

Standards for Modular Electronics

the past, the present and the future

Markus Joos

CERN

- **The past:**
 - *QIM*
- **The present:**
 - PCI and PCIe
 - SHB Express
- **The future:**
 - **Serial interconnects**
 - *VXS*
 - *ATCA*
 - *MTCA*

Why Modular Electronics?

- As in programming a system becomes unmanageable if too much functionality is put into a single functional block
- Modularizing DAQ electronics helps in these respects:
 - Allows for the **re-use** of generic modules in different applications
 - **Limiting the complexity** of individual modules increases their reliability and maintainability
 - You can profit from **3rd party support** for common modules
 - Makes it easier to achieve **scaleable designs**
 - **Upgrades** (for performance or functionality) are less difficult
 - Etc.

Why use Standards?

- Benefit from **3rd party products, services and support**
- **Competition** gives you **better prices** and **alternative suppliers**
- Standards make it easier to define **interfaces** between sub-systems
- But not all standards are equally good:
 - **Too old**: poor performance, few suppliers, expensive
 - **Too new**: Interoperability issues, unclear long term support
 - **Too exotic**: Too few suppliers (sometimes just one)

NIM

- Initially (1964): NIM = Nuclear Instrument Modules
 - But it was used outside of "nuclear science"
 - Therefore: NIM = National Instrument Modules
 - But is was used outside of the USA
 - Therefore: NIM stands for NIM

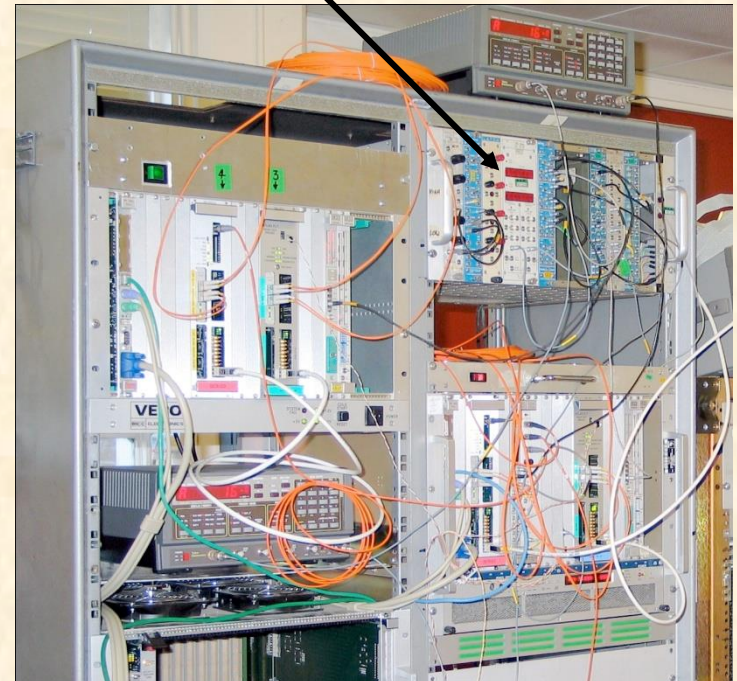
NIM modules (usually)

- Need no software
- Are not connected to a computer
- Are used to implement trigger logic

These functions (any many others) are available

- Discriminators
- Coincidences
- Amplifiers
- Timers
- Logic gates (and / or)
- Level converters
- HV power supplies
-

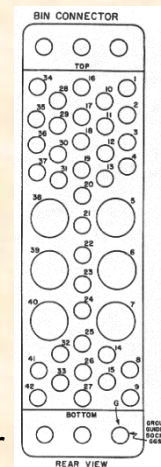
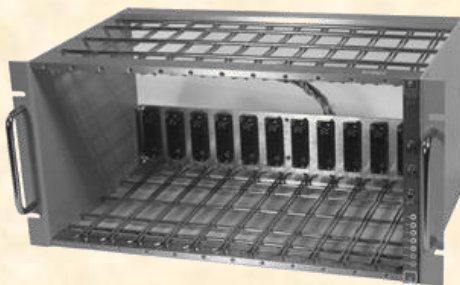
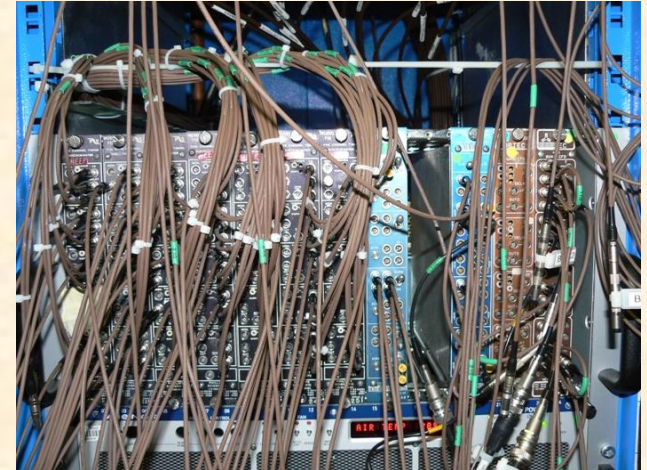
NIM crate



A small DAQ system 3

NIM basics

- 1st NIM standard: **July 1964**
 - 1st commercial module: November 1964
- Module dimensions: 34 x 221 x 246 mm
- NIM logic levels:
 - **0 = 0A (0V)**
 - **1 = -12 to -32 (typical -16) mA at 50 Ω (-0.8V)**
- NIM connector
 - 42 pins in total
 - 11 pins used for power (+/- 6, 12, 24V)
 - 2 logic pins (reset & gate)
- 29 pins reserved for future use since 1964
- 1983 NIM digital bus (IEEE 488 – GPIB)
 - Rarely used



NIM connector



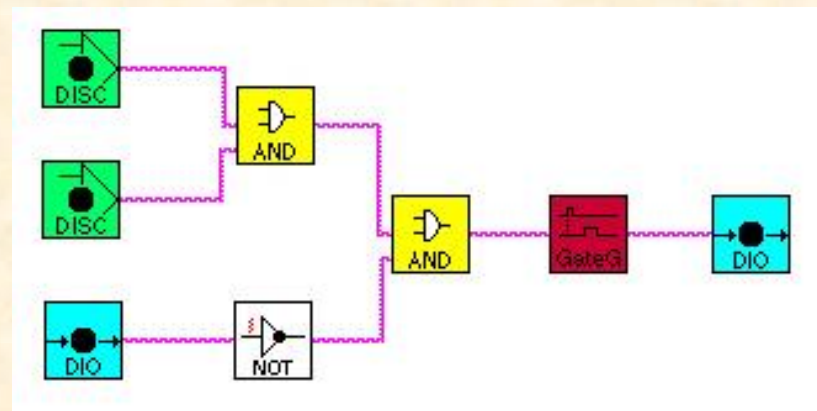
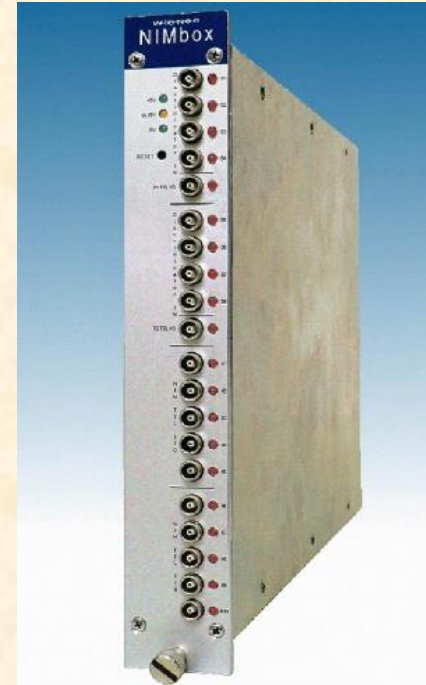
NIM – the next generation

NIM is still very alive
Some examples


100 MS/s
digitizer
with optical
read-out

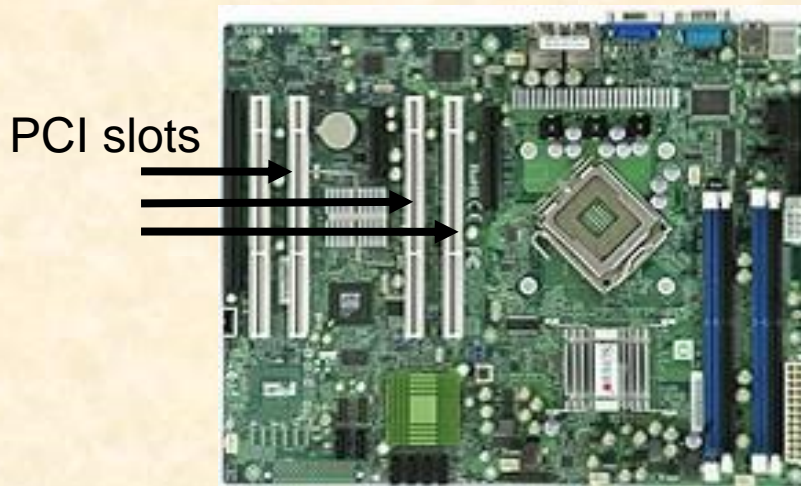


General
purpose NIM
module with
programmab
le logic
(LabView)

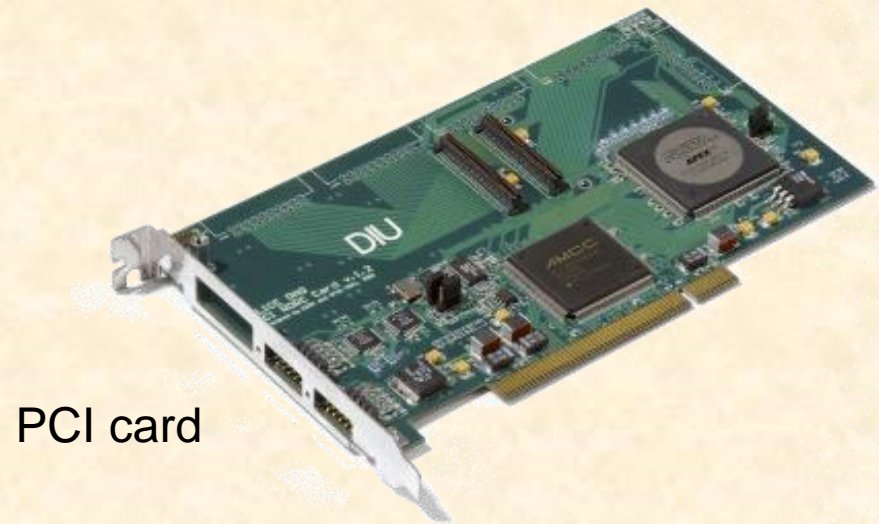


PCI

- First standardized in 1991
- Replaced the older ISA cards
- Initially intended for PC cards
 - Later **spin-offs**: CompactPCI, PXI, PMC 
- **Parallel** PCI has almost **disappeared** -> replaced by **serial** PCIe
 - But there are still some ICs with parallel PCI in use on modern PCs/SBCs



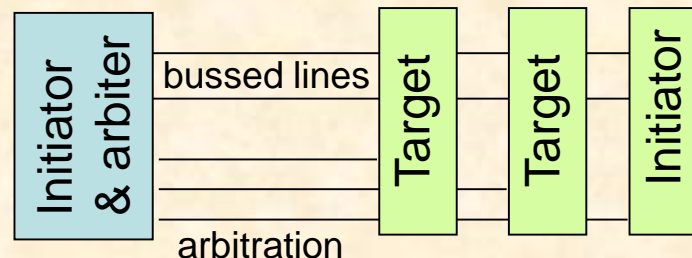
PC motherboard



PCI card

PCI basics

- Main features of the original parallel protocol (**not to be confused with PCIe**)
 - **Synchronous timing**
 - But wait cycles possible
 - **Clock rates**
 - Initially 33 MHz. Later: 66 MHz, (PCI-X: 100 and 133 MHz)
 - **Bus width**
 - Initially 32 bit. Later: 64 bit
 - **Signaling voltage**
 - Initially 5 V. Later 3.3 V (->slot keying)
 - **Terminology**
 - A data transfer takes place between an INITIATOR (master) and a TARGET (slave)
 - **Bus topology**
 - 1 to 8 (depending on clock rate) slots per bus
 - Busses can be connected to form a tree
 - Address and data as well as most protocol lines are shared by all devices; The lines used for arbitration are connected point-to-point; The routing of the interrupt request lines is more complicated...
 - A system can consist of several Initiators and Targets but only one Initiator can receive interrupts



PCI basics - 2

- Address spaces
 - **Configuration space**
 - Standardized registers for the dynamic configuration of the H/W (plug-and play)
 - **I/O space**
 - For device specific registers
 - **MEM space**
 - General purpose space for registers and memory
- **Cycle types** (encoded in the C/BE[3::0]# lines)
 - **Single cycles**
 - Read / write of all 3 address spaces
 - **Bursts**
 - MEM read / write (with special features for cache handling)
- (Typical) performance
 - **Single cycle:** 2 (3 for read) -> ~10 clock cycles
 - 33 MHz / 32 bit: 66 MB/s -> ~10 MB/s
 - 64 MHz / 64 bit: 264 MB/s -> ~40 MB/s
 - **Bursts:**
 - 33 MHz / 32 bit: Max. 132 MB/s
 - 64 MHz / 64 bit: Max. 528 MB/s
 - PCI-X @ 133 MHz: 1.06 GB/s
 - PCI-PCI **bridges** add additional delays

PCI devices under Linux

The command “lspci” displays information about the PCI devices of a computer

Show PCI tree: lspci -t -v

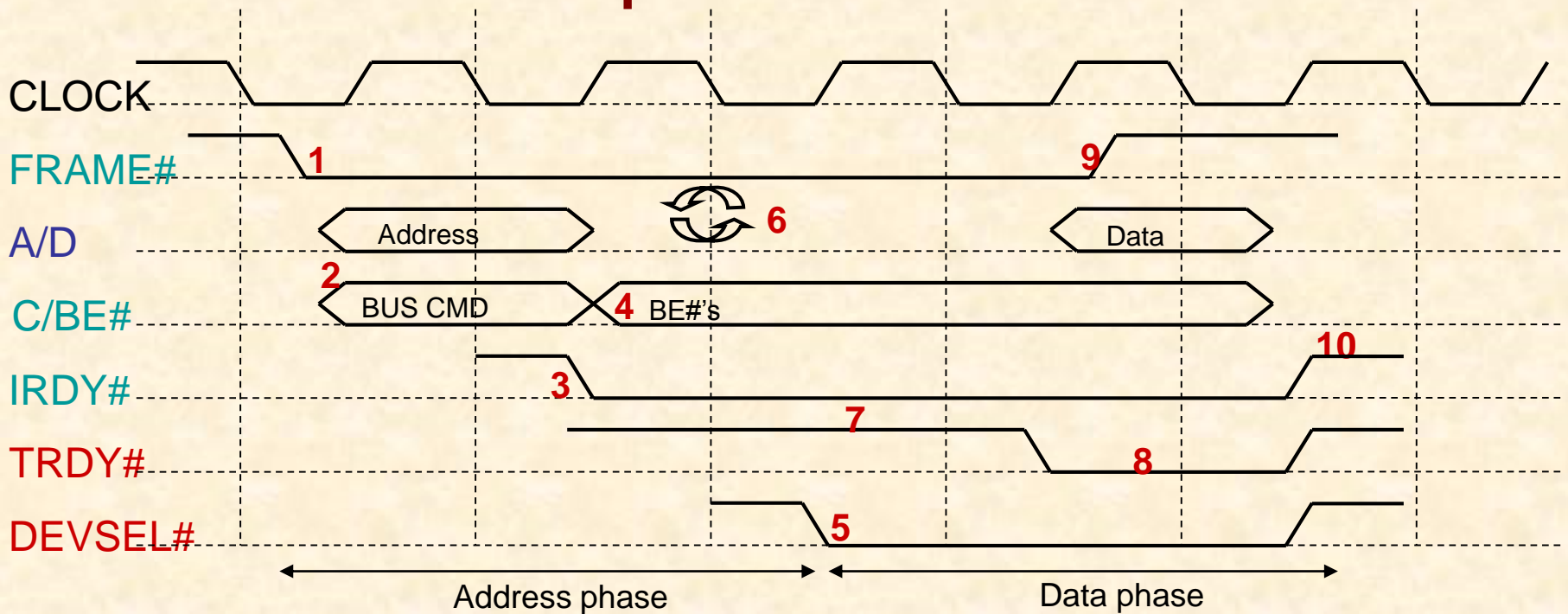
```
-[0000:00]--00.0 Intel Corporation E7520 Memory Controller Hub
  +-00.1 Intel Corporation E7525/E7520 Error Reporting Registers
  +-01.0 Intel Corporation E7520 DMA Controller
  +-02.0-[0000:01-03]---+00.0-[0000:02]----03.0 CERN/ECP/EDU Unknown device 0144
    |
    |   +-00.1 Intel Corporation 6700/6702PXH I/OxAPIC Interrupt Controller A
    |   |
    |   |   +-00.2-[0000:03]----01.0 CERN/ECP/EDU Unknown device 0144
    |   |   |
    |   |   |   \-00.3 Intel Corporation 6700PXH I/OxAPIC Interrupt Controller B
    |   |
    |   +-04.0-[0000:04]----00.0 Broadcom Corporation NetXtreme BCM5721 Gigabit Ethernet PCI Express
    |   +-05.0-[0000:05]----00.0 Broadcom Corporation NetXtreme BCM5721 Gigabit Ethernet PCI Express
    |   +-06.0-[0000:06-08]----00.0-[0000:07-08]---+04.0 Broadcom Corporation NetXtreme BCM5714 Gigabit Ethernet
    |   |
    |   |   +-04.1 Broadcom Corporation NetXtreme BCM5714 Gigabit Ethernet
    |   |   |
    |   |   |   \-08.0-[0000:08]---+06.0 Broadcom Corporation NetXtreme BCM5704 Gigabit Ethernet
    |   |   |
    |   |   |   \-06.1 Broadcom Corporation NetXtreme BCM5704 Gigabit Ethernet
    |   |
    |   +-07.0-[0000:09-0b]---+00.0-[0000:0a]----02.0 CERN/ECP/EDU Unknown device 0144
    |   |
    |   |   +-00.1 Intel Corporation 6700/6702PXH I/OxAPIC Interrupt Controller A
    |   |   |
    |   |   |   +-00.2-[0000:0b]----01.0 CERN/ECP/EDU Unknown device 0144
    |   |   |   |
    |   |   |   |   \-00.3 Intel Corporation 6700PXH I/OxAPIC Interrupt Controller B
    |   |
    |   +-1d.0 Intel Corporation 82801EB/ER (ICH5/ICH5R) USB UHCI Controller #1
    |   +-1d.1 Intel Corporation 82801EB/ER (ICH5/ICH5R) USB UHCI Controller #2
    |   +-1d.2 Intel Corporation 82801EB/ER (ICH5/ICH5R) USB UHCI Controller #3
    |   +-1d.3 Intel Corporation 82801EB/ER (ICH5/ICH5R) USB UHCI Controller #4
    |   +-1d.7 Intel Corporation 82801EB/ER (ICH5/ICH5R) USB2 EHCI Controller
    |   +-1e.0-[0000:0c]----01.0 ATI Technologies Inc Rage XL
    |   +-1f.0 Intel Corporation 82801EB/ER (ICH5/ICH5R) LPC Interface Bridge
    \-1f.3 Intel Corporation 82801EB/ER (ICH5/ICH5R) SMBus Controller
```

Show device details: lspci -v -s 02:03.0

```
02:03.0 Co-processor: CERN/ECP/EDU Unknown device 0144 (rev ac)
Subsystem: Unknown device 2151:1087
Flags: bus master, 66MHz, medium devsel, latency 32, IRQ 209
Memory at d7200000 (32-bit, non-prefetchable) [size=512]
I/O ports at 2000 [size=256]
Memory at d8000000 (32-bit, non-prefetchable) [size=16M]
Capabilities: <access denied>
```

Parallel PCI protocol

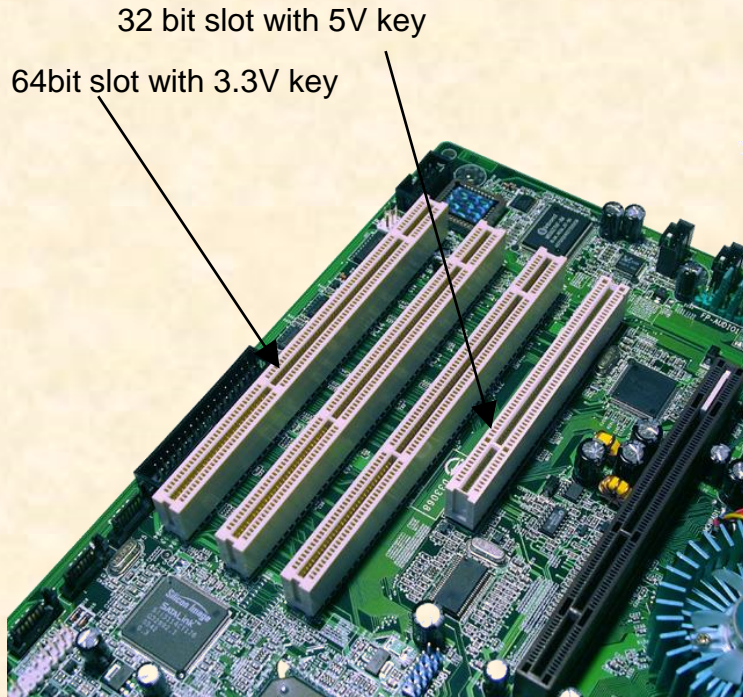
Example: Single cycle read



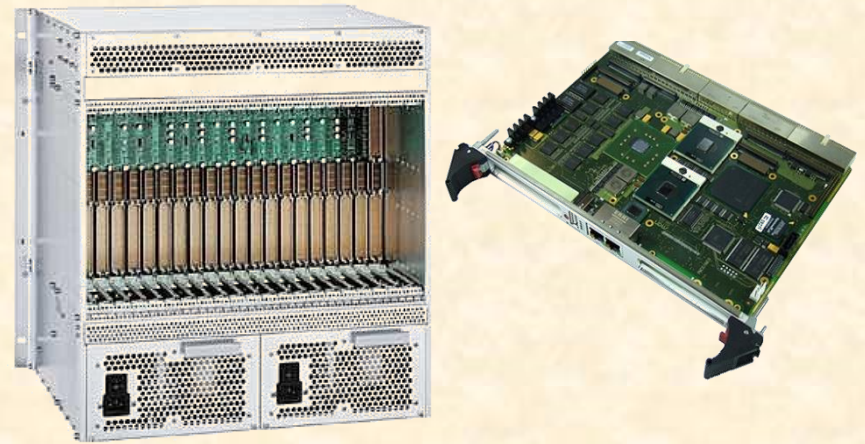
- 1) Assertion of FRAME starts cycle
- 2) Initiator puts address and command (cycle type) on the bus
- 3) The Initiator signals that it is ready to receive data
- 4) The initiator uses the C/BE lines to define which bytes it wants to read
- 5) Target looks at the Address and drives DEVSEL if it was addressed. If no target drives DEVSEL after at most 6 clock the Initiator will abort the cycle
- 6) The ownership of the AD lines changes from Initiator to target (only for read cycles). This requires one clock cycle

- 7) The Target does not yet drive TRDY (it may need time to prepare the data) but asks the Initiator to wait
- 8) The Target has the data ready on the AD lines. The Initiator fetches the data in the same clock cycle
- 9) By de-asserting FRAME the Initiator tells to the Target that it does not want additional data after the next data word
- 10) The cycle is over and the protocol lines get released

Some examples of Parallel PCI H/W



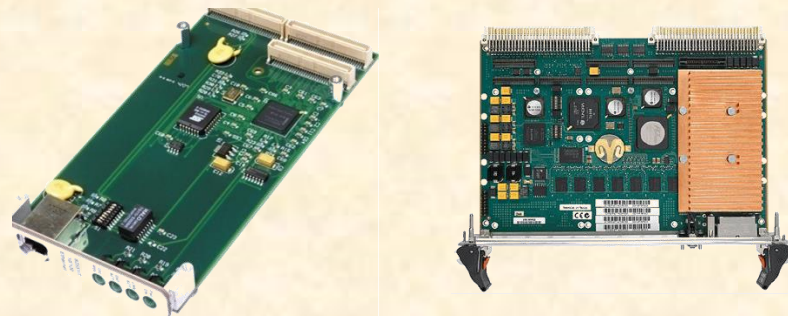
PC motherboard with PCI slots



6U CompactPCI chassis and card



PXI system



PMC card and carrier (VMEbus)



CompactPCI (and friends)

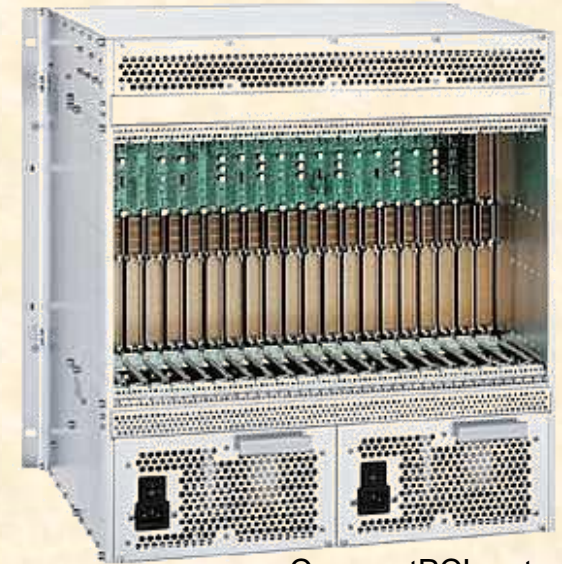
Year	1995
Module dimensions	Same as 3U and 6U VMEbus
Connector	Various type (parallel and serial protocol)

Special features

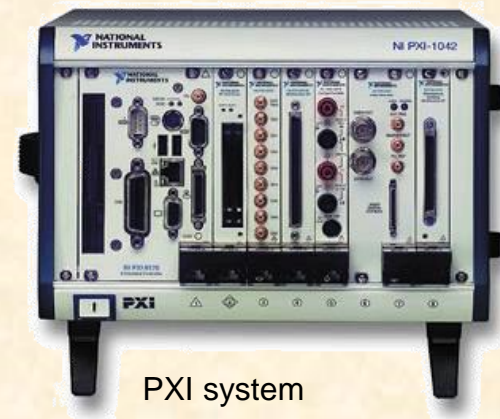
- Based on the **PCI(e) protocol**
- Many **derivatives**: CompactPCI Serial, CompactPCI PlusIO, PXI, CompactPCI Express
- **S/W compatibility** in PCI->PCIe migration
- Single master (scalability)

Why was / is it **partially** successful?

- No large performance advantage over (well established) VMEbus
- Too late to market
- Many modules for Test & Measurement (PXI)



CompactPCI crate



PXI system

Parallel bus -> Serial link

Parallel Buses Are Dead! (RT magazine, 2006)

What is wrong about “parallel”?

- You need lots of pins on the chips and wires on the PCBs
- The skew between lines limits the maximum speed

What is wrong about “bus”?

- Speed is a function of the length (impedance) of the lines
- Communication is limited to one master/slave pair at a time (no scalability)
- The handshake may slow down the maximum speed

All parallel buses are dead. All? No!

- VMEbus is still used (military / research)
- There is lots of PCI legacy equipment


What next?

- Switched serial interconnects



(Switched) serial links

- Standards (just the most important)

- PCIe
- 1 / 10 GB Ethernet
- Serial RapidIO
- Infiniband 
- Serial ATA
- FiberChannel
-

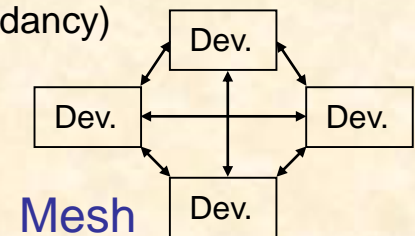
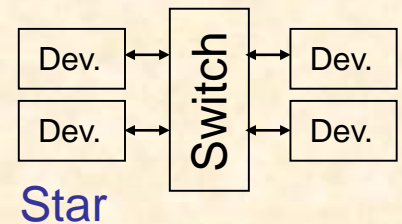
- Commonalities

- Signal rate: 2.5 – 10 GHz
- Packet switching
- Topology

- Star: Devices connect to a fabric switch
 - Dual Star: Devices connect to two fabric switches (for redundancy)
- Mesh: All devices have direct links to all others

- Differences

- Support for interrupts
- Support for programmed I/O
- Quality of service (guaranteed bandwidth)



Infiniband

- Developed by Compaq, IBM, Hewlett-Packard, Intel, Microsoft and Sun from 1999 onwards
- Characteristics
 - Bi-directional serial link
 - Aggregation of links (4x, 12x possible)
 - Link speed: 2.5, 5, 10 GHz
 - Special features
 - Data transfer performed without involvement of OS (latency < 2 μ s)
 - Remote DMA (fetch data from the memory of a remote system)
 - Main field of application
 - Server and storage interconnect for high performance computing
 - Relevance for DAQ
 - Limited for a lack of DAQ F/E products
 - Used by CMS for the HLT N/W

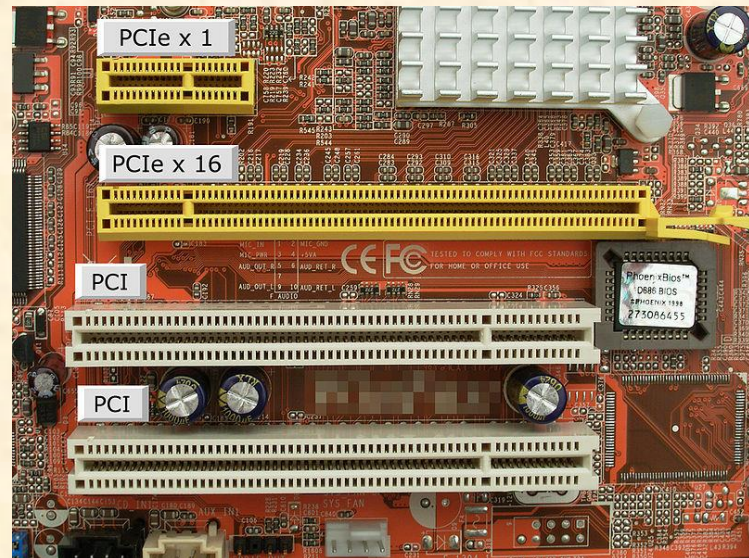
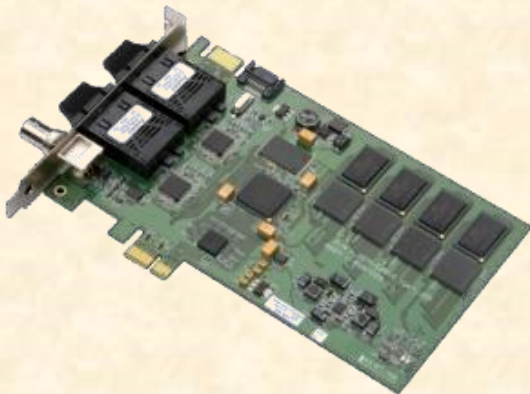
Serial Rapid I/O

- Developed by Mercury Computer Systems and Motorola from 1997 onwards
- Characteristics
 - Bi-directional serial link
 - Aggregation of links (2x, 4x, 8x, 16x possible)
 - Link speed: 1.25, 2.5, 3.125, 5, 6.25 GHz
 - Special features
 - Quality of Service (transfer requests can be prioritized)
 - Multicast
 - Main field of application
 - Chip/chip and board/board communication
 - Relevance for DAQ
 - Limited for a lack of DAQ products but some AMC/ATCA products



PCIe (aka PCI Express)

- Not a bus any more but a point-to-point link
- Data not transferred on parallel **lines** but on one or several serial **lanes**
 - **Lane**: One pair of LVDS lines per direction
 - Clock rate: 2.5 GHz (PCIe2.0: 5 GHz, PCIe 3.0: 8 GHz, PCIe 4.0: 16 GHz)
 - 8b/10b encoding (PCIe3.0 & 4.0: 128/130b encoding)
 - 250 MB/s (PCIe 1.0) raw transfer rate per lane
 - Devices can support up to 32 lanes
- Protocol at the link layer has nothing to do with protocol of parallel PCI
- Fully transparent at the S/W layer



PCIe performance

- Data is transferred in **frames**:

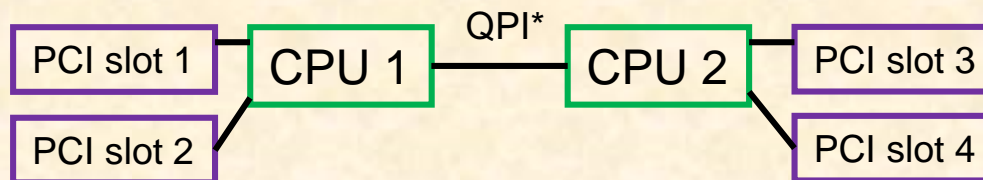
Start 1 byte	Sequence 2 bytes	Header 12 or 16 bytes	Payload 0 - 4096 bytes	ECRC 4 bytes	LCRC 4 bytes	End 1 byte
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- Note:

- H/W may limit **max payload size** (typically 128, 256 or 512 bytes)
- Every data packet has to be **acknowledged** (additional overhead)
- **Read** transactions may cause additional delays

- The actual performance may be as low as **~15%** of the theoretical maximum
- Achieving more than **~80%** link efficiency is difficult

- The **topology** of the system (PC motherboard) matters as well
- You may have to use process / thread **affinity** in order to tie your I/O code to the CPU that connects directly to your I/O cards



PICMG 1.3 – The basic idea

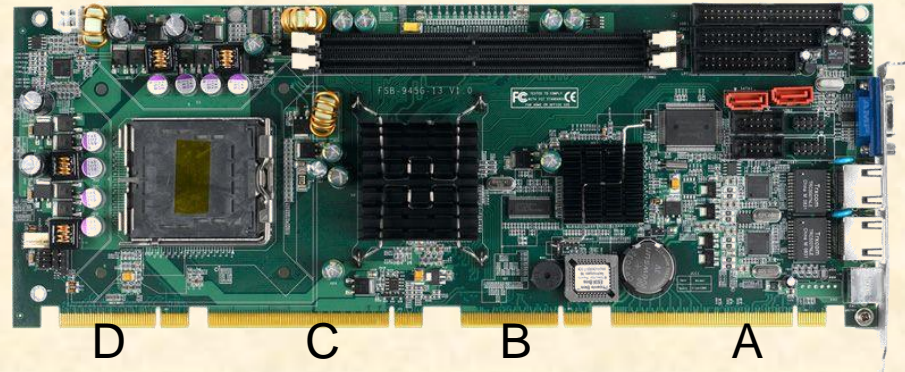
- A desk-top PC has at most **7 slots** for PCI(e) cards
- PC **motherboards** are **quickly** getting **obsolete**
 - Let's design a standard that is more adapted for using PCI cards in an **industrial domain**
 - Modularize system by decoupling computing core from PCI card backplane

PICMG 1.3 – SHB Express

- **SHB Express** = **System Host Board** standard for **PCIe**
- Standardized in 2005
- Defined in the standard
 - SHB board mechanics (two board formats)
 - PCI(e) interface between SHB and backplane
 - Additional I/O (SATA, USB, Ethernet, etc.) that may be routed to the backplane
 - Backplane design rules
- Systems consist of:
 - One SHB
 - One backplane
 - One or several PCIe, PCI-X or PCI cards

The SHB

- Two (A & B) or 4 (A, B, C & D) connectors
 - Connector A: PCIe
 - (1 x16) or (2 x8) or (1 x8 + 2 x4) or (4 x4)
 - Connector B: PCIe
 - (1 x4) or (4 x1)
 - Connector C:
 - Additional I/O
 - Connector D:
 - 1 32bit PCI(-X)



SHB – the backplanes

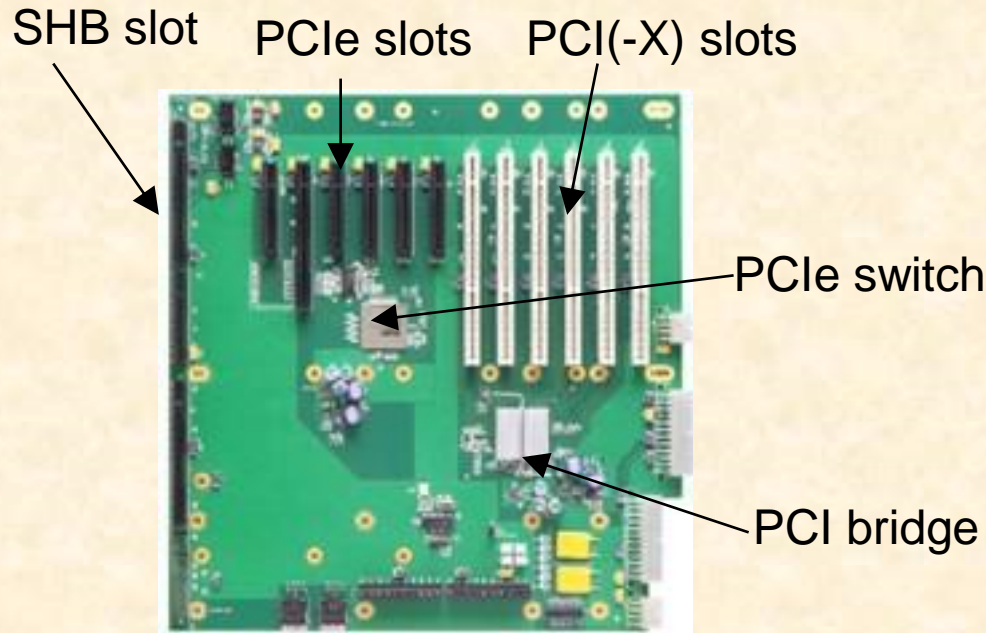
The backplane has to match the PCIe configuration of the SHB

- x16 on connector A: graphics class
- 2 x8 on Connector A: server class

Relevance for DAQ:
• For small systems
• For re-use of old PCI cards



Segmented backplane with 4 SHB and 12 PCIe slots for a 19" 4U chassis



A complete 4U system

The next generation

What new standards are available?

- **VITA41**: VXS
- **PICMG 3.x**: ATCA (Advanced Telecommunications Computing Architecture)
- **PICMG MTCA.x**: MicroTCA/ μ TCA
- **PICMG AMC.x**: Advanced Mezzanine Card (for ATCA and μ TCA)

Not covered in this talk:

- **VITA46**: VPX
- **PICMG 2.x**: Compact PCI (cPCI)
- **PICMG EXP.0**: PCIe for cPCI
- **PCIMG CPCI-S.0**: CompactPCI serial
- **PICMG ATCA300.0**: ATCA for 300mm deep systems (no rear I/O)
- And many more...

PICMG:	www.picmg.org
PCI-SIG:	www.pcisig.com
VITA:	www.vita.com

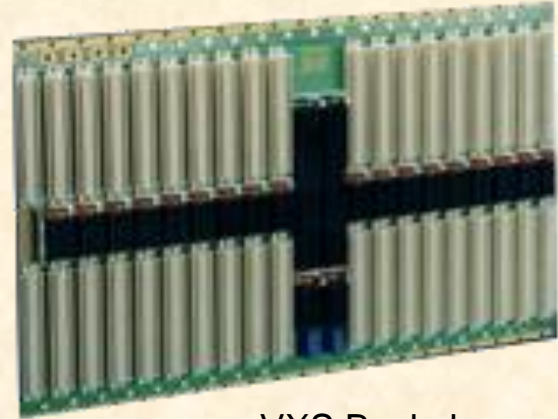
VXS – The basic idea

- VMEbus **mechanics** is not so bad:
 - Let's keep it
- There is a lot of **legacy equipment**:
 - Let's re-use it
- The data transfer bandwidth could be better:
 - Let's add an optional **high-speed communication** channel

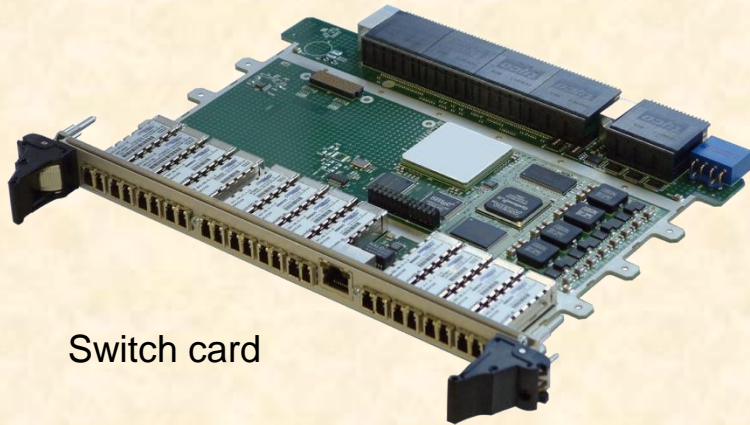
VXS- Components



VMEbus crate



VXS Backplane



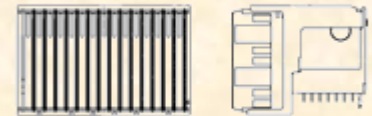
Switch card



Payload card

VXS (VITA 41, ~100 pages)

- Essentially 6U (but 9U not excluded) **VMEbus with a new P0 connector**
- Two types of cards
 - **Payload**
 - **Switch** (one card required, second for redundancy)
- Network topology: (dual) star
- Connectivity for payload cards
 - **16 differential** pairs (10 GHz) defined by the standard (and routed to switch cards)
 - **31 reserved pins** available on P0
- Sub-standards
 - 41.1: Infiniband
 - 41.2: Serial RapidIO
 - 41.3: IEEE Std 802.3 (1000 Mb/s Ethernet)
 - 41.4: PCIe
- Hot Swap: According to VITA 1.4
- System management based on **I²C / IPMI** but only formulated as recommendation



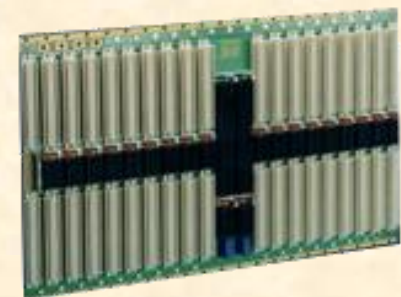
VXS connector



Switch card

Why was / is it **NOT** successful?

- Had to compete with xTCA
- Did not address many shortcomings of VMEbus
 - Power, cooling, management, hot swap, module width
- Little market interest
- Backwards compatibility not necessarily an advantage



Backplane

Advanced TCA – the basic idea

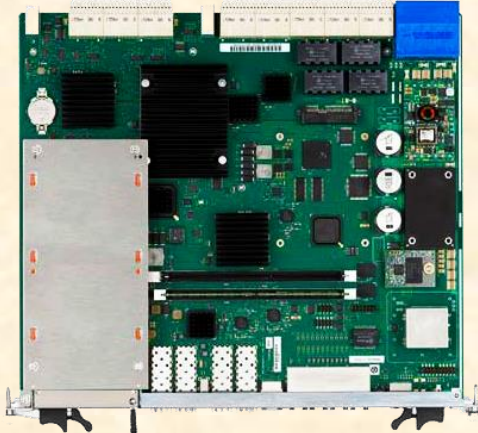
- Telecom companies are using proprietary electronics:
 - Let's design a standard for them from scratch
 - It has to have all the features telecom companies need:
 - High availability (99.999%)
 - Redundancy at all levels
 - Very high data throughput
 - Sophisticated remote monitoring and control

Advanced TCA - Components

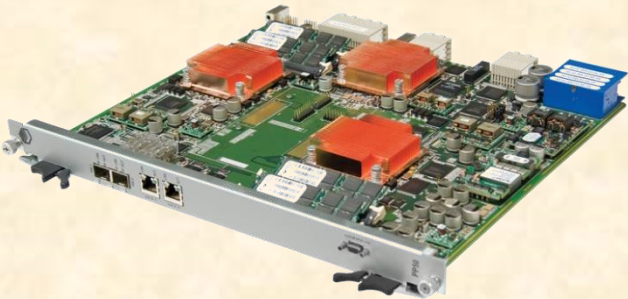
Shelves



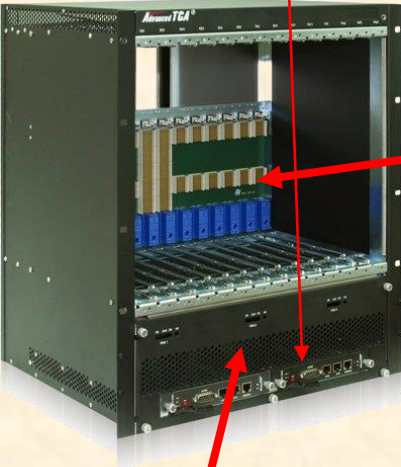
Shelf manager(s)



Switch blade



Payload card

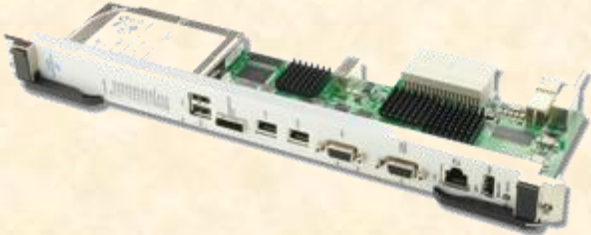


Backplane

Hot-swap fans



AMC carrier

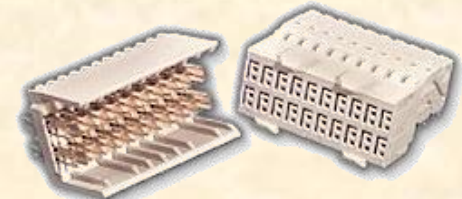


Rear Transition Module

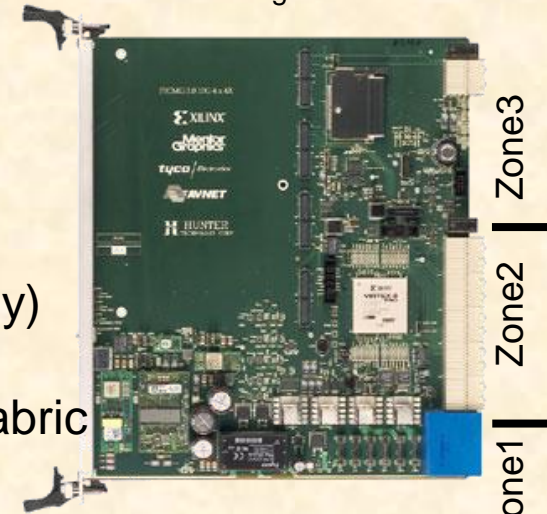
Advanced TCA (650 pages + IPMI)

- More of a system than a board standard
- Started in **2001** by ~100 companies
- **One form factor**
 - Front: 8U x 280 mm x 30.48 mm (14 slots per 19" crate)
 - Rear: 8U x 60 mm (**5W**)
- Supply voltage: **-48 V** (-> DC-DC conversion each on-board)
- Power limit: **200 W** (400-600-800 W) per card
- Connectors
 - Zone 1: One connector for power & system management
 - Zone 2: One to five ZD connectors for data transfer
 - Zone 3: User defined connector for rear I/O
- Connectivity
 - Up to **200 differential pairs**
 - **4 groups**
 - 64 pairs for Base Interface (usually Eth., star topology)
 - 120 pairs for Fabric Interface (star or full mesh)
 - Ethernet, PCIe, Infiniband, serial RapidIO, StarFabric
 - 6 pairs for Clock Synchronization
 - 10 pairs for Update Channel
- System management based on **IPMI, I²C and FRU data**

**Relevance for DAQ:
Very trendy!
(and very complex)
Replaces 9U VME**



ATCA signal connector



ATCA board

ATCA HA features

(applies also largely to μ TCA)

Redundancy

- Power Supply modules
- Ventilators
- Shelf managers
- Switch blades

Electronic Keying

- Based on FRU information payload cards may be accepted / rejected in a given slot

Hot swap

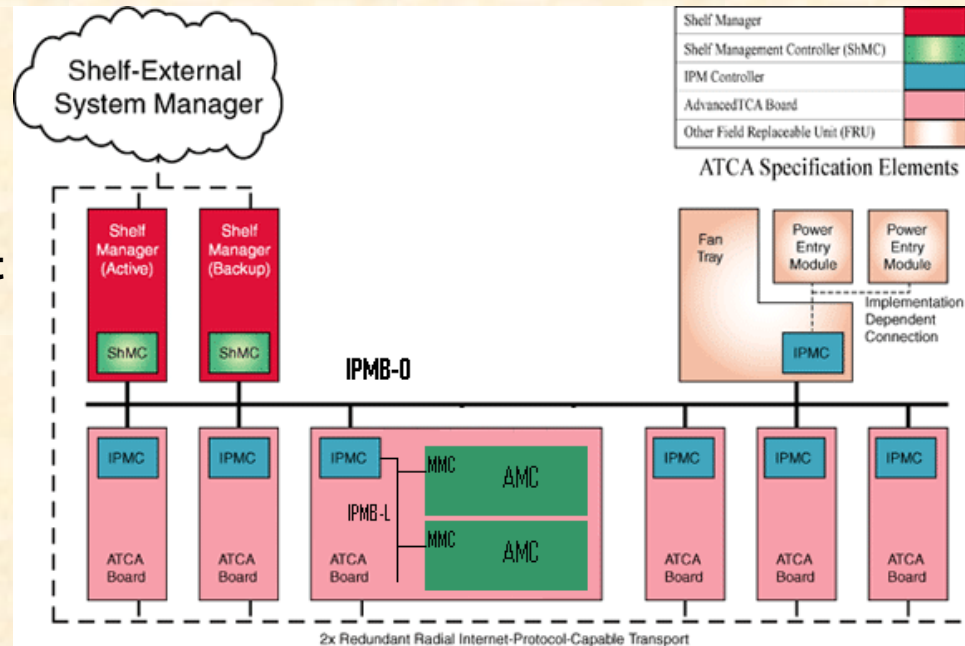
- Payload board will only receive (payload) power if the shelf manager can guaranty for the availability of the required resources (power, cooling, signal connections)

Monitoring

- Low level: IPMI on I²C
- High level: SNMP (Simple Network Management Protocol) and other protocols on top of TCP/IP
- System event logs

Cooling

- Dynamically controlled fans and several alarm levels

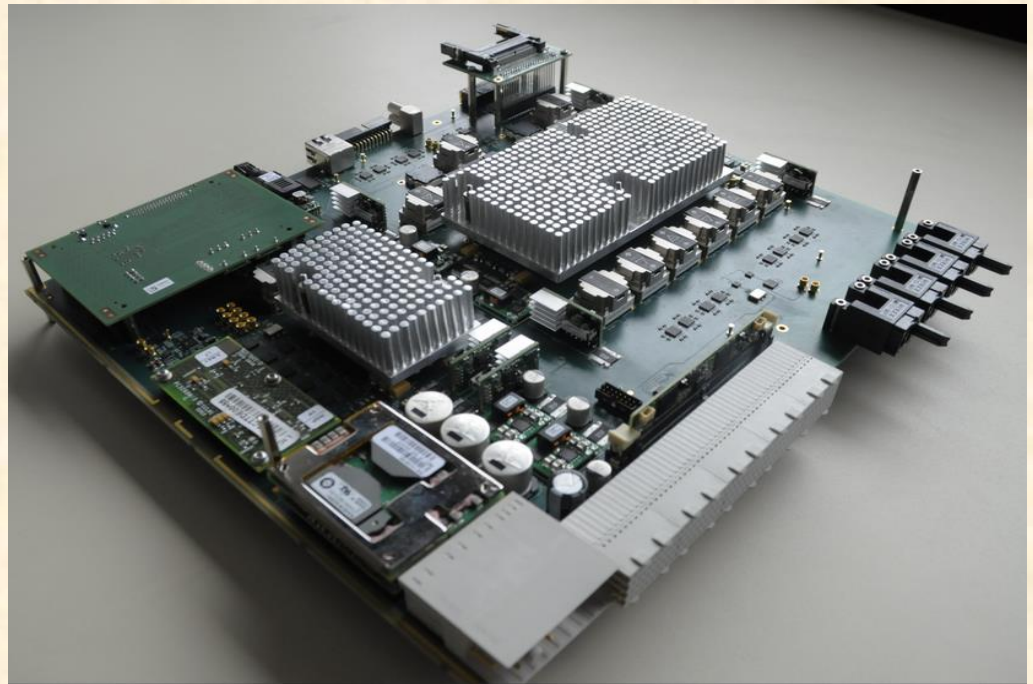


Dedicated tree for control and monitoring

ATCA – An example

The ATLAS L1Topo board

- 2 Xilinx Virtex7 XC7V690T FPGAs for data processing
- 1 Kintex7 FPGA for control and data transmission
- 22 layers PCB
- Processes 1 Tb/s with a latency budget of 150 ns

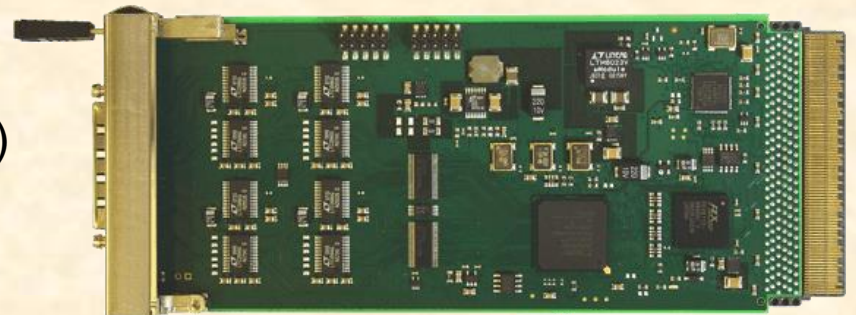
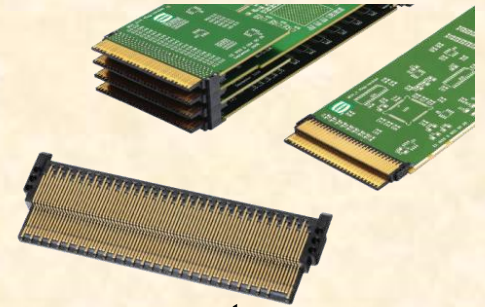


AMC – The basic idea

- **ATCA blades** are **big**. Small **mezzanine** modules could be helpful to modularize their functionality
- PMC/XMC mezzanines are not **hot-swappable**
 - Let's design a new type of mezzanine for ATCA

AMC

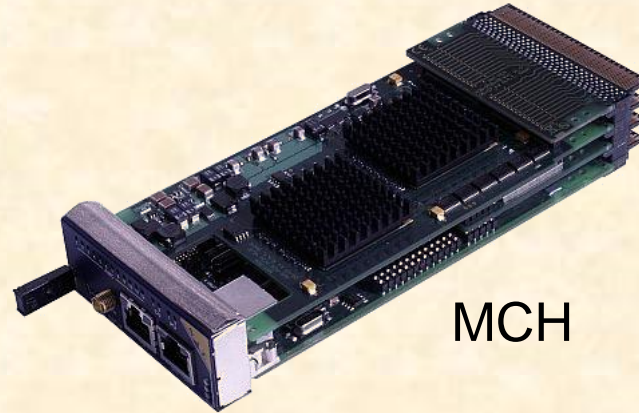
- Originally intended as **hot-swappable** mezzanine standard for ATCA but soon used as the basis for the μ TCA standard
- 6 form factors:
 - 74 or 149 mm **wide**
 - 13, 18 or 28 mm **high**
 - 180 mm **deep**
- Power supply: **80W** (max) on **+12V** (and 0.5W on 3.3V management power)
- Connector: 85 pin (single sided) or 170 pin (double sided) edge connector
- Connectivity
 - Up to **12.5 Gb/s**
 - **20+20 LVDS signal pairs** for data transfer (Eth, PCIe, SAS/SATA, Serial RapidIO)
 - Clock interface, JTAG
- Managed via local microcontroller (**MMC**)
 - **IPMI** messages on I²C



μ TCA / MTCA – The basic idea

- AMC mezzanines are great but ATCA is a heavy standard and the H/W is expensive
 - Let's define a standard that allows for **using AMCs directly in a shelf** (i.e. Promote the AMC from “mezzanine” to “module”)

μ TCA / MTCA - Components



MCH



Shelves



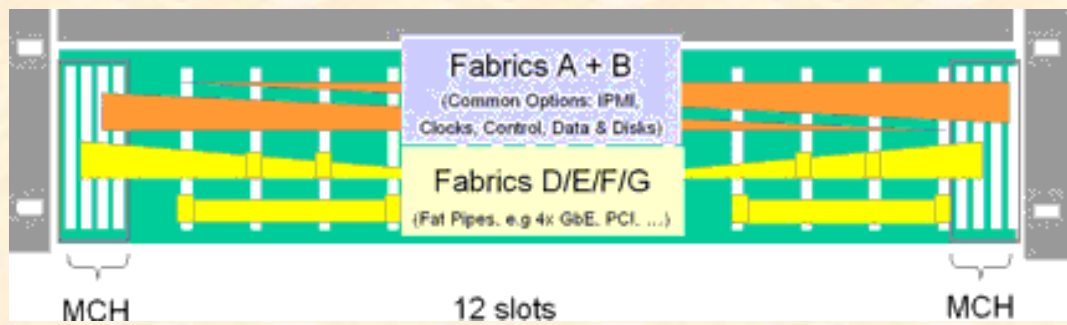
AMCs

μTCA

Relevance for DAQ:
Very trendy!
(watch out for interoperability issues)
Replaces 6U VME

- A system standard based on the AMC, standardized in 2006
- Min. signaling speed: 3.125 GHz
- Connectivity:
 - 4 AMC LVDS pairs defined as “Common Options” (2 Eth. & 2 SAS ports) and connect to 1 or 2 MCH boards which provide the switching
 - 8 AMC LVDS pairs defined as (extended) fat pipes (1 or 10 G Eth, PCIe, RapidI/O). Connection to MCH not standardized
 - Remaining 8 LVDS pairs not defined (can be used for rear I/O (but rear I/O not foreseen in uTCA standard))
- System management based on IPMI / I²C
- Hot-swap support for PSU & cooling
- Redundant MCH (μTCA Controller Hub)
- The MCH connector supports up to 84 differential pairs. Therefore only 7 pairs per AMC (based on a 12-slot backplane) can be routed to the switch.

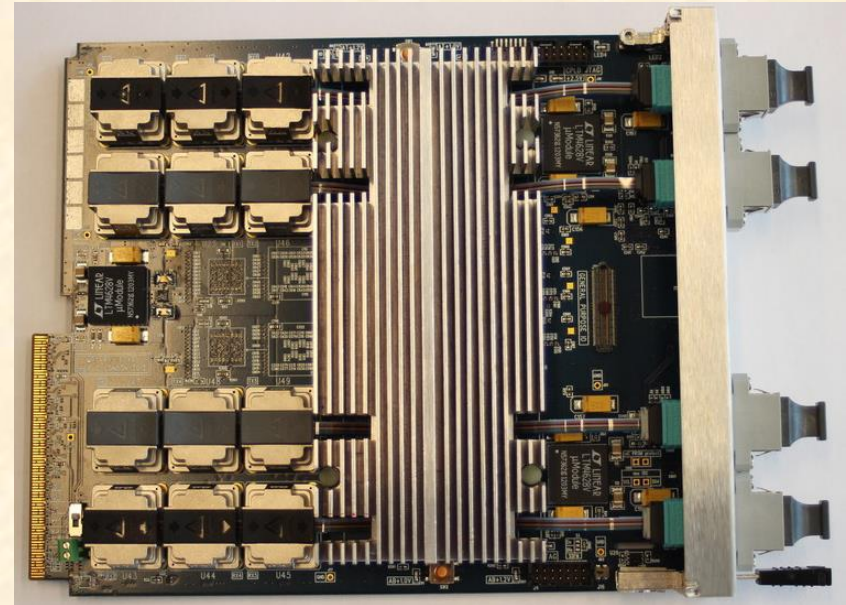
Connector Region	AMC Port #	Signal Conventions				MCH Fabric #
Common Options	0	AMC.2 1000Base-BX				A
	1	AMC.2 1000Base-BX				2/A
	2	AMC.3 SAS				B
	3	AMC.3 SAS				2/B
Fat Pipes	4	AMC.1 x4 PCIe	AMC.4 x4 SRIO	AMC.2 1000Base-BX	AMC.2 10GBase-BX4	D
	5			AMC.2 1000Base-BX		E
	6			AMC.2 1000Base-BX		F
	7			AMC.2 1000Base-BX		G
Extended Fat Pipes	8	AMC.4 x4 SRIO	AMC.2 1000Base-BX	AMC.2 1000Base-BX	AMC.2 10GBase-BX4	2/D
	9			AMC.2 1000Base-BX		2/E
	10			AMC.2 1000Base-BX		2/F
	11			AMC.2 1000Base-BX		2/G



μ TCA – An example

The CMS MP7 AMC

- A generic stream-processing engine
 - Main workhorse for the calorimeter trigger
- One Virtex-7 (XC7VX690T) FPGA
- 144 differential pairs running at 10 Gb/s
 - 72 Rx, 72 Tx
- To date, the MP7s of CMS have transferred in excess of an Exabit of data without an observed error, giving a limit on the per-board bit-error rate of approximately $3 * 10^{-17}$.
- Lessons learned:
 - Power budget (80W) at the limit
 - Density very (too?) high
 - CMS now looking into ATCA



xTCA degrees of freedom (not necessarily a complete list)

- ATCA

- Communication protocol(s) on the fabric channels
- Routing of the fabric channels on the backplane (network topology)
- Connection between front board and RTM
- Degree of redundancy
- Power supply at shelf level (230 VAC or -48 VDC)

- AMC

- Card height (13, 18 & 28 mm)
- Card width (74 & 149 mm)
- Communication protocols (currently 4 options)
- Number of pins on the connector (85 or 170)
- JTAG support

- uTCA

- AMC height & width
- Degree of redundancy (MCH, PSU, cooling)
- Routing of the fabric channels on the backplane (custom backplanes)
- JTAG support
- Connectivity of MCH to backplane (1 to 4 tongues) and type of communication protocol on the fat pipes
- Rear transition modules (MTCA.4)

xTCA issues

- The operation of an xTCA system requires a complex, standard compliant S/W infrastructure
 - Efforts to provide **open source management S/W for xTCA**: OpenSAF, SAForum
- As many features of the standard(s) are optional, products from different vendors may not be compatible
 - Efforts to insure **interoperability of xTCA products**: CP-TA, SCOPE alliance
 - Interoperability workshops
- **Sub-standards for use in “physics”**
 - **ATCA 3.8**: Standardizes RTMs and clock signals
 - **MTCA.4**: Adds RTMs (and other features) to MTCA. AMCs communicate via PCIe
- The market does not yet provide lots of **front end modules** for physics DAQ
 - See: <http://mtca.desy.de/>
- There is little information available about the **system performance** (end to end H/W performance and S/W overhead) of the data transfer links
 - This makes it difficult to dimension a DAQ system

Mezzanines

A “module” is not necessarily monolithic. Often it carries mezzanines

Use mezzanines to:

- Improve maintainability (mezzanines are easy to replace)
- Implement general purpose functions (e.g. controller, ADC, DC/DC)

- Some popular mezzanine standards

- **PMC** (IEEE P1386.1)
 - Relatively old PCI based standards for VMEbus, CompactPCI, etc.
- **XMC** (VITA 42)
 - PMC with additional high speed interface (e.g. PCIe)
- **FMC** (VITA 57)
 - Small mezzanine for FPGA based designs



PMC



FMC



XMC

Complexity is increasing

(but how can we measure that?)

By the number of pages of the standard?

Standard	Number of Pages
ATCA	660
MTCA	540
MTCA.4	100
AMC	370
IPMI 1.5	460
VME64	306
VME64X	100
VXS	60
VPX	107
NIM	75

Note: Only the base documents are listed
Sub-standards increase the volume further.
Standards for the communication protocols (PCI,
Eth. Etc) are also not counted

By the number (sub)-standard documents?

Standard family	Number of documents
ATCA (with HPM)	12
MTCA (with HPM)	8
AMC	5
VME64x	10
VXS	4
VPX	19
cPCI (with Serial and Express)	21

Complexity leads to interoperability
issues and long development cycles

How much xTCA for the upgrade of the LHC Experiments?

- All experiments have looked at xTCA for various upgrade projects and took different roads....
 - ALICE: No xTCA (but PCIe cards in servers and still VMEbus)
 - ATLAS: ATCA
 - CMS: MTCA (and later also ATCA)
 - LHCb: No xTCA (but PCIe cards in servers)

xTCA features in they eyes of the LHC experiments:

xTCA feature	ALICE	ATLAS	CMS	LHCb
Redundancy of I/O modules	Not important	Not important	Not important	Not important
Board space	MTCA sufficient	ATCA needed	MTCA and ATCA needed	PCIe sufficient
Cooling	Server PC sufficient	Important. Up to 400 W per blade	Important	Server PC sufficient
Integration density	Minor advantage	Not important	Minor advantage	Not important
Hot Plug	Not important	Not important	Used but not crucial	Not important
Costing	Chosen solution cheaper	Not an issue	Good deal	Chosen solution cheaper
xTCA strong points	None	Cooling, card size, PSU, IPMI (powerful but complex)	Good (but complex) system standards	Cooling and PSU quality. PCs may be less reliable

Science fiction

- PICMG has announced **GEN4** in 2014
 - <http://www.picmg.org/gen4-new-high-performance-platform/>
 - System throughput (to **hundreds of terabits/s**), module bandwidth (to tens of terabits/s), and storage capacity in **exabytes**.
 - Module cooling capacity (over **2000 Watts**, with **fluid cooling** options)
 - Not H/W compatible with ATCA
 - What I read in my crystal ball:
 - Don't expect H/W before 2020++ (now progress update since 2014)
 - Try not to be an early adopter
- **Optical backplanes**
 - Not a new idea
 - Already exist for niche applications
 - Very expensive
 - What I read in my crystal ball:
 - Will come but not anytime soon
- **Servers**
 - Data processing may shift from FPGA to CPU (or hybrids)
 - Networks will play a more important role
 - Servers with custom PCIe I/O cards may become (more) attractive
 - **No longer science fiction for LHCb and ALICE**

So, what is the right standard for me?

- This obviously **depends on** your **requirements**
 - **Bandwidth & latency**
 - Availability of **commercial products** (front end)
 - **Existing infrastructure** (S/W and H/W) and expertise in your experiment
 - **Start** and **duration** of the experiment
 - **Scalability** requirements
- Trends in HEP
 - LHC & experiments @ CERN: Still VMEbus & PCI based
 - **CMS**: Several μ TCA systems in operation
 - **ATLAS**: ATCA proposed as VMEbus replacement, many R&D projects
 - **LHCb and ALICE**: first favored ATCA then decided to go for PCs
 - **Beam control**: μ TCA for (non LHC) machine control under discussion
 - Control systems of new accelerators: **μ TCA everywhere**
 - XFEL @ DESY, SCLS @ SLAC, FAIR @ GSI