {
        return m_string;
    }
private:
    std::string m_string;
};
```

```
DBObjPtr<MyConditionsClass> myObj;
if(!conditionsObj){
    B2ERROR("NoConditionsDataAvailable");
}else{
    B2INFO("Conditions:" << myObj->getString());
}
DBArray<MyConditionsClass> myList("SpecialName");
B2INFO("Found" << myList.getEntries() << "objects");
```

Hides updates from the user

- ▶ user can check if payload changed
- ▶ user can register callback on change



Creation of Payloads

similar classes to create payloads

- ▶ DBImportObjPtr and DBImportArray
- ▶ allow to create payloads with simple interface

IntraRun Dependency

Some payloads might change more frequent than per *run*, for example Beamspot positions

- ▶ handled completely on client side
- ▶ different types of dependencies: event number, time stamp, ...
- ▶ usage completely transparent

```
DBImportObjPtr<MyConditionsClass> myObjImport;
myObjImport.construct("initial_value");
myObjImport.addEventDependency(10, "from_event_10");
myObjImport.addEventDependency(50, "from_event_50");
myObjImport.import(iov);
```

Different Storage Backends

Software offers different storage backends

- ▶ using REST api to obtain payloads from central database
- ▶ using local folder with payloads and text file defining validity.

This simplifies development and debugging:

- ▶ users can create and test their payloads locally without uploading
- ▶ users can continue to develop without internet connection
- ▶ snapshots of the database can be downloaded for isolated environments

Configuration and Usage

Usage of the database can be easily configured from the steering file

- ▶ several backends can be searched in order
- ▶ access to central database can be completely disabled

```
import basf2
# clear defaults
basf2.reset_database()
# use more than one source for payloads
basf2.use_database_chain()
# local fallback database looking in folder "db/"
basf2.use_local_database("db/payloads.txt", "db/")
# use central database as primary source and obtain
# payloads from global tag "mytag"
basf2.use_central_database("mytag")
```

Download of Payloads

Payload files are downloaded from the server using curl and stored in a local directory for caching

- ▶ if all payloads are found locally only metadata obtained from server
- ▶ md5sum of file is checked before opening
- ▶ multiple processes may be running at once, synchronization an issue

