

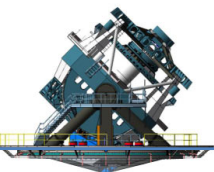


The Large Synoptic Survey Telescope Camera Data Acquisition System

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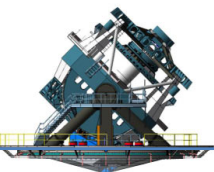


What is LSST?



- LSST is a telescope that is being built on Cerro Pachón in Chile
 - Will conduct a 10-year survey of the optical sky
 - Scheduled to begin in 2022
 - Has an 8.4m primary mirror and wide field of view
 - One image will cover 49 times the area of the full moon
 - Able to survey the southern hemisphere sky every few nights in 6 wavelength bands
 - Data will be archived at NCSA and made publicly available along with tools to access and study it
 - The final image collection will be 0.5 exabytes
 - The peak compute power in LSST data centers will be 1.8 PFLOPS
- Diverse science goals drive LSST
 - The Nature of Dark Matter and Dark Energy
 - Cataloging the Solar System (moving objects)
 - Exploring the Changing Optical Sky
 - Milky Way Structure and Formation

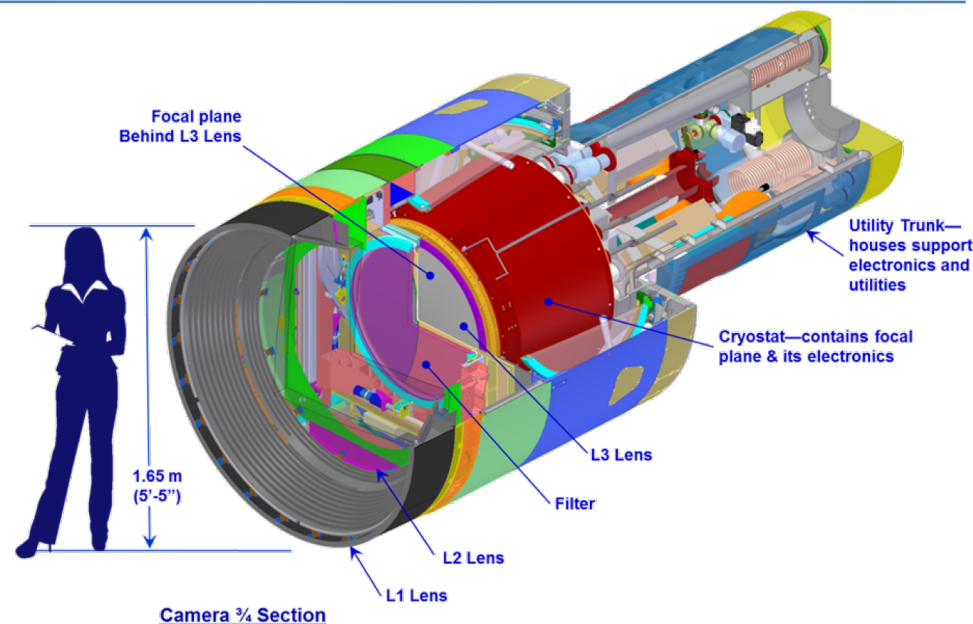




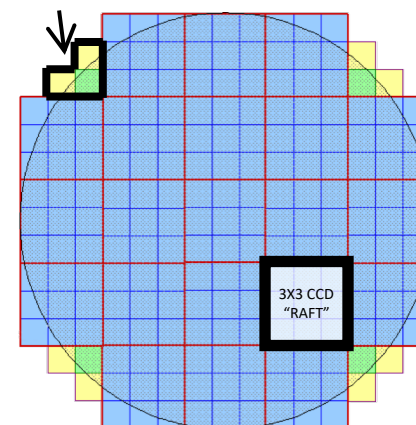
The LSST Camera



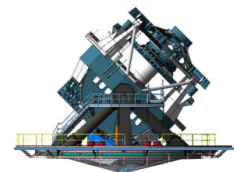
- The largest digital camera constructed for astronomy
 - 3.2 Gigapixels digitized with 18-bit accuracy
 - Each 16-megapixel sensor is read out in parallel by 16 amplifiers
 - 189 science sensors
 - 8 guide sensors
 - 4 wavefront sensors
- 3 science sensors are controlled by a Readout Electronic Board (REB)
 - Three REBs and their associated sensors form a mechanical unit called a Raft
 - There are 21 Science Rafts
- Guiding and wavefront sensors are contained in the four Corner Rafts
- Nominal cadence is 17 seconds
 - 15 second exposure
 - 2 second readout
- Project completion scheduled for mid-2020



4 Corner areas for wavefront sensing (green) and guiding (yellow).



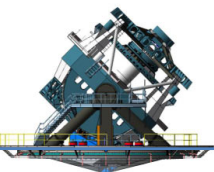
21 rafts make up the science array



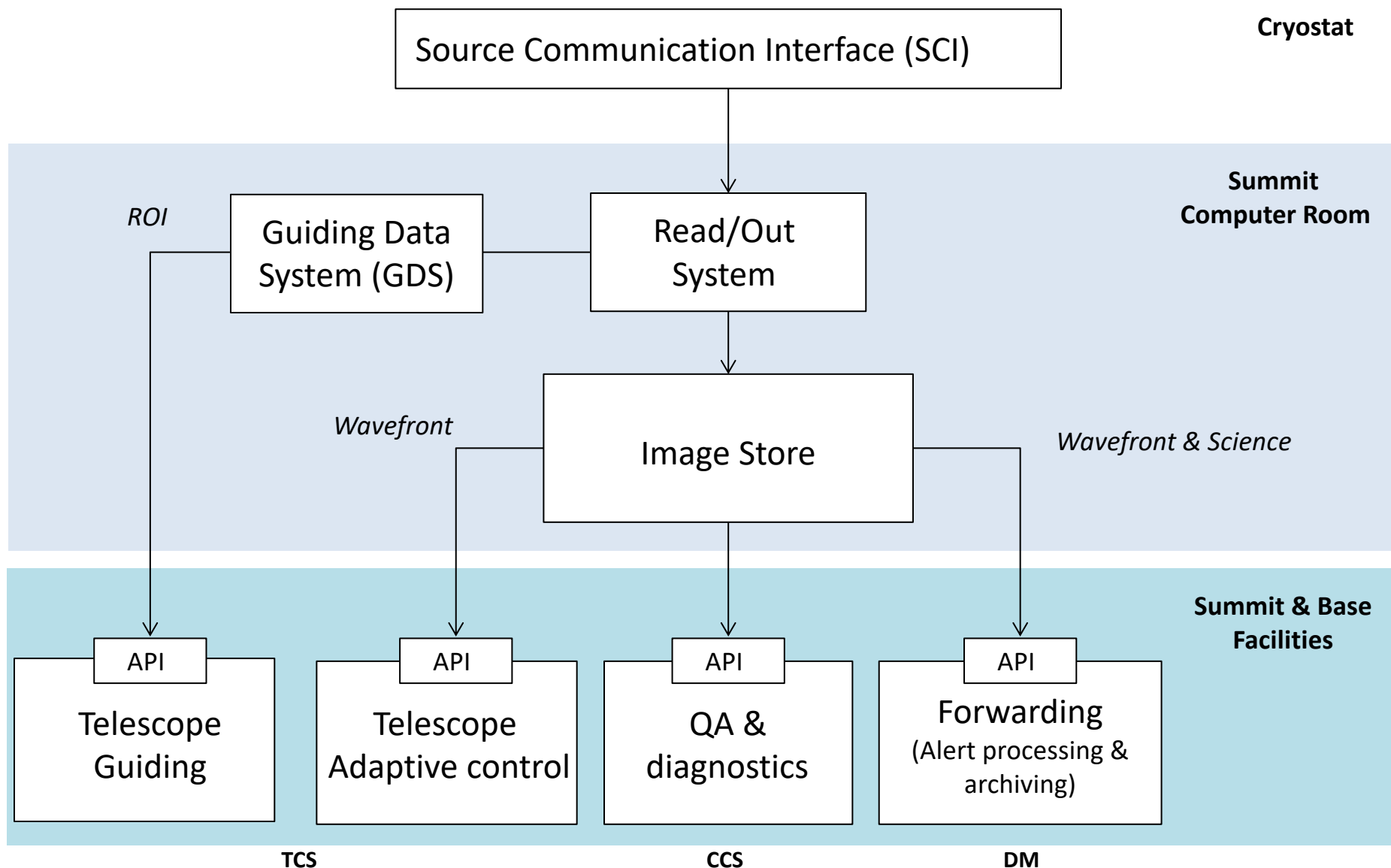
The Camera DAQ

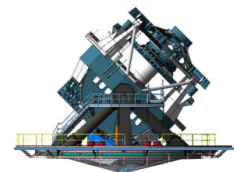


- Provides access to image data to multiple, concurrent clients at read-out rate, in “real-time”
 - Read-out rate is ~ 3.6 Gigabytes/second
- Buffers all data for up to 7 days
 - This allows continued observation from the summit in the event of communication loss
 - 2 days covers the Mean Time To Repair (MTTR) for summit/base
 - 7 days covers the MTTR for base/NCSA
- Provides cross-talk corrected data if requested
- Provides access to raft electronics for the purpose of configuration, control, and monitoring
- Provides common system clock & synchronous timing
- Provide windowed guiding data at 9 Hz



The DAQ Components and Clients

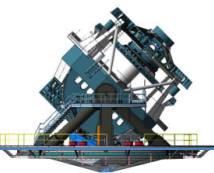




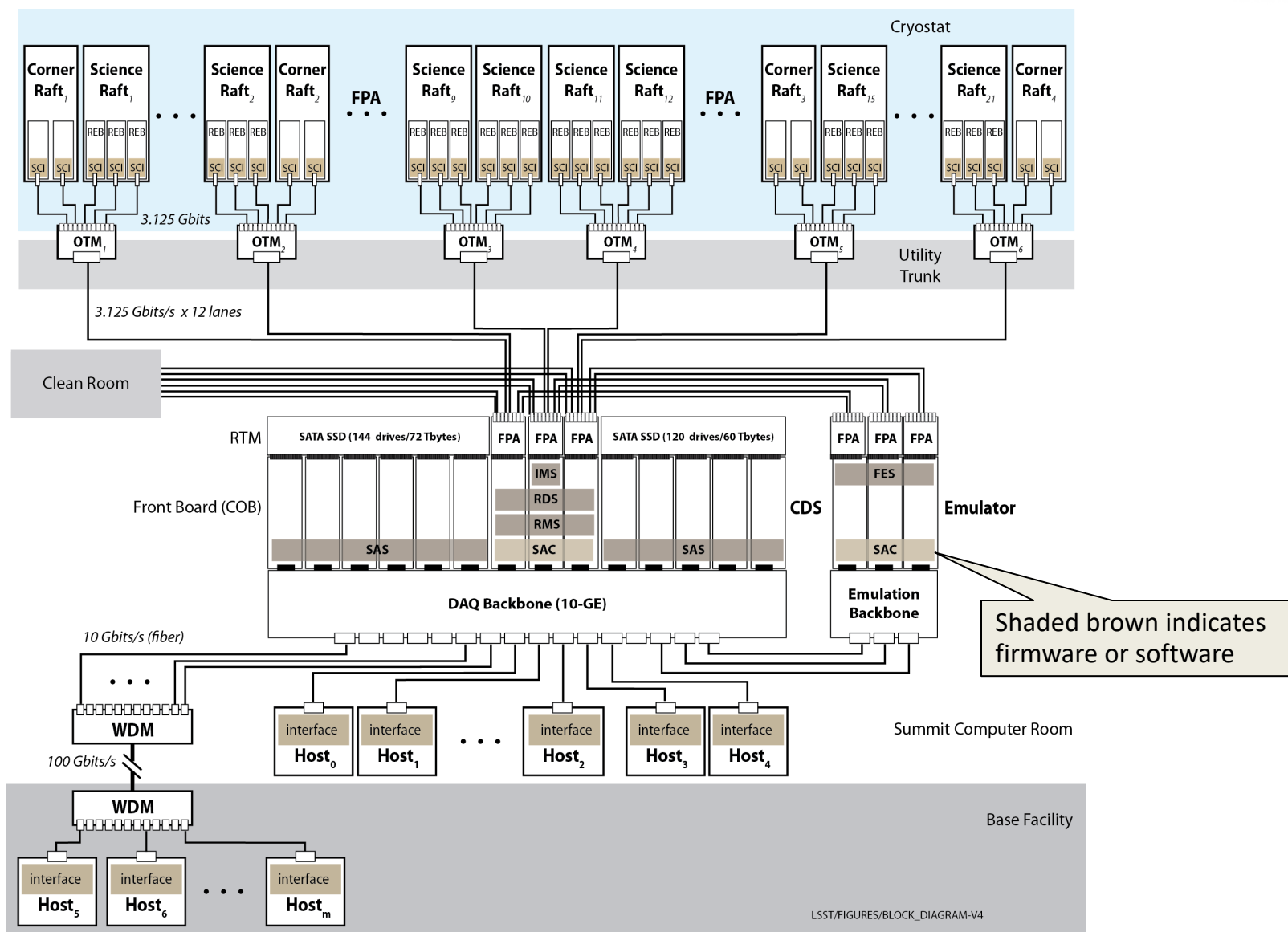
DAQ System Novelties



- “Event” size is large at 7.2 GB and rate is low at 0.06 Hz
 - And that data is almost exclusively collected at night...
- However, we must provide the data at the rate it is generated in the front end
- DAQ latency requirements are driven by the Observatory real-time alert latency of 60 seconds
 - ~10 million such alerts are expected to be generated each night
- DAQ client machines are distributed over more than 100 km
 - All clients, and indeed DAQ compute elements, are equal peers on a single 10G Ethernet
- There are 142 high speed serial links which must penetrate the cryostat in a very limited area ($6 \times \sim 8 \text{ cm}^2$) and then travel 145 meters to the summit computer room

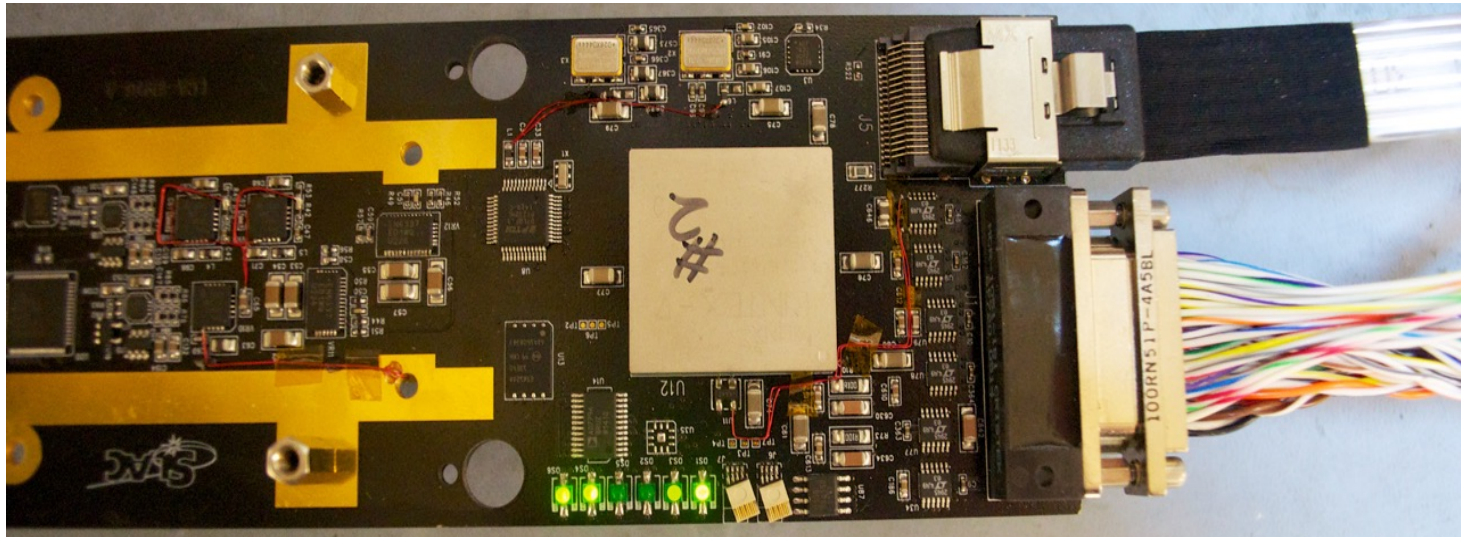


Block diagram of the DAQ System

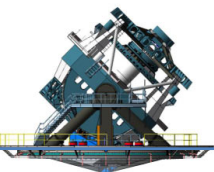




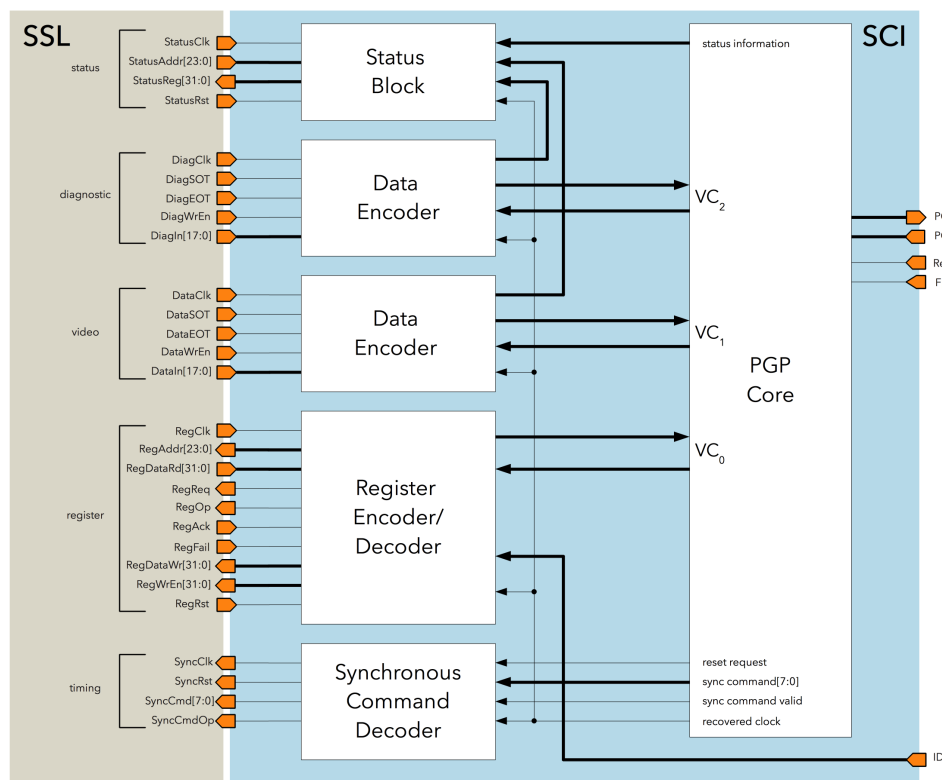
The Raft Electronics Board



- Each REB, regardless of type (Science, Guider, or Wavefront) contains an identical FPGA
- FPGA firmware is partitioned into two components separated by a controlled interface
 - The Source Communication Interface (SCI) provided by the DAQ
 - The sensor specific logic provided by the electronics group
- The DAQ specifies the Data connector and its pinout

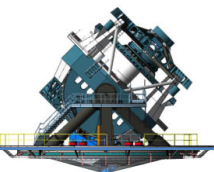


The Source Communication Interface

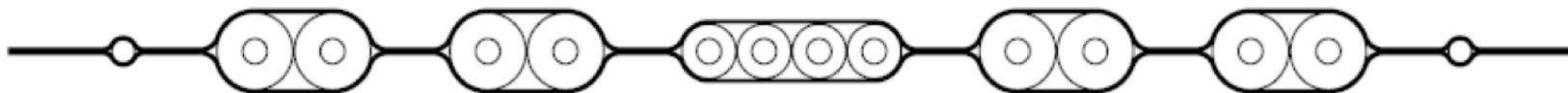


- A small, lightweight, self-contained set of firmware sharing the FPGA with the Sensor Specific Logic
- Employs high speed (3.125 Gbits/sec) point-to-point, serial communication protocol (PGP)
 - Protocol assures QOS through four Virtual Channels
- The SCI has four principal functions
 - Provide a stable, system reference clock and synchronous commands
 - This clock is the recovered clock from the serial data link
 - Reliably encode and transmit 18-bit pixel data to the CDS
 - Provide a mechanism for external configuration, control and monitoring of the REB's sensor electronics

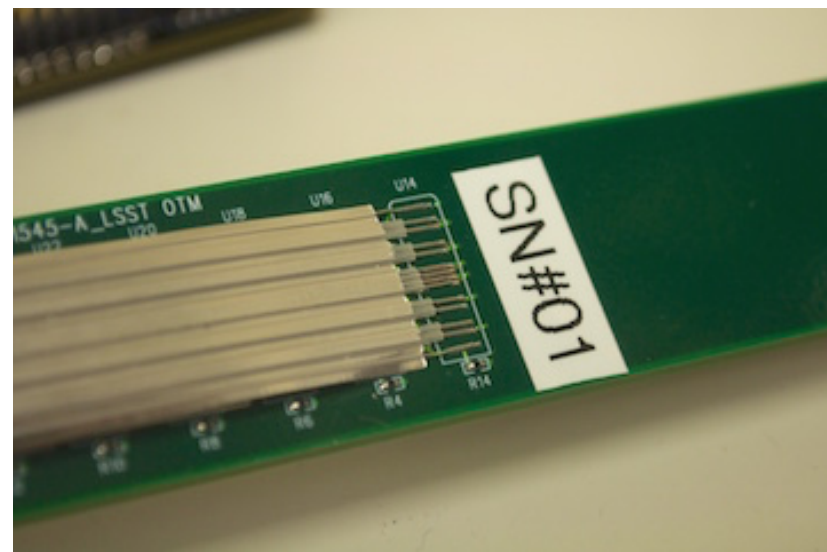
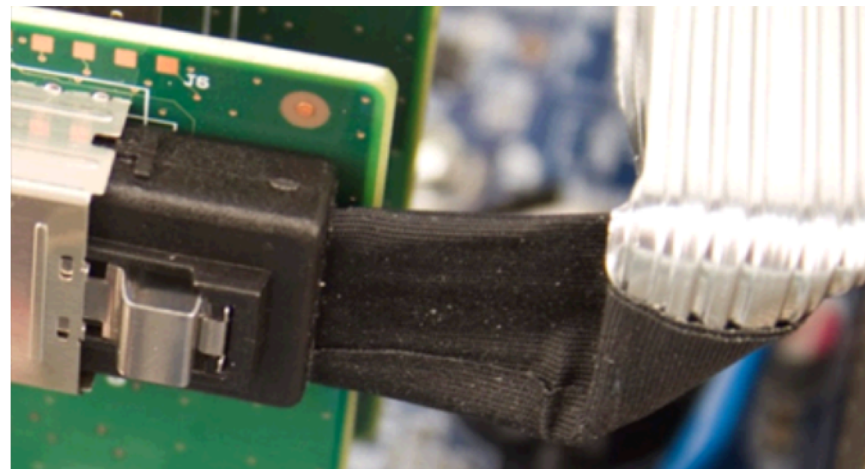
See Stefano Russo's poster 446 for some of what goes in the SSL box!

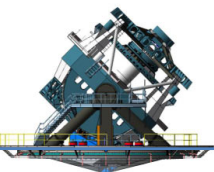


Cables between SCI & OTM



- 3M Twin Axial cable
 - Longitudinal aluminum shield
 - 2 ground wires connected to shield
 - 4 pairs for high speed signals
 - Impedance : 100 Ohm
 - Propagation delay : 4.95 ns/m
 - Intra-pair skew : <10 ps @ 3 m
 - Attenuation : -4.9 dB/m @ 10 GHz
 - 4 single ended “sideband” signals
 - 1 mm minimum bend radius
- High speed pairs (PGP primary & redundant)
- 4 single ended wires (used as 2 LVDS pairs)
- Terminations
 - REB side uses Mini-SAS connector
 - OTM side soldered directly to OTM

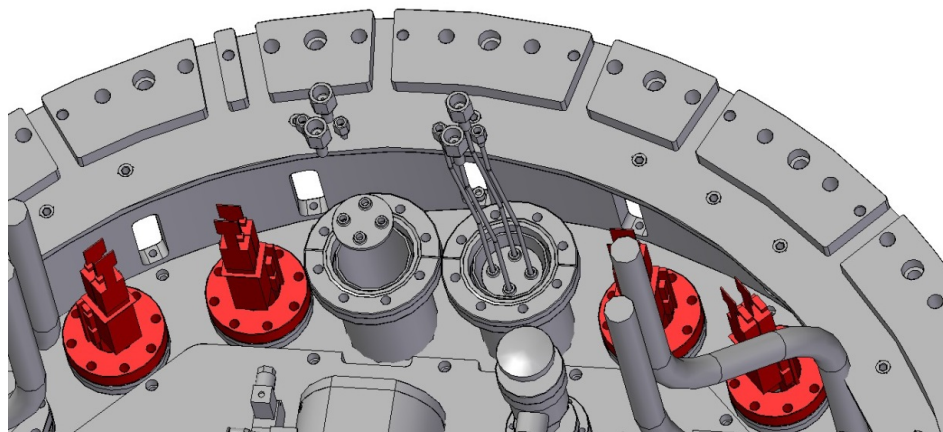
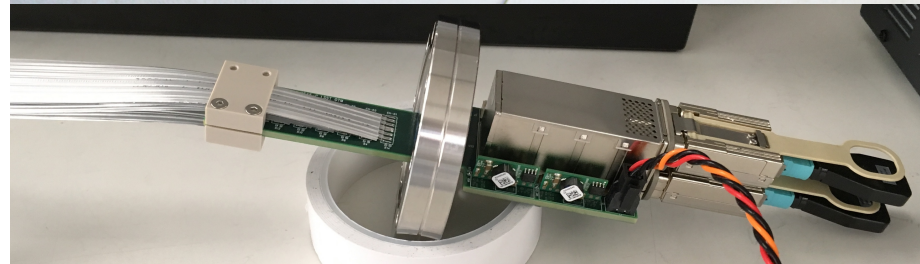
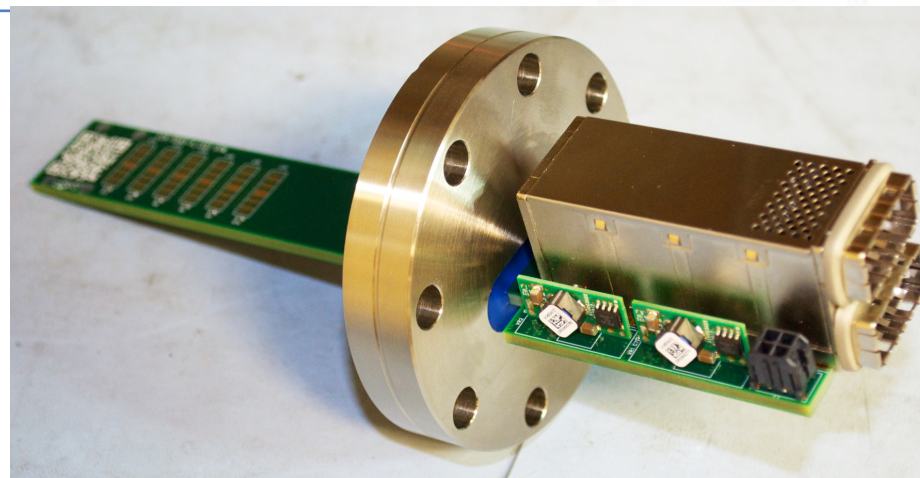




The Optical Transition Module



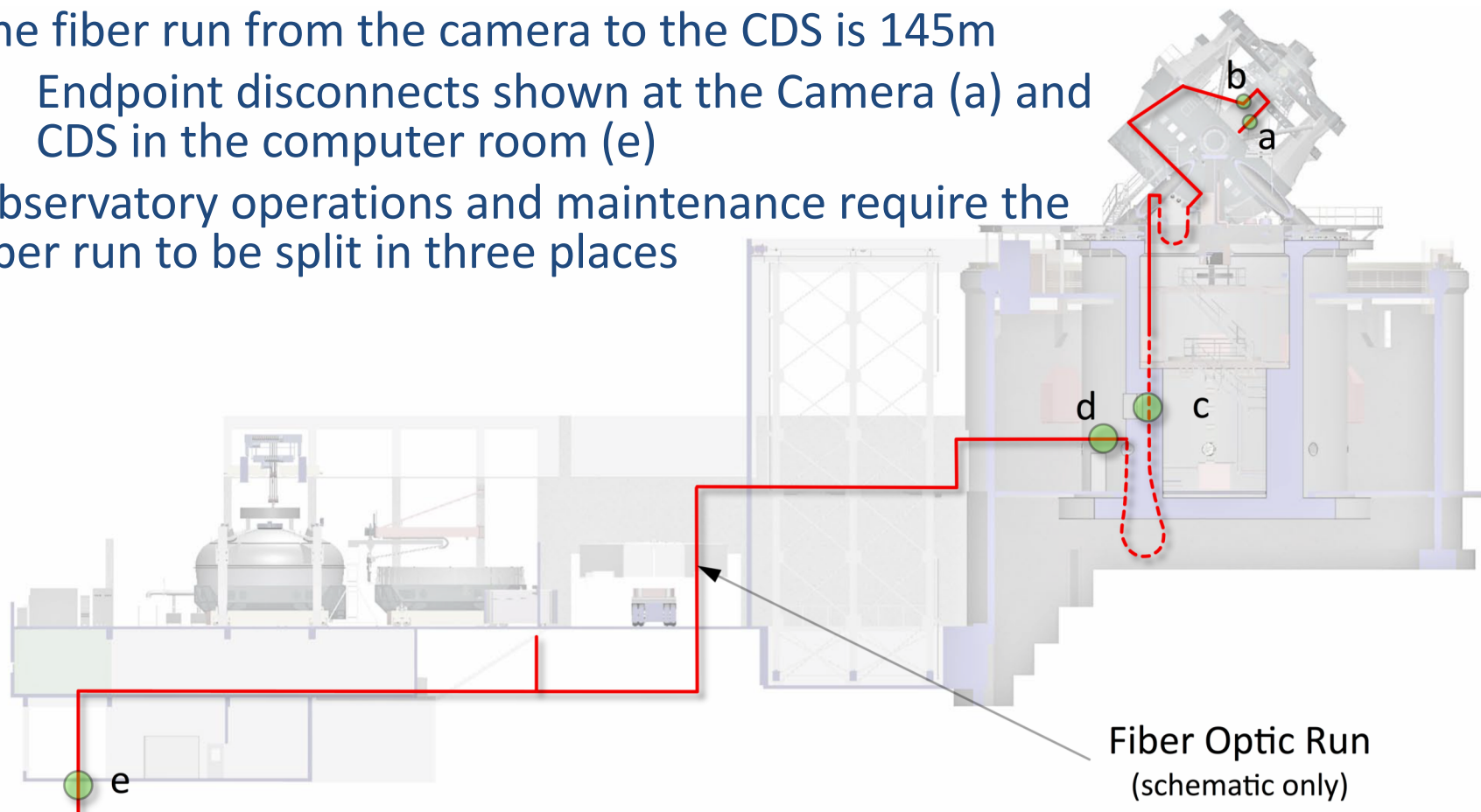
- Two purposes
 - Converts signals between copper and fiber
 - Penetrates the cryostat
- The PCB board is potted into a 3 3/8" Conflat vacuum flange
 - The vacuum side connects to 12 SCIs over copper
 - The air side has two transceivers
 - One is active, the other a cold spare
 - connected to the SCI primary and redundant links, respectively
 - Selection is done by powering one or the other
 - Each transceiver accepts a 24-fiber MTP connector
- 6 OTMs serve the focal plane's 71 SCIs
 - 12 cables pass through the Camera's Utility Trunk to the Camera/Telescope Interface

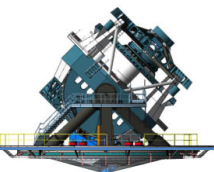


Fiber run between camera & summit computer room



- The Telescope provides the fiber between the Camera and the summit computer room
 - Camera DAQ specifies the optical properties
- The fiber run from the camera to the CDS is 145m
 - Endpoint disconnects shown at the Camera (a) and CDS in the computer room (e)
- Observatory operations and maintenance require the fiber run to be split in three places

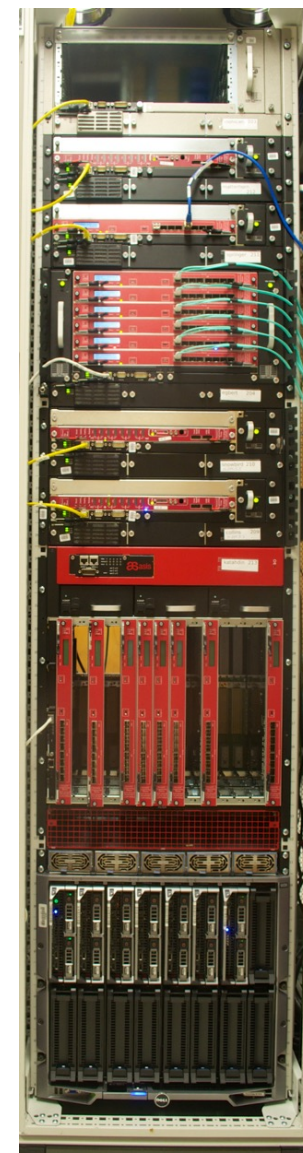




The Camera Data System

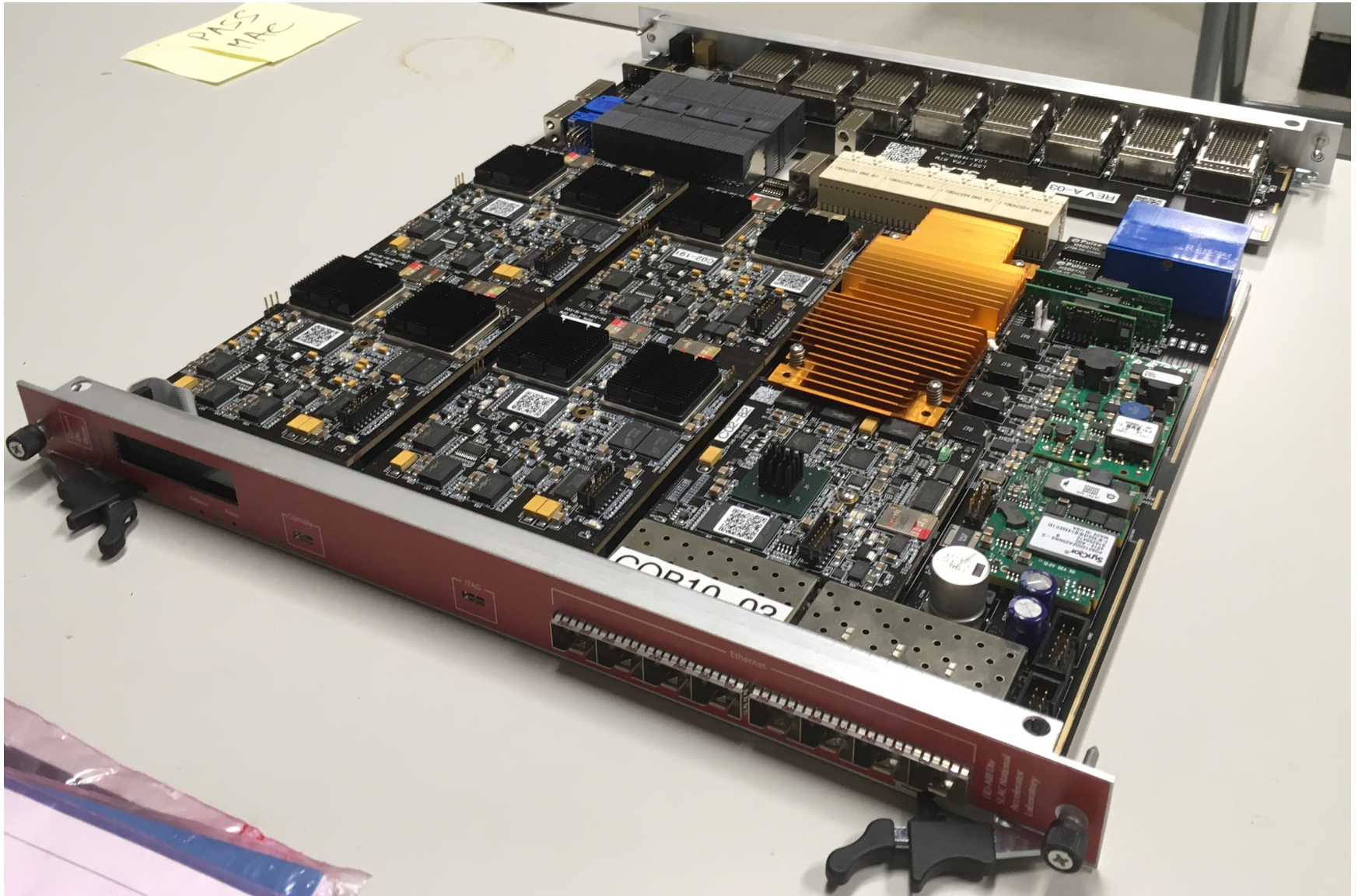


- The CDS is a 14 slot ATCA shelf with a full mesh backplane
- The Front Boards are custom carrier boards (COBs)
 - Each carries 8 Reconfigurable Cluster Elements (RCEs)
 - Ours are Xilinx Zynq-7000 SoC based
- COBs are partitioned into two sets defined by their RTM
 - 3 service the FPA (FPA RTM)
 - 8 CXP transceivers, one connected to each RCE
 - 11 service the Image Store (SSD RTM)
 - 24 SSDs, three connected to each RCE
- The system clock is distributed to all RCEs from a master over the ATCA Clock Synchronization Bus
 - This is used as the reference clock for the Zynq GTX transceivers
 - When recovered in the SCI, this clock is shared by all REBs
- Serialized commands are also fanned out to all RCEs this way
 - From there they are sent to the SCIs with fixed latency

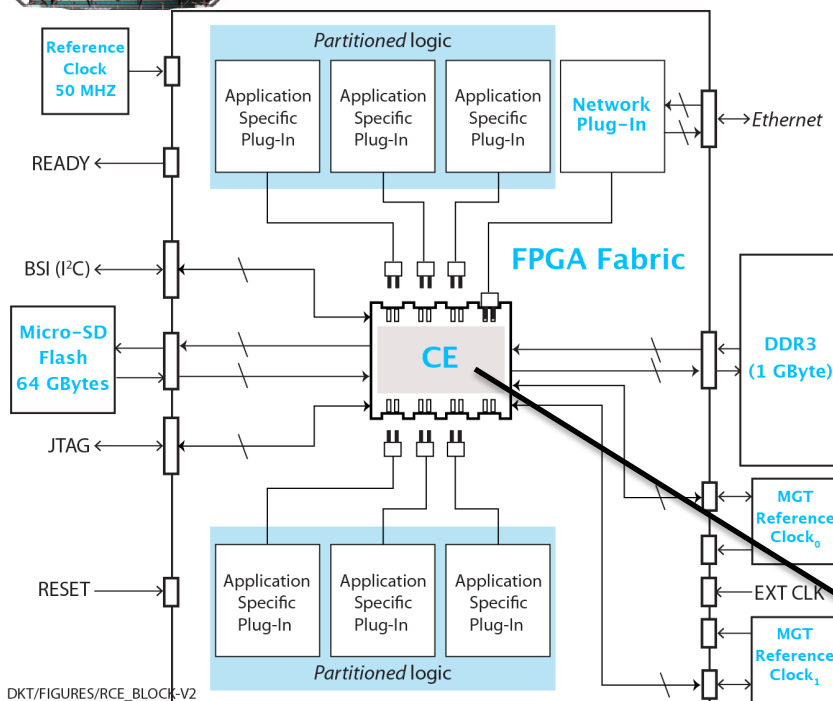




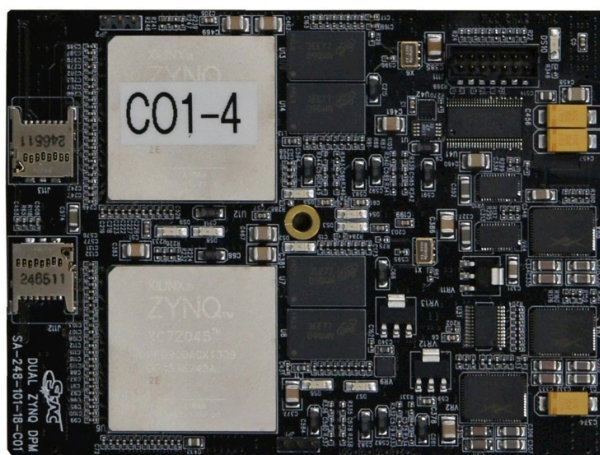
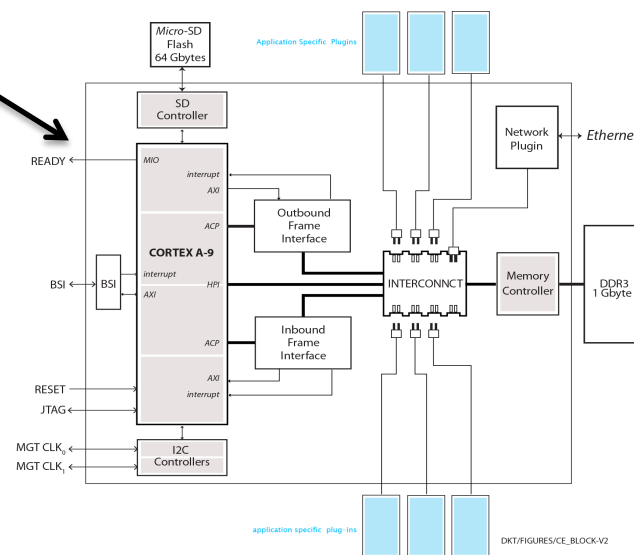
COB

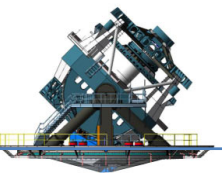


The Reconfigurable Cluster Element



- Based on System-On-Chip technology
- The RCE is a generic computational node
- It's an FPGA, it's a DSP, it's a processor
 - Dual-core (A-9) ARM processor (@1 GHz)
 - 1 GB of DDR3 RAM
 - Up to 64 GB of flash
 - Memory subsystem has > 6 GB/s of I/O capacity
 - Real-Time kernel (RTEMS)
 - Full TCP/IP stack

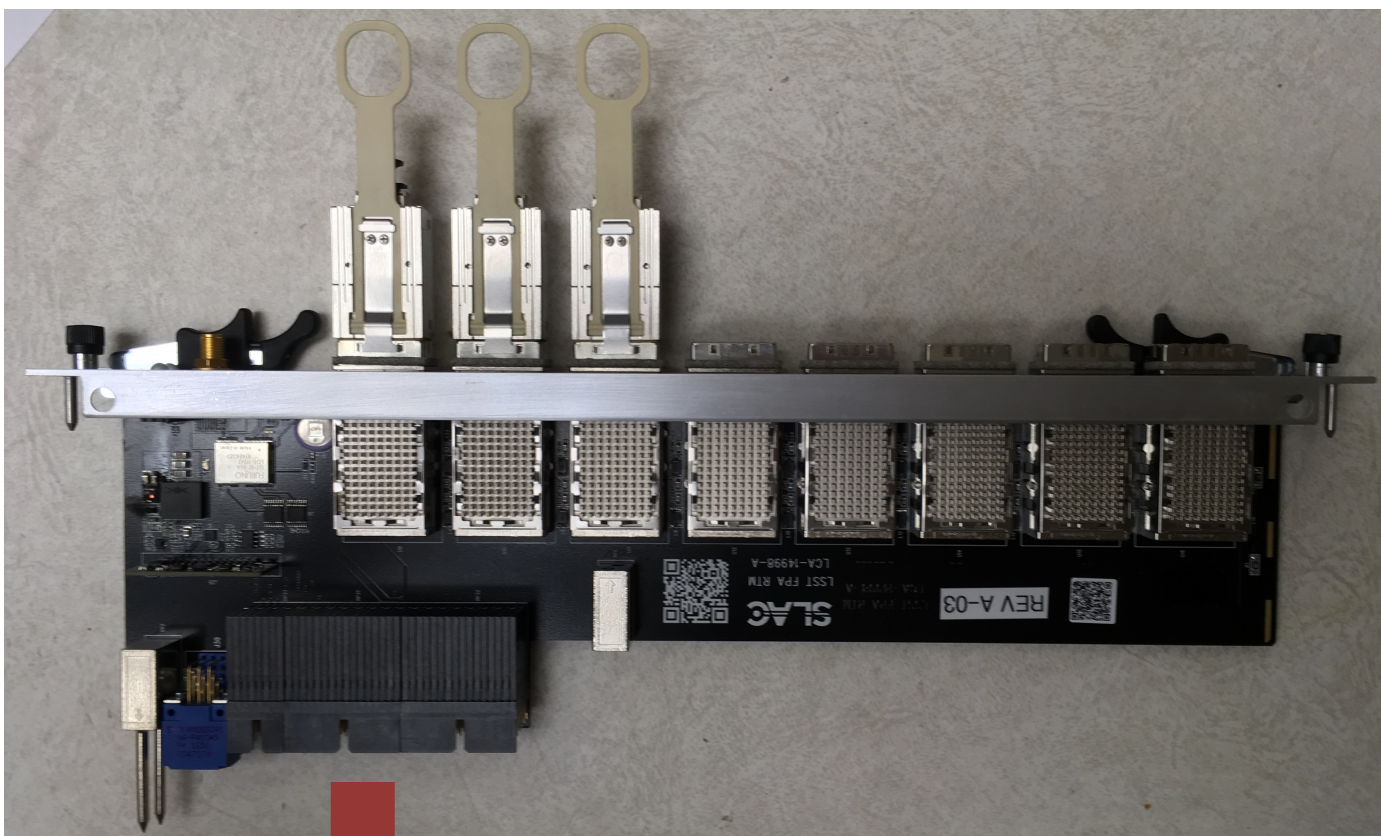




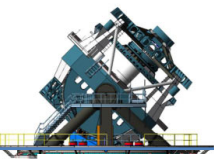
FPA-RTM



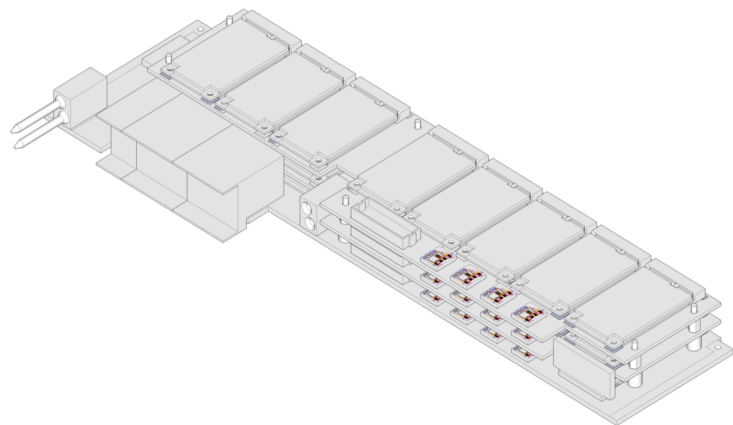
To (up to) 9 SCI's on 1 to 3 rafts



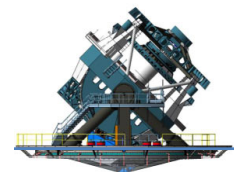
To COB (its RCEs)



SSD-RTM



To COB (its RCEs)



Status and Summary



- All the hardware for the DAQ has been prototyped, and full production runs will occur this year
- Scaled down versions of the CDS and its associated software have been used by other LSST groups in their development for many years
- Work remains on the final implementation of the Image Store, Guider Data System, and Crosstalk Correction
- The LSST Camera DAQ has features that distinguish it from other large experiment's DAQ systems
 - The large geographic distribution of its components
 - The need to buffer many days worth of data
 - The high speed serial data are generated in a cryostat and need to get out



End of Presentation

