
HIE-Isolde Low Level RF *proposal*

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BE/RF/FB

Outline

- 1. New LLRF developments in the BE/RF/FB section
- 2. LHC LLRF
- 3. Linac4 LLRF and SPL studies
- 4. HIE-Isolde LLRF *proposal*

1. BE/RF/FB section

LLRF in the BE/RF/FB section

- RF **operation** of six machines
 - ❑ PSB, PS, SPS, LHC
 - ❑ LEIR
 - ❑ AD
- Fourteen staff members
- **Ongoing** LLRF projects
 - ❑ **LHC** re-start
 - ❑ **PSB**
 - ❑ **Linac4**
 - ❑ **SPL studies**

2. LHC LLRF

LHC LLRF

- ❑ **Super Conducting** Standing Wave Cavities, single-cell, $R/Q = 45$ ohms, 6 MV/m nominal
- ❑ Movable Main Coupler
 $10000 < Q_L < 180000$
- ❑ Mechanical Tuner range = 100 kHz
- ❑ 1 klystron per cavity
 - 330 kW max (58 kV, 8.4 A)
 - In operation < 200 kW CW
- ❑ **0.5 A DC current**

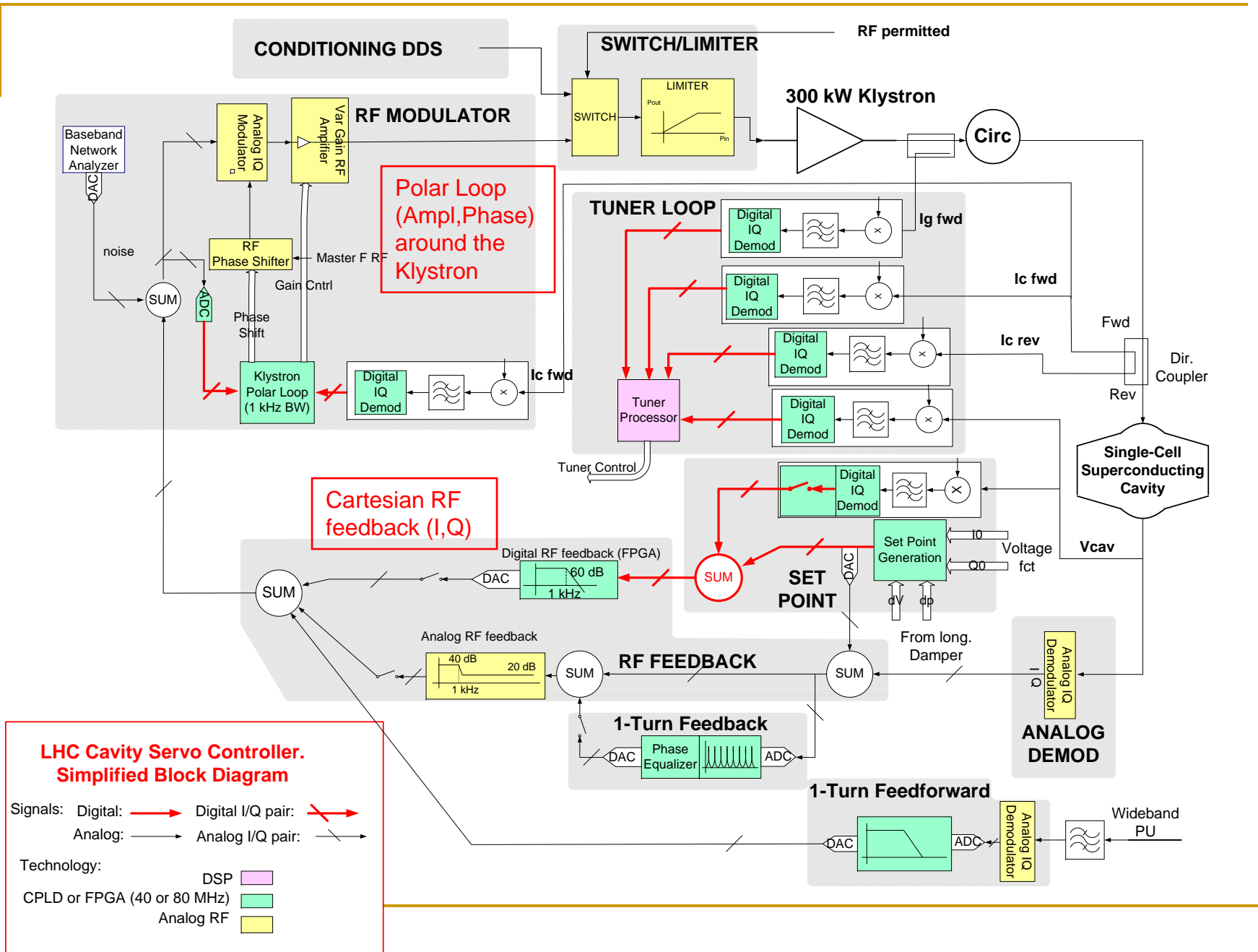
Hadron collider with very high beam current.

Challenges: Impedance reduction (stability) and low noise (lifetime)



LHC Cavity Controller Loops

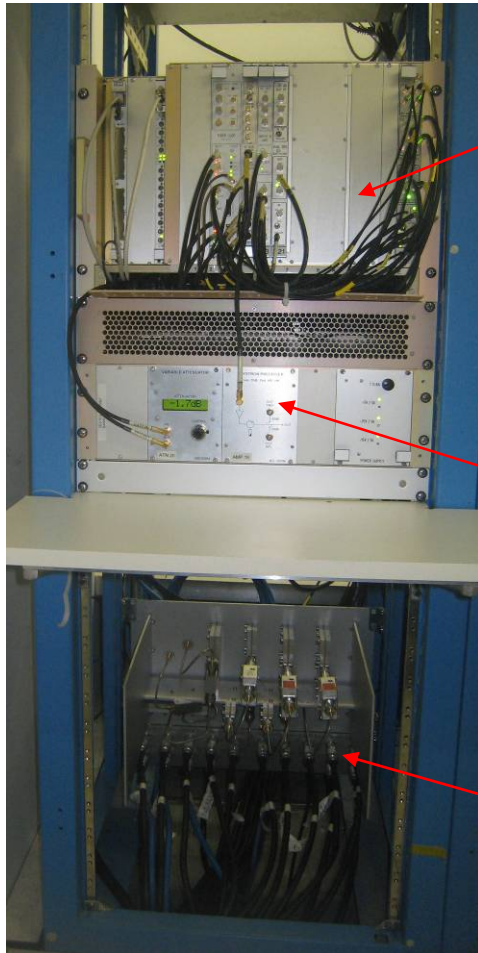
- **A Tuner Loop:** Minimizes klystron current. (Half detuning)
- **An RF Feedback Loop:** Reduces the cavity impedance at the fundamental (by 20 linear for $Q=20000$, by 180 at $Q = 180000$). Precision of RF voltage, transient beam loading and longitudinal stability
- **A Klystron Polar Loop:** Compensates for the klystron gain/phase changes. (HT drifts and ripples).
- **A 1-T Feedback:** Adds factor 10 reduction on the revolution frequency side-bands. (Transient beam loading + longitudinal stability)
- **A Conditioning System** monitoring the Main Coupler Vacuum while feeding the Line with Frequency Modulated bursts of RF power of increasing amplitude
- **A Klystron Drive Limiter** that prevents from driving the klystron over the saturation limit during loop transients.



Features

- RF feedback implemented in a low group delay **I/Q Loop**
- Extensive **Diagnostics**:
 - Important signals (~30/cavity) are stored for monitoring
 - Two sets of memory
 - **Post-Mortem memory**: Free-running, stopped by specific machine-wide post-mortem trigger, fixed sampling rate. Meant to correlate acquisitions after a fault.
 - **Observation**: Piloted by operator that sets sample rate and triggers the acquisition. Meant for monitoring during operation.
 - **Built-in Network Analyzer**
 - Excitation memories to inject signals (step, sine-wave, white noise,...) coupled with observation memories implement a Signal Analyzer
- Fully remote controlled

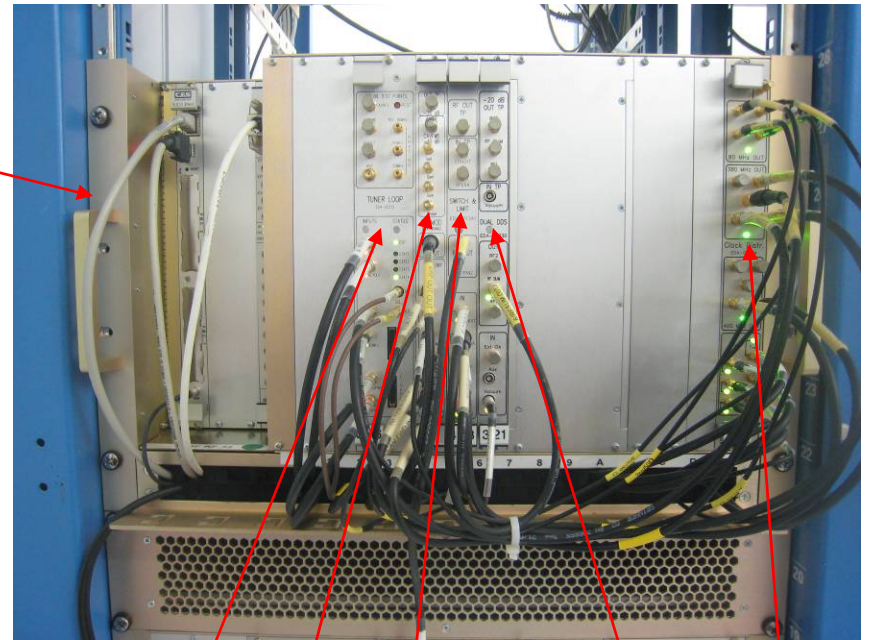
Implementation



Cavity Controller
VME crate

Antenna calibration
and 100 mW pre-
driver

RF cable splitting



Tuner Control

Switch&Limit

RF Modulator

Conditioning DDS

Clock Distri

LHC LLRF VME Tuner Crate

LHC LLRF



LHC LLRF Faraday Cage

Noise reduction with RF feedback



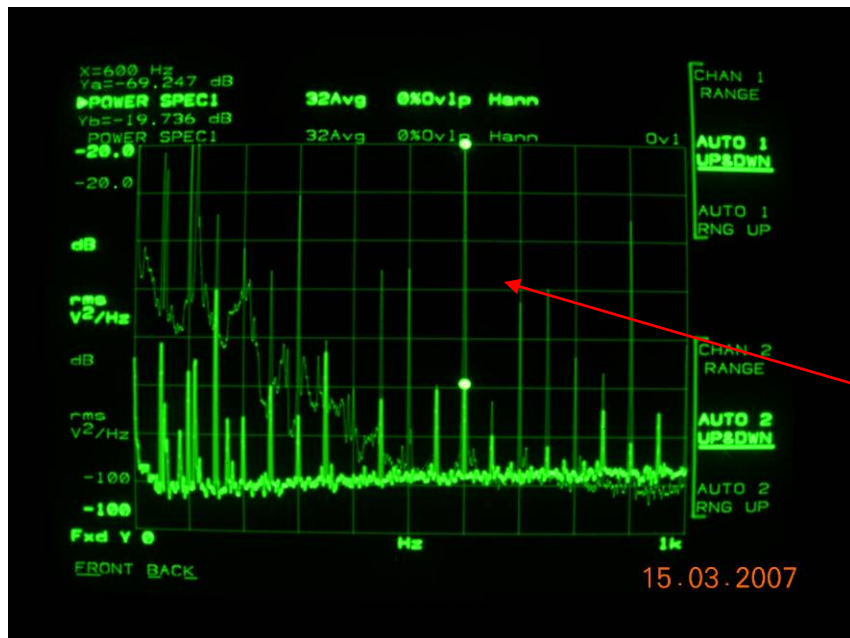
Phase
Vcav/Ref



Open Loop 10 mV/div -> **5 dg pk-pk**, 5 ms/div (File PhaseMeasOpen 14 March 2007)

Closed Loop 2 mV/div -> **0.1 dg pk-pk**, 5 ms/div (PhaseMeasAtt_0A 14 March 2007)

- Phase noise Vcav vs ref.
- SM18 test stand, March 2007
- Calibration: 10 mV/dg @ 400 MHz
- Q=60000, 1 MVacc, 35 kW



- Power Spectral Density of cavity phase noise (V_{cav} vs Ref) with and without RF feedback
- ZLW1 mixer and Spectrum Analyzer
- 300 mV/dg @ 400 MHz
- 50 dB reduction of 600 Hz line

Open Loop vs Close Loop. 50 dB
reduction @ 600 Hz
(File PhaseNoise3 15 March 2007)

LHC LLRF Developments

- LLRF design started in 2003. Completed by 2008+.
- ~ 4 man.year per year over the seven years period
- Volume:
 - 20 racks in UX45 plus 15 racks in SR4
 - ~ 50 special LLRF VME crates plus 5 standard VME crates
 - ~ 500 NIM/VME cards of 36 different makes
- Much expertise developed
 - Signal Processing in FPGA (CIC filters, CORDIC, I/Q Demodulator)
 - Synchronization problems in multi-clocks systems
 - Mixed signals PCBs: RF front-end and digital part. Grounding, decoupling, linear/switched mode P.S.
 - Design flow/tools: Visual Elite (FPGA) then Cadence (Schematics/Layout)
 - Use of on-board diagnostic memories plus excitation buffers

3. Linac4 LLRF

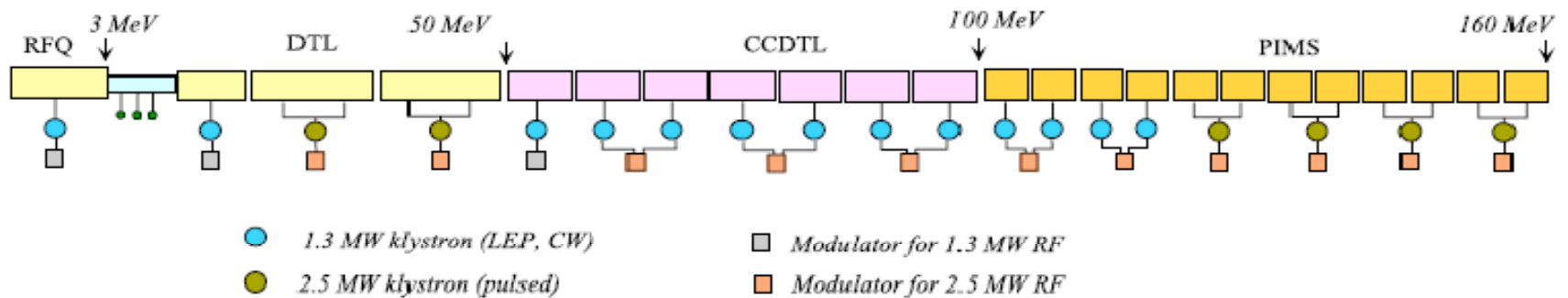
Linac4 LLRF

- H- Linac injecting 160 MeV beam in the PSB
- Replaces Linac 2 (designed 1975)
- Commissioning in 2013. From start-up 2014 source of all proton beams
- ~80 m long
- Normal Conducting structures (Q_L from 6k to 40k) at 352.2 MHz
- 2 Hz rep rate
- 40 mA Linac current
- Beam Pulse length: 80 - 400 μ s nominal, 1 ms max
- Wide variety of structures: re-entrant cavities (buncher), RFQ, DTL, CCDTL, PIM
- LLRF design started in 2009.
- **Target: Field stabilization within 1 deg and 1 %**

Moderate intensity pulsed NC Linac.

Challenge: Transient Beam Loading (chopping)

Lay-out



Linac 4 lay-out.

Functionalities. For each tank

- A **Tuner Loop** to keep the structure on resonance
- An **RF Feedback**, and a **Feedforward** (Iterative Learning) to keep the accelerating voltage at the desired value in the presence of beam transient
- A **Klystron Polar Loop** to compensate the variation of klystron gain and phase shift caused by High Voltage (HV) supply fluctuations and droop
- A **Conditioning System** monitoring the Cavity Vacuum/Reflected Power while feeding the Line with Frequency Modulated bursts of RF power of increasing amplitude
- A **Klystron Drive Limiter** that prevents from driving the klystron over the saturation limit during loop transients.

Similar – but somewhat simpler – than the LHC LLRF (slide 7)

Block diagram

Polar Loop
(Ampl, Phase)
around the
Klystron

Cartesian RF
feedback (I,Q)

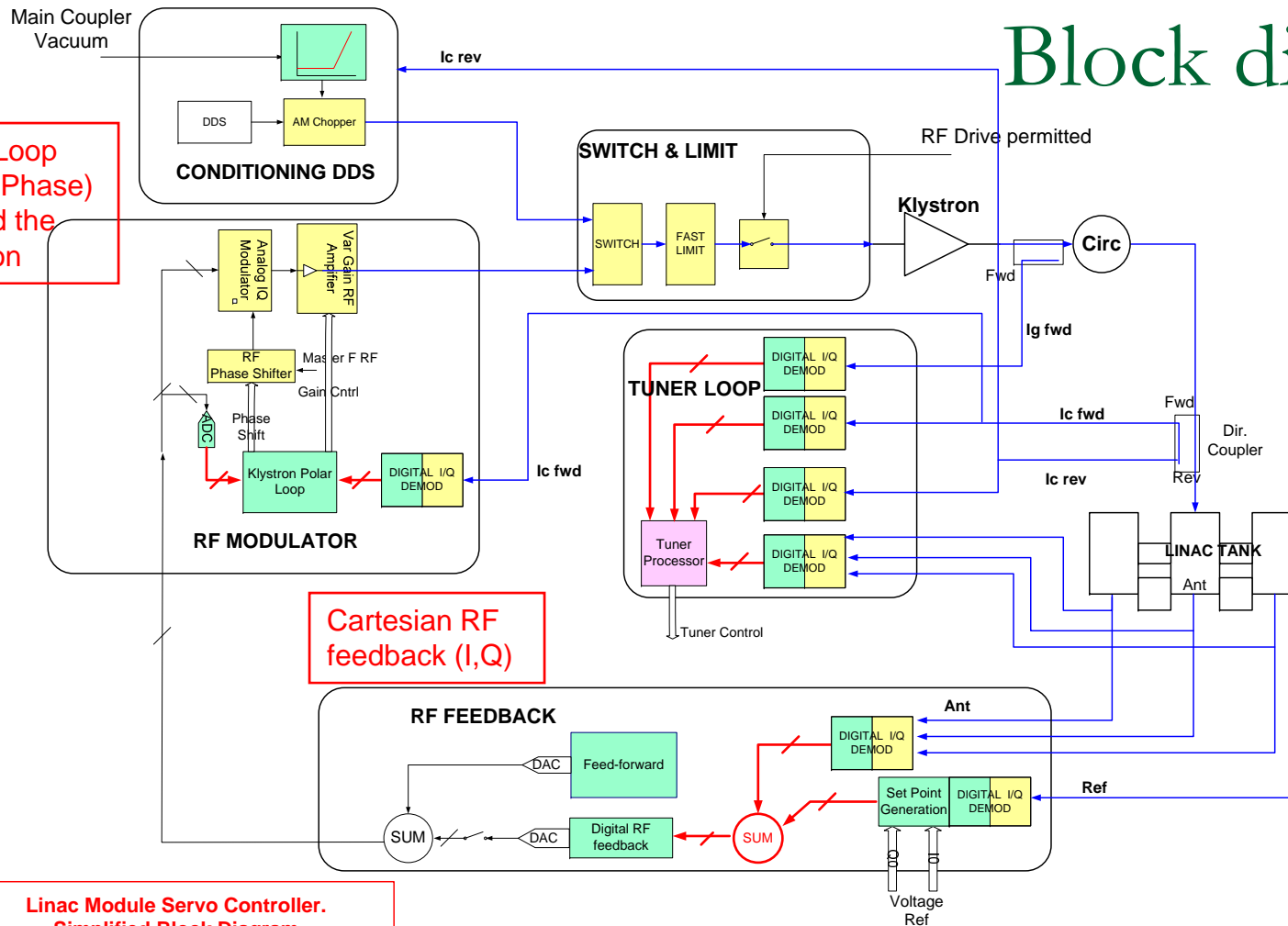
**Linac Module Servo Controller.
Simplified Block Diagram**

Signals:

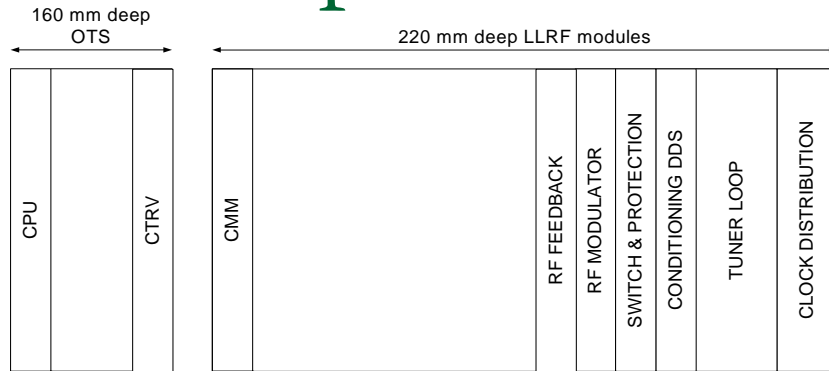
- Digital: →
- Analog baseband: →
- RF @ 352.2 MHz: →
- Digital I/Q pair: ↔
- Analog I/Q pair: ↔

Technology:

- DSP:
- CPLD or FPGA:
- Analog RF:



Developments



- Same crate as LHC LLRF but re-assigned lines on J2 backplane
- Same design flow: Visual Elite for FPGAs, Cadence
- Re-use FPGA blocks: I/Q demod, CIC, Cordic
- But... **re-do all VME modules** (simplifications, obsolete components,...)

		A	B	C	
1	Timings (12x)	Cycle Start*	● ● ●	RF ON*	AnalyzeTrig*
		Beam In*	● ● ●	RF OFF*	Post-mortem Trig*
		BpTA3* / Beam Out*	● ● ●	Beam On wn*	Observation Trig*
4		BpTA4*	● ● ●	Beam Off wn*	Cold reset*
5			● ● ●		
	Digital data (3x6)		● ● ●		See page 2
			● ● ●		
			● ● ●		
10			● ● ●		
	Intlk/Alarm (3x)	Inj Enable	● ● ●	ConfigDone	
	FG	SDin	● ● ●	DGND, SDout	
13		spare	● ● ●	spare	
		35.22 MHz-	● ● ●	35.22 MHz+	
		spare	● ● ●	spare	
	Clocks (Differential ECL)	17.61 MHz-	● ● ●	17.61 MHz+	
		MA0	● ● ●	MA1	
	Module Address (MA3-0)	10 MHz-	● ● ●	10 MHz+	8 x DGND
		MA2	● ● ●	MA3	
		Fc-	● ● ●	Fc+	
21			● ● ●	-5.2 V (for backplane ECL buffers only!)	
	Jtag	TDI	● ● ●	DGND, TDO	
		TCK	● ● ●	IENA, TMS	
	Extra Digital V		● ● ●	+3.3 V	Switched Mode Power Supply
			● ● ●	DGND	
26		spare	● ● ●	AGND	
			● ● ●	Module Serial Number Bus	
	Analog Power Supply + AGND (3 pins each)		● ● ●	+12 V	Linear Power Supply
			● ● ●	+6 V	
			● ● ●	-6 V	
			● ● ●	-12 V	
32			● ● ●	AGND	

LINAC LLRF backplane
Lower connector: 3 x 32 pins
version 11/30/2008

SPL LLRF studies

- H- Linac at Linac4 output (from 160 MeV to 4 GeV)
- Multi-cell Super-Conducting structures ($Q_L \sim 10^6$) at 704.4 MHz
- 2 Hz rep rate
- 20 mA Linac current
- Only study so far (fast tuner to compensate the Lorentz Force detuning)

4. HIE-Isolde LLRF *proposal*

HIE-Isolde LLRF

- CW operation
- Super Conducting QWR structures
- $Q_L \sim 10^7$ around 100 MHz
- Solid state amplifier Peak Power < 1 kW . One amplifier per cavity. 250W needed on tune.
- 1 pA Linac current
- **Target: Field stabilization within 0.5 deg and 0.5 %**

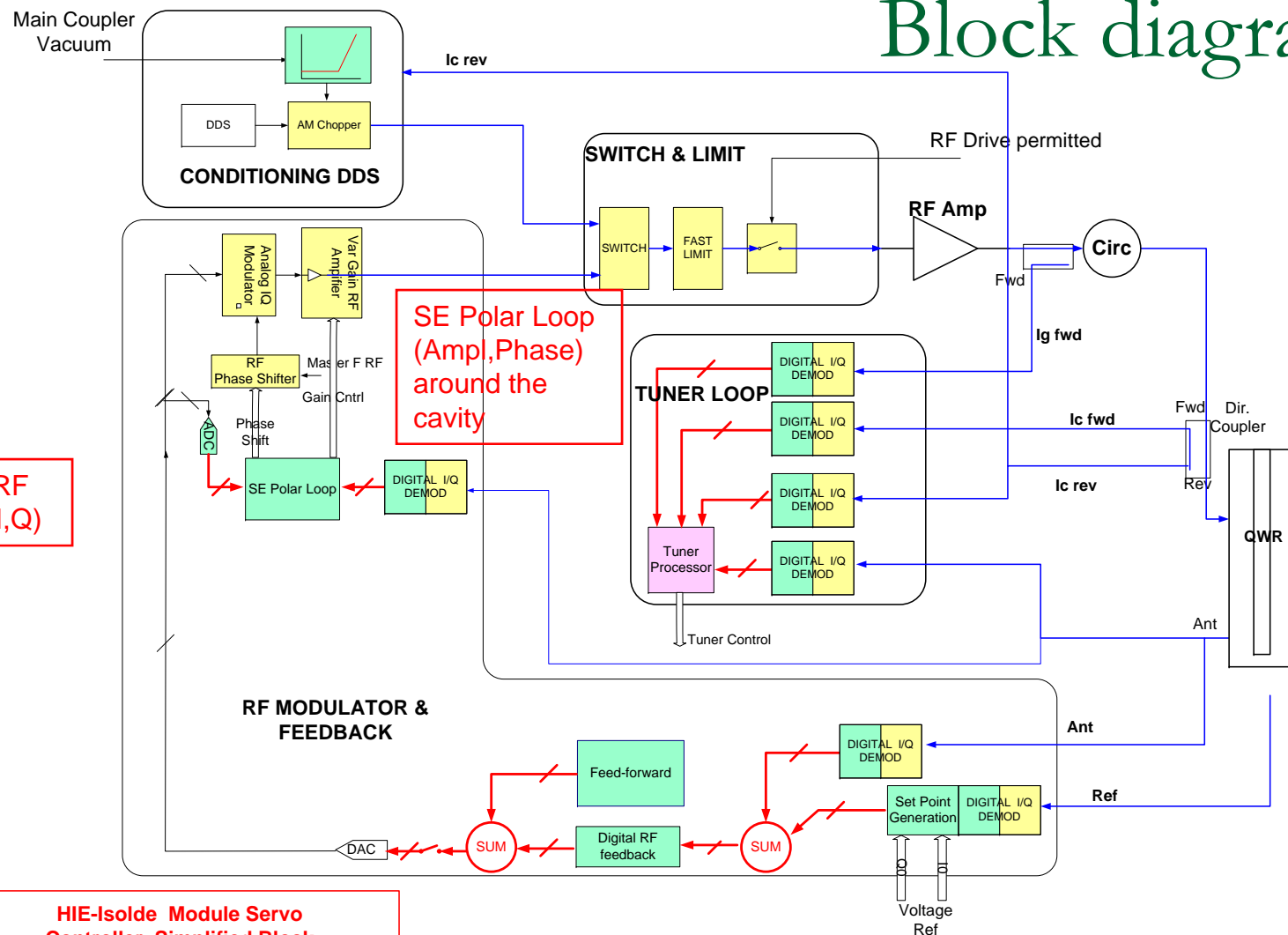
Very low intensity CW SC Linac.
Challenge: **Very high Q_L**

Functionalities. For each cavity

- A **Tuner Loop** to keep the structure on resonance
- An **RF Feedback** to keep the accelerating voltage at the desired value in the presence of perturbations (vibrations, Helium pressure fluctuations, ..). Normal operation in **Driven Mode**.
- A **Self-Excited Polar Loop** to enable **SEL Operation** at start-up when the tune is way off or without tuner
- A **Conditioning System** monitoring the Window Vacuum while feeding the cavity with Frequency Modulated bursts of RF power of increasing amplitude
- A **Klystron Drive Limiter** to limit the drive in Self-Excited Loop mode

Similar to Linac4 – but klystron loop replaced by SEL loop around the cavity

Block diagram




Cartesian RF
feedback (I,Q)


SE Polar Loop
(Ampl,Phase)
around the
cavity


HIE-Isolde Module Servo Controller. Simplified Block Diagram

Diagram


Signals:


Digital:  Digital I/Q pair: 


Analog baseband:  Analog I/Q pair: 

RF @ 100 MHz 

Technology:

DSP 

CPLD or FPGA 

Analog RF 

Version: 20090614

Normal operation. Driven feedback system.

- Cavity Controller close to Cavity.
 - Max 30 m round-trip (~ 100 ns cable delay)
 - Allowing 100 ns for RF Amplifier
- RF feedback BW (2-sided) in excess of 2 MHz ...if sufficient Amplifier power.
- For each cavity, the Set point is **individually** provided as an (I,Q) set vector
- The Phase and amplitude controls in the RF Modulator are set at fixed values (SE Polar Loop OFF)

Tuner

- $Q=10^7$ -> only 10 Hz 2-sided BW
- **Stability of the structure**
 - Mechanical resonances (64 Hz?)
 - Microphonics (2 Hz rms?)
 - Sensitivity to He pressure fluctuations 0.01 Hz/mbar (0.3 Hz for expected 30 mbar ripple)
 - Precision of the tuning mechanics: **1 μm** -> ~ 10 Hz = **1 BW !**

To be measured ASAP

Then study/simulation with the LLRF

- **Resolution** of the Tuner RF front-end
 - 200 kHz tuning range = 20000 BW
 - At 5 kHz offset, V_{cav} is reduced by 60 dB

Startup

- With cavity way out of tune, Tuner loop may not lock...
- Two possibilities
 - **Open Loop** using the Conditioning DDS
 - Sweep frequency of Conditioning DDS to find the resonance.
 - Then move the tuner to get in the Locking Range of the tuner loop
 - **Self-Excited Mode**
 - With the **RF Feedback**
 - Reduce RF feedback gain so that resonance can only take place in the Cavity BW
 - Intentionally add 180 degrees to the Modulator Phase to make the RF feedback unstable
 - With the **SE Polar Loop**
 - Open the RF feedback. Set a fixed (I,Q) at the modulator input.
 - Adjust phase of SE Polar Loop to initiate resonance
- Advantage: The Self-Excited Loop can be **used without tuner** (Lab tests)
- To be studied
 - SEL implemented in I/Q coordinates (using the RF feedback) vs. implementation using the SE Polar loop
 - Control of Cavity voltage when in SEL mode

Thank you...

Additional material if questions arise

RF feedback Theory

- RF Feedback theory [6],[7]
 - Minimal cavity impedance (with feedback) **scales linearly with T**
- $$R_{\min} = \frac{2}{\pi} \frac{R}{Q} \omega_0 T$$
- Achieved for a gain value **proportional to Q**
- $$G_{\text{opt}} \approx \frac{Q}{\omega_0 T}$$
- Achievable fdbk BW **inversely proportional to T**

$$\Delta\omega = \frac{1.3}{T}$$

