

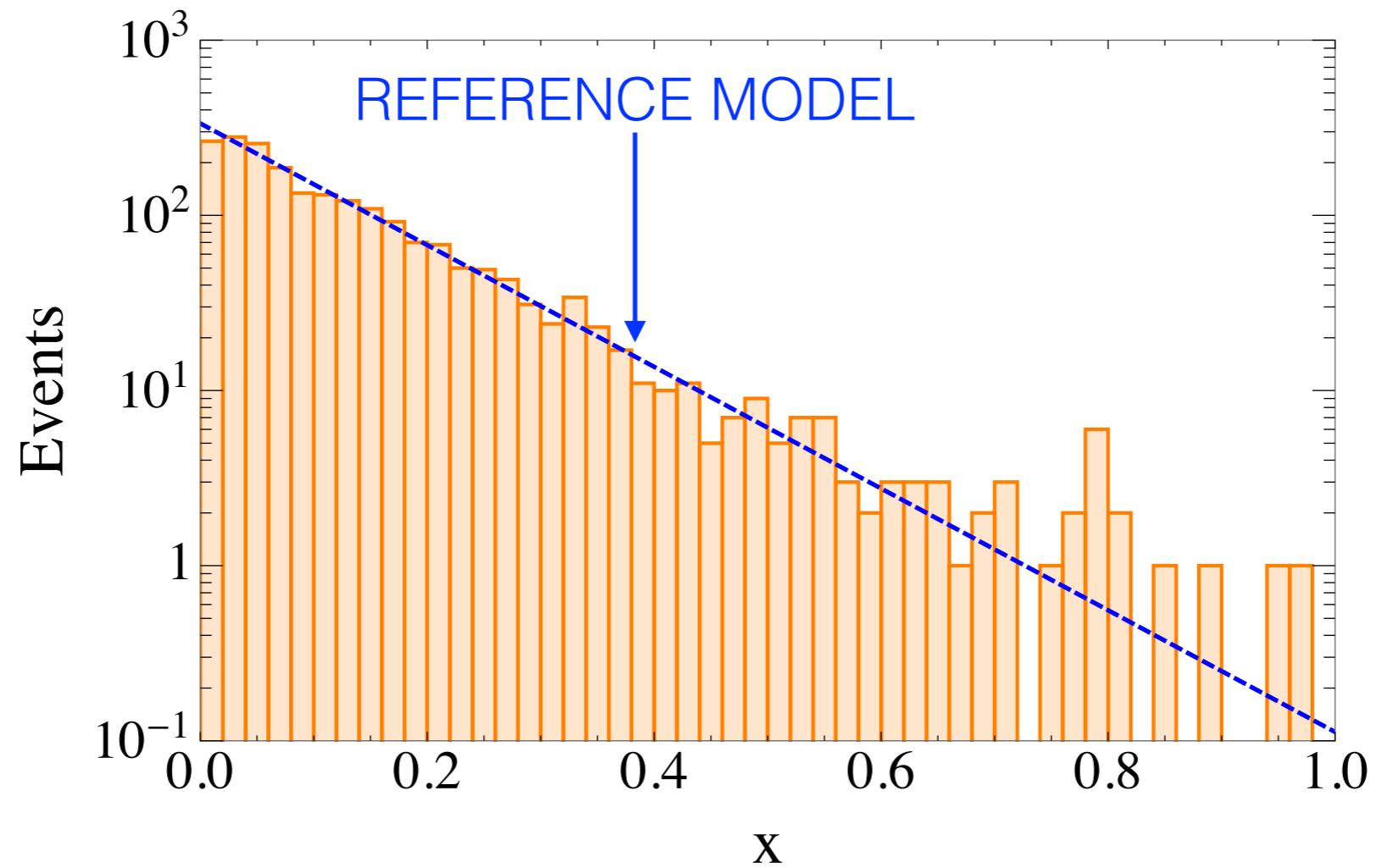
# LEARNING NEW PHYSICS FROM A MACHINE

Raffaele Tito D'Agnolo - SLAC



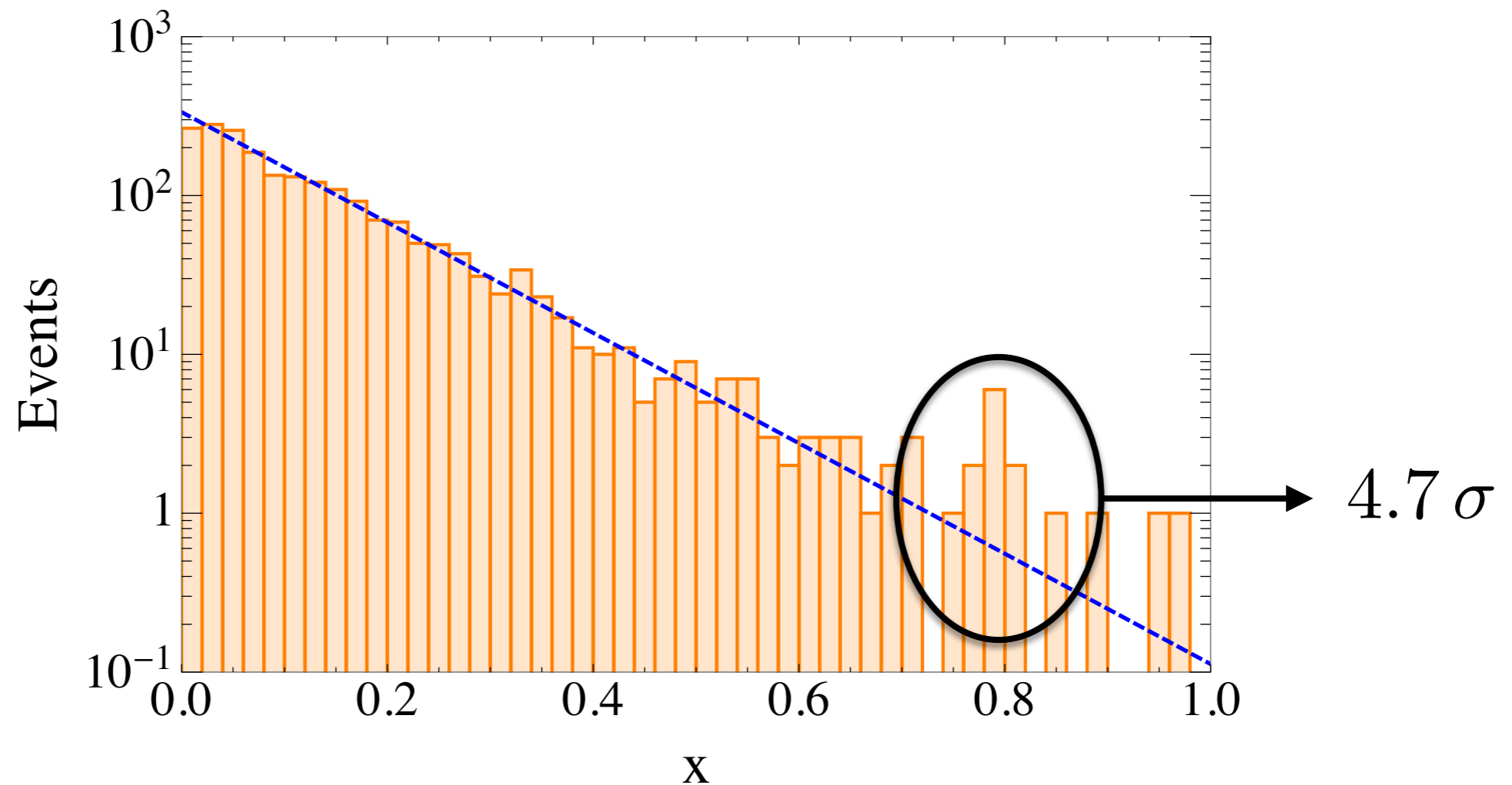
Raffaele Tito D'Agnolo and Andrea Wulzer  
1806.02350, Phys.Rev. D99 (2019) no.1, 015014

# THE PROBLEM



$$\chi^2 = 47 \quad N_{\text{bins}} = 50 \quad p\text{-value} < 1\sigma$$

# THE PROBLEM



$$t_{\text{id}}(\mathcal{D}) = 2 \log \left[ \frac{e^{-N(\text{NP})}}{e^{-N(\text{R})}} \prod_{x \in \mathcal{D}} \frac{n(x|\text{NP})}{n(x|\text{R})} \right]$$

# WHAT IS A NEURAL NETWORK?

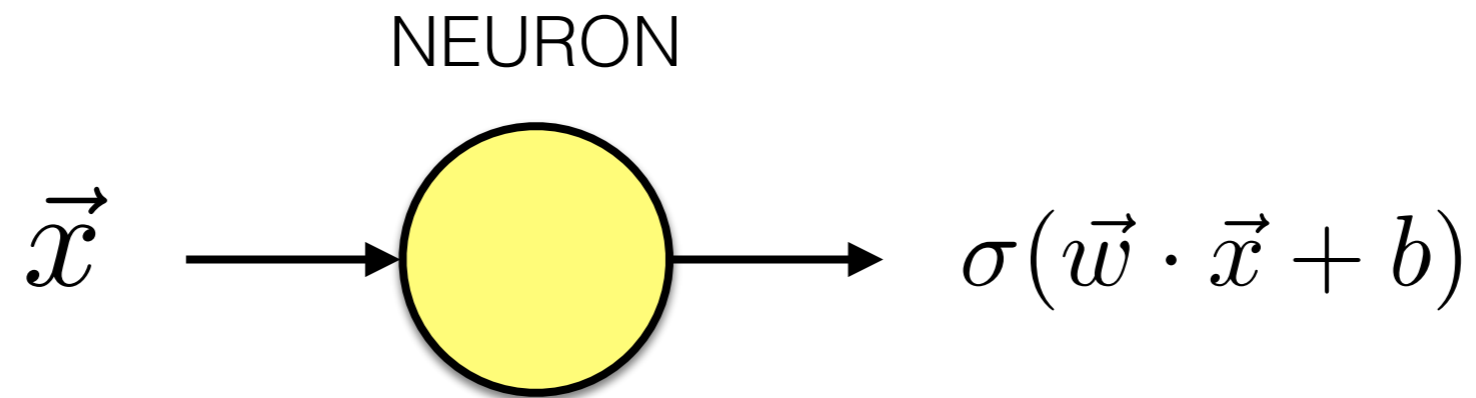
SET OF FUNCTIONS  
+  
FITTING ALGORITHM

# WHAT IS A NEURAL NETWORK?

## SET OF FUNCTIONS

$$f_{w_1}^{(1)} \left( f_{w_2}^{(2)} \left( f_{w_3}^{(3)} (\dots) \right) \right)$$

# BUILDING BLOCKS

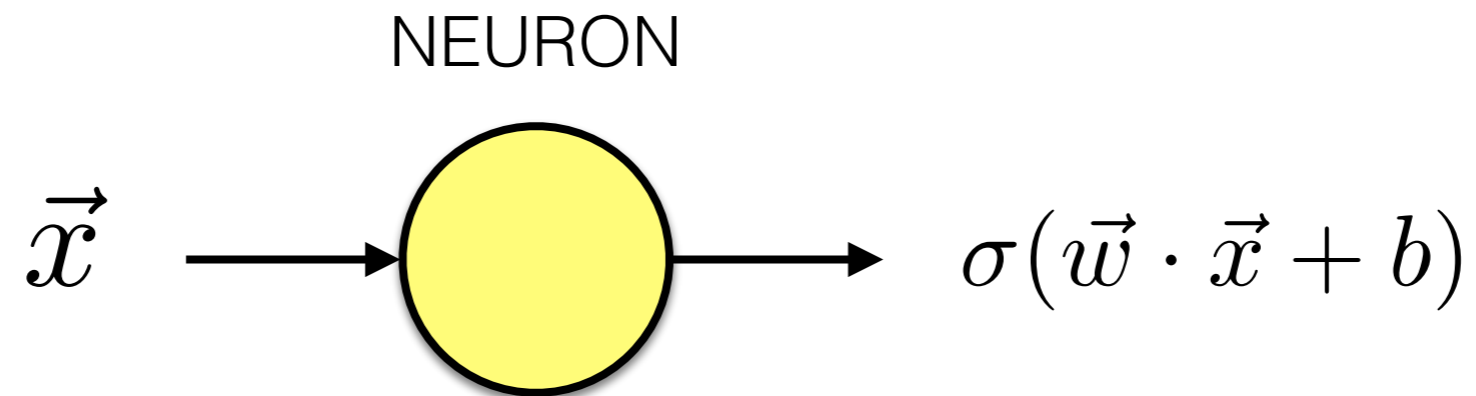


1. LINEAR TRANSFORMATION  $z = \vec{w} \cdot \vec{x} + b$

FREE PARAMETERS

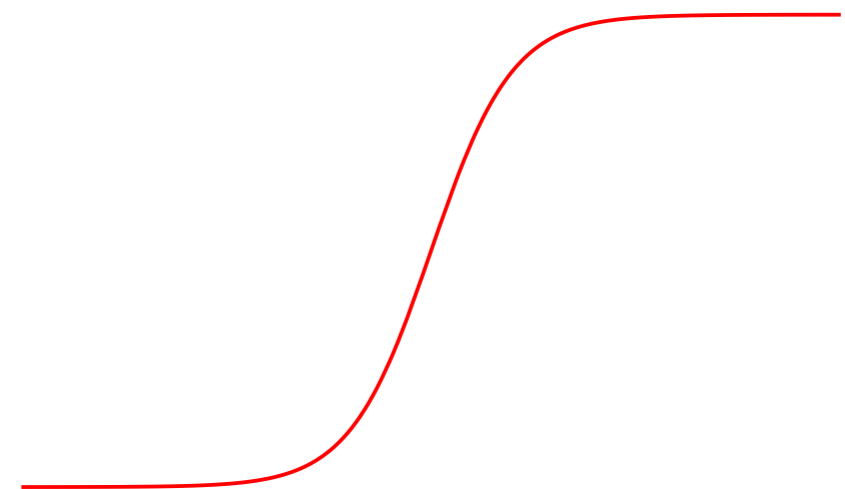
2. NON-LINEAR TRANSFORMATION  $\sigma(z)$  FIXED

# BUILDING BLOCKS



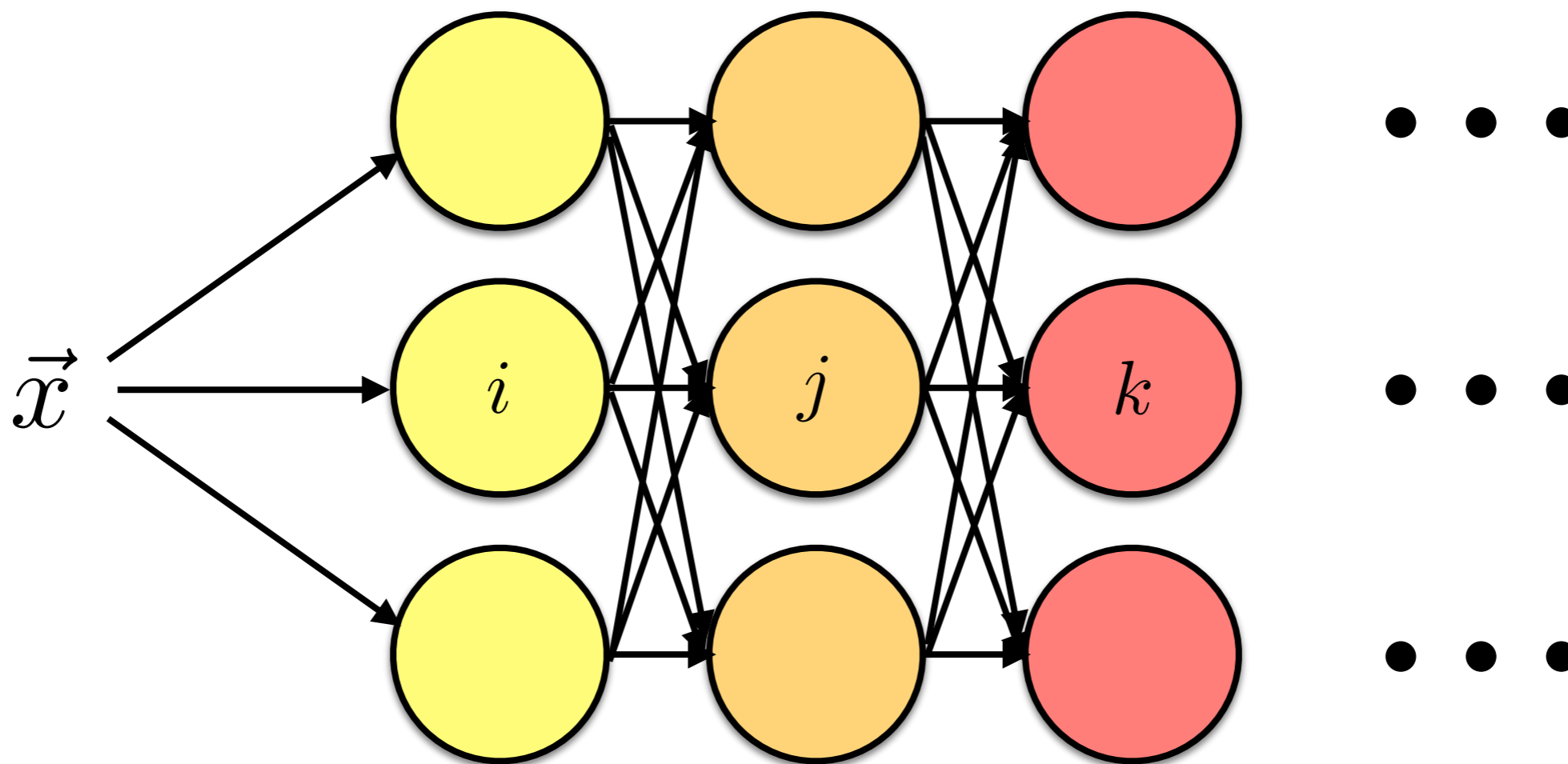
## 2. NON-LINEAR TRANSFORMATION

$$\sigma(z) = \begin{cases} \tanh(z) \\ \text{ReLU} \\ \frac{1}{1+e^{-z}} \\ \dots \end{cases}$$



# THE NETWORK

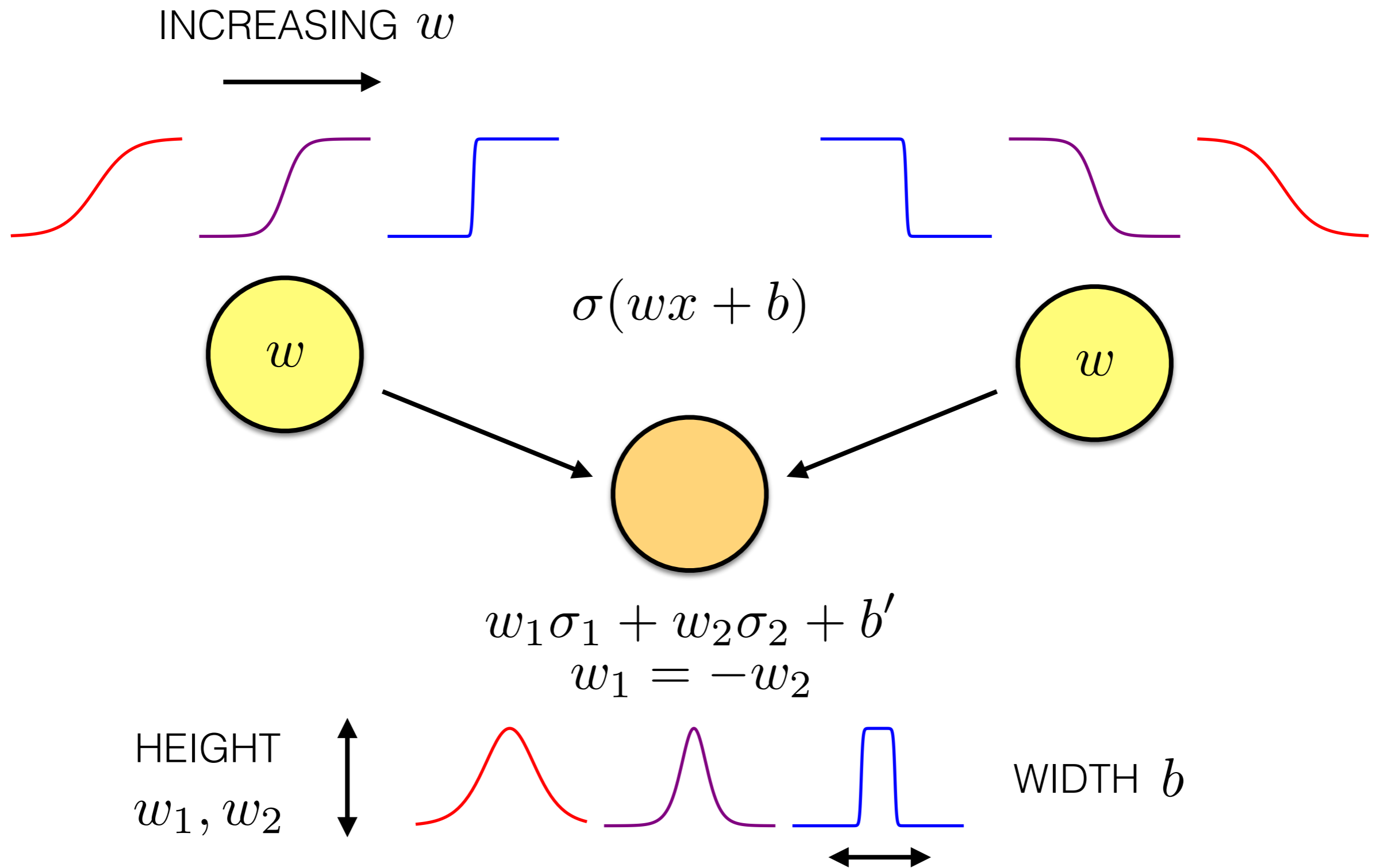
FEEDFORWARD, FULLY CONNECTED



$$\sigma \left( \sum_{k=1}^3 w_{jk} \sigma_k \left( \sum_{i=1}^3 w_{ki} \sigma_i \left( \sum_{l=1}^d w_{il} x_l + b_i \right) + b_k \right) + b_j \right)$$



# UNIVERSAL APPROXIMANTS



# MAXIMUM LIKELIHOOD DICTIONARY

## ELEMENTARY STATISTICS

PARAMETERS

$$\theta$$

LIKELIHOOD

$$\mathcal{L}(\theta; x)$$

DATA

## NEURAL NETWORK

WEIGHTS AND BIASES

$$w, b$$

LOSS FUNCTION

$$-L(w, b; x)$$

TRAINING SAMPLE

# FITTING ALGORITHM

LOSS FUNCTION



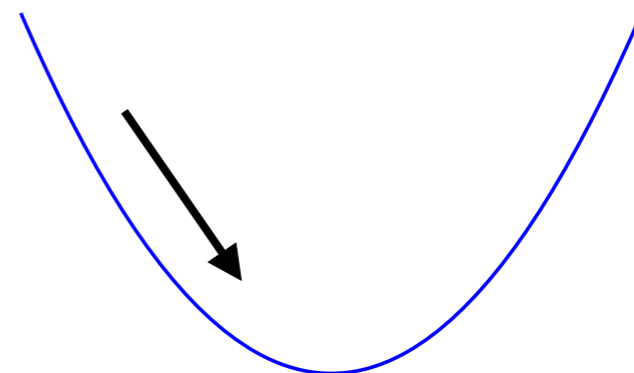
$$L = \frac{1}{N_c} \sum_{i=1}^{N_c} [1 - f_{NN}(\vec{x}_i, \mathbf{w}, \mathbf{b})]^2 + \frac{1}{N_d} \sum_{j=1}^{N_d} [f_{NN}(\vec{x}_j, \mathbf{w}, \mathbf{b})]^2$$

TRAINING

$$w_{t+1} \rightarrow w_t - \epsilon \partial_w \hat{L}$$

$\hat{L}$  SUBSET OF THE SAMPLE

$\epsilon$  LEARNING RATE

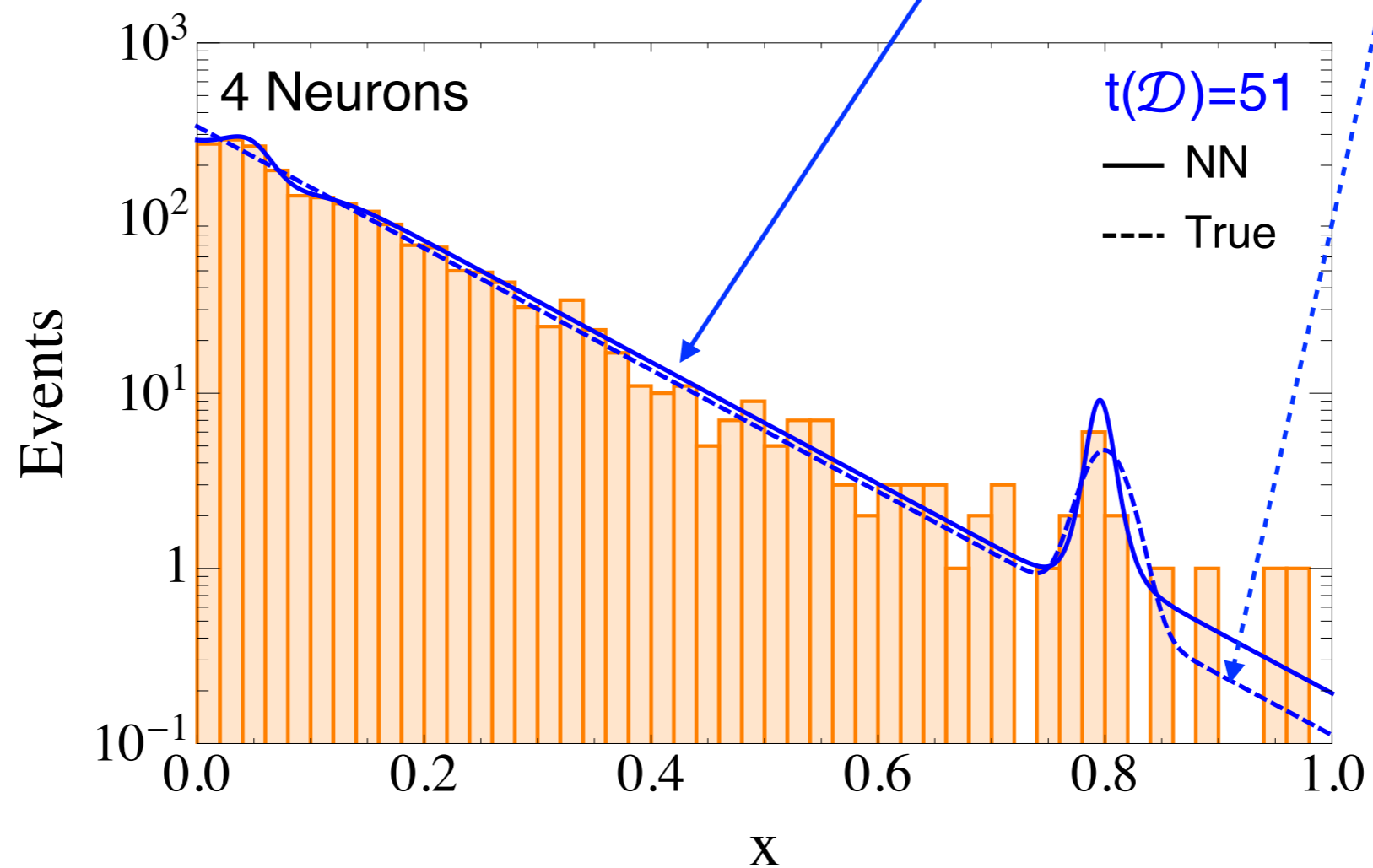


# LEARNING NEW PHYSICS



# A SIMPLE STRATEGY

1. LEARN THE DATA DISTRIBUTION  $n(x|\hat{\mathbf{w}}) \approx n(x|\mathbf{T})$



# A SIMPLE STRATEGY

1. LEARN THE DATA DISTRIBUTION  $n(x|\hat{\mathbf{w}}) \approx n(x|\mathbf{T})$
2. CHECK IF IT IS DIFFERENT FROM THE REFERENCE ONE

$$t(\mathcal{D}) = 2 \log \left[ \frac{e^{-N(\hat{\mathbf{w}})}}{e^{-N(\mathbf{R})}} \prod_{x \in \mathcal{D}} \frac{n(x|\hat{\mathbf{w}})}{n(x|\mathbf{R})} \right] \quad p_{\text{obs}} = \int_{t_{\text{obs}}}^{\infty} dt P(t|\mathbf{R})$$

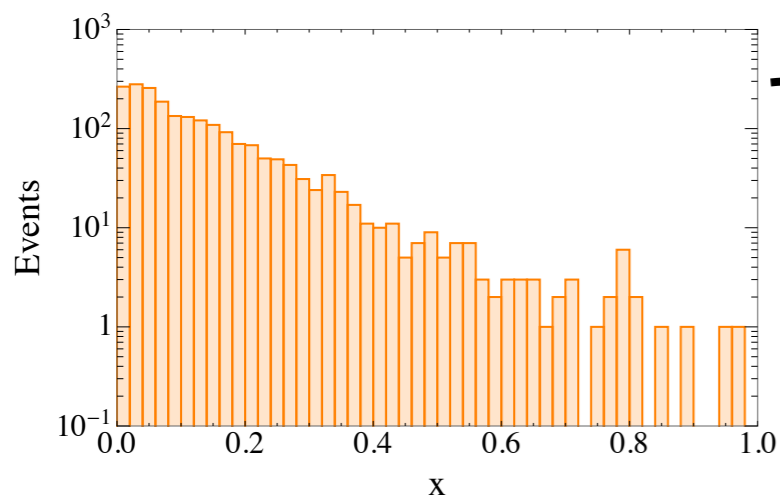
↓  
STANDARD LIKELIHOOD RATIO  
NEYMAN-PERSON TEST STATISTIC

↓  
REFERENCE  
DISTRIBUTED  
TOYS

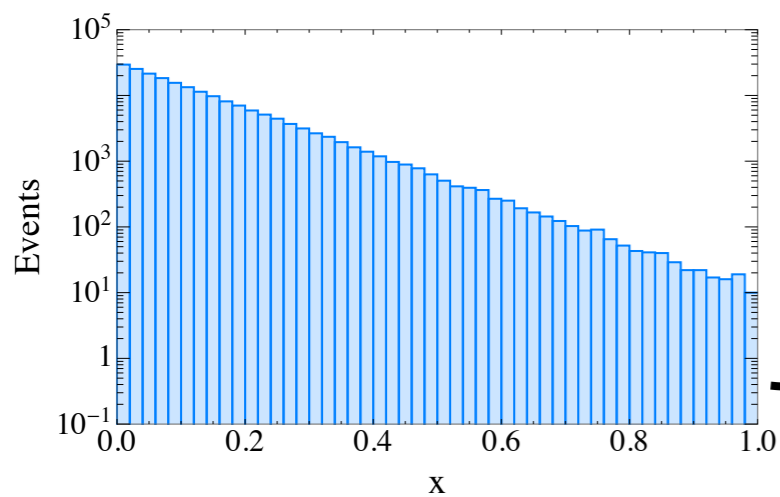
# LEARNING PDFs

## INPUT

Data sample  $\mathcal{D}$

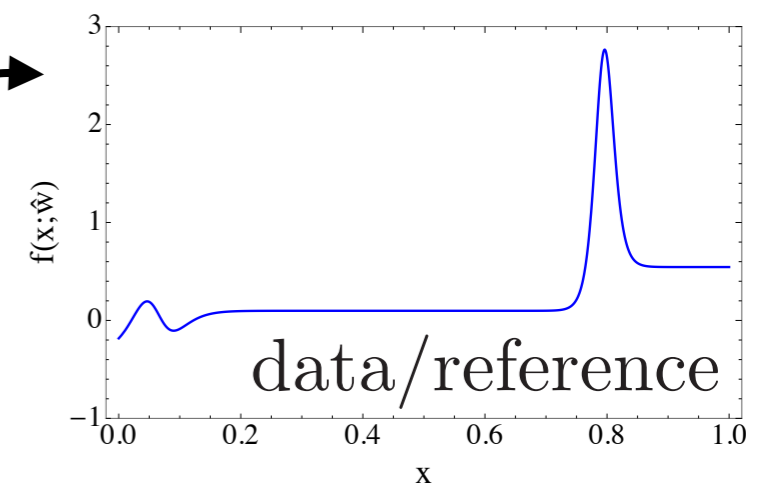


Reference sample  $\mathcal{R}$



## OUTPUT

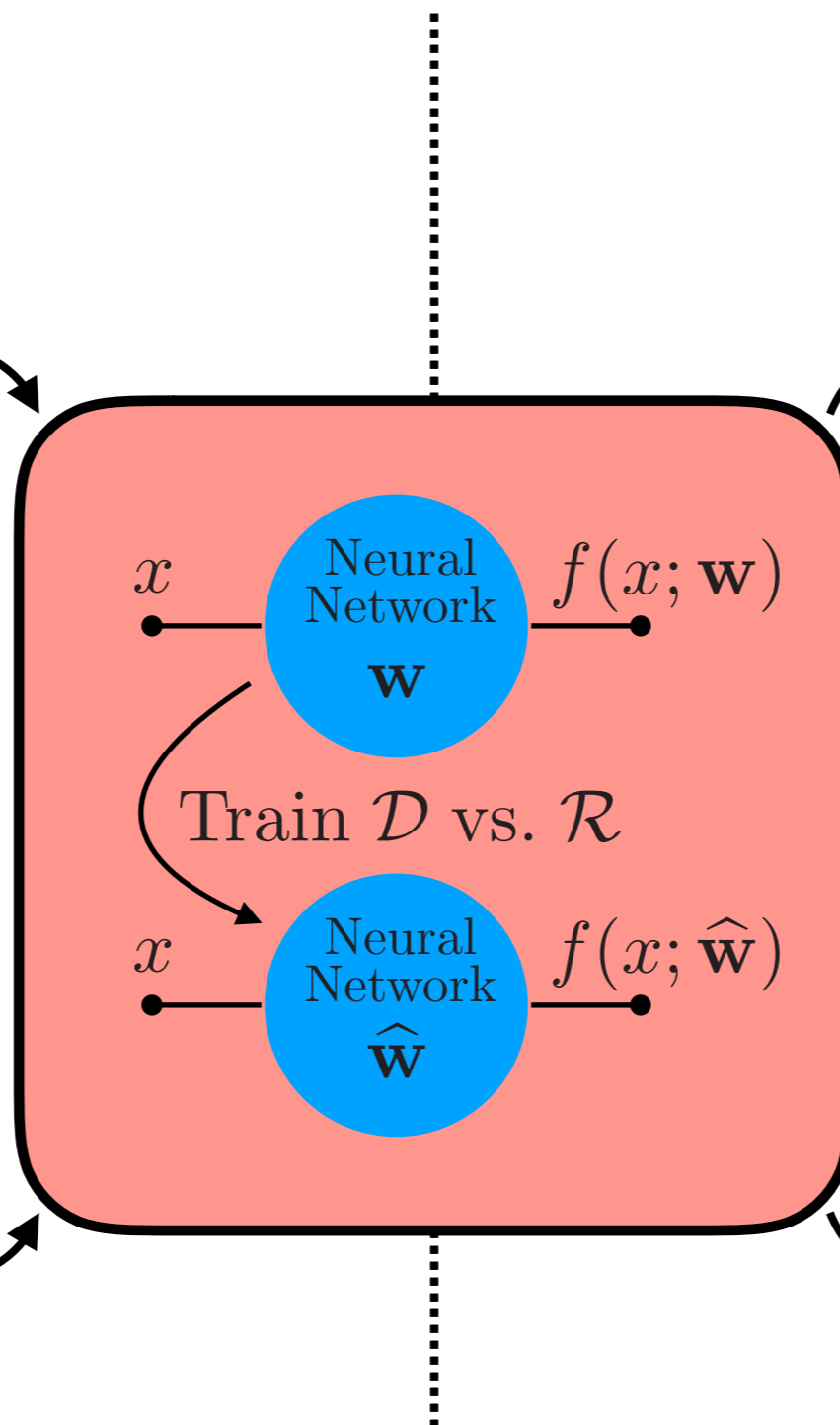
Dist. log ratio



$$f(x; \hat{\mathbf{w}}) \simeq \log \left[ \frac{n(x|\mathcal{T})}{n(x|\mathcal{R})} \right]$$

**Test statistic  $t$**   
computed on the  
data sample  $\mathcal{D}$

$$t(\mathcal{D}) = -2 \underset{\{\mathbf{w}\}}{\text{Min}} L[f]$$



# THE LOSS FUNCTION

$$n(x|\mathbf{w}) = n(x|\mathbf{R}) e^{f(x;\mathbf{w})} \longrightarrow \text{NEURAL NETWORK}$$

$$t(\mathcal{D}) = 2 \log \left[ \frac{e^{-N(\hat{\mathbf{w}})}}{e^{-N(\mathbf{R})}} \prod_{x \in \mathcal{D}} \frac{n(x|\hat{\mathbf{w}})}{n(x|\mathbf{R})} \right]$$

$$= -2 \operatorname{Min}_{\{\mathbf{w}\}} \left[ \frac{N(\mathbf{R})}{\mathcal{N}_{\mathcal{R}}} \sum_{x \in \mathcal{R}} (e^{f(x;\mathbf{w})} - 1) - \sum_{x \in \mathcal{D}} f(x;\mathbf{w}) \right]$$

$$\equiv -2 \operatorname{Min}_{\{\mathbf{w}\}} L[f(\cdot, \mathbf{w})] \longrightarrow \text{LOSS FUNCTION}$$



# SUMMARY

## 1. TRAIN THE NETWORK ON THE DATA

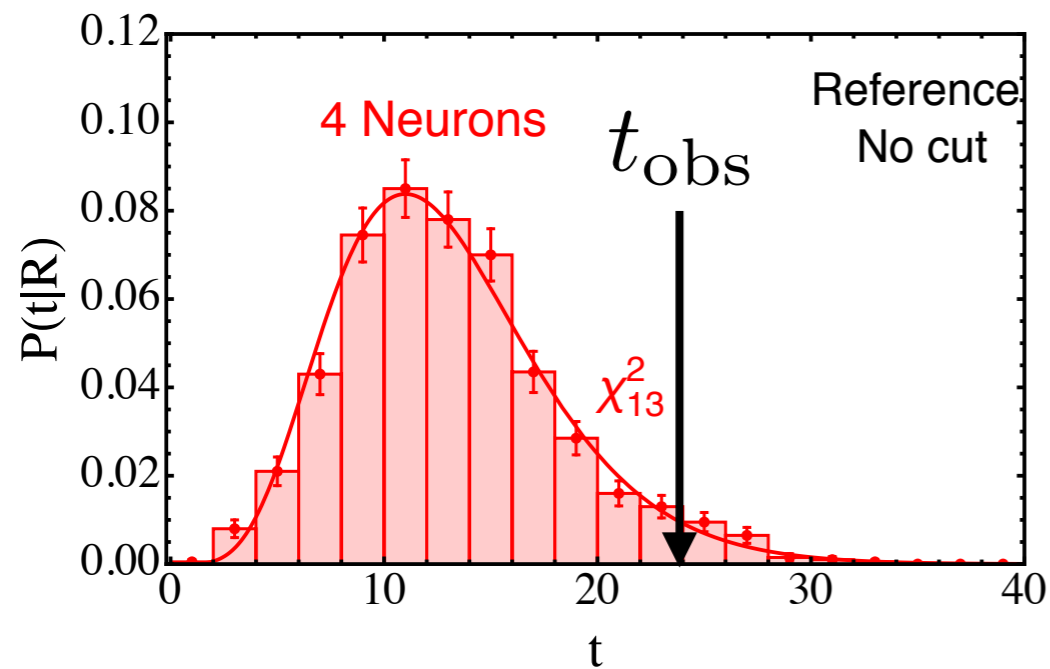
- **INPUT:** ONE DATA SAMPLE AND ONE REFERENCE SAMPLE
- **OUTPUT:** TEST STATISTIC ON THE DATA SAMPLE AND DISTRIBUTION LOG-RATIO

## 2. GENERATE TOY DATA SAMPLES THAT FOLLOW THE REFERENCE DISTRIBUTION AND TRAIN THE NETWORK AGAIN USING THEM AS DATA

- **INPUT:** TOY DATA AND SAME REFERENCE SAMPLE AS ABOVE
- **OUTPUT:** DISTRIBUTION OF THE TEST STATISTIC IN THE REFERENCE HYPOTHESIS

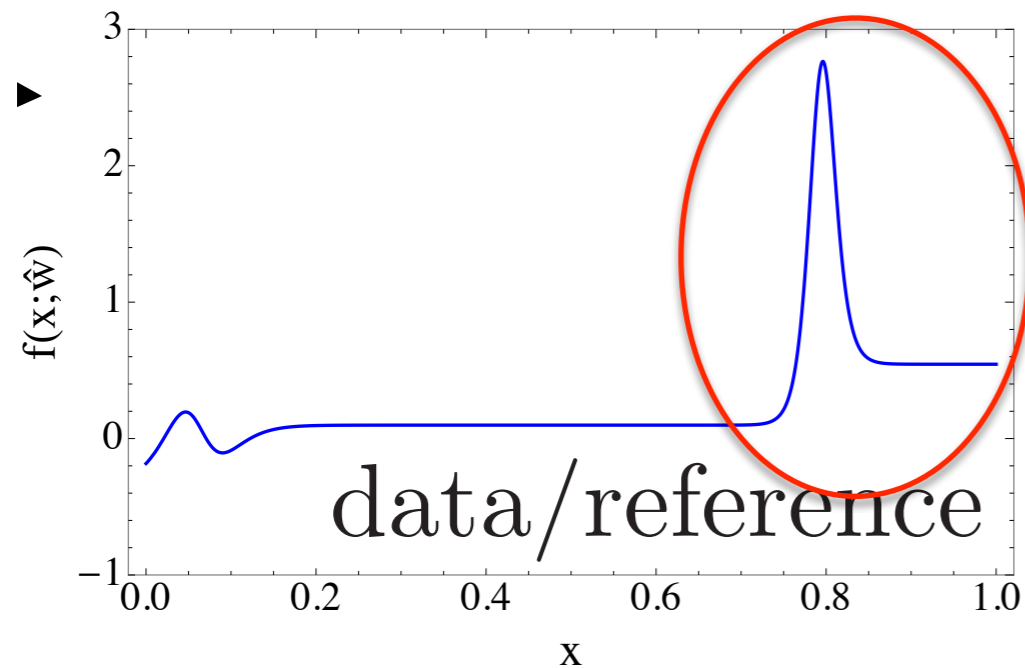
# SUMMARY

3.



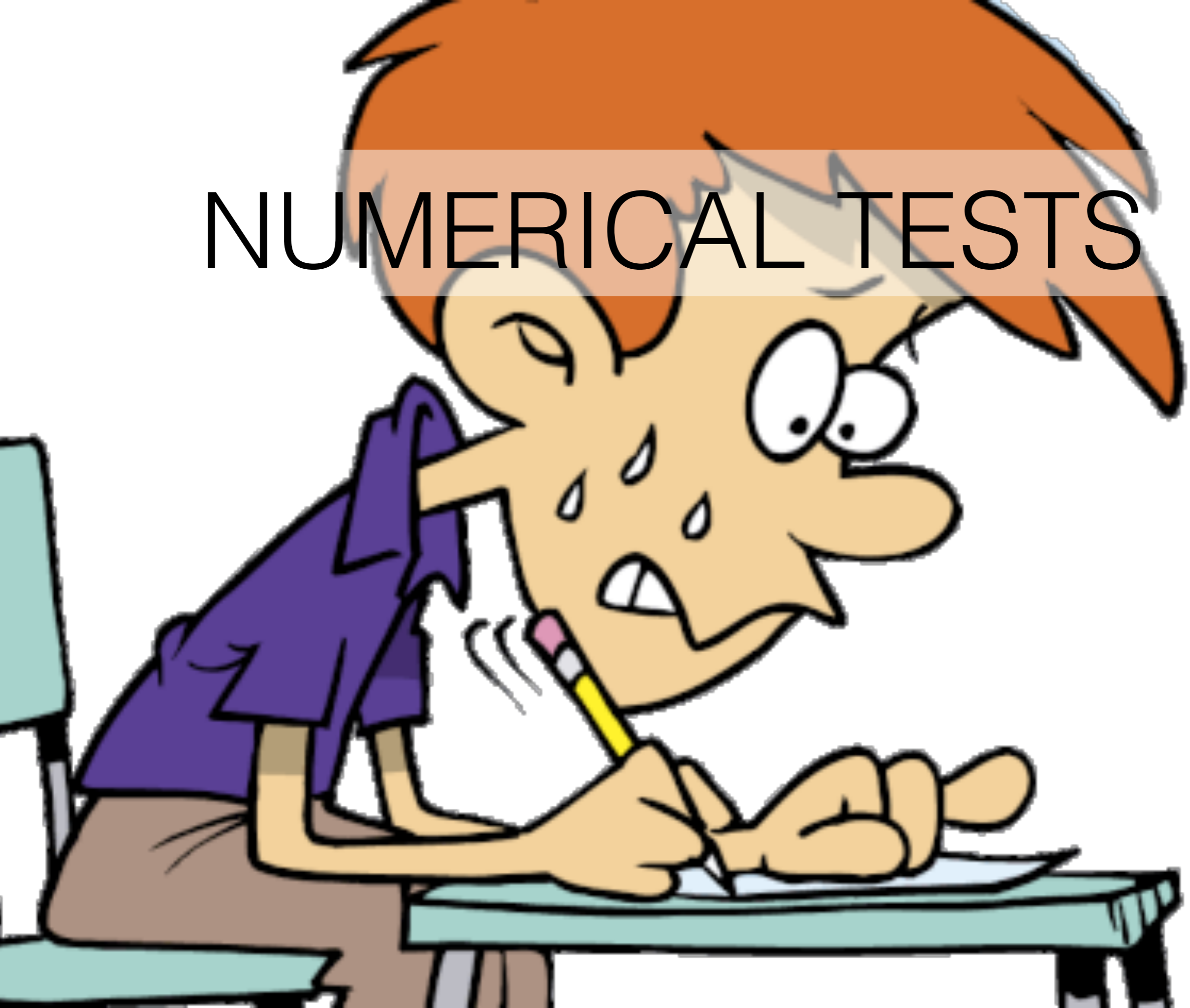
$$p_{\text{obs}} = \int_{t_{\text{obs}}}^{\infty} dt P(t|R)$$

4.

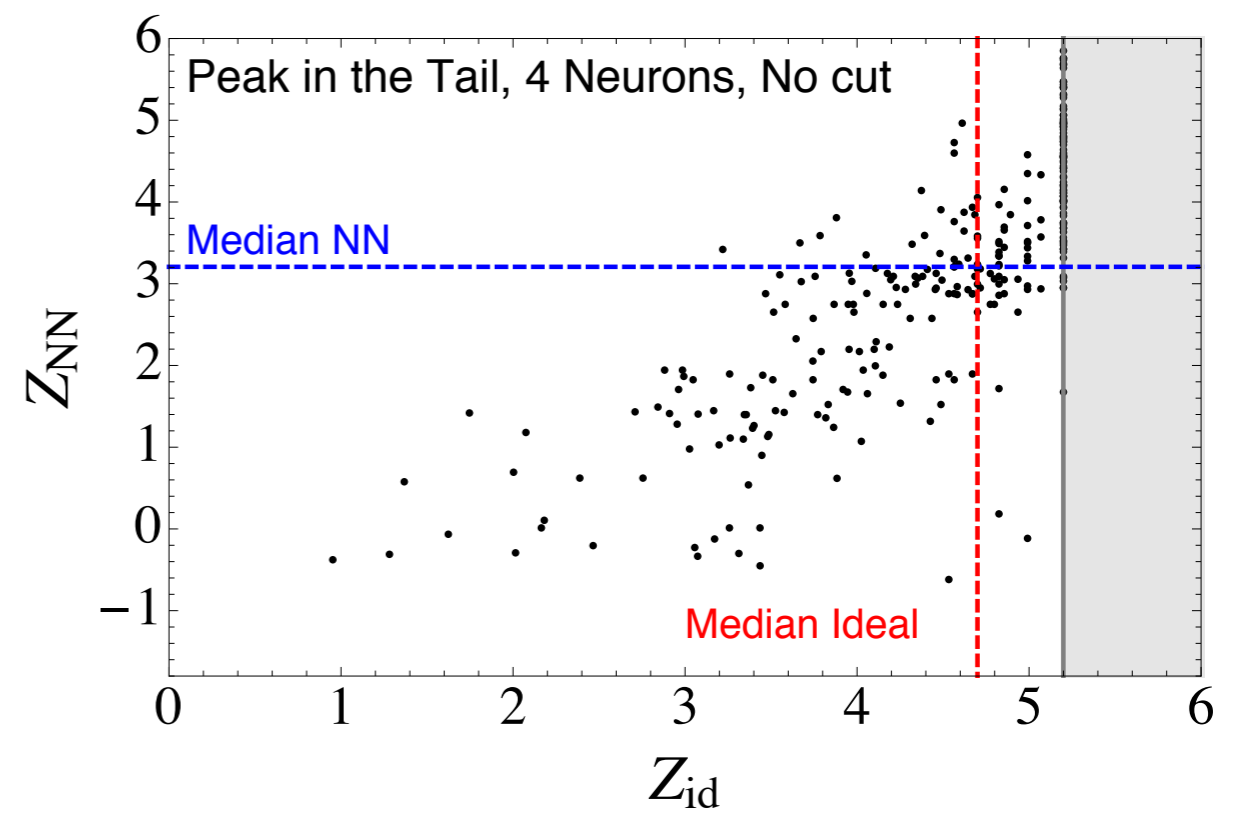
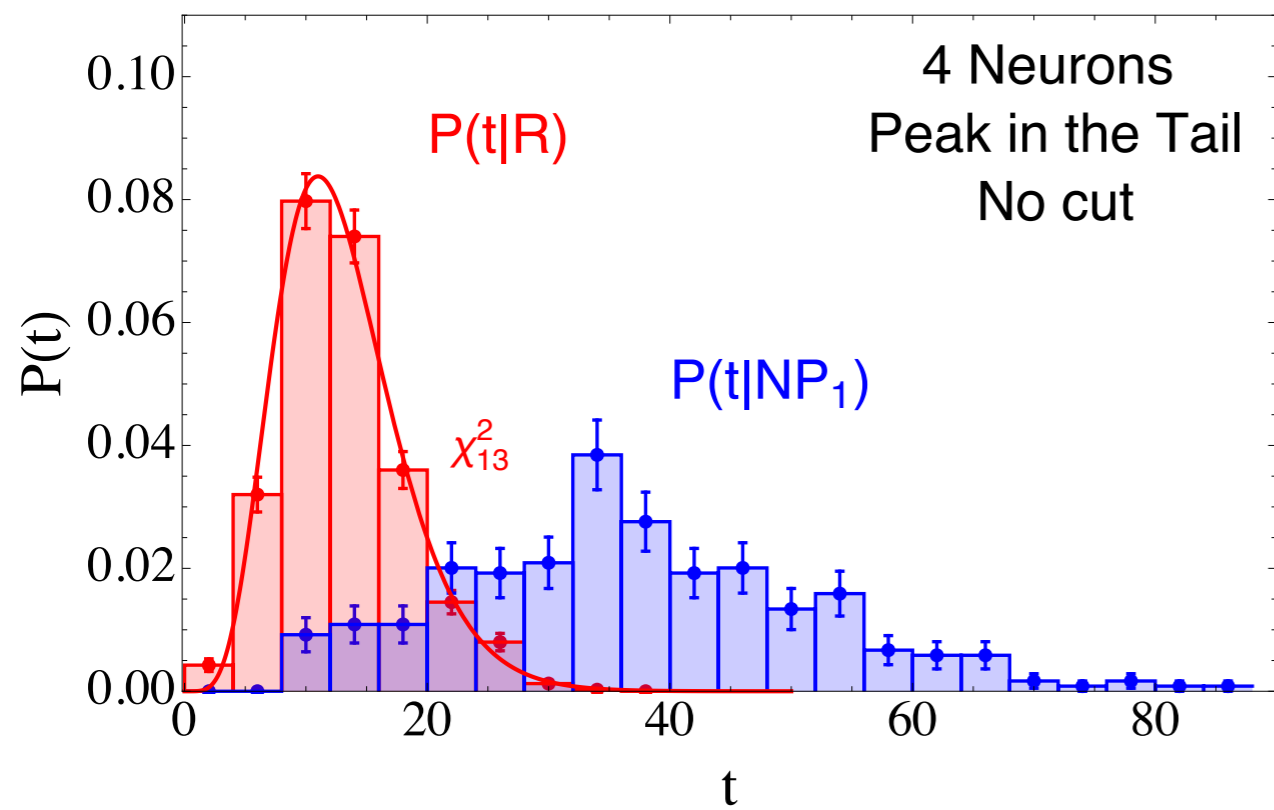


IDENTIFY AND CHARACTERIZE  
NEW PHYSICS

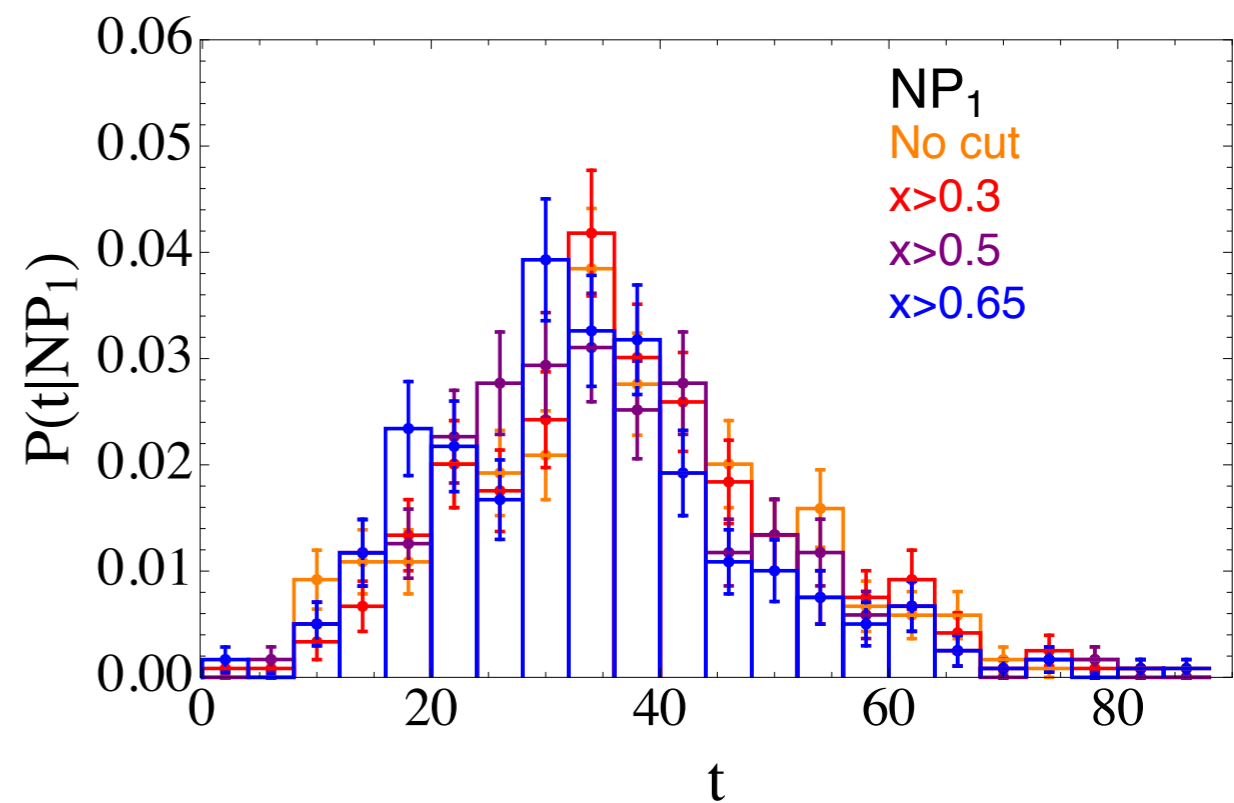
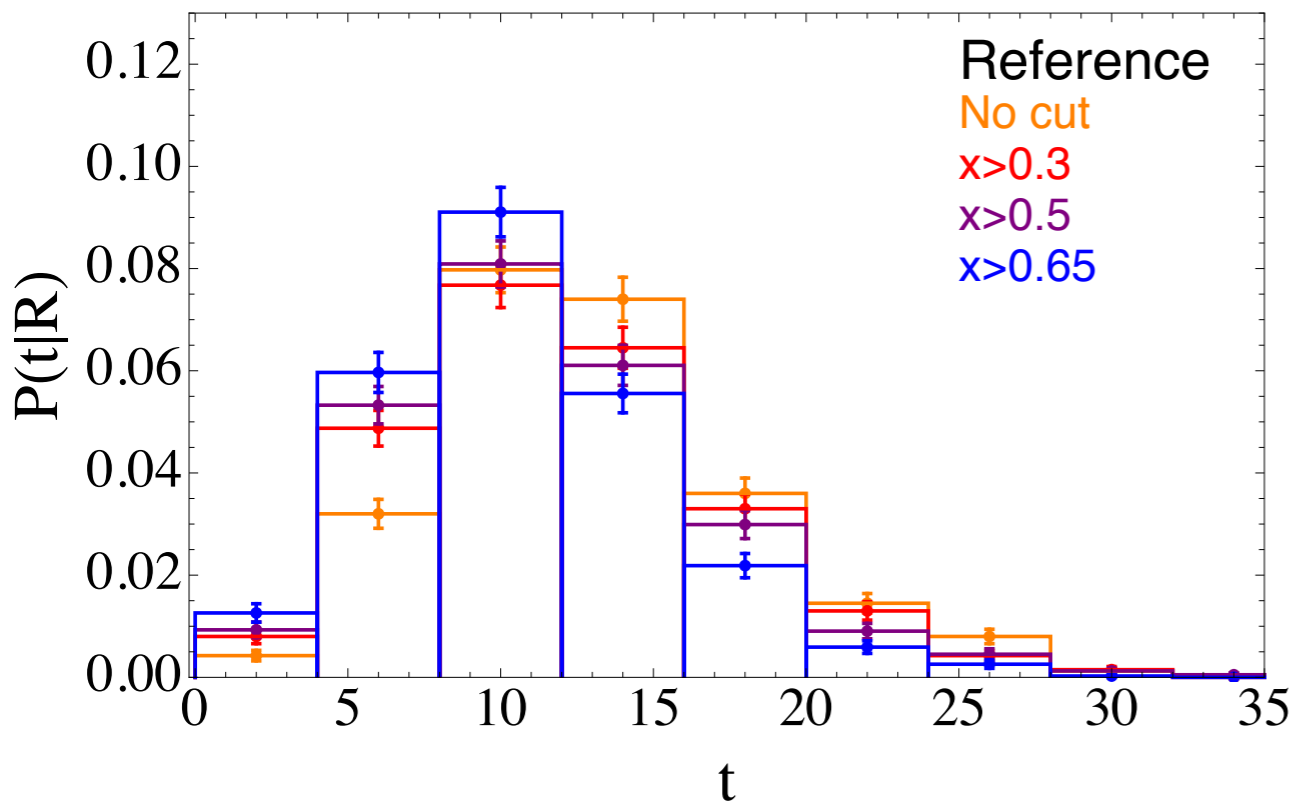
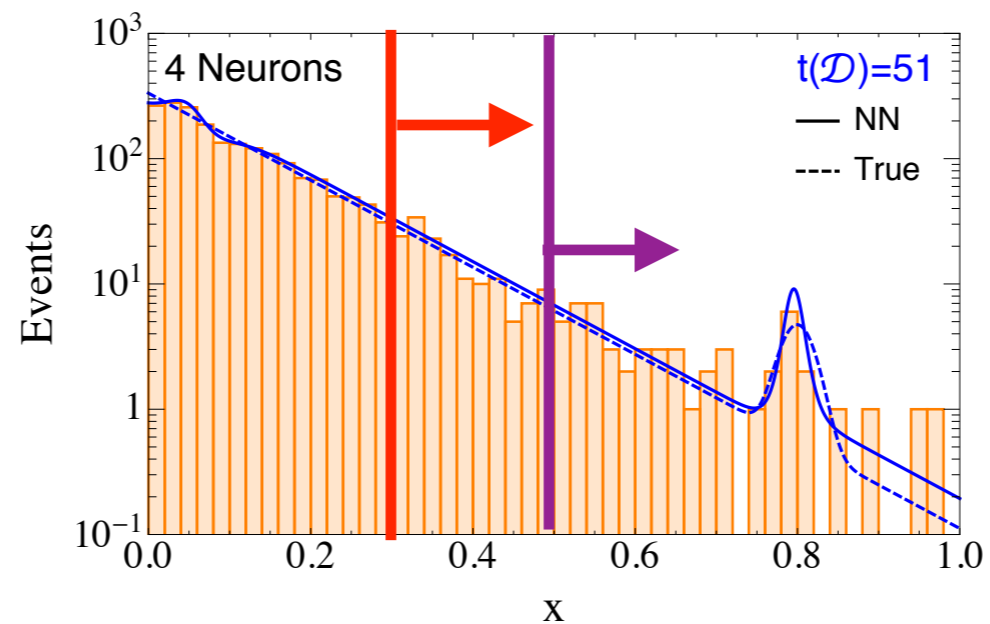
# NUMERICAL TESTS



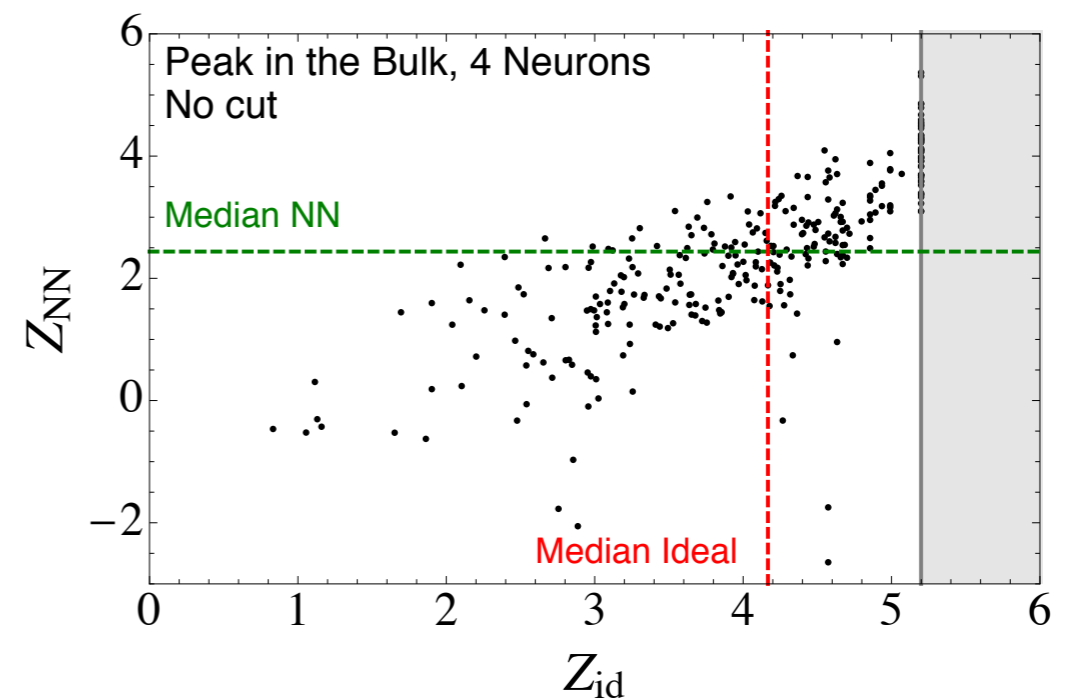
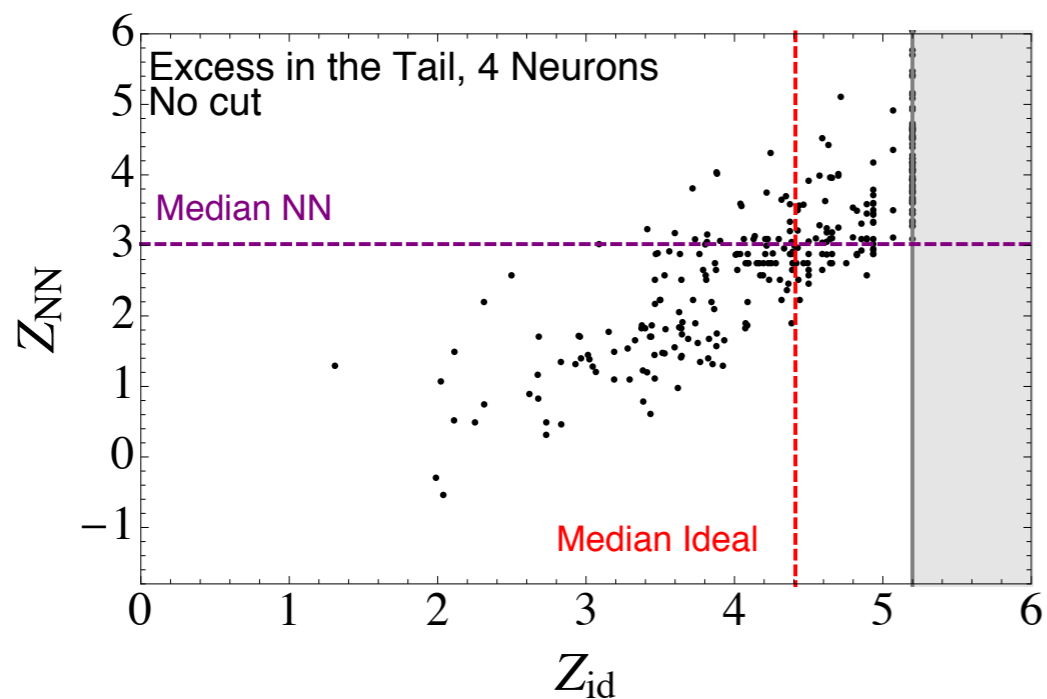
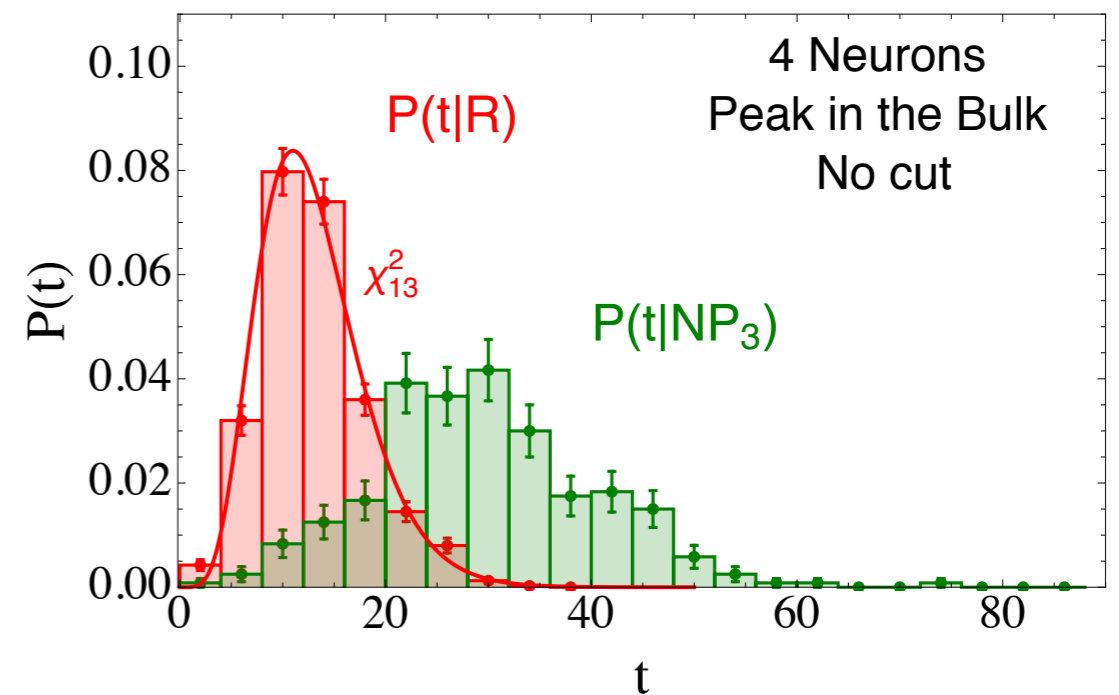
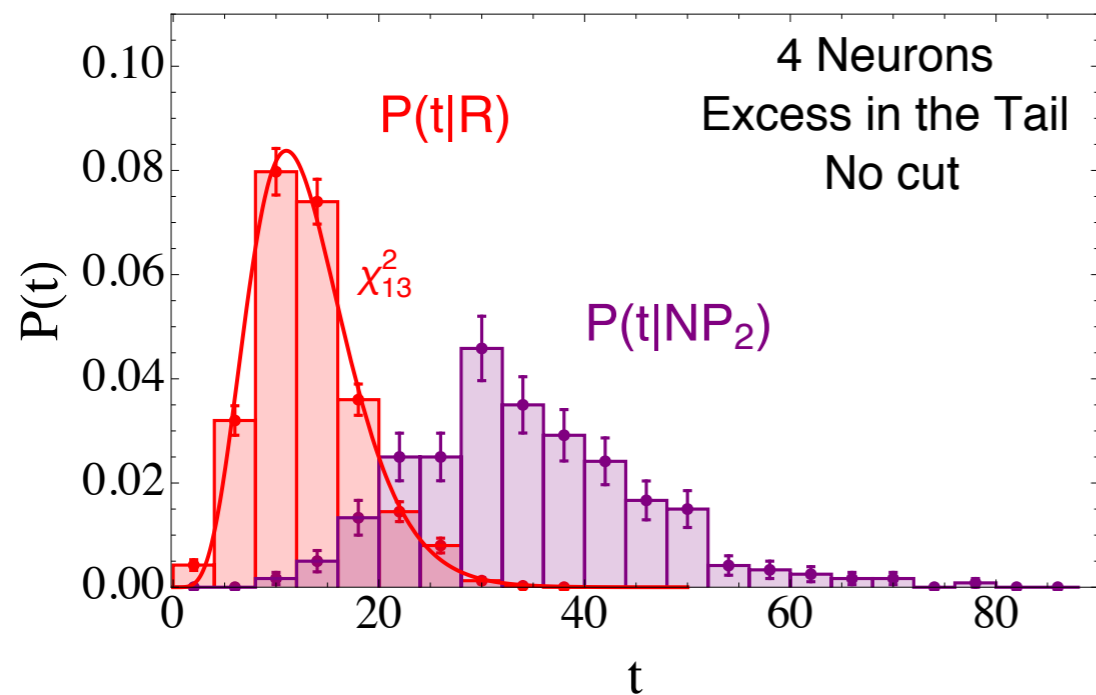
# SENSITIVE TO NEW PHYSICS



# INSENSITIVE TO CUTS



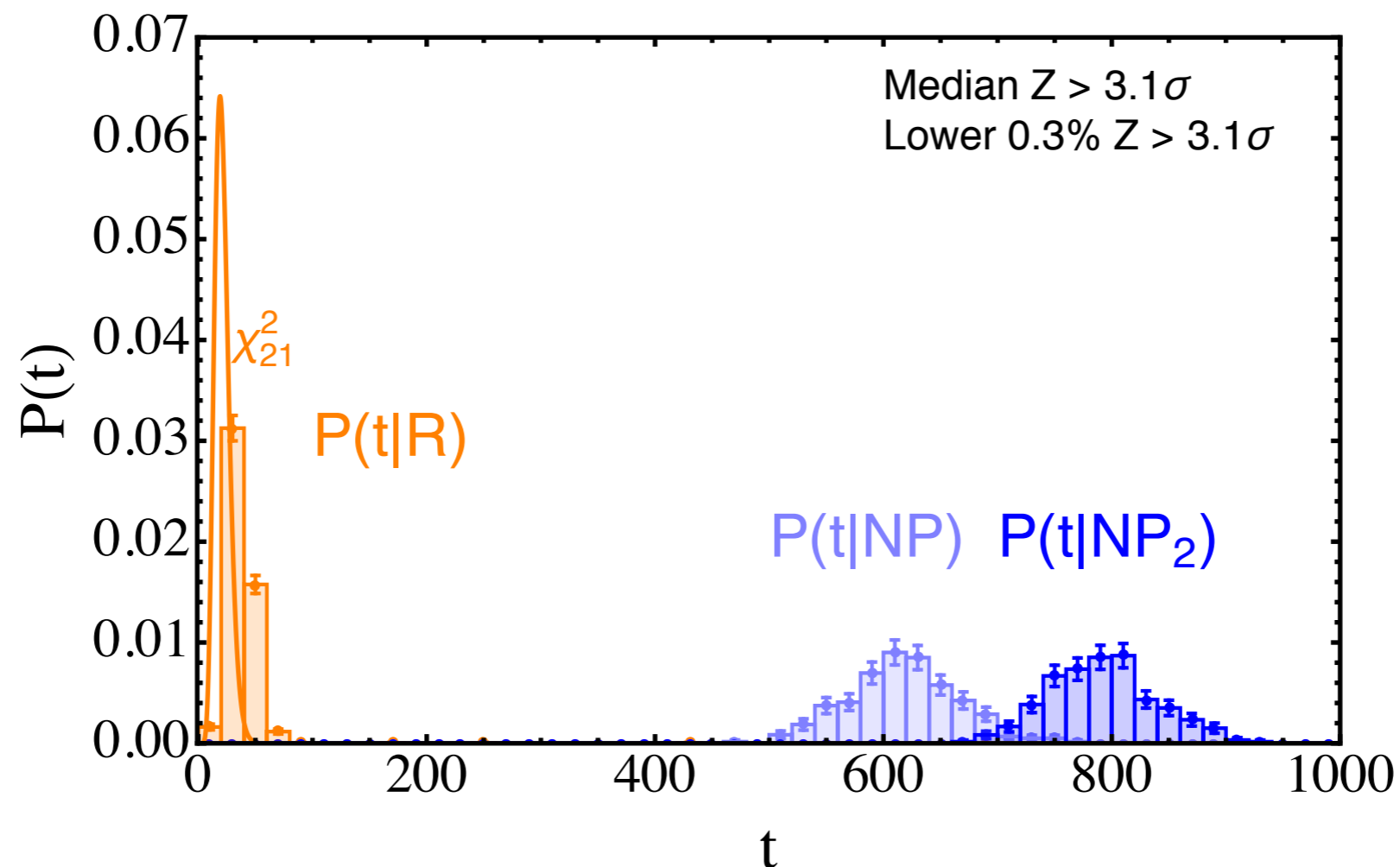
# MODEL-INDEPENDENT



# COMPARISONS

[arXiv:1807.06038](https://arxiv.org/abs/1807.06038)

Trial Dataset	$\mu_T$	$\Sigma_T$	$p$ -value	$Z$
$\mathcal{T}_{G0}$	$(1.0, 1.0)^T$	$((1.0, 0.0), (0.0, 1.0))$	$8.2 \times 10^{-1}$	$0.2 \sigma$
$\mathcal{T}_{G1}$	$(1.12, 1.12)^T$	$((1.0, 0.0), (0.0, 1.0))$	$2.8 \times 10^{-2}$	$2.2 \sigma$
$\mathcal{T}_{G2}$	$(1.0, 1.0)^T$	$((0.95, 0.1), (0.1, 0.8))$	$4.0 \times 10^{-4}$	$3.5 \sigma$
$\mathcal{T}_{G3}$	$(1.15, 1.15)^T$	$((1.0, 0.0), (0.0, 1.0))$	$1.2 \times 10^{-6}$	$4.9 \sigma$

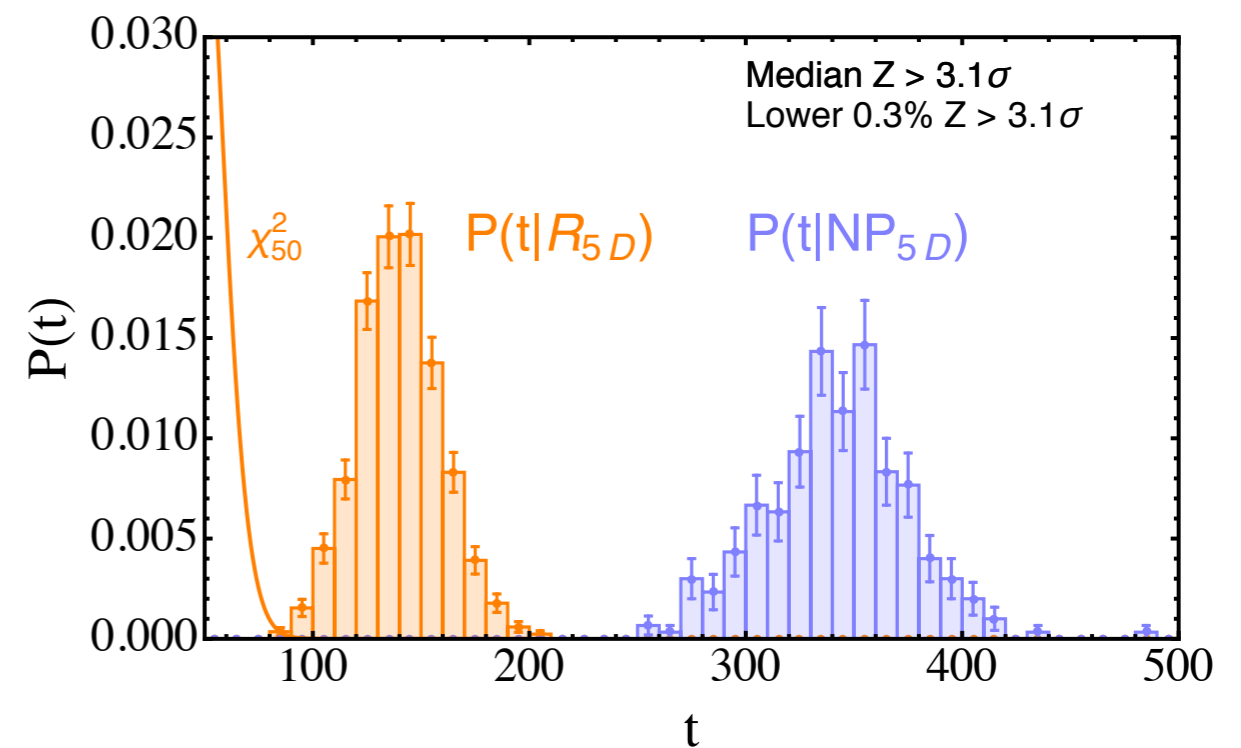
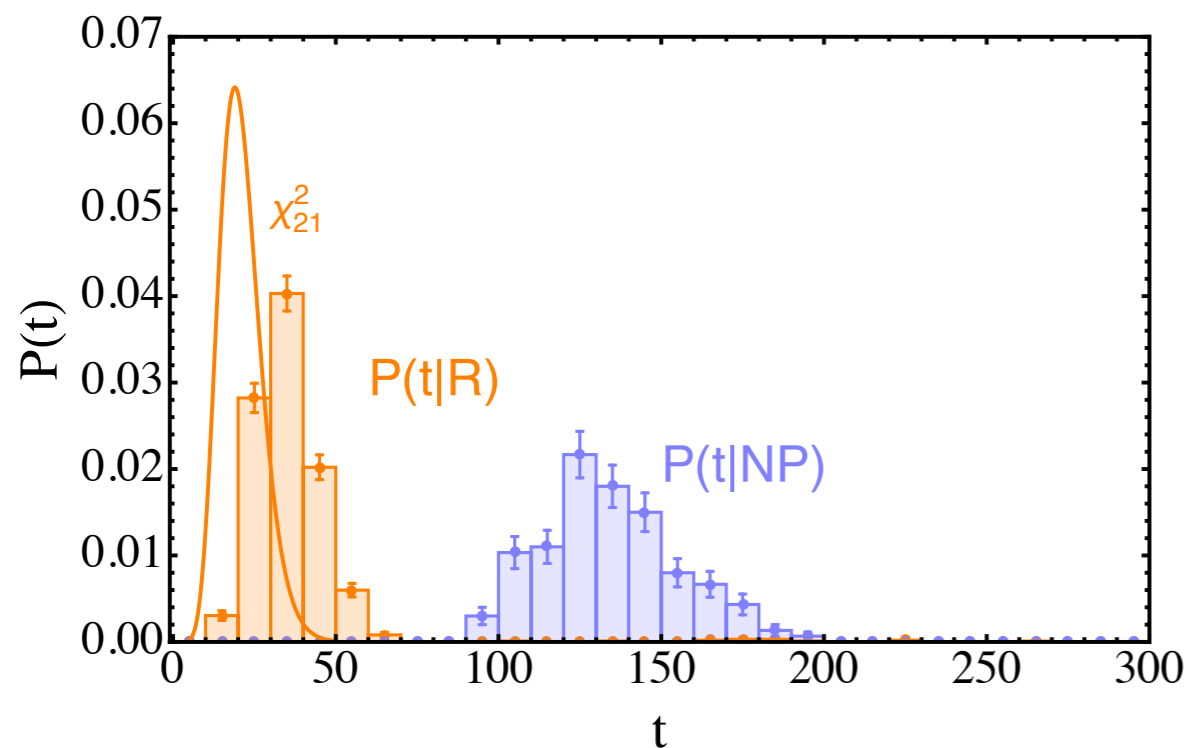
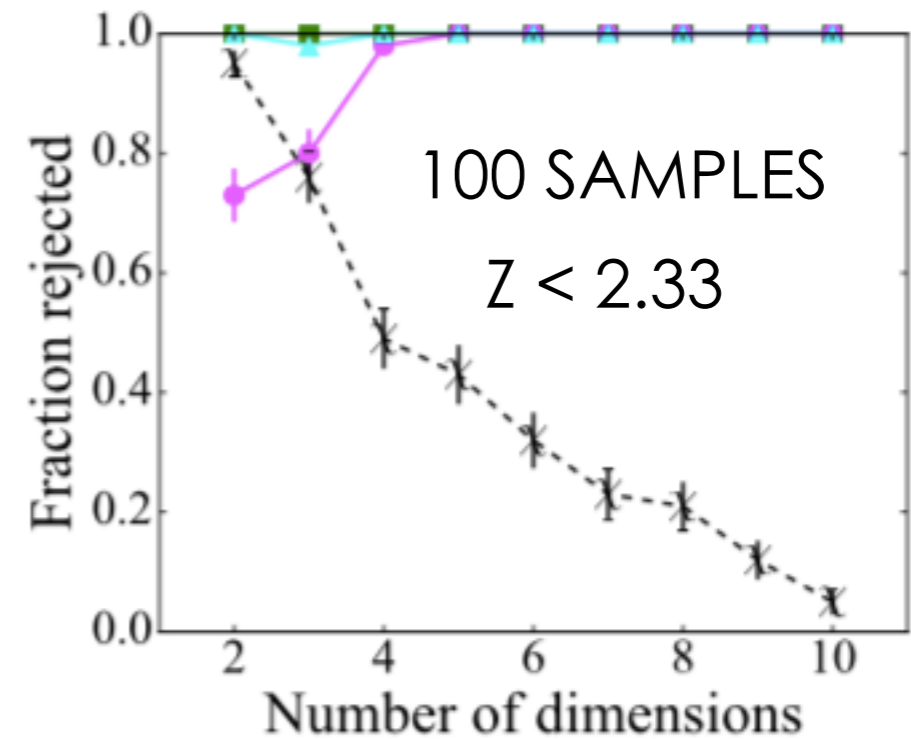


# COMPARISONS

[arXiv:1612.07186](https://arxiv.org/abs/1612.07186)

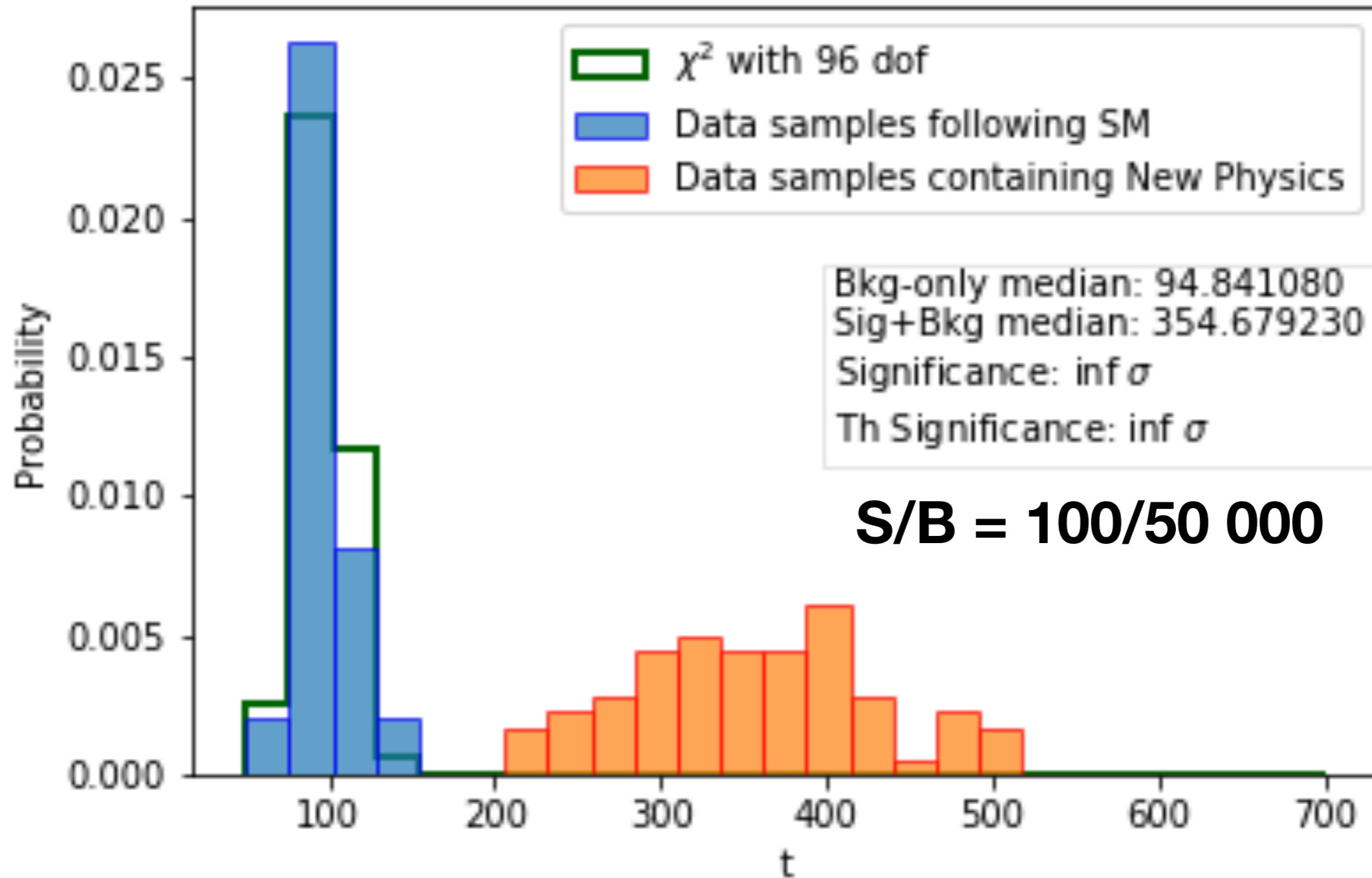
$$n(x|R) = \prod_{k=1}^D \mathcal{N}(0, 1)$$

$$n(x|NP) = \prod_{k=1}^D \mathcal{N}(0, 0.95)$$





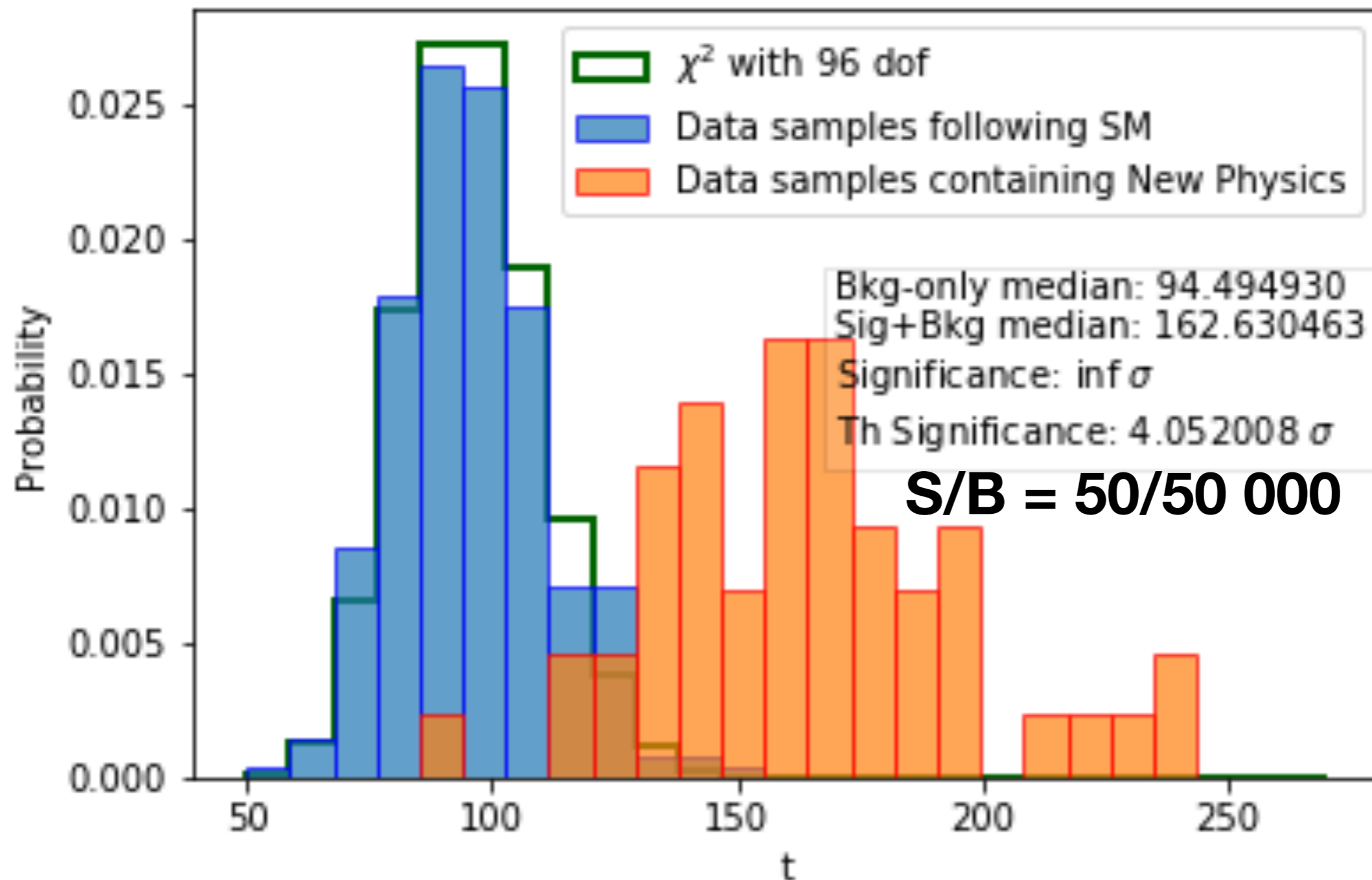
# Z' TO DILEPTONS (5D)



**S/B = 100/50 000**

**S/ $\sqrt{B}$   $\approx$  26.0  $\pm$  0.6**

# Z' TO DILEPTONS (5D)



$$S/\sqrt{B} \approx 13 \pm 0.3$$

THAT WAS SURPRISINGLY EASY. HOW COME THE ROBOTIC UPRISING USED SPEARS AND ROCKS INSTEAD OF MISSILES AND LASERS.?

IF YOU LOOK TO HISTORICAL DATA, THE VAST MAJORITY OF BATTLE-WINNERS USED PRE-MODERN WEAPONRY.

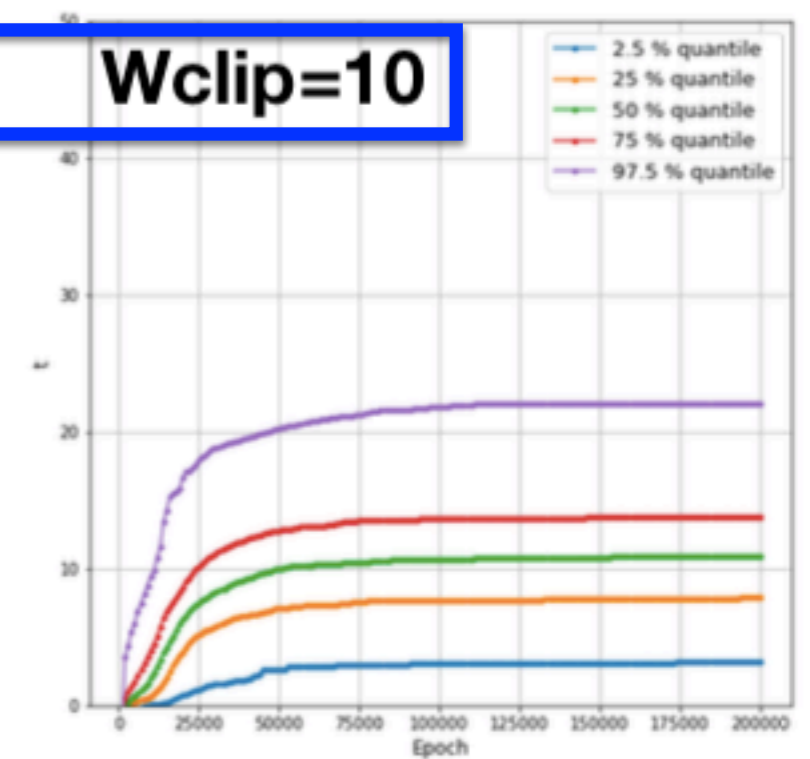
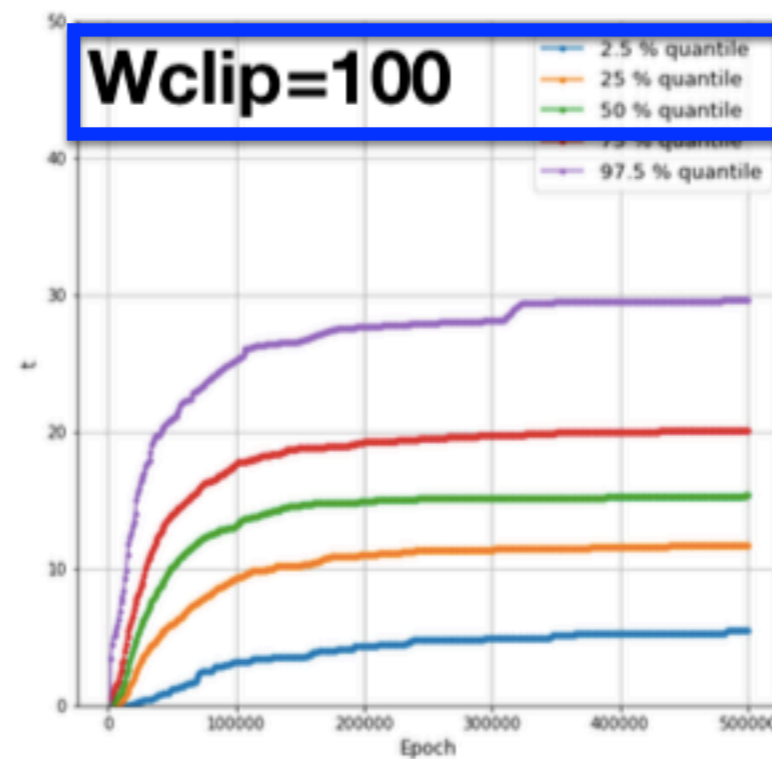
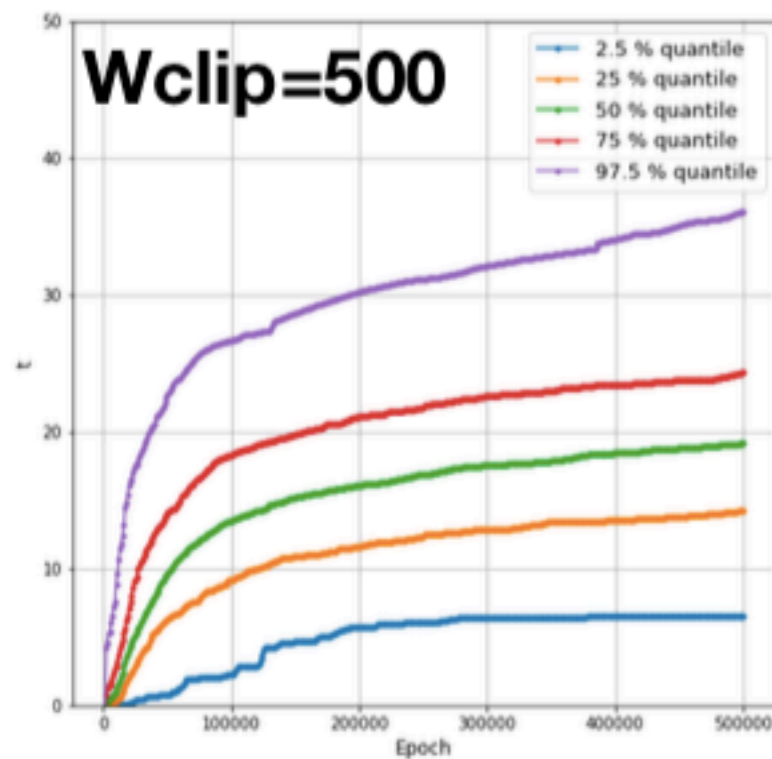
# NETWORK ARCHITECTURE

Thanks to machine-learning algorithms, the robot apocalypse was short-lived.

# NETWORK ARCHITECTURE

O. Cerri, **Gaia Grosso**, RTD, M. Pierini, A. Wulzer, M. Zanetti in progress

1. GIVEN A NETWORK ARCHITECTURE FIND A RANGE OF THE WEIGHT CLIPPING THAT DOES NOT GENERATE OUTLIERS IN THE REFERENCE MODEL (=NO OVERFITTING)



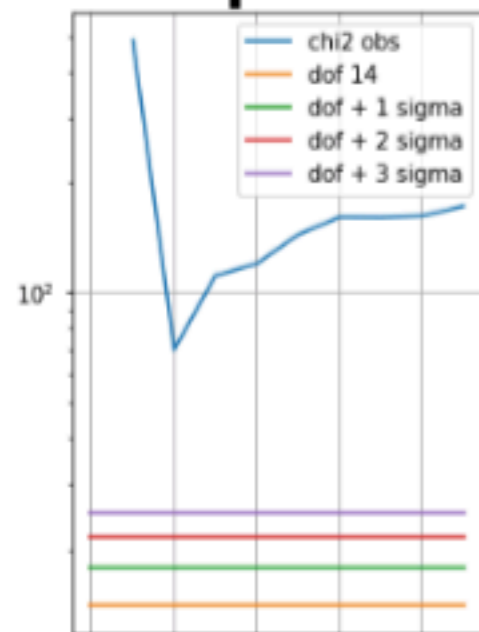
# NETWORK ARCHITECTURE

O. Cerri, **Gaia Grosso**, RTD, M. Pierini, A. Wulzer, M. Zanetti in progress

2. WITHIN THE RANGE CHOOSE THE WEIGHT CLIPPING THAT MAXIMIZES THE COMPATIBILITY WITH THE CHI2

3. PICK THE MINIMUM VALUE OF TRAINING ROUNDS THAT DOES NOT SPOIL 1. AND 2.

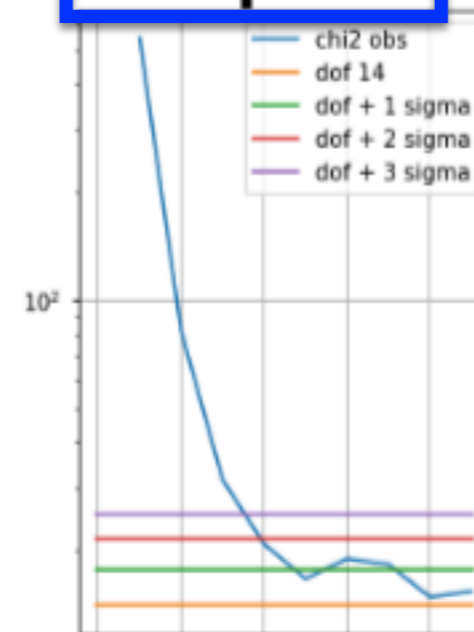
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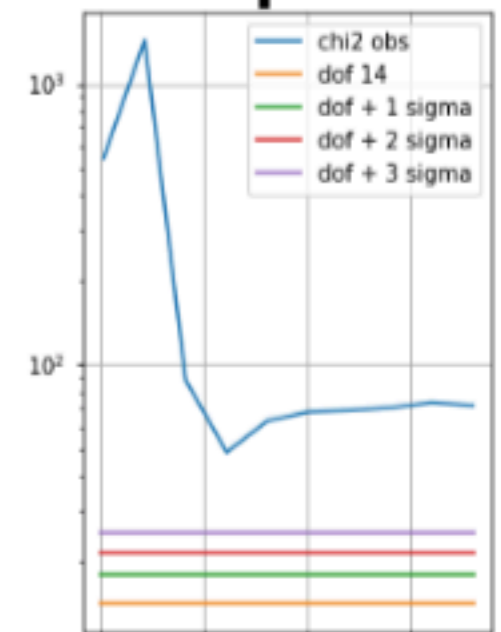
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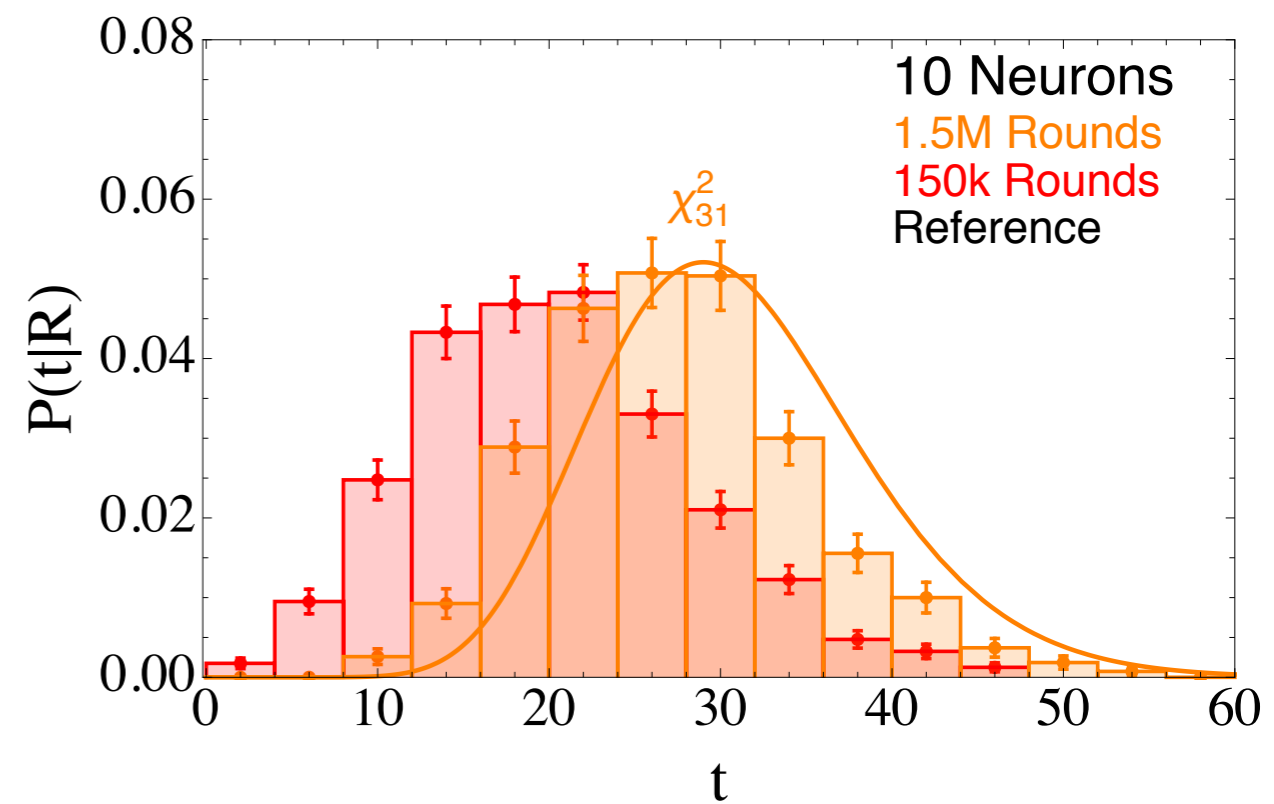
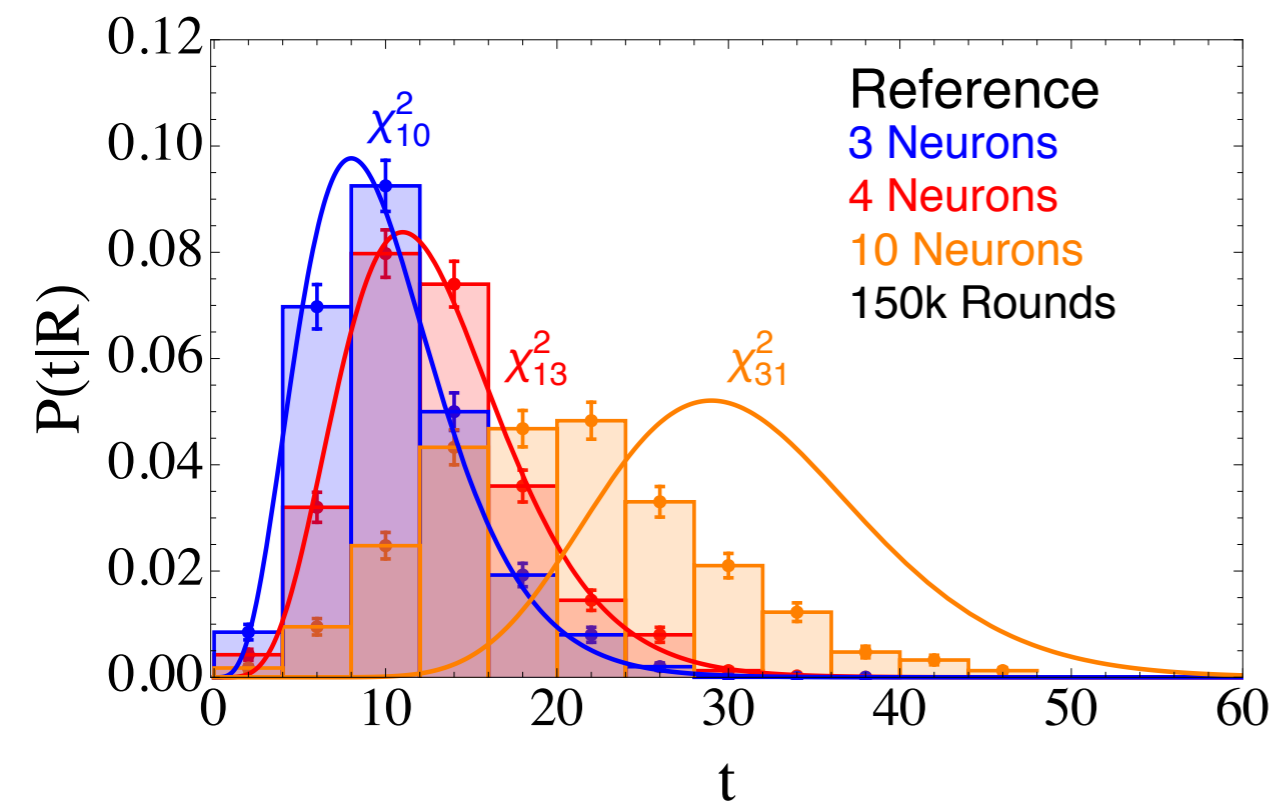
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**Wclip=10**



# NETWORK ARCHITECTURE



# CONCLUSION AND OUTLOOK

- TODAY IN FUNDAMENTAL PHYSICS WE HAVE LARGE, MULTIVARIATE, SM-LIKE DATASETS AND STRONG REASONS TO BELIEVE THAT THEY SHOULD NOT BE SM-LIKE
- OUR BEST GUESSES FOR NEW PHYSICS ARE NOT BEING DETECTED AND ANYTHING THAT HELPS US TO SEARCH WITHOUT ANY BIAS CAN BE USEFUL
- NEURAL NETWORKS ARE WIDELY USED TO APPROXIMATE PROBABILITY DISTRIBUTIONS AND ARE IDEAL CANDIDATES FOR THIS TYPE OF PROBLEM
- TODAY I HAVE DESCRIBED AN APPLICATION OF NEURAL NETWORKS, FOUNDED ON SOLID STATISTICAL PRINCIPLES, WHICH GOES IN THIS DIRECTION
  - ITS VIRTUES (SENSITIVITY TO NP, MODEL-INDEPENDENCE, INSENSITIVITY TO CUTS) HAVE BEEN TESTED ON SIMPLE 1D AND 2D EXAMPLES
  - MORE WORK IS NEEDED IN THE 2D AND HIGHER-DIMENSIONAL CASE

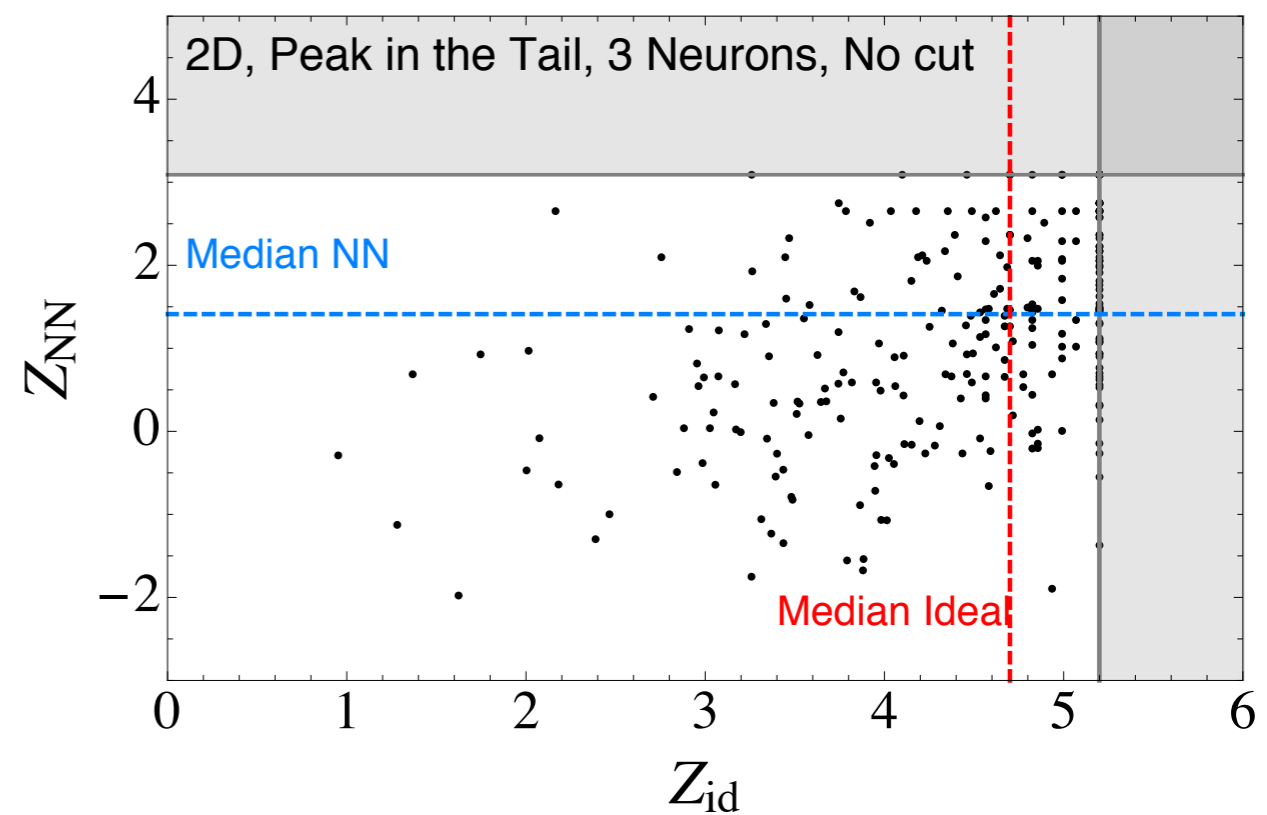
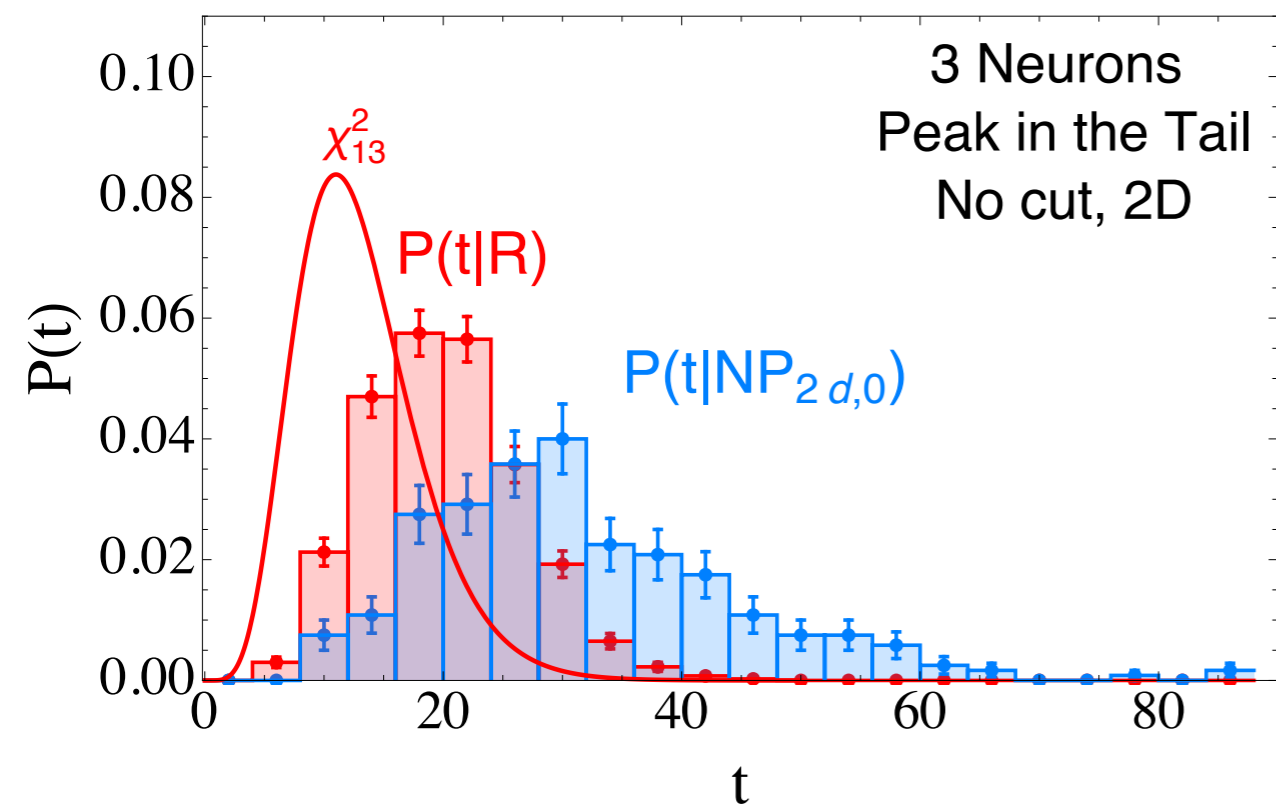
BACKUP



# TWO DIMENSIONS

NP:  $x \sim \text{EXPONENTIAL} + \text{PEAK}$   
R:  $x \sim \text{EXPONENTIAL}$

$y \sim \text{UNIFORM}$   
 $y \sim \text{UNIFORM}$



RECOVERS COMPARABLE SENSITIVITY TO 1D FOR  $x > 0.3$  OR  
DOUBLING THE EVENTS