

Differential equation approach to perturbative calculations.

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Outline

- 1 Introduction
- 2 Reduction to ε -form
- 3 Examples of application
- 4 Summary

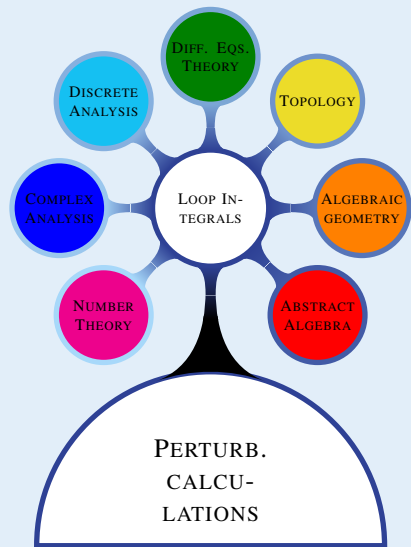
Why multiloop integrals?

Perturbative calculations

Technically, perturbative calculations are reduced to the calculation of (multi)loop integrals.

Multiloop integrals

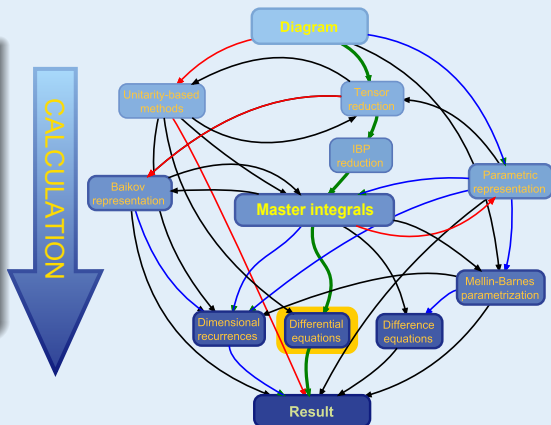
- Physical applications
- Beautiful mathematics
- Open problems



Multiloop calculations

Problem

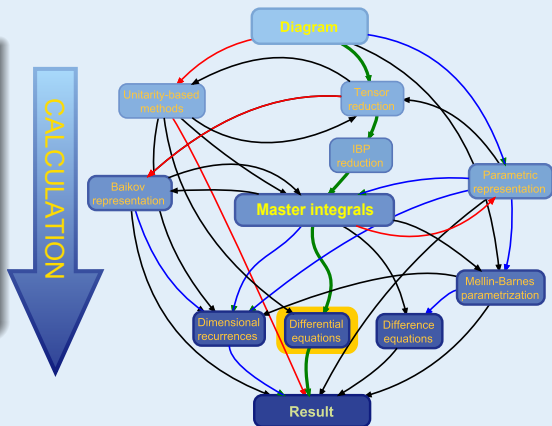
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- Phenomenological applications often require **a few** loops but **many** scales.



Multiloop calculations

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Multiscale problems: IBP+DE approach.

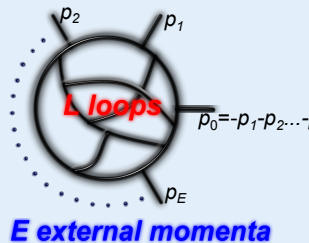
IBP reduction (Chetyrkin&Tkachov 1981)

Scalar integrals family labeled by \mathbf{n}

$$J(\mathbf{n}) = \int d^d l_1 \dots d^d l_L j(\mathbf{n}) = \int \frac{d^d l_1 \dots d^d l_L}{\pi^{\frac{Ld}{2}} D_1^{n_1} \dots D_N^{n_N}}$$

D_1, \dots, D_M — denominators of the diagram,

D_{M+1}, \dots, D_N — numerators ($n_{M+1}, \dots, n_N \leq 0$).



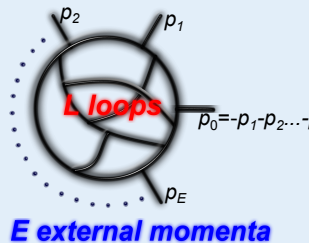
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Basic idea of IBP reduction

- Explicit differentiation in (IBP&LI) gives recurrence relations between integrals $J(\mathbf{n})$ with different \mathbf{n} .
- Using these relations, any integral can be reduced to **finite number** of *master integrals*.

IBP

$$\int d^d l_1 \dots d^d l_L \frac{\partial}{\partial l_i} \cdot q_j j(\mathbf{n}) = 0$$

LI

$$p_{1\mu} p_{2\nu} \sum_e p_e^{[\mu} \partial_e^{\nu]} J = 0$$

Differential equations(Kotikov,1991;Remiddi, 1997)

Differentiating the column-vector \mathbf{J} of master integrals with respect to mass or some invariant and performing IBP reduction we obtain differential equations

$$\partial \mathbf{J}(x) / \partial x = \mathbb{M}(x, \boldsymbol{\varepsilon}) \mathbf{J}(x)$$

with $\mathbb{M}(x, \boldsymbol{\varepsilon})$ being a rational matrix of x and $\boldsymbol{\varepsilon}$.

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Recent remarkable observation (Henn, 2013)

By a suitable change of functions $\mathbf{J}(x) \rightarrow \mathbb{T}(x, \varepsilon) \tilde{\mathbf{J}}(x)$, it is possible to transform equation to ε -factorized form (ε -form)

$$\partial \tilde{\mathbf{J}}(x) / \partial x = \varepsilon \mathbb{S}(x) \tilde{\mathbf{J}}(x)$$

Moreover, rational matrix $\mathbb{S}(x)$ has only simple poles and falls off at infinity ($\mathbb{S}(x) = \sum_i \mathbb{S}_i / (x - x_i)$), i.e., the system is globally *Fuchsian*.

Benefits of ε -form

- Given the equation

$$\partial \mathbf{J}(\varepsilon, x) / \partial x = \varepsilon \mathbb{S}(x) \mathbf{J}(\varepsilon, x)$$

it is easy to find coefficients of expansion $\mathbf{J}(\varepsilon, x) = \sum \mathbf{J}_n(x) \varepsilon^n$ 1 by 1:

$$\mathbf{J}_n(x) = \int dx \mathbb{S}(x) \mathbf{J}_{n-1}(x) .$$

The coefficients are automatically expressed in terms of Goncharov polylogs and obey the property of uniform transcendentality.

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- For many variables if we secure simultaneous ε -form

$\partial \mathbf{J}(\varepsilon, \vec{x}) / \partial x_i = \varepsilon \mathbb{S}_i(\vec{x}) \mathbf{J}(\varepsilon, \vec{x})$, the integrability condition splits into two $\partial_j \mathbb{S}_i = \partial_i \mathbb{S}_j$ and $\mathbb{S}_j \mathbb{S}_i = \mathbb{S}_i \mathbb{S}_j$ and the system can be rewritten as

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- Usually the form of the system is drastically simplified.

Example

Original matrix:

$$\left(\begin{array}{cccccccc} \frac{(x^2+1)(2\epsilon-1)}{(x-1)x(x+1)} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{2(\epsilon-1)(\epsilon x^4 - x^4 + 10\epsilon x^2 - 8x^2 + \epsilon - 1)}{(x-1)x(x+1)(x^2+1)(3\epsilon-2)} & \dots & \dots & 0 & 0 & 0 & 0 \\ 0 & -\frac{(4\epsilon-3)(\epsilon x^4 - 2\epsilon x^2 + 4x^2 + \epsilon)}{(x-1)x(x+1)(x^2+1)} & \dots & \dots & 0 & 0 & 0 & 0 \\ 0 & \frac{2\epsilon^3 x^8 - 3\epsilon^2 x^8 + \epsilon x^8 + 16\epsilon^3 x^6 - 84\epsilon^2 x^6 + 102\epsilon x^6 - 36x^6 - 36\epsilon^3 x^4 - 18\epsilon^2 x^4 + \dots}{6(x-1)x^3(x+1)(x^2+1)(\epsilon-1)(3\epsilon-2)} & \dots & \dots & 0 & 0 & 0 & 0 \\ \frac{2(x-1)(x+1)\epsilon(2\epsilon-1)}{x^2(4\epsilon-1)} & 0 & 0 & 0 & \dots & \dots & 0 & 0 \\ 0 & 0 & 0 & 0 & \dots & \dots & 0 & 0 \\ 0 & \frac{\epsilon^2 x^4 - \epsilon x^4 - 2\epsilon^2 x^2 + 18\epsilon x^2 - 12x^2 + \epsilon^2 - \epsilon}{2(x-1)x(x+1)(x^2+1)(2\epsilon-1)} & \dots & \dots & 0 & 0 & \dots & \dots \\ 0 & -\frac{(x-1)(x+1)(\epsilon^2 x^4 - \epsilon x^4 - 26\epsilon^2 x^2 + 34\epsilon x^2 - 12x^2 + \epsilon^2 - \epsilon)}{2x^3(x^2+1)(3\epsilon-2)} & \dots & \dots & 0 & 0 & \dots & \dots \end{array} \right)$$

Example

After the change of functions:

$$\varepsilon \begin{pmatrix} \frac{2(x^2+1)}{(x^2-1)x} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{2(x^2+1)}{(x^2-1)x} & \frac{1}{x} & 0 & 0 & 0 & 0 & 0 \\ 0 & -\frac{4}{x} & 0 & -\frac{1}{x} & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{12}{x} & -\frac{6(x^2+1)}{(x^2-1)x} & 0 & 0 & 0 & 0 \\ \frac{1}{x} & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{2}{x} & \frac{2(x^2+1)}{(x^2-1)x} & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & \frac{2(x^2+1)}{(x^2-1)x} & -\frac{2}{x} \\ 0 & \frac{4}{x} & 0 & \frac{1}{x} & 0 & 0 & \frac{2}{x} & -\frac{2(x^2-1)}{(x^2+1)x} \end{pmatrix}$$

Problem formulation

Given a system

$$\partial \mathbf{J}(x) / \partial x = \mathbb{M}(x, \varepsilon) \mathbf{J}(x)$$

is it possible and how to find a change of functions reducing the system to ε -form

$$\partial \tilde{\mathbf{J}}(x) / \partial x = \varepsilon \sum_k \frac{\mathbb{S}_k}{x - x_k} \tilde{\mathbf{J}}(x),$$

i.e., is it possible and how to find such $\mathbb{T}(x, \varepsilon)$ that

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Approaches so far:

- Using ad hoc arguments, e.g., finding homogeneous integrals from Feynman parametrization (Henn, 2013, 2014).
- Applying a regular procedure when luckily hitting a special form of the initial matrix \mathbb{M} (Gehrmann et al., 2014), (Argeri et al., 2014). E.g., when $\mathbb{M}(x, \varepsilon) = \mathbb{M}_0(x) + \varepsilon \mathbb{M}_1(x)$

Algorithm of reduction to ε -form (R.L. 2015)

Stage 1. Eliminating higher-order poles

Input: Rational matrix $\mathbb{M}(x, \varepsilon)$

Output: Rational matrix with only simple poles (*Fuchsian* singularities) on the extended complex plane, $\mathbb{M}(x, \varepsilon) = \sum_k \frac{\mathbb{M}_k(\varepsilon)}{x-x_k}$.

Stage 2. Normalizing eigenvalues

Input: Matrix from the previous step, $\mathbb{M}(x, \varepsilon) = \sum_k \frac{\mathbb{M}_k(\varepsilon)}{x-x_k}$.

Output: Matrix of the same form, but with the eigenvalues of all $\mathbb{M}_k(\varepsilon)$ confined to unit interval $(-1/2, 1/2]$.

Stage 3. Factoring out ε

Input: Matrix from the previous step.

Output: Matrix in ε -form, $\mathbb{M}(x, \varepsilon) = \varepsilon \sum_k \frac{\mathbb{S}_k}{x-x_k}$

Reduction to ε -form

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- Almost. In particular, Barkatou&Pfluegel algorithm eliminates higher-order poles in all **finite points** giving $\mathbb{M}(x) = \sum_k \frac{\mathbb{M}_k}{x-x_k} + P(x)$, where $P(x)$ is a polynomial.

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- Why not try to do better — get rid of $P(x)$?
- Not always possible due to negative solution of the Riemann-Hilbert problem by Bolibrukh(Bolibrukh,1989).
- **No algorithms for global reduction (including infinity point) so far.**

Idea of reduction

Balance transformation

- Both reduction to Fuchsian form and normalization of the matrix residues are based on the following transformation

$$\mathbb{T}(x) = \mathcal{B}(\mathbb{P}, x_1, x_2 | x) \stackrel{\text{def}}{=} \bar{\mathbb{P}} + \frac{x - x_2}{x - x_1} \mathbb{P},$$

where \mathbb{P} is some projector and $\bar{\mathbb{P}} = \mathbb{I} - \mathbb{P}$. When $x_1 = \infty$ or $x_2 = \infty$ omit denominator or numerator, respectively.

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- Classical algorithms put $x_2 = \infty$ and try to construct \mathbb{P} improving system property at x_1 .
- In a long sequence of such transformations the system is reduced in all finite points, but behaviour at $x = \infty$ is **totally spoiled**.

Idea of global reduction

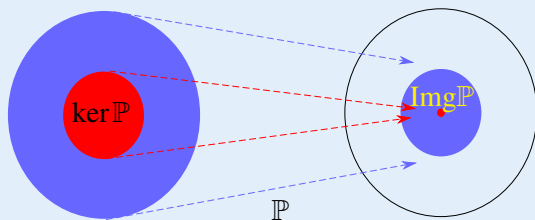
Scrutinizing Barkatou&Pfluegel algorithm.

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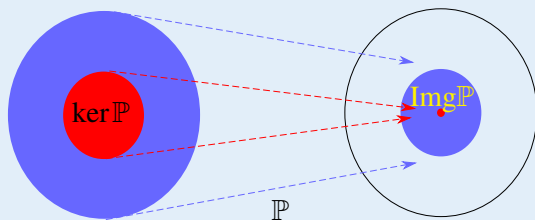
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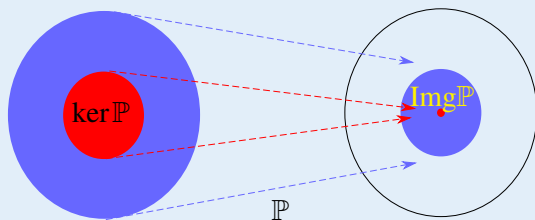
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- Idea of global reduction: use the above freedom to keep system properties at x_2 under control.



Stages 2 & 3: Factoring out ε

After Stage 2 we should have

$$\mathbb{M}(x, \varepsilon) = \sum_k \frac{\mathbb{M}_k(\varepsilon)}{x - x_k},$$

such that all eigenvalues of all “residues” $\mathbb{M}_k(\varepsilon)$ are $\propto \varepsilon$. We need to find an x -independent transformation $\mathbb{T}(\varepsilon)$, such that

$$\mathbb{T}^{-1}(\varepsilon) \mathbb{M}_k(\varepsilon) \mathbb{T}(\varepsilon) = \varepsilon \mathbb{S}_k$$

How can we do it without knowing \mathbb{S}_k in r.h.s.?

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Stage 3. Trick: write it twice

$$\mathbb{T}^{-1}(\varepsilon) \frac{\mathbb{M}_k(\varepsilon)}{\varepsilon} \mathbb{T}(\varepsilon) = \mathbb{S}_k = \mathbb{T}^{-1}(\mu) \frac{\mathbb{M}_k(\mu)}{\mu} \mathbb{T}(\mu)$$

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Linear system for matrix elements of $\mathbb{T}(\varepsilon, \mu) = \mathbb{T}(\varepsilon) \mathbb{T}^{-1}(\mu)$

$$\frac{\mathbb{M}_k(\varepsilon)}{\varepsilon} \mathbb{T}(\varepsilon, \mu) = \mathbb{T}(\varepsilon, \mu) \frac{\mathbb{M}_k(\mu)}{\mu}$$

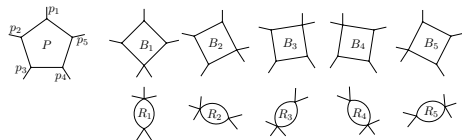
What may go wrong

- At stage 1 and 2 we might fail to construct \mathbb{P} with required properties due to the restriction $\text{Im}g^{\mathbb{P}} \cap \ker \mathbb{P} = \{0\}$. This is naturally associated with obstructions to positive solution of Hilbert's 21st problem. In particular, if some monodromy matrix is diagonalizable, we can always balance with the corresponding point.
- Eigenvalues of matrix residues after Stage 1 might be not of the form $n + \alpha\varepsilon$. In particular, it often happens that n is half-integer in a pair of points x_1 and x_2 . One can then get rid of half-integer n by passing to $y = \sqrt{(x - x_1)/(x - x_2)}$, so that $x = (x_1 - x_2 y^2)/(1 - y^2)$ is a rational substitution.
- Third step might result in degenerate matrix $\mathbb{T}(\varepsilon, \mu)$ for any μ . E.g. $\mathbb{T}(\varepsilon, \mu) = 0$.
- Computational complexity might be overwhelming. One should use block-triangular structure of the equations.

Example applications of ε -form

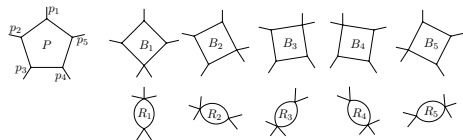
Onshell pentagon in d dimensions (M. Kozlov & R.L., 2016)

Master integrals



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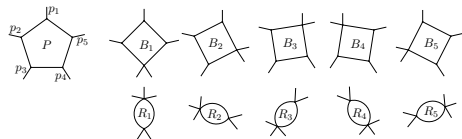
New functions \tilde{P} , \tilde{B} , \tilde{R}

$$P = \frac{\sqrt{\Delta}}{s_1 s_2 s_3 s_4 s_5} \left(\tilde{P} - \sum_{i=1}^5 \frac{1}{2} \left(1 - \frac{r_i}{\sqrt{\Delta}} \right) \tilde{B}_i \right),$$

$$B_i = \frac{1}{s_{i+2} s_{i-2}} \tilde{B}_i, \quad R_i = \frac{\epsilon}{2(1-2\epsilon)} \tilde{R}_i.$$

Onshell pentagon in d dimensions (M. Kozlov & R.L., 2016)

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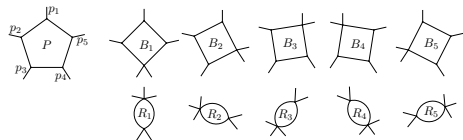
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Equation for new functions (ε -form)

$$d\tilde{P} = -\varepsilon \left\{ \tilde{P} d(\log S) + \sum_{i=1}^5 \left[-\tilde{B}_i d\left(\log\left(1 + \frac{r_i}{\sqrt{\Delta}}\right)\right) + \tilde{R}_i d\left(\log\left(\frac{(\sqrt{\Delta} + r_i)(r_{i+2} + r_{i-2})}{(\sqrt{\Delta} + r_{i+2})(\sqrt{\Delta} + r_{i-2})}\right)\right) \right] \right\},$$

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$$B_i = \frac{1}{s_{i+2} s_{i-2}} \tilde{B}_i, \quad R_i = \frac{\epsilon}{2(1-2\epsilon)} \tilde{R}_i.$$

Equation for new functions (ϵ -form)

$$d\tilde{P} = -\epsilon \left\{ \tilde{P} d(\log S) + \sum_{i=1}^5 \left[-\tilde{B}_i d\left(\log\left(1 + \frac{r_i}{\sqrt{\Delta}}\right)\right) + \tilde{R}_i d\left(\log\left(\frac{(\sqrt{\Delta} + r_i)(r_{i+2} + r_{i-2})}{(\sqrt{\Delta} + r_{i+2})(\sqrt{\Delta} + r_{i-2})}\right)\right) \right] \right\},$$

Result for $s_i < 0$

$$P^{(6-2\epsilon)}(s_1, s_2, s_3, s_4, s_5) = \frac{2\Gamma(1-\epsilon)^2 \Gamma(1+\epsilon)}{\epsilon \Gamma(1-2\epsilon)} \left[\frac{2\pi^{3/2} \Gamma[1/2-\epsilon]}{\Gamma[1-\epsilon] \sqrt{\Delta}} (-S)^{-\epsilon} \right. \\ \left. + \sum_{i=1}^5 (-s_i)^{-\epsilon} \int_1^{\infty} \frac{dt}{t} t^\epsilon \operatorname{Re} \frac{1}{b_i(t)} \left\{ \arctan \frac{b_i(t)}{r_i} - \arctan \frac{b_i(t)}{r_{i+2}} - \arctan \frac{b_i(t)}{r_{i-2}} + \frac{\pi}{2} [\operatorname{sign} r_{i+2} + \operatorname{sign} r_{i-2} - \operatorname{sign} r_i - \operatorname{sign}(r_{i+2} + r_{i-2})] \right\} \right].$$

Onshell pentagon in d dimensions

A few words about analytical continuation

- 1 Initially the result is obtained in Euclidean region $s_i < 0$.

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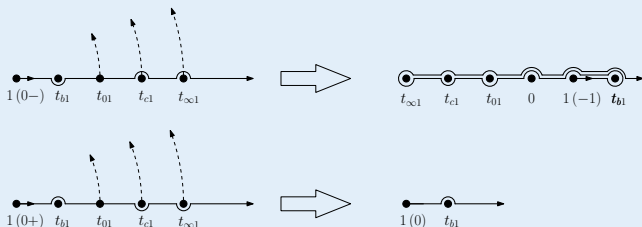
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- 3 Feynman prescription: $P(s_1, s_2, s_3, s_4, s_5)$ is analytic in the region $\text{Im}s_i > 0$ So, we may move between the regions via “upper octant” of \mathbb{C}^5 .

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- $P(s_1, s_2, s_3, s_4, s_5)$ is given by one-fold integral with branching integrand. We should track movement of branching points with changing of s_i .



Onshell pentagon in d dimensions

Result of analytical continuation

$$\begin{aligned}
 p^{(6-2\varepsilon)}(s_1, s_2, s_3, s_4, s_5) &= \frac{2\Gamma(1-\varepsilon)^2\Gamma(1+\varepsilon)}{\varepsilon\Gamma(1-2\varepsilon)} \left[\Theta(s_i s_j > 0) \frac{2\pi^{3/2}\Gamma[1/2-\varepsilon]}{\Gamma[1-\varepsilon]\sqrt{\Delta}} (-S-i0)^{-\varepsilon} \right. \\
 &+ \left. \sum_{i=1}^5 (-s_i - i0)^{-\varepsilon} \int_1^\infty \frac{dt}{t} t^\varepsilon \operatorname{Re} \frac{1}{b_i(t)} \left\{ \arctan \frac{b_i(t)}{r_i} - \arctan \frac{b_i(t)}{r_{i+2}} - \arctan \frac{b_i(t)}{r_{i-2}} + \frac{\pi}{2} [\operatorname{sign} r_{i+2} + \operatorname{sign} r_{i-2} - \operatorname{sign} r_i - \operatorname{sign}(r_{i+2} + r_{i-2})] \right\} \right], \\
 r_n &= \sum_{i=0}^4 (-1)^i s_{n+i} s_{n+i+1}, \quad \Delta = \det(2p_i \cdot p_j |_{i,j=1,\dots,4}) = \sum_{i=1}^5 r_i r_{i+2}, \quad S = 4s_1 s_2 s_3 s_4 s_5 / \Delta, \quad b_i(t) = \sqrt{(St/s_i - 1)\Delta + i0}.
 \end{aligned}$$

Note 1: Analytical continuation is **not** reduced to the replacement $s_i \rightarrow s_i + i0$.

Note 2: arbitrary order of ε -expansion is one-fold integral of elementary functions.

Electromagnetic e^+e^- -pair production in ion collisions

Total Born cross section (R.L.& K. Mingulov, 2016)

At $\gamma = 1/\sqrt{1-\beta^2} \gg 1$ up to power suppressed (w.r.t. $1/\gamma$) terms Racah obtained in 1936 (At that time — heroic deed!)

$$\sigma = \frac{(Z_1\alpha)^2(Z_2\alpha)^2}{\pi m^2} \left[\frac{28L_0^3}{27} - \frac{178L_0^2}{27} + \left(\frac{370}{27} + \frac{7\pi^2}{27} \right) L_0 + \frac{7\zeta_3}{9} - \frac{13\pi^2}{54} - \frac{116}{9} \right], \quad L_0 = \log(2\gamma).$$

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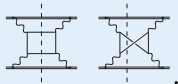
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Simple application of presented approach: exact in γ calculation.

- Three-loop cut diagrams:



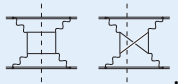
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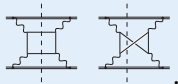
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Simple application of presented approach: exact in γ calculation.



- Three-loop cut diagrams:
- IBP reduction $\rightarrow 8$ masters.
- DE reduction:

$$\frac{\partial}{\partial x} \tilde{\mathbf{J}} = \varepsilon \left[\frac{1}{x} M_0 + \frac{1}{x-1} M_1 + \frac{1}{x+1} M_2 \right] \tilde{\mathbf{J}}, \quad x = \frac{1-\beta}{1+\beta},$$

$$M_0 = \begin{bmatrix} -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 3 & 3 & 0 & 0 \\ 0 & 0 & 0 & -1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 2 & 1 & 0 & 1 & 1 \end{bmatrix}, \quad M_1 = \text{diag}(2, 0, 2, 2, -6, 0, 2, 0), \quad M_2 = \text{diag}(0, 0, 0, 0, 0, 0, 0, -2).$$

Electromagnetic e^+e^- -pair production in ion collisions

Exact in γ result

$$\sigma = \frac{(Z_1\alpha)^2(Z_2\alpha)^2}{\pi m^2} \left\{ -\frac{1-\beta^2}{12\beta^2} L^4 + \frac{2(23\beta^2-37)S_{3a}}{9\beta^2} + \frac{2(11\beta^2-25)S_{3b}}{9\beta^2} - \frac{26S_2}{9\beta} \right. \\ \left. - \frac{(\beta^6+217\beta^4-135\beta^2+45)L^2}{54\beta^6} + \frac{5(67\beta^4-48\beta^2+18)L}{27\beta^5} - \frac{2(78\beta^4-35\beta^2+15)}{9\beta^4} \right\},$$

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$$S_{3a} = \text{Li}_3\left(\frac{1-\beta}{1+\beta}\right) + L\text{Li}_2\left(\frac{1-\beta}{1+\beta}\right) - \frac{L^2}{2}\log\left(\frac{2\beta}{1+\beta}\right) - \frac{L^3}{12} - \zeta_3,$$

$$S_{3b} = \text{Li}_3\left(-\frac{1-\beta}{1+\beta}\right) + \frac{L}{2}\text{Li}_2\left(-\frac{1-\beta}{1+\beta}\right) + \frac{L^3}{24} - \frac{\pi^2L}{24} + \frac{3\zeta_3}{4},$$

$$S_2 = \text{Li}_2\left(-\frac{1-\beta}{1+\beta}\right) + L\log\left(\frac{\beta+1}{2}\right) - \frac{L^2}{4} + \frac{\pi^2}{12}, \quad L = \log\left(\frac{1+\beta}{1-\beta}\right).$$

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High-energy asymptotics:

$$\sigma = \frac{(Z_1\alpha)^2(Z_2\alpha)^2}{\pi m^2} \left\{ \frac{28L_0^3}{27} - \frac{178L_0^2}{27} + \left(\frac{370}{27} + \frac{7\pi^2}{27} \right) L_0 + \frac{7\zeta_3}{9} - \frac{13\pi^2}{54} - \frac{116}{9} \leftarrow \text{Racah results} \right. \\ \left. \text{First correction} \Rightarrow -\frac{1}{\gamma^2} \left[\frac{4L_0^4}{3} - \frac{98L_0^3}{27} + \frac{188L_0^2}{27} - \left(\frac{172}{27} + \frac{25\pi^2}{54} \right) L_0 - \frac{73\zeta_3}{18} + \frac{5\pi^2}{27} + \frac{43}{27} \right] + \dots \right\},$$

Electromagnetic e^+e^- -pair production in ion collisions

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$$\sigma = \frac{(Z_1\alpha)^2(Z_2\alpha)^2}{\pi m^2} \left\{ -\frac{1-\beta^2}{12\beta^2} L^4 + \frac{2(23\beta^2-37)S_{3a}}{9\beta^2} + \frac{2(11\beta^2-25)S_{3b}}{9\beta^2} - \frac{26S_2}{9\beta} \right. \\ \left. - \frac{(\beta^6+217\beta^4-135\beta^2+45)L^2}{54\beta^6} + \frac{5(67\beta^4-48\beta^2+18)L}{27\beta^5} - \frac{2(78\beta^4-35\beta^2+15)}{9\beta^4} \right\},$$

Low-energy asymptotics:

$$\sigma = \frac{296(Z_1\alpha)^2(Z_2\alpha)^2\beta^8}{55125\pi m^2} \left(1 + \frac{7708\beta^2}{3663} + \dots \right).$$

Note: highly suppressed as β^8 !

Summary

- IBP reduction +DE reduction to ε -form is the most powerful approach to multiscale (multi)loop problems.
- An algorithm of finding ε -form of the differential systems for multiloop integrals is developed.
- Some applications of this algorithm already appeared. Applications to perturbative QCD calculations are ongoing. Suggestions are welcome!

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Thank you!