

GQLink

An implementation of Quantized State System (QSS) methods in Geant4

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ACAT 2017, 21-25 August

University of Washington, Seattle, WA



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Introduction

The background of the slide is a complex, abstract pattern of thin, overlapping lines in various colors including red, green, blue, yellow, and purple. These lines are scattered across the entire frame, creating a sense of dynamic movement and complexity. In the center of the image, there is a distinct, dense cluster of blue lines that form a roughly circular shape, acting as a focal point. A thin, horizontal orange line is positioned just below the word 'Introduction', extending from the left edge of the slide towards the center.

Motivation of this work

- Simulation in HEP involves the numerical solution of ODE systems in order to determine the trajectories described by charged particles in a magnetic field.
- As a particle moves through a detector, each volume crossing interrupts the underlying numerical solver.
- Traditional methods can invest considerable computational efforts to handle very frequent discontinuities accurately (detection of intersection points).

Motivation of this work

- **Quantized State System** methods (**QSS**, Kofman 2001 [7]) is a modern family of numerical integration methods exhibiting attractive features for this type of HEP simulation scenarios.
- The goals pursued in this work are:
 - ▶ To develop a proof-of-concept implementation of QSS within the Geant4 simulation toolkit.
 - ▶ To address its suitability as an alternative production integrator, and
 - ▶ To characterize its performance in a realistic HEP application.

The background is a complex, abstract pattern of thin, overlapping lines in various colors including red, green, blue, yellow, and purple. These lines form a dense, chaotic web. In the center of the image, there is a prominent, circular cluster of blue lines that are more tightly packed than the surrounding lines. A horizontal orange line is positioned to the left of the central blue cluster, extending from the left edge of the frame towards the cluster.

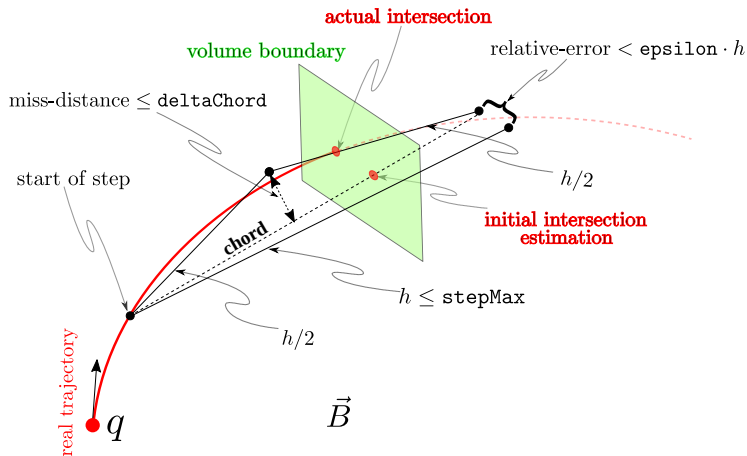
Background information

The Geant4 simulation toolkit

- **Geant4** [1] is the most widely used simulation toolkit in contemporary HEP experiments.
- Provides classical numerical methods based on **time discretization** [3] (variations of the Runge-Kutta family of numerical solvers [4]).
- Uses custom iterative algorithms to approximate the event times of each spatial discontinuity (which mostly occur after a physics interaction).
- When these events are very frequent, they can dominate the CPU time dedicated to the integration method, and reduce considerably its performance.

Geant4: particle transport

Transportation of a charged particle q along a step of length h proposed by a physics process:



\Rightarrow a total of 11 RHS evaluations involved for the 4th order Runge-Kutta.

Quantized State System methods

- QSS methods are based on **state variable quantization**.
- As opposed to traditional solvers which discretize **time** (e.g., Runge-Kutta family) QSS methods discretize the system's **state variables**.
- **Continuous state variables** are thus **quantized** and approximated by their corresponding **quantized variables**.
- The relation between both is given by a **quantization function** which is in charge of the **error control** and **accuracy control**.

ODE system

$$\dot{\mathbf{x}}(t) = \mathbf{f}(\mathbf{x}(t))$$

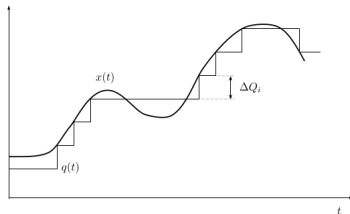
\Rightarrow

Quantized system

$$\dot{\mathbf{x}}(t) = \mathbf{f}(\mathbf{q}(t))$$

QSS1: first order quantization function

$$q_i(t) = \begin{cases} x_i(t) & \text{if } |q_i(t^-) - x_i(t)| \geq \Delta Q_i \\ q_i(t^-) & \text{otherwise} \end{cases}$$



- ΔQ_i is the **quantum**.
 - ▶ **Maximum deviation allowed** between x_i and q_i (error control).
 - ▶ Derived from the **precision** demanded by the user.
- Higher order methods (**QSS n**) follow essentially the same principle.
 - ▶ From the definition above, in QSS1 $q(t)$ follows piecewise constant trajectories.
 - ▶ In QSS n , $q(t)$ is composed of piecewise $(n - 1)$ -th order polynomials.

QSS features

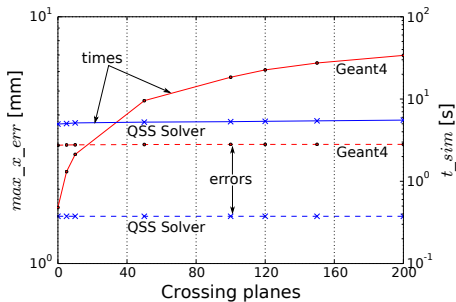
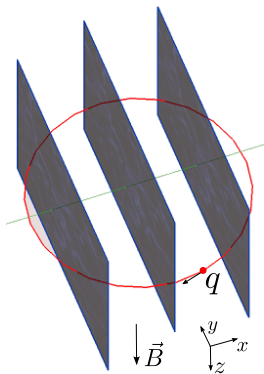
- QSS features attractive for HEP problems
 - ▶ **Asynchronicity**
Decoupled, independent computation of changes in states variables.
 - ▶ **Lightweight discontinuity handling**
Boundary crossings detected by finding roots of polynomial equations.
 - ▶ **Dense trajectory output**
- Selected speedups reported for QSS vs. time-slicing methods modeling processes in various domains [6][2]

Model	Features	Speedup
advection-reaction	10^4 state variables	30x
spiking neurons	10^3 state variables	35x
logic inverters chain	4000 neurons, 80 connections per neuron	100x
cellular division	100 cells, 600 state variables	100x to 1000x

- The QSS Solver [5] is an open-source standalone simulation tool.
- Provides C implementations for several QSS methods.
- Provides also implementations of some traditional algorithms (e.g., Dormand-Prince method).
- Our **GQLink interface** partially relies on the QSS Solver's simulation engine.

Preliminary comparison between Geant4 and QSS Solver

- Circular 2D particle motion, uniform magnetic field, crossing equidistant parallel planes.
 - ▶ Known exact analytic solution facilitates error analysis.
 - ▶ Physics processes turned off.



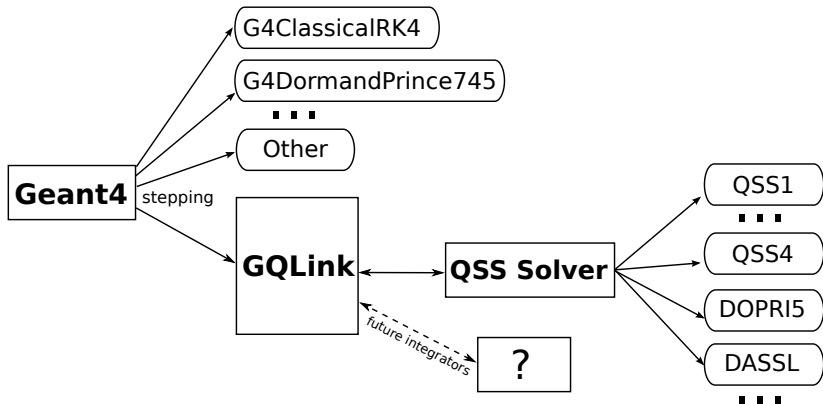
- With 200 plane crossings and a track length of 100 m, QSS Solver is 6x faster than Geant4[9][8].

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Geant4 to QSS Link (GQLink): an implementation of QSS within Geant4

- GQLink is a proof-of-concept implementation of QSS in Geant4.
 - ▶ Geant4 version 10.03.p01 (released February 24, 2017).
 - ▶ QSS Solver engine from version 3.0 (as of March 2016).
- Provides three new shared libraries to Geant4:
 - ▶ `libqss`: QSS core functionality.
 - ▶ `libgqlink`: interface API between Geant4 and QSS.
 - ▶ `libmodel`: model definition and structure (i.e., Lorentz equations).
- QSS methods have complete control over the propagation for each Geant4 transportation step.
 - ▶ QSS manages accuracy in its own terms (through the control of the quantum ΔQ).

GQLink: high-level diagram



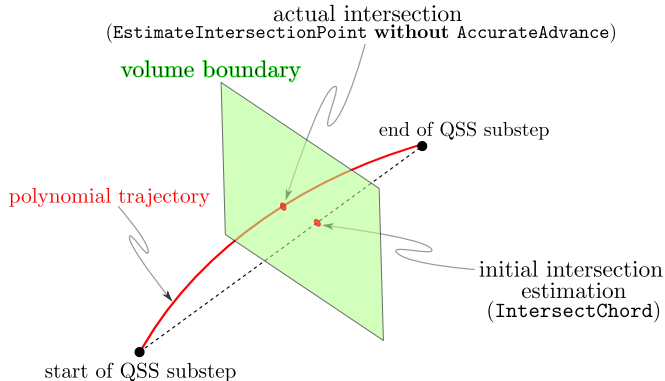
- GQLink: not another *Geant4 stepper*.
- An abstract, clean, single entry point interface to the QSS Solver family of numerical integration methods.

Detection of boundary crossings

- Boundary crossings are detected through Geant4's geometry library.
- Follows same call pattern as in standard Geant4 simulations:
 - ▶ `LocateGlobalPointWithinVolume`
 - Notifies the geometry navigator that the particle has moved to a new position inside the current volume.
 - ▶ `IntersectChord`
 - Computes an initial estimation of an intersection by means of a linear segment between the endpoints of the step.
 - ▶ `EstimateIntersectionPoint`
 - Refines the initial estimation mentioned above through an iterative procedure.

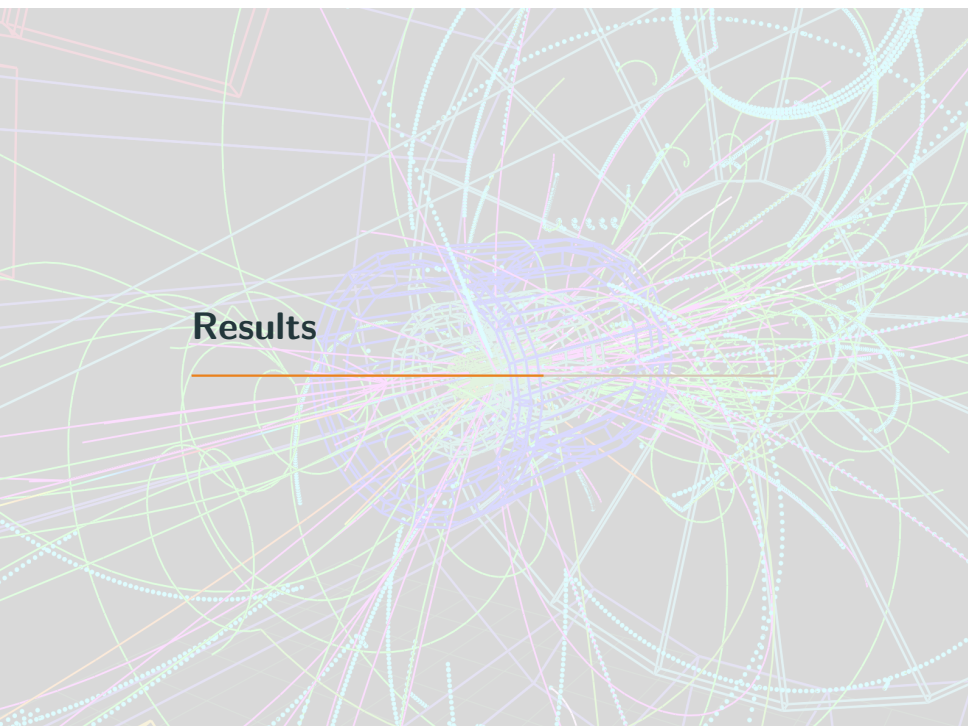
Detection of boundary crossings

Cheaper particle transport until the crossing point using QSS polynomial dense output instead of iterative procedures:



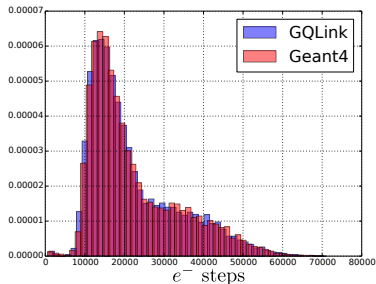
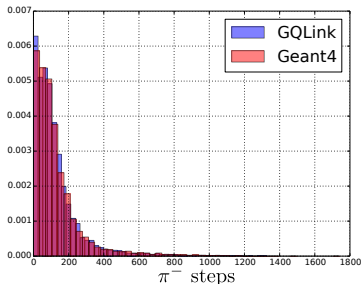
- QSS dense output not fully exploited yet for boundary crossing detection \Rightarrow main goal driving our current work.

Results



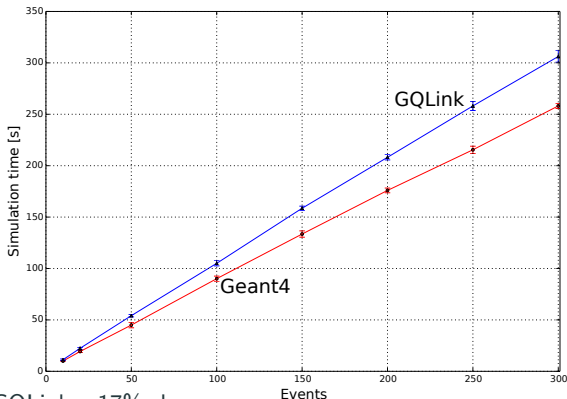
CMS application analysis

- GQLink validation was performed against a standalone Geant4 application featuring:
 - ▶ Full CMS (Run1) detector geometry.
 - ▶ Volume base magnetic field excerpted from CMSSW.
 - ▶ Particle gun shooting π^- particles (10 GeV, 10^4 events).
 - ▶ Pythia $pp \rightarrow H \rightarrow ZZ$ (Z to all channels) ($\sqrt{s} = 14$ TeV, 50 events).
- Step count distribution for π^- (left) and secondary electrons (right) for 10^4 single π^- events, showing equivalency of GQLink simulations:



CMS application: performance comparison

- Single π^- events



- ▶ GQLink $\sim 17\%$ slower.

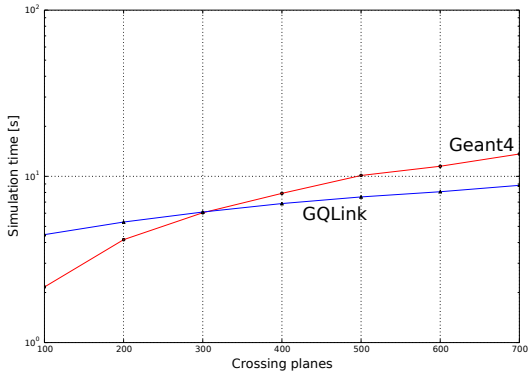
- Pythia $H \rightarrow ZZ$ events

- ▶ GQLink $\sim 22\%$ slower (5.86 hours vs. 4.8 hours).

- Geant4 stepper: G4ClassicalRK4 (accuracy set to $\epsilon = 10^{-5}$).

Alternative scenario: helix and parallel planes

- Different scenario: helix trajectory crossing parallel equidistant planes & more frequent boundary crossings.
- Physics processes turned off.
- Using G4ClassicalRK4 stepper (accuracy set to $\epsilon = 10^{-5}$).

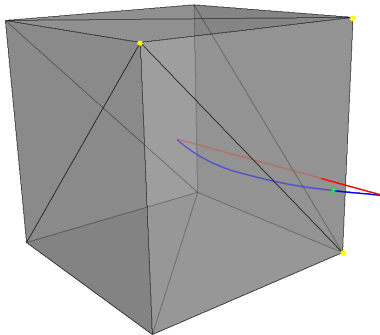


- GQLink outperforms Geant4 when using ≥ 300 planes ($\sim 35\%$ faster for 700 planes).

The background is a complex, abstract composition of numerous thin, overlapping lines in various colors including red, green, blue, yellow, and purple. These lines are mostly curved and chaotic, creating a sense of movement and complexity. In the center of the image, there is a dense, spherical cluster of blue lines, which appears to be the focal point of the composition. A solid horizontal brown line is positioned below the text, extending across the width of the text area.

Work in progress

- Exploitation of QSS capabilities for efficient geometry crossing detection:
 - ▶ Conversion of Geant4 solids into faceted polyhedrons.
 - ▶ Finding **intersection points** by (analytically) solving a polynomial equation given by the equation of a plane and the QSS polynomials approximating the **trajectory**.
 - ▶ Candidate plane given by the **face** crossed by the **linear segment** joining the endpoints of a step.



Conclusions

Conclusions

- We developed **GQLink**, a prototype for QSS methods within Geant4.
- Validation: number of steps and tracks produced are statistically consistent with Geant4's for both toy examples and realistic HEP applications.
- Performance:
 - ▶ We found that GQLink can outperform Geant4 in certain simplified scenarios involving tracking only.
 - ▶ Preliminary tests revealed GQLink is currently $\sim 17\%$ slower than standard Geant4 in a full CMS realistic scenario (using single π^- events).
- From an abstract viewpoint, GQLink also opens new possibilities to interface Geant4 with any external stepper.

Thank you!

Questions?



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