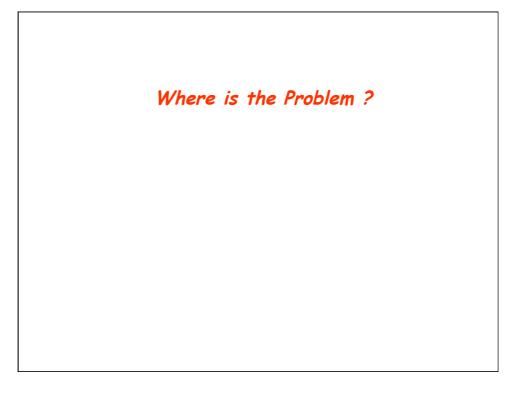
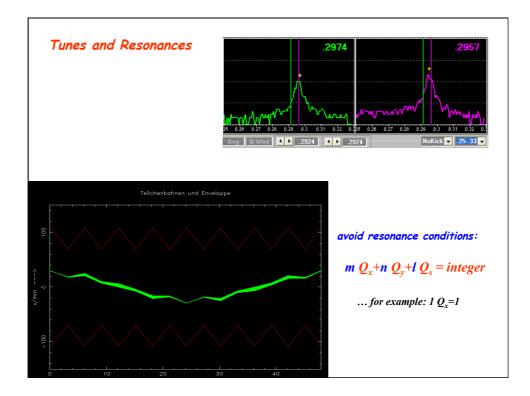
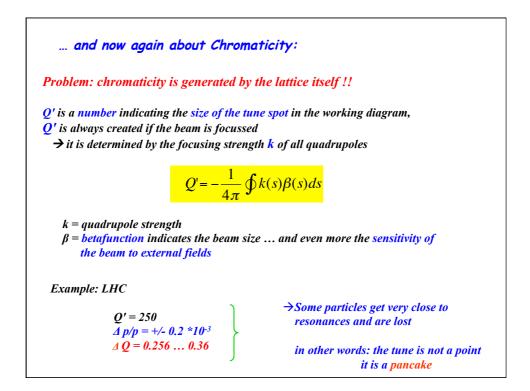
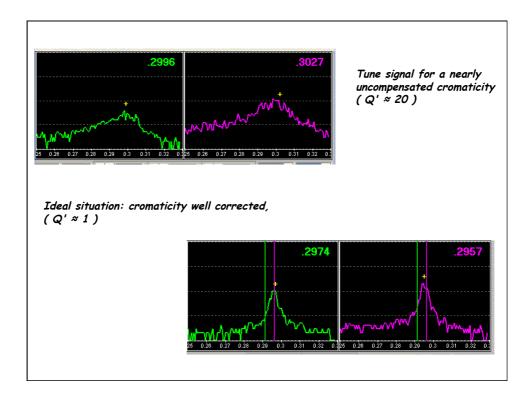


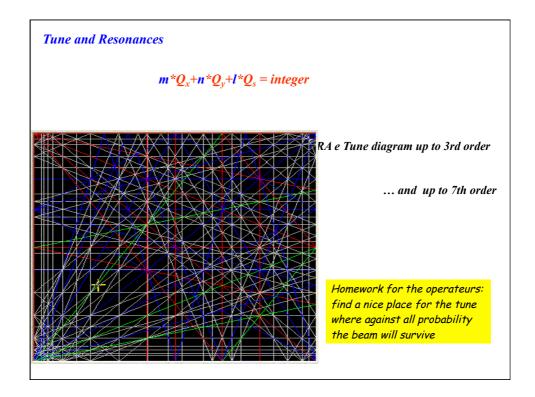
Chromaticity: Q' $k = \frac{g}{p_{e}} \qquad p = p_{0} + \Delta p$ in case of a momentum spread: $k = \frac{eg}{p_{0} + \Delta p} \approx \frac{e}{p_{0}} (1 - \frac{\Delta p}{p_{0}}) g = k_{0} + \Delta k$ $\Delta k = -\frac{\Delta p}{p_{0}} k_{0}$... which acts like a quadrupole error in the machine and leads to a tune spread: $\Delta Q = -\frac{1}{4\pi} \frac{\Delta p}{p_{0}} k_{0} \beta(s) ds$ definition of chromaticity: $\Delta Q = Q' \quad \frac{\Delta p}{p} ; \qquad Q' = -\frac{1}{4\pi} \oint k(s) \beta(s) ds$

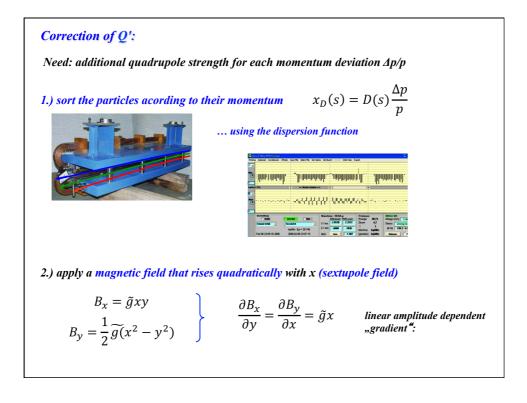


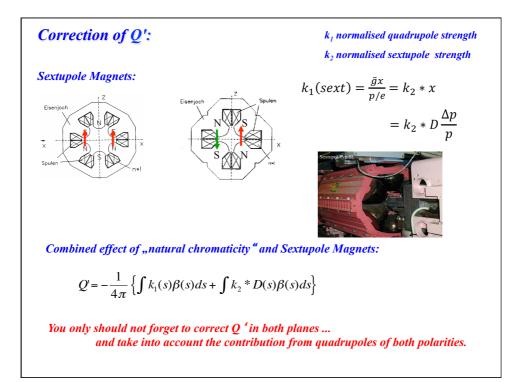


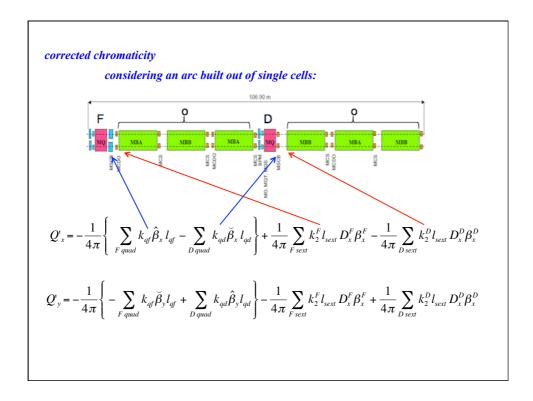


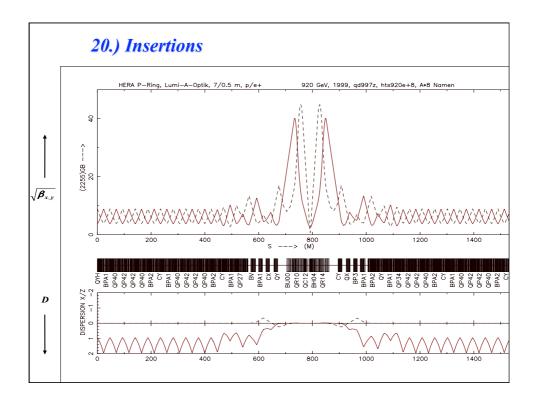


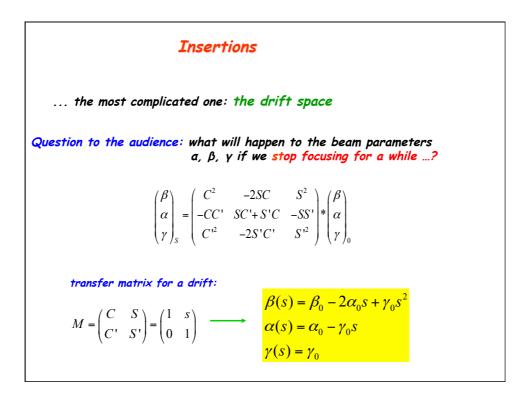


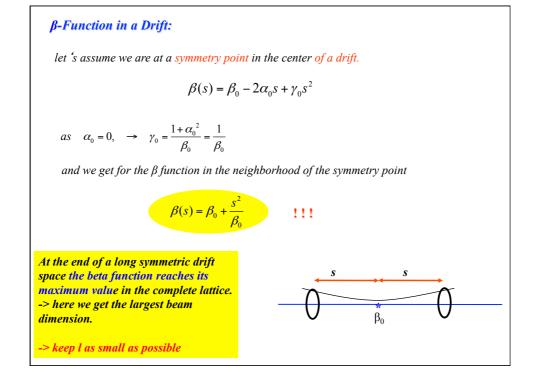


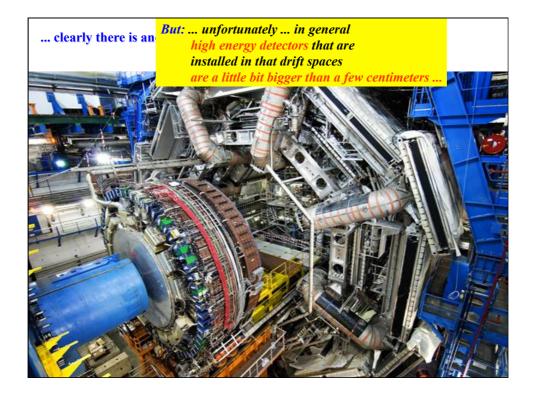


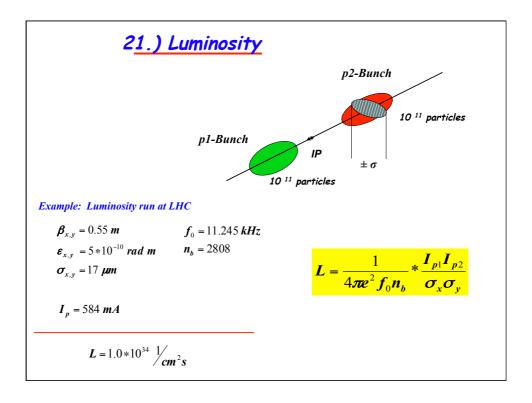


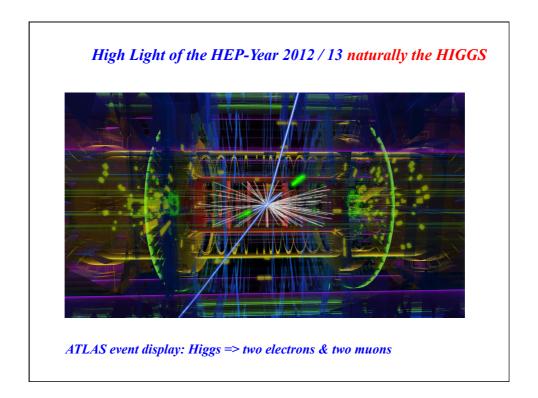


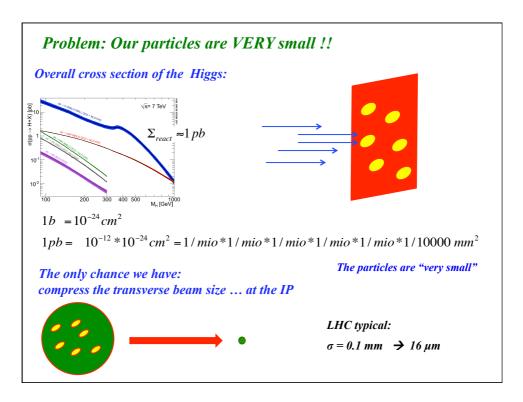


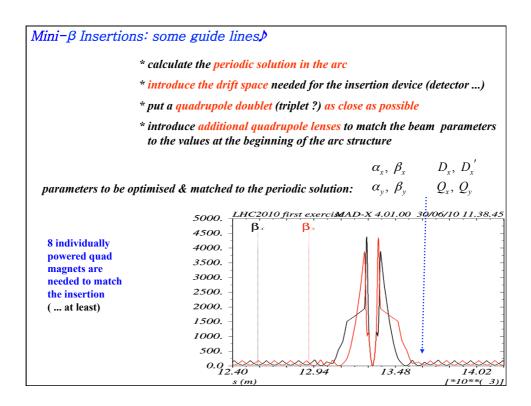


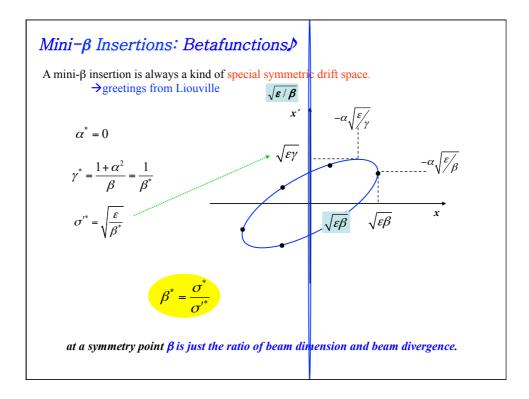


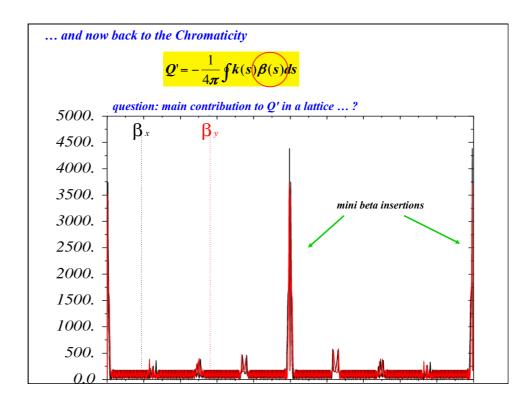




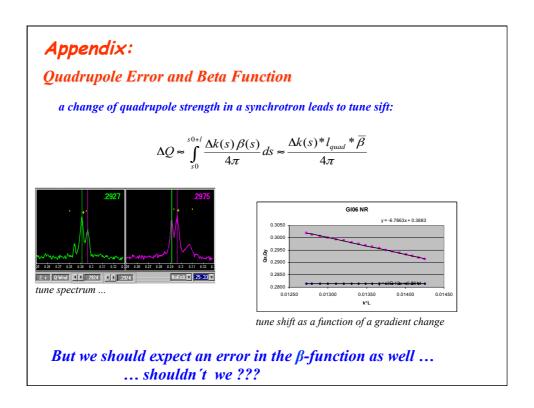


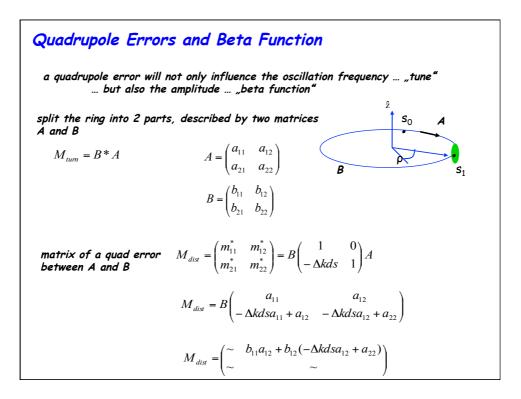






Resume':	
quadrupole error: tune shift	$\Delta \boldsymbol{Q} \approx \int_{s_0}^{s_0+l} \frac{\Delta \boldsymbol{k}(s) \boldsymbol{\beta}(s)}{4\boldsymbol{\pi}} ds \approx \frac{\Delta \boldsymbol{k}(s) \boldsymbol{l}_{quad} \boldsymbol{\overline{\beta}}}{4\boldsymbol{\pi}}$
beta beat	$\Delta \boldsymbol{\beta}(s_0) = \frac{\boldsymbol{\beta}_0}{2\sin 2\pi \boldsymbol{Q}} \int_{s_1}^{s_1+l} \boldsymbol{\beta}(s_1) \Delta k \cos(2(\boldsymbol{\psi}_{s_1} - \boldsymbol{\psi}_{s_0}) - 2\pi \boldsymbol{Q}) ds$
chromaticity	$\Delta Q = Q' \frac{\Delta p}{p}$
	$Q' = -\frac{1}{4\pi} \oint k(s) \beta(s) ds$
momentum compaction	$\frac{\delta l_{\varepsilon}}{L} = \alpha_p \frac{\Delta p}{p}$
	$\boldsymbol{\alpha}_{p} \approx \frac{2\boldsymbol{\pi}}{L} \langle \boldsymbol{D} \rangle \approx \frac{\langle \boldsymbol{D} \rangle}{R}$
beta function in a symmateric drift	$\beta(s) = \beta_0 + \frac{s^2}{\beta_0}$





the beta function is usually obtained via the matrix element "m12", which is in Twiss form for the undistorted case

$$m_{12} = \beta_0 \sin 2\pi Q$$

and including the error:

$$m_{12}^{*} = b_{11}a_{12} + b_{12}a_{22} - b_{12}a_{12}\Delta kds$$
$$m_{12} = \beta_{0}\sin 2\pi Q$$
(1)
$$m_{12}^{*} = \beta_{0}\sin 2\pi Q - a_{12}b_{12}\Delta kds$$

As M^* is still a matrix for one complete turn we still can express the element m_{12} in twiss form:

(2)
$$m_{12}^* = (\beta_0 + d\beta) * \sin 2\pi (Q + dQ)$$

Equalising (1) and (2) and assuming a small error

$$\beta_0 \sin 2\pi Q - a_{12} b_{12} \Delta k ds = (\beta_0 + d\beta)^* \sin 2\pi (Q + dQ)$$

$$\beta_0 \sin 2\pi Q - a_{12} b_{12} \Delta k ds = (\beta_0 + d\beta)^* \sin 2\pi Q \cos 2\pi dQ + \cos 2\pi Q \sin 2\pi dQ$$

$$\approx 1 \qquad \approx 2\pi dQ$$

$$\beta_{0} \sin 2\pi Q - a_{12}b_{12}\Delta k ds = \beta_{0} \sin 2\pi Q + \beta_{0} 2\pi dQ \cos 2\pi Q + d\beta_{0} \sin 2\pi Q + d\beta_{0} 2\pi dQ \cos 2\pi Q$$
ignoring second order terms
$$-a_{12}b_{12}\Delta k ds = \beta_{0} 2\pi dQ \cos 2\pi Q + d\beta_{0} \sin 2\pi Q$$
remember: tune shift dQ due to quadrupole error:
$$dQ = \frac{\Delta k \beta_{1} ds}{4\pi}$$

$$-a_{12}b_{12}\Delta k ds = \frac{\beta_{0}\Delta k \beta_{1} ds}{2} \cos 2\pi Q + d\beta_{0} \sin 2\pi Q$$
solve for dβ
$$d\beta_{0} = \frac{-1}{2\sin 2\pi Q} \{2a_{12}b_{12} + \beta_{0}\beta_{1} \cos 2\pi Q\}\Delta k ds$$
express the matrix elements a_{12} , b_{12} in Twiss form
$$M = \begin{pmatrix} \sqrt{\frac{\beta_{s}}{\beta_{0}}} (\cos \psi_{s} + a_{0} \sin \psi_{s}) & \sqrt{\beta_{s}\beta_{0}} \sin \psi_{s} \\ (\alpha_{0} - \alpha_{s}) \cos \psi_{s} - (1 + \alpha_{0}\alpha_{s}) \sin \psi_{s} \\ \sqrt{\beta_{s}\beta_{0}} & \sqrt{\frac{\beta_{0}}{\beta_{s}}} (\cos \psi_{s} - \alpha_{s} \sin \psi_{s}) \end{pmatrix}$$

