

HLS and WPS used at the ESRF

David Martin

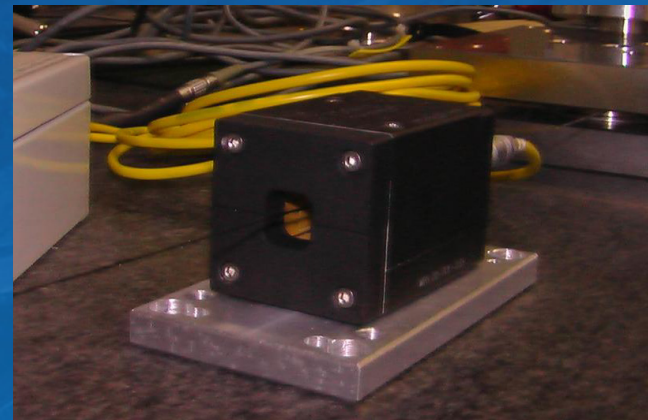
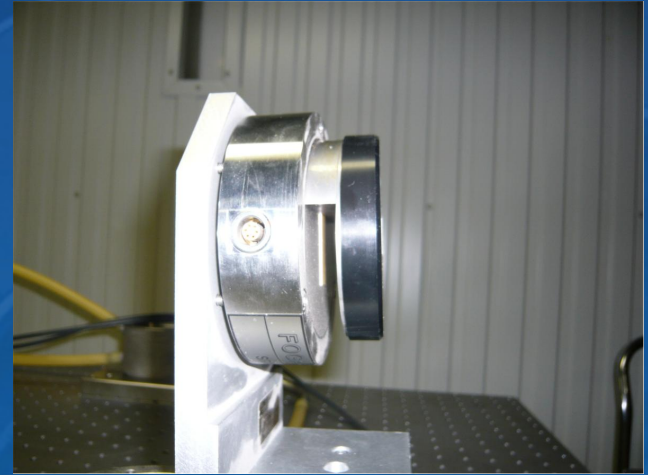
- to inventory the existing WPS and HLS sensors (*and what we do with them to establish context*);
- to record the means, methods and conditions of tests on these sensors;
- to define the tests to be performed on these sensors during the inter-comparison;
- to establish a basis for inter-comparison and envisage collaboration with your laboratory on this study.

Inventory of existing ESRF WPS sensors

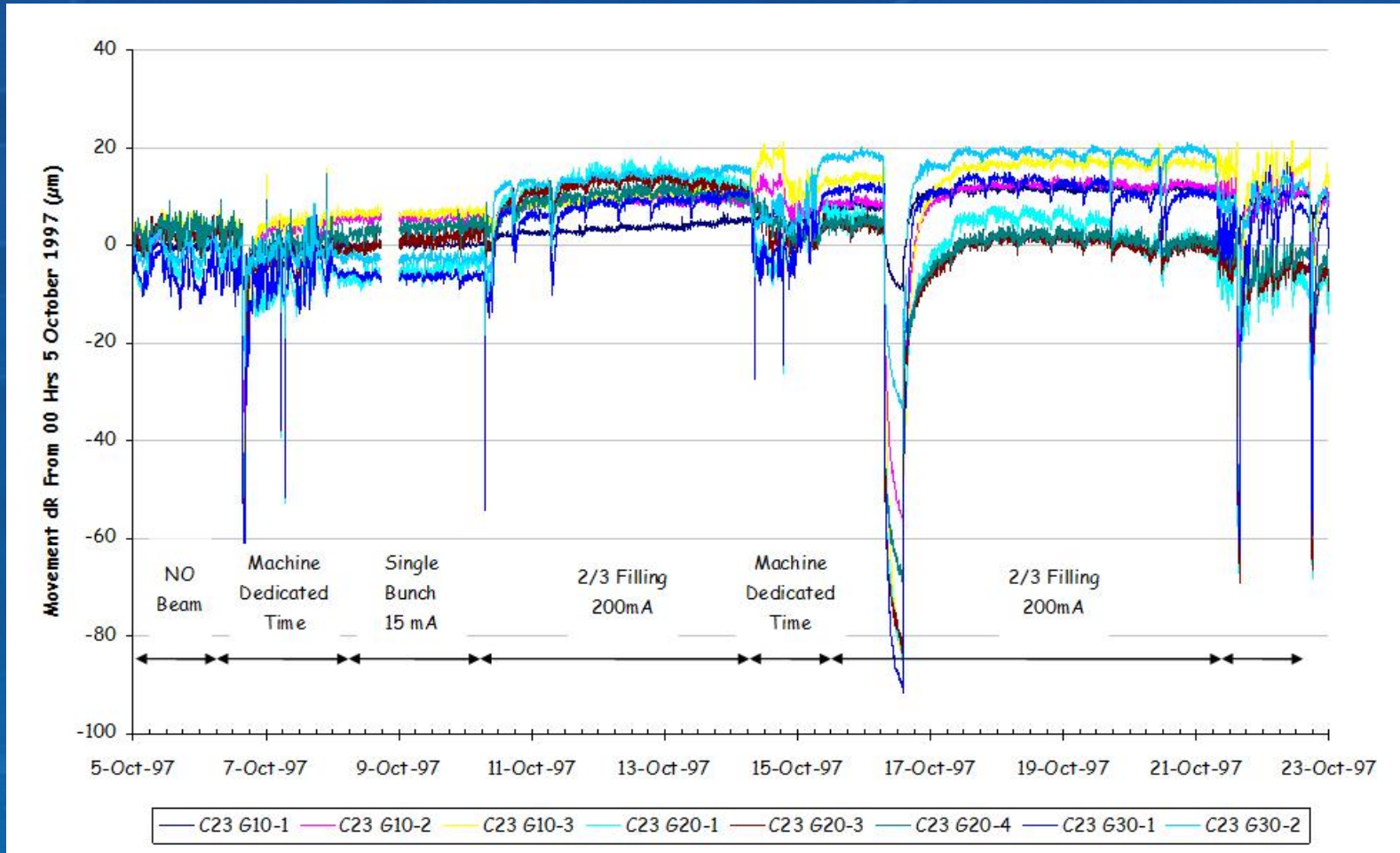
The ESRF has 18 single axis and 4 bi-axial WPS sensors.

The single axis system has been used to control planimetric movements of the ESRF SR magnet girders.

The biaxial system has been used to control the ESRF calibration bench carriage movements.



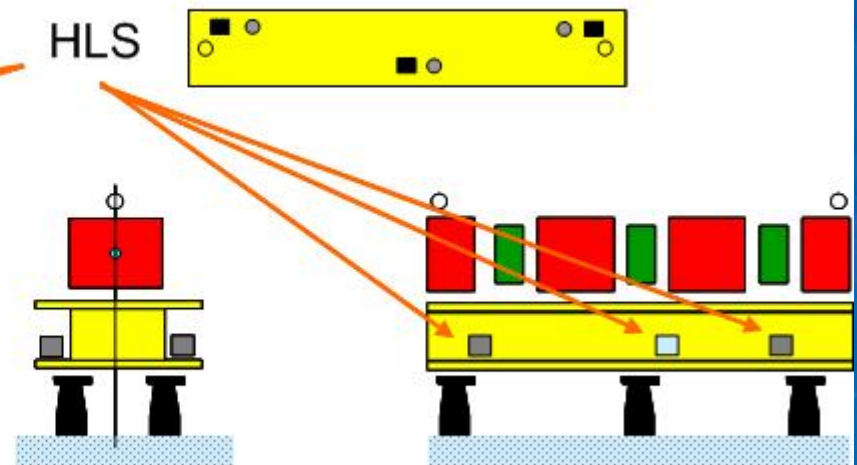
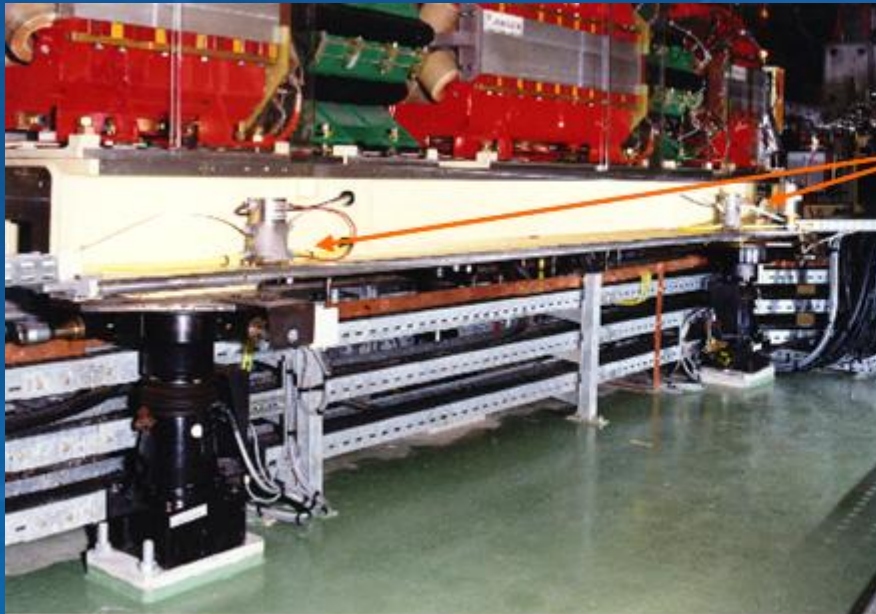
ESRF WPS sensors - SR Girder Movements



Inventory of existing ESRF HLS sensors

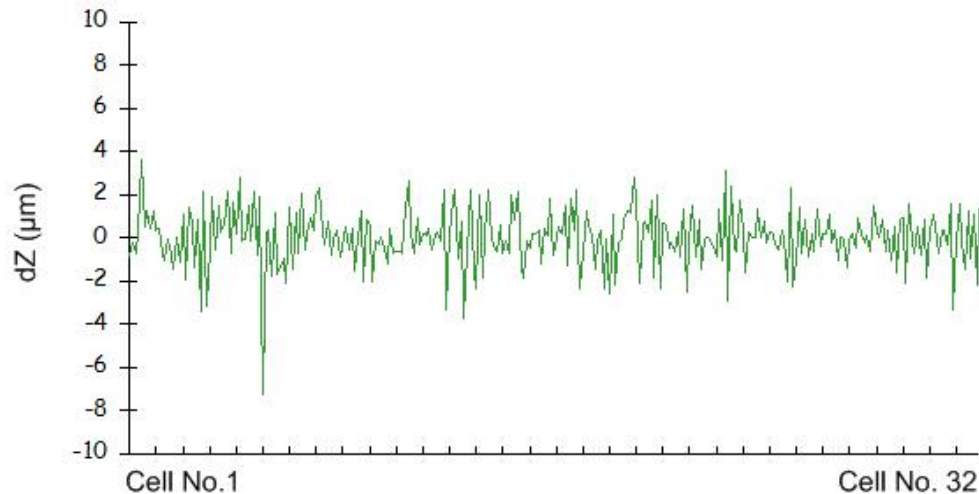
The ESRF has 288 'first' generation HLS sensors installed on the Storage Ring.

This system has been used since 1993 to control the periodic machine vertical realignment.



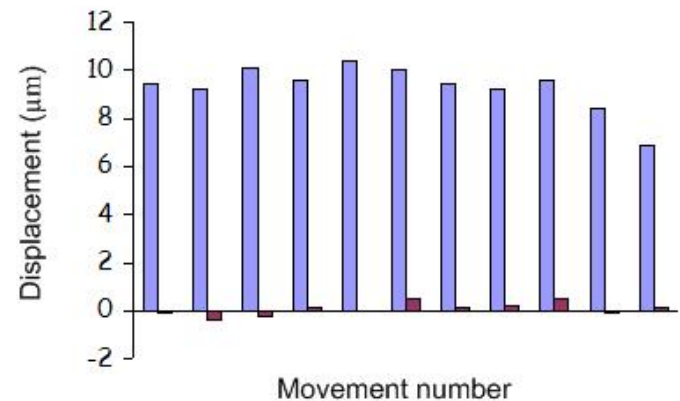
ESRF HLS sensors – ‘first generation’ Storage Ring realignment

Difference between the Jack Movements and HLS readings
Standard Deviation = 1.3 μm



Development around the SR

Jack Movements SR Beam Calibration
+10 μm movement standard deviation = 1 μm
Return to zero movement standard deviation = 0.3 μm



Inventory of existing HLS sensors



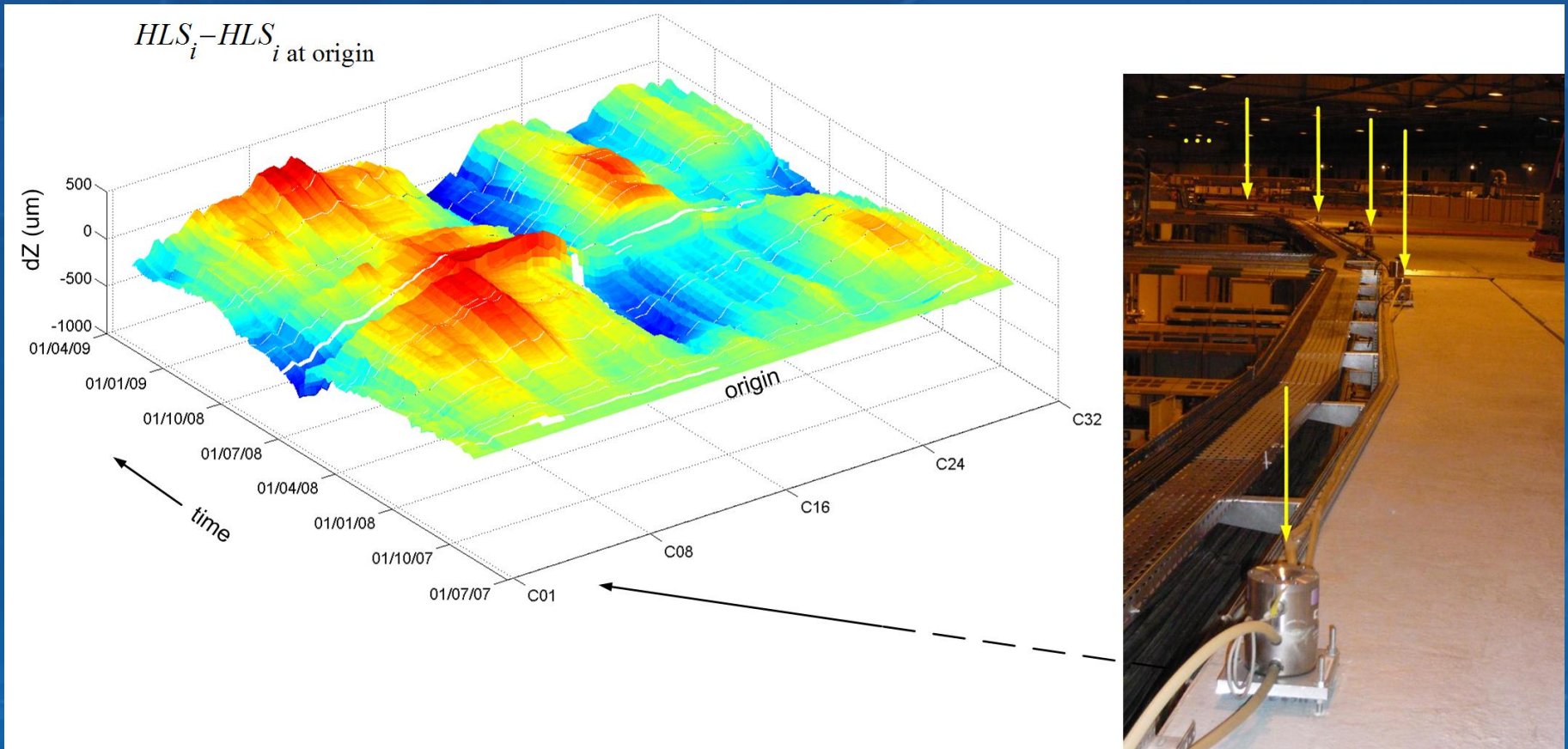
The ESRF has ~200 'second' generation HLS sensors.

This system is installed on the ESRF SR tunnel roof and on the beam lines.

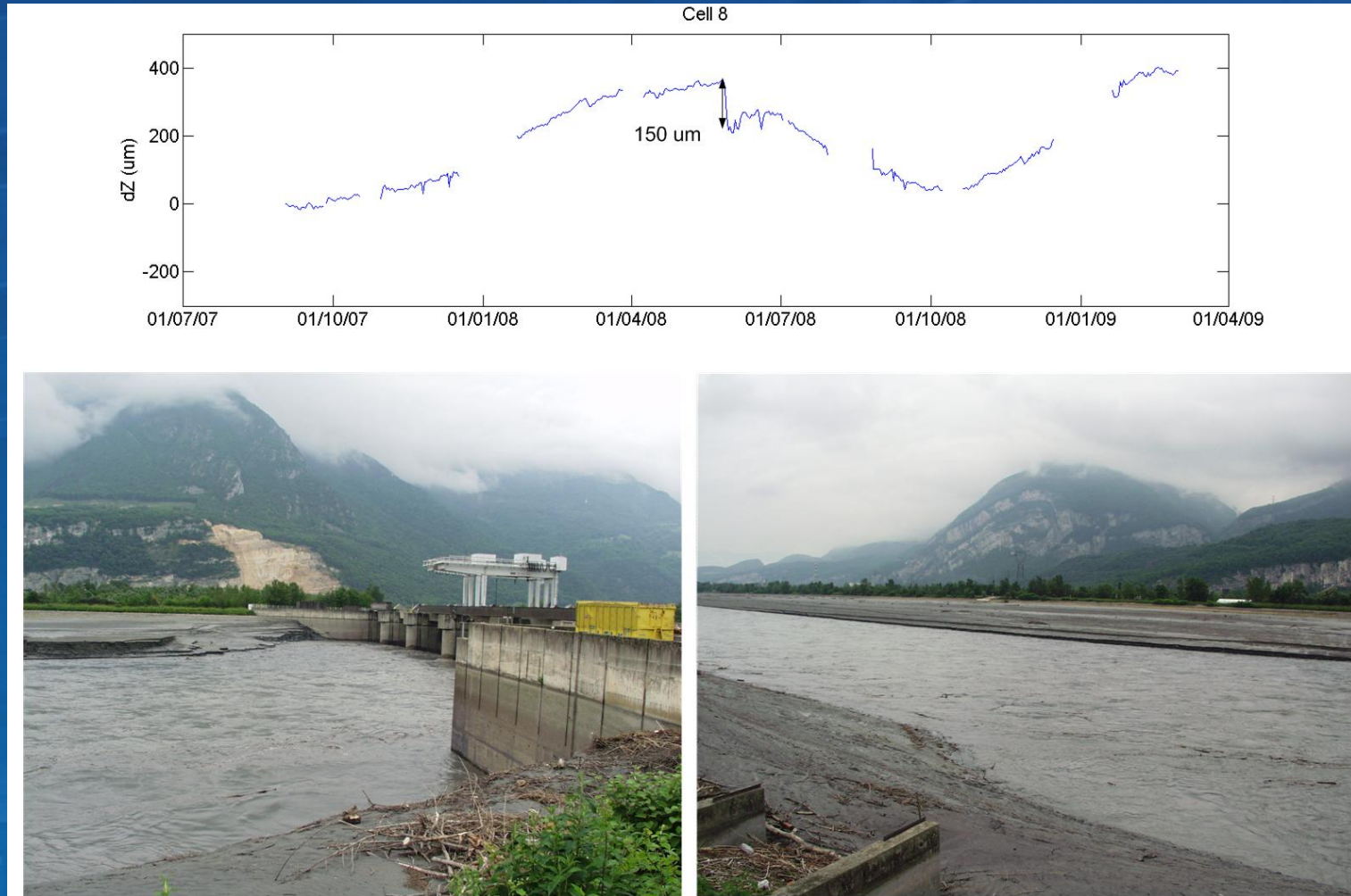
It is used to monitor long term site settlement.



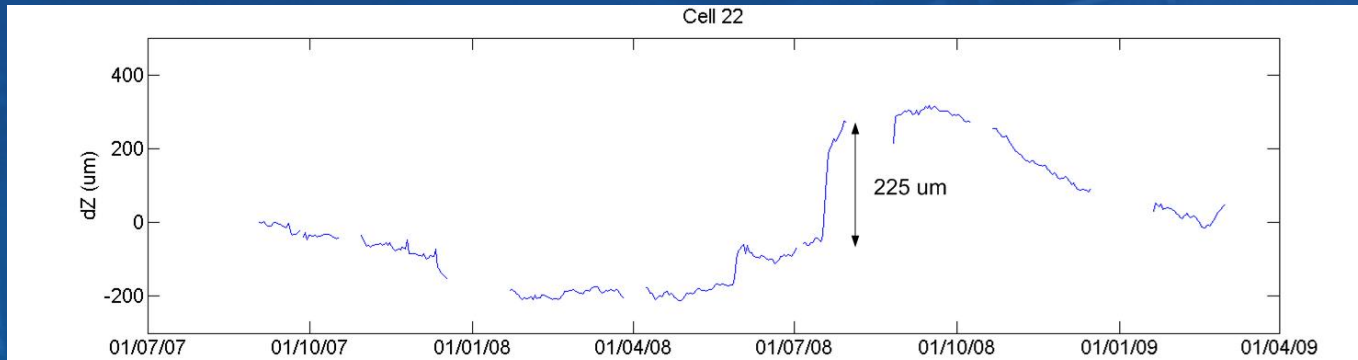
ESRF HLS sensors – ‘second generation’ site movements



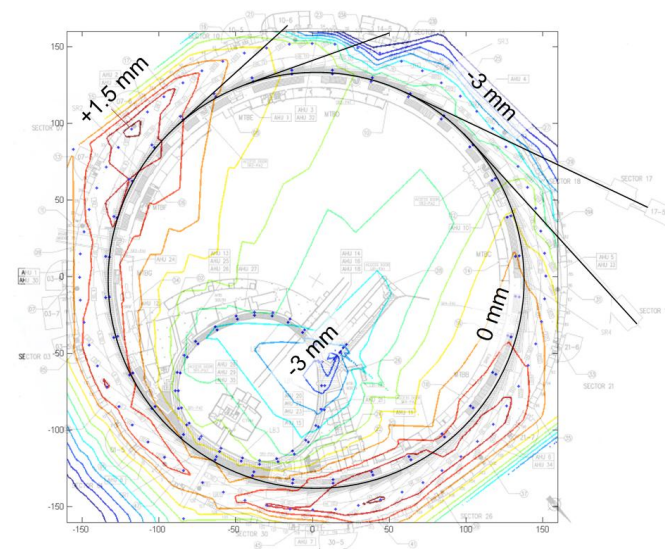
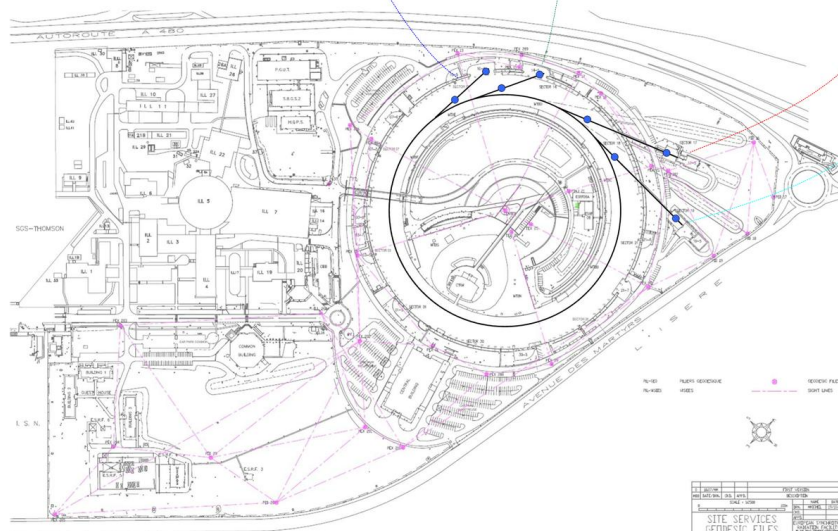
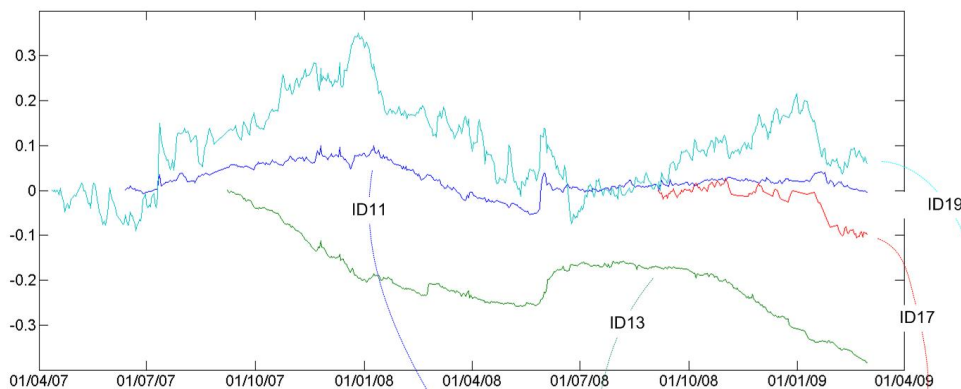
ESRF HLS sensors – ‘second generation’ site movements dam purge



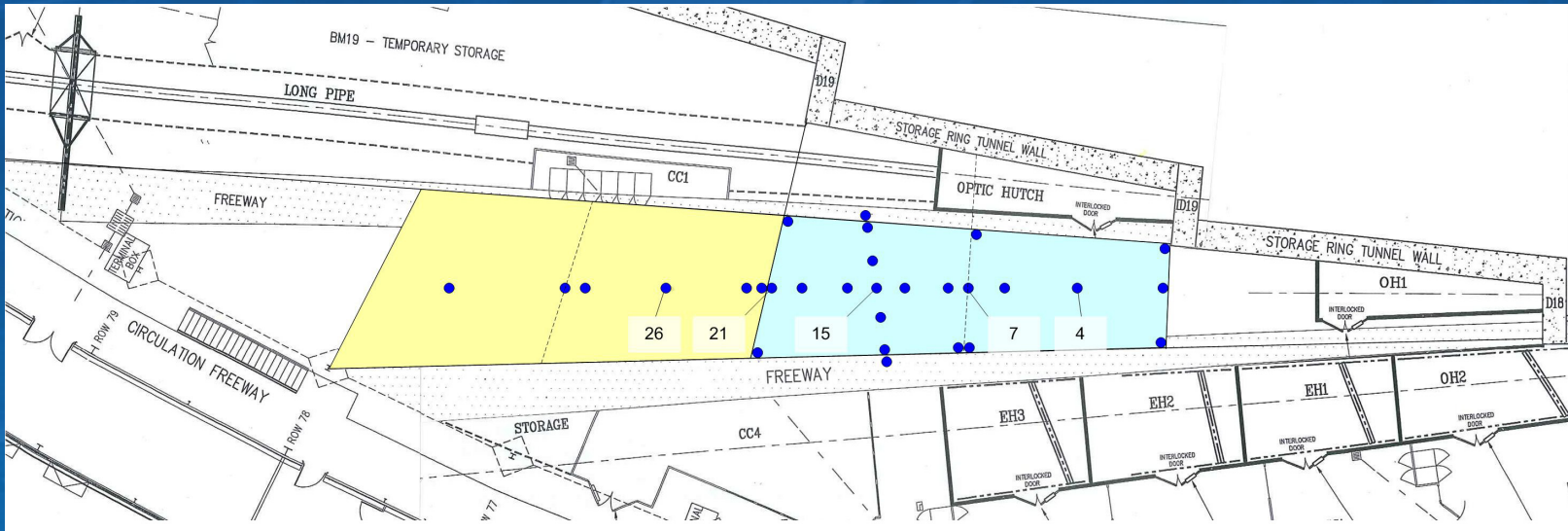
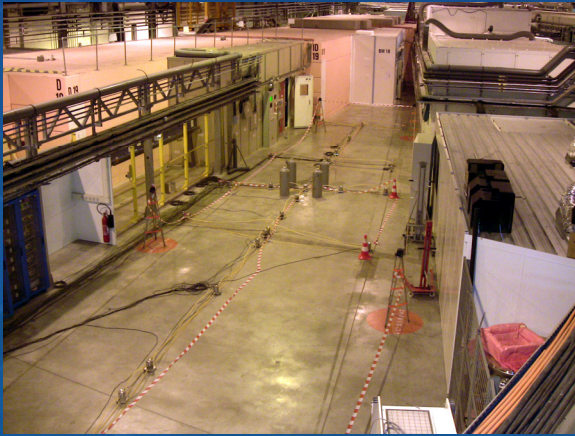
ESRF HLS sensors – ‘second generation’ site movements excavation



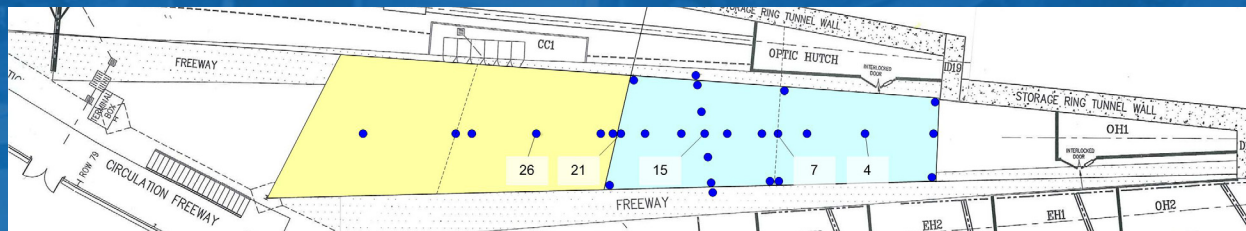
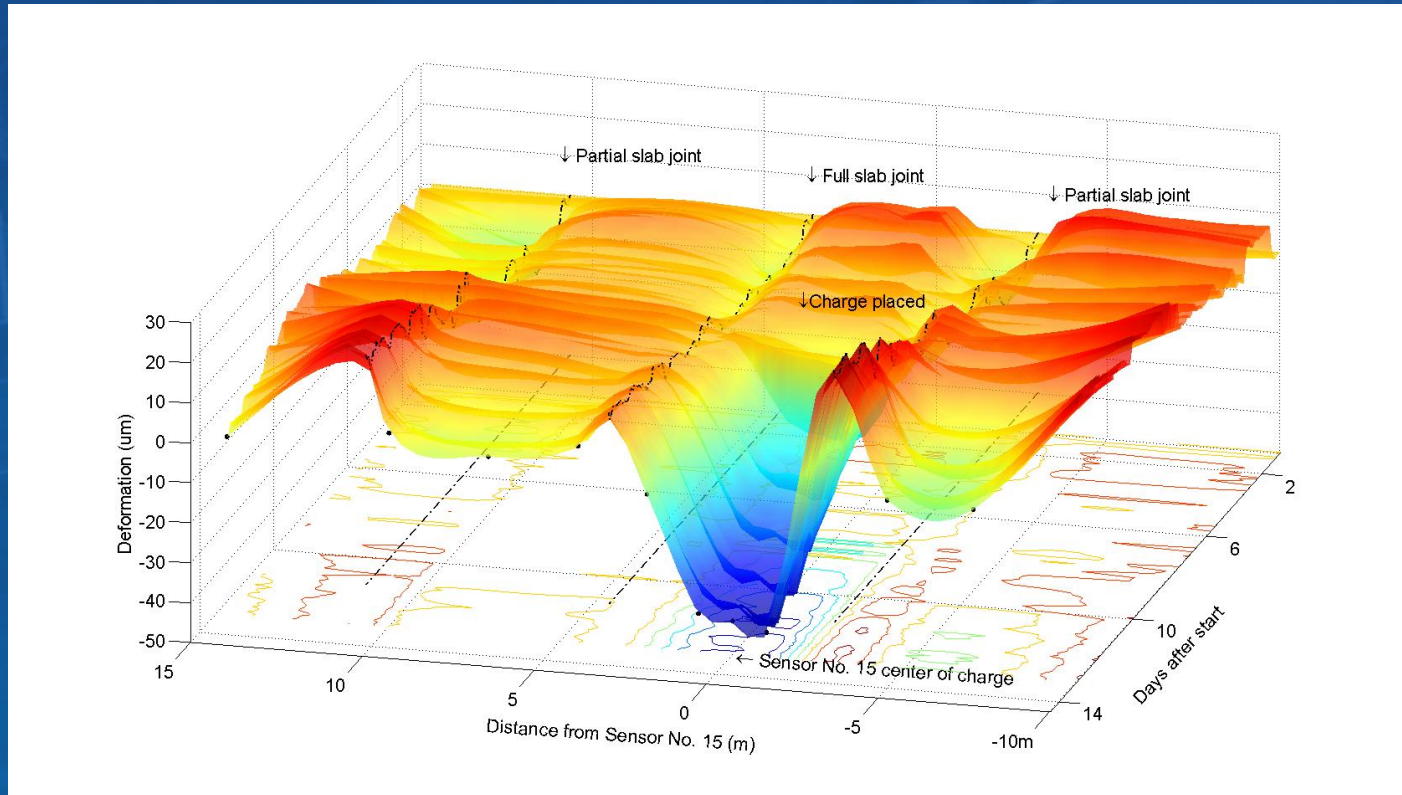
ESRF HLS sensors – ‘second generation’ long term site movements



ESRF HLS sensors – ‘second generation’ BM18 slab study



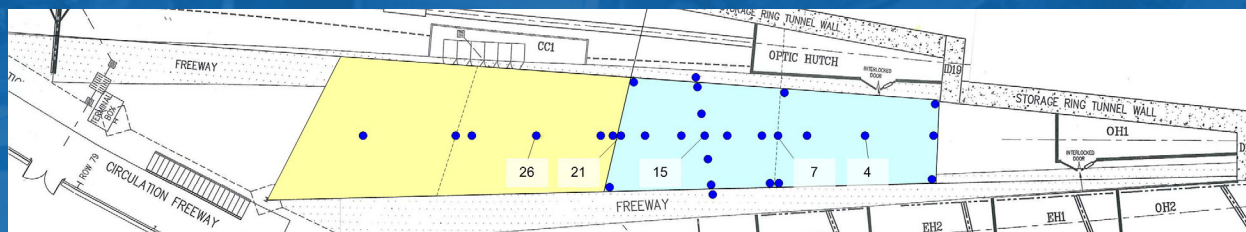
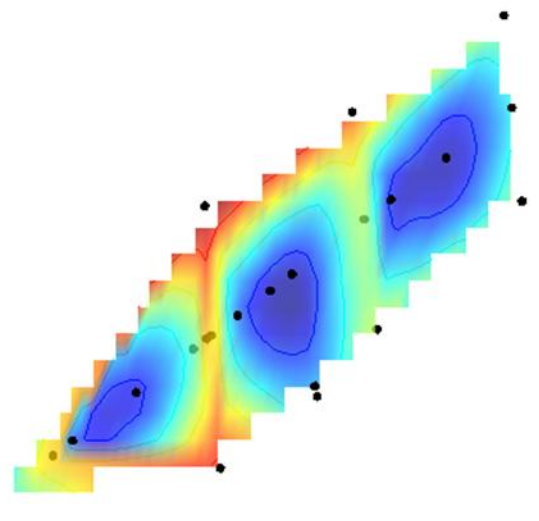
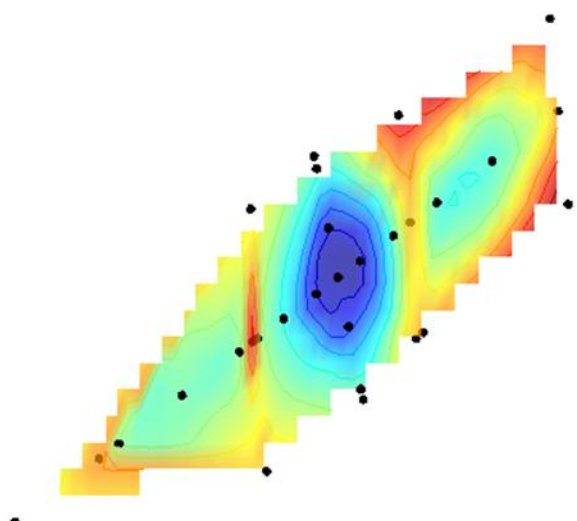
ESRF HLS sensors – ‘second generation’ BM18 slab study



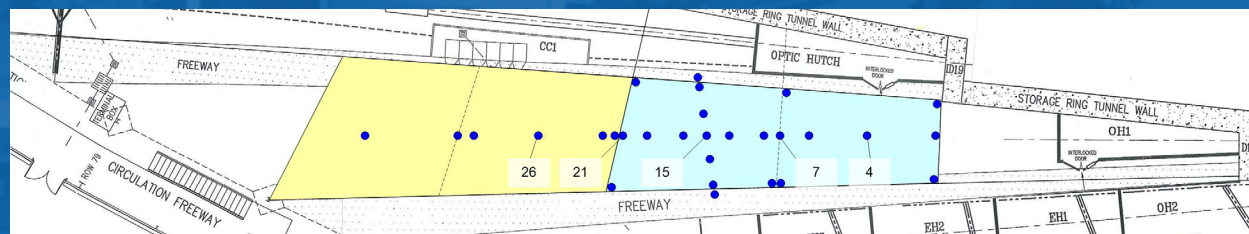
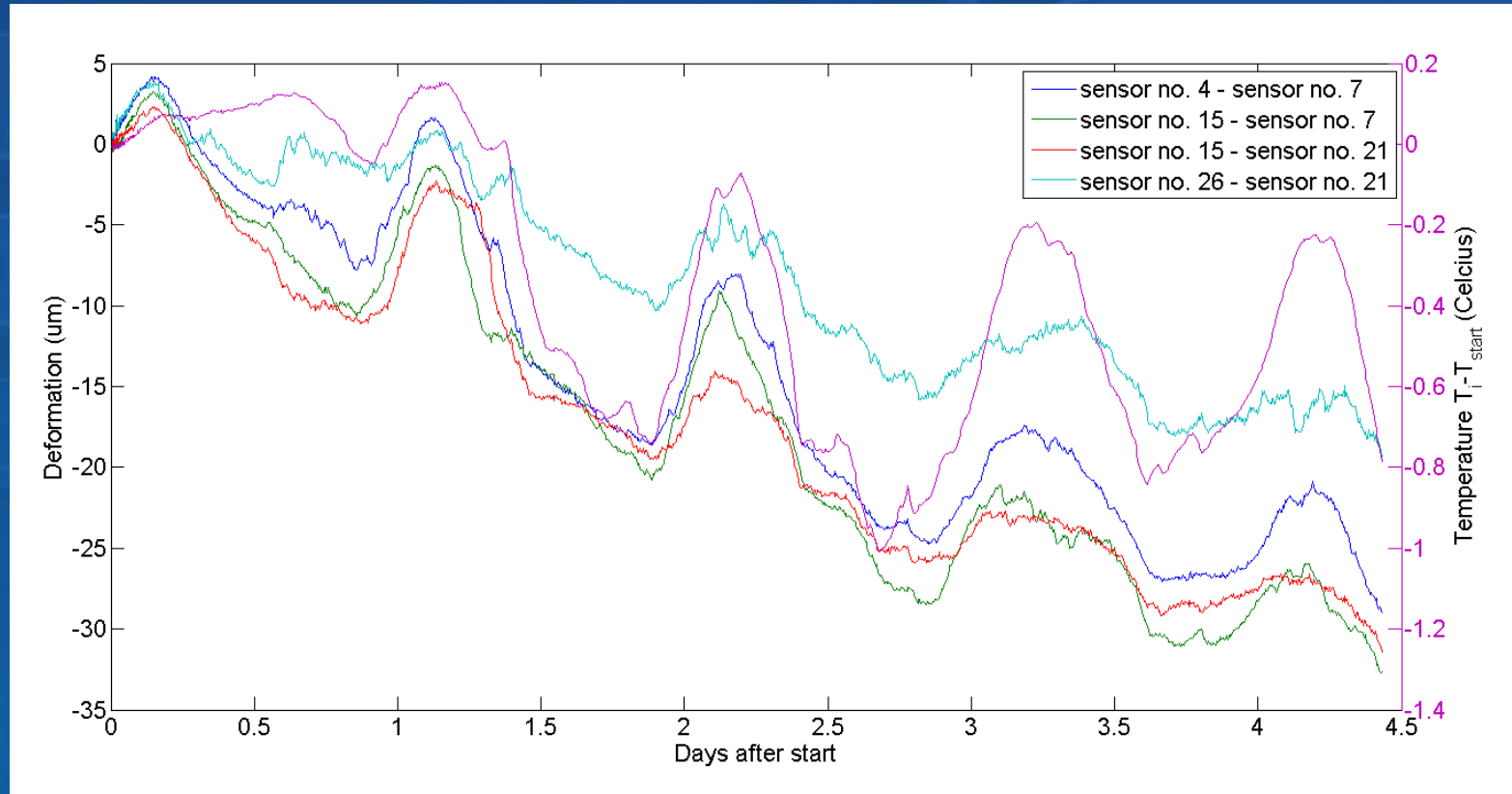
ESRF HLS sensors – ‘second generation’ BM18 slab study

February 2, 2009 - January 23, 2009

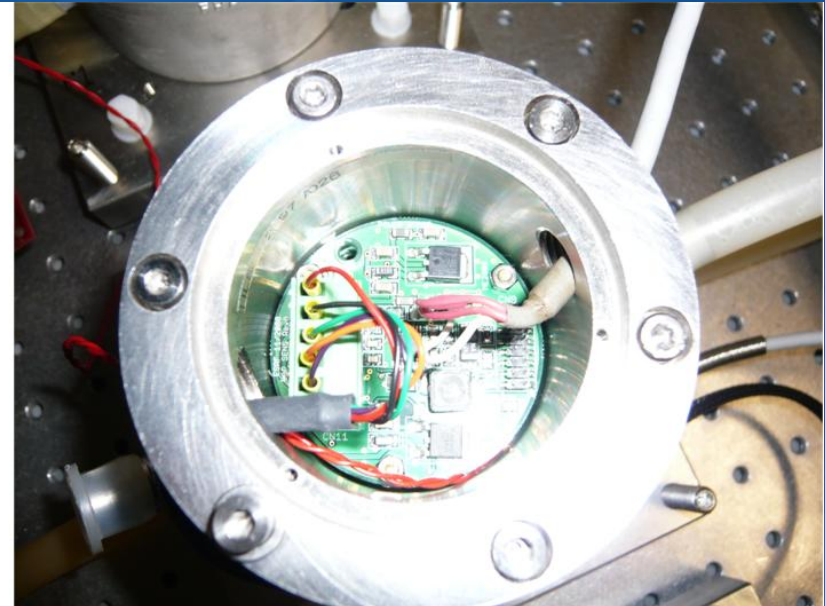
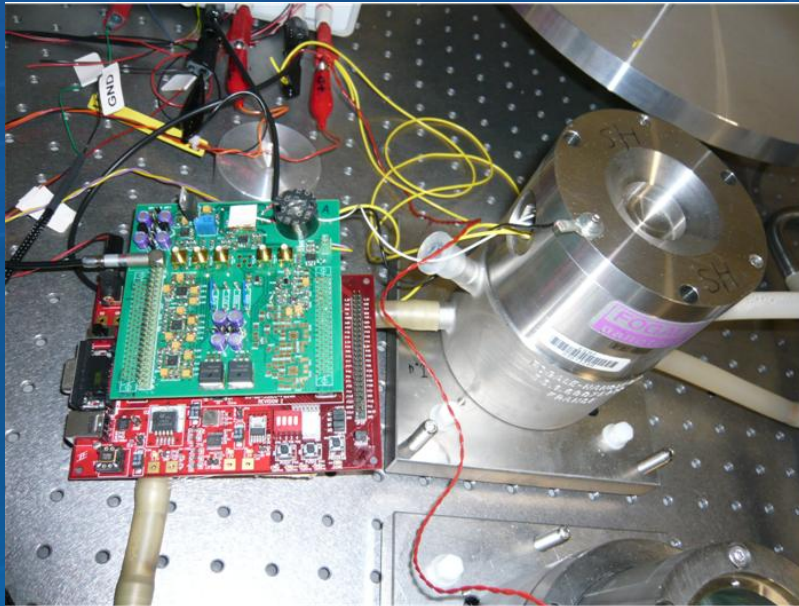
January 10, 2009 – December 24, 2009



ESRF HLS sensors – ‘second generation’ BM18 slab study



ESRF HLS sensors – ‘next generation’ digital capacitance electronic



Methods and conditions of tests on these systems - questions

How reliable are the measurements issued from these systems?

How can we test or calibrate them?

What is their uncertainty?

Are we speaking the same language?

What is our standard?



Methods and conditions of tests on these systems - uncertainty



Low accuracy
Low precision



Low accuracy
High precision



High accuracy
High precision

Error and Uncertainty

Error is the difference between the measured value and the true value of a measurement

Uncertainty of measurement is the doubt that exists about the result of any measurement. It is an expression of our confidence in it.

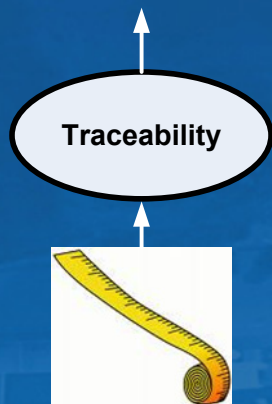
Methods and conditions of tests on these systems - traceability



... NIST F1, the world's best clock...

One of the pillars of instrument calibration and all legal metrology is the notion of traceability.

Traceability is a method of ensuring that a measurement (even with its uncertainties) is an accurate representation of what it is trying to measure.



Methods and conditions of tests on these systems - traceability



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The commonly accepted way to go about determining uncertainty in the metrology world follows the 'GUM' uncertainty framework.

This requires a *standard* or *etalon*.

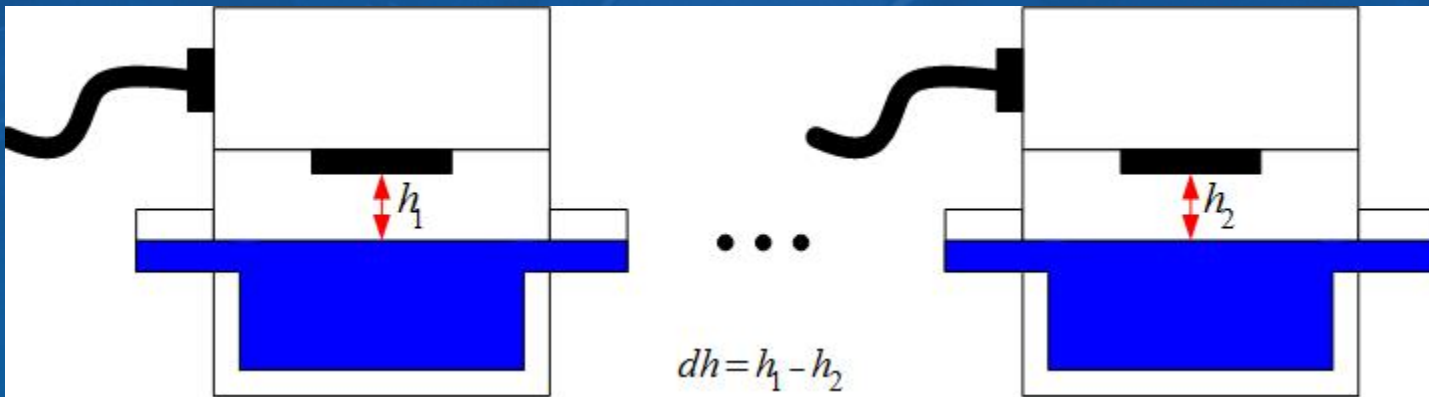
Uncertainties are divided into two categories:
Type A and *Type B*.

Type A : method of evaluation of uncertainty by the statistical analysis of series of observations,

Type B: method of evaluation of uncertainty by means other than the analysis of series of observations.

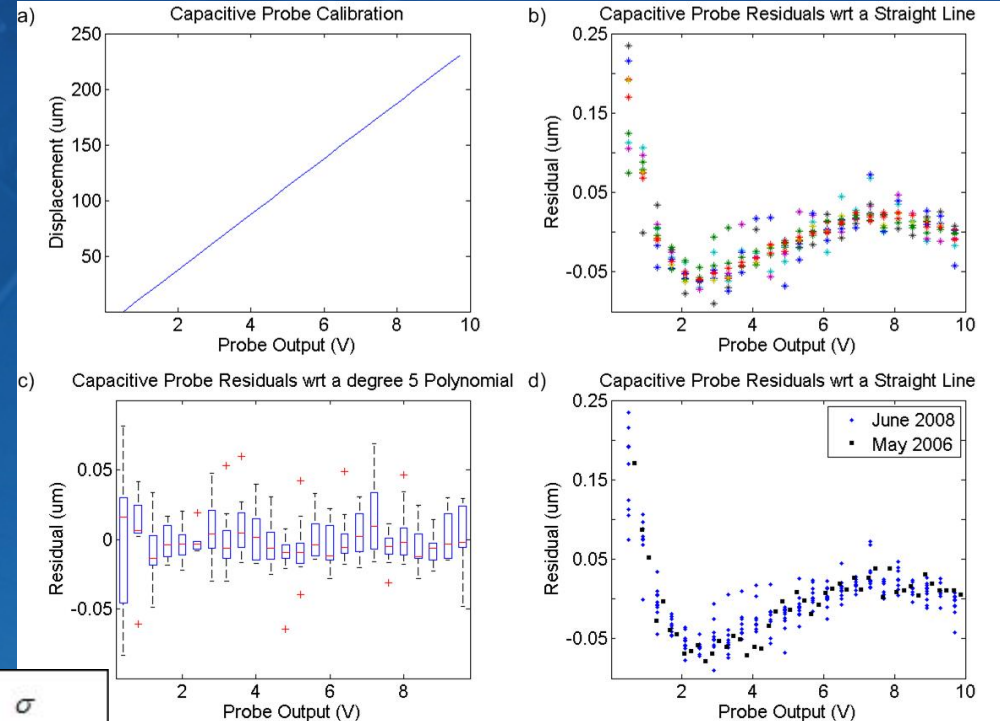
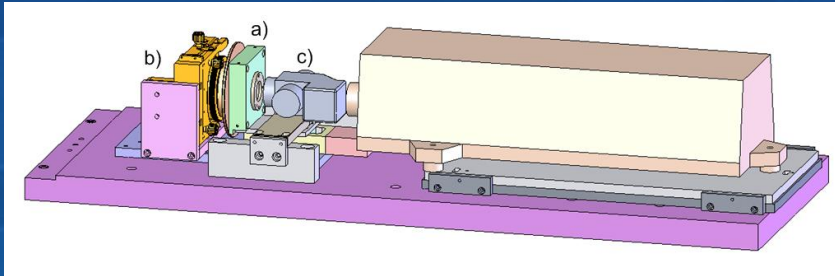
Methods and conditions of tests on these systems – HLS measurand

First what are we measuring - what is the measurand[†]?
 What is the principle of the measurement?



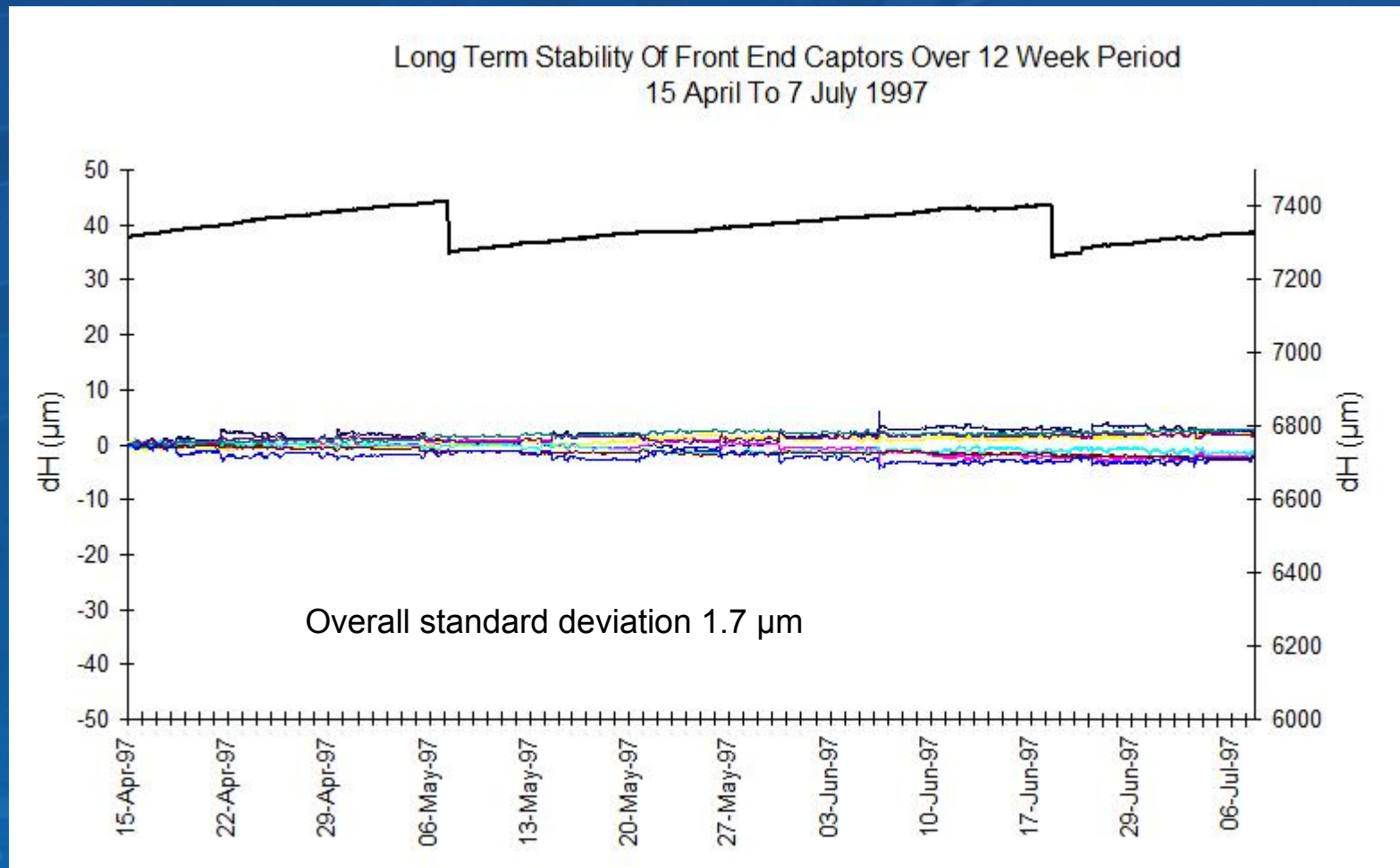
[†]Measurand: the quantity intended to be measured (VIM)

Uncertainty - example Type B for HLS probe calibration

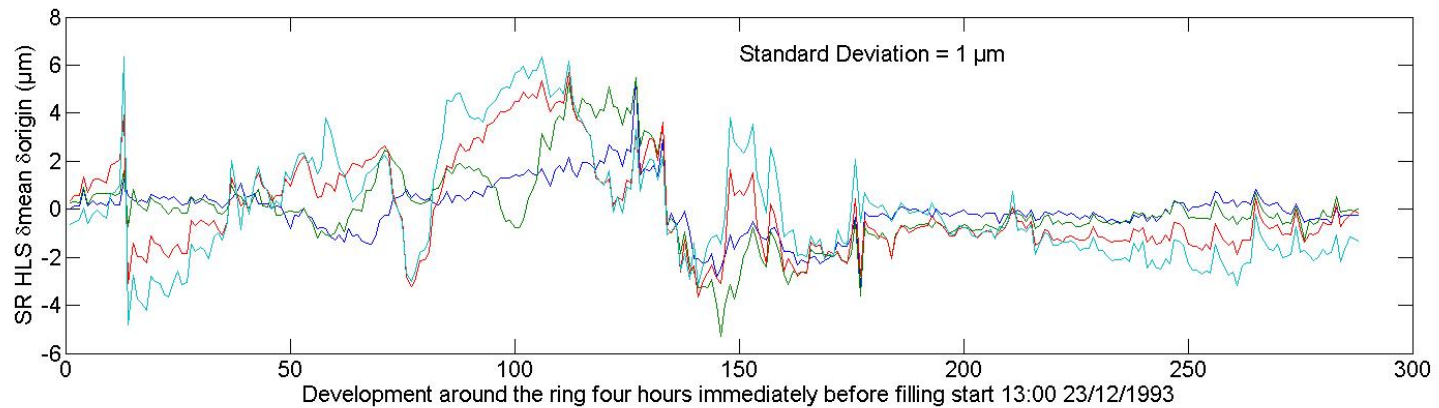
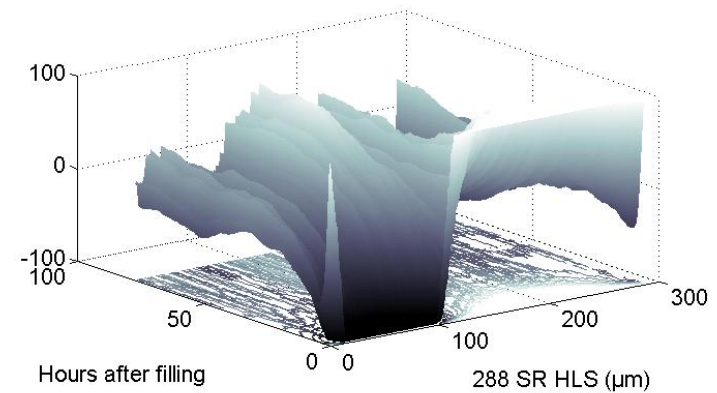
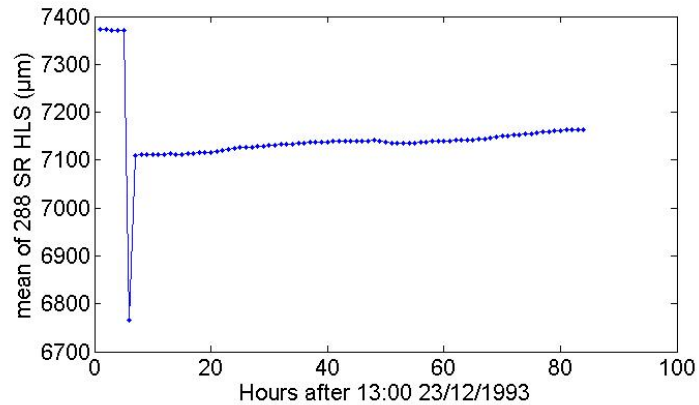


Quantity	PDF	μ	σ
Intrinsic Uncertainty	$N(\mu, \sigma^2)$	0	0.013 μm
Calibration of probe	$N(\mu, \sigma^2)$	0	0.014 μm
Repeatability of calibration	$N(\mu, \sigma^2)$	0	0.022 μm
Final probe calibration uncertainty	$N(\mu, \sigma^2)$	0	0.029 μm

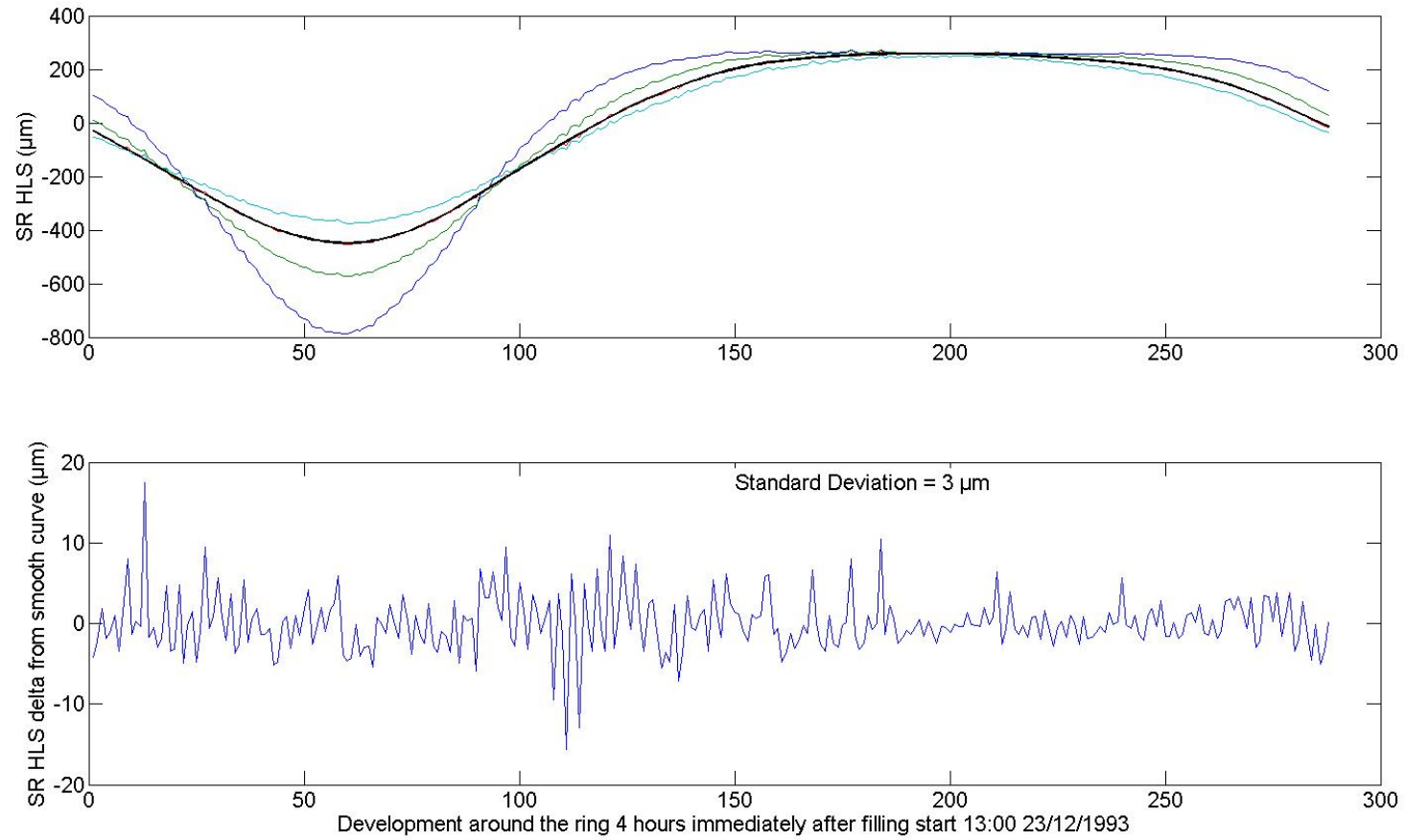
Uncertainty - example Type B for HLS probe laboratory temporal stability



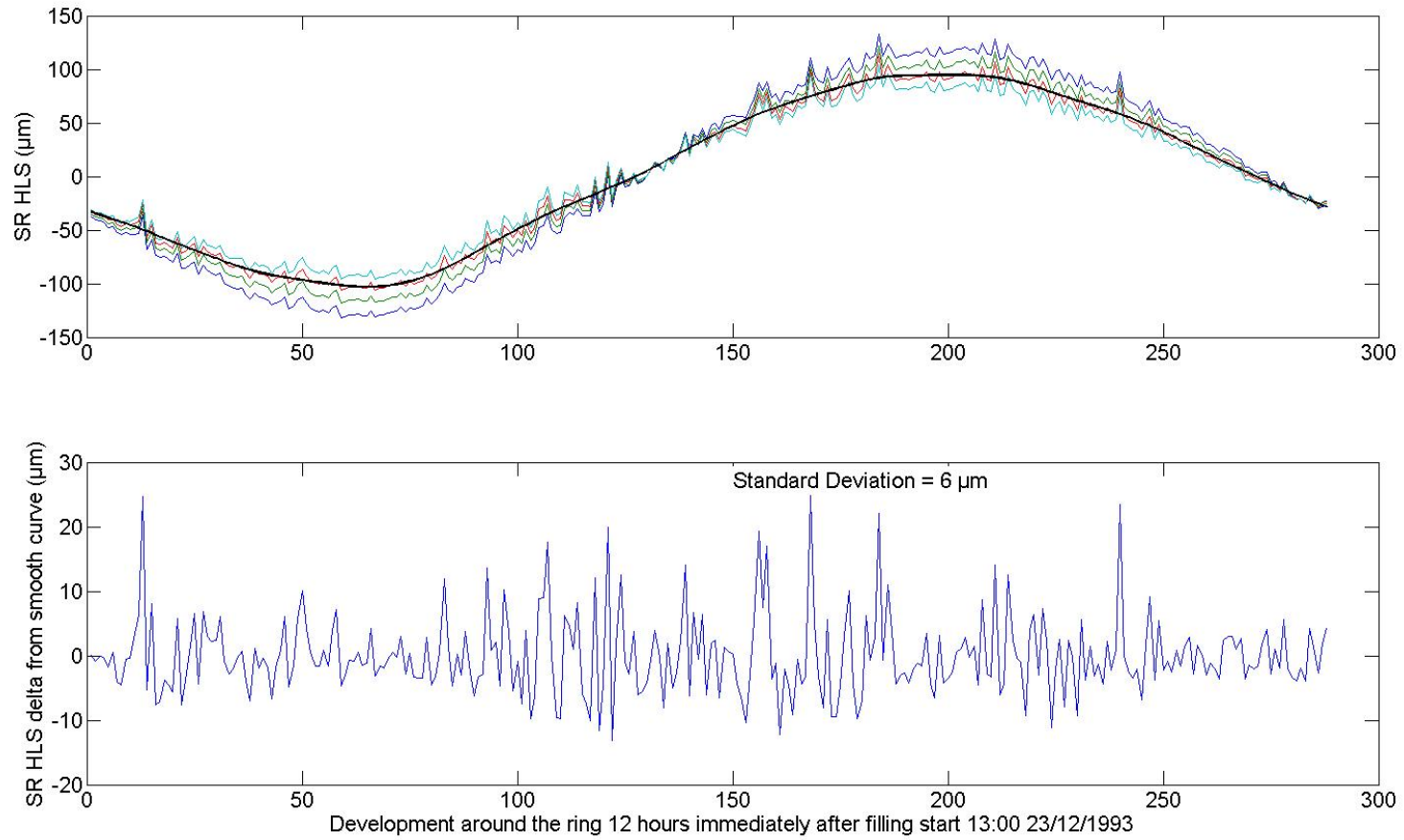
Uncertainty - example Type B for HLS system filling/purging behaviour



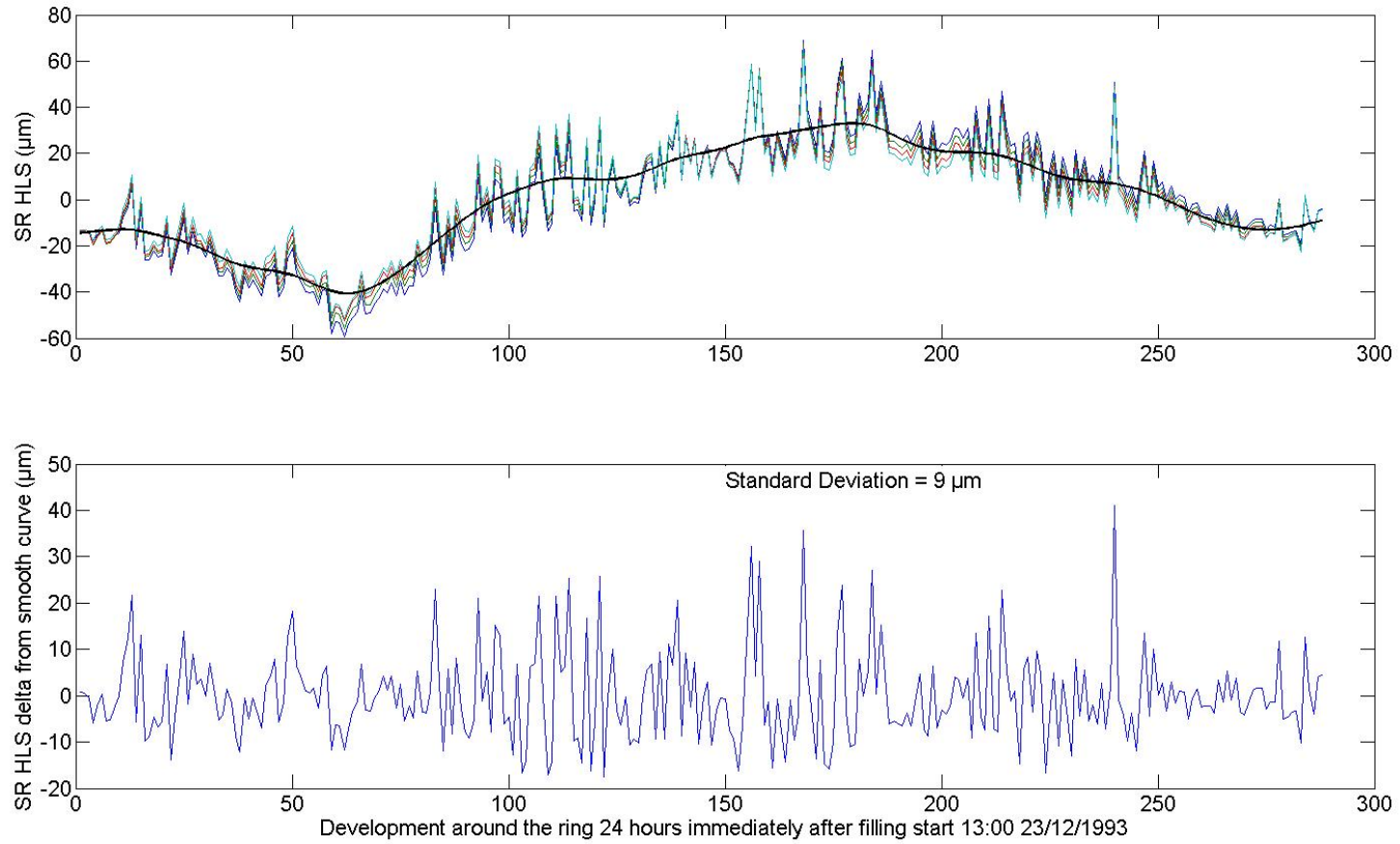
Uncertainty - example Type B for HLS system filling/purging behaviour



Uncertainty - example Type B for HLS system filling/purging behaviour



Uncertainty - example Type B for HLS system filling/purging behaviour



Uncertainty - example Type B for HLS other contributions

There are certainly other Type B contributions to the uncertainty of the HLS ...

Uncertainty - Type A for HLS

Recall Type A uncertainty evaluates uncertainty statistical analysis of series of observations.

Implicitly there is a comparison with a 'traceable' standard or etalon.

What is the standard?

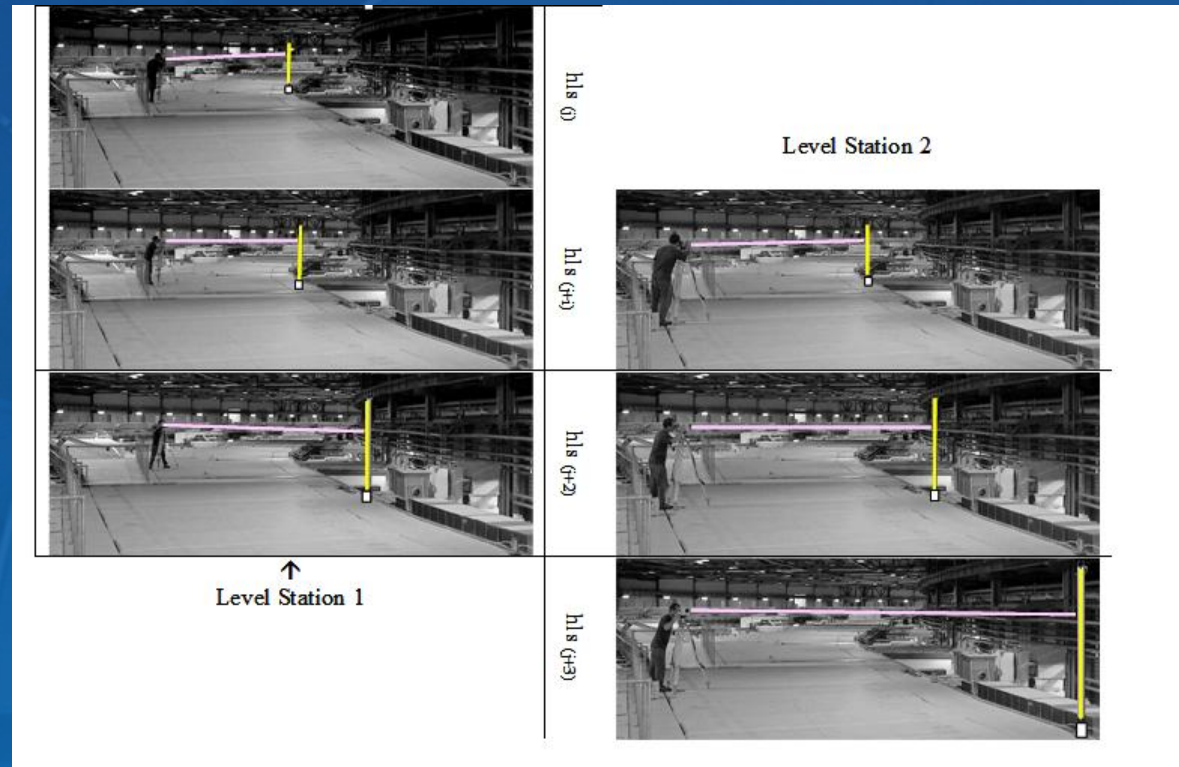
One reasonable standard for the qualification of an HLS is the level.

This implies levelling the HLS.



Uncertainty - Type A for HLS

Qualifying an HLS by levelling is discussed in my 2004 IWAA paper. It is shown there that we can expect an uncertainty in the height differences determined between the level network and the HLS of between $30\mu\text{m}$ and $60\mu\text{m}$.



Methods and conditions of tests on these systems – uncertainty calculation

$$U(dH) = \sqrt{(\text{Type A})^2 + \sum (\text{Type B})^2}$$

Uncertainty contribution		Type B (μm)
Calibration	U(c)	0.029
Temporal Stability	U(s)	1.7
Filling – non-linearity	U(nl)	6

$$U(dH) = \sqrt{45^2 + 96 \times (0.03^2 + 1.7^2) + 6^2} = 48.4 \mu\text{m}$$

Conclusion

From what we have seen in these last slides, it is considered of primal importance to establish a clear set of tests, guidelines and related uncertainties for the HLS and WPS.

The ESRF is open to any inter-laboratory comparison and collaboration with this study



References

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