Processing multiple events, lumis, runs

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A little warning

It may be that my proposal solves a problem that de-facto does not exist for ATLAS and LHCb

Run/lumi-dependent data

One of the dreams is to have "stateless" (well, re-entrant) algorithms. This is destroyed by *frame*-dependent (*) data like:

- 1. Statistics counters (#events seen, efficiencies, ...)
- 2. Monitoring histograms
- 3. ...

 \Rightarrow we should factor them out and **separate algorithms and data** \Rightarrow frame-dependent data are hidden behind special handles and live outside the algorithm

(*) *frame* is a more generic term for run, lumi, ...

Using frame slots

Generalize and replace the *eventSlot* with a **frameSlot**:

- → the number of frameSlots defines how many lumis/runs/conditions can be active at a time
- → access to run/lumi-specific data is forwarded to the respective slot
- → both event and frame slots are managed by the *EventLoopMgr*

Could re-use interface of data handles:

- 1. *Frame*Specific<T> for frame specific data
- 2. *Frame*Read<T>, *Frame*Write<T> for data stored in run/lumi blocks

From user perspective:

```
// event specific
ReadDataHandle<ElectronCollection> m_electrons{...};
// run data
RunSpecific<Counter> m_events;
```

Notification about begin/end of frames

The incidents as implemented now are not context-aware \Rightarrow need to add a context to such messages

Once a new frame enters the event loop, the EventLoopManager picks a frameSlot, and notifies clients via ::begin*Frame*(frameSlot)

Once all events of a frame left the event loop, the EventLoopManager notifies all clients via ::end*Frame*(slot) and is then free to re-use the slot.

It is not entirely trivial, as a certain order may be needed, e.g. run data has to written into the run record **before** the data are written to disk.

 \Rightarrow no new requirement w.r.t. current framework though

A full example

Reading new run and a few events from input file triggers the following behaviour:

The EventLoopMgr

- 1. Opens a new frame slot for that run
- 2. Triggers beginRun (frameSlot) for all relevant componentsa. Algorithms initialize run-specific data
- 1. Opens eventSlots for all events and pushes them to the scheduler
- 2. Upon completion of all events in the run trigger endRun (frameSlot)
 - a. Algorithms flush run-specific data
- 3. Frees the frame slot

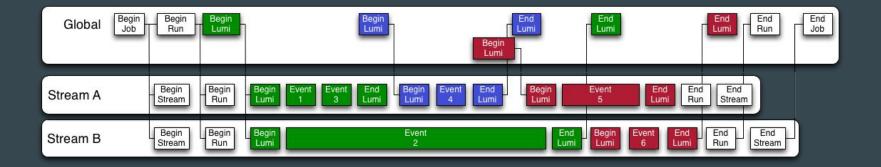
Comparison to CMS' solution

This proposal: separate algorithms and data

- \Rightarrow algorithms are frame-independent
- \Rightarrow data are multiplied for multiple frames
- \Rightarrow access to data is dispatched at runtime
- \Rightarrow #concurrent frames limited by #slots

CMS: split application into "streams" that have a guaranteed run ordering

- \Rightarrow algorithms with run-specific states are tied to a given stream (required deriving from different classes to pick proper behaviour)
 - (required deriving from different classes to pick proper behavior
- \Rightarrow algorithms and states therein are multiplied for multiple streams
- \Rightarrow #concurrent runs limited by #streams



Status and Summary

Proposed a solution for handling runs and lumi-sections in general

- 1. Even better separation of algorithms and data
- 2. Context-aware pointers

Made a (dirty!) proof-of-principle in a branch of mine: <u>https://gitlab.cern.ch/hegner/Gaudi/tree/frame</u>