

YETS 2016

Vacuum Alignments

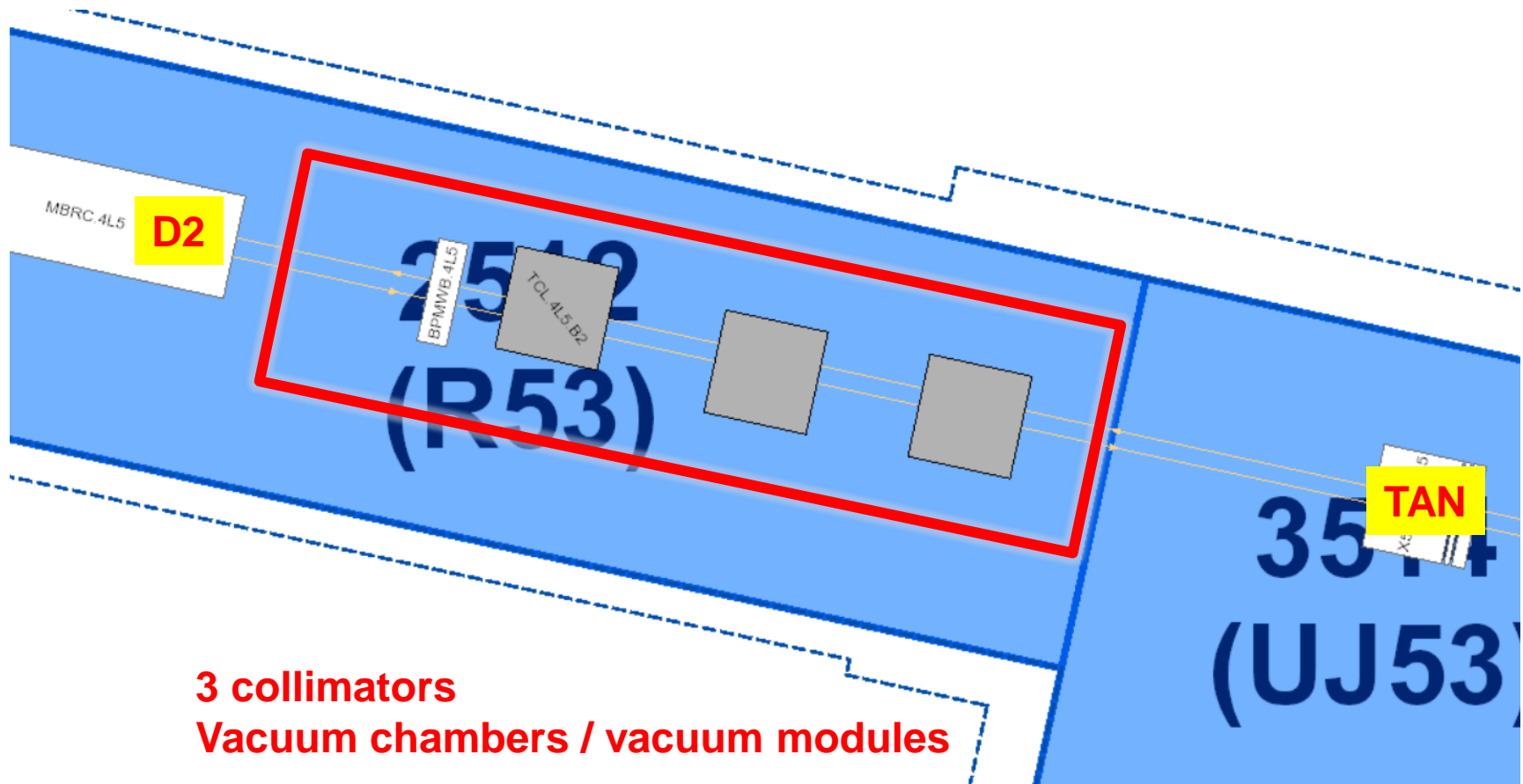
(LSS1 / LSS5)

Jean-Frederic FUCHS

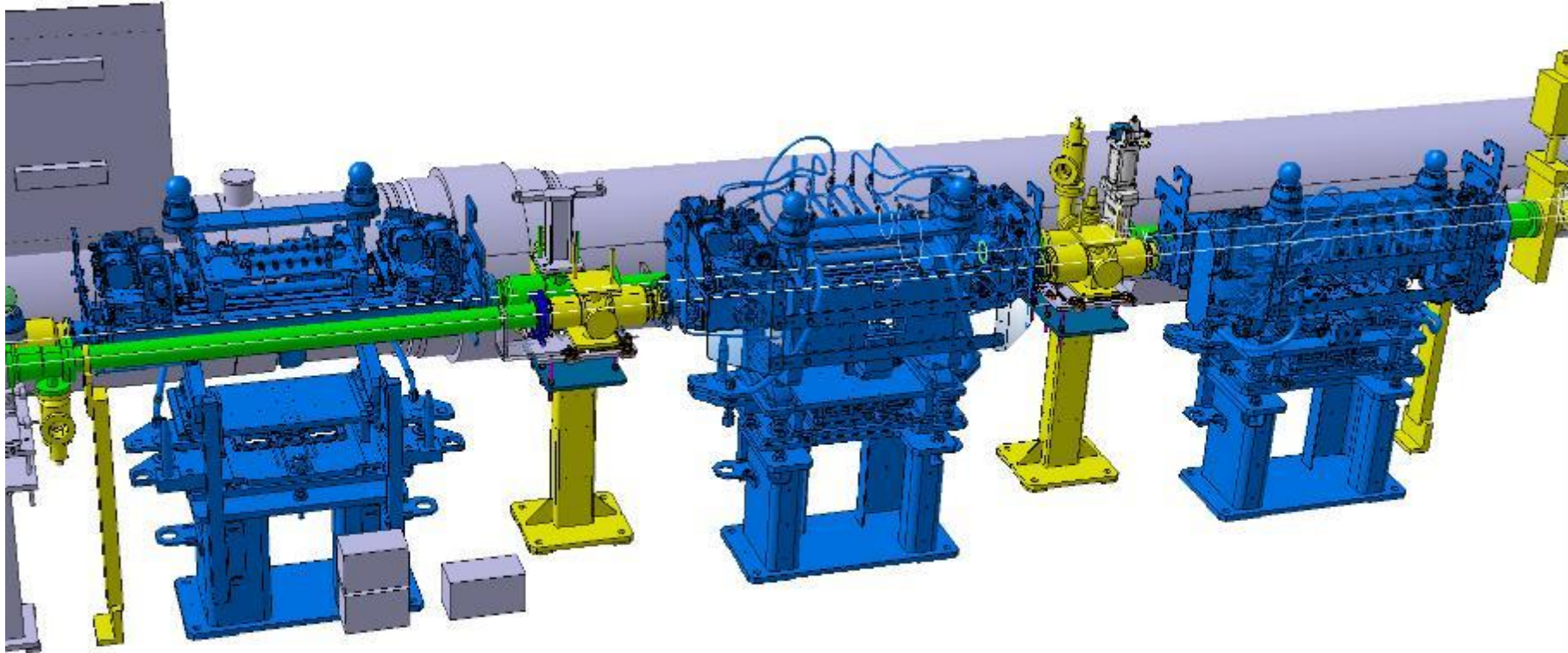


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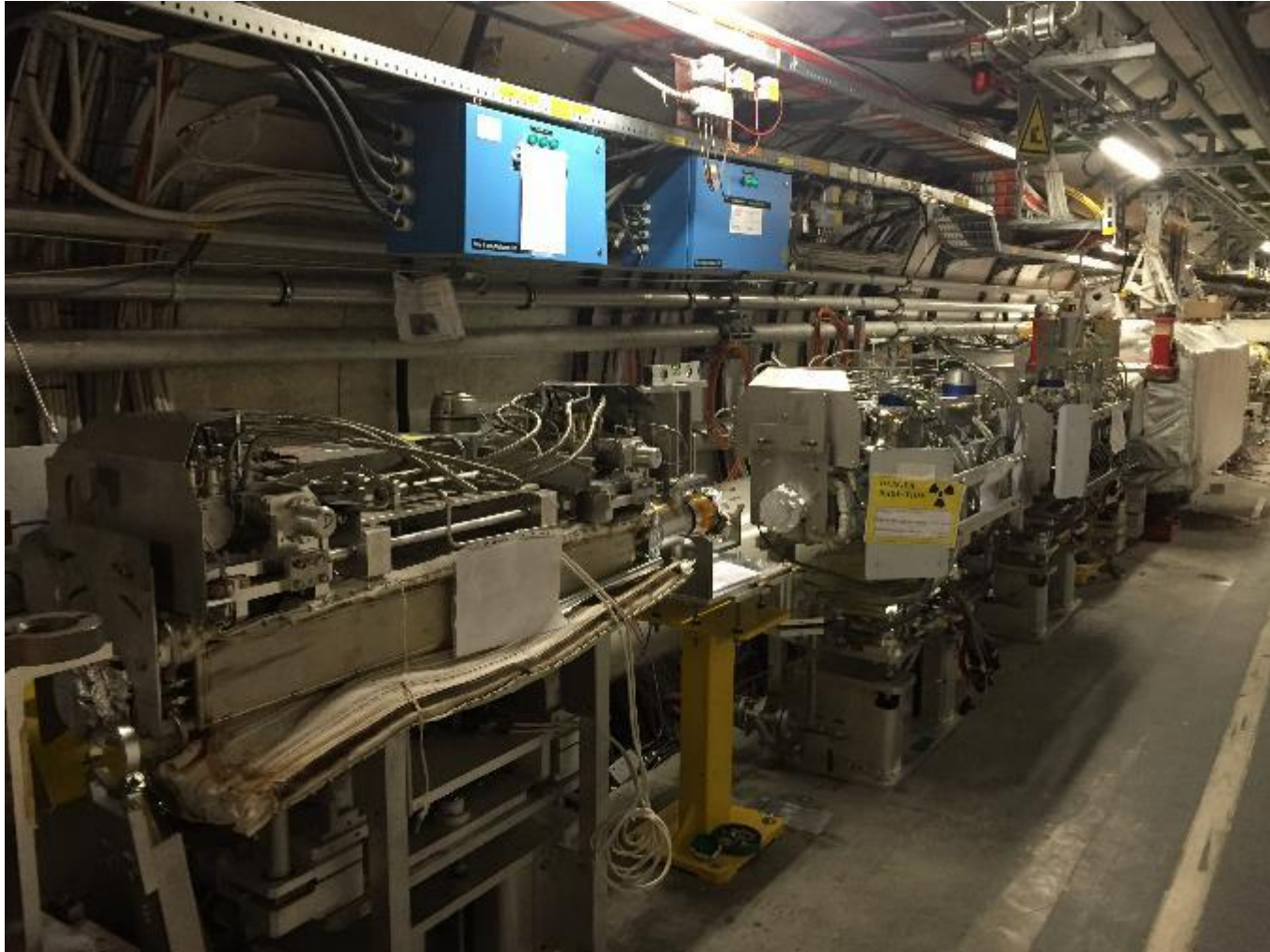
Top view : 4L5 (example)



General view

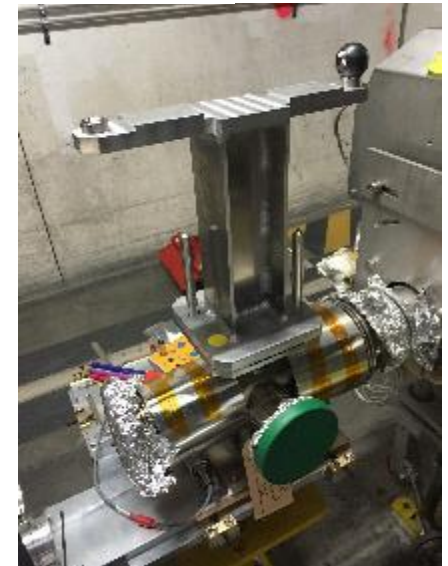
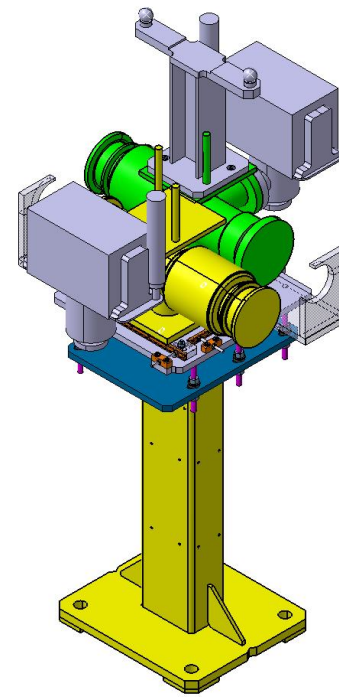


General view

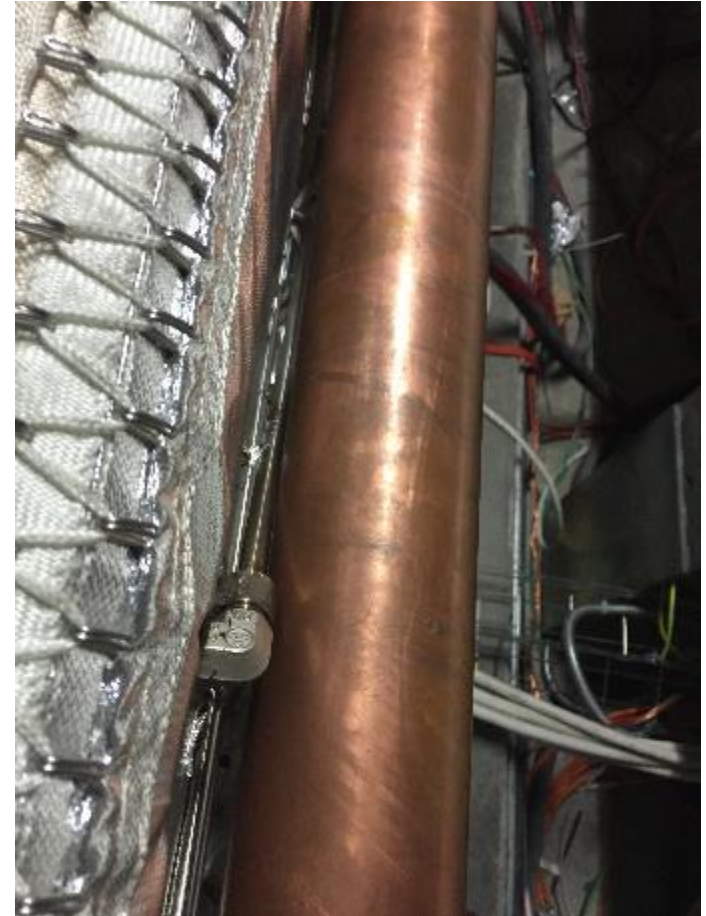


Survey activities

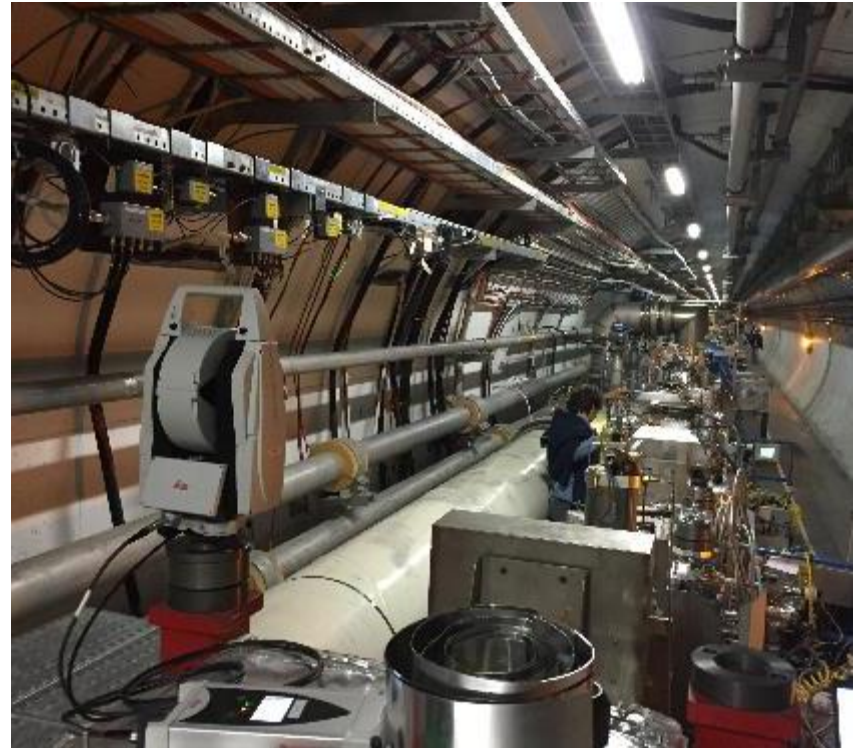
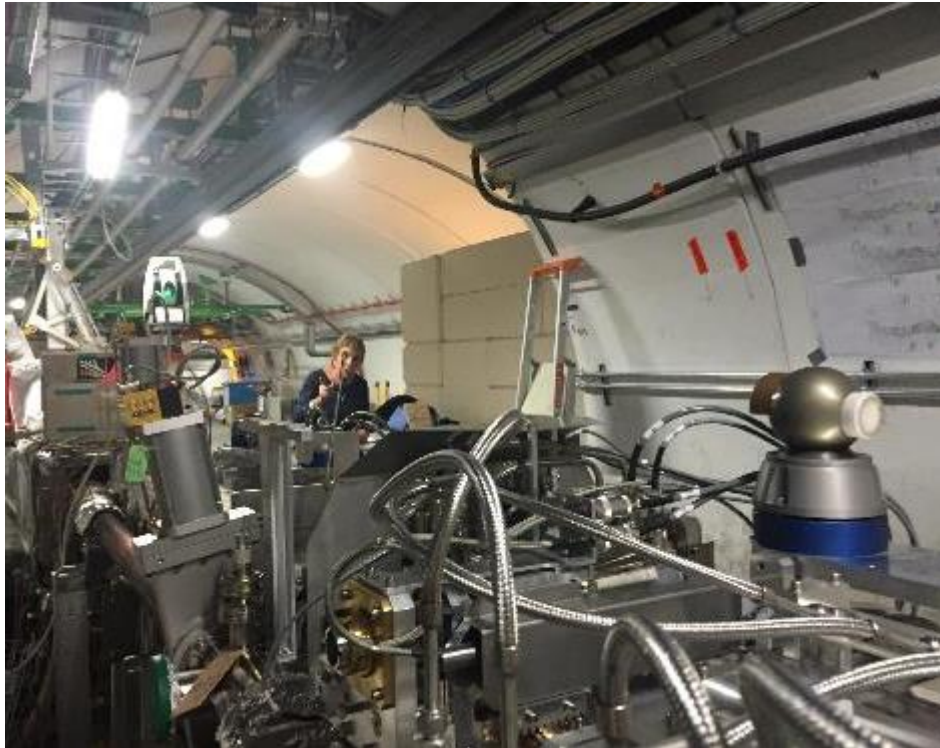
- Insertion of the “vacuum data” in GEODE
- Fiducialisation of the 8 modules (metrology lab)
- Tracing the position of the 8 feet (vacuum modules) and the new position of the collimators
- For each LSS side (x4) :
 - Alignment of collimators (x3) : 2D + 1
 - Alignment of vacuum modules (x2) : 3D



- The vacuum modules have been re-re-aligned for various reasons :
 - Loss of the fiducialisation,
 - Installation of the vacuum chambers : conflict with the collimator !
 - Ask for optimization of the vacuum chamber position (BE/ABP)



- Many obstacles, work on QRL side, access,

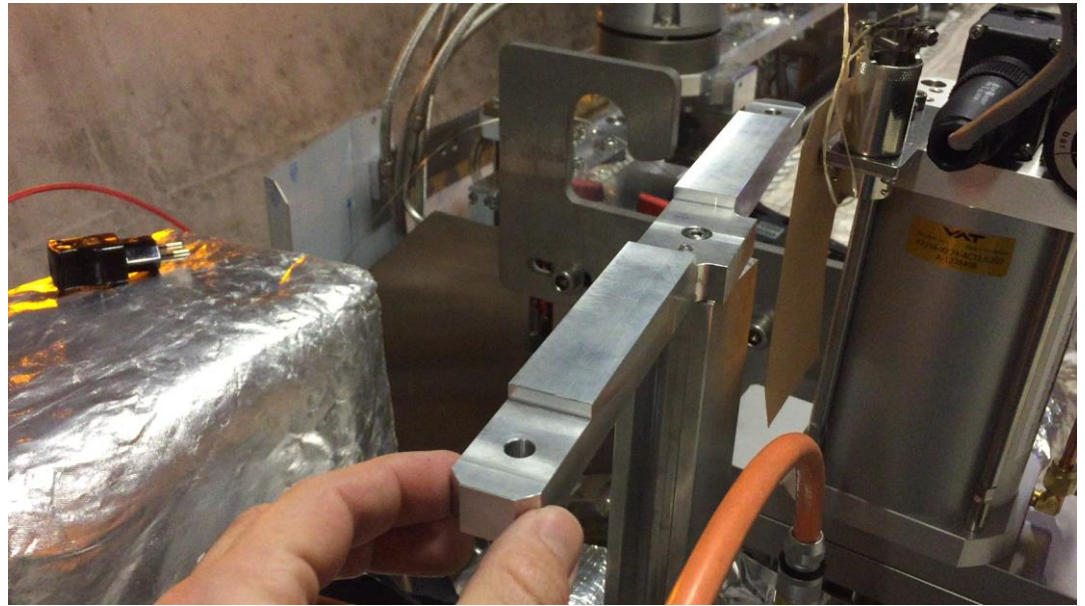


- SU need “references” : TAN + D2



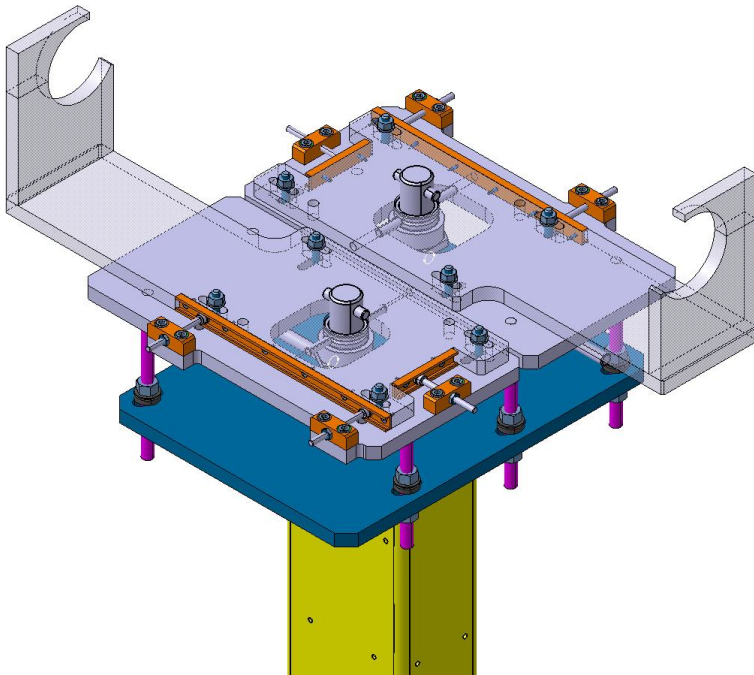
To be improved

- Some target supports in the vacuum modules were not well usable (stability, not fixed,
- Tilt surface !



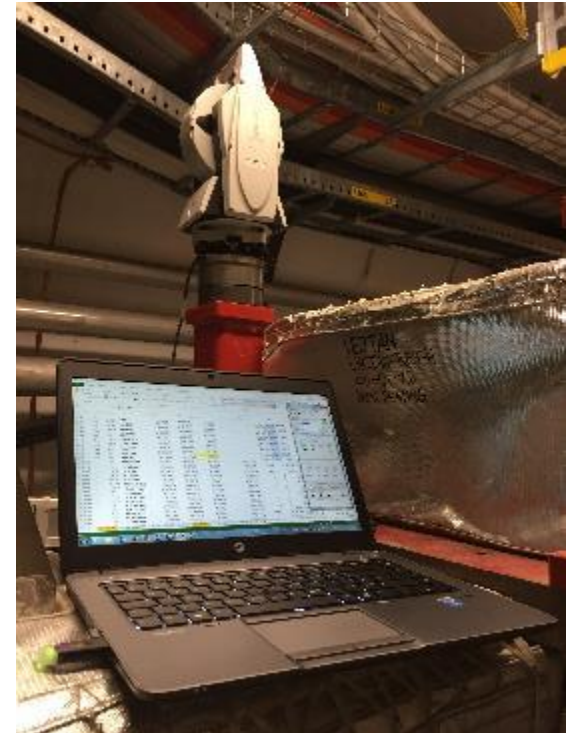
To be improved

- Alignment system need to be optimized



At the end SU measured the chamber axis

- Many obstacles
- Cannot be used for the alignment process



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- SURVEY is not in charge of the vacuum chamber alignments
- SU need (ask for) a management decision
- Many improvements are needed
 - Input data / fiducialisation
 - Alignment systems
 - “Targets” on the object / stability
 - Survey corridors
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