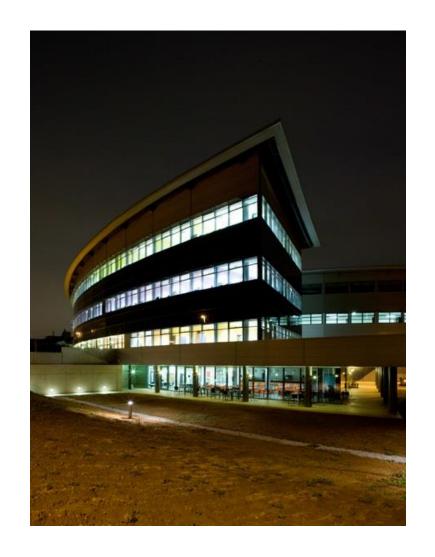


The Use of PANIC Alarm System at ALBA

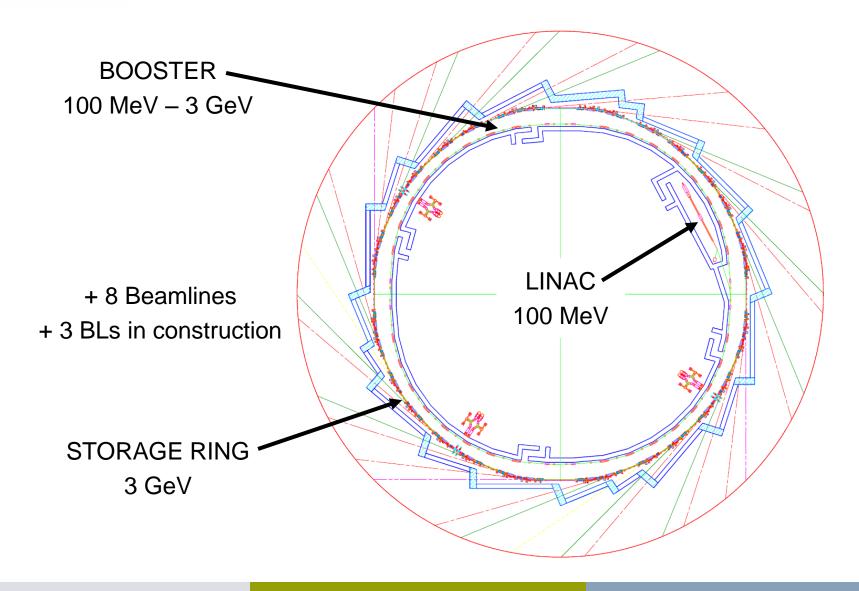
Ferran Fernandez
ARW2017



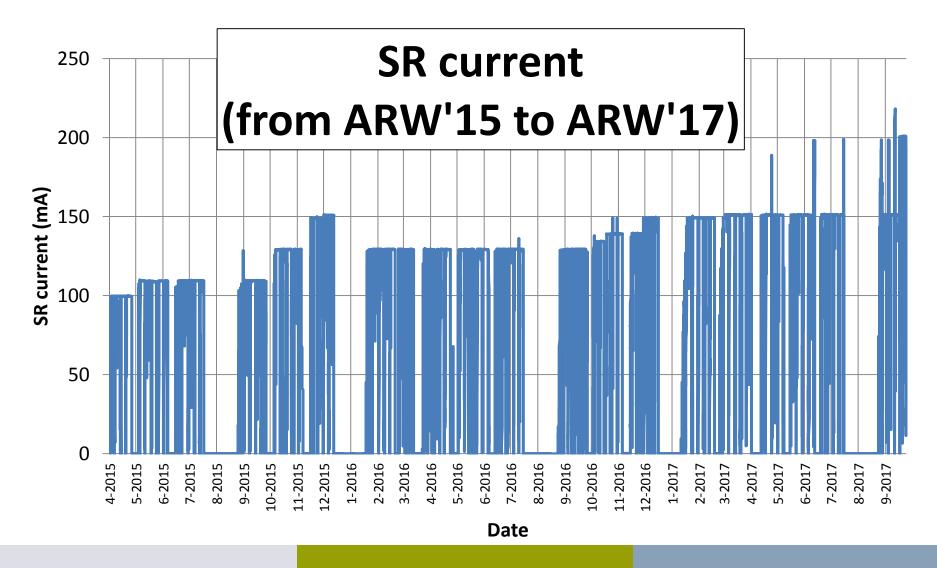


- Introduction to the ALBA synchrotron light source
- The PANIC alarm system
- The use of PANIC at ALBA



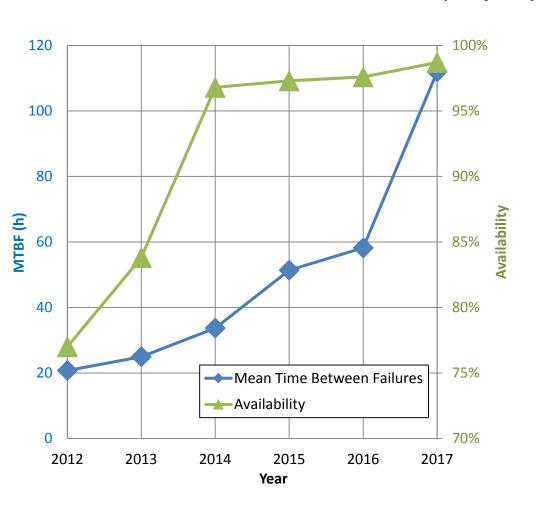


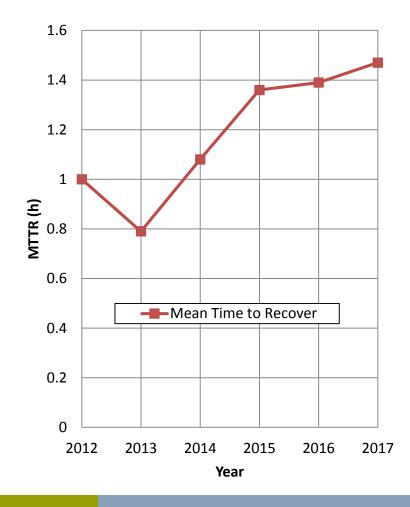






Started with users 2012 (Top-up summer 2014)







- The ALBA Accelerator Operators
 - 7 operators
 - 50% On Shift // 50% "office"
 - 20% Machine days // 80% Beamlines days
 - Operation tasks: eLog, new procedures development, programming new GUIs and scripts,...

Check O.Serres poster --> 31. Operation Scripts

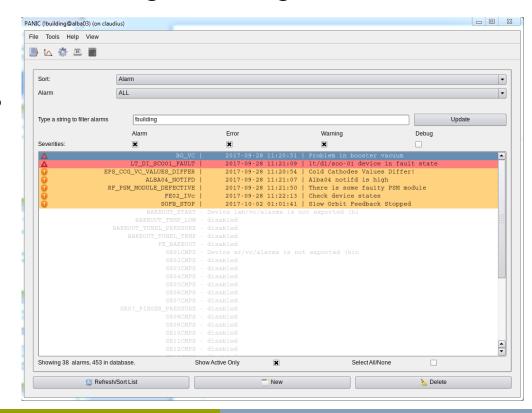
 Each operator is also assigned to a subsystem to provide support and to obtain a higher degree of specialization from which the operation also benefits



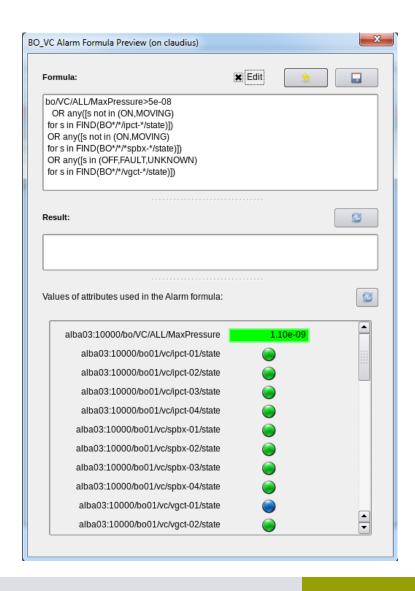
- Programable Alarms and Notifications InCidences
- PANIC is an alarm handler developed at ALBA under the Tango Control System framework based on the PyAlarm engine
- It was developed during the construction and installation phase (2007-2010) to provide remote control of the equipments on site; mainly Vacuum and Linac
- It is being adopted by other members of the Tango collaboration like MaxLab, Solaris or SKA



- PANIC notifies of abnormal process conditions or equipment malfunction
- Each alarm evaluates a formula using the Tango Database
- Once the alarm is activated, PANIC performs the programmed action
- The management of all the alarms is centralized with PANIC, but alarms run in the different device servers



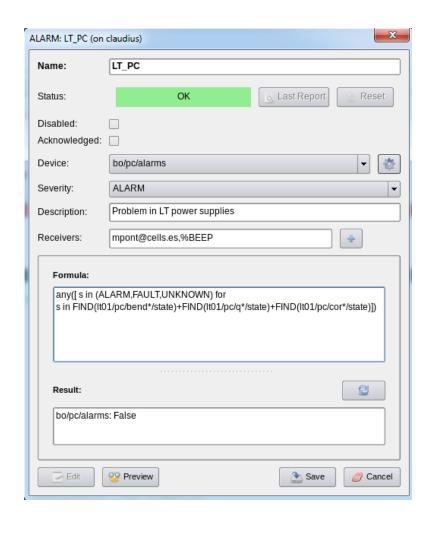




Easily configurable by users

- Flexible Formulas syntax:
 - Strings (States), Booleans, float (analogs)
 - Can combine them
 - Can use "FIND" within all the Tango Database attributes
- "Preview" functionality:
 - Formulas can be quickly evaluated
 - Involved devices can be checked





- Different actions can be defined:
 - Notification: email, SMS or Telegram
 - Control Room loudspeaker (VERY USEFUL!!!)
 - Database insertions
 - Tango commands
 - Run python scripts
- "Password required" can be set to create/edit/delete alarms



- Parameters of the alarm can be configured:
 - Pooling period
 - Alarm threshold
 - Autoreset
 - Eval Timeout
 - Reminder
- Import/Export alarms





SPOILER ALERT: CONCLUSION

- A good alarm system is <u>very useful</u>...
 - Loudspeaker in the Control Room
 - OnCall alarms for subsystem responsible
 - Automatic actions on the machine

...if the final **user can easily edit** the alarms



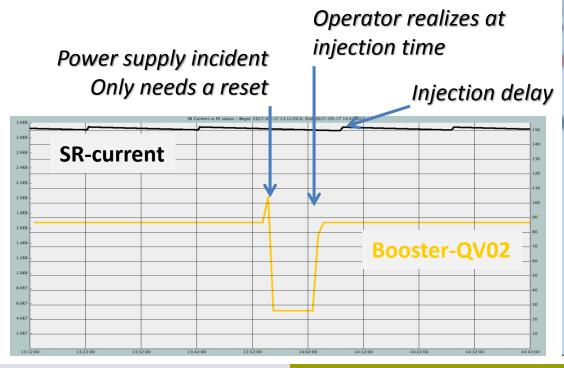
- As said, the PANIC project was initiated during the construction/installation phase to provide remote control of the installed equipment on site; mainly Vacuum and Linac
- During commissioning not much used by Accelerators because "many eyes were on the screens"
- From 2012 (start with users) and mainly from 2014 (start top-up) the use of PANIC has grown a lot in the Control Room

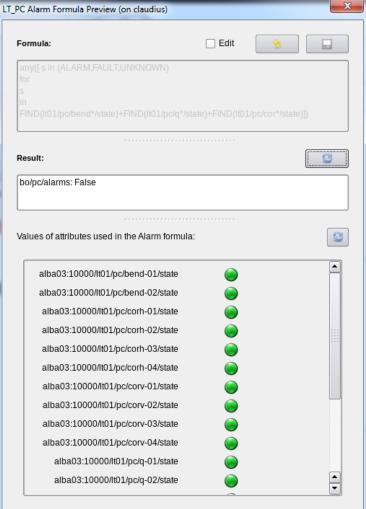


- Four types of alarms (from the user's point of view)
 - 1. Problem in the Injector
 - 2. Abnormal condition in the Storage Ring
 - 3. Subsystem notification to experts
 - 4. Bonus track: automatic actions



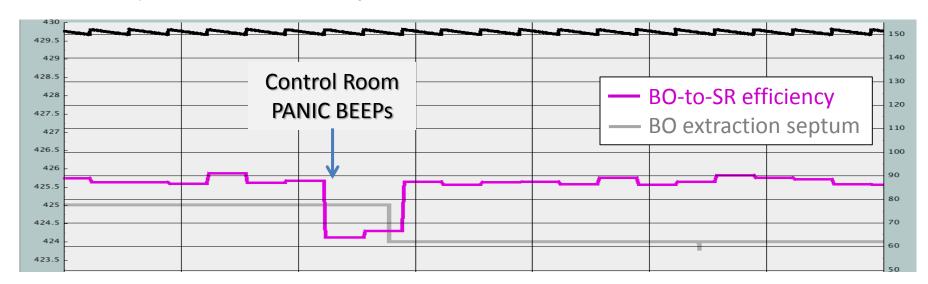
- Injector problem
 - LTB, Booster, BT power supplies
 - Pulsed magnets



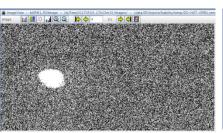




- Abnormal condition in the Storage Ring
 - Injection efficiency







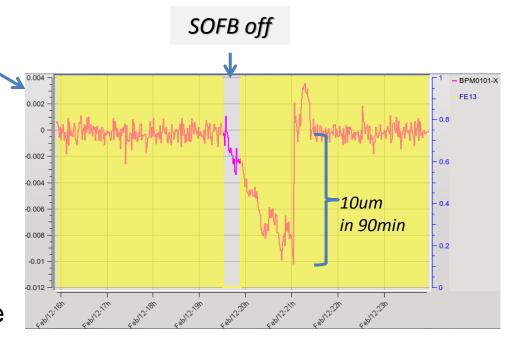


BO-to-SR synchrotron radiation monitor



- Abnormal conditions in the Storage Ring
 - Orbit distortion
 - Low/high lifetime
 - Beam size
 - Radiation monitors
 - SR temperatures
 - Cooling water flow,
 pressure and temperature
 - SCW quench







- Subsystem notifications to experts
 - Linac
 - Radiofrequency

From Accelerators

Timing

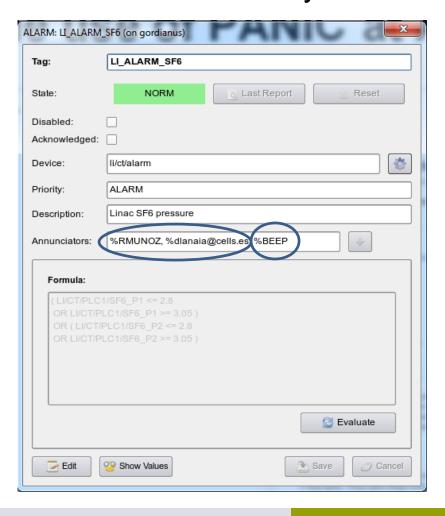
From other Divisions

- Controls servers
- Vacuum lab. Bakeouts
- Civil engineering
 - Cooling water
 - Electrical supply



Accelerator subsystem --> Linac

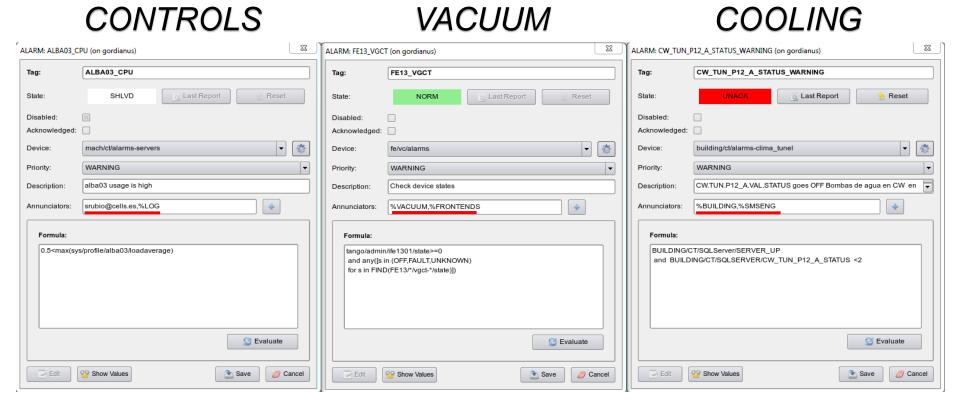




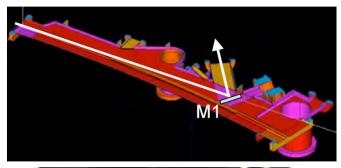
The aim of this procedure is to give a very brief explanation of why one linac alarm beeps and how to solve it	
SF6 Alarm	
_	ops Power Drive
Cooling Lo Vacuum	ops Heater Resistor Temperature
Bunker ter	nperature
	tron for KA1 and KA2
Linac KlysLinac Mag	
Linac Mag Linac Elec	
Klystron U	V Fire Detector
F6 Alarm	
Procedure:	check: IVct/pic2/SF6_pressure s: SF6 refill procedure and Empty the SF6 gas (for EXPERTS)
cooling Loop	s Power Drive
	IS POWER DRIVE IN: LI_COOLING and LI_COOLING_PWR
Panic Alarn Description:	n: LI_COOLING and LI_COOLING_PWR These alarm beeps when one of the 3 cooling loops power drive is out of range and when the cooling loop
Panic Alarn Description: stops for sore	n: LI_COOLING and LI_COOLING_PWR These alarm beeps when one of the 3 cooling loops power drive is out of range and when the cooling loop ne reason.
Panic Alarn Description: stops for sore	n: LI_COOLING and LI_COOLING_PWR These alarm beeps when one of the 3 cooling loops power drive is out of range and when the cooling loop me reason. ck on taurustrend the cooling loop behaviour. Look for pressure and temperature variation. Apply
Panic Alarn Description: stops for sor TODO: Che this procedu Attributes to	n: LI_COOLING and LI_COOLING_PWR These alarm beeps when one of the 3 cooling loops power drive is out of range and when the cooling loop me reason. ck on taurustrend the cooling loop behaviour. Look for pressure and temperature variation. Apply re. check: li/ct/pic2/cl_temperature, cl_pwd, cl_pressure
Panic Alarn Description: stops for sor TODO: Che this procedu Attributes to	n: LI_COOLING and LI_COOLING_PWR These alarm beeps when one of the 3 cooling loops power drive is out of range and when the cooling loop me reason. ck on taurustrend the cooling loop behaviour. Look for pressure and temperature variation. Apply re.
Panic Alarm Description: stops for soi TODO: Che this procedu Attributes to Procedure:	n: LI_COOLING and LI_COOLING_PWR These alarm beeps when one of the 3 cooling loops power drive is out of range and when the cooling loop me reason. ck on taurustrend the cooling loop behaviour. Look for pressure and temperature variation. Apply re. check: li/ct/pic2/cl_temperature, cl_pwd, cl_pressure
Panic Alarm Description: stops for soo TODO: Che this procedu Attributes to Procedure: Cooling Loop	n: LI_COOLING and LI_COOLING_PWR These alarm beeps when one of the 3 cooling loops power drive is out of range and when the cooling loop me reason. ck on taurustrend the cooling loop behaviour. Look for pressure and temperature variation. Apply re. check: ii/ct/pic2/ci_temperature, ci_pwd, ci_pressure s: Linac cooling loop trouble shooting
Description: stops for soil TODO: Che this procedure: Attributes to Procedure: Panic Alarn Description:	n: LI_COOLING and LI_COOLING_PWR These alarm beeps when one of the 3 cooling loops power drive is out of range and when the cooling loop ne reason. ck on taurustrend the cooling loop behaviour. Look for pressure and temperature variation. Apply re. check: li/ct/pic2/cl_temperature, cl_pwd, cl_pressure s: Linac cooling loop trouble shooting s Heater Resistor Temperature n: LI_COOLING_RES_TEMP This alarms beeps when one of the 3 cooling loop heater resistor temperature exceeds the 110 degrees.
Panic Alam Description: stops for soi TODO: Che this procedure: Procedure: Cooling Loop Panic Alam Description:	n: LI_COOLING and LI_COOLING_PWR These alarm beeps when one of the 3 cooling loops power drive is out of range and when the cooling loop me reason. ck on taurustrend the cooling loop behaviour. Look for pressure and temperature variation. Apply re. check: li/ct/pic2/cl_temperature, cl_pwd, cl_pressure s: Linac cooling loop trouble shooting s Heater Resistor Temperature
Panic Alam Description: stops for soi TODO: Che this procedu Attributes to Procedure: Cooling Loop Panic Alam Description: Before this a	n: LI_COOLING and LI_COOLING_PWR These alarm beeps when one of the 3 cooling loops power drive is out of range and when the cooling loop ne reason. ck on taurustrend the cooling loop behaviour. Look for pressure and temperature variation. Apply re. check: li/ct/pic2/cl_temperature, cl_pwd, cl_pressure s: Linac cooling loop trouble shooting s Heater Resistor Temperature n: LI_COOLING_RES_TEMP This alarms beeps when one of the 3 cooling loop heater resistor temperature exceeds the 110 degrees.



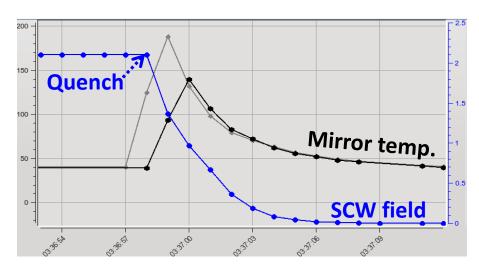
Subsystems from other Divisions







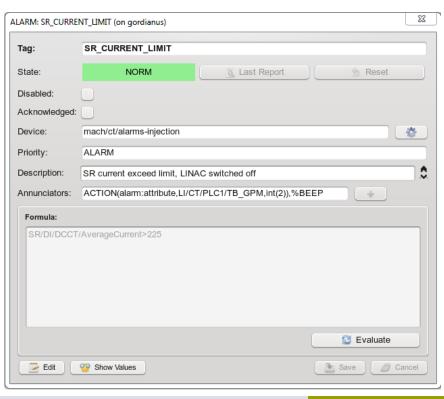
Infrared Beamline mirror

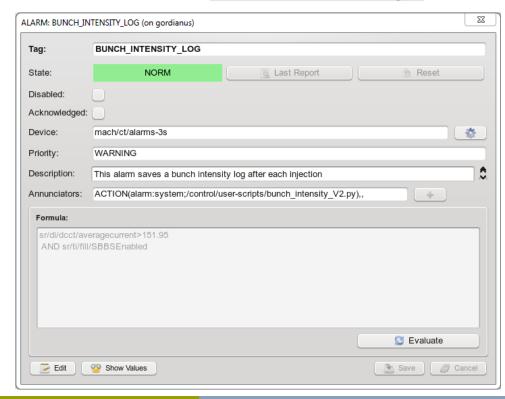


- ✓ Small orbit distortions "hit/heat" the mirror.
- ✓ Insert mirror only if SR<2mA and orbit ok</p>
- Automatic actions
 - Beam Lost → Remove IR beamline mirror



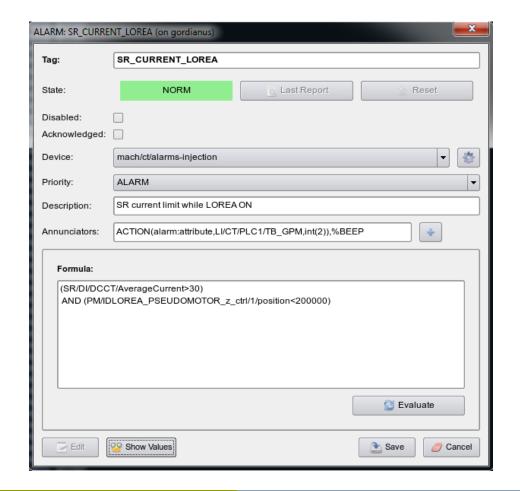
- Automatic actions
 - SR current limit → stops Linac (<u>Tango command</u>)
 - Save bunch intensity after injections (<u>launches script</u>)







- Automatic actions: example of flexibility and "other" use
 - New Insertion Device commissioning
 - FE not yet ready
 - Limit SR current while gap closed





Questions?

Acknowledgments
Thanks to Operators and to S.Rubio