

Real-Time Redundancy for the 1.3 GHz Master Oscillator of the European-XFEL

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Introduction

- European XFEL
 - DESY
 - Hamburg, Germany
 - Over 3.4 km long facility
 - Stringent requirements for reference signal
 - Femtosecond short- and long-term stability
- Complex synchronisation system
 - 1.3 GHz master oscillator
 - RF/optical reference distribution system

Motivation

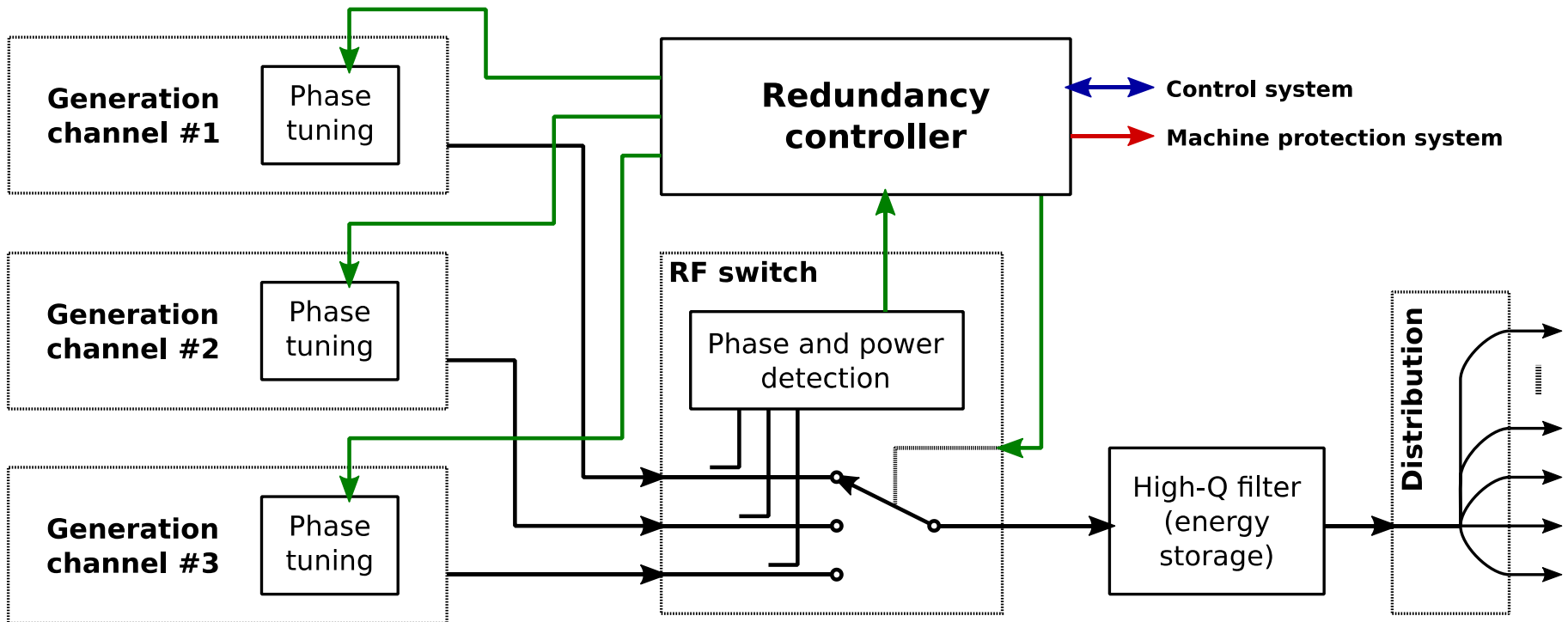
- Reference signal usage
 - Generation of derived frequency signals
 - Eg. LO or ADC clock signals
 - PLL and frequency dividers
 - Well defined time relations
- Reference signal disturbances
 - Cycle-slips
 - Time relations change
 - New set-points required

Motivation

- Reference disturbances vs accelerator availability
 - Disturbances: ns– μ s
 - Accelerator: potentially hours
- Performance vs reliability
 - Stringent performance requirements
 - Reduced choice of components and solutions
 - Failures were observed
 - In previous systems
 - During development
- Existing solution – hot spare
 - Switching after failure

System concept

- Generation channels
- Redundancy module



Failure detection

- Issue
 - Disturbances of phase and/or amplitude
- Detection
 - Monitoring of phase and amplitude
 - All *important* failures detectable
- „*Unimportant*“ failure
 - Phase noise degradation
 - No immediate action needed

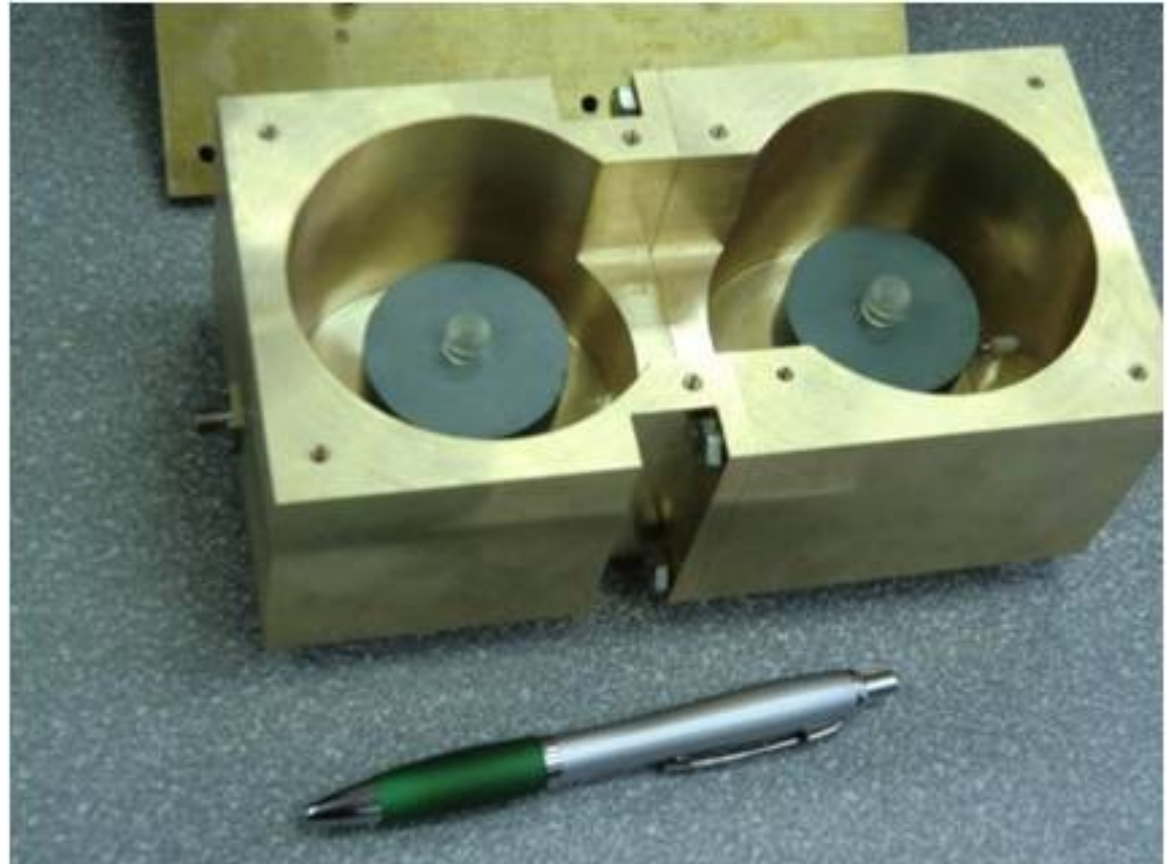
Maintaining signal continuity

- Energy storage in high-Q filter
- Switching between generation channels
 - 40 dBm signals
 - Within tens of ns
- Phase alignment
 - Closed loop synchronisation
 - Integrating controller
 - Vector modulator as phase shifter
 - Infinite shift range

Hardware – Filter

- Dual dielectric resonators
 - Q-factor $>10^4$

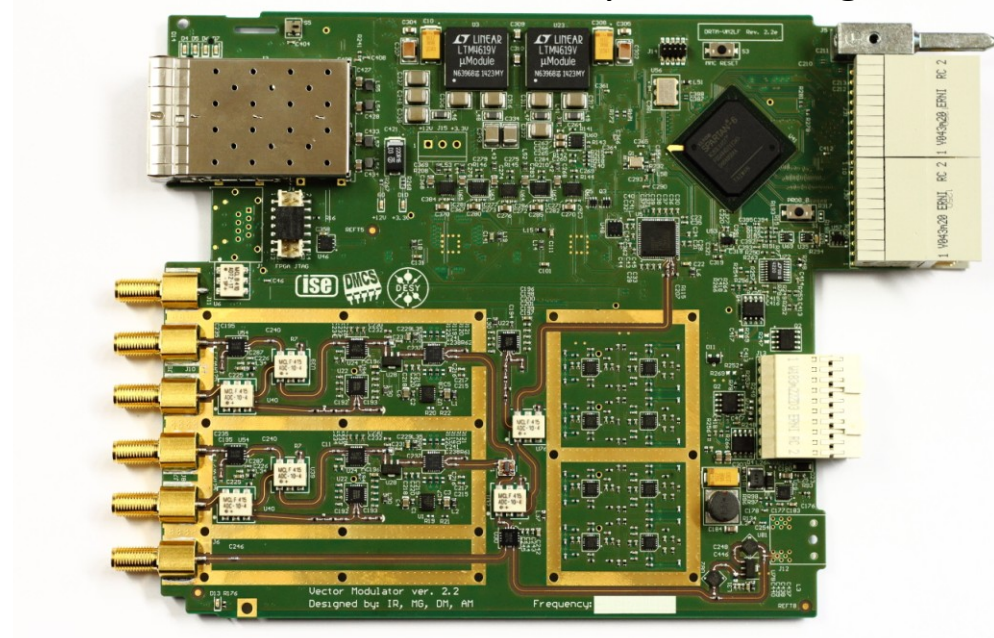
Courtesy of A. Abramowicz



Hardware – Vector Modulator

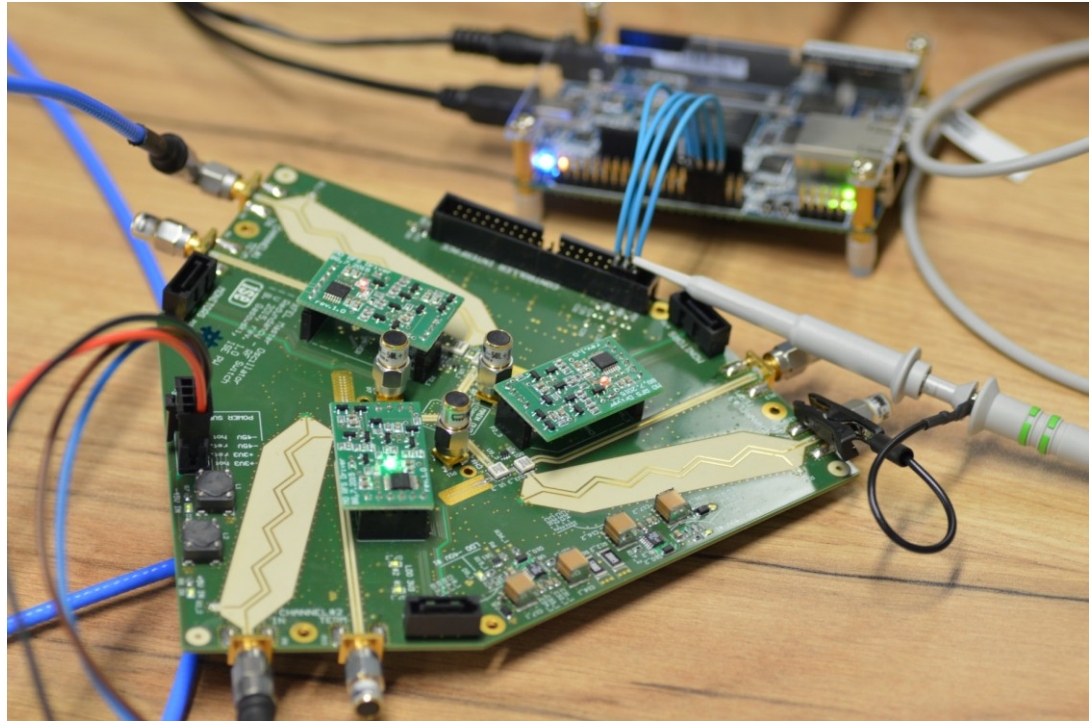
- DRTM-VM2LF
 - Used in European-XFEL LLRF
- Modified: reduced baseband bandwidth
 - Improved phase noise performance

Courtesy of M. Grzegorzka



Hardware – RF Switch Module

- Three-way RF Switch
 - +43 dBm power handling
 - < 50 ns switching latency

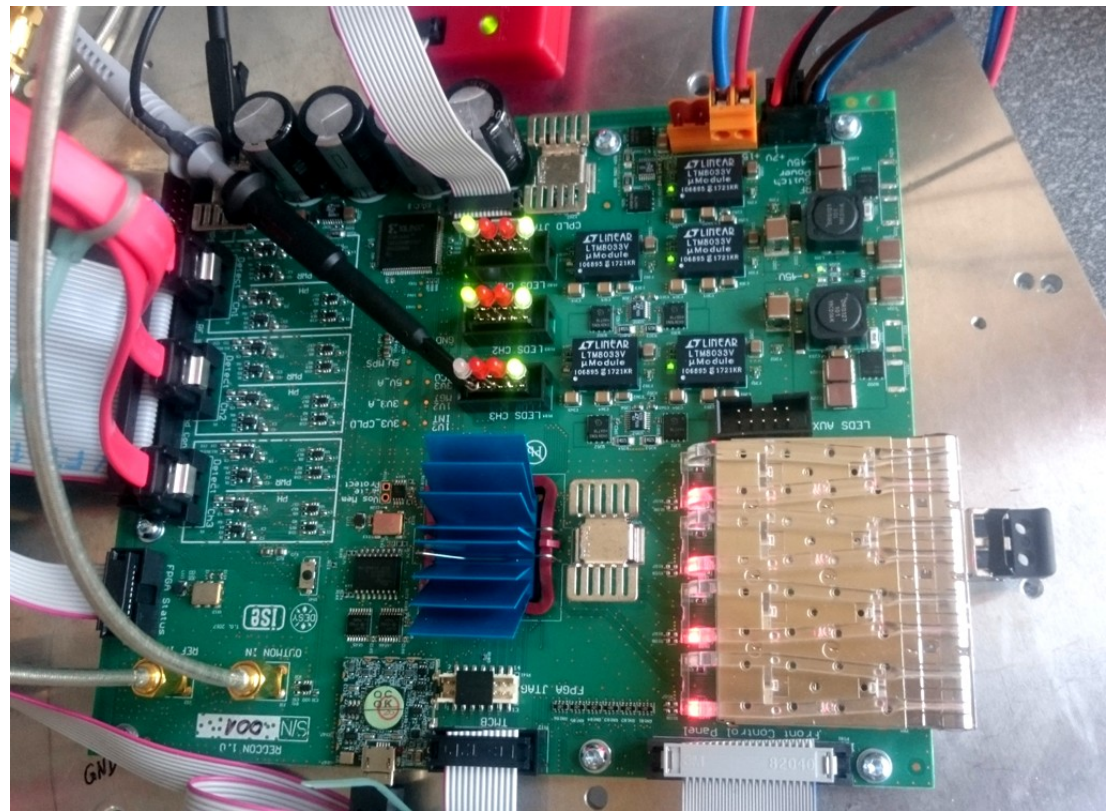


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Hardware – Redundancy Controller

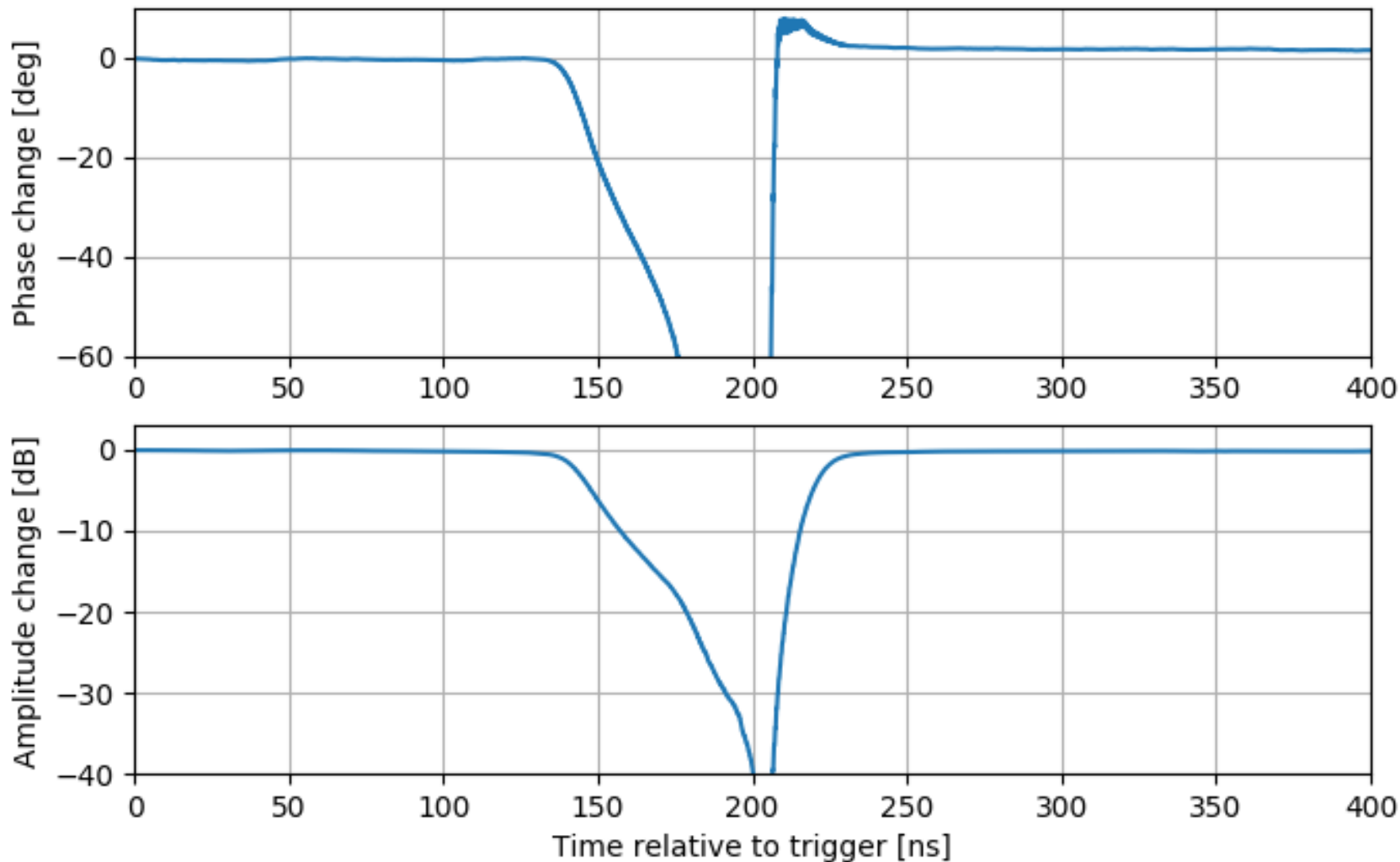
- CPLD – low-latency decision logic
 - Triple modular redundancy
- FPGA
 - Synchronisation
 - Supervision
 - Interfacing
 - Control
 - Diagnostics



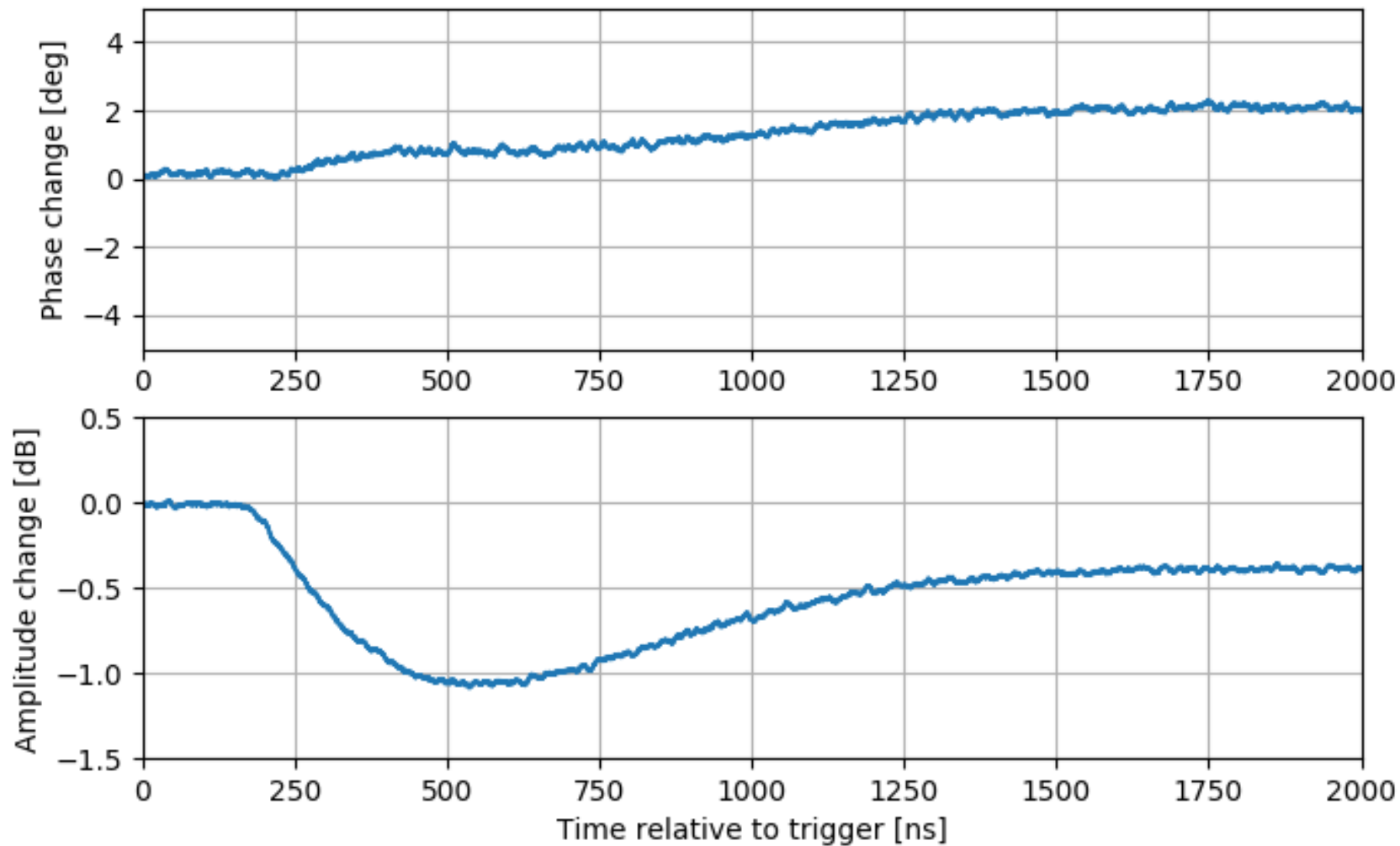
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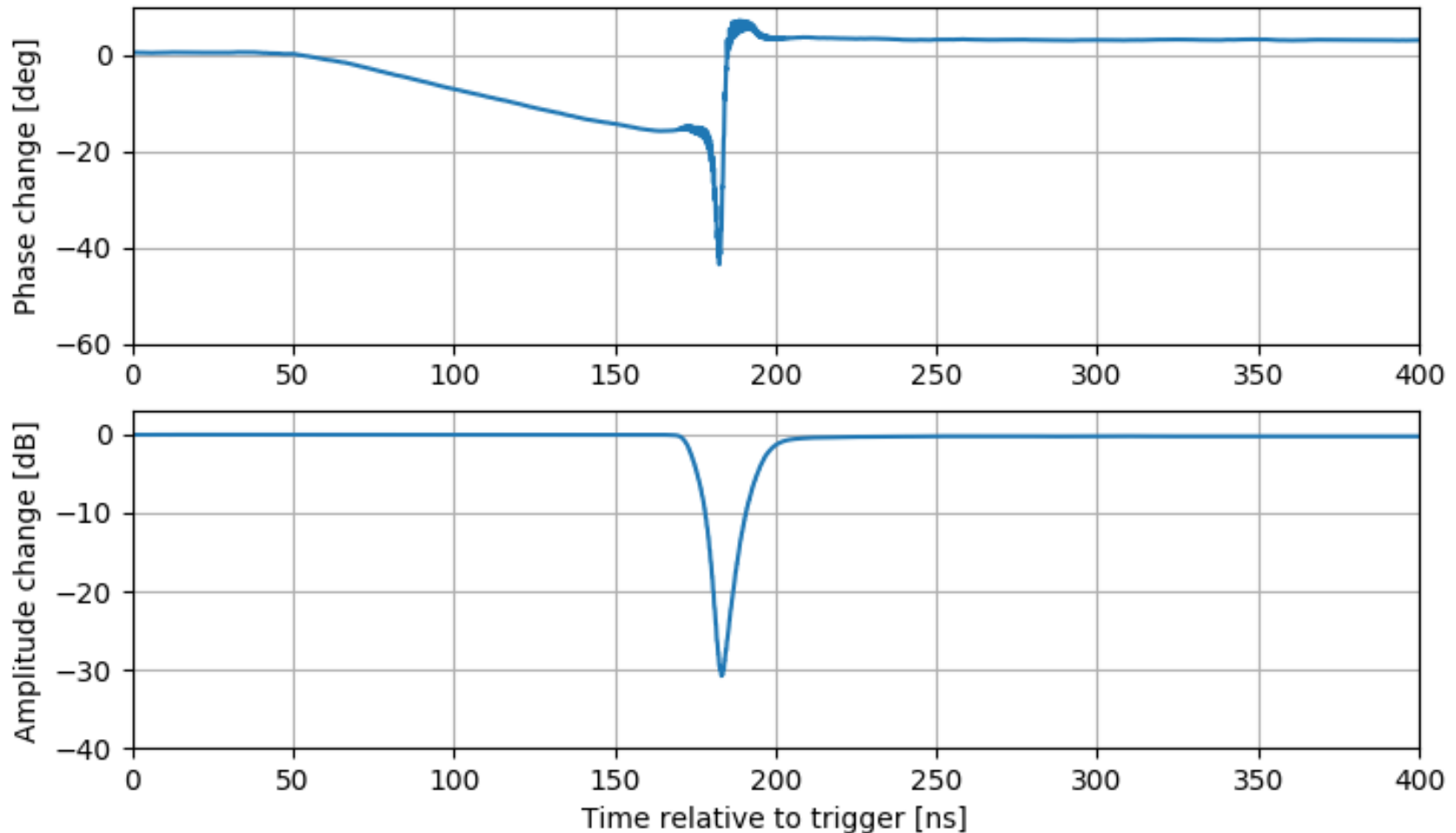
Test results – power dip (before filter)



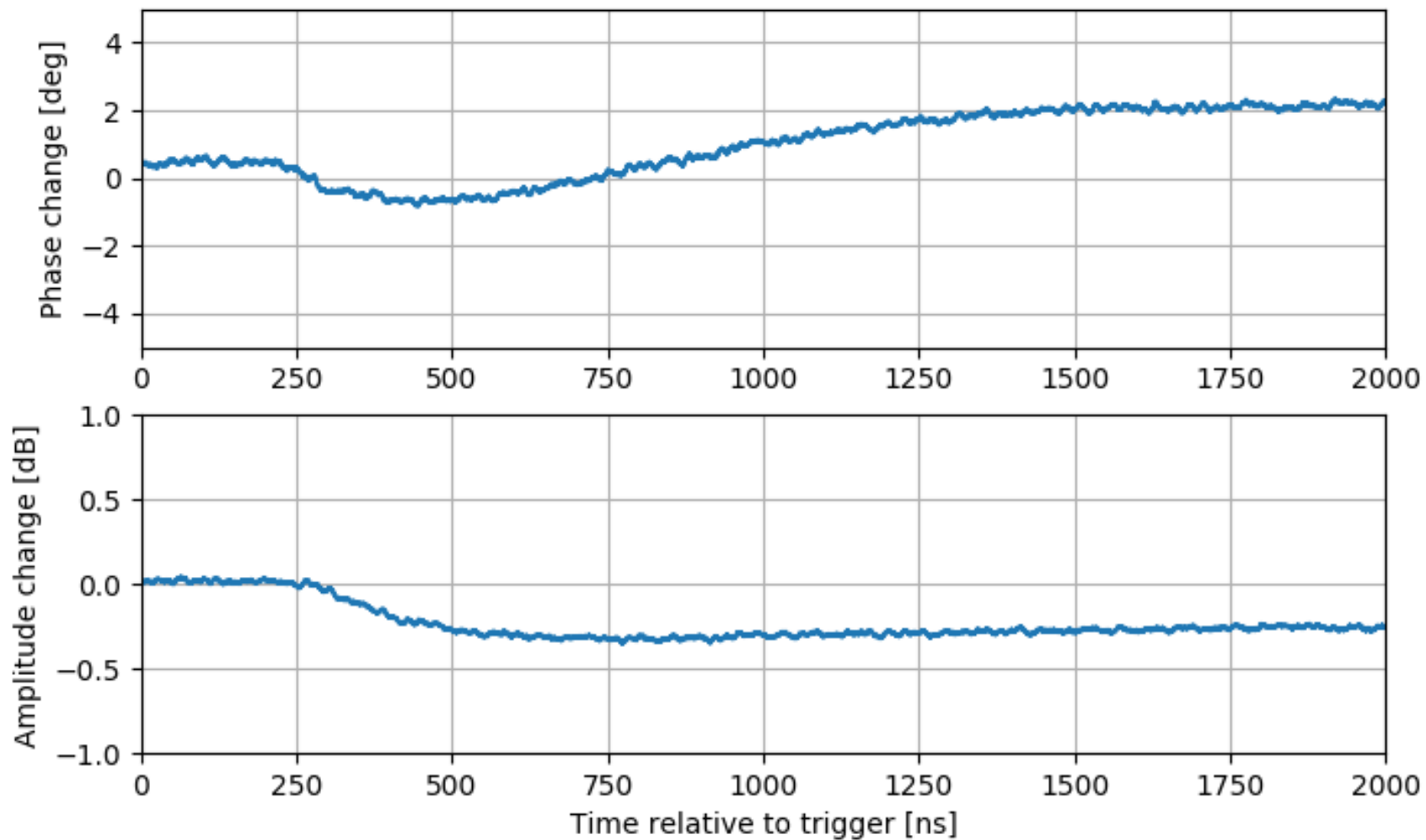
Test results – power dip (after filter)



Test results – phase change (before filter)



Test results – phase change (after filter)



Current status

- All hardware modules ready and tested
- Parts of firmware still missing
 - Synchronisation
 - Auto-calibration
- Testing in progress
 - Low-power signals
 - Manual synchronisation
 - Successful reaction to artificially induced failures

Conclusion and plans

- Successful reaction to failure proven
- Further development and tests
 - High-power signals (+41 dBm)
 - Firmware development
 - Improvement of detection accuracy

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