PAUL SCHERRER INSTITUT



Thomas Schmidt :: Paul Scherrer Institut

Apple-X undulator for SwissFEL Athos and EU-XFEL (SASE 3)

8th Hard X-ray FEL Collaboration Meeting



SwissFEL Ethos 250eV - 1900eV @ 3 +- 0.25 GeV for Kz, Kx, circular APPLE type **UE38** K = 1 ... 3.5 SmCo vacuum chamber: dia 5mm Hall - probe: 3mm

EU-XFEL SASE 3 Afterburner

0.4 - 1.6nm @ 15 GeV 3.1keV - 775 eV Linear 0 - 90°, circular UE90 K = 3.6 ... 7.7 NdFeB vacuum chamber: dia 5mm Hall - probe: 3mm

Chicane:

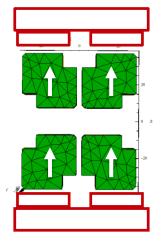
PM / Dispersion / offset

Chicane:

PM

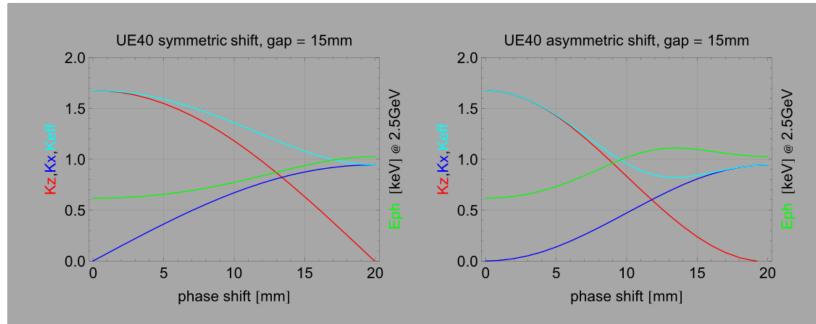


APPLE II - work horse in storage rings

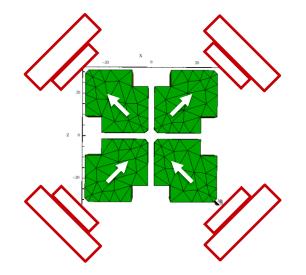


$K_z > K_circ > K_x > K_45^{\circ}$

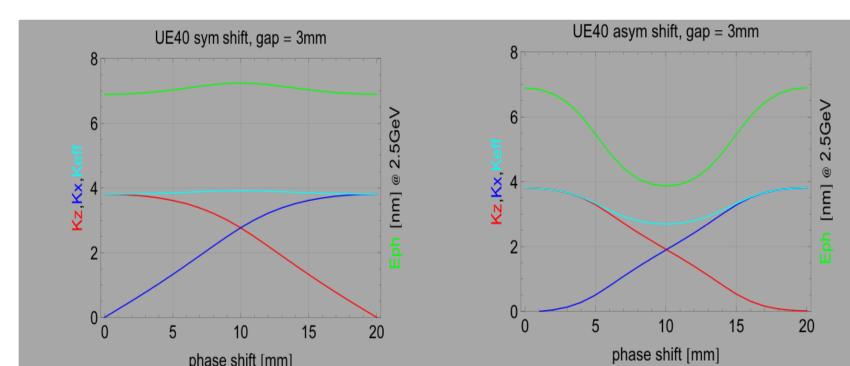
gap and shift drive, coupled



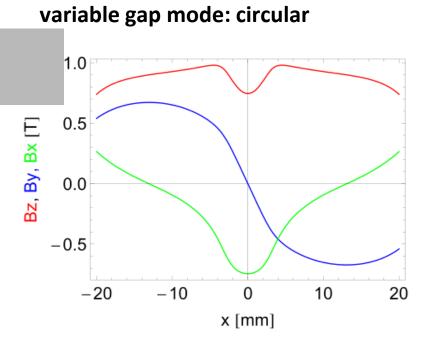




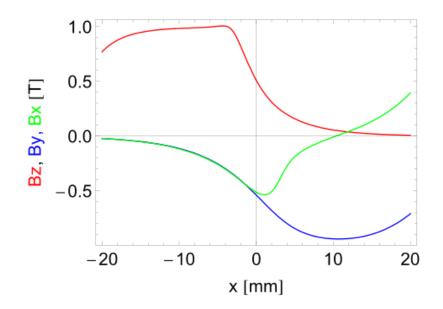
 $K_z = K_circ = K_x > K_45^{\circ}$ gap = slit for all gaps full symmetric design







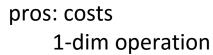
fixed gap mode: circular



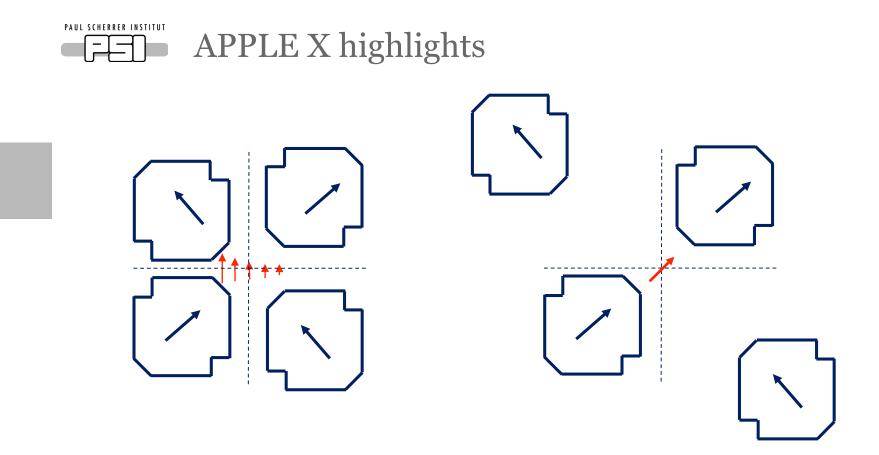
pros: good field region +- 60μm no longitudinal field on axis

cons: gap and shift dependent

benefit: adjustable linear taper with gradient and yaw angle

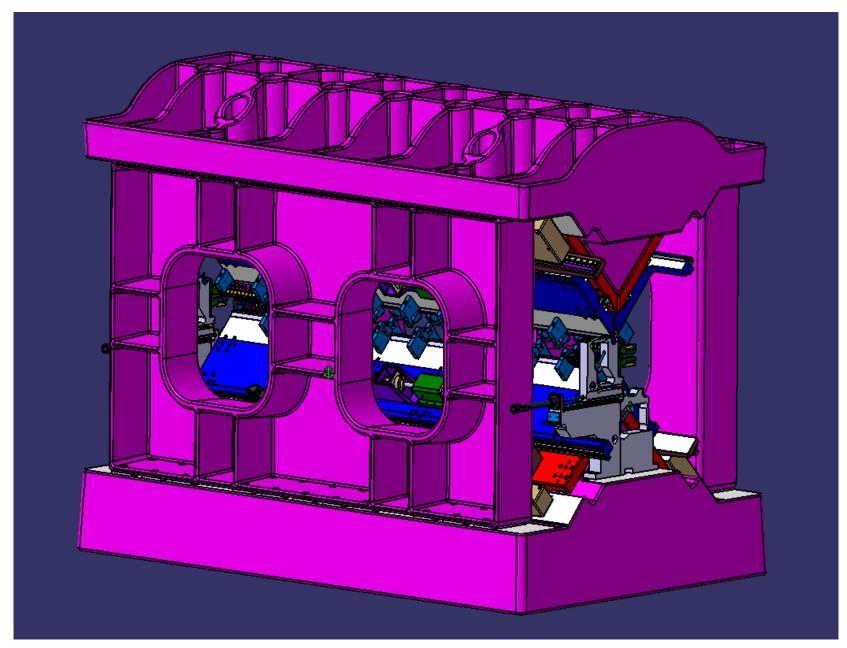


cons: strong gradients in Bz / Bx and By on axis no good field region dE/E = 1E-4: 1µm !!!

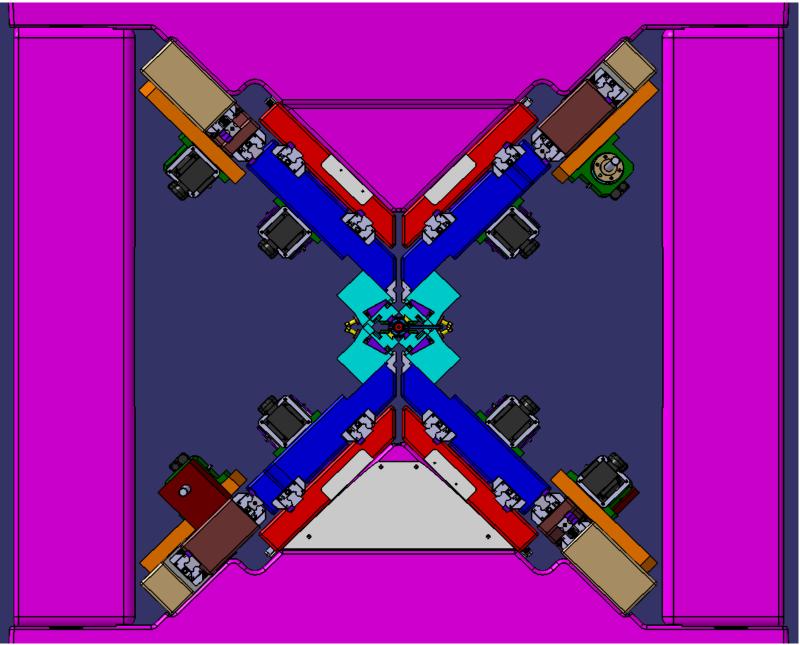


highest flexibility -> gradients for ultra high bandwith mode highest flexibility -> 45° without longitudinal forces



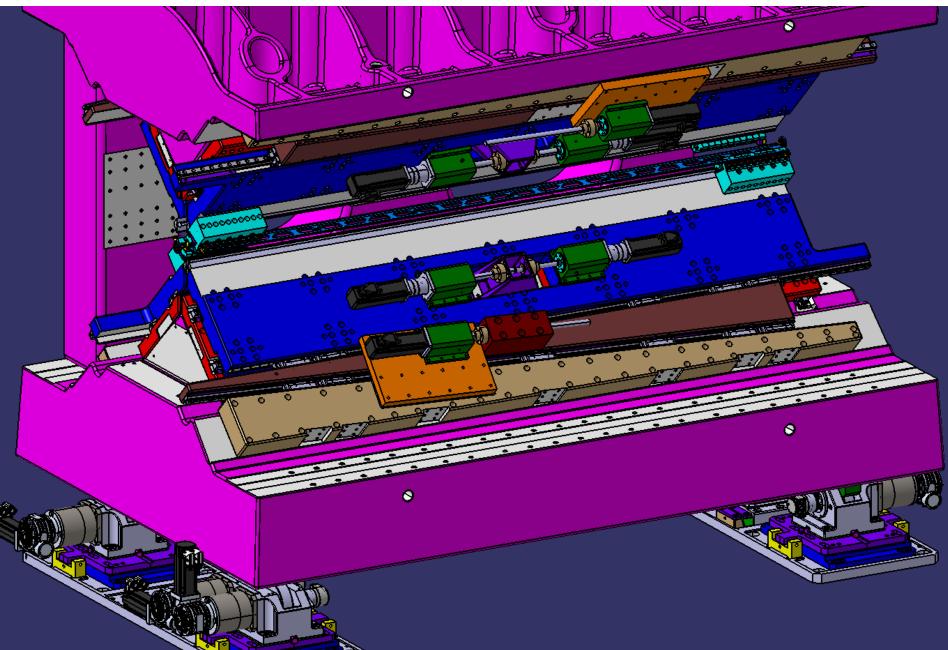






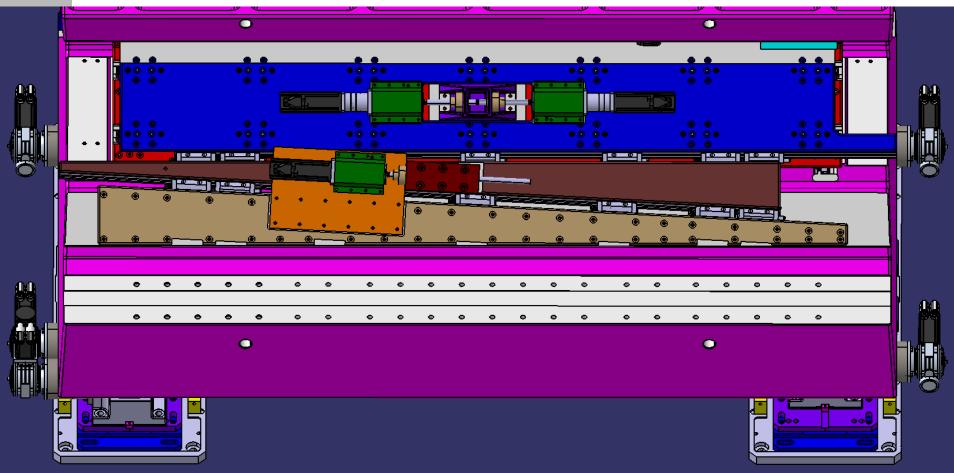


APPLE - X design study



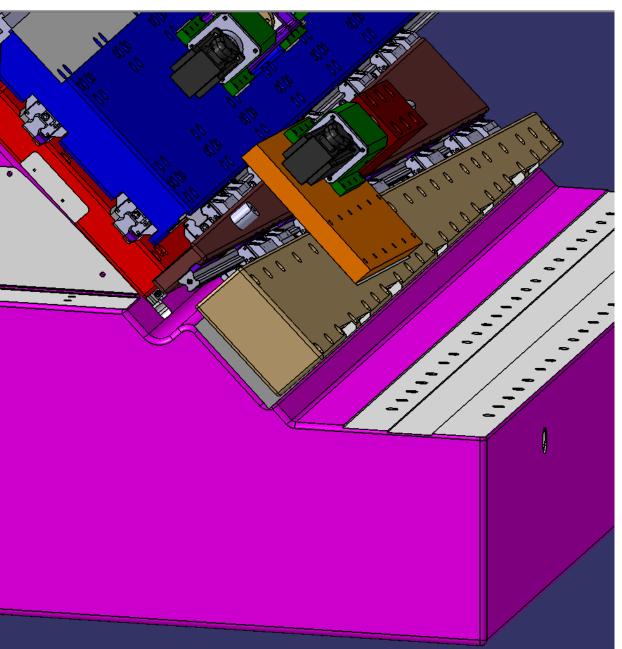


shift drive with 2 servos and satellite roller screw (<= 0.5mm pitch) position control and moment control to minimize backlash



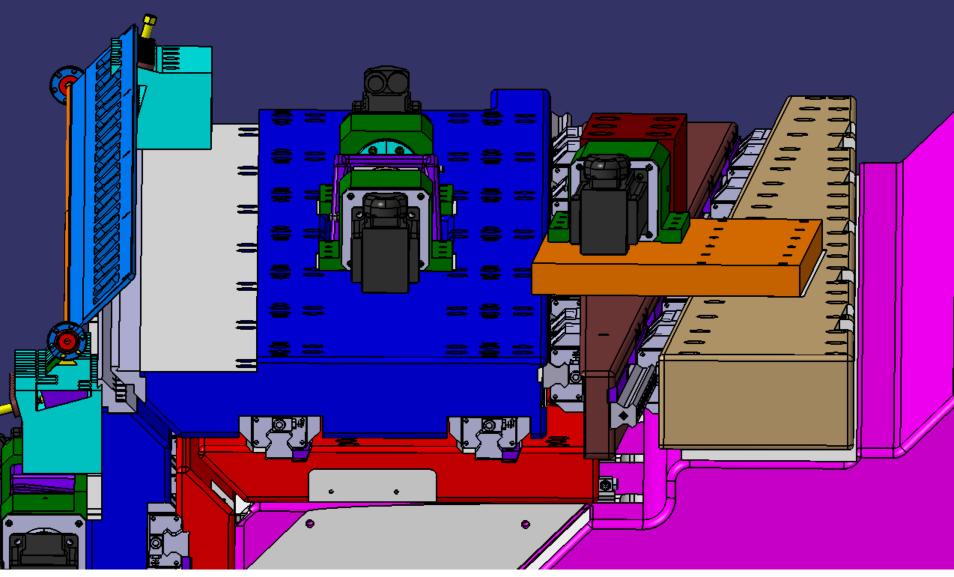
wedge based radial drive for high accuracy (< Aramis U15) servo - differential satellite roller screw - wedge: minimum backlash





support: cast iron wedges and main plates: stainless steel

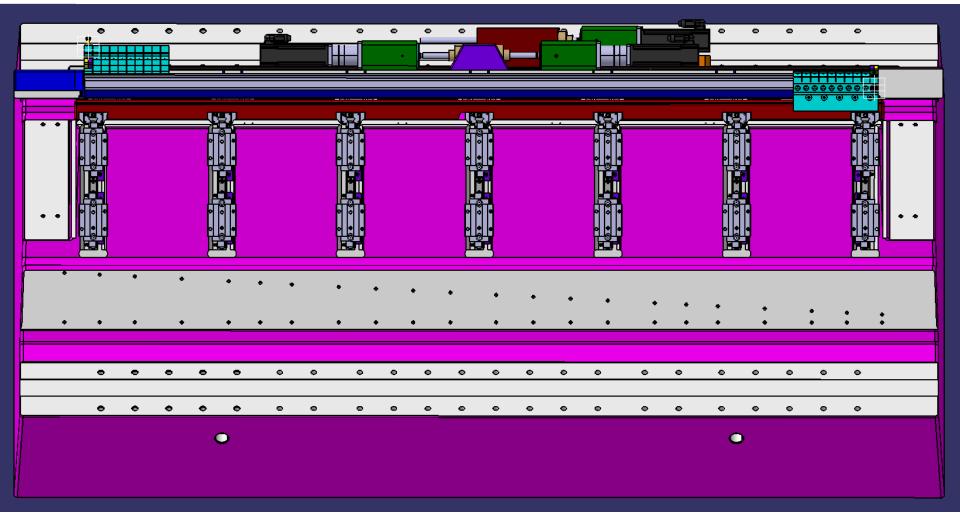




blue: shift plate, keeper interface machined after assembly red: radial plate radial bearings to support

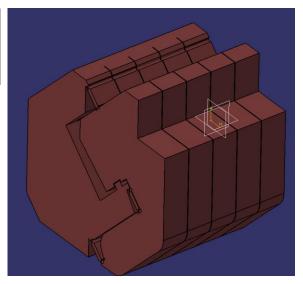


7 radial shifts located on top of support structure ribs FEM: 10 slightly better but higher friction



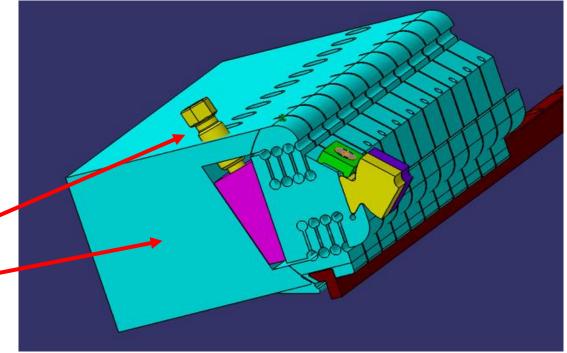


Keeper Optimization



differential screw for wedge separated preload adjustment range: +/- 60 µm Design favorite after workshop August 2015

simplified "better" design January 2016



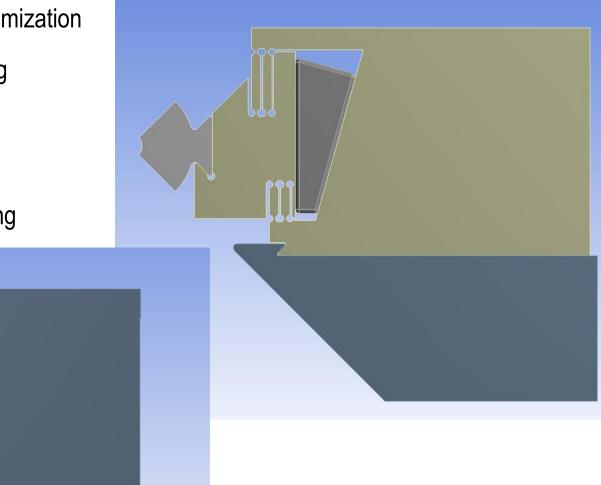


Keeper Optimization

Parametric software optimization

ANSYS / OptiSlang

Prototype already existing



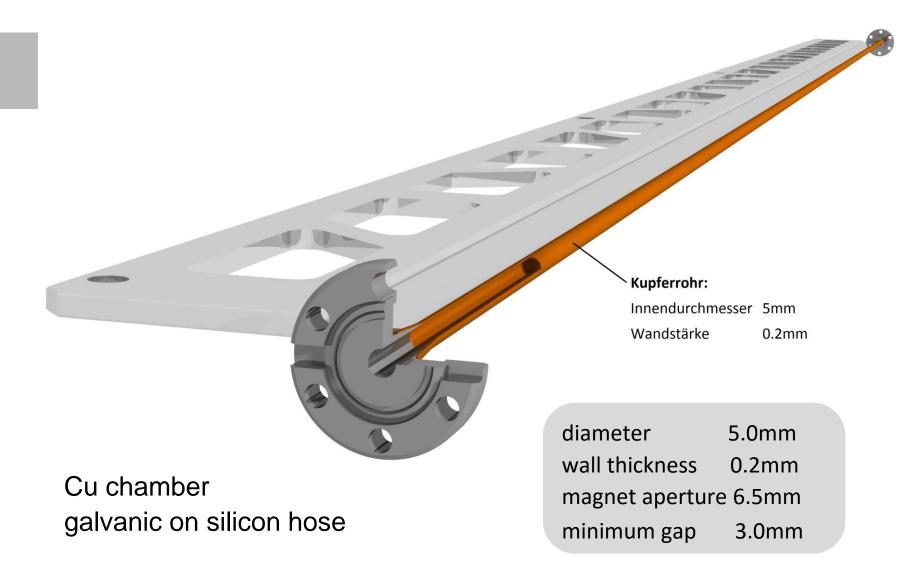


APPLE - X design study

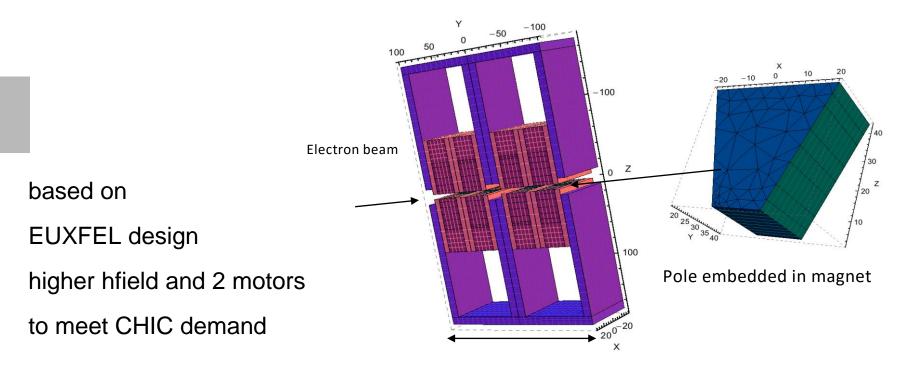


5-axis cam-shaft mover 5-axis (SLAC, PSI: SLS, SwissFEL) alignment in x and y, pitch, yaw and roll longitudinal taper with gradients and pitch for CHIC modes





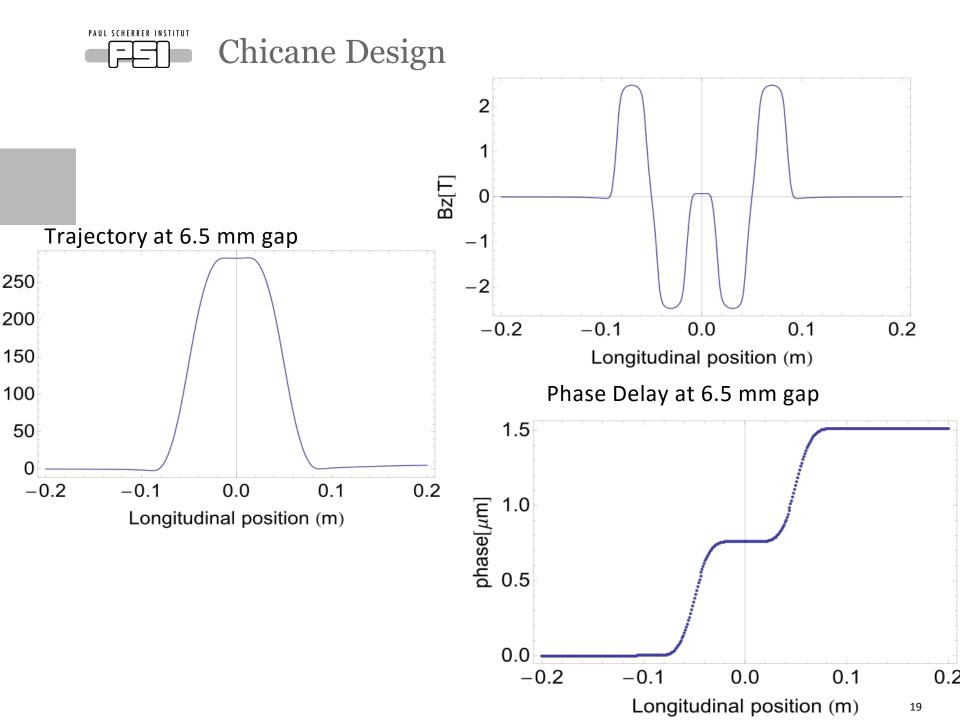




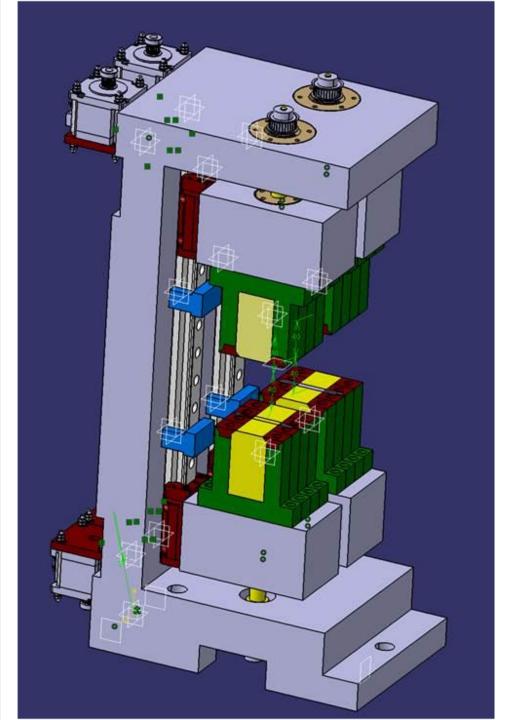
Chicane length: 200 mm Maximum delay: 5 fs (1.5 um) Maximum hor. shift: 280 µm

and you know Phase shifter for EUXFel

is Optical klystron for SwissFEL



PAUL SCHERRER INSTITUT





Concluding Remarks

APPLE X / DELTA II

is a strong design

dedicated to single pass machines

PSI undulator design to be used for EUXFEL EUXFEL Chicane design used by PSI with 4 motors

LCLS DELTA II design more compact but limited access PSI APPLE X allows use of automated optimization

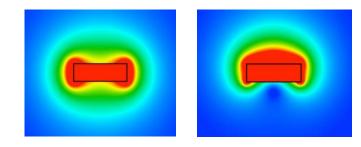


thanks for listening





UE38 Magnet Design



shaped field design ٠ with local manufacturer Arnold Magnetics supported by CTI

inhomogenious magnetization to concentrate on axis flux

works for Sm2Co17	
to be extended for SmCo5	

	remanence	permeability
SmCo5	0.95 T	1.01 / 1.04
Sm2Co17	1.1 T	1.06 / 1,15

field integral changes	
due to shift	
up to 4 x reduced	

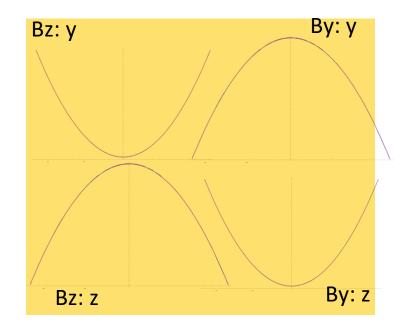
	SmCo5		SmCo17		
LH	0	0	0	0	Gcm
C+	-0,824	7,16	0,89	29	
C-	0,824	-7,16	-0,88	-29	
LV circ	4,68	18	74,3	20,4	
LV lin	0	0	0	0	
45°	0	0	0	0	

+ 5% field - 30% forces



Tolerance Studies

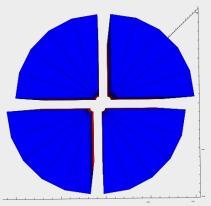
good field re mode LH	egion shar y-dir +- 47	bed field: z-dir +- 52	
circ	+- 45	+- 60	1*10 -4
	+- 78	+- 78	3*10-4
	+- 101	+- 135	5*10-4
good field s	tandard m	agnets:	
circ	+- 47	+- 67	
	+- 80	+- 116	



assembly error by 0.1mm upper vs lower half:

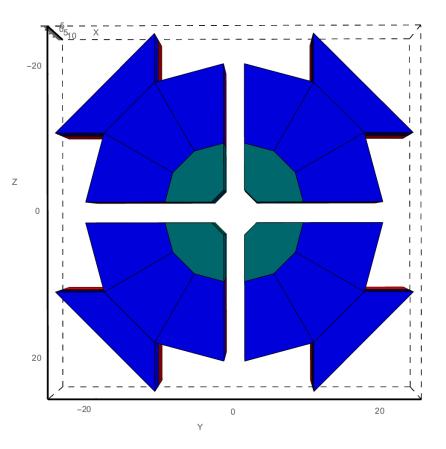
+- 104 +- 150

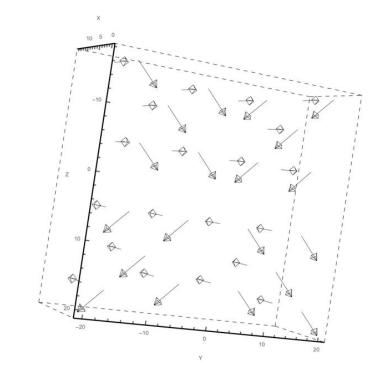
center moves by 0.05 Δ Kz/Kz = 1.9 10⁻⁴ Δ Ky/Ky = 7 10⁻⁶





• n = 1



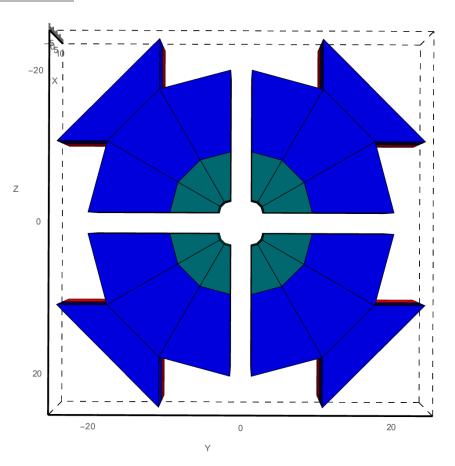


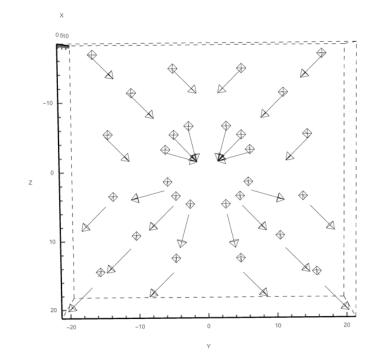
25



Radia Model

• n = 3

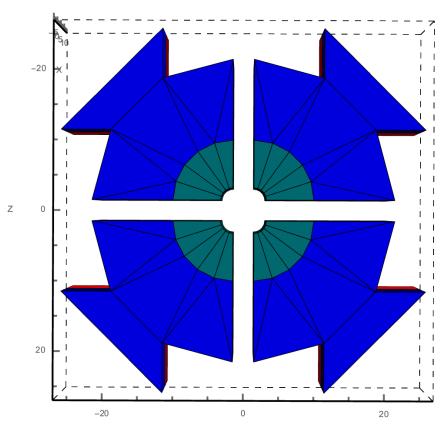


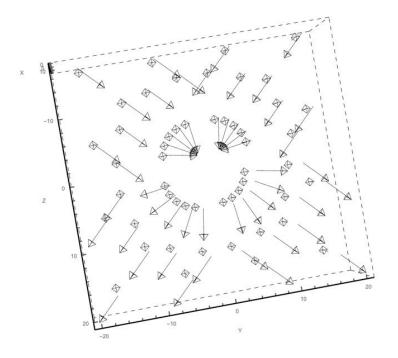




Radia Model

• n = 5



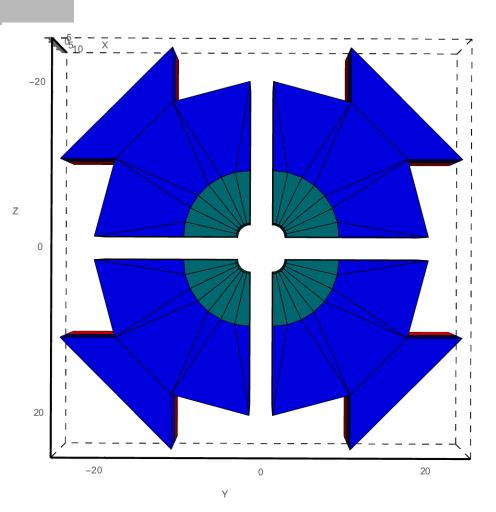


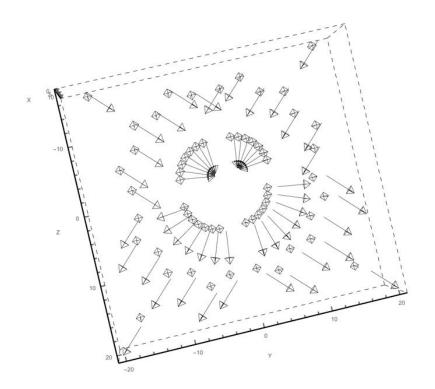
Υ



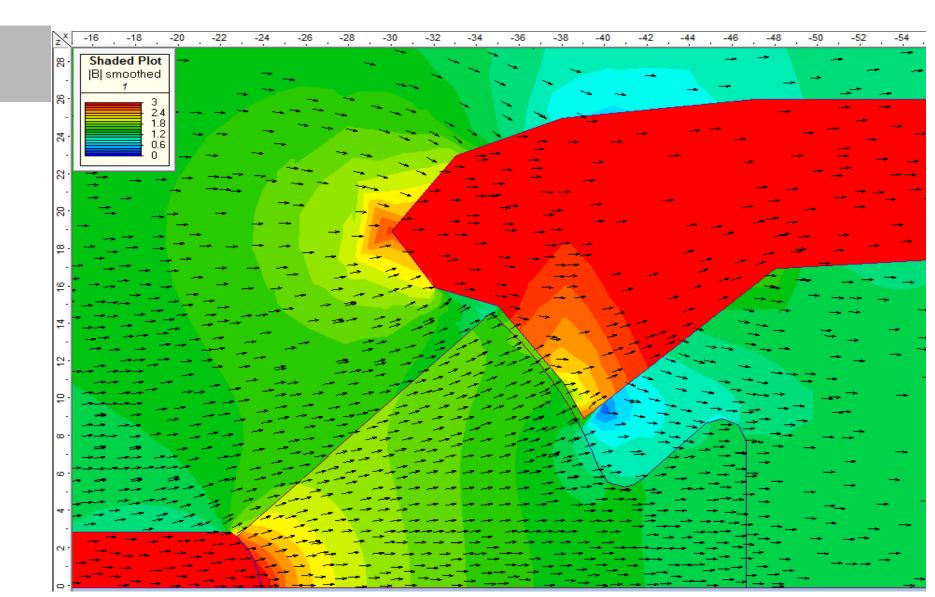
Radia Model

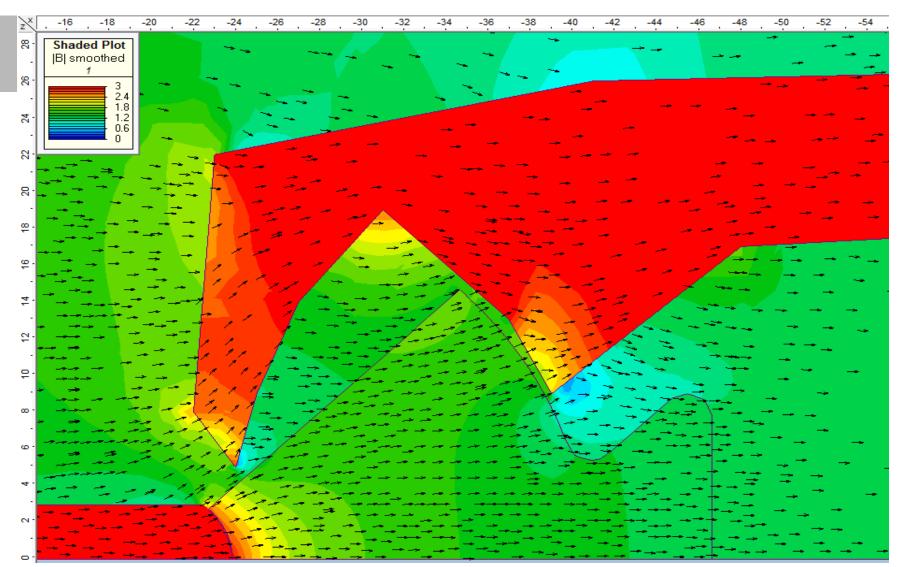
• n = 5





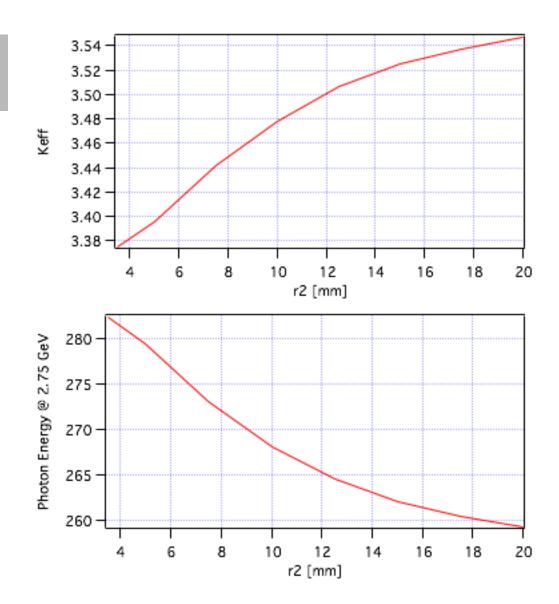








shaped field: effectivity



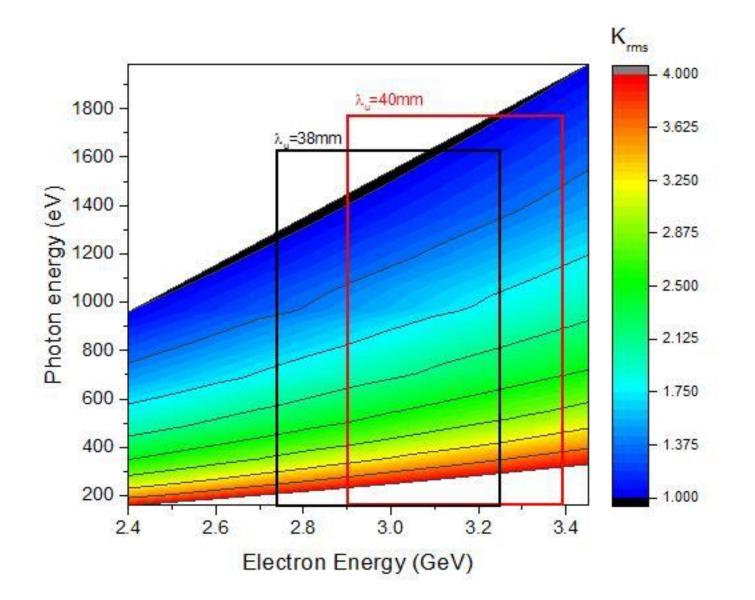
UE38 SmCo5 r1 = 3.25 r3 = 21.5 slit = 3 radial segments: 5 r2 is the radius up to

which the angle change works

total increase:



Athos extraction energy





- full symmetric mode
- •
- design for SwissFEL and EUXFEL
- use of EUXFEL phase shifter design
- but with 2 motors allows all flexibility needed for CHIC modes
- Chicanes for high power and improved coherence
- gradient field scheme (important for that is the mover concept
 - (SLAC, PSI, ..)
- because of small vacuum chamber technology this can be brought also in hard x-ray wall thickness 160mu galvanic copper (surface roughness?) check in old FLAC meeting
- again: gradients to be handled but not the baseline
- maximum tilt angles required reasonable length of bellows as vacuum chamber is supported by the undulatory



what's next Athos?

20	016			201			2018							20)19					2020																																																																																						
de	design & prototype							ototype series production																																																																																																						
			procurement																	E																																																																																										
			design & procurement										commissioning						pilot experiments		r operation																																																																																									
		Dog	Dogleg						Dogleg						Dogleg					Dogleg						Dogleg						Dogleg						Dogleg					ogleg					ogleg				ogleg				Dogleg				Dogleg				Dogleg				ogleg				dogleg commissioning				ng	RF stations, undulator line, photon beamline, experiments																	nse																
			Cabling, cooling stations, building																																																																																																											
		2016 design & protot	design & prototype		design & prototype	design & prototype	design & prototype procur	design & prototype procureme desig	design & prototype procurement design & Dogleg com	design & prototype procurement design & prototype design & prototype design & pro design & pro design & pro dogle commissi	design & prototype procurement design & procure design & procure design & procure design & procur design & procur	design & prototype seri procurement design & procurement design & procurement design & procurement	design & prototype series procurement design & procurement design & procurement	design & prototype series prototype seri	design & prototype series production of the se	design & prototype series production procurement design & procurement Dogleg RF stations photon beam	design & prototype series production procurement design & procurement design & procurement design & procurement	design & prototype series production procurement design & procurement Dogleg RF stations, undulated photon beamline, expressioning	design & prototype series production procurement design & procurement Dogleg RF stations, undulator photon beamline, experi	design & prototype series production procurement design & procurement design & procurement design & procurement	design & prototype series production procurement design & procurement Dogleg dogleg commissioning	design & prototype series production procurement design & procurement Dogleg RF stations, undulator line, photon beamline, experiments	design & prototype series production procurement design & procurement design & procurement co Dogleg RF stations, undulator line, photon beamline, experiments	design & prototype series production procurement design & procurement design & procurement commissioning Dogleg dogleg commissioning RF stations, undulator line, photon beamline, experiments	design & prototype series production procurement design & procurement design & procurement commissioning Dogleg RF stations, undulator line, photon beamline, experiments	design & prototype series production procurement design & procurement design & procurement commissioning Dogleg RF stations, undulator line, photon beamline, experiments	design & prototype series production procurement design & procurement design & procurement commissioning Dogleg dogleg commissioning RF stations, undulator line, photon beamline, experiments	design & prototype series production procurement design & procurement design & procurement commissioning Dogleg dogleg commissioning RF stations, undulator line, photon beamline, experiments	design & prototype series production procurement design & procurement design & procurement Dogleg dogleg commissioning RF stations, undulator line, photon beamline, experiments	design & prototype series production procurement design & procurement design & procurement Dogleg dogleg commissioning RF stations, undulator line, photon beamline, experiments	design & prototype series production procurement design & procurement design & procurement Dogleg dogleg commissioning RF stations, undulator line, photon beamline, experiments	design & prototype series production procurement grocurement design & procurement commissioning Dogleg dogleg commissioning RF stations, undulator line, photon beamline, experiments																																																																														

calculations done till mid of September:

Review (best with LCLS team, ...) LCLS: APPLE X with alternative concept drawings: end of the year prototype manufacturing: Jan – June 2016 (Daetwlyer) parallel magnet fabrication (Arnold) parallel construction of modified measurement bench undulator field measurements summer 2017 ready for series production end Q3 2017