

Lecture 2: Magnetization, cables and ac losses

Magnetization

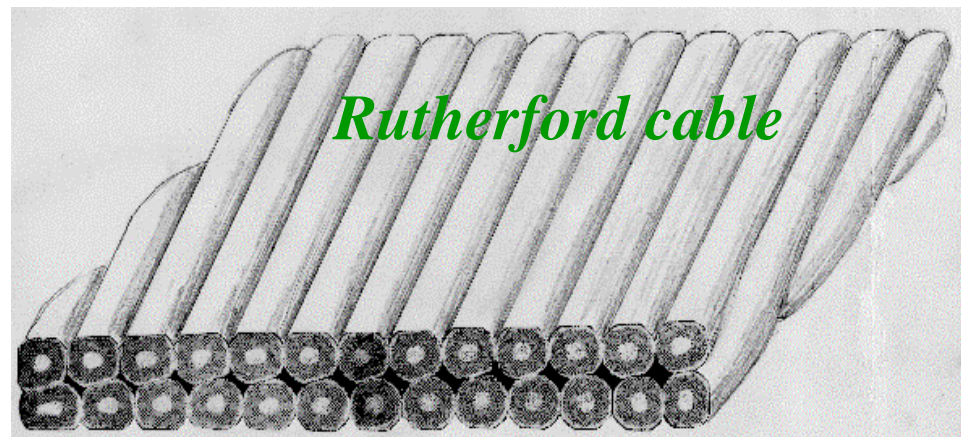
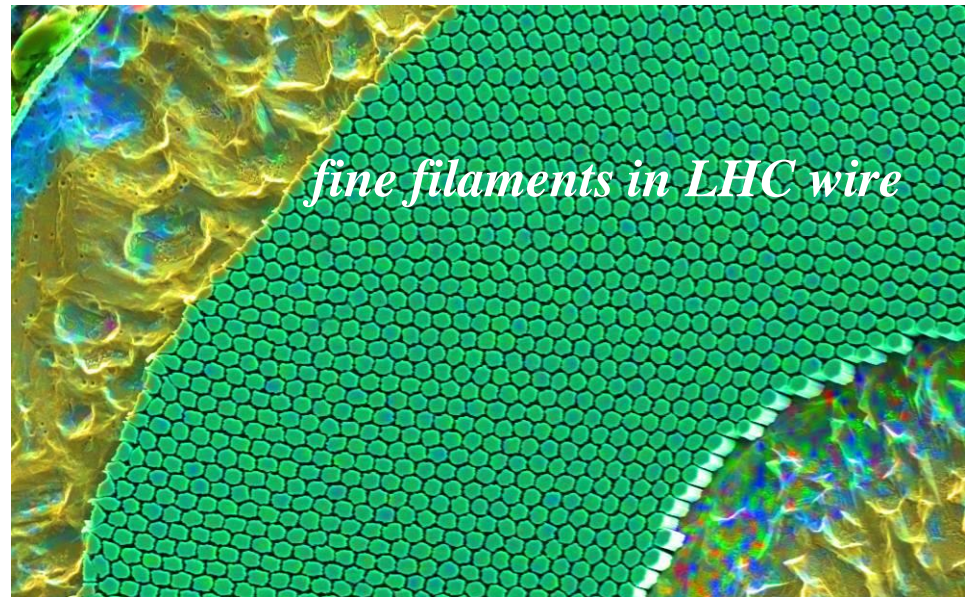
- superconductors in changing fields
- magnetization of wires & filaments
- coupling between filaments
- flux jumping

Cables

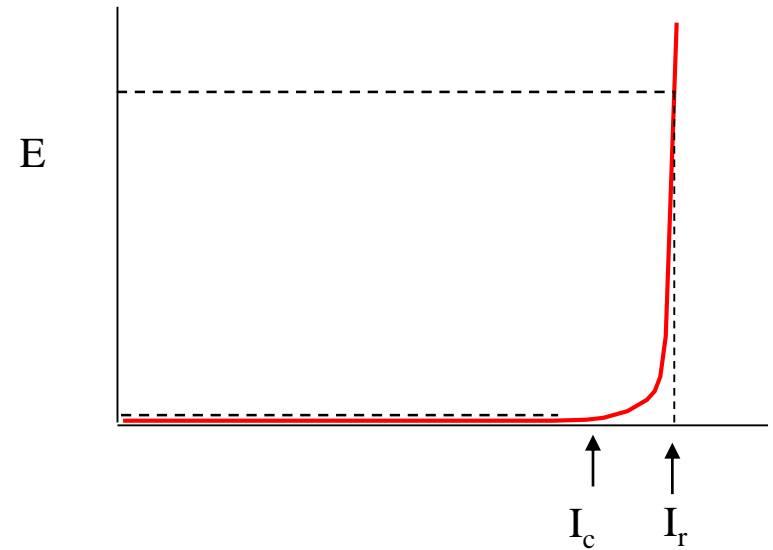
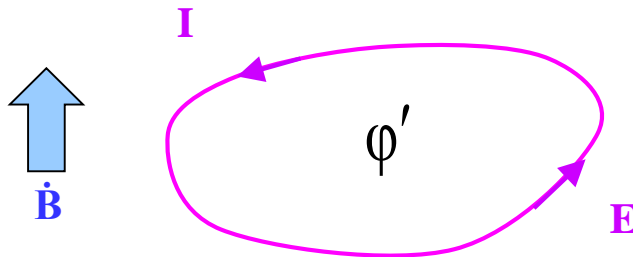
- why cables?
- coupling in cables
- effect on field error in magnets

AC losses

- general expression
- losses within filaments
- losses from coupling



Superconductors in changing magnetic fields



Faraday's Law of EM Induction

$$\oint E dl = \int B' dA = \dot{\phi}'$$

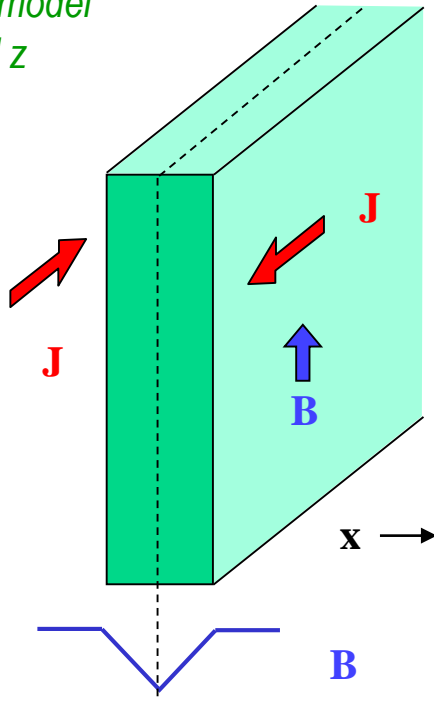
- changing field
 - changing flux linked by loop
 - electric field E in superconductor
 - current I_r flows around the loop
- change stops
 - electric field goes to zero
 - superconductor current falls back to I_c (not zero)
 - current circulates for ever **persistent current**

changing magnetic fields
on superconductors
→ electric field
→ resistance
→ power dissipation

Persistent screening currents

- **screening currents** are in addition to the **transport current**, which comes from the power supply
- like eddy currents but, because no resistance, they don't decay

simplified slab model
infinite in y and z



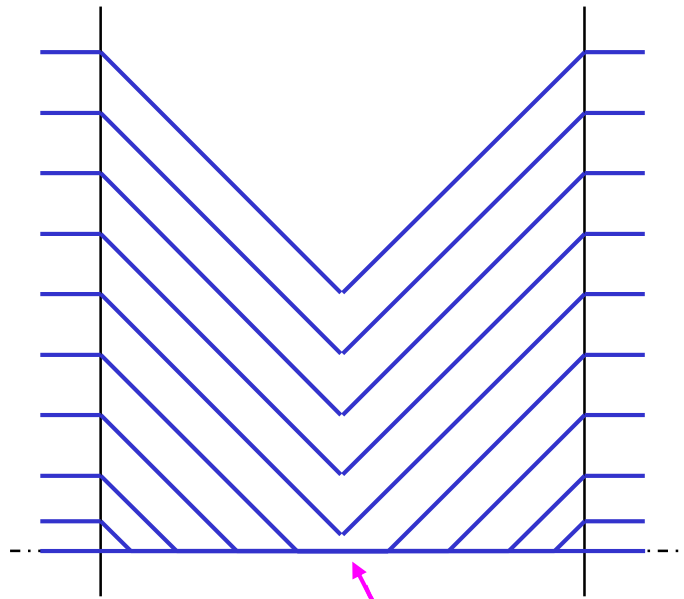
- dB/dt induces an electric field E which drives the screening current up to current density J_r
- dB/dt stops and current falls back to J_c
- so in the steady state we have persistent $J = +J_c$ or $J = -J_c$ or $J = 0$ nothing else
- known as the **critical state model** or **Bean London model**
- in the 1 dim infinite slab geometry, Maxwell's equation says

$$\frac{\partial B_y}{\partial x} = -\mu_0 J_z = \mu_0 J_c$$

- so a uniform J_c means a constant field gradient inside the superconductor

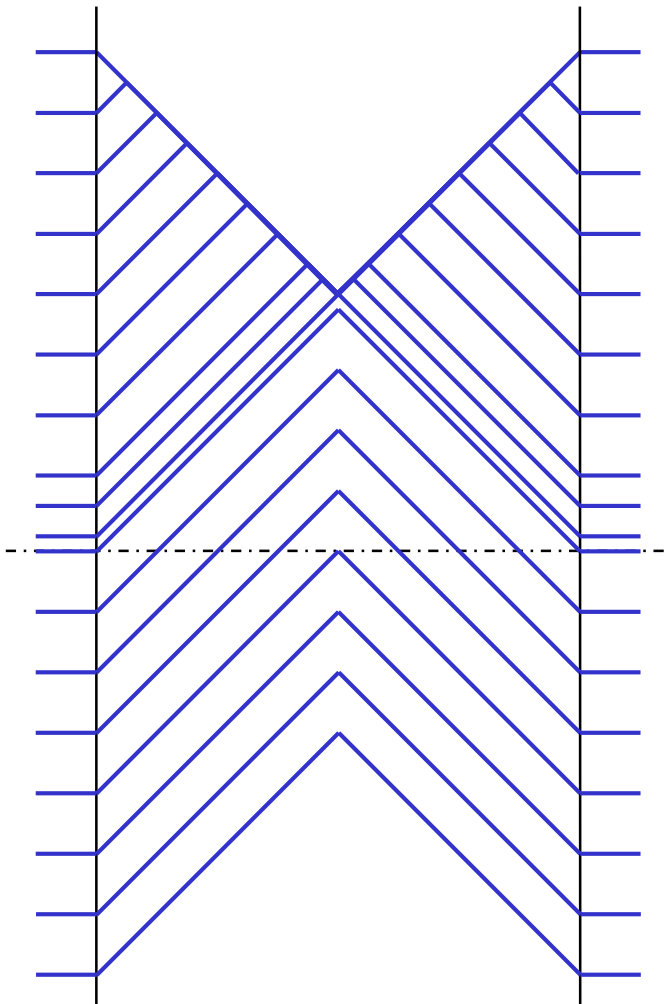
The flux penetration process

plot field profile across the slab



fully penetrated

field increasing from zero



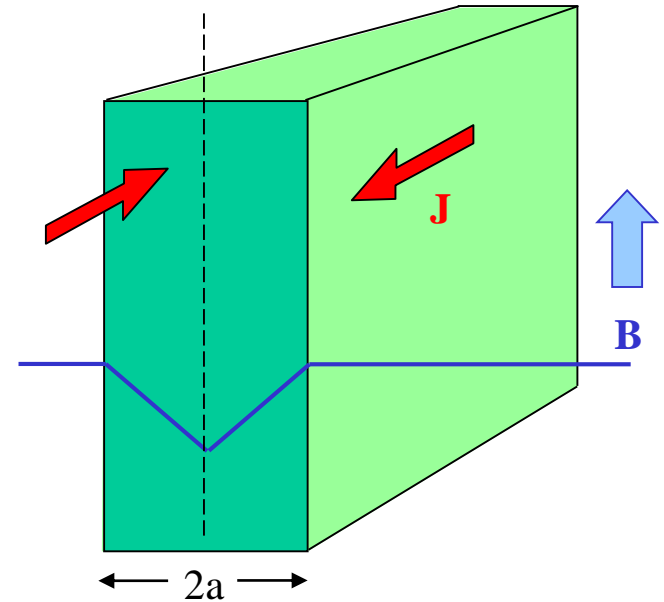
field decreasing through zero

Bean London critical state model

- current density everywhere is $\pm J_c$ or zero
- change comes in from the outer surface

Magnetization

- screening currents are a problem because they
 - are irreversible \Rightarrow losses in changing field
 - affect the field shape
 - can go unstable (flux jump)
- when viewed from outside the sample, the persistent currents produce a magnetic moment.
- by analogy with a magnetic material can define a magnetization = magnetic moment per unit volume



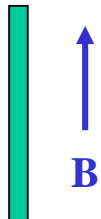
$$M = \sum_V \frac{I \cdot A}{V} \quad \text{NB units of H}$$

for a fully penetrated slab *(symmetry about centre line)*

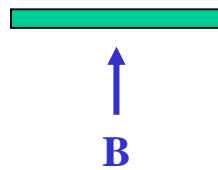
$$M_s = \frac{1}{a} \int_0^a J_c \cdot x \cdot dx = \frac{J_c \cdot a}{2}$$

- slab approximation

good for a single tape parallel to field



not good for single tape perpendicular to field



but OK for stack of tapes perpendicular to field



to reduce M need small 'a'

thin layers

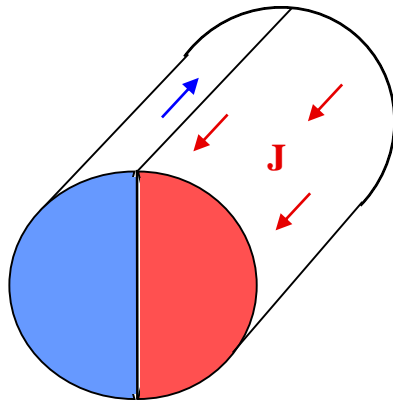
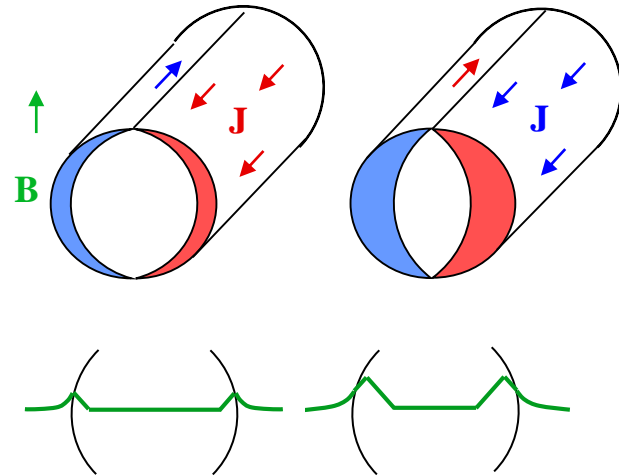
fine filaments

parallel to field

Magnetization of cylindrical filaments



when field has not fully penetrated the inner current boundary is roughly elliptical

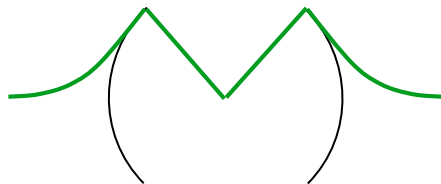


when fully penetrated, the calculation is similar to slab but more complicated - magnetization is

$$M_s = \frac{4}{3\pi} J_c a = \frac{2}{3\pi} J_c d_f$$

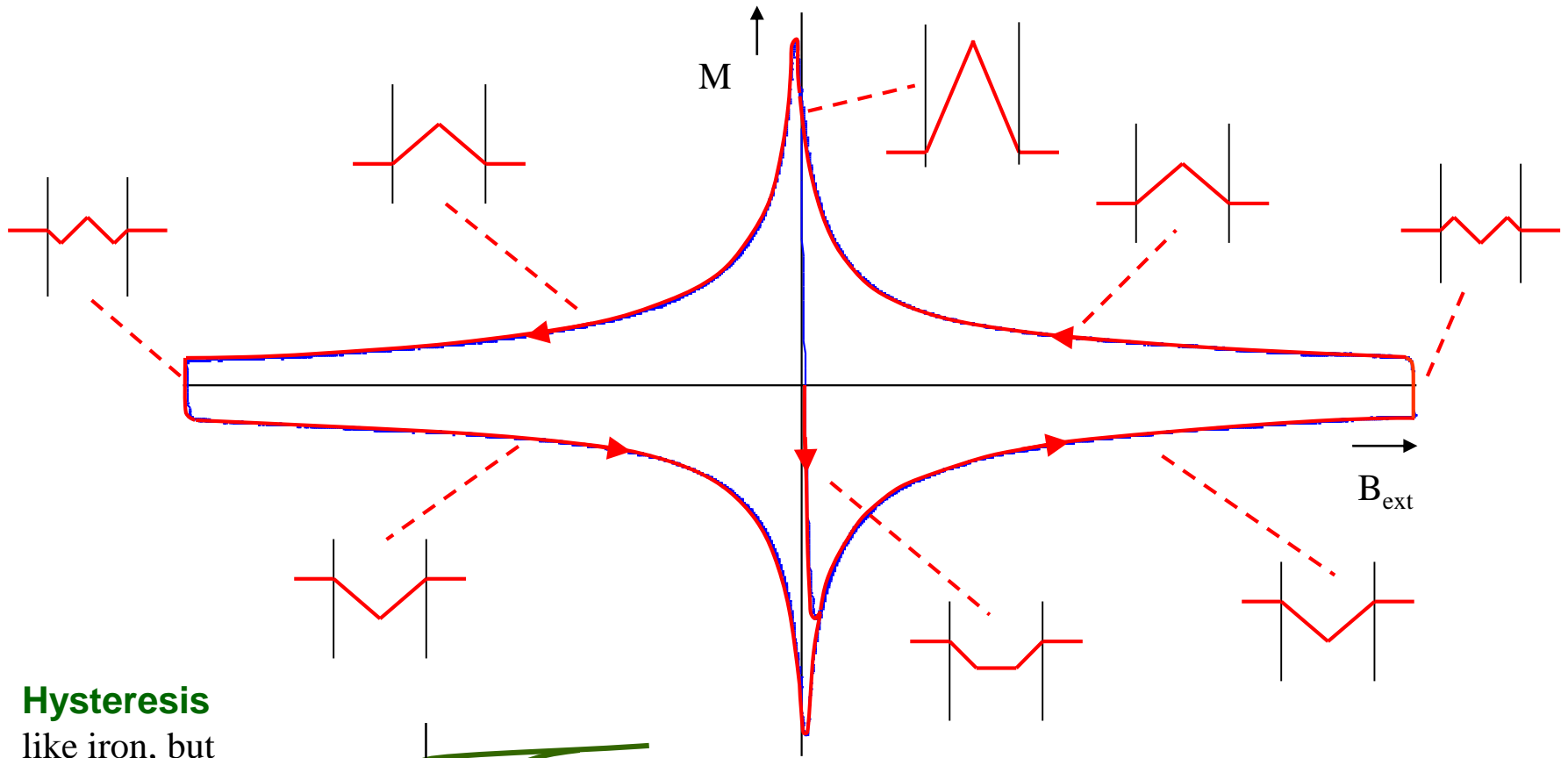
where a , d_f = filament radius, diameter

Note: M is defined per unit volume of filament

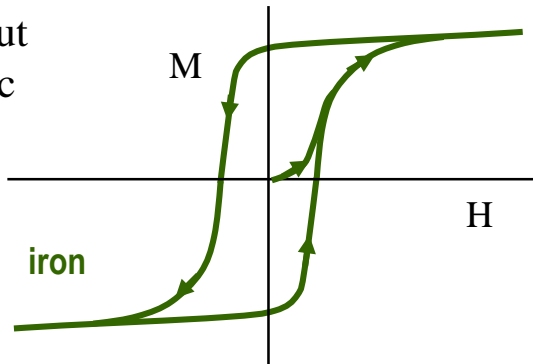


to reduce M need small d_f - fine filaments

Magnetization of NbTi

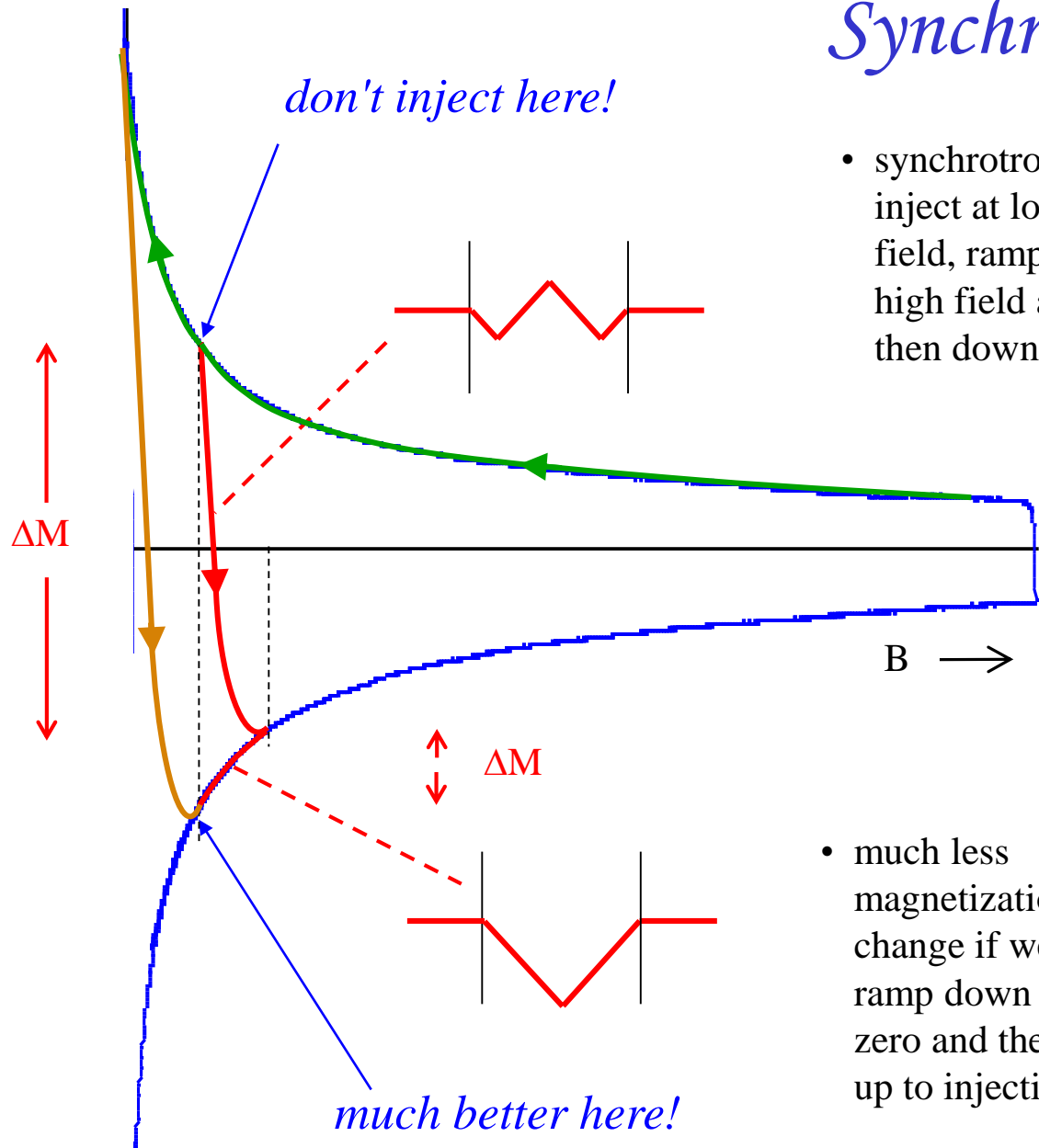


Hysteresis
like iron, but
diamagnetic

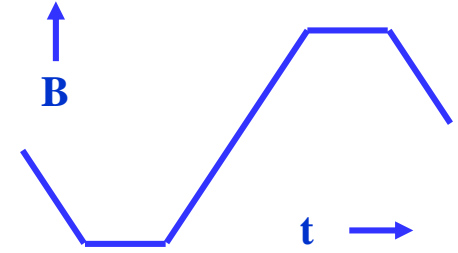


Magnetization is important because
it produces field errors and ac losses

Synchrotron injection

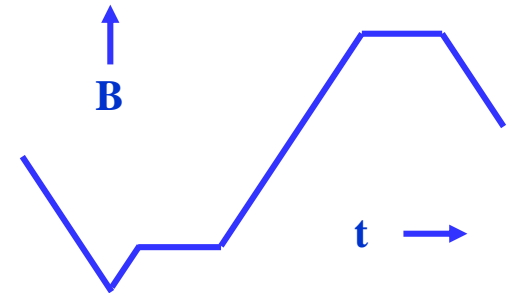


- synchrotrons inject at low field, ramp to high field and then down again



- note how quickly the magnetization changes when we start the ramp up

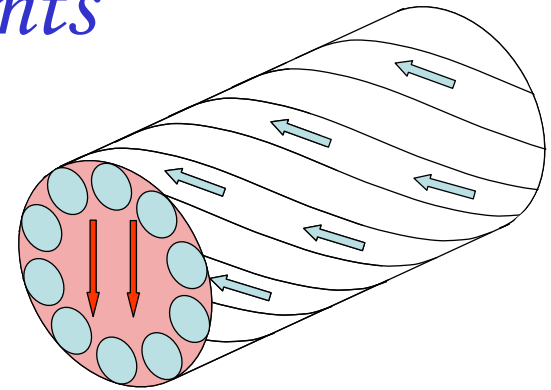
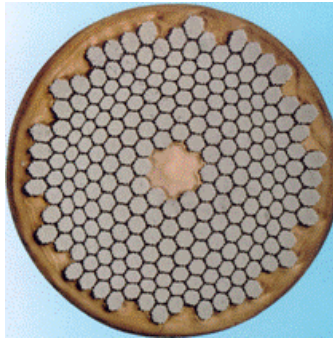
- much less magnetization change if we ramp down to zero and then up to injection



Coupling between filaments

recap $M_s = \frac{2}{3\pi} J_c d_f$

- reduce M by making fine filaments
- for ease of handling, filaments are embedded in a copper matrix



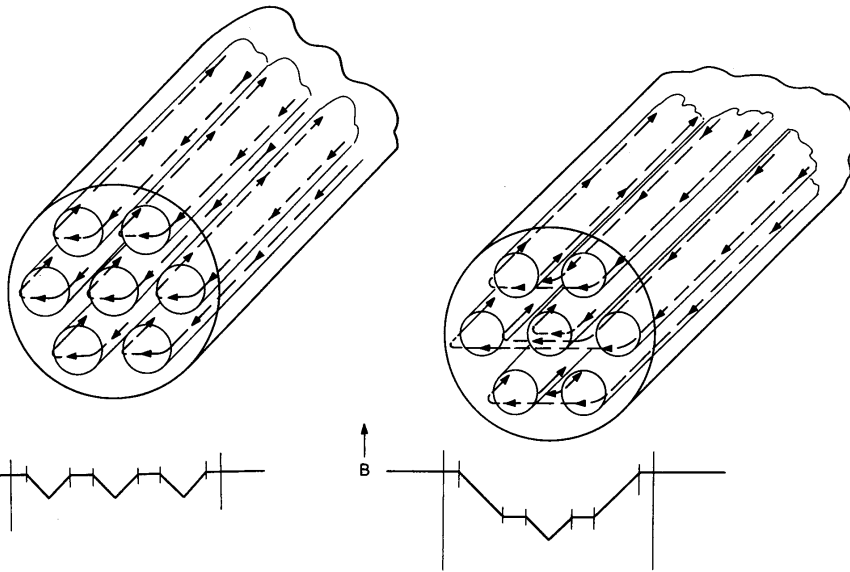
- coupling currents flow along the filaments and across the matrix
- reduce them by twisting the wire
- they behave like eddy currents and produce an additional magnetization

$$M_e = \frac{dB}{dt} \frac{1}{\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$

$$M_e = \frac{2}{\mu_o} \frac{dB}{dt} \tau \quad \text{where} \quad \tau = \frac{\mu_o}{2\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$

per unit volume of wire

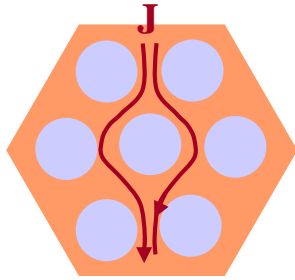
$\rho_t =$ resistivity across matrix, $p_w =$ wire twist pitch



- but in changing fields, the filaments are magnetically coupled
- screening currents go up the left filaments and return down the right

Transverse resistivity across the matrix

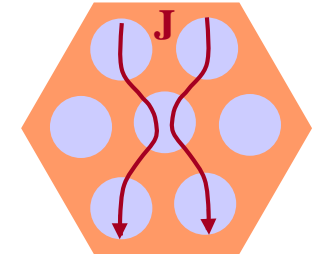
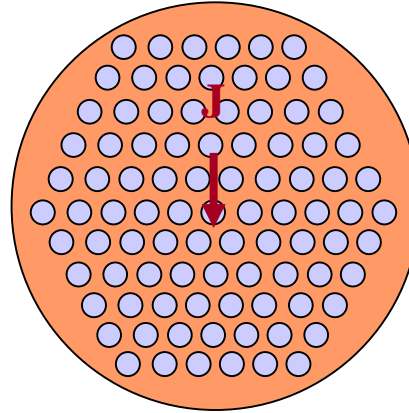
Poor contact to filaments



$$\rho_t = \rho_{Cu} \frac{1 + \lambda_{sw}}{1 - \lambda_{sw}}$$

where λ_{sw} is the fraction of superconductor in the wire cross section (after J Carr)

Good contact to filaments

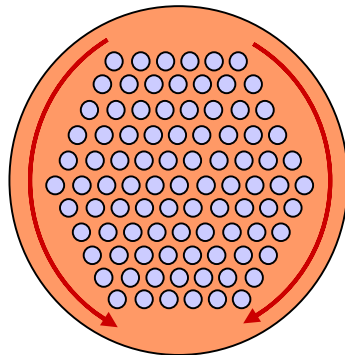


$$\rho_t = \rho_{Cu} \frac{1 - \lambda_{sw}}{1 + \lambda_{sw}}$$

Some complications

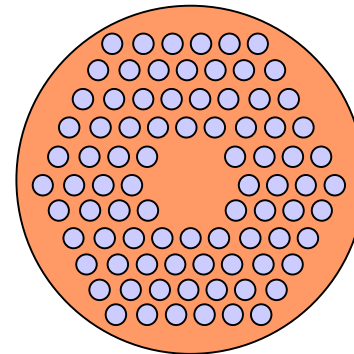
Thick copper jacket

include the copper jacket as a resistance in parallel

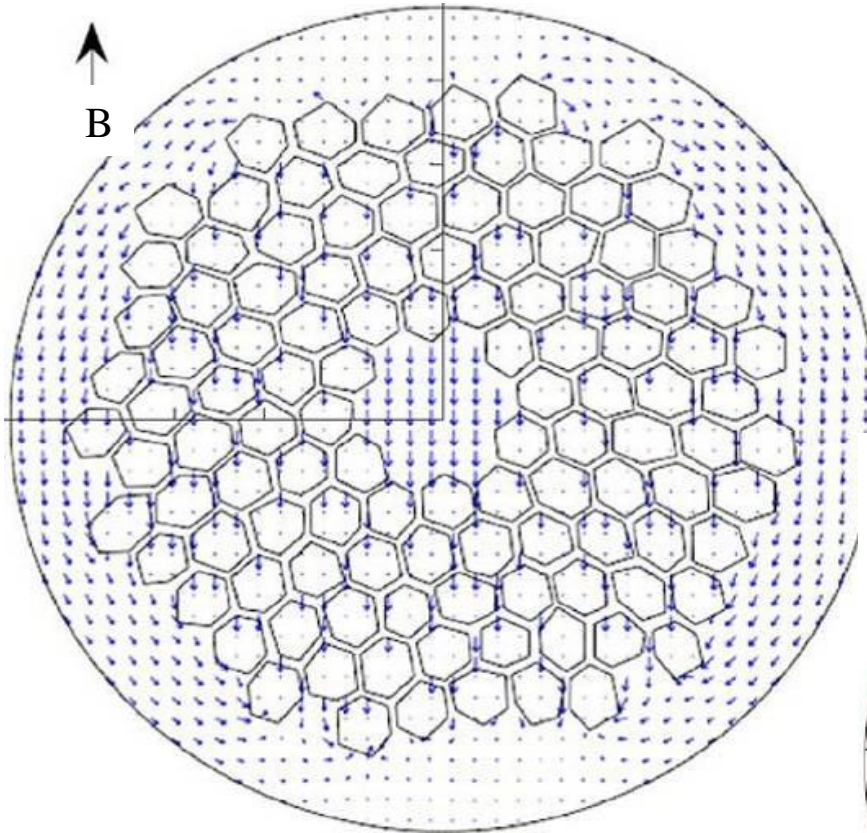


Copper core

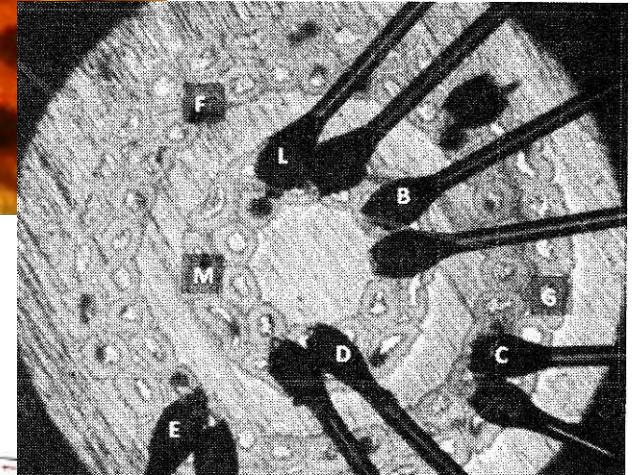
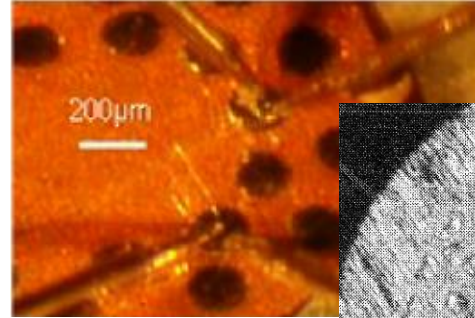
resistance in series for part of current path



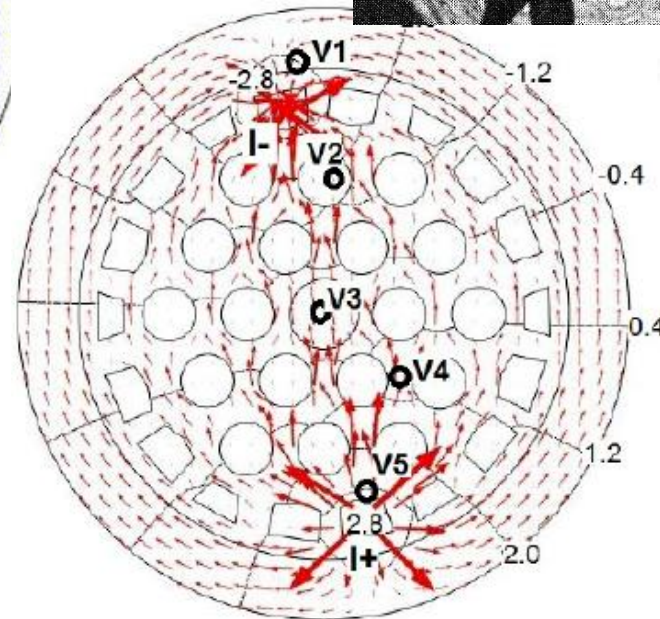
Computing & measuring current flow across matrix



calculated using the COMSOL code
by P.Fabbricatore et al JAP, 106, 083905 (2009)



measuring
by point
contacts



simulation
by COMSOL

C Zhou et al IEEE
Trans App Sup 23
3 p 6000204

Two components of magnetization

1) persistent current within the filaments

$$M_s = \lambda_{su} \frac{2}{3\pi} J_c(B) d_f$$

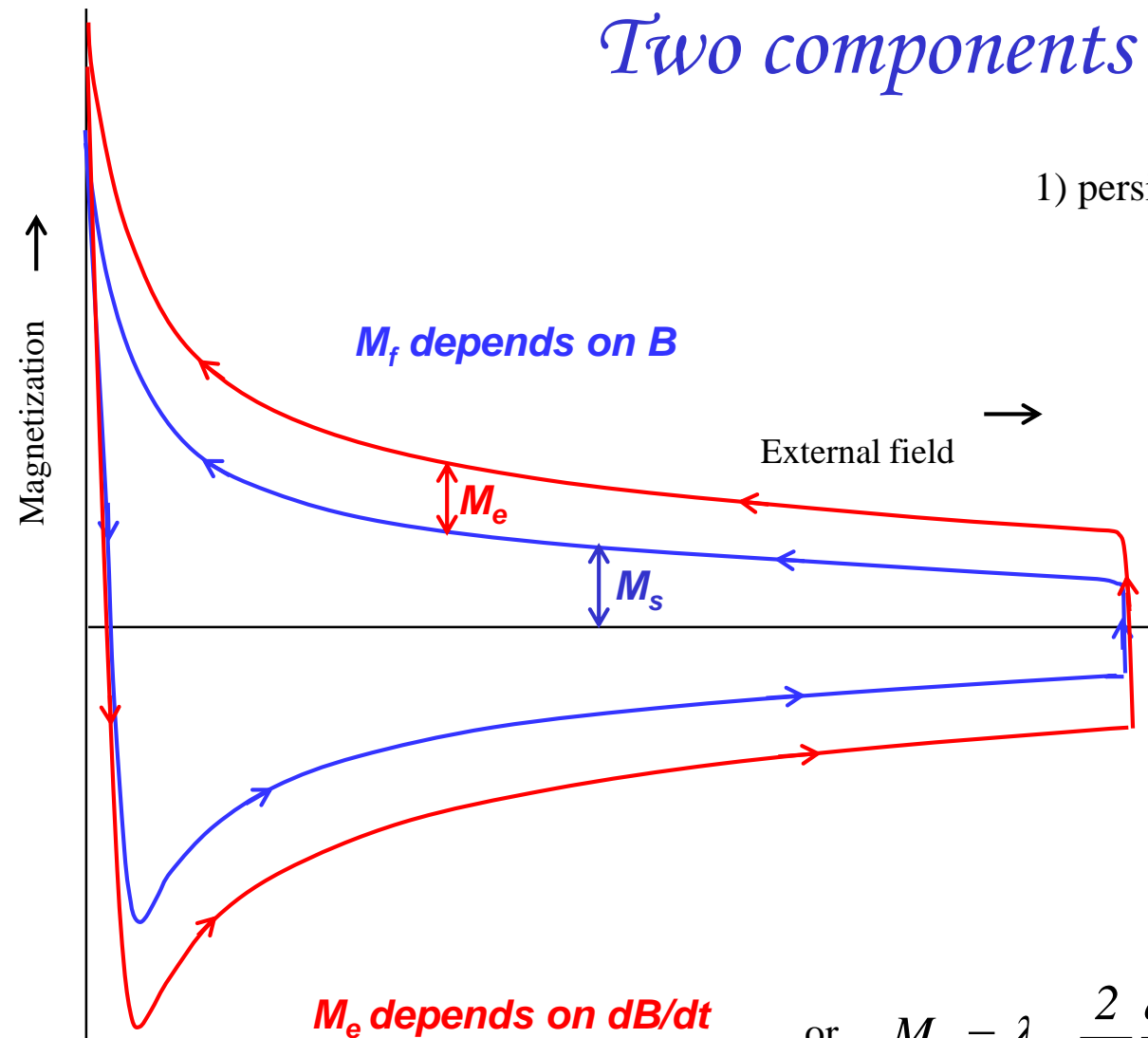
where λ_{su} = fraction of superconductor in the unit cell

2) eddy current coupling between the filaments

$$M_e = \lambda_{wu} \frac{dB}{dt} \frac{1}{\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$

or $M_e = \lambda_{wu} \frac{2}{\mu_o} \frac{dB}{dt} \tau$ where $\tau = \frac{\mu_o}{2\rho_t} \left[\frac{p_w}{2\pi} \right]^2$

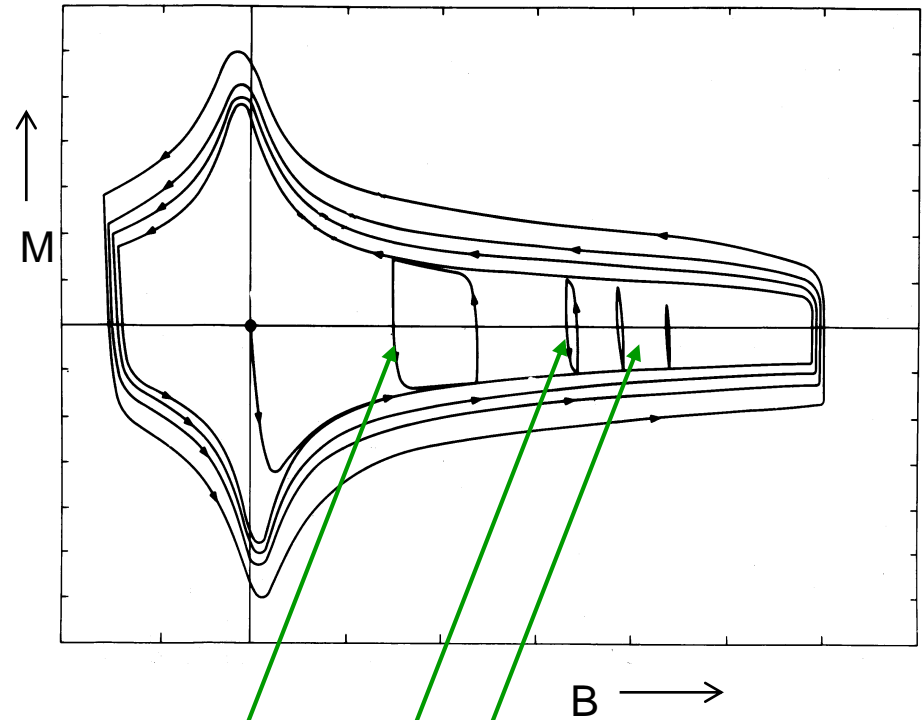
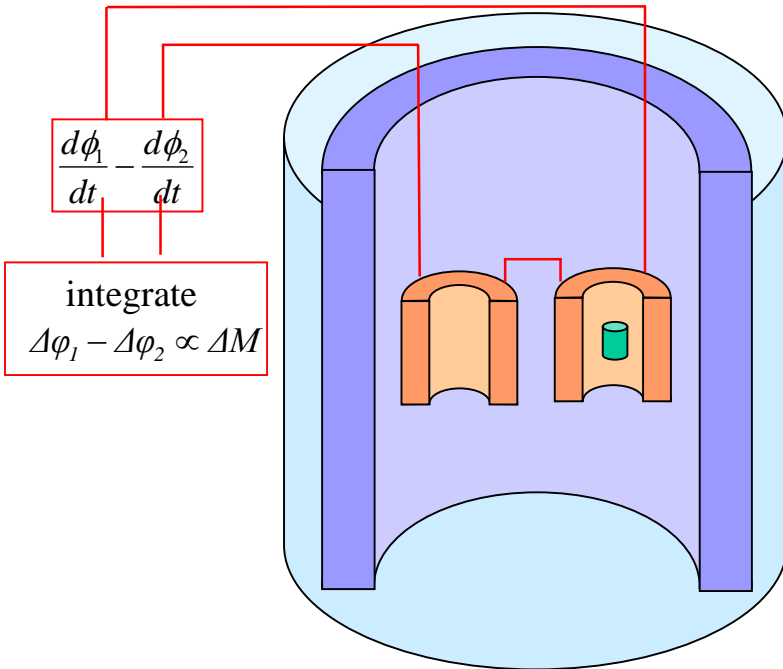
where λ_{wu} = fraction of wire in the section



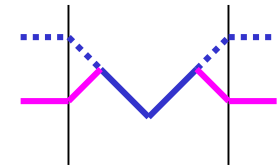
Magnetization is averaged over the unit cell

Measurement of magnetization

- in field, superconductor behaves like a magnetic material.
- plot the magnetization curve using a magnetometer.
- shows hysteresis - like iron but magnetization is both diamagnetic and paramagnetic.



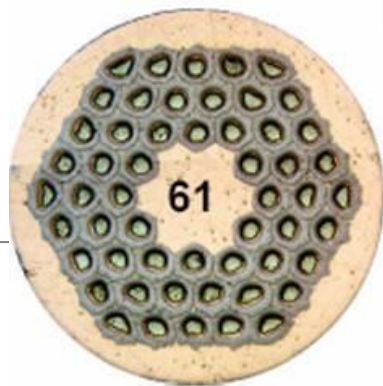
minor loops, where field and therefore screening currents are reversing



Two balanced search coils connected in series opposition, are placed within the bore of a superconducting solenoid. With a superconducting sample in one coil, the integrator measures ΔM when the solenoid field is swept up and down

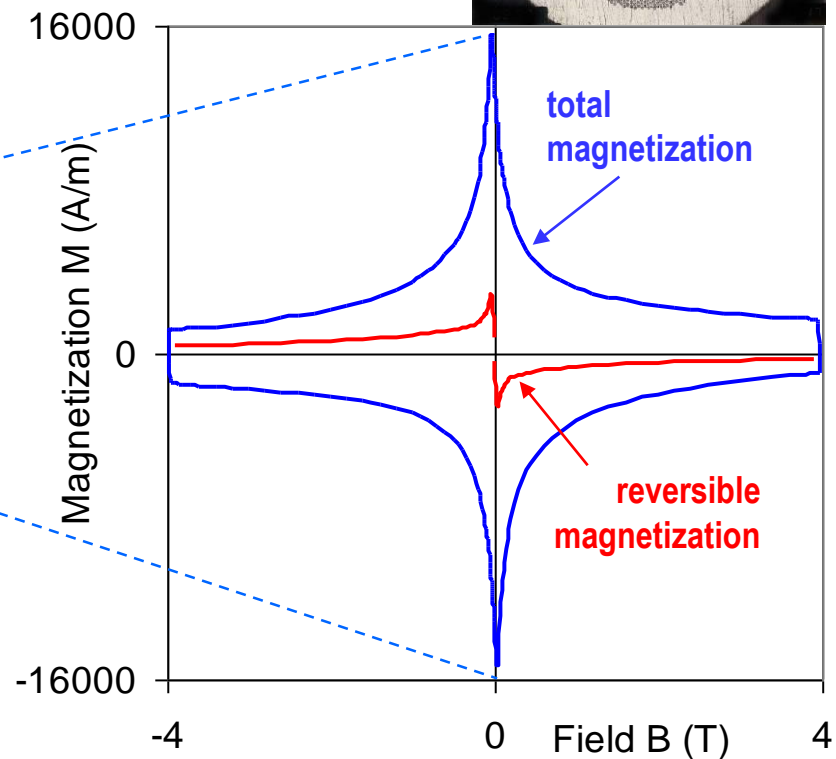
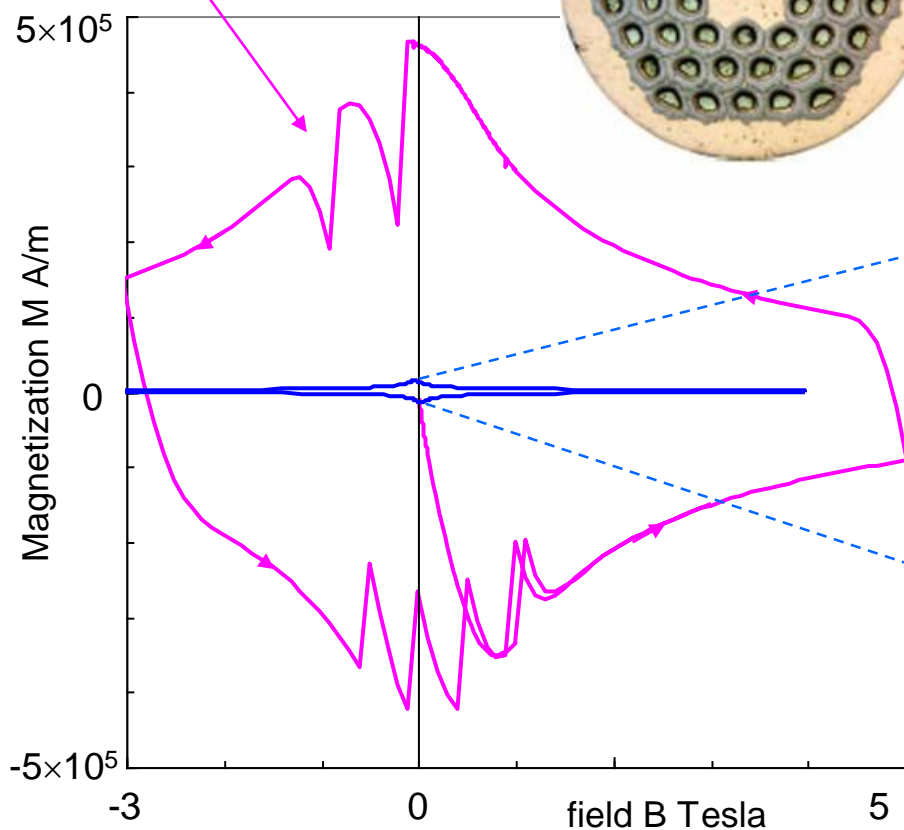
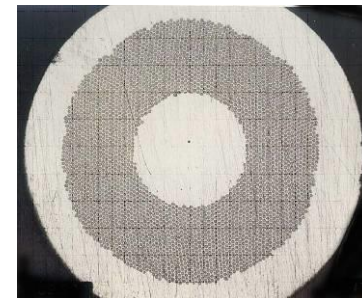
Magnetization measurements

flux jumping at low field caused by large filaments and high J_c



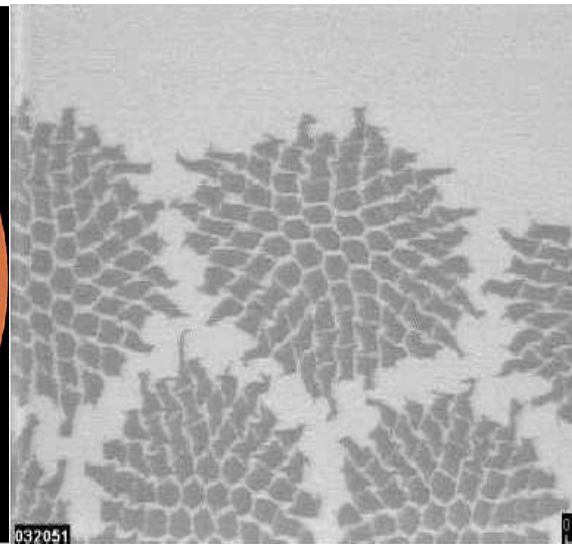
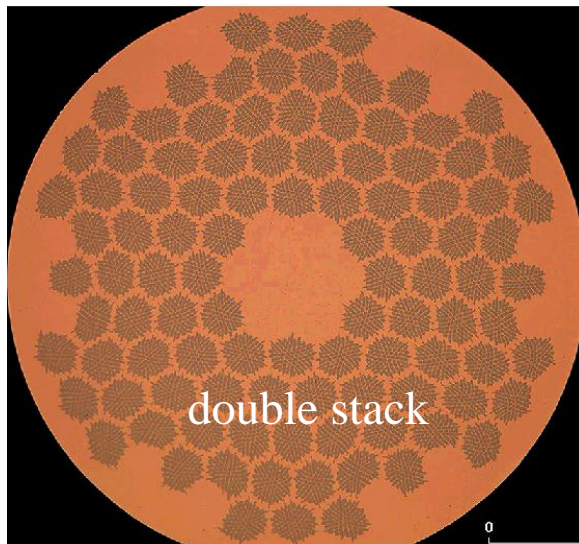
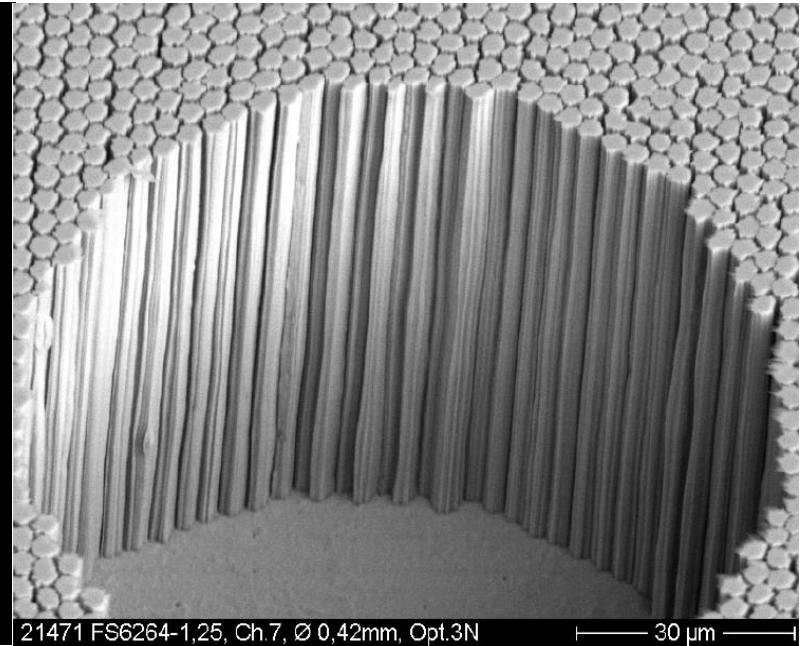
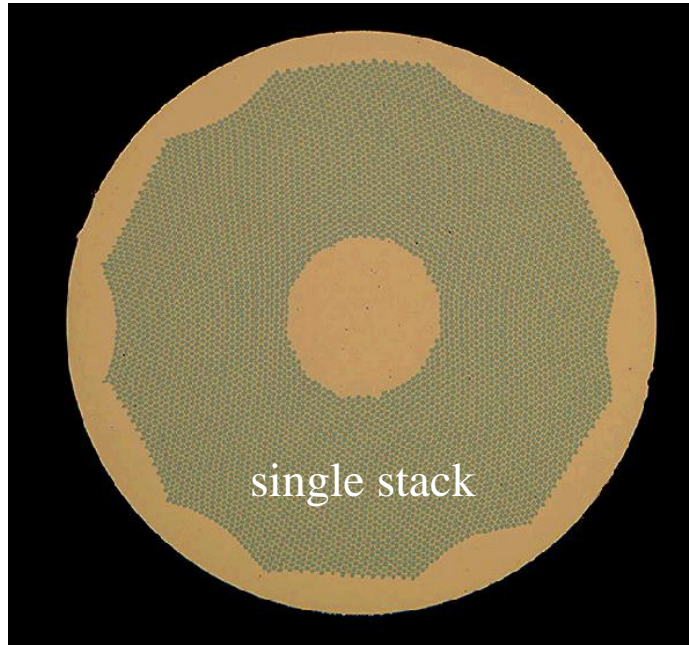
RRP Nb_3Sn wire with $50\mu m$ filaments

NbTi wire for RHIC with $6\mu m$ filaments



Fine filaments for low magnetization

Accelerator magnets need the finest filaments - to minimize field errors and ac losses



- typical diameters $\sim 5 - 10\mu\text{m}$.
- smaller diameters \Rightarrow lower magnetization, but at the cost of lower J_c and more difficult production.

Flux Jumping

a magnetic thermal feedback instability

- screening currents

- temperature rise

- reduced critical current density

- flux motion

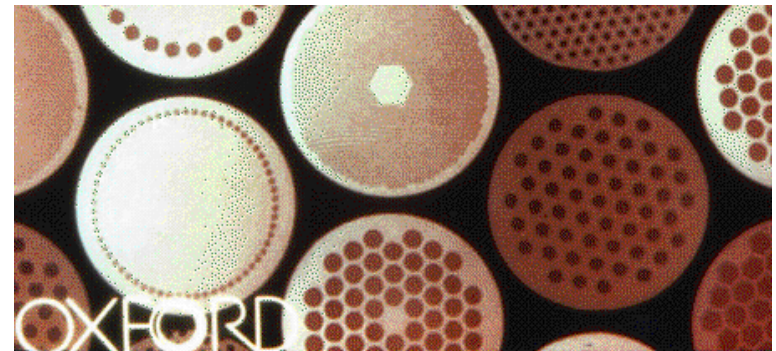
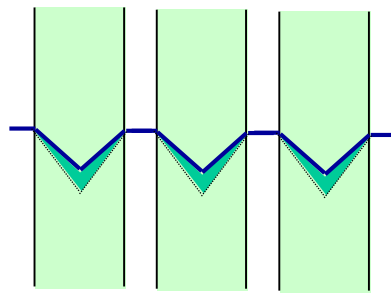
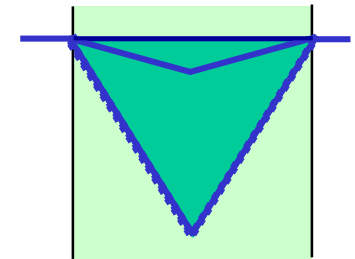
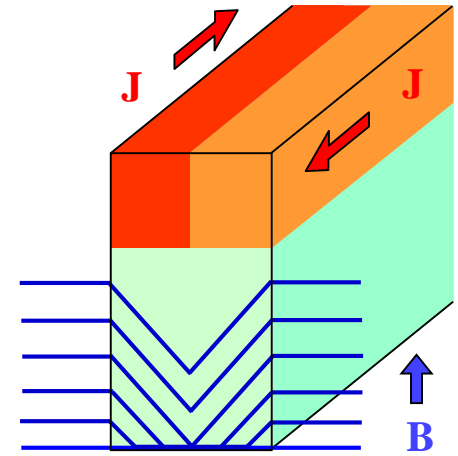
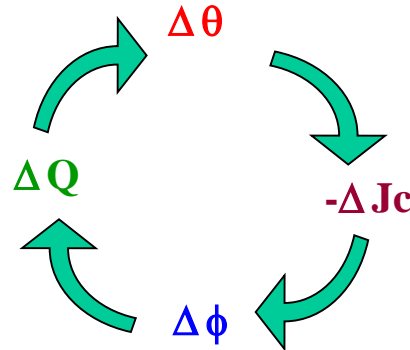
- energy dissipation

- temperature rise

- cure flux jumping by weakening a link in the feedback loop

- fine filaments reduce $\Delta\phi$ for a given $-\Delta J_c$

- for NbTi the stable diameter is $\sim 50\mu\text{m}$



Flux jumping: the numbers

stable against flux jumping when filament diameter d

$$d \leq \frac{2}{J_c} \left\{ \frac{3\gamma C(\theta_c - \theta_o)}{\mu_o} \right\}^{\frac{1}{2}}$$

NbTi at 4.2K and 1T

J_c critical current density = $7.5 \times 10^9 \text{ Am}^{-2}$

γC specific heat/volume = $3400 \text{ J.m}^{-3}\text{K}^{-1}$

θ_c critical temperature = 9.0K

⇒ filament diameter $d < 52\mu\text{m}$

- least stable at low B because of high J_c
- and at low θ because of high J_c and low C

Nb₃Sn at 4.2K and 2T

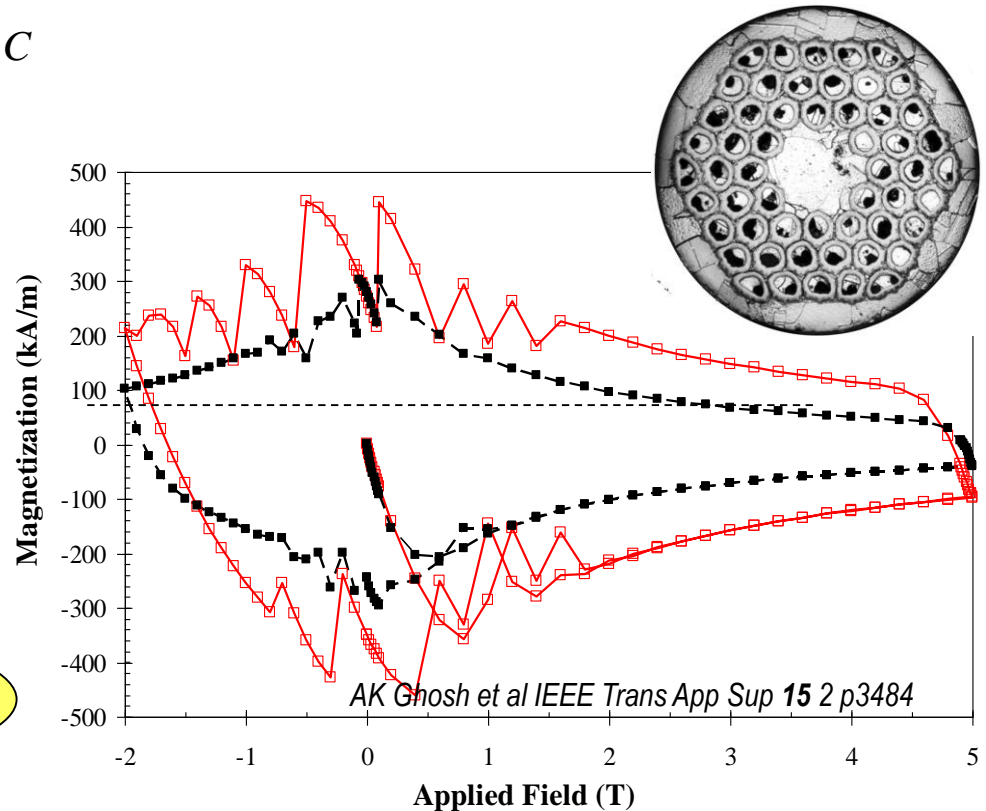
J_c critical current density = $1.7 \times 10^{10} \text{ Am}^{-2}$

γC specific heat/volume = $1600 \text{ J.m}^{-3}\text{K}^{-1}$

θ_c critical temperature = 15.7K

⇒ filament diameter $d < 25\mu\text{m}$

Flux jumping is a solved problem ✓



Cables - why do we need them?

- for accurate tracking we connect synchrotron magnets in series
- for a given field and volume, stored energy of a magnet is fixed, regardless of current or inductance

- for rise time t and operating current I , charging voltage is

$$V = \frac{LI}{t} = \frac{2E}{It}$$

$$E = \frac{1}{2} LI^2 = \frac{B^2}{2\mu_0} vol$$

RHIC $E = 40\text{kJ/m}$, $t = 75\text{s}$, 30 strand cable

cable $I = 5\text{kA}$, charge voltage per km = **213V**

wire $I = 167\text{A}$, charge voltage per km = **6400V**

FAIR at GSI $E = 74\text{kJ/m}$, $t = 4\text{s}$, 30 strand cable

cable $I = 6.8\text{kA}$, charge voltage per km = **5.4kV**

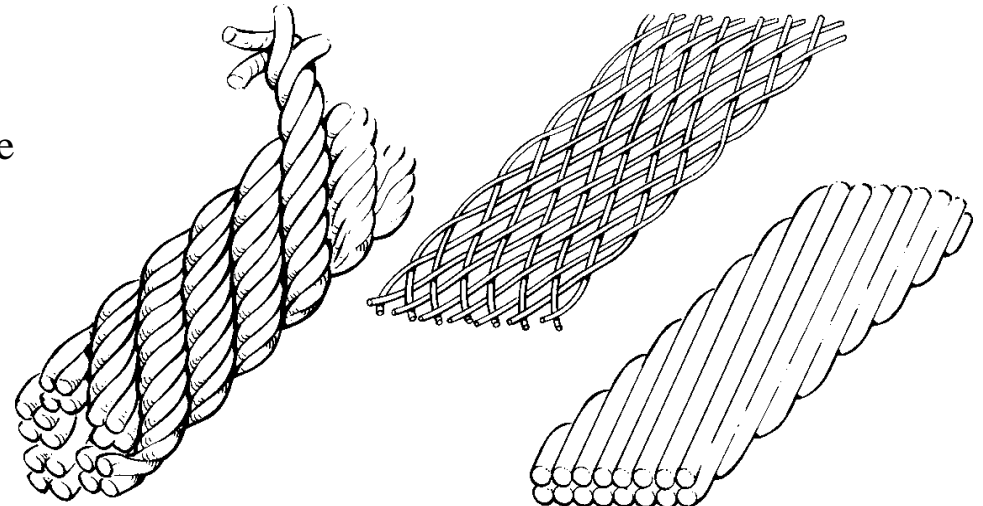
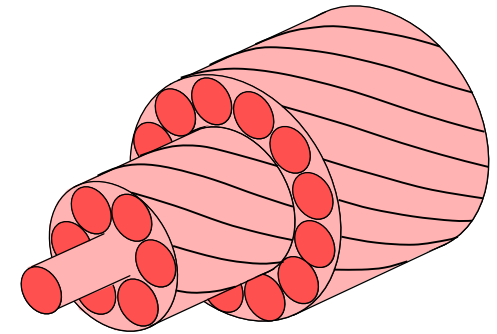
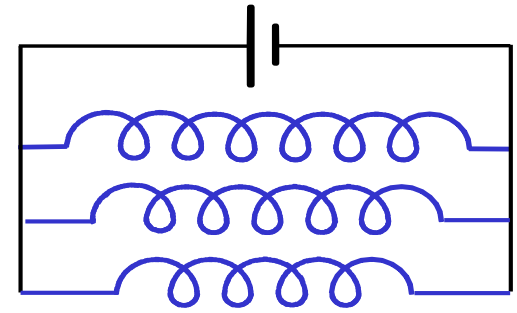
wire $I = 227\text{A}$, charge voltage per km = **163kV**

- so we need high currents!
- a single $5\mu\text{m}$ filament of NbTi in 6T carries 50mA
- a composite wire of fine filaments typically has 5,000 to 10,000 filaments, so it carries 250A to 500A
- for 5 to 10kA, we need 20 to 40 wires in parallel - **a cable**

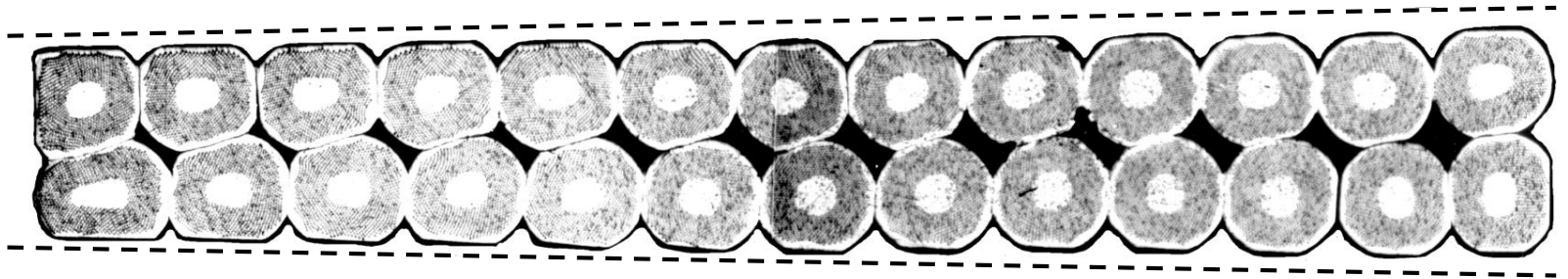
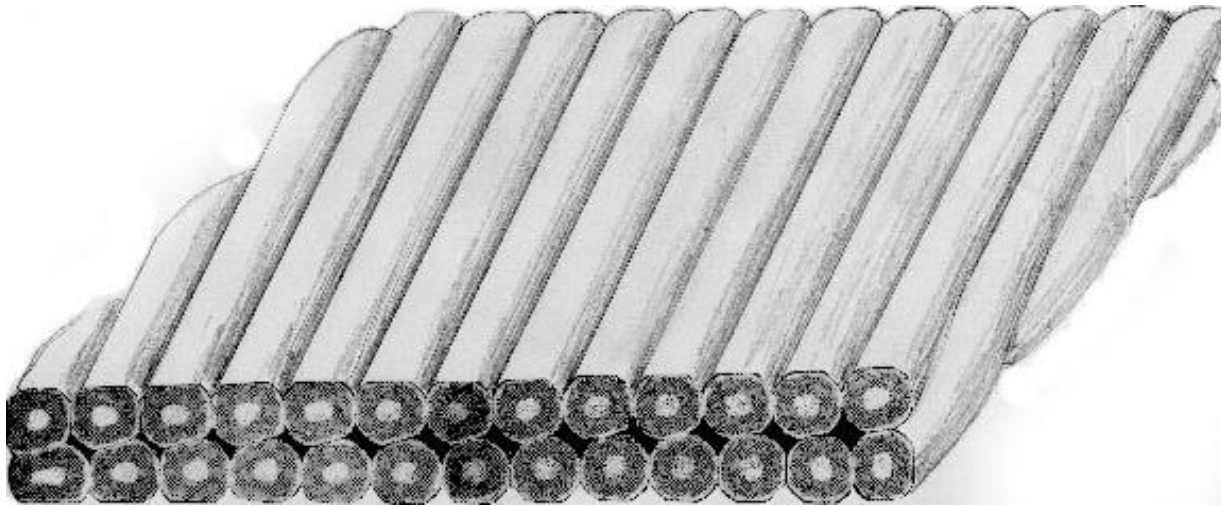


Cable transposition

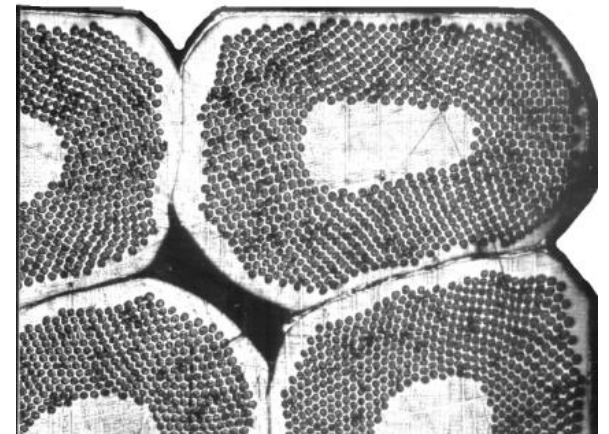
- many wires in parallel - want them all to carry same current
zero resistance - so current divides according to inductance
- in a simple twisted cable, wires in the centre have a higher self inductance than those at the outside
- current fed in from the power supply therefore takes the low inductance path and stays on the outside
- outer wires reach J_c while inner are still empty
- so the wires must be fully **transposed**, ie every wire must change places with every other wire along the length
inner wires \Rightarrow outside outer wire \Rightarrow inside
- three types of fully transposed cable have been tried in accelerators
 - rope
 - braid
 - Rutherford



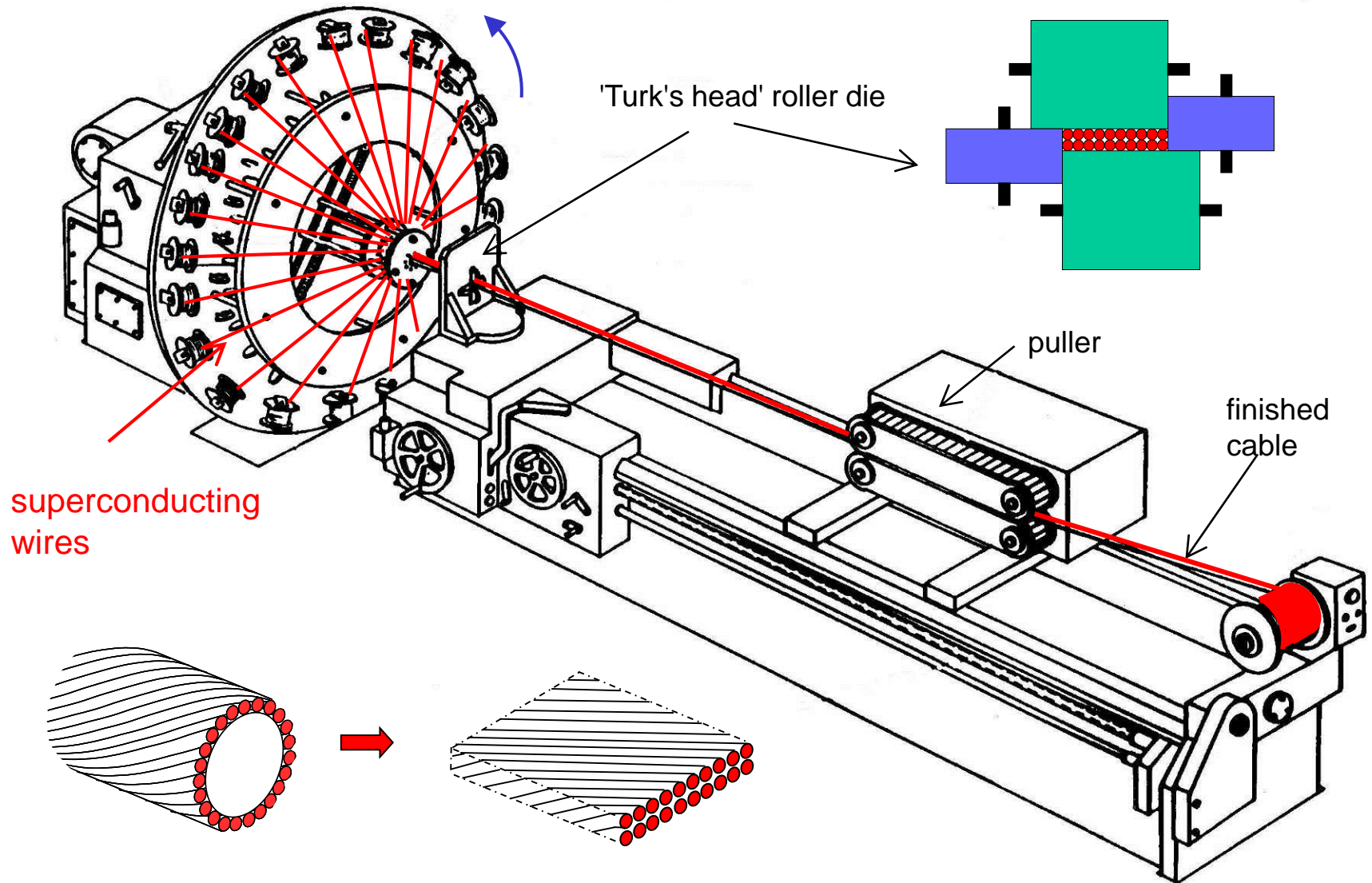
Rutherford cable



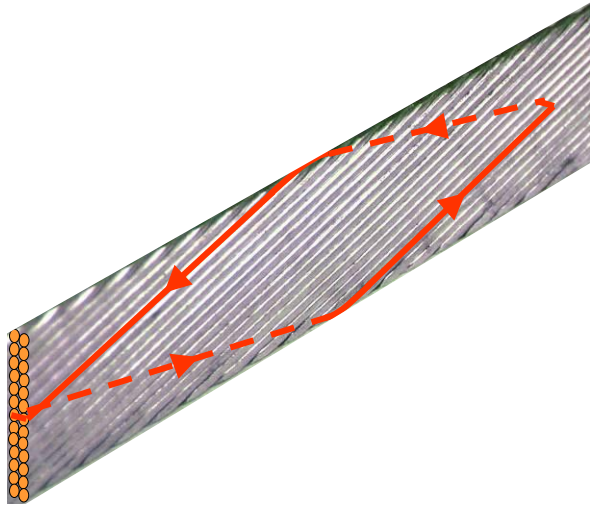
- Rutherford cable succeeded where others failed because it could be compacted to a high density (88 - 94%) without damaging the wires, and rolled to a good dimensional accuracy ($\sim 10\mu\text{m}$).
- Note the 'keystone angle', which enables the cables to be stacked closely round a circular aperture



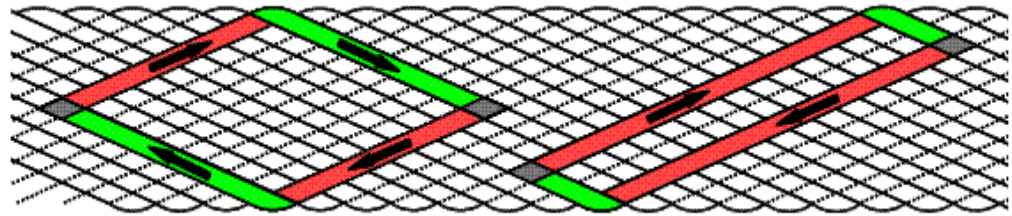
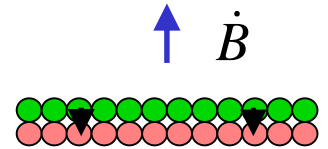
Manufacture of Rutherford cable



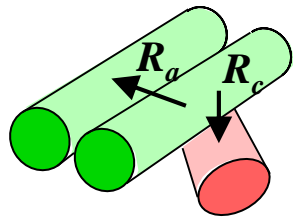
Coupling in Rutherford cables



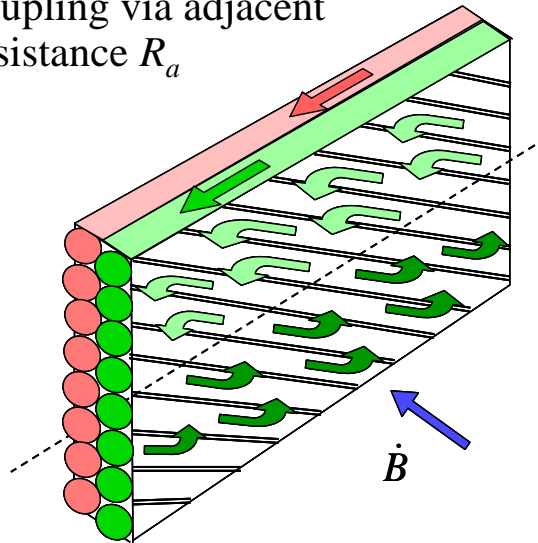
- Field transverse coupling via crossover resistance R_c



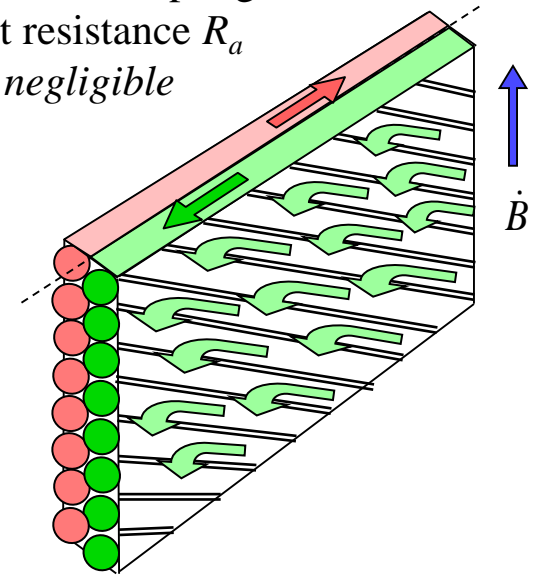
- Field transverse coupling via adjacent resistance R_a



crossover resistance R_c
adjacent resistance R_a



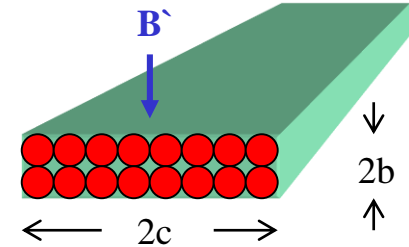
- Field parallel coupling via adjacent resistance R_a usually negligible



Magnetization from coupling in cables

- Field transverse
coupling via
crossover
resistance R_c

$$M_{tc} = \frac{1}{120} \frac{B'_t c}{R_c b} p N(N-1) = \frac{1}{60} \frac{B'_t}{\rho_c} p^2 \frac{c^2}{b^2}$$



where M = magnetization *per unit volume of cable*, p = twist pitch, N = number of strands
 R_c R_a = resistance per crossover ρ_c ρ_a = effective resistivity between wire centres

- Field transverse

coupling via adjacent resistance R_a

where θ = slope angle of wires $\text{Cos} \theta \sim 1$

$$M_{ta} = \frac{1}{6} \frac{B'_t}{R_a} p \frac{c}{b} = \frac{1}{48} \frac{B'_t}{\rho_a} \frac{p^2}{\text{Cos}^2 \theta}$$

- Field parallel

coupling via adjacent resistance R_a

$$M_{pa} = \frac{1}{8} \frac{B'_p}{R_a} p \frac{b}{c} = \frac{1}{64} \frac{B'_p}{\rho_a} \frac{p^2}{\text{cos}^2 \theta} \frac{b^2}{c^2}$$

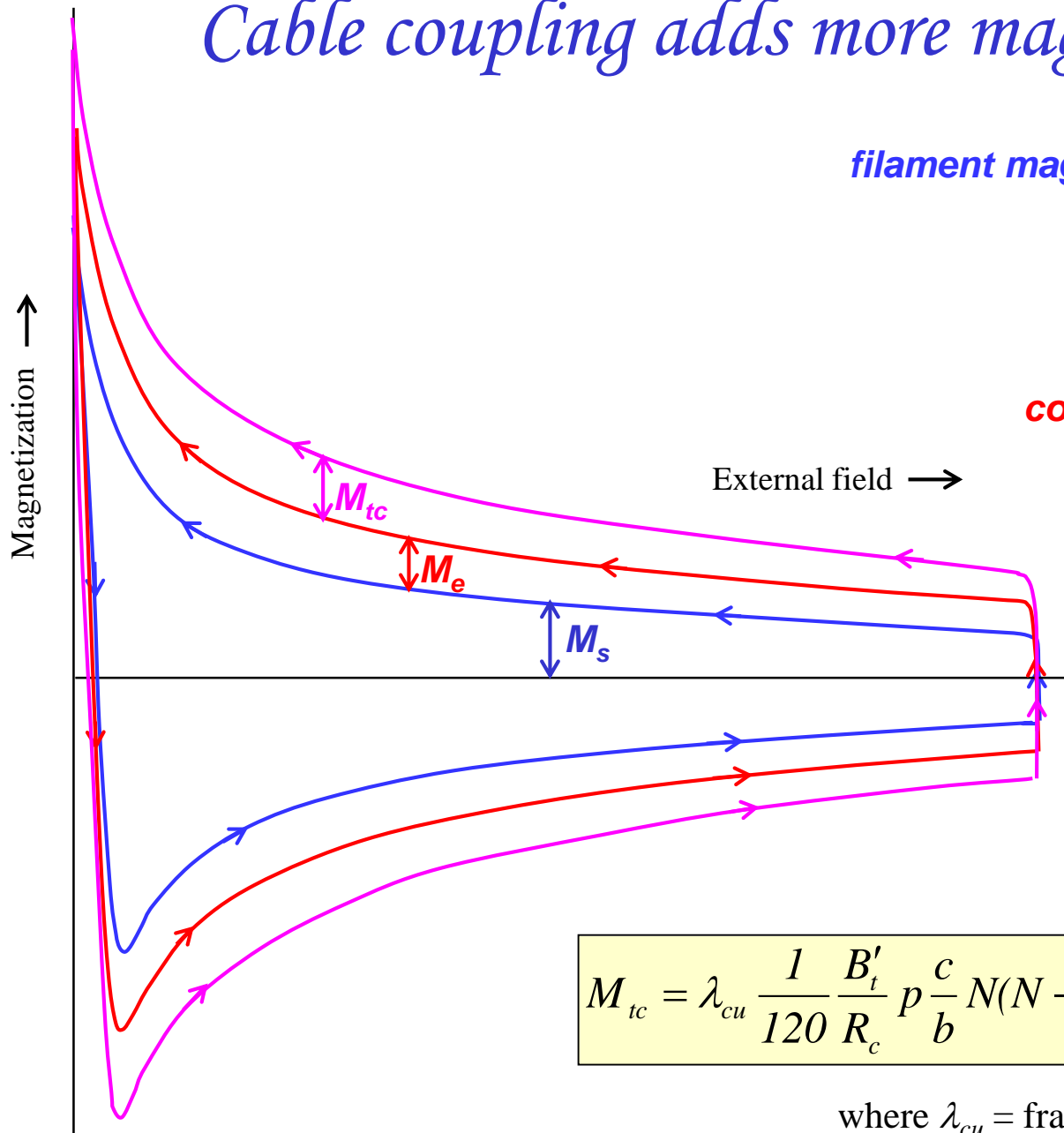
(usually negligible)

- Field transverse
ratio crossover/adjacent

$$\frac{M_{tc}}{M_{ta}} = \frac{R_a}{R_c} \frac{N(N-1)}{20} \approx 45 \frac{R_a}{R_c}$$

So without increasing loss too much can make R_a 50 times less than R_c - anisotropy

Cable coupling adds more magnetization



filament magnetization M_f depends on B

$$M_s = \lambda_{su} \frac{2}{3\pi} J_c(B) d_f$$

coupling between filaments M_e depends on dB/dt

$$M_e = \lambda_{wu} \frac{dB}{dt} \frac{1}{\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$

coupling between wires in cable depends on dB/dt

$$M_{tc} = \lambda_{cu} \frac{1}{120} \frac{B'_t}{R_c} p \frac{c}{b} N(N-1)$$

$$M_{ta} = \lambda_{cu} \frac{1}{6} \frac{B'_t}{R_a} p \frac{c}{b}$$

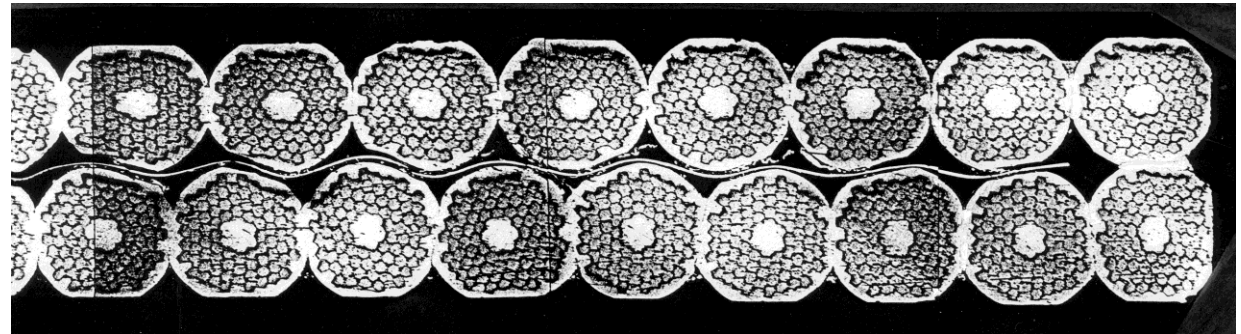
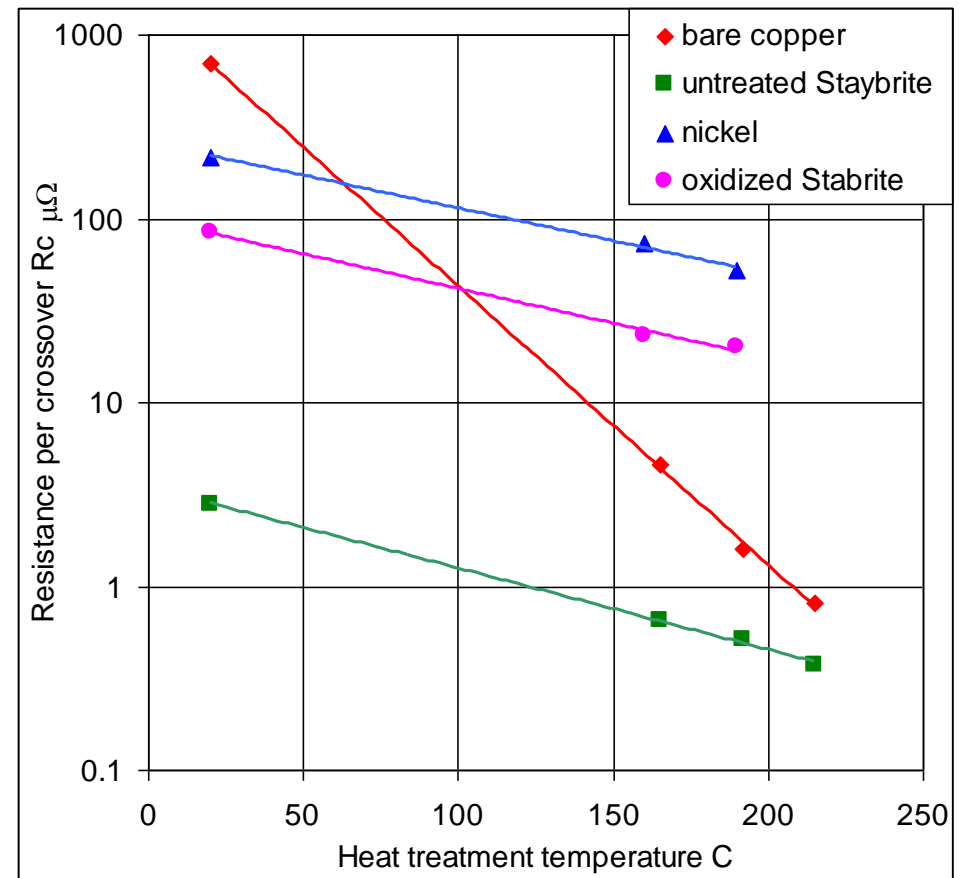
where λ_{cu} = fraction of cable in the section

Controlling R_a and R_c

- can adjust contact resistance by surface coatings on the wires
- contact resistance is sensitive to pressure and heat treatments used in coil manufacture (to cure the adhesive between turns)
- *data from David Richter CERN*

Cored Cables

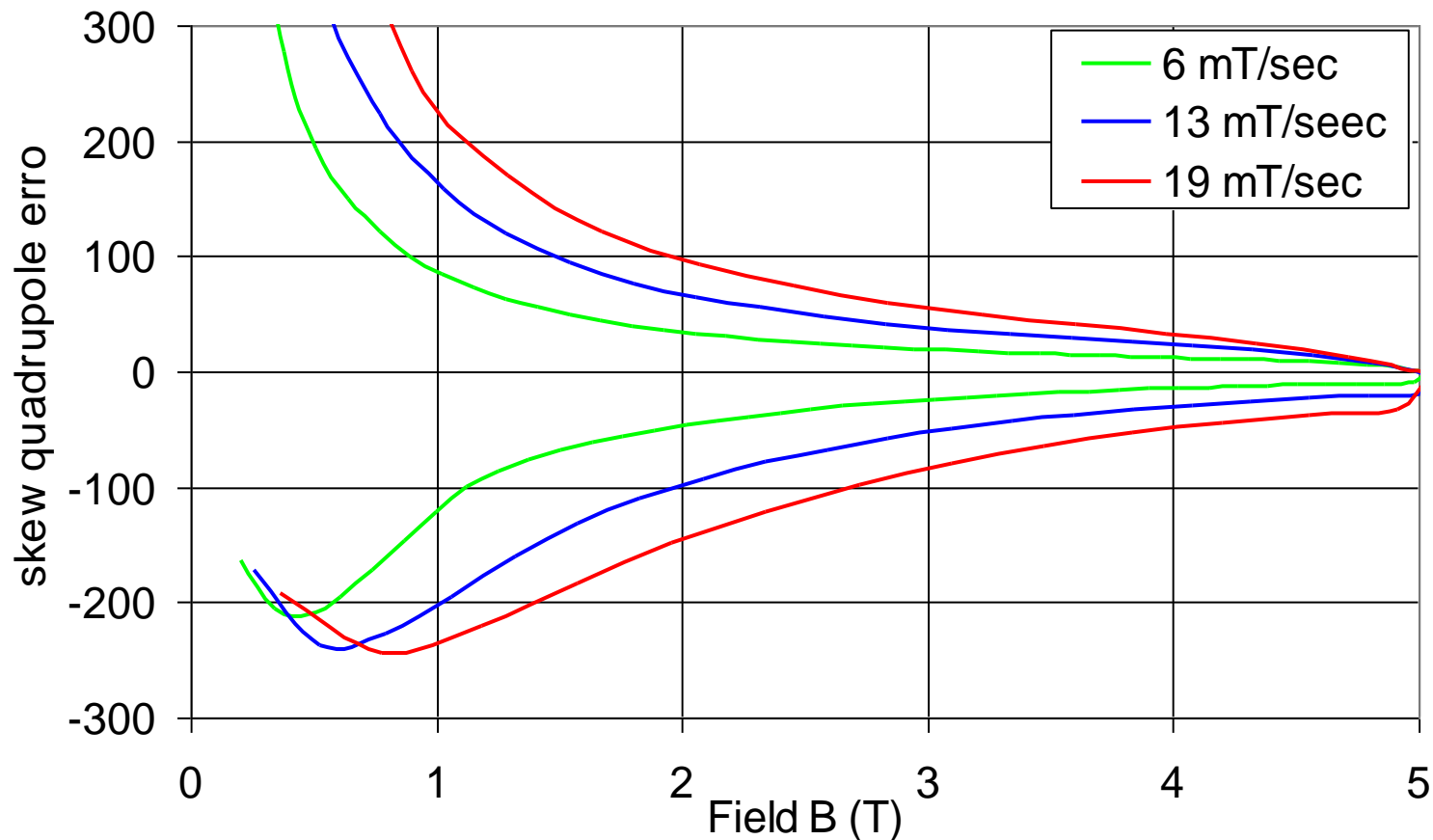
- resistive core foil increases R_c but leaves R_a the same
- reduces magnetization but keeps good current transfer between wires
- not affected by heat treatment



Magnetization and field errors – an extreme case

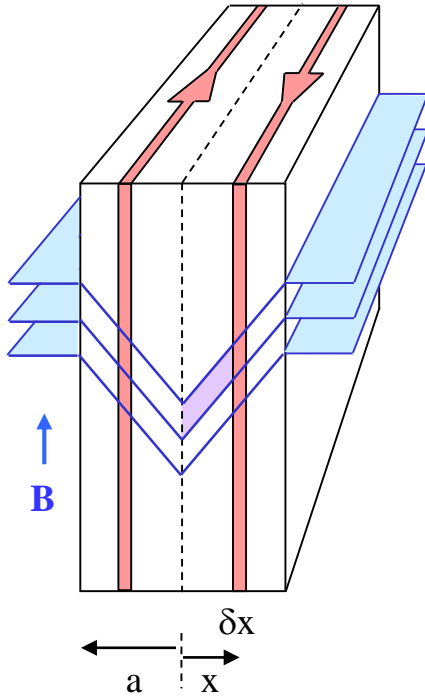
Magnetization is important in accelerators because it produces field error. The effect is worst at injection because

- $\Delta B/B$ is greatest
- magnetization, ie ΔB is greatest at low field



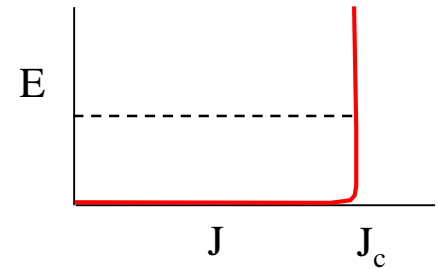
*skew
quadrupole
error in
Nb₃Sn dipole
which has
exceptionally
large
coupling
magnetization
(University of
Twente)*

AC loss power



Faraday's law of induction

$$\oint E dl = \frac{d}{dt} \int_A B dA$$



loss power / unit length in slice of width dx

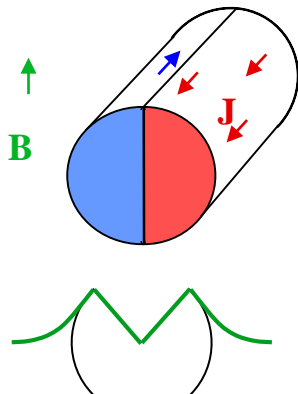
$$p(x) = E J_c \delta x = \frac{d\phi}{dt} J_c \delta x = \frac{dB}{dt} x J_c \delta x$$

total loss in slab per unit volume

$$P = \frac{1}{a} \int_0^a p(x) dx = \frac{1}{a} \frac{dB}{dt} J_c \int_0^a x dx = B' J_c \frac{a}{2} = B' M$$

for round wires (not proved here)

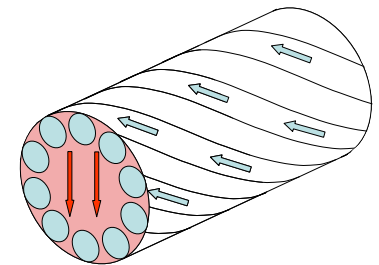
$P = B' M$



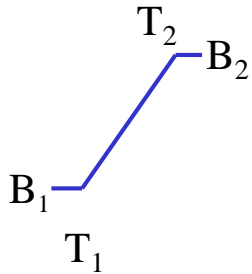
$$P = B' M = \frac{4}{3\pi} B' J_c a = \frac{2}{3\pi} B' J_c d_f$$

also for coupling magnetization

$$P_e = B' M_e = B'^2 \frac{1}{\rho_t} \left[\frac{p_w}{2\pi} \right]^2 = \frac{B'^2}{\mu_o} 2\tau$$



Hysteresis loss



loss over a field ramp

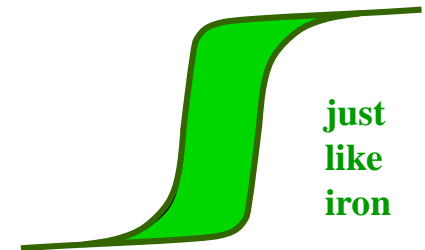
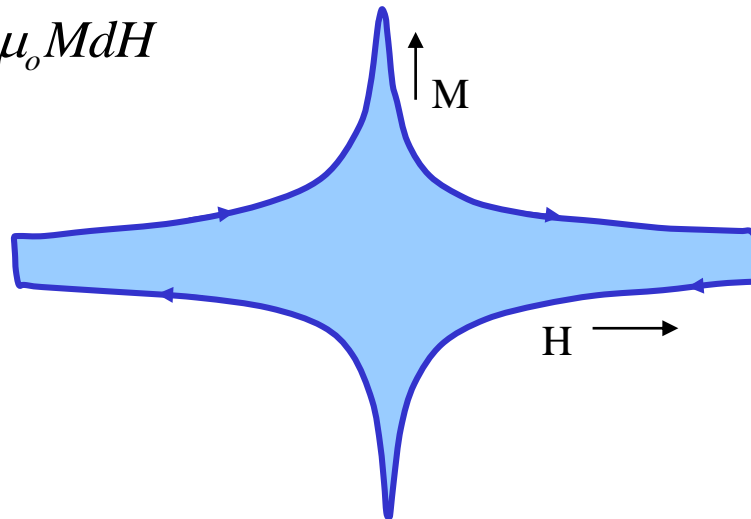
$$Q = \int_{T_1}^{T_2} M \frac{dB}{dt} dt = \int_{B_1}^{B_2} M dB$$

loss per ramp
independent of \dot{B}

- in general, when the field changes by δB the magnetic field energy changes by $\delta E = H\delta B$ (see textbooks on electromagnetism)
- so work done by the field on the material $W = \int \mu_o H dM$
- around a **closed loop**, this integral must be the energy dissipated in the material

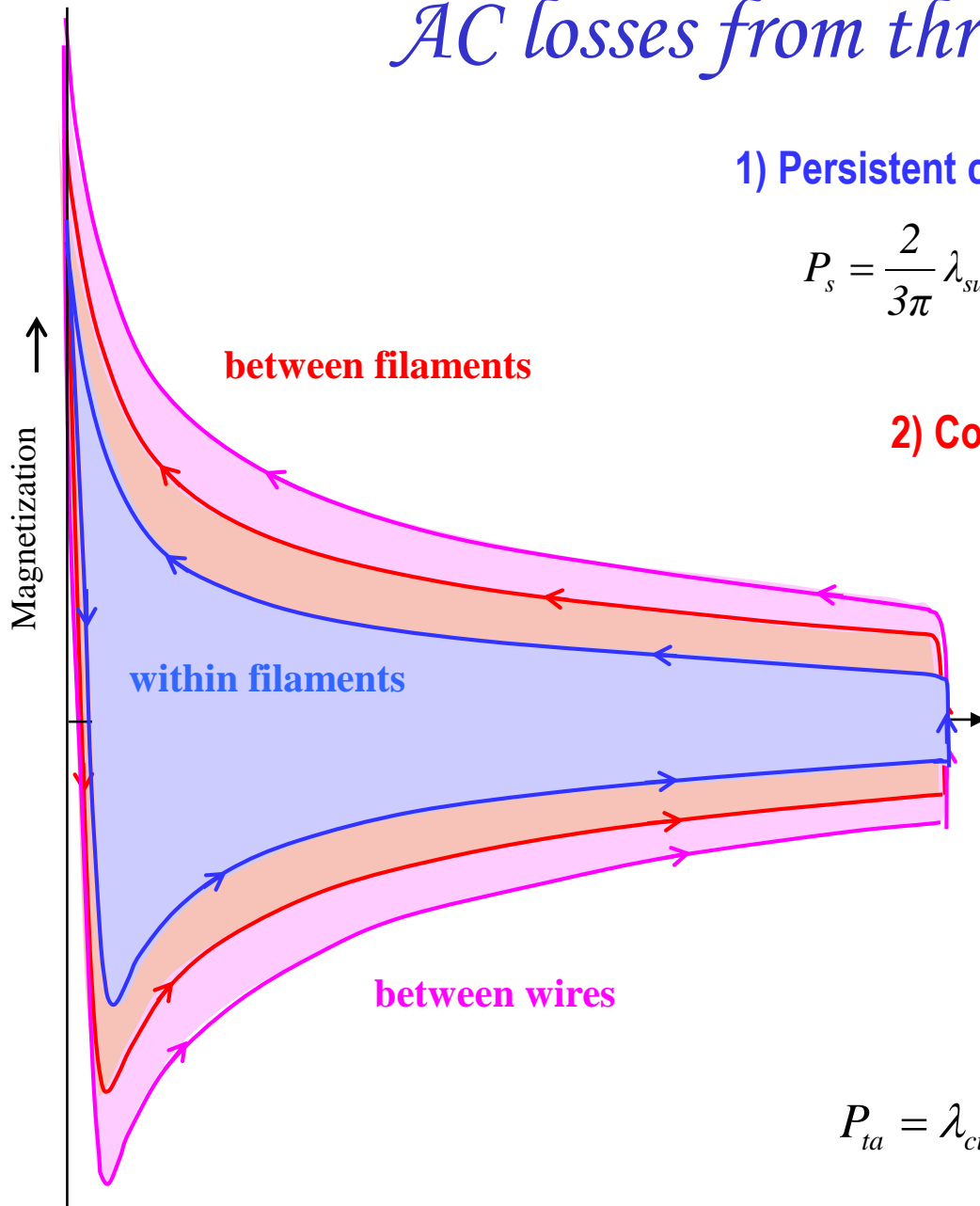
$$Q = \int \mu_o H dM = \int \mu_o M dH$$

hysteresis loss
per cycle
(not per ramp)



just
like
iron

AC losses from three sources



1) Persistent currents within filaments

$$P_s = \frac{2}{3\pi} \lambda_{su} B' J_c(B) d_f \quad Q_s = \frac{2}{3\pi} \lambda_{su} d_f \int J_c(B) dB$$

2) Coupling between filaments within the wire

$$P_e = \lambda_{wu} B'^2 \frac{1}{\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$

$$Q_e = \lambda_{wu} B' \Delta B \frac{1}{\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$

3) Coupling between wires in the cable

$$P_{tc} = \lambda_{cu} \frac{1}{120} \frac{B_t'^2}{R_c} \frac{c}{b} p_c N(N-1)$$

$$P_{ta} = \lambda_{cu} \frac{1}{6} \frac{B_t'^2}{R_a} p_c \frac{c}{b} \quad P_{pa} = \lambda_{cu} \frac{1}{8} \frac{B_p'^2}{R_a} p_c \frac{b}{c}$$

Summary of losses - per unit volume of winding

1) Persistent currents in filaments

power W.m^{-3}

$$P_s = \lambda_{su} M_f B' = \lambda_{su} \frac{2}{3\pi} J_c(B) d_f B'$$

where λ_{su} , λ_{wu} , λ_{cu} = fractions of superconductor, wire and cable in the winding cross section

2) Coupling currents between filaments in the wire

power
 W.m^{-3}

$$P_e = \lambda_{wu} M_e B' = \lambda_{wu} \frac{B'^2}{\rho_t} \left(\frac{p}{2\pi} \right)^2$$

3) Coupling currents between wires in the cable

transverse field crossover
resistance power W.m^{-3}

$$P_{tc} = \lambda_{cu} \frac{1}{120} \frac{B_t'^2}{R_c} p \frac{c}{b} N(N-1)$$

transverse field adjacent
resistance power W.m^{-3}

$$P_{ta} = \lambda_{cu} \frac{1}{6} \frac{B_t'^2}{R_a} p \frac{c}{b}$$

don't forget the filling factors

parallel field adjacent
resistance power W.m^{-3}

Concluding remarks

- changing magnetic fields drive superconductor into resistive state \Rightarrow losses – leave persistent currents
- screening currents produce magnetization (magnetic moment per unit volume)
 \Rightarrow lots of problems - field errors and ac losses
- in a synchrotron, the field errors from magnetization are worst at injection
- we reduce magnetization by making fine filaments - for practical use embed them in a matrix
- in changing fields, filaments are coupled through the matrix \Rightarrow increased magnetization
 - reduce it by twisting and by increasing the transverse resistivity of the matrix
- flux jumping is an electromagnetic/thermal instability that afflicts all high field superconductors
 - solved problem – fine filaments
- accelerator magnets must run at high current because they are all connected in series
 - combine wires in a cable, it must be fully transposed to ensure equal currents in each wire
- wires in cable must have some resistive contact to allow current sharing
 - in changing fields the wires are coupled via the contact resistance
 - different coupling when the field is parallel and perpendicular to face of cable
 - coupling produces more magnetization \Rightarrow more field errors
- irreversible magnetization \Rightarrow ac losses in changing fields
 - coupling between filaments in the wire adds to the loss
 - coupling between wire in the cable adds more

never forget that magnetization and ac loss are defined per unit volume - ***filling factors***