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ARC Control Tower and ARC CE

ARC CE and NDGF

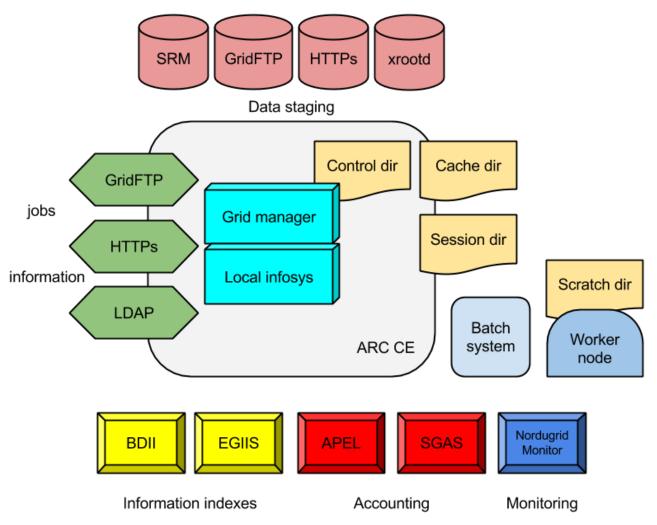
- Distributed dCache
 - Requires synchronous data transfer and local caching
- No middleware or connectivity from worker nodes
- ARC CE performs pre and post job data transfer
- Input files are downloaded to local shared filesystem cache



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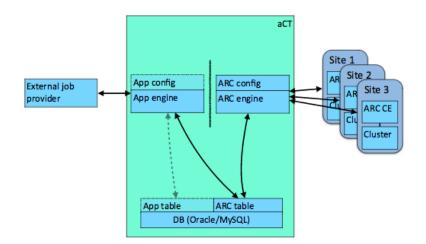
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ARC CE Components

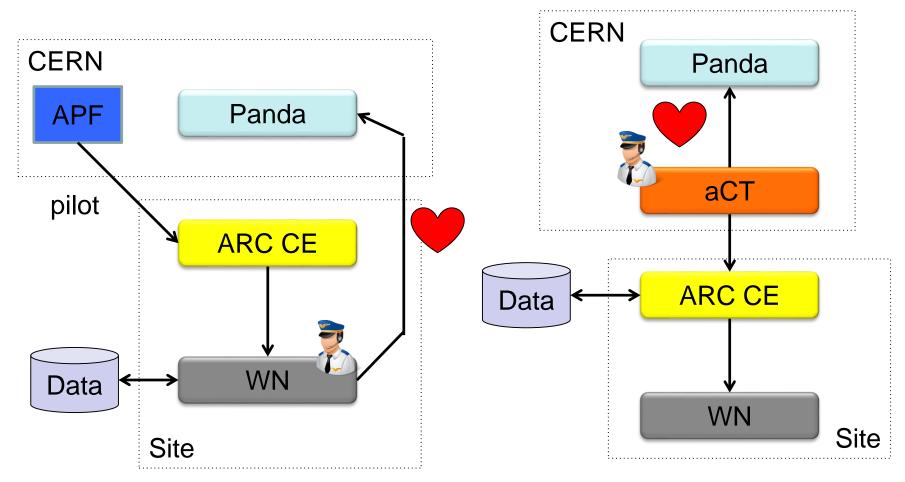


Need for ARC Control Tower

- The pilot model does not work well for NDGF
 - Requires middleware on the WN, outbound connectivity, synchronous data-staging
- Put a service in between Panda and ARC CE
 - A "fake fat pilot" pulling jobs, sending them to ARC and dealing with communication with Panda
 - Started as ATLAS-specific project, now generic



APF vs aCT job submission



Issues with pilot job framework

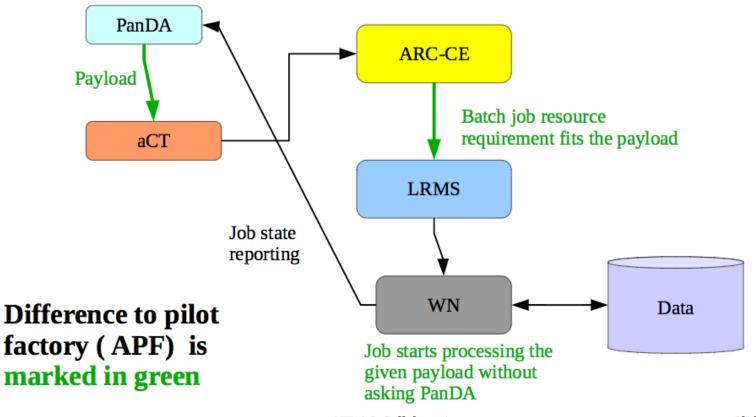
- ATLAS uses different workloads by memory, cputime, corecount requirements
 - But pilots are submitted with fixed requirements
- The only way to run different workloads is different Panda queues:
 - single-core
 - multi-core
 - analysis
 - hi-memory
 - very hi-memory
 - ...
- A task with radically new requirements requires a new Panda queue – heavy maintenance cost
- Fixed requirements lead to sub-optimal batch system scheduling

aCT "Truepilot" mode

- For sites running ARC CE who do not need the full "native" mode with staging etc
- aCT fetches the payload and submits it to the ARC-CE
- ARC-CE submits the batch job with predefined payload and requirements
- Pilot on the worker node does the same as on the conventional pilot sites, but skips the fetching of payload from PanDA
- aCT sends heartbeats to Panda up until job is running, then leaves it to pilot

aCT Truepilot

A. Filipcic, CHEP 2015



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Pilot factory vs aCT Truepilot

Pilot factory:

A. Filipcic, CHEP 2015

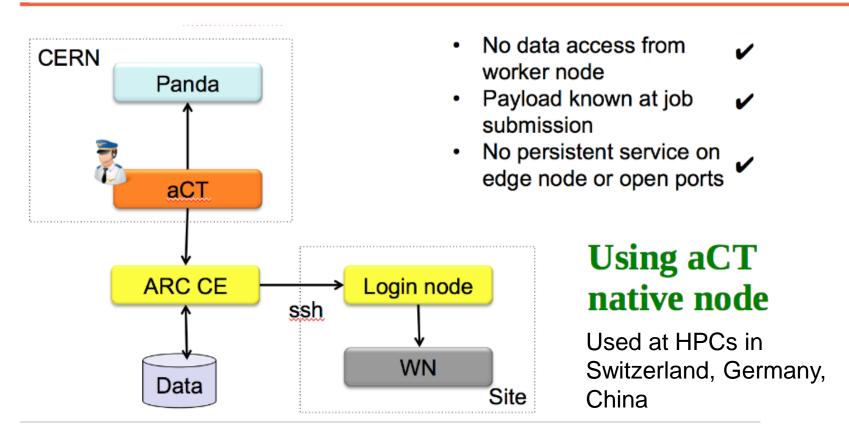
- Highest priority jobs start running first
- But the batch jobs have all the same resources
- aCT truepilot:
 - Payload known in advance the batch job has the resource requirements fit to the job
 - Payload can request any memory, cputime, corecount, of course in agreement with site capabilities
 - But the late-binding is partially lost highest priority jobs need to wait some time in the batch
 - Bad worker nodes can cause black holes fast resubmission cycle

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aCT and Supercomputers - HPCs

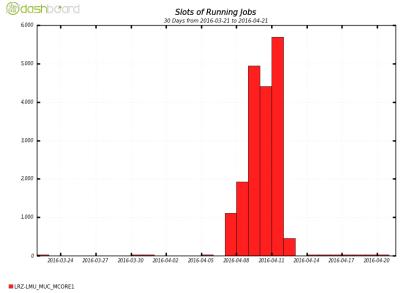
A. Filipcic, CHEP 2015



ATLAS Collaboration

aCT, ARC CE and Event Service

- Solution for HPC backfilling where there is no WN connectivity
- Instead of uploads to OS from WN, ARC CE uploads all events at the end of the job
 - This was shown to be a bottleneck zipping by pilot can address this issue
- aCT reports completed events to Panda
- For jobs preempted by the batch system:
 - An ARC CE plugin "unfails" the job and does pilot post-processing (metadata xml, log tarball etc)
 - Tested in SuperMUC HPC (300 x 24 cores)



Maximum: 5,688 , Minimum: 0.00 , Average: 587.25 , Current: 0.00

aCT service and sites

- 4 machines at CERN
 - 2 prod: large physical machines, one master, one hot spare
 - 2 dev: VMs, for testing, eg Event Service workflow
- Databases:
 - Prod machines: MySQL database on demand
 - Dev machines: local MySQL
- Serving ~12% of all ATLAS jobs:
 - ND, DE T2s, RAL, TW, BOINC, ...
- Very basic monitoring:
 - <u>https://voatlas403.cern.ch/data/aCTReport.html</u>
- Kibana service status probe is running (but reporting 100%)
- Source code (5k lines of python): https://gitlab.cern.ch/arc/aCT

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Mon Apr 25 13:55:45 CEST 2016

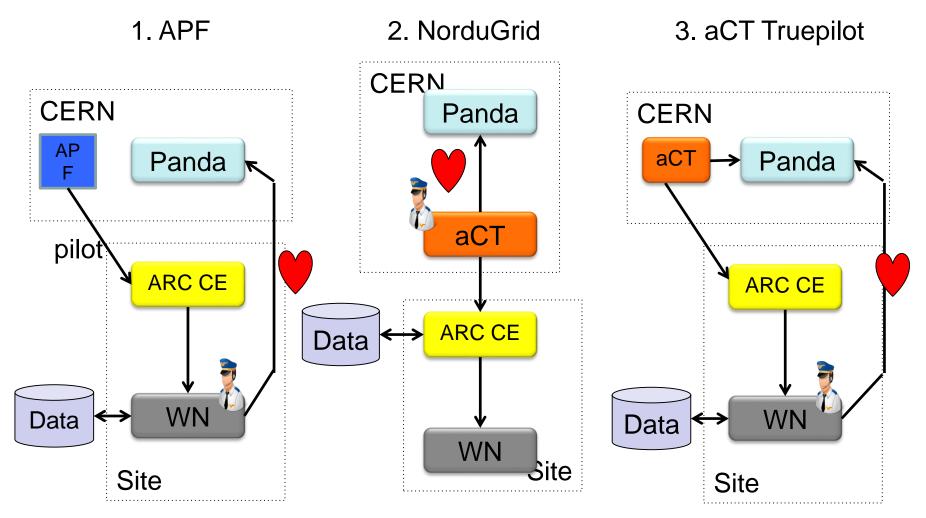
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RA	18	110	-	1	-	2	nordugrid.unibe.ch:
	740	90	39	69	-	37	pikolit.ijs.si:
RAI	18697	4931	68	560	4	1691	Totals:

Summary of aCT/ARC modes



Current Issues and Future Work

- Lost heartbeat problem:
 - In true pilot mode, bad nodes can cause job to fail before any heartbeat is sent
 - aCT doesn't send any heartbeats or resubmit jobs so info/logs are lost (in fact aCT has the logs but can't tell panda where they are)
- Top priority jobs
 - Inherent latency in the model but not really an issue for high-throughput sites where batch system priorities work
- Missing software release/badly matched job requirements can block a site
 - Improve monitoring and reporting back to panda
- Improve service resilience
 - Remove afs dependency
 - Automatic failover to hot spare
- Monitoring improvements
 - Jobs and monitoring of service itself
- Move more sites to aCT reduce panda queues!

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References

- CHEP papers:
 - <u>http://iopscience.iop.org/article/10.1088/1742-6596/664/6/062042/pdf</u>
 - <u>http://iopscience.iop.org/article/10.1088/1742-6596/664/6/062042/pdf</u>
- CHEP talks:
 - <u>https://indico.cern.ch/event/304944/contributions/1672319/a</u> <u>ttachments/578552/796696/chep2015act.pdf</u>
 - <u>https://indico.cern.ch/event/304944/contributions/1672645/a</u> <u>ttachments/578833/797024/ARC_Control_Tower_-</u> <u>_CHEP2015v5.pdf</u>
- Operations twiki:
 - <u>https://twiki.cern.ch/twiki/bin/view/AtlasComputing/ARCCont</u> <u>rolTower</u>