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Further developments on Data communication related to FE processing in Medical Imaging

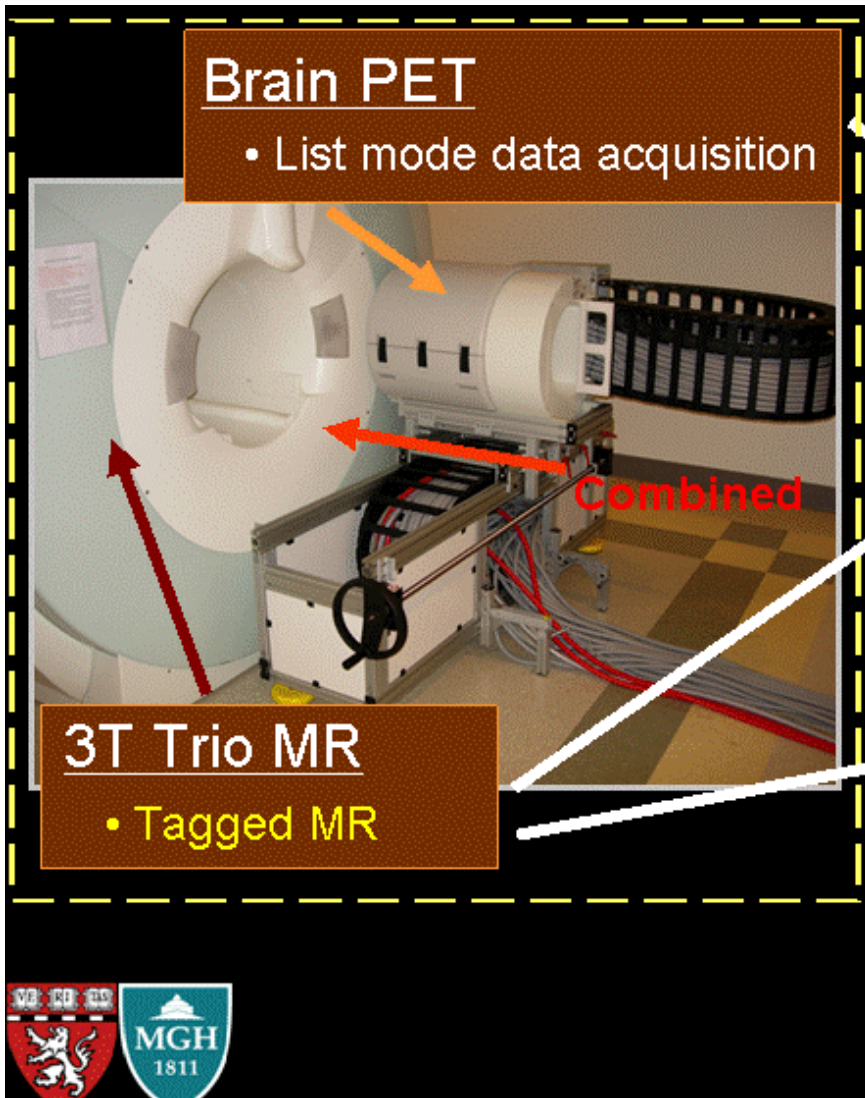
Georgios Konstantinou



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European Union's Seventh Framework Programme
for research, technological development and
demonstration under grant agreement n° 317446

Outline

- Introduction
- Event rate expected
- Readout of single event
- Firmware architecture
- Data throughput
- Workplan



G. El Fakhri, MGH-Harvard

Issues:

Detectors size
Connections to the DAQ

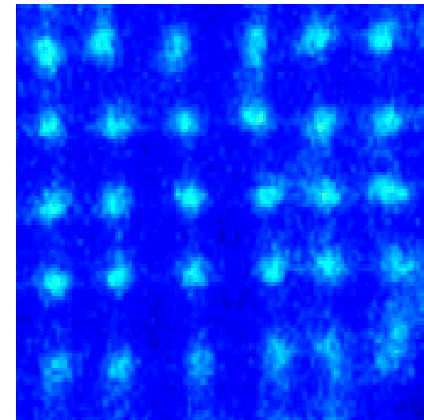
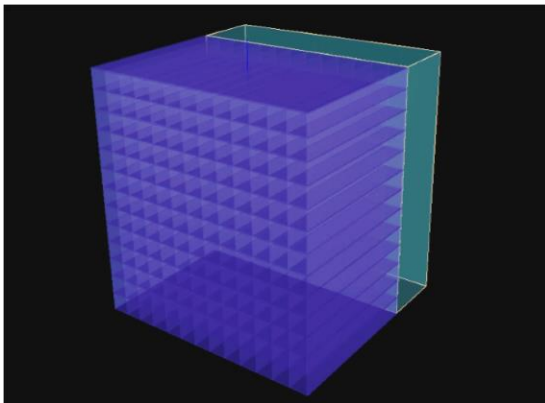
Detectors size: SiPM + SSLE

Sub-Surface Laser Engraving for scintillators

- **SSLE Nd:YAG laser and GAMOS simulations**
- **Scintillator pixelation without external reflectors**
- **Depth of interaction have been achieved.**

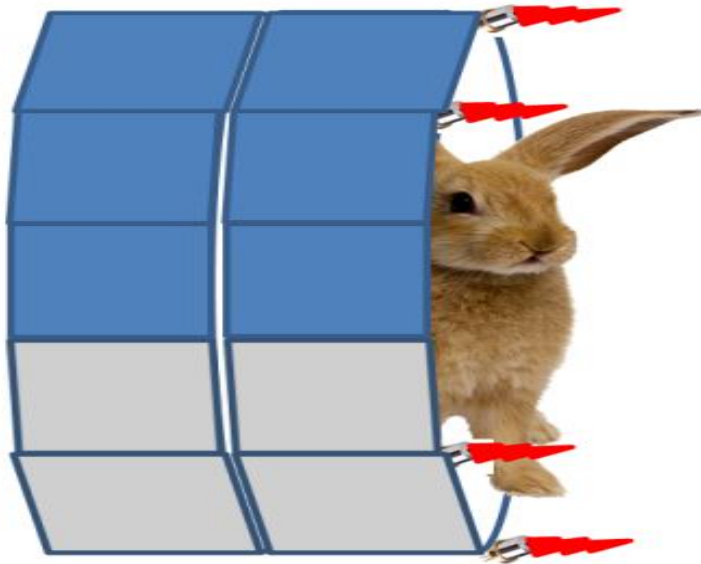
Advantages:

- Design flexibility**
- Higher packing fraction and sensitivity**
- Light sharing necessary for Anger logic**
- Cost effectiveness.**



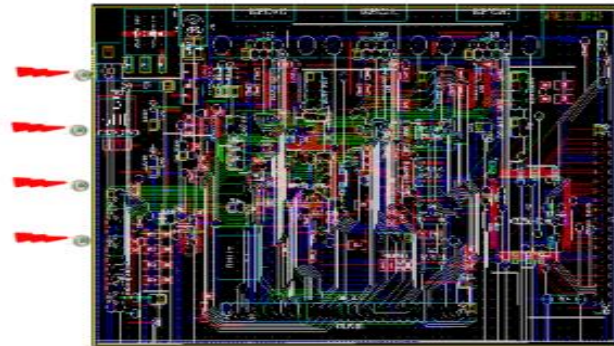
Connections: wireless detector

- How far out of the MRI is far enough?
- What wavelength could do the trick?
- How much electronics can we keep outside?
- What are the drawbacks?



Insert

Can this be wireless?



base station

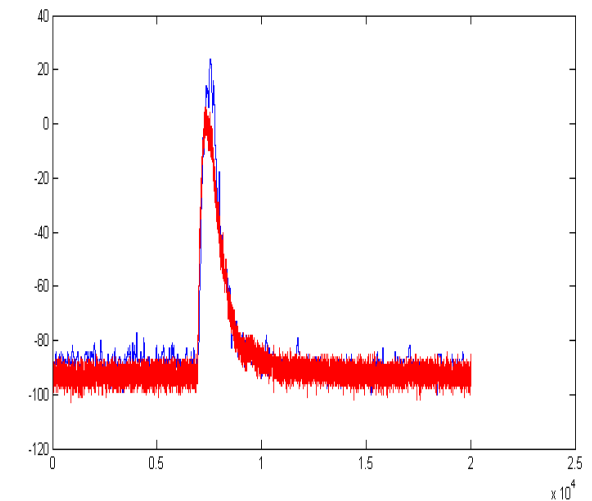
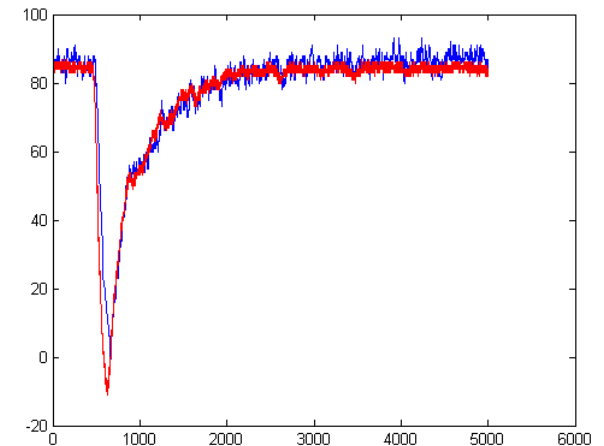
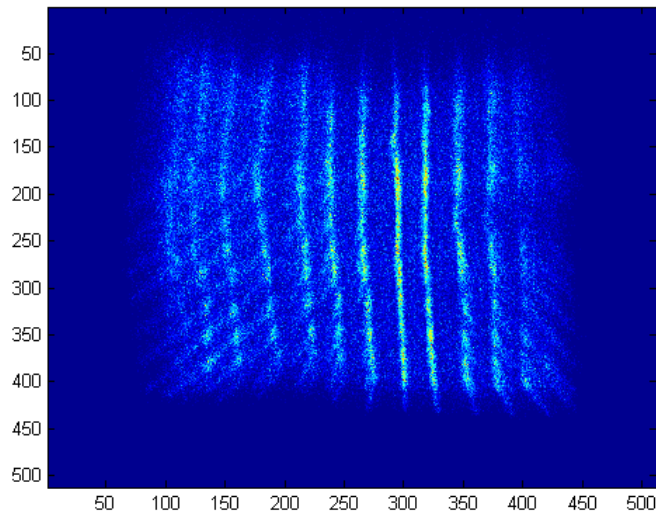
Initial experimental setting

- Necessary measurements for PET:
 - Transmission jitter $\rightarrow \sim 80$ ps, within specifications
 - Transmission bandwidth \rightarrow higher than 250 MHz (sufficient)



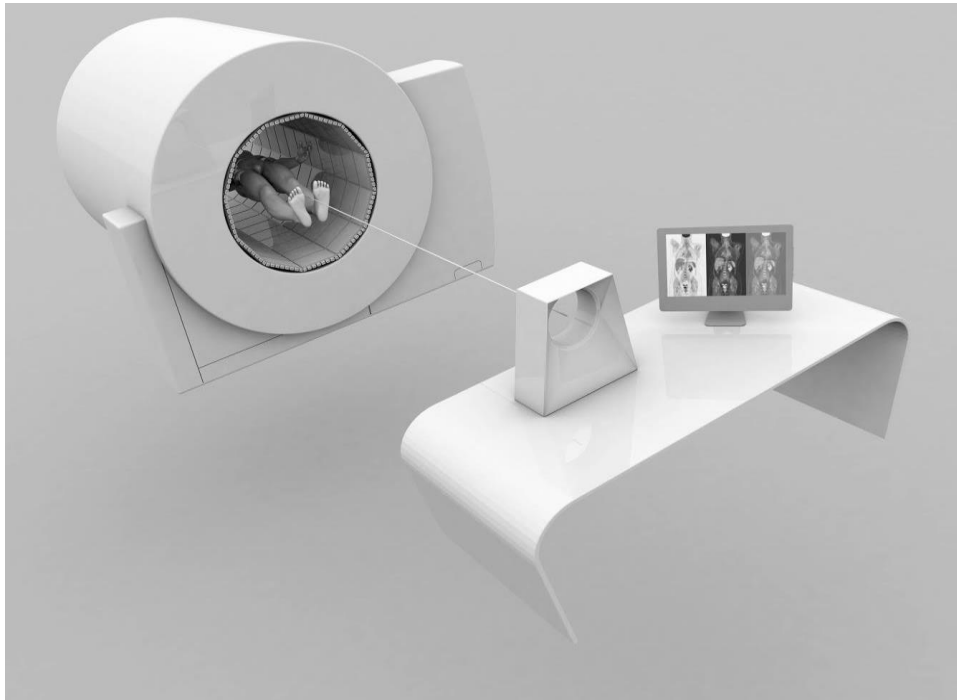
Testing

- Amplified output (red Tx, blue Rx)
- SiPM output (red Rx, blue Tx)
- Profile with conventional and OWC channels



First ideas

- Innovative, cost-effective, miniaturized, versatile MR-compatible front-end scintillation detector.
- Handheld gamma camera



Wireless analog front-end



Gamma camera

Current status

- ✓ Studies on the application of shorter scintillator crystal treated with SSLE techniques
- ✓ Prototyping with SiPM
- ✓ Studies on feasibility of analog OWC

What about data processing?

Nutaq PicoDigitizer-125

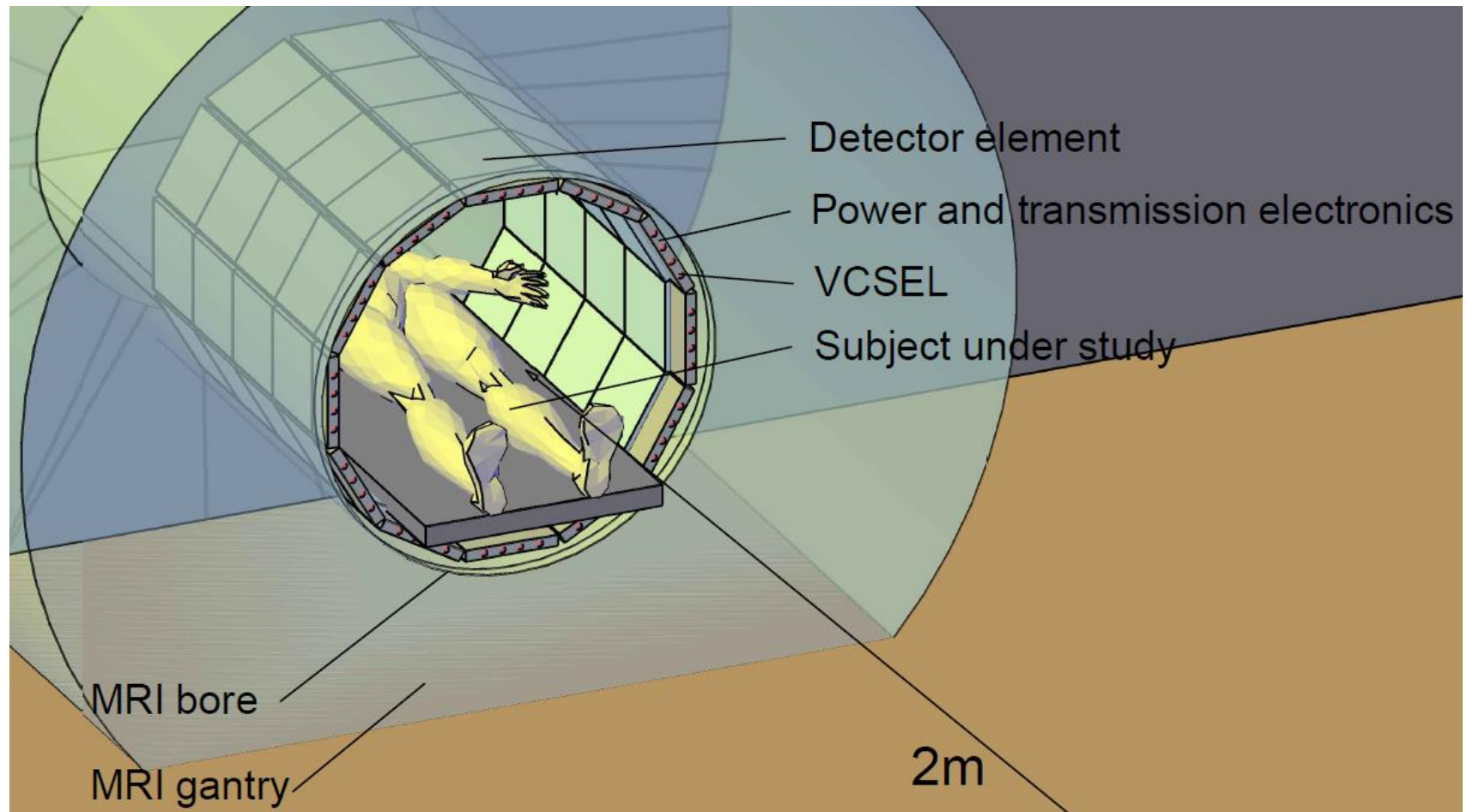
Key Features:

- Up to 64 channels coupled to a large Virtex-6 FPGA
- 125 MSPS ADCs, 14 bit resolution
- Phase aligned channels and phase coherent sampling
- GigE and PCIe 4x high speed interfaces
- AC-DC coupling options, single-ended or differential
- Model-based design integration
- Optional DACs, 1000 MSPS (Int. Modes), 16-bit



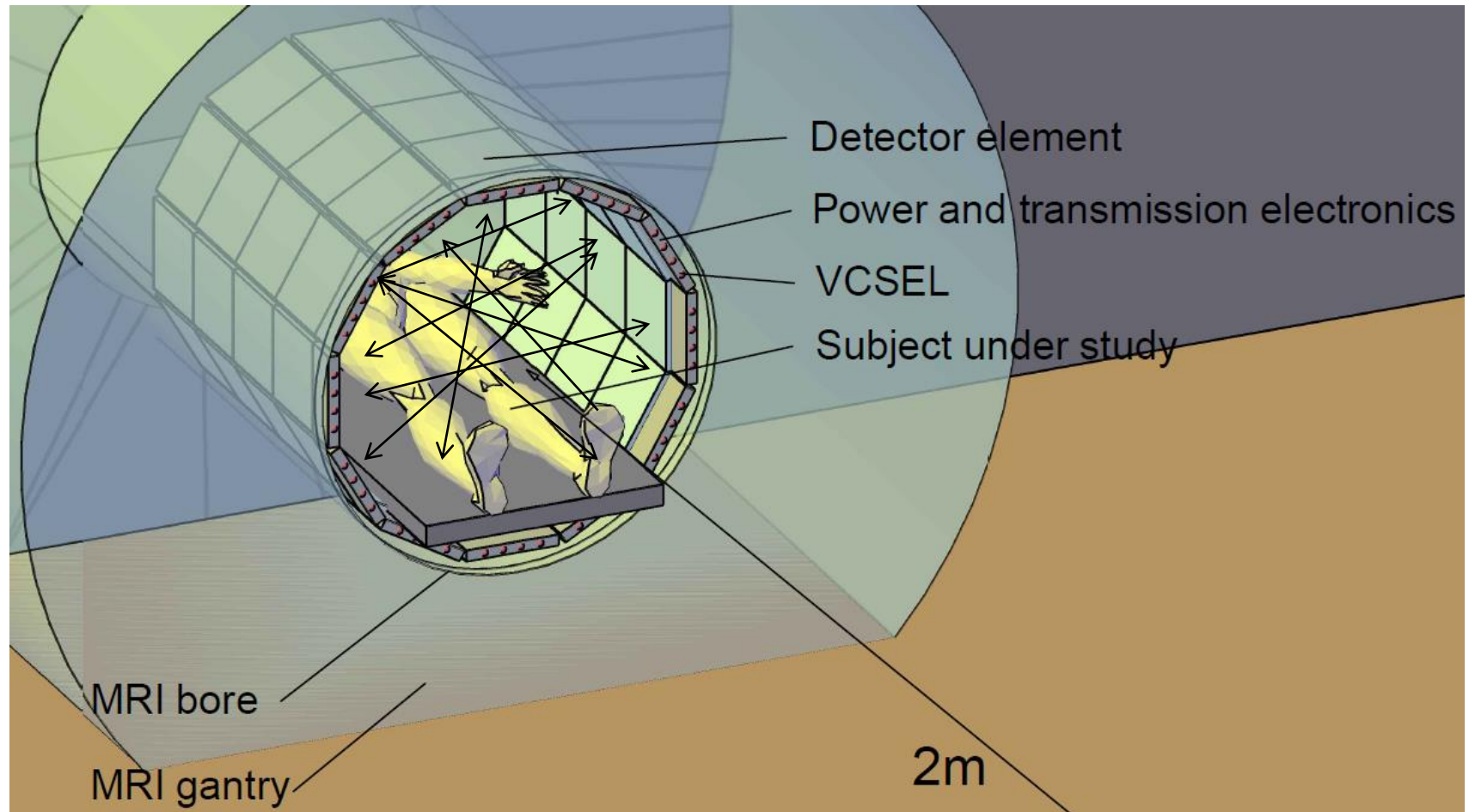
Event rate calculation

■ Focusing on the subject under study:



Event rate calculation

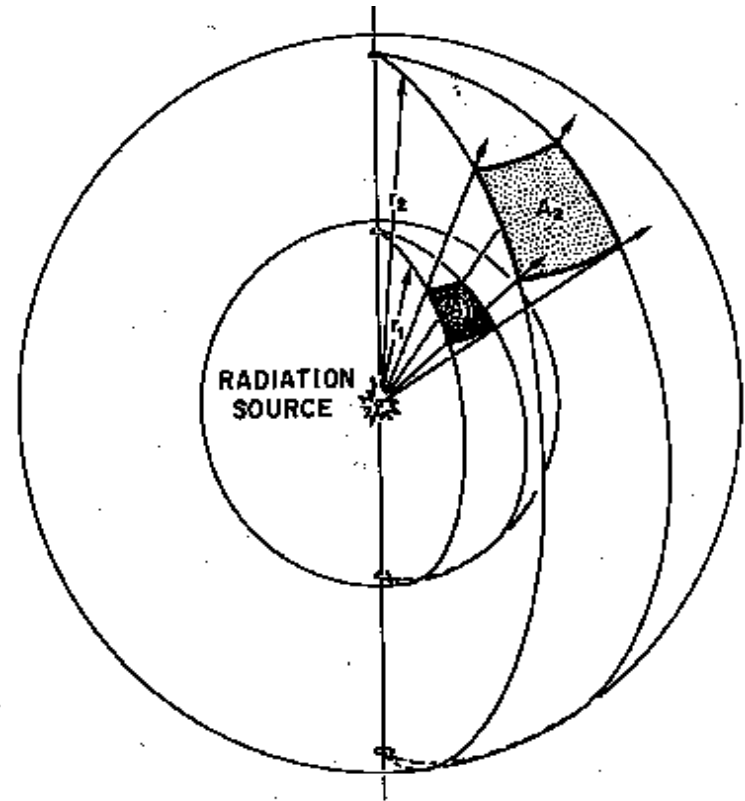
■ Focusing on the subject under study:



Event rate calculation

Theoretical model:

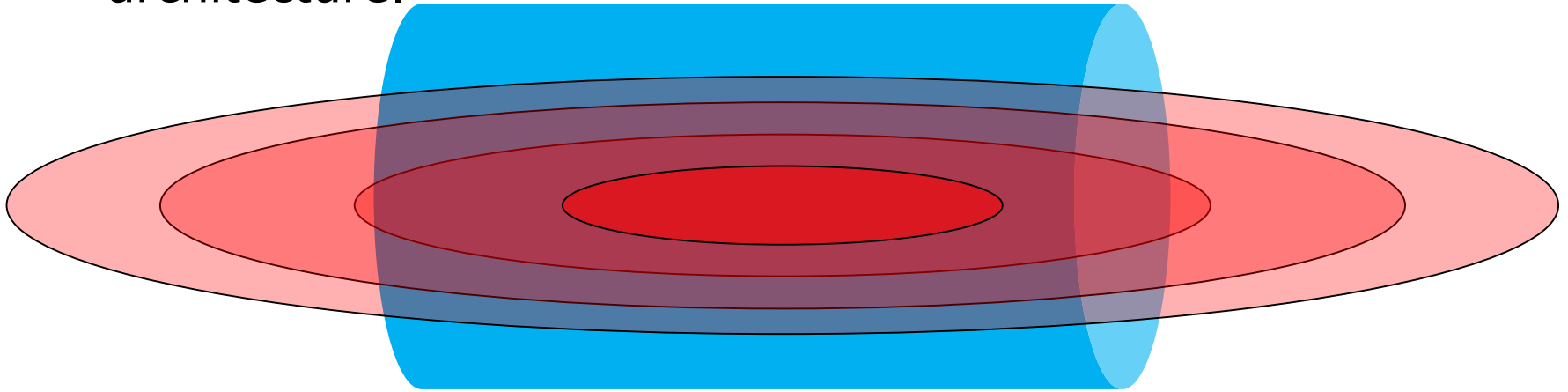
- Radioactive source with spatial distribution of spherical (or spheroid, depending on the considered shape of source) field.
- The intensity of the field is a function of the radiotracer dose.
- The detector (square of area a^2) has a given distance h from the center, thus a solid angle of $\Omega = \frac{a^2}{h^2}$ maximum.
- The radiant intensity equals $I_E = \frac{\partial \Phi}{\partial \Omega}$



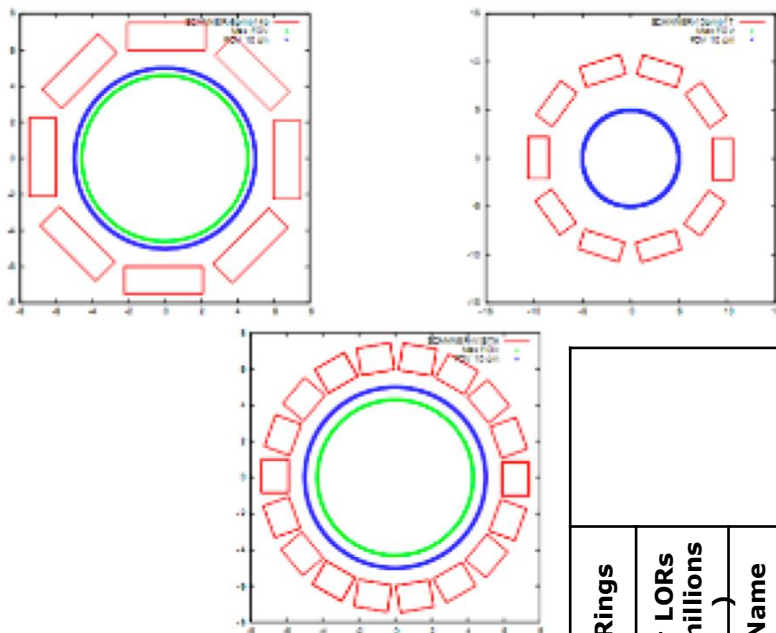
Event rate calculation

Theoretical model:

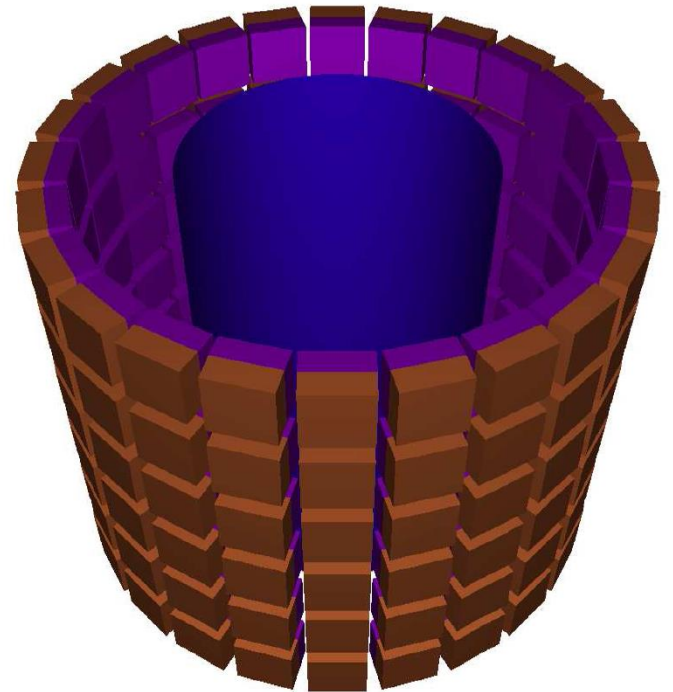
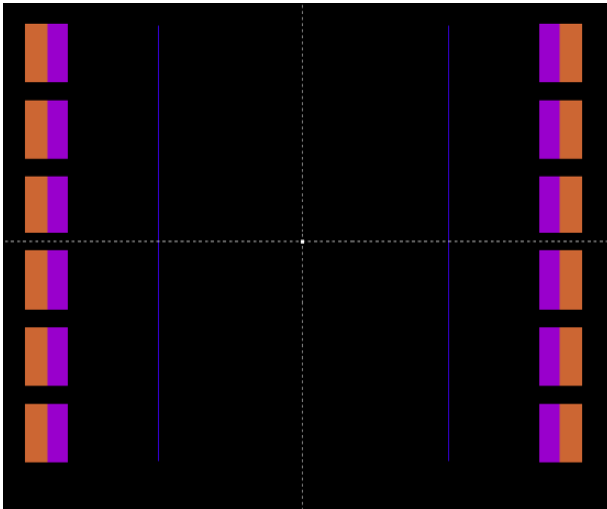
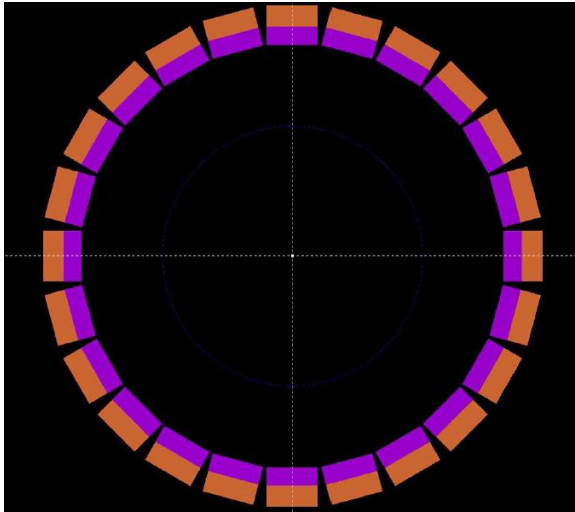
- Taking into account the dead time in order **to avoid pile-up for 95%** of events (also cosmic, singles) we choose the **Maximum Acquired Rate** (MAR) from expected radiant intensity.
- **MAR < 1Mhz** limits I_E and Ω , thus $a^2 < 6\text{cm}^2$, for each independent readout.
- With this modular dimension, we build our detector architecture.



Existing systems



Scanner									FOV Trans-axial (cm)	FOV Axial (cm)	CPSS 250-700 KeV (%)	FWHM (Intirns ic, mm)
Rings	# LORs (millions)	Name	Gap Size (mm)	Diam (cm)	Detec/R	# Det. In coinc.	Crystal Length and pitch (mm)					
2	28	Vista	7.8	11.8	18	7	7(LYSO)+8(GSO) 1.55	8.6 (7.0-8.0)	4.8	4.0	1.5	
4	143	Inveon	0.1	16.1	16	9	10 (LSO) 1.60	12. (10.0-11.0)	12.8	10.9	1.7	
6	543		6.0	16.2	24	11	7(LYSO)+8(GSO) 1.55	12.5 (10.5-11.5)	15.0	10.1	<1.6	
5	377		6.0	16.2	24	11	7(LYSO)+8(GSO) 1.55	12.5 (10.5-11.5)	12.5	8.6	<1.6	



Geometry calculation

- To build a cylindrical insert, the diameter D of which is dictated by the dimensions of the MRI bore and the thickness of the module h_{module} . To evaluate the number of modules per ring we follow the equation:

$$N_{\text{detectors}} = \left\lfloor \frac{2\pi a}{\arcsin\left(\frac{a}{D - 2 * h_{\text{module}}}\right)} \right\rfloor$$

- For the height of the cylinder, since not the whole length of the bore is necessary, we take the dimensions of the desired field of view

$$N_{\text{rings}} = \left\lceil \frac{h_{\text{FOV}}}{a} \right\rceil$$

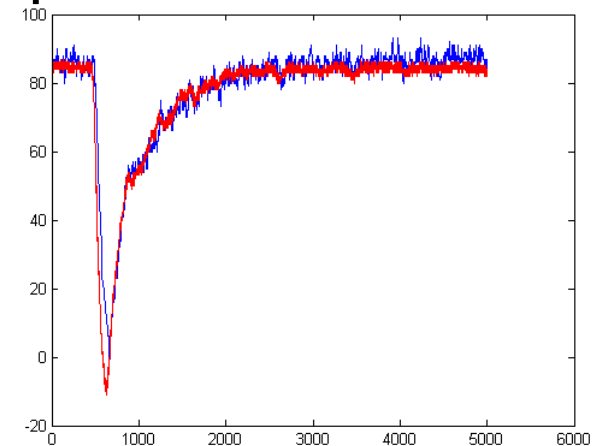
- Realistic example:

- $D=20$ cm,
- $h_{\text{FOV}}=20$ cm
- $a=5.8$ cm,
- $h_{\text{module}}=2.2$ cm

$$N_{\text{detectors}} = 16 \text{ and } N_{\text{rings}} = 4 \rightarrow 64 \text{ modules}$$

Readout of detector element: pulse model

- Scintillation event:
 - Described by bi-exponential model: $e^{-t/0.72} - e^{-t/43}$
 - Duration ~ 200 ns
- Spectrum: Depends on the bandwidth of electronics (theory \rightarrow infinite, practice changes the model)
- **Digitalization Rate** of ~ 200 Mhz possible and sufficient (~ 5 ns step)
- Digital pulse duration: ~ 40 words
- Digitalization in 12bits/word
- Pulse digital size: 16 bits.

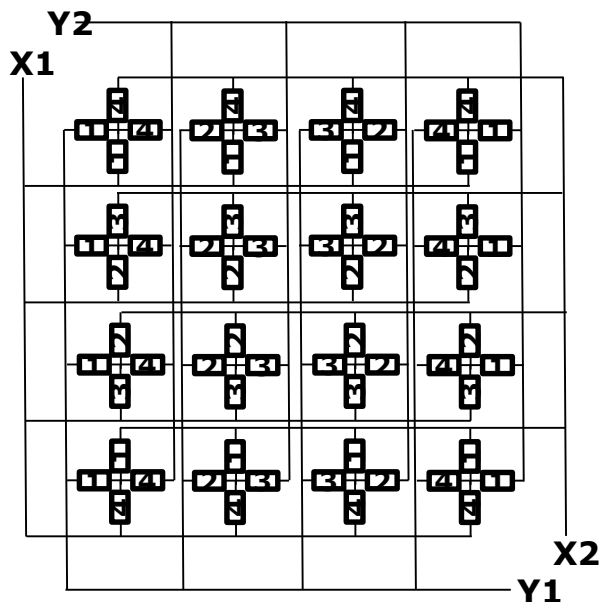
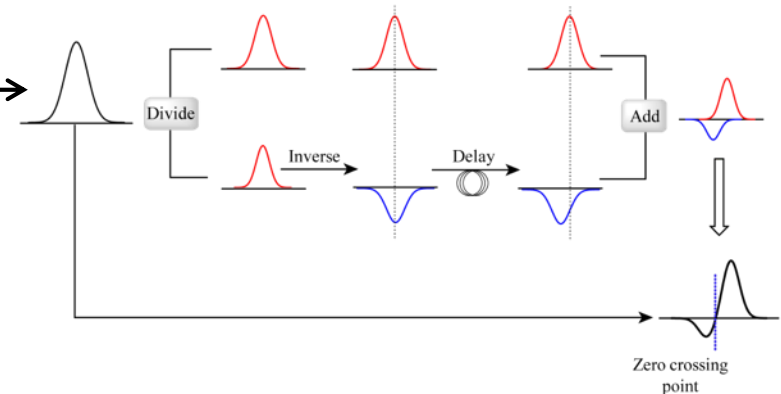


Deterioration of fast element due to high frequency filtering

Readout of detector element

■ Event information:

- Timing
- Fine position (pixel ID), X and Y
- Event Energy



■ Constant fraction discriminator

- This is not relevant for the Gamma camera

■ Charge addition network (Anger logic) codifying position and energy from the integrals of pulses:

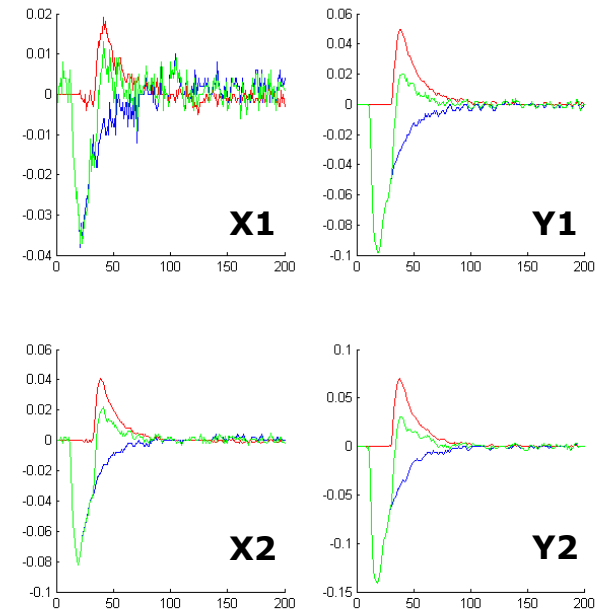
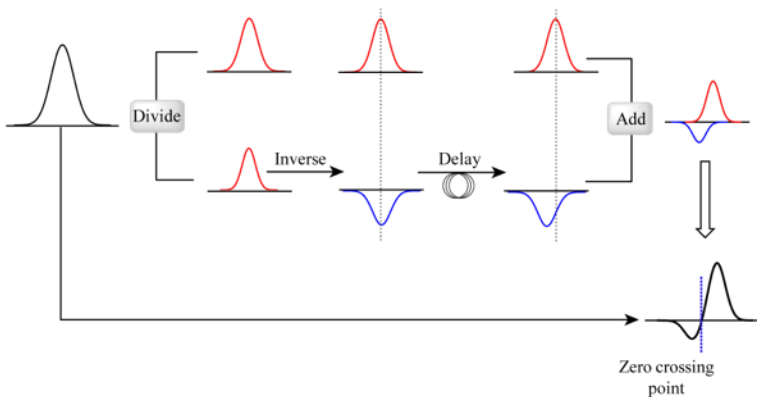
$$X = \frac{X_1 - X_2}{X_1 + X_2}$$

$$Y = \frac{Y_1 - Y_2}{Y_1 + Y_2}$$

$$E = X_1 + X_2 + Y_1 + Y_2$$

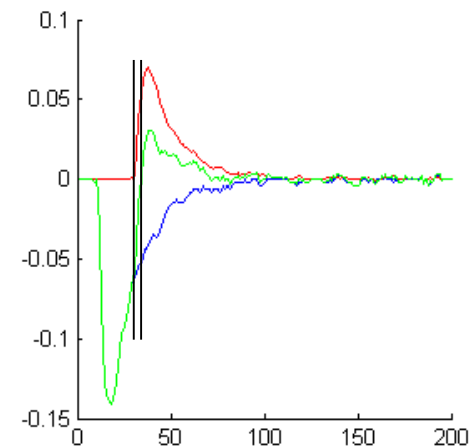
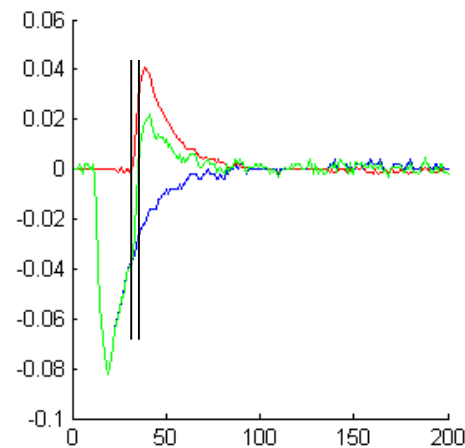
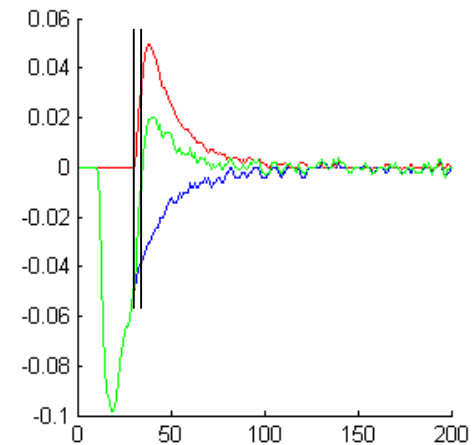
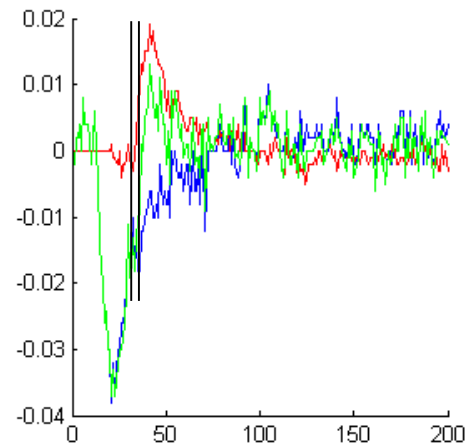
Readout of detector element- timing (CFD)

- Since anyway four pulses are recorded for energy measurement, **why not evaluate all four and take a mean?**
- Another idea, take a weighted mean, depending on predominant channel (more energy, event closer to the given channel pair, timing more accurate)



Readout of detector element- timing

- Zero crossing point results from **linear interpolation** between bigger negative and smaller positive value.
- By scaling the values to the MSB a small look up table can be created to avoid the division necessary for interpolation
- 2^6 values \rightarrow fine time $< 100\text{ps}$.



Readout of detector element-energy/position

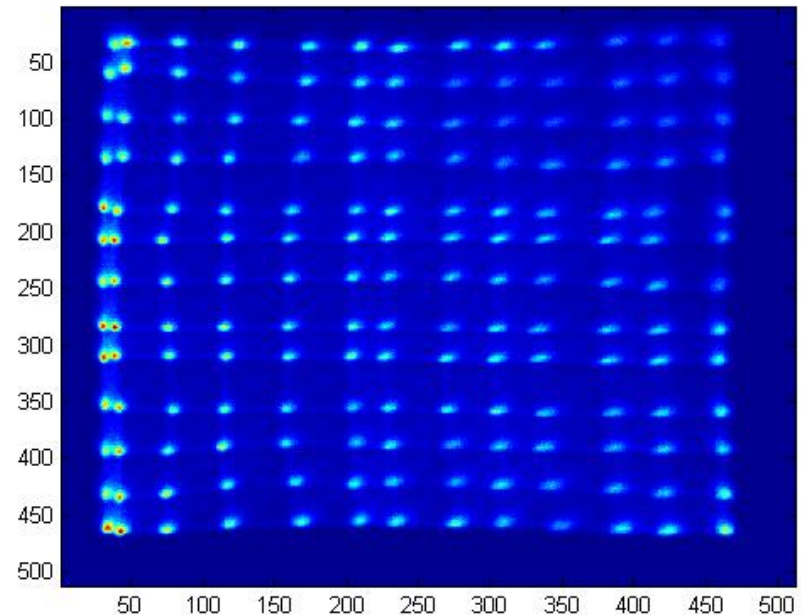
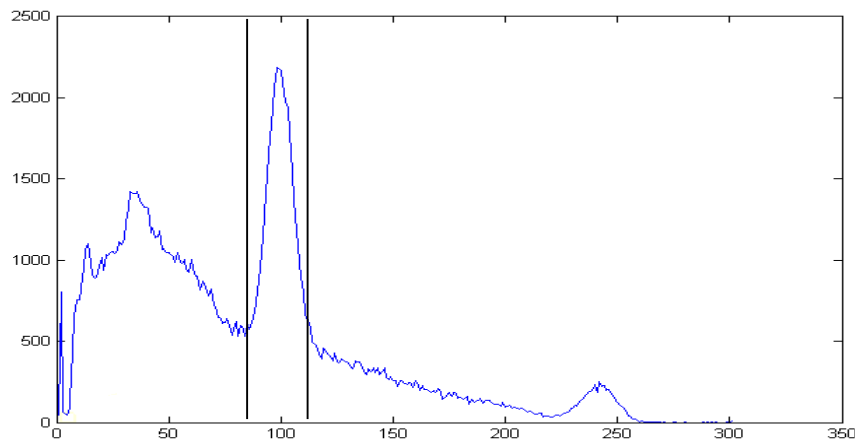
Integration by addition of words of pulse duration: Can be rounded (no need for 2^{16} different values).

How many bits are necessary for the results (generously)?

512 values for X, Y

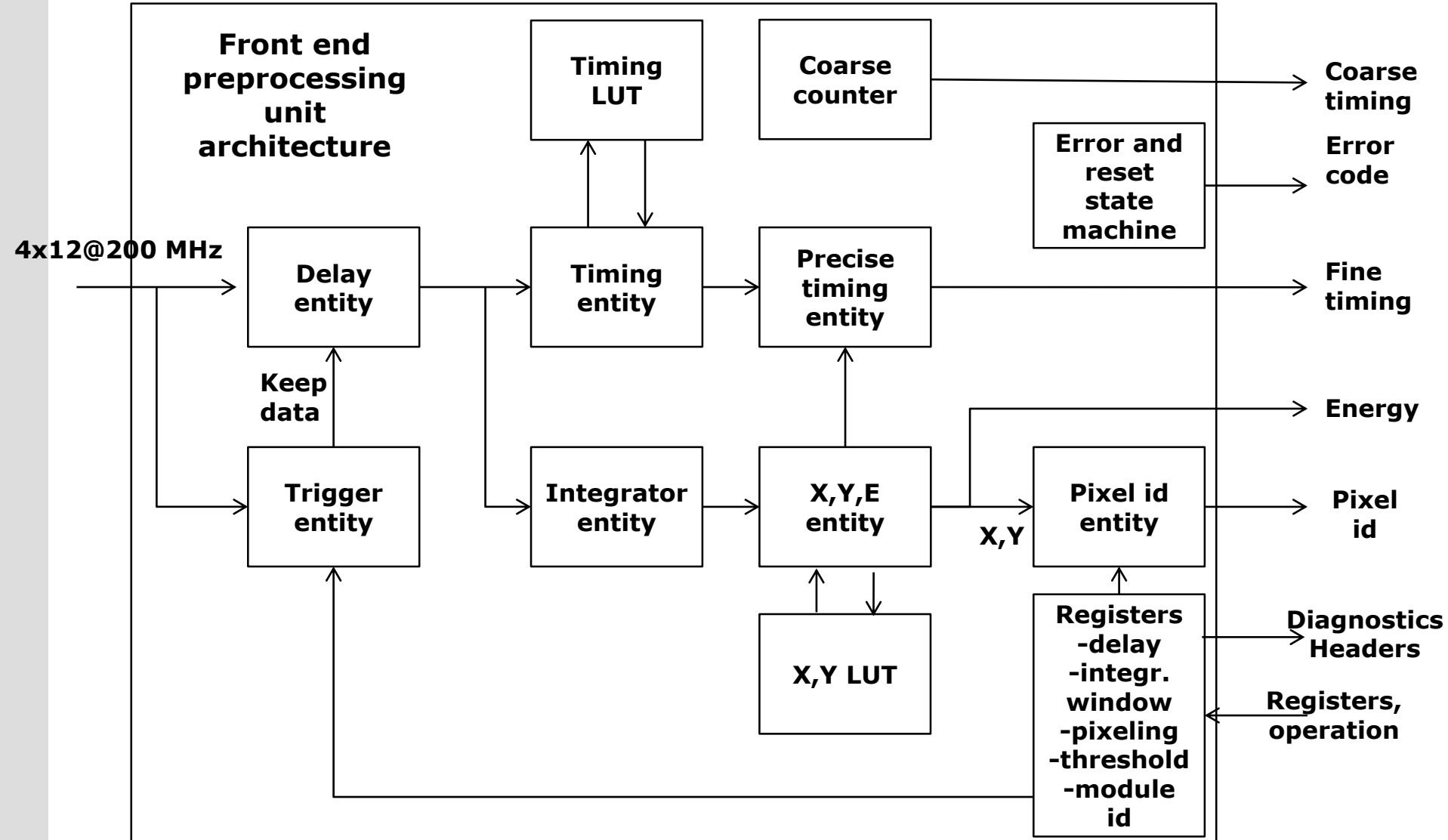
256 values for Energy

Thus $2^{16} \rightarrow 2^9$

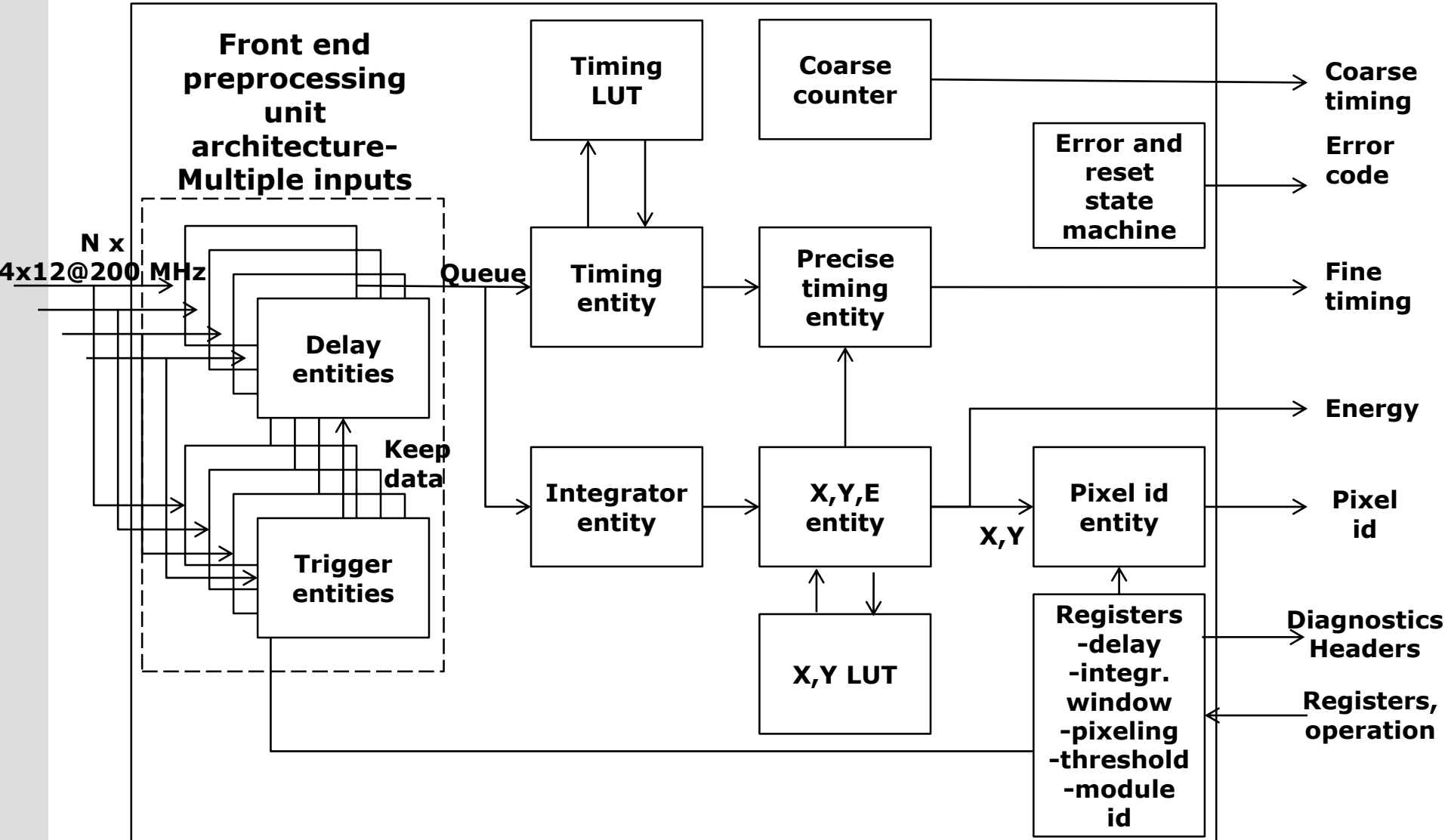


- X,Y can be calculated through a LUT, to avoid digital division...
- Furthermore, once a detector image has been analyzed, X,Y can be given directly in pixel ID, needing 11 bits (pixel size ~ 1 mm)...

Firmware architecture



Firmware architecture-multiple detectors



Workplan

- We need to evaluate the size of the architecture, but initial goal is a small FPGA (Artix, Zynq PL, Cyclone).
- The possibility of more than one front-end modules connected to one FPGA will be also evaluated.
- Most of the independent entities have been algorithmically developed.
- A big number of pre-recorded pulses exist and will be used for test benching.
- Secondment will be undertaken in INFN Pisa in November, supervised by Giancarlo Sportelli as an FPGA specialist.



The end



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Firmware architecture- Gamma camera

