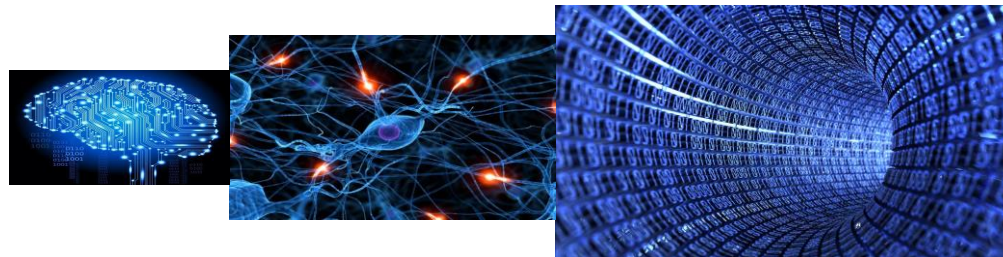


# ACAT Track 2 Summary

**Sergei Gleyzer**

**University of Florida**



**August 25, 2017**

- **33 talks**
- **26 posters**
- **13 collaborations represented**
  - ALPHA, ATLAS, Belle II, BESIII, CMS, Dune, DZero, IceCube, JUNO, LHCb, MicroBooNE, Opera, PANDA

- **Algorithms and applications**
  - Physics, object id, reconstruction, tracking, trigger, simulation
- **Analysis Tools**
  - General, Simulation, Fitting, ML, Visualization, Preservation

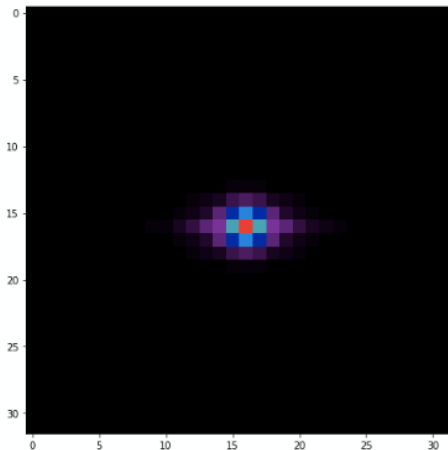
# Machine Learning



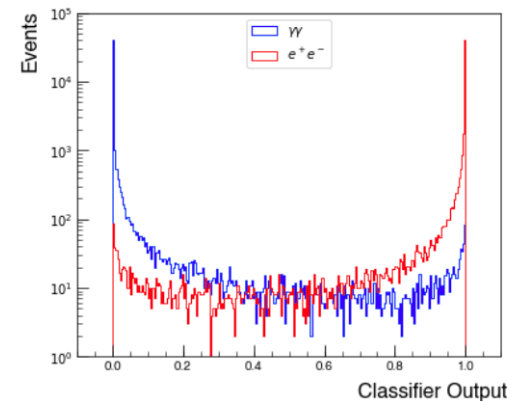
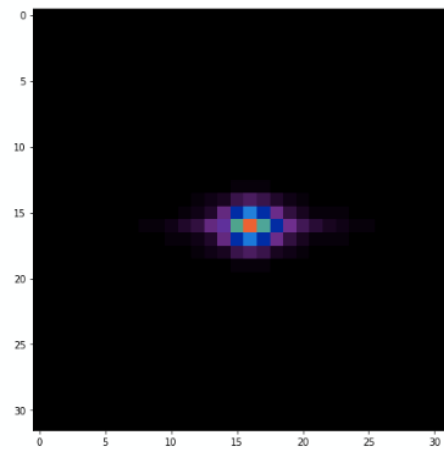
## Convolutional Neural Networks

- By-passing traditional reconstruction

Photon-Induced EM Shower  
mean energy distribution over 10k events



Electron-Induced EM Shower  
mean energy distribution over 10k events



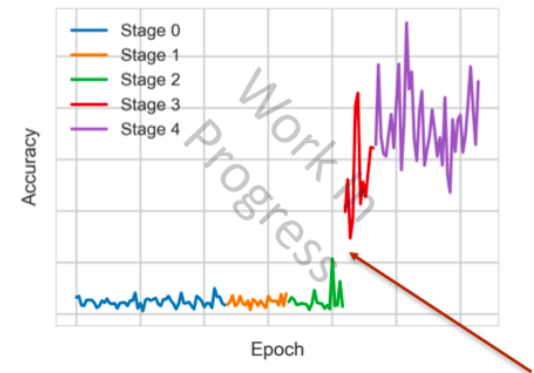
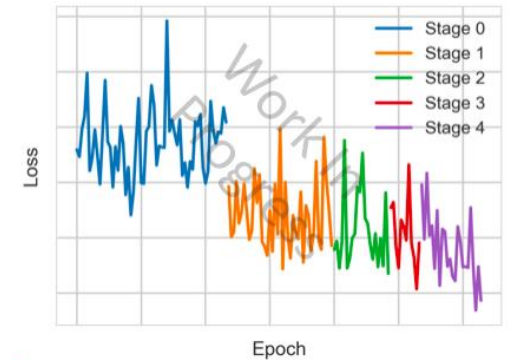
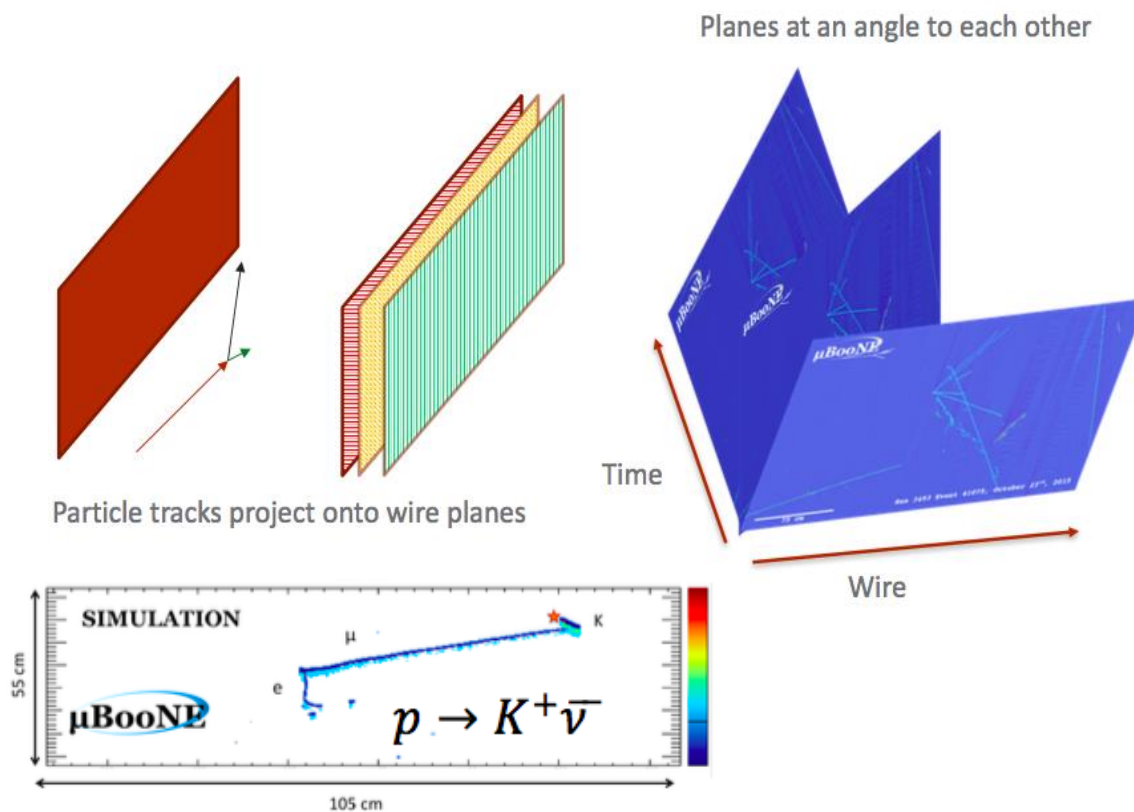
**ResNet-23**

Test Set ROC AUC

0.997

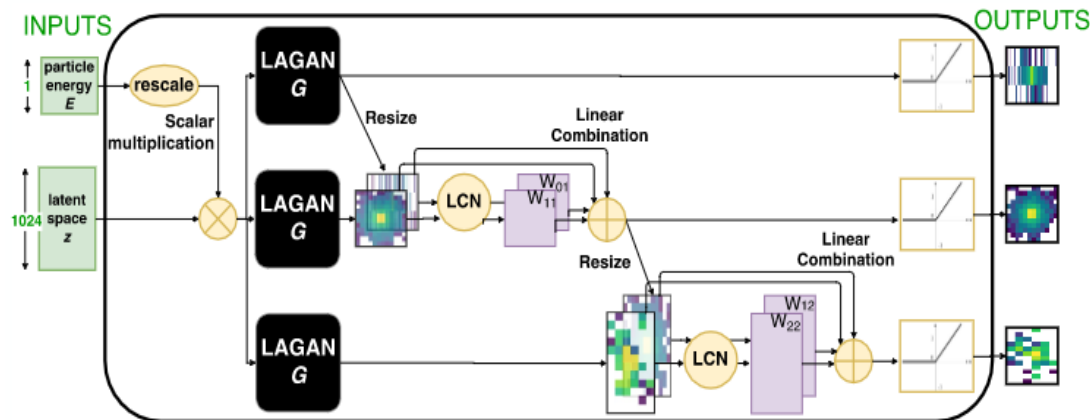
Talk by M. Andrews

## Convolutional NNs in $\mu$ BooNE

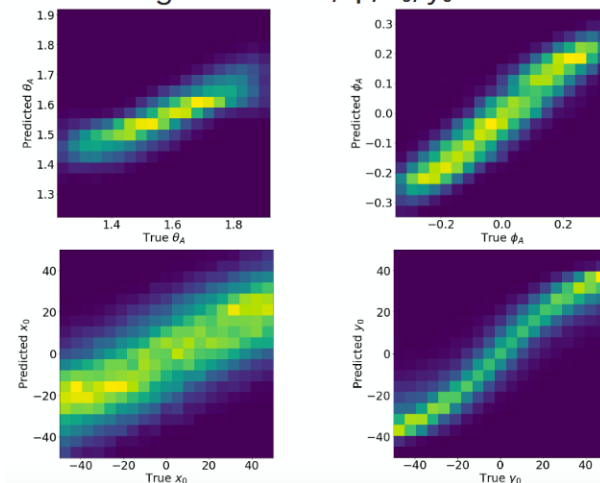


Talk by K. Wierman

# Simulation GANs

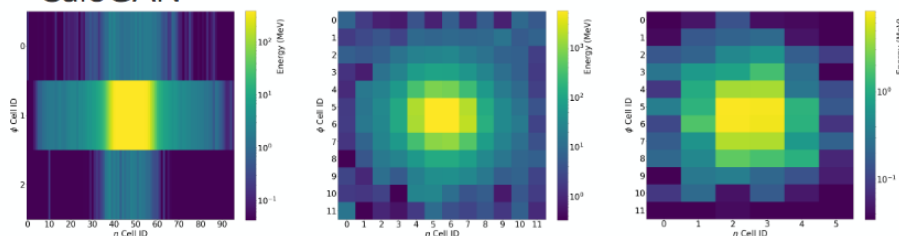


- Regression on  $\theta$ ,  $\varphi$ ,  $x_0$ ,  $y_0$

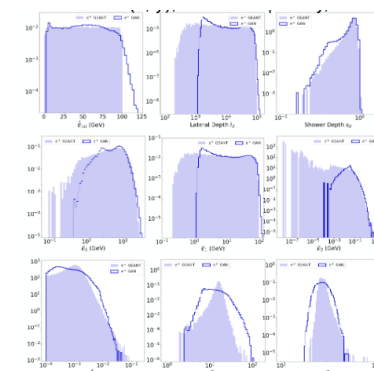
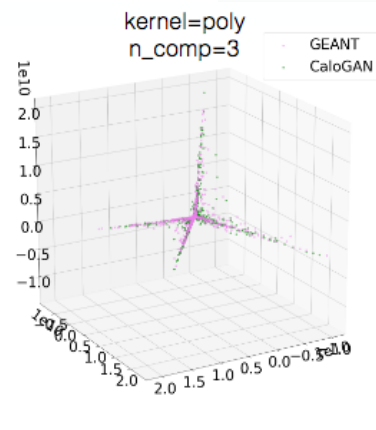
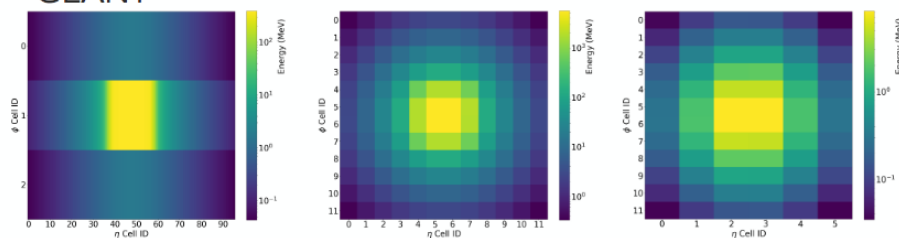


Dataset:  $5^\circ$ ; Net: soft sparsity, multiplied E, Conv. attn. and layers

## • CaloGAN

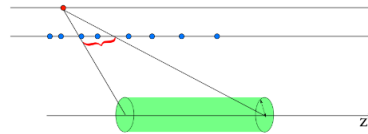
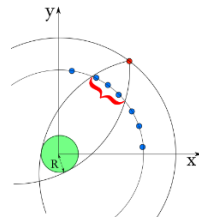
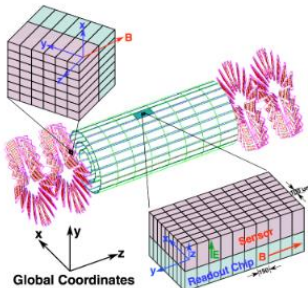
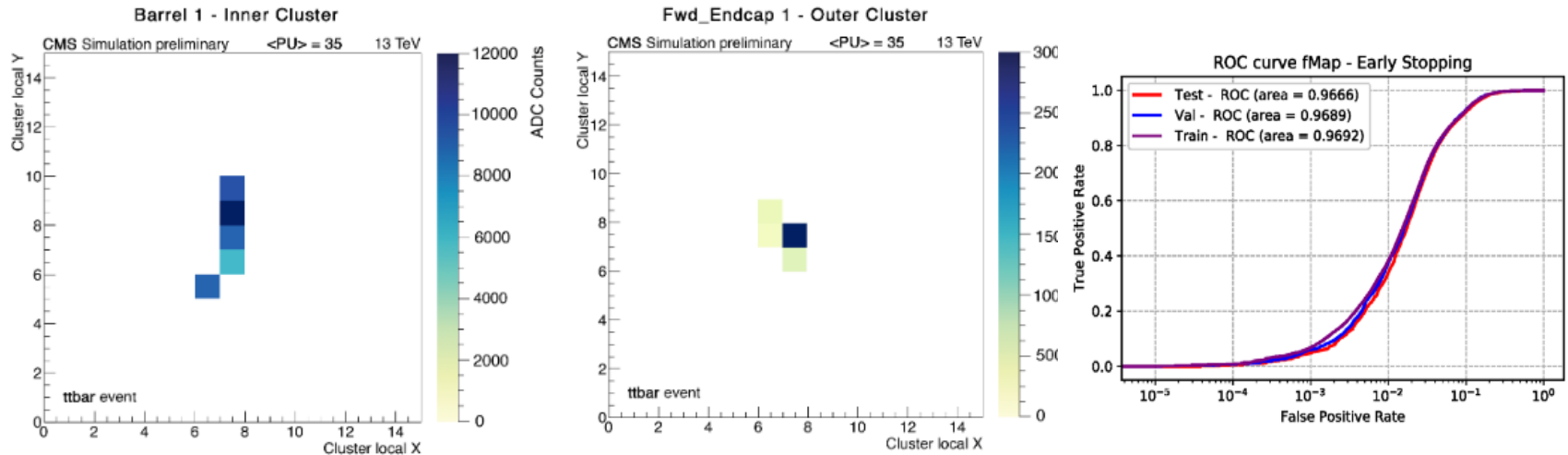


## • GEANT



Talk by L. de Oliveira

## CNNs for track seeding at CMS HLT



Efficiency (tpr) @ fake rejection

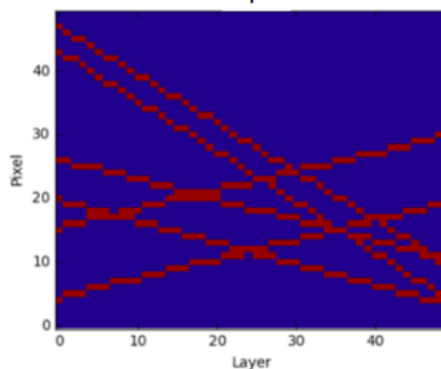
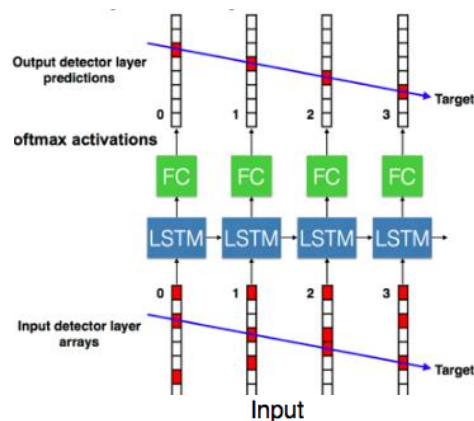
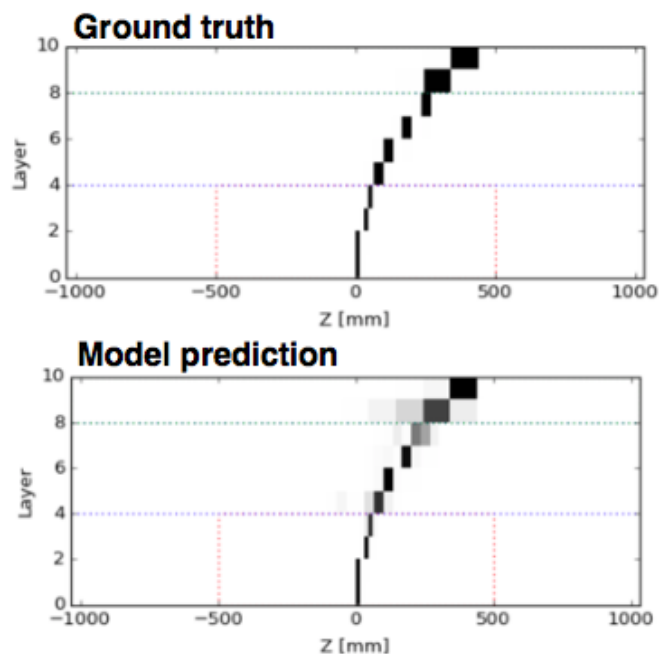
tpr @ rej 50%: 0.99767728149  
tpr @ rej 75%: 0.986272733607  
tpr @ rej 90%: 0.896151255429  
tpr @ rej 99%: 0.285555013588

Talk by F. Pantaleo

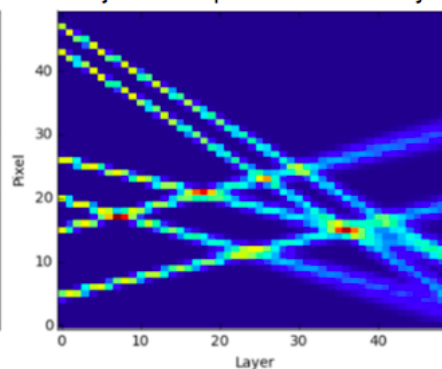


## Recurrent networks for tracking

Time dimension  
(state memory)



Projected Output with Uncertainty

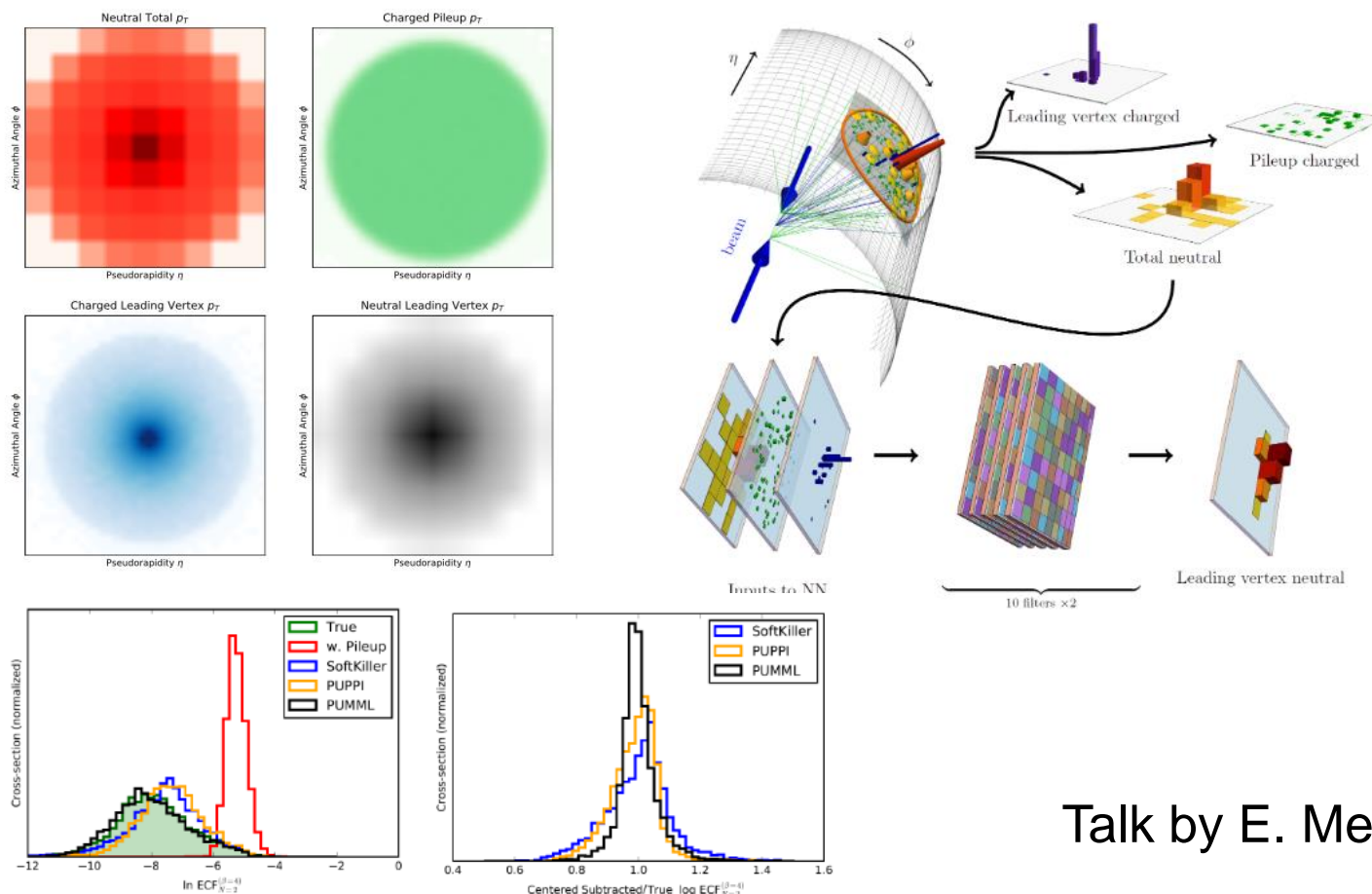


Talk by A. Tsaris

# Pileup Removal

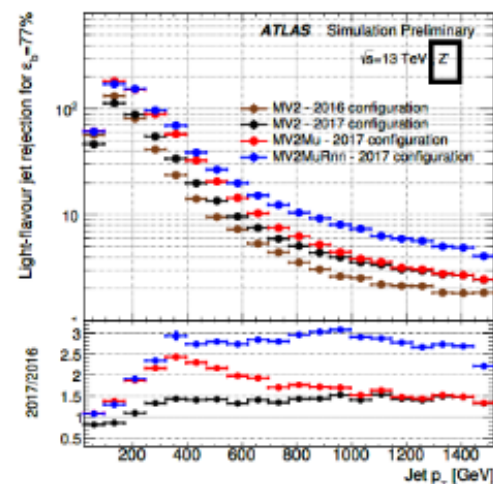
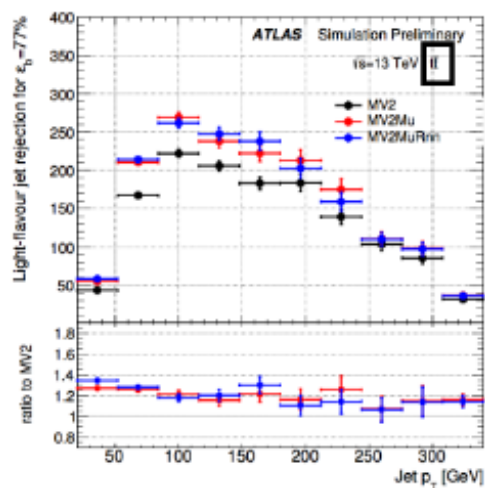
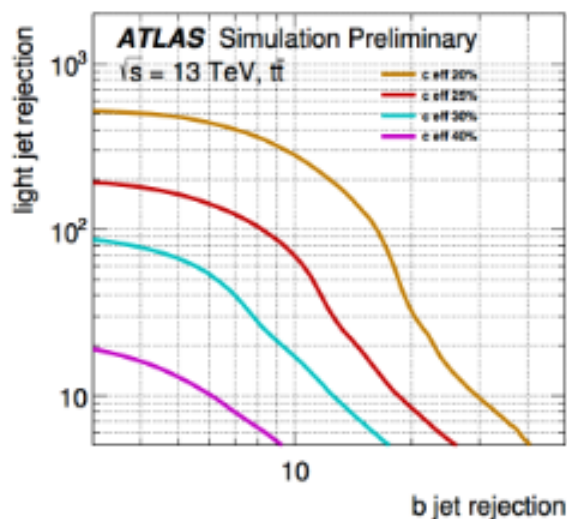
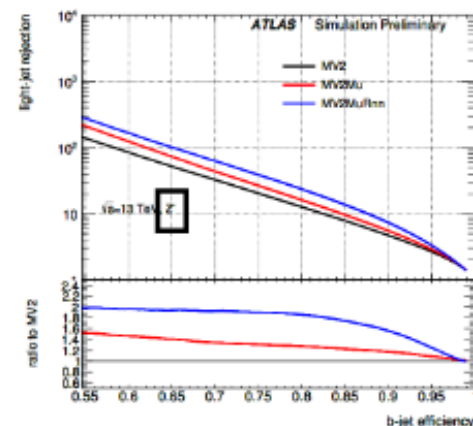
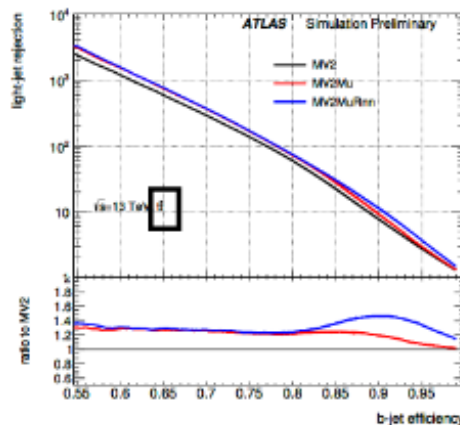
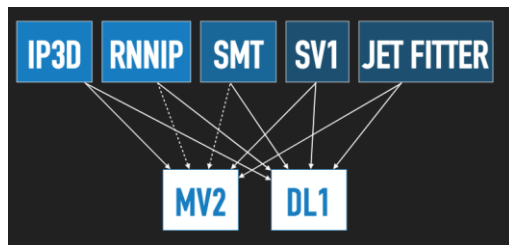


## Convolutional NNs with images



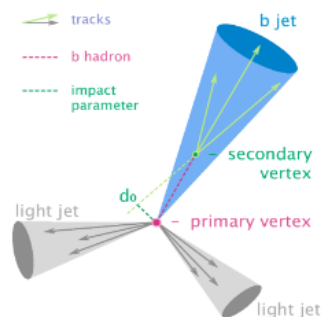
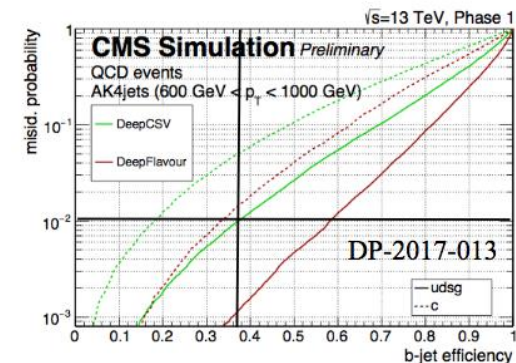
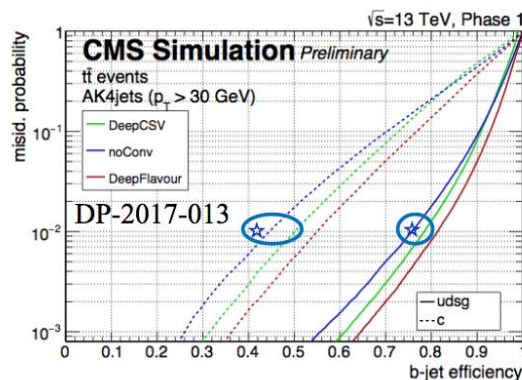
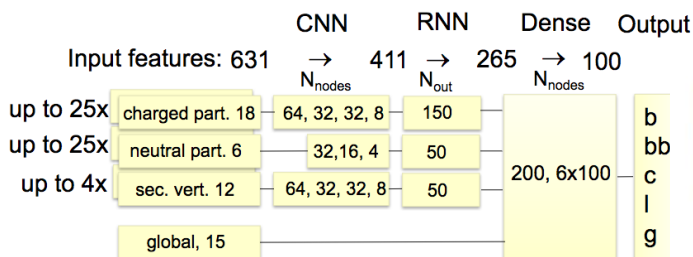
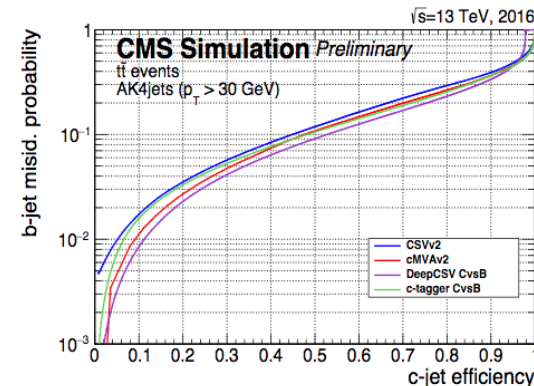
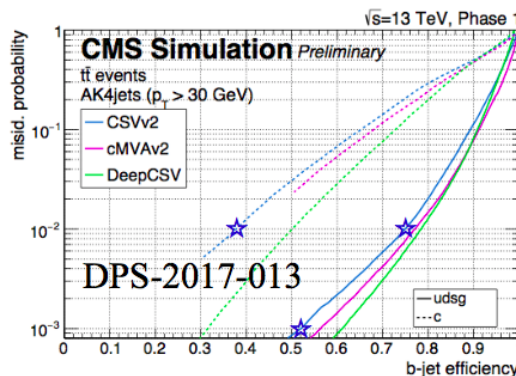
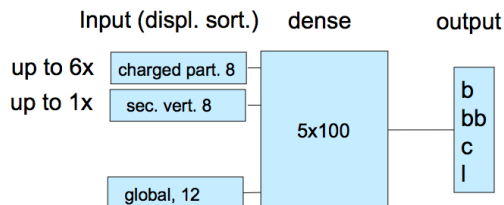
Talk by E. Metodiev

# ATLAS B Tagging



Talk by M. Paganini

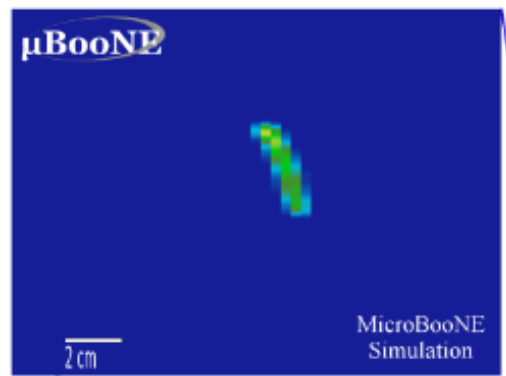
# CMS Flavor Tagging



1.7	2.8	Baseline, $p_T^{\text{miss}} > 300, \geq 3b$	4.6 ± 0.4	2.5	4.0
		Baseline, $p_T^{\text{miss}} > 300, 4b$			

e.g. up to ~50% more signal for 15% more bkg

Talk by M. Stoye



$P(p)$	=	<b>0.9789</b>
$P(\mu^\pm)$	=	0.0012
$P(\pi^\pm)$	=	0.0067
$P(e^\pm/\gamma)$	=	0.0075
$P(\text{cosmic})$	=	0.0058

## Boosting and the XGBoost<sup>[3]</sup> algorithm

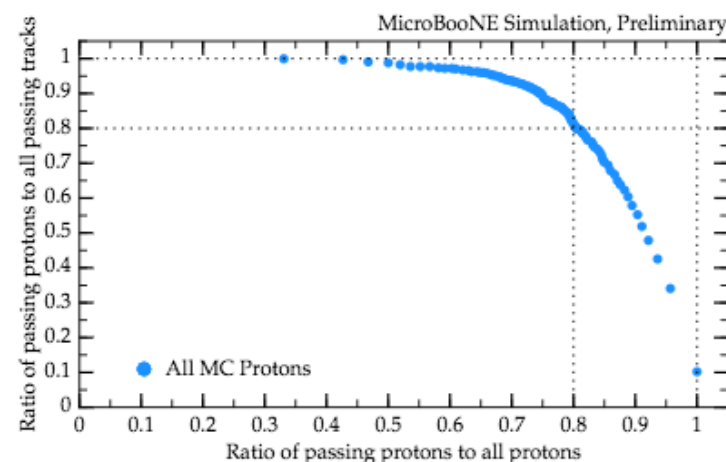
### Gradient-Boosting:

- The loss function,  $l$  at tree  $t$  is

$$l(y_i, \hat{y}_i^{(t-1)} + f_t(\mathbf{x}_i))$$

- the difference between the true label ( $y_i$ ) and the prediction of the existing ensemble ( $\hat{y}_i^{(t-1)}$ ) plus the output of the new tree ( $f_t(\mathbf{x}_i)$ )
- To simplify the computation, use the second-order approximation:

$$l(y_i, \hat{y}_i^{(t-1)} + f_t(\mathbf{x}_i)) \approx l(y_i, \hat{y}_i^{(t-1)}) + \frac{\partial l(y_i, \hat{y}_i^{(t-1)})}{\partial \hat{y}_i^{(t-1)}} f_t(\mathbf{x}_i) + \frac{1}{2} \frac{\partial^2 l(y_i, \hat{y}_i^{(t-1)})}{\partial^2 \hat{y}_i^{(t-1)}} f_t^2(\mathbf{x}_i)$$



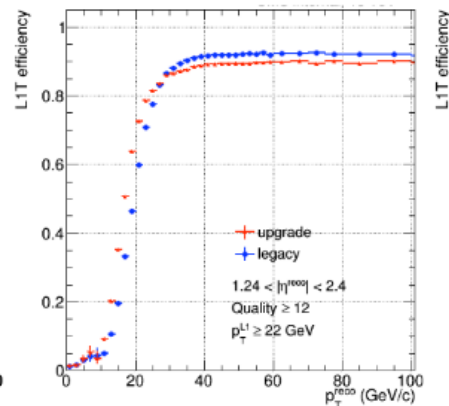
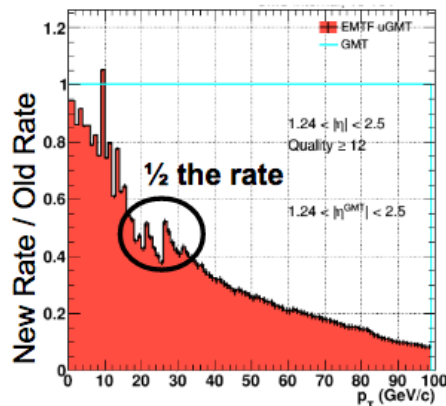
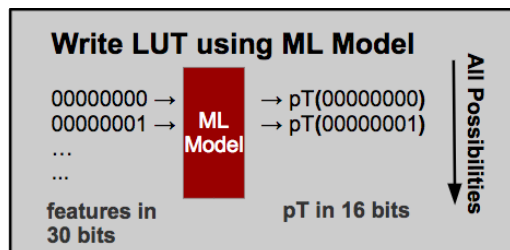
Talk by K. Woodruff



# Trigger Applications

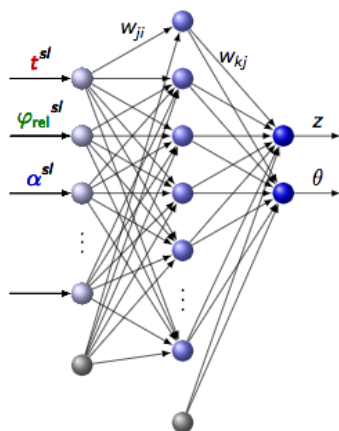


## CMS L1

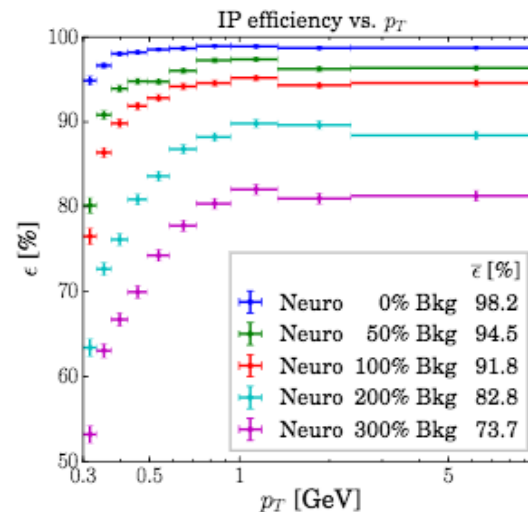
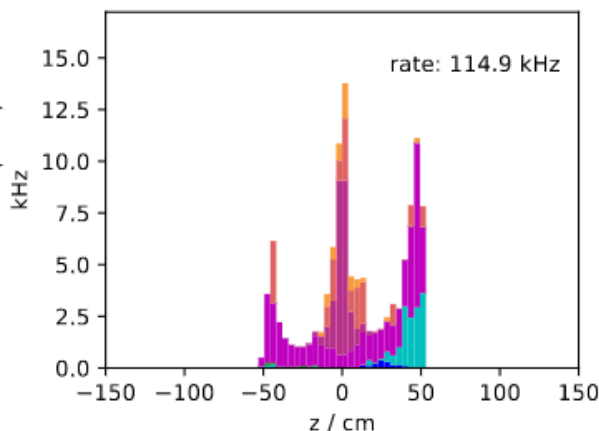


Talk by A. Carnes

## Belle II



### Neural Network Track Estimates



Talk by S. Skambraks

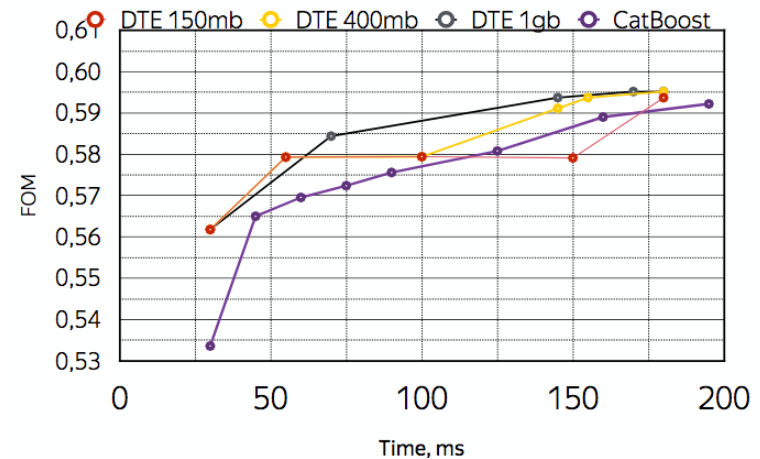
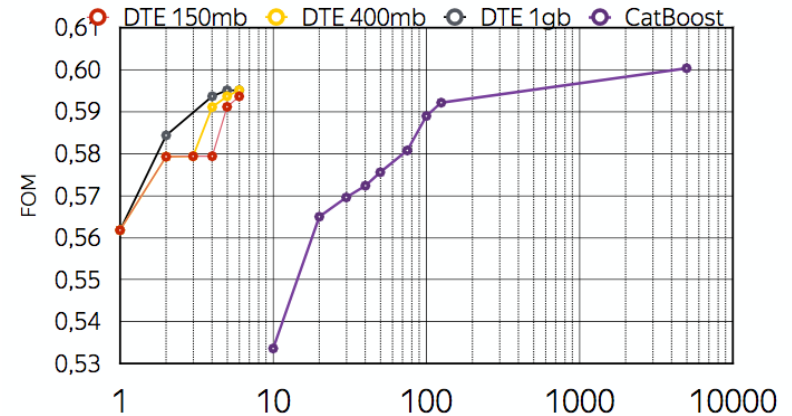
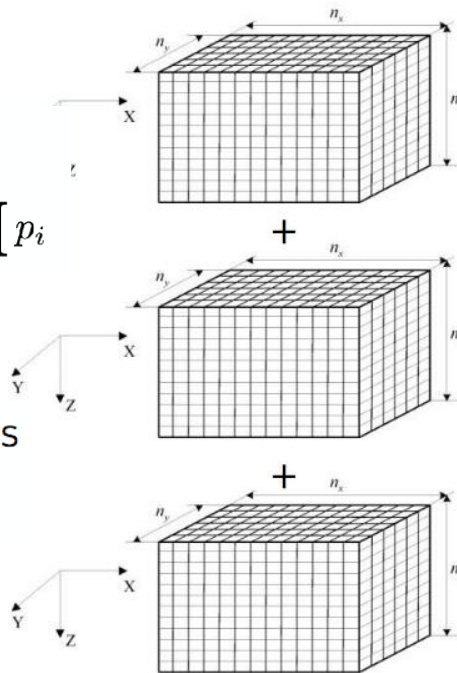
## LHCb

$$\begin{aligned} & D = (f_1, \dots, f_n) \\ & f_i = \{b_{i1}, \dots, b_{ip_i}\} \\ & S(D) \propto \prod |f_i| = \prod p_i \end{aligned}$$

> CatBoost

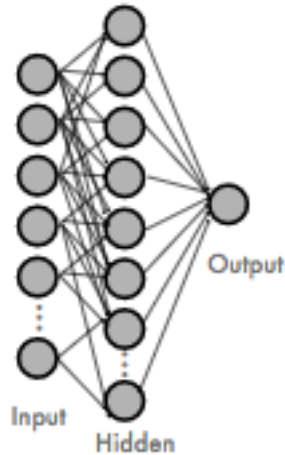
> Uses oblivious trees

> Discretize features



Talk by A. Ustyuzhanin

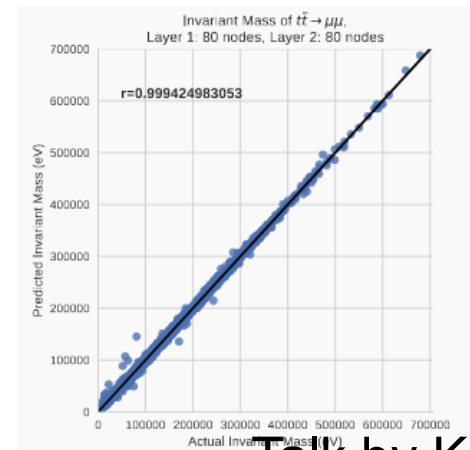
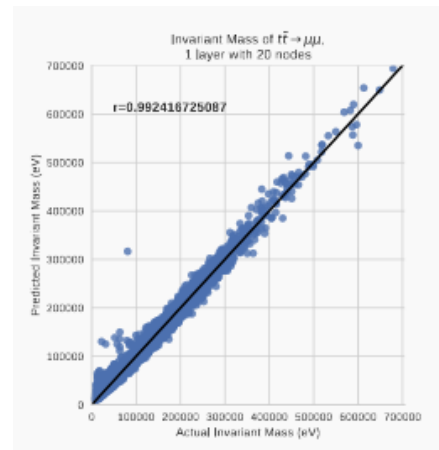
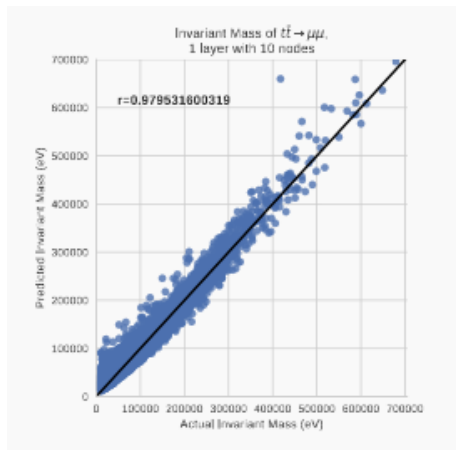
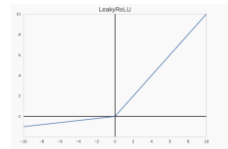
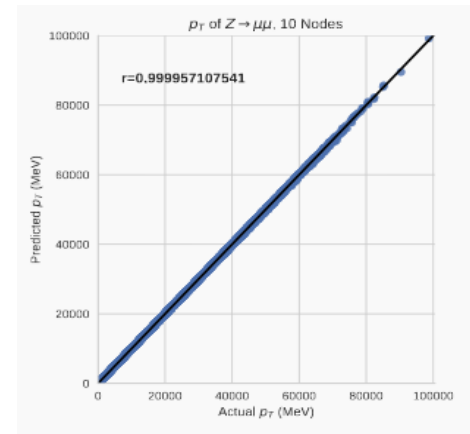
# Learning Features



**Problem:**  
Networks with  $> 1$  layer are  
very difficult to train.

**Consequence:**  
Networks are not good  
at learning non-linear functions.  
(like invariant masses!)

**In short:**  
Can't just throw 4-vectors at NN.



Talk by K. Chitturi



# Analysis Tools

## Conclusion – Main Evolution Items

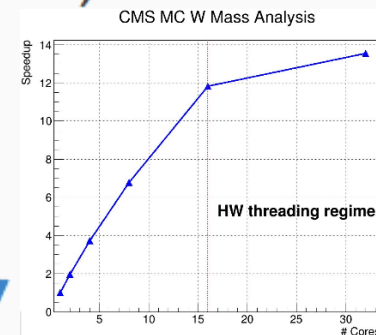
- ❖ I/O: LZ4, vectorized zlib; TTree merging
- ❖ Parallelization: math, I/O, analysis
- ❖ Vectorization: math, user interfaces
- ❖ Math: see above, plus RooFit, TMVA with GNN, RNN
- ❖ Graphics: using web technology

Talk by A. Naumann



# TDataFrame: Declarative Analysis

- ▶ New way to interact with ROOT columnar data format
  - Inspiration from Pandas, Spark, and others
  - Similar ideas proposed in the past (e.g. LINQToROOT by G. Watts)
- ▶ Analysis is a graph of:
  - **Transformations**: filter, add a column, ...
  - **Actions**: Fill an histogram, a profile, count events, ...
- ▶ Specify **what** you want and let ROOT choose **how**
  - Computation triggered lazily
  - Several optimisations (e.g. partitioning, caching, reordering, parallelisation)



Talk by G. Amadio

## DIANA: Histogrammar

- Spark manages concurrency (no event loop)
- Histogrammar designed for map-reduce environment
  - Functional interface
    - Fill histograms by passing lambda functions
    - Same as transformations in Spark
  - Histogrammar fills histogram data structures → afterwards convert into favorite plotting tool

*histo·grammar*  
/histō,'gɹæm.ər/

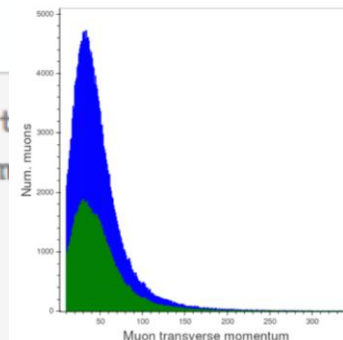
MAKING HISTOGRAMS FUNCTIONAL

ROOT:

```
histogram = ROOT.TH1F("name", "title", 100, 0, 10)
for muon in muons:
    if muon.pt > 10:
        histogram.fill(muon.mass)
```

Histogrammar:

```
histogram = Select(lambda mu: mu.pt
                    Bin(100, 0, 10, lambda mu: mu.mass
                        Count()))
for muon in muons:
    histogram.fill(muon)
```



Talk by O. Gutsche

<http://histogrammar.org>

# More Tools



**GooFit 2.0**

**Matex**

**Vispa**

**CatBoost**

**Rift**

**RECAST**

**Fitting**

**Deep learning**

**Deep learning**

**Gradient Descent**

**VR**

**Re-interpretation**

# Summary



- **Excellent sessions**
- **State of ML in HEP**
- **Thanks to all the presenters and attendees**