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# Alternative integration methods and utilisation of dense output for field propagation

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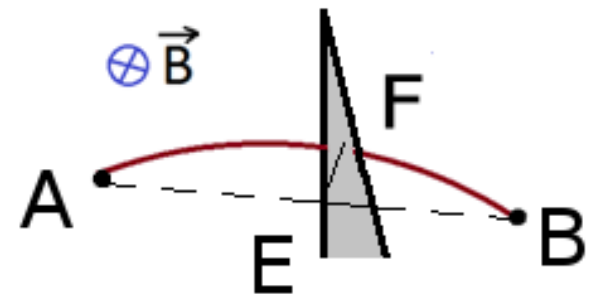
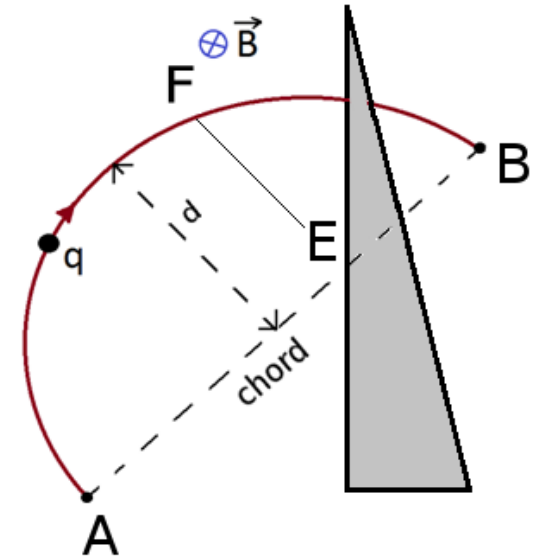
Mentored by: John Apostolakis

# Outline

- Field propagation in Geant4
- The Bulirsch-Stoer method
- Alternative integration strategy for dense output methods
- Verification
  - Propagation in uniform magnetic field
  - NTST test

# Field propagation in Geant4

- Uses Runge-Kutta integration with adaptive step size control
  1.  $d < \text{deltaChord}$
  2.  $\Delta B < \text{deltaOneStep}$
- Locates boundary intersection using iterative intersections of chords



Until  $|F - E| < \text{deltaIntersection}$

# Project goals

- Implement the Bulirsch-Stoer method
- *Motivation: For smooth functions and large steps, extrapolation methods are more efficient than the Runge-Kutta methods. One of the most efficient extrapolation methods is the Bulirsch-Stoer method.*
- Develop the alternative integration strategy for dense output methods
- *Motivation: Integration methods may need a fixed number of extra field evaluations to provide dense output. Using dense output the solution can be evaluated for any point within the integration interval.*

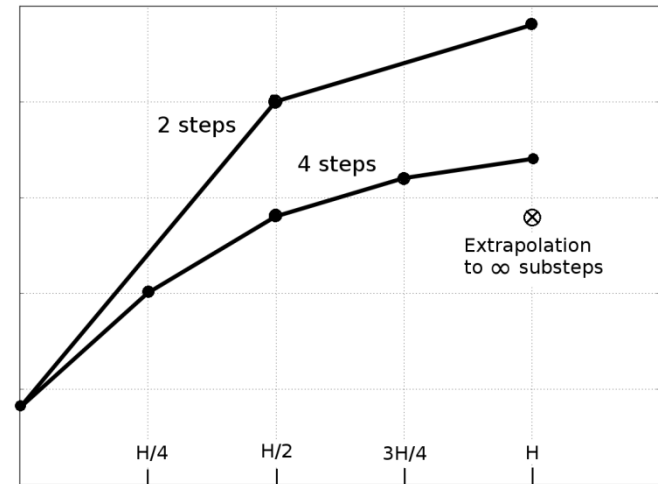
# The Bulirsch-Stoer method

## Idea:

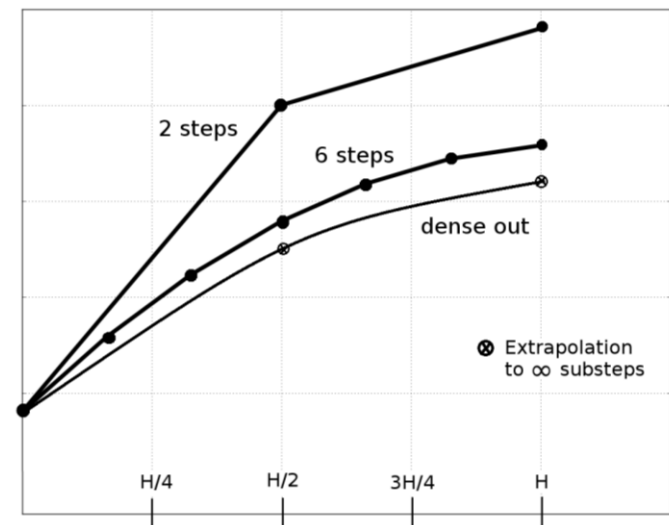
- Use midpoint method to estimate integral
- Vary number of intermediate points
- Approximate the integral using rational functions & extrapolate to  $n = \infty$

## Advantages:

- Step size and order control
- Very good for smooth problems and large steps
- Can provide dense output



$$n = 2i+2, \text{ for } i = 0, 1, 2, \dots$$



$$n = 4i+2, \text{ for } i = 0, 1, 2, \dots$$

# Alternative integration strategy for dense output methods

## Old strategy

- Make series of steps without error control to predict the step size (satisfying  $d < \text{deltaChord}$ )
- Make a step with error control to improve the accuracy ( $\Delta B < \text{deltaOneStep}$ )
- If the chord intersects:
  - make a series of substeps with error control to locate the intersection point

## New strategy

- Make one step with error control
- Use dense output to divide the step to substeps (satisfying  $d < \text{deltaChord}$ )
- For each substep:
  - if the chord intersects:
    - Use dense output to locate the intersection point

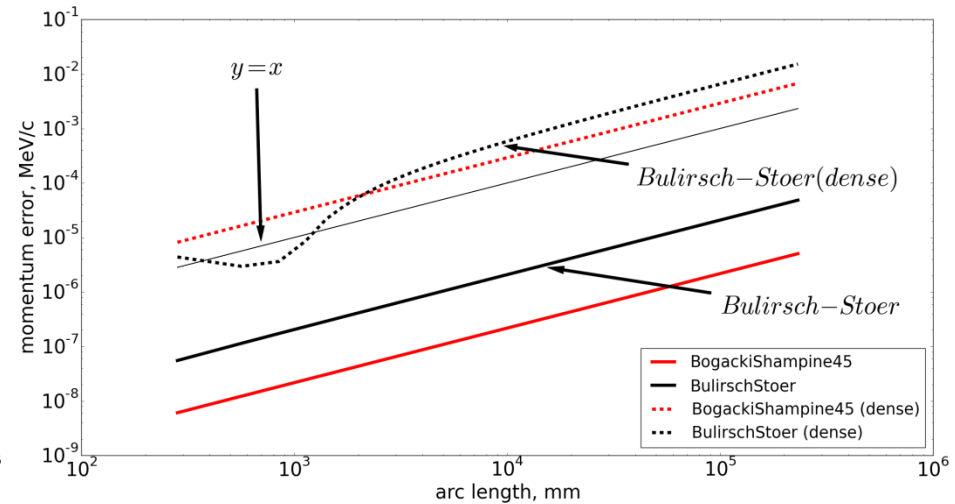
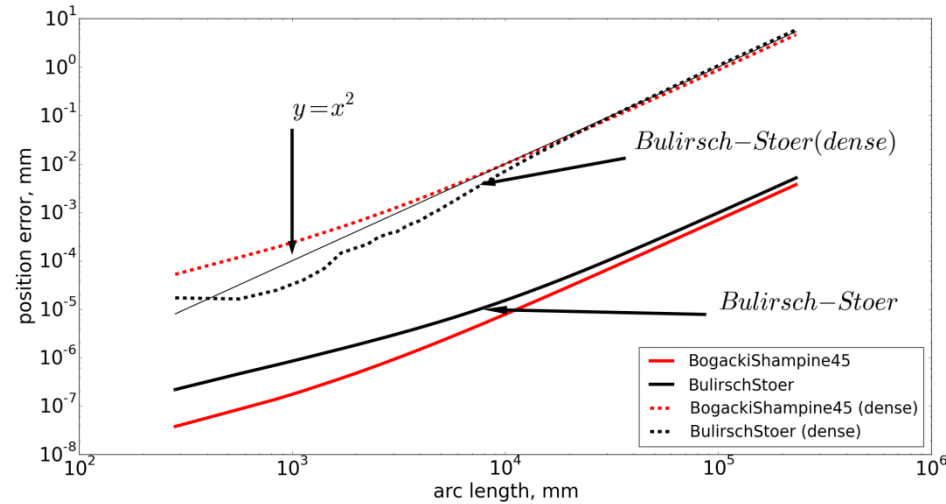
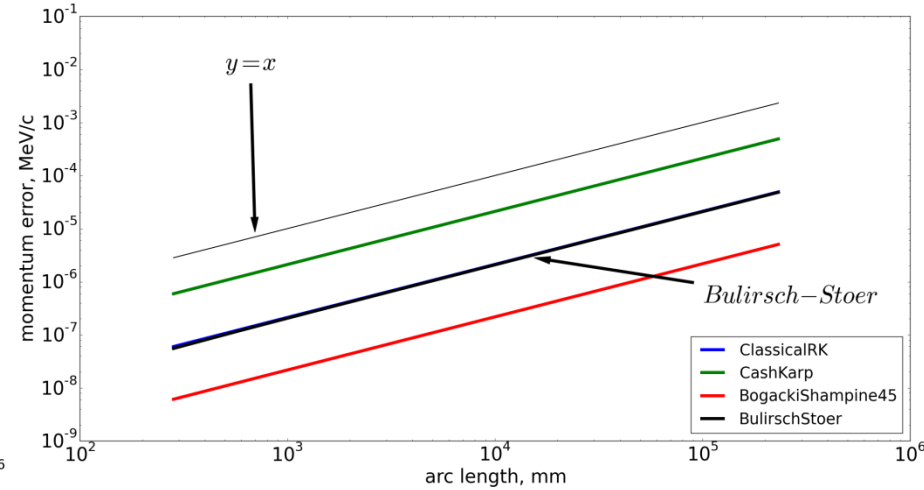
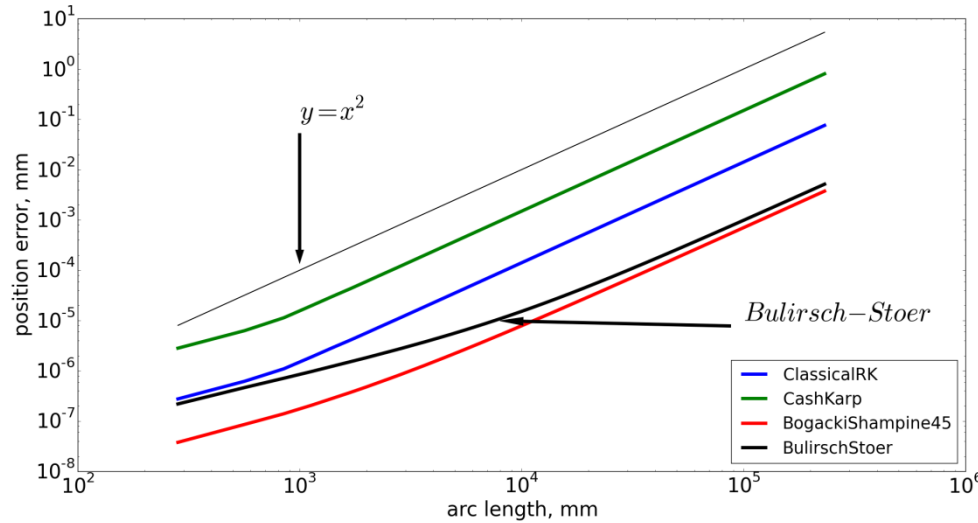
*Pros:* A lot fewer field evaluations required for large steps

*Cons:* Dense output is less accurate than the solution

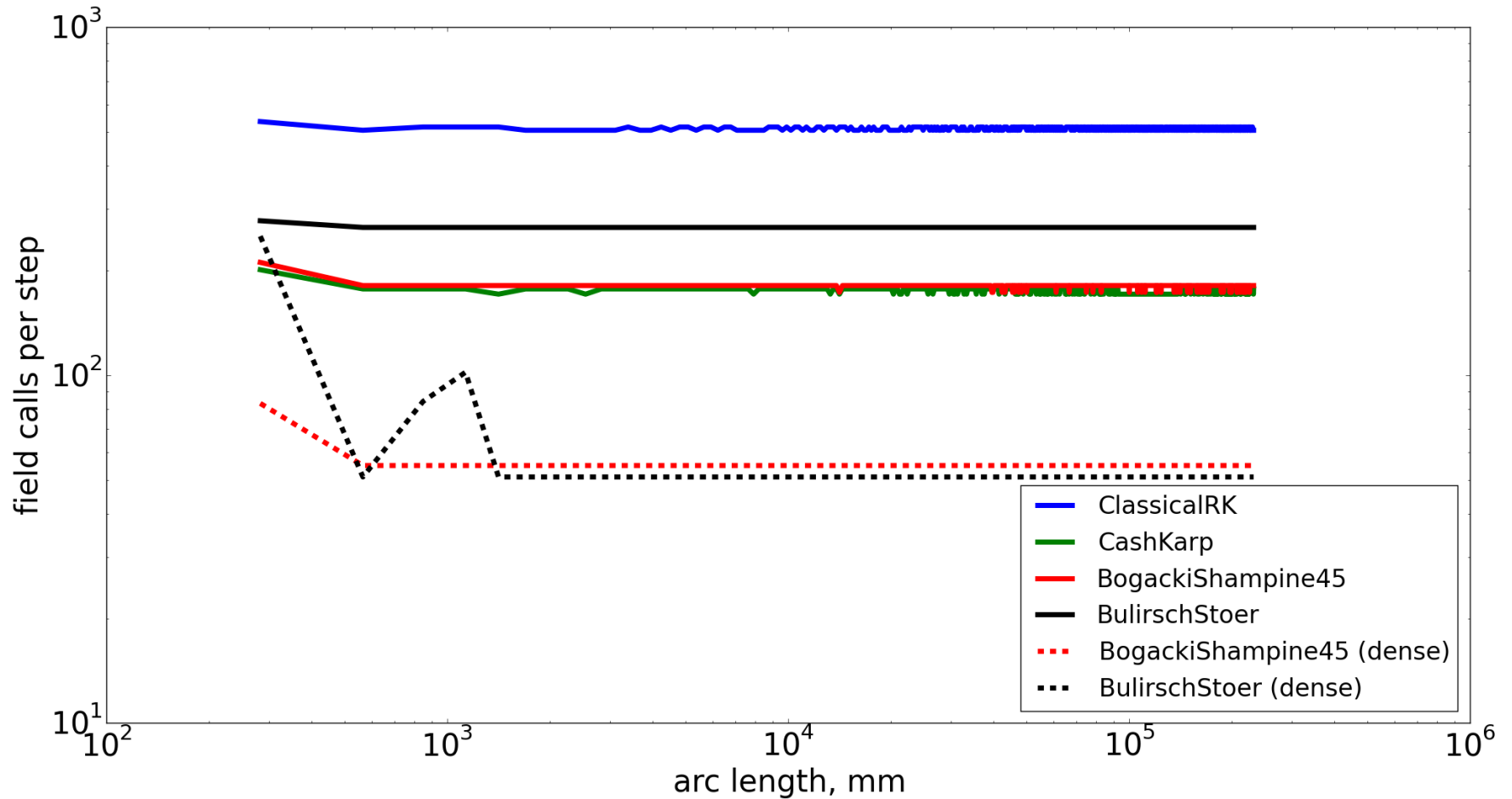
# Propagation in uniform magnetic field

1 MeV proton in the uniform 1 tesla magnetic field. Radius of the circle in xz plane is 102.20 mm

Momentum is 43.33 MeV/c.  $\Delta_{\text{OneStep}} = 1e-4$  mm,  $\Delta_{\text{Intersection}} = 1e-5$  mm



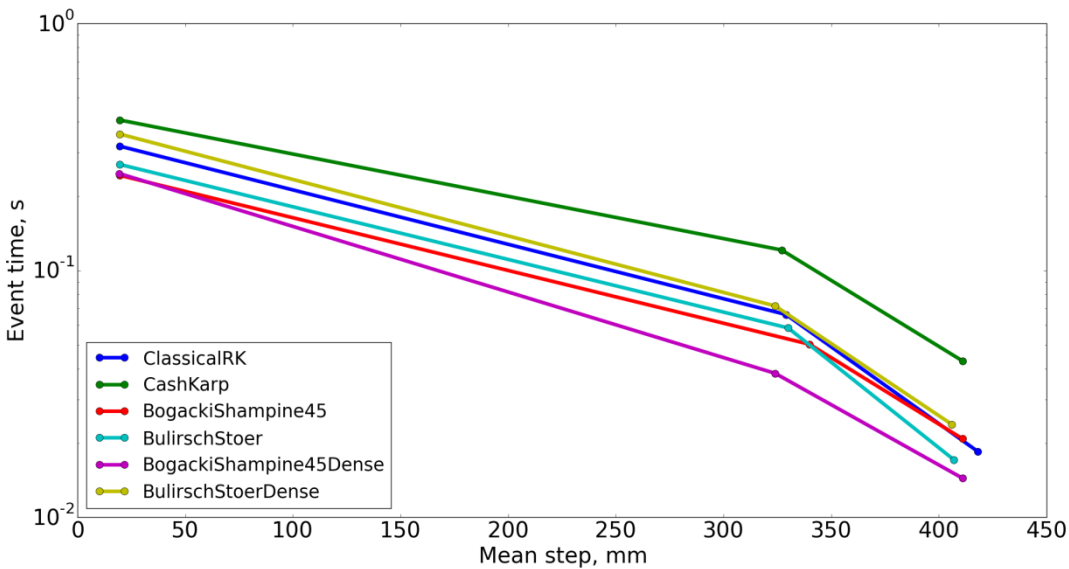
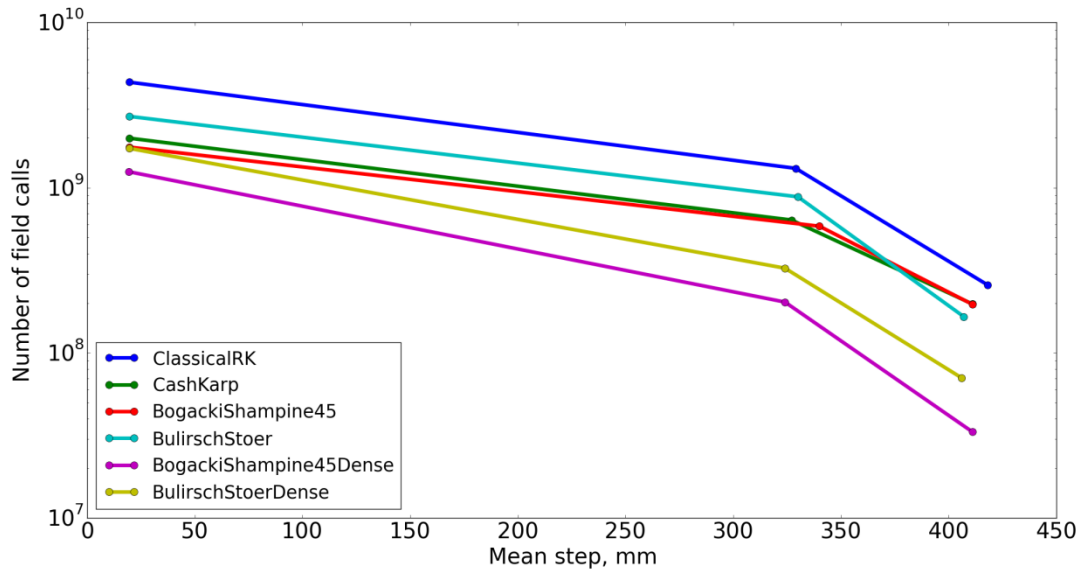
# Propagation in uniform magnetic field





# NTST test

Geant4 benchmark test.  
 Simulates the BaBar silicon  
 vertex tracker and 40-layer  
 drift chamber.



File	range cut	looper cut	min Ecat
run2a. mac	1 mm	200 MeV	1 MeV
run2b. mac	1 mm	Not applied	1 MeV
run2c. mac	1 mm	Not applied	Not applied

Thank you